

# SMALL SIZE DC SERVOMOTORS Minertia Motor J Series

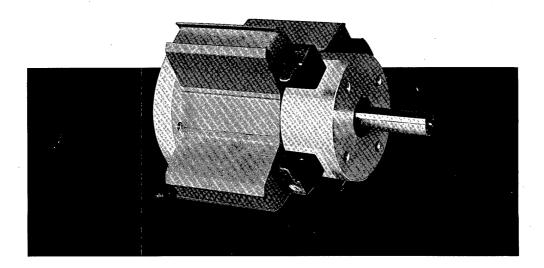
Type J03

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#### Designed to meet the Demands of Computer Peripherals

Creative design engineering and time-proven manufacturing technologies blended with accumulated knowledge of computer peripherals, achieve light weight, low cost, and high reliability in J Series.

J Series is a new line mainly for printer drivers. Construction feature is the employment of ceramic magnet for magnetic field formation and slotted core armature. Modifications are easily accomplished in a compact figure, because detecting devices like DC tachometer generators and optical encoders can be built-on the motors.



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- · Ceramic magnet DC servomotor
- 4-pole configuration for high performance in a small package
- · Low inertia High peak torque
- High torque-to-size ratio due to low thermal resistance
- Available with analog tachometers and optical encoders
- Substantial price reductions in OEM volumes

## **APPLICATIONS**

- · Carriage of medium- or high-speed serial printers
- X-Y plotters
- Recorders



## **RATINGS AND SPECIFICATIONS**

Minertia	Motor	LOGGA	10000	10000		100110		* ** ** ** ** **		
J Ser		J03SA	J03SB	Jose	JOSMA	J03MB	J03MC	J03LA	J03LB	J03FC
Peak Rated Torque	oz∙in		186			266			344	
Rated Torque	oz∙in	40.3			54.2			66.7		
Torque Constant	oz·in/amp±10%	8.66	13.3	17.3	12.3	18.9	24.6	16.0	24.5	31.9
Armature Winding Resistance (at 25 ℃)		0.69	1.66	2.86	0.88	2.12	3.66	1.08	2.58	4.45
Armature Inductance	mH	0.43	1.0	1.7	0.68	1.6	2.7	0.94	2.2	3.8
Peak Current	Α	22	14.3	11	22	14.3	11	22	14.3	11
Voltage Constant	$V/1000 rpm \pm 10\%$	6.4	9.8	12.8	9.1	14.0	18.2	11.8	18.1	23.6
Viscous Damping Coefficient	oz·in/1000rpm		1.4			2.0			2.5	
Friction Torque	oz∙in	3.6			4.7			5.8		
Breakaway Torque	oz∙in	_								
Cogging Torque at Zero Excitation	oz∙in	_			_					
Inertia	$oz \cdot in \cdot sec^2 \times 10^{-3}$		3.1			4.29			5.48	
Mechanical Time Cor	<b>nstant</b> ms		4.1			3.6			3.4	
Electrical Time Cons	tant ms		0.6			0.76			0.85	
Power Rate	kW/sec		3.69			4.82			5.71	
Torque Inertia Ratio	rad/sec <sup>2</sup>		13000			12600			12200	
Thermal Resistance	deg C/watt		3.1			2.8			2.5	
Thermal Time Consta	ant minutes				_			_		
Max Allowable Armature Temperatu	re °C	155			155			155		
Rated Speed	rpm	1000	1000	1000	1000	1000	1000	1000	1000	1000
Max Safe Operating S	Speed rpm	3000	3000	3000	3000	3000	2400	3000	2500	1600
Max No Load Speed	rpm	5000	4900	4100	5000	3800	2900	4500	2900	2200
Cooling Required	cfm, in H₂O		TENV			TENV			TENV	

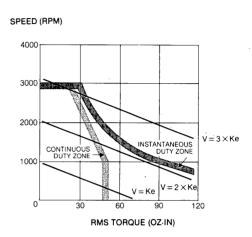
## **TORQUE-SPEED CURVES**

Shown below are the torque-speed curves under the following environmental conditions:

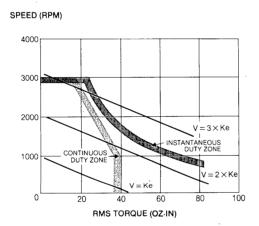
Temperature: 25°C Humidity: 80%

Armature temperature: 125 °C Magnet temperature: 80 °C Heat sink:  $10'' \times 10'' \times 1/4''$ 

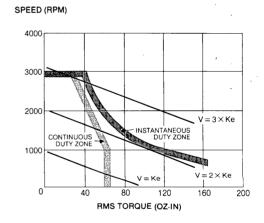
#### Type J03M



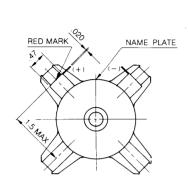
#### Type J03S

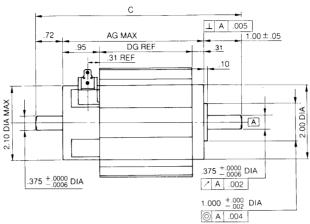


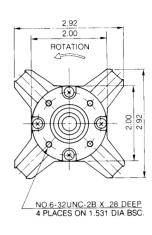
#### Type J03L



## **DIMENSIONS** in inches

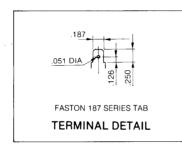






#### Note

- 1. Ccw rotation with positive voltage applied to red mark terminal when viewed from drive end.
- 2. The motor shaft is pre-loaded with spring washers toward opposite drive end by 5 pounds.
- 3. Shaft end play .002 max under of 2 pounds thrust.
- 4. All dimensions in inches, 2-decimal tolerance ± .03,
- 3-decimal tolerance  $\pm .010$ .



Туре	С	AG	DG	Weight lbs
J03S	4.89	3.23	1.91	2.9
J03M	5.44	3.78	2.46	3.6
J03L	5.99	4.33	3.01	4.4

## **ALLOWABLE RADIAL AND THRUST LOAD**

Minertia Motor Type	Allowable Radial Load (FR) lb	Allowable Thrust Load (Fs) lb	Reference Diagram in.
J03S			- <del></del> -8
J03M	18.5	7	Fs
J03L			

Note: Allowable thrust and radial loads are based on the assumption that motor is driven at rated speed and has 10,000 hours of bearing life.

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Due to ongoing product modification/improvement, data subject to change without notice.

