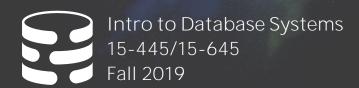


9 Index Concurrency



AP Andy Pavlo
Computer Science
Carnegie Mellon University

ADMINISTRIVIA

Project #1 is due Fri Sept 27th @ 11:59pm

Homework #2 is due Mon Sept 30th @ 11:59pm

Project #2 will be released Mon Sept 30th



OBSERVATION

We assumed that all the data structures that we have discussed so far are single-threaded.

But we need to allow multiple threads to safely access our data structures to take advantage of additional CPU cores and hide disk I/O stalls.







CONCURRENCY CONTROL

A <u>concurrency control</u> protocol is the method that the DBMS uses to ensure "correct" results for concurrent operations on a shared object.

A protocol's correctness criteria can vary:

- → **Logical Correctness:** Can I see the data that I am supposed to see?
- → **Physical Correctness:** Is the internal representation of the object sound?



TODAY'S AGENDA

Latches Overview

Hash Table Latching

B+Tree Latching

Leaf Node Scans

Delayed Parent Updates



LOCKS VS. LATCHES

Locks

- → Protects the database's logical contents from other txns.
- \rightarrow Held for txn duration.
- → Need to be able to rollback changes.

Latches

- → Protects the critical sections of the DBMS's internal data structure from other threads.
- \rightarrow Held for operation duration.
- \rightarrow Do not need to be able to rollback changes.



LOCKS VS. LATCHES

Lecture 17

Locks

Separate... User transactions

Protect... Database Contents

During... Entire Transactions

Modes... Shared, Exclusive, Update,

Intention

Deadlock Detection & Resolution

...by... Waits-for, Timeout, Aborts

Kept in... Lock Manager

Latches

Threads

In-Memory Data Structures

Critical Sections

Read, Write

Avoidance

Coding Discipline

Protected Data Structure

Source: Goetz Graefe



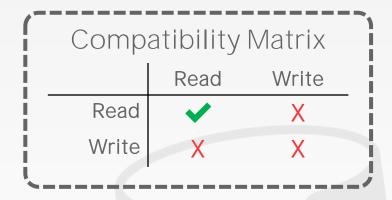
LATCH MODES

Read Mode

- → Multiple threads can read the same object at the same time.
- → A thread can acquire the read latch if another thread has it in read mode.

Write Mode

- → Only one thread can access the object.
- → A thread cannot acquire a write latch if another thread holds the latch in any mode.





Approach #1: Blocking OS Mutex

- → Simple to use
- → Non-scalable (about 25ns per lock/unlock invocation)
- → Example: **std::mutex**

```
std::mutex m;
:
m.lock();
// Do something special...
m.unlock();
```



Approach #2: Test-and-Set Spin Latch (TAS)

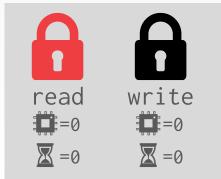
- → Very efficient (single instruction to latch/unlatch)
- → Non-scalable, not cache friendly
- → Example: **std::atomic<T>**

```
std::atomic<bool>
std::atomic_flag latch;
:
while (latch.test_and_set(...)) {
    // Retry? Yield? Abort?
}
```

Approach #3: Reader-Writer Latch

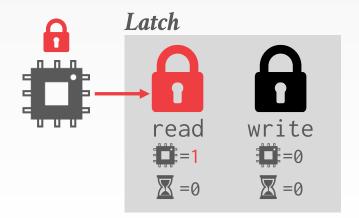
- → Allows for concurrent readers
- → Must manage read/write queues to avoid starvation
- → Can be implemented on top of spinlocks

Latch



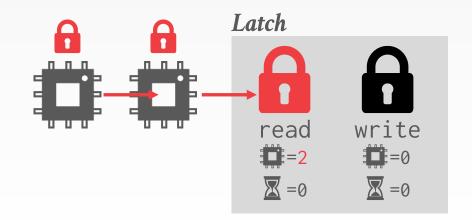


- → Allows for concurrent readers
- → Must manage read/write queues to avoid starvation
- → Can be implemented on top of spinlocks



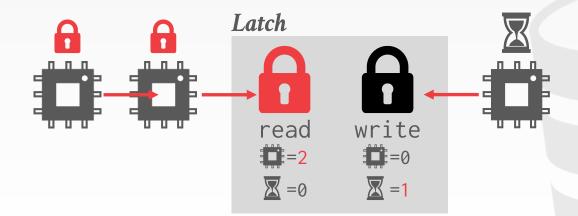


- → Allows for concurrent readers
- → Must manage read/write queues to avoid starvation
- → Can be implemented on top of spinlocks



