Eigenvalues and Eigenvectors

Let $A\in\mathbb{C}^{n\times n}$, the **eigenvalue problem** consists in finding a scalar λ (real or complex) and a nonnull vector \mathbf{x} such that

$$A\mathbf{x} = \lambda \mathbf{x} \tag{1}$$

Any such λ is called an **eigenvalue** of A, while \mathbf{x} is the associated **eigenvector**. The latter is not unique; indeed all multiples of \mathbf{x} , $\alpha \mathbf{x}$ with $\alpha \neq 0$, are also eigenvectors associated with λ .

Should x be known, λ can be recovered by using the **Rayleigh quotient**

$$\mathbf{x}^H A \mathbf{x} / ||\mathbf{x}||^2 = \bar{\mathbf{x}}^T A \mathbf{x} / ||\mathbf{x}||^2.$$

The eigenvalues of A are the roots of the **characteristic polynomial** of A:

$$p_A(\lambda) = \det(A - \lambda I).$$

A $n \times n$ matrix has exactly n eigenvalues (real or complex), not necessarily distinct. A matrix $A \in \mathbb{C}^{n \times n}$ is said to be **diagonalizable** if there exists a nonsingular matrix $U \in \mathbb{C}^{n \times n}$ such that

$$U^{-1}AU = \Lambda = \operatorname{diag}(\lambda_1, \dots, \lambda_n). \tag{2}$$

The columns of U are the eigenvectors of A. If A is diagonal or triangular, the λ 's are its diagonal entries; otherwise, if A is a general large matrix, seeking the zeros of p_A is hard.

The power method

Let $A \in \mathbb{R}^{n imes n}$, so with real entries, and assume that its eigenvalues are ordered

$$|\lambda_1| = |\lambda_{\max}| > |\lambda_2| \ge |\lambda_3| \ge \ldots \ge |\lambda_n| = |\lambda_{\min}|.$$

The **power method** can find the greater eigenvalue $\lambda_{\max} = \lambda_1$ of a non-singular matrix A.

Let $\mathbf{x}^{(0)} \in \mathbb{C}^n$ be given and set $\mathbf{y}^{(0)} = \mathbf{x}^{(0)}/||\mathbf{x}^{(0)}||$, for $k=1,2,\ldots$ compute

$$egin{aligned} \mathbf{x}^{(k)} &= A\mathbf{y}^{(k-1)} \ \mathbf{y}^{(k)} &= rac{\mathbf{x}^{(k)}}{||\mathbf{x}^{(k)}||} \ \lambda^{(k)} &= (\mathbf{y}^{(k)})^H A\mathbf{y}^{(k)} \end{aligned}$$

until $|\lambda^{(k)} - \lambda^{(k-1)}| < \varepsilon |\lambda^{(k)}|$ (stopping condition), where ε is the desired tolerance.

By induction on k one can check that

$$\mathbf{y}^{(k)} = rac{\mathbf{x}^{(k)}}{||\mathbf{x}^{(k)}||} = rac{A\mathbf{y}^{(k-1)}}{||A\mathbf{y}^{(k-1)}||} = \ldots = rac{A^k\mathbf{y}^{(0)}}{||A^k\mathbf{y}^{(0)}||}, \quad k \geq 1.$$

This relation explains the role played by the powers of A in the method: the term $\mathbf{y}^{(k)}$ can also be expressed as a power, thus the name of the method.

This method generates a sequence of unitary vectors $\{\mathbf{y}^{(k)}\}$ such that for $k \to \infty$ they align in the direction of the eigenvector \mathbf{x}_1 . In all cases, we have that $\lambda^{(k)} \to \lambda_{\max} = \lambda_1$ for $k \to \infty$.

