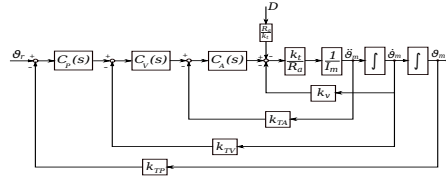
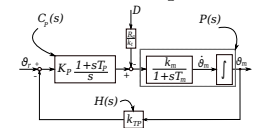


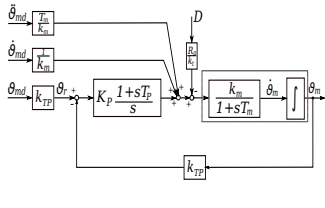
struttura generale di controllo indipendente ai giunti



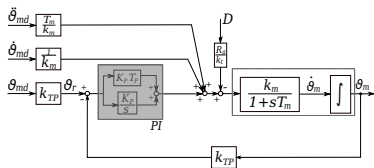
retroazione di posizione



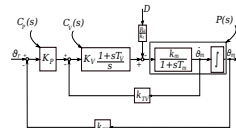
compensazione in avanti



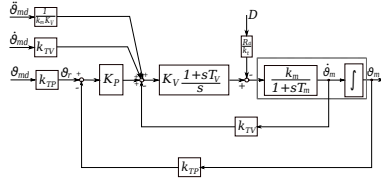
PI



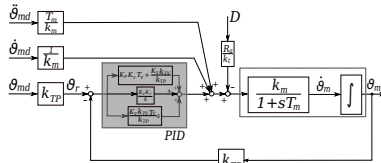
retroazione di posizione e velocità



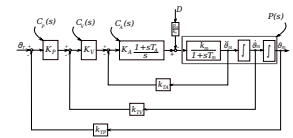
compensazione in avanti



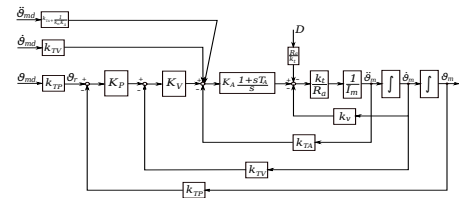
PID



retroazione di posizione, velocità e accelerazione



compensazione in avanti



PIDD²