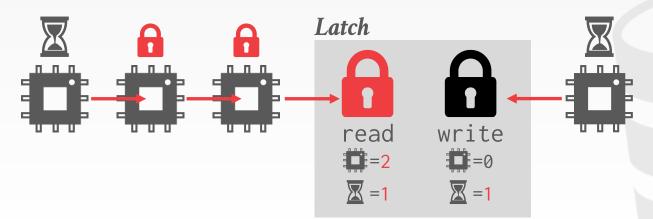


- → Allows for concurrent readers
- → Must manage read/write queues to avoid starvation
- → Can be implemented on top of spinlocks





- → Allows for concurrent readers
- → Must manage read/write queues to avoid starvation
- → Can be implemented on top of spinlocks





HASH TABLE LATCHING

The ways which threads can interact with our hash table is limited

Easy to support concurrent access due to the limited ways threads access the data structure.

- → All threads move in the same direction and only access a single page/slot at a time.
- \rightarrow Deadlocks are not possible.

To resize the table, take a global latch on the entire table (i.e., in the header page).



HASH TABLE LATCHING

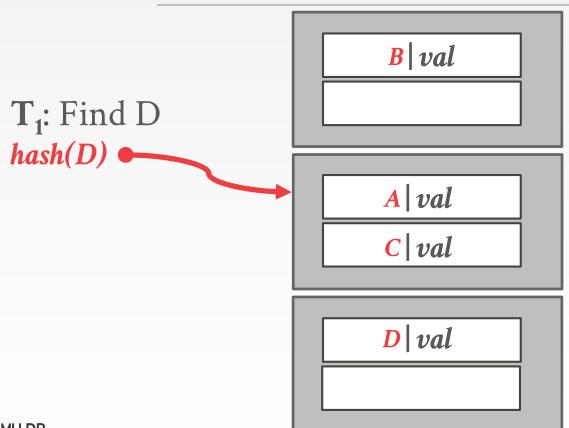
Approach #1: Page Latches

- → Each page has its own reader-write latch that protects its entire contents.
- → Threads acquire either a read or write latch before they access a page.

Approach #2: Slot Latches

- \rightarrow Each slot has its own latch.
- → Can use a single mode latch to reduce meta-data and computational overhead.