Convergence

Since the eigenvectors $\mathbf{x}_1, \dots, \mathbf{x}_n$ of A are linearly independent, these eigenvectors form a basis for \mathbb{C}^n . Thus the vectors $\mathbf{x}^{(0)}$ and $\mathbf{y}^{(0)}$ can be written as

$$\mathbf{x}^{(0)} = \sum_{i=1}^n lpha_i \mathbf{x}_i, \qquad \mathbf{y}^{(0)} = eta^{(0)} \sum_{i=1}^n lpha_i \mathbf{x}_i, \qquad ext{with } eta^{(0)} = 1/||\mathbf{x}^{(0)}|| ext{ and } lpha_i \in \mathbb{C}.$$

At the first step the power method gives

$$egin{aligned} \mathbf{x}^{(1)} &= A \mathbf{y}^{(0)} = eta^{(0)} A \sum_{i=1}^n lpha_i \mathbf{x}_i = eta^{(0)} \sum_{i=1}^n lpha_i \lambda_i \mathbf{x}_i \quad ext{and, similarly,} \ \mathbf{y}^{(1)} &= eta^{(1)} \sum_{i=1}^n lpha_i \lambda_i \mathbf{x}_i, \quad eta^{(1)} &= rac{1}{||\mathbf{x}^{(0)}|| \cdot ||\mathbf{x}^{(1)}||}. \end{aligned}$$

At a given step k we will have

$$\mathbf{y}^{(k)} = eta^{(k)} \sum_{i=1}^n lpha_i \lambda_i^k \mathbf{x}_i, \qquad eta^{(k)} = rac{1}{||\mathbf{x}^{(0)}|| \cdots ||\mathbf{x}^{(k)}||} = rac{1}{\prod_{i=0}^k ||\mathbf{x}^{(i)}||}$$

And therefore

$$\mathbf{y}^{(k)} = \lambda_1^k eta^{(k)} \left(lpha_1 \mathbf{x}_1 + \sum_{i=2}^n lpha_i rac{\lambda_i^k}{\lambda_1^k} \mathbf{x}_i
ight).$$

Since $|\lambda_i/\lambda_1| < 1$ for i = 2, ..., n, the vector $\mathbf{y}^{(k)}$ tends to align along the same direction as the eigenvector \mathbf{x}_1 when k tends to $+\infty$, provided $\alpha_1 \neq 0$.

The inverse power method

The **inverse power method** can find the smaller eigenvalue of a non-singular matrix A. It is like the previous method, but if A is non-singular we can use A^{-1} , which eigenvalues are the reciprocal of those of A, to obtain the eigenvalue of A with minimum modulus.

Let $\mathbf{x}^{(0)} \in \mathbb{C}^n$ be given and set $\mathbf{y}^{(0)} = \mathbf{x}^{(0)}/||\mathbf{x}^{(0)}||$, for $k=1,2,\ldots$ compute

$$egin{aligned} \mathbf{x}^{(k)} &= A^{-1}\mathbf{y}^{(k-1)} \ \mathbf{y}^{(k)} &= rac{\mathbf{x}^{(k)}}{||\mathbf{x}^{(k)}||} \ \mu^{(k)} &= (\mathbf{y}^{(k)})^H A^{-1}\mathbf{y}^{(k)} \end{aligned}$$

until $|\mu^{(k)} - \mu^{(k-1)}| < \varepsilon |\mu^{(k)}|$, where ε is the desired tolerance.

If A admits n linearly independent eigenvectors, and if also the eigenvalue $\lambda_{\min}=\lambda_n$ of minimum modulus is distinct from the others, then

$$\lim_{k o\infty}\mu^{(k)}=1/\lambda_{\min},$$

At each step k we have to solve a linear system of the form $A\mathbf{x}^{(k)} = \mathbf{y}^{(k-1)}$, and we can use for example the LU factorization or the Cholesky factorization.

The power method with shift

The power method with shift can find the eigenvalue of A near to a given number μ .

Define $A_{\mu}=A-\mu I$, whose eigenvalues are $\lambda(A_{\mu})=\lambda(A)-\mu$. In order to approximate λ_{μ} , we can at first approximate the eigenvalue of minimum length of A_{μ} with the inverse power method. Let $\mathbf{x}^{(0)}\in\mathbb{C}^n$ be given and set $\mathbf{y}^{(0)}=\mathbf{x}^{(0)}/||\mathbf{x}^{(0)}||$, for $k=1,2,\ldots$ compute

$$egin{aligned} \mathbf{x}^{(k)} &= A_{\mu}^{-1}\mathbf{y}^{(k-1)} \ \mathbf{y}^{(k)} &= rac{\mathbf{x}^{(k)}}{||\mathbf{x}^{(k)}||} \ \lambda_{\mu}^{(k)} &= rac{1}{(\mathbf{y}^{(k)})^{H}A_{\mu}^{-1}\mathbf{y}^{(k)}} \end{aligned}$$

until $|\lambda_{\mu}^{(k)} - \lambda_{\mu}^{(k-1)}| < \varepsilon |\lambda_{\mu}^{(k)}|$, where ε is the desired tolerance. The searched eigenvalue of A is approximated by $\lambda = \lambda_{\mu} + \mu$.

The value of the shift can be modified during the iterations, by setting $\mu=\lambda^{(k)}$. This yields a faster convergence; however the computational cost grows substantially since now at each iteration the matrix A_μ does change and the LU factorization has to be performed at each iteration.

How to compute the shift

We need to locate (more or less accurately) the eigenvalues of A in the complex plane.

Let $A\in\mathbb{C}^{n\times n}$ be a square matrix of dimension n. The **Gershgorin circles** $C_i^{(r)}$ and $C_i^{(c)}$ associated with its i-th row and i-th column are respectively defined as

$$egin{aligned} \mathcal{R}_i &= C_i^{(r)} = \left\{z \in \mathbb{C}: |z-a_{ii}| \leq \sum_{j=1, j
eq i}^n |a_{ij}|
ight\}, \ \mathcal{C}_i &= C_i^{(c)} = \left\{z \in \mathbb{C}: |z-a_{ii}| \leq \sum_{j=1, j
eq i}^n |a_{ji}|
ight\}. \end{aligned}$$

 \mathcal{R}_i is called the i-th $\operatorname{\textbf{row circle}}$ and \mathcal{C}_i the i-th $\operatorname{\textbf{column circle}}$.

First Gershgorin theorem. All the eigenvalues of a given matrix $A \in \mathbb{C}^{n \times n}$ belong to the region of the complex plane which is the intersection of the two regions formed respectively by the union of the row circles $\mathcal{S}_{\mathcal{R}} = \bigcup_{i=1}^n \mathcal{R}_i$ and the union of the column circles $\mathcal{S}_{\mathcal{C}} = \bigcup_{i=1}^n \mathcal{C}_i$:

$$orall \lambda \in \sigma(A), \quad \lambda \in \mathcal{S}_{\mathcal{R}} \bigcap \mathcal{S}_{\mathcal{C}}.$$

Moreover, should m row circles (or column circles), with $1 \le m \le n$, be disconnected from the union of the remaining n-m circles, then their union contains exactly m eigenvalues.

There is no guarantee that a circle should contain eigenvalues, unless it is isolated from the others. The information provided by Gershgorin circles are in general quite coarse, thus the previous result can provide only a preliminary guess of the shift.

Remark. Note that all the eigenvalues of a strictly diagonally dominant matrix are non-null.

The ${\it QR}$ method

We will see some iterative techniques for simultaneously approximating all the eigenvalues of a given matrix A. The basic idea consists of reducing A, by means of suitable similarity transformations, into a form for which the calculation of the eigenvalues is easier than on the starting matrix.

If A and B are similar $P^{-1}AP=B$ then $\lambda_A=\lambda_B$

$$BP^{-1}\mathbf{x} = P^{-1}A\mathbf{x} = \lambda P^{-1}\mathbf{x}$$

A method to compute all the eigenvalues of \boldsymbol{A} is transforming it in a similar diagonal / triangular matrix.

The QR method uses repeatedly the QR factorization to compute λ .

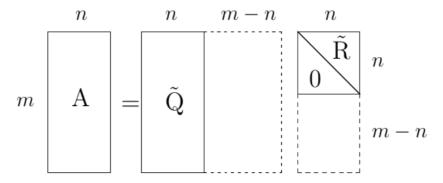


Fig. 3.1. The reduced factorization. The matrices of the QR factorization are drawn in dashed lines

$$\implies Q^{(k+1)}R^{(k+1)} = A^{(k)} \implies A^{(k+1)} = R^{(k+1)}Q^{(k+1)}$$

 $A^{(k)}$ and $A^{(k+1)}$ are similar and the rate of decay to zero of lower triangular coefficients in $A^{(k)}$ depends on $\max_i |\lambda_{i+1}/\lambda_i|, \ \forall i$. If A is symmetric, $A^{(k)}$ for $k \to \infty$ is diagonal.