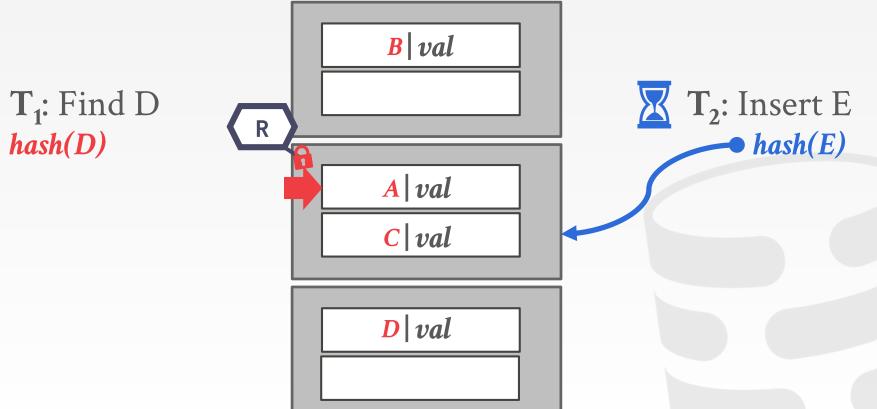




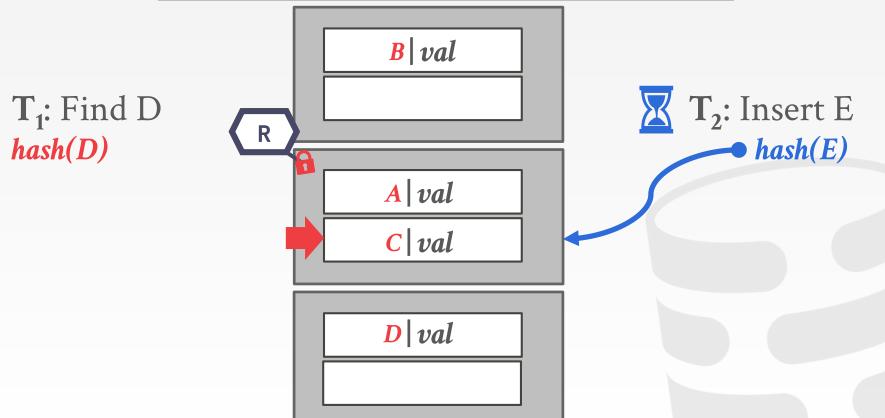
D | val

B | valT₁: Find D hash(D) R A | val C | val

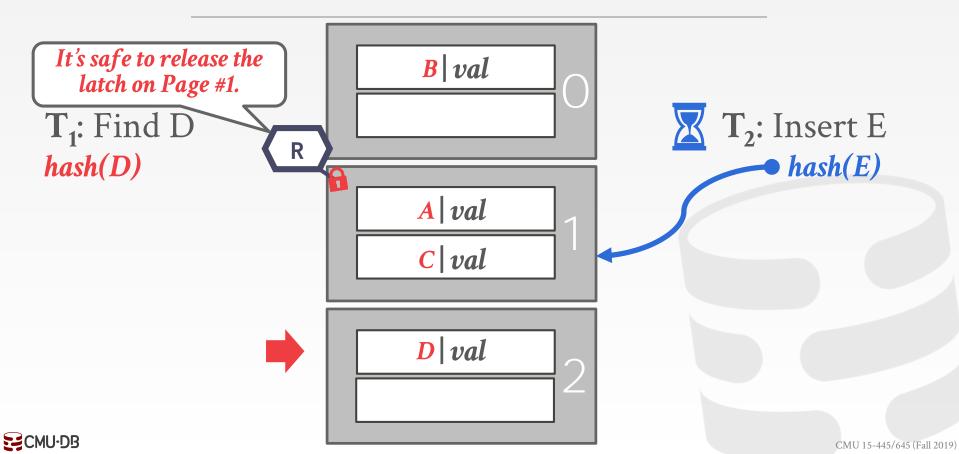




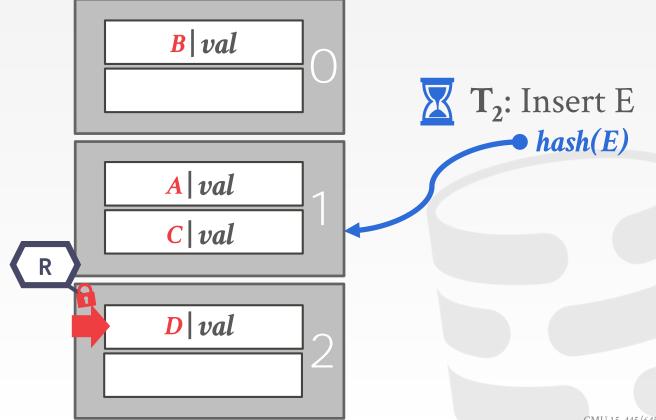






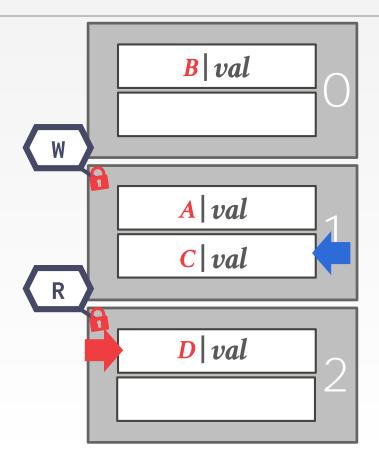


T₁: Find D hash(D)

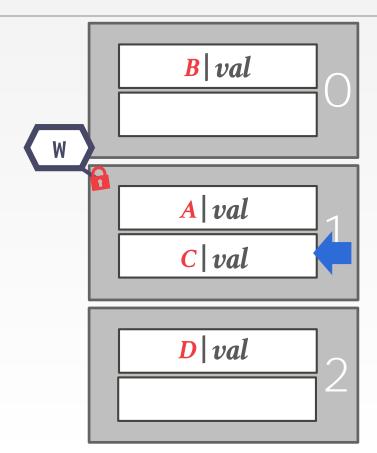




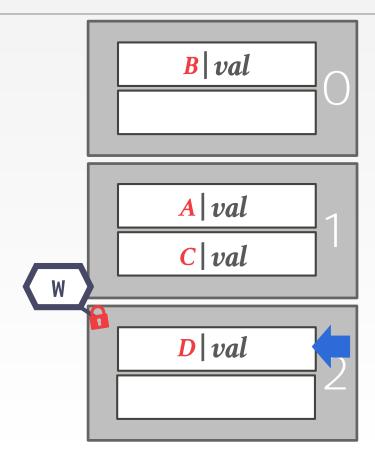
T₁: Find D hash(D)



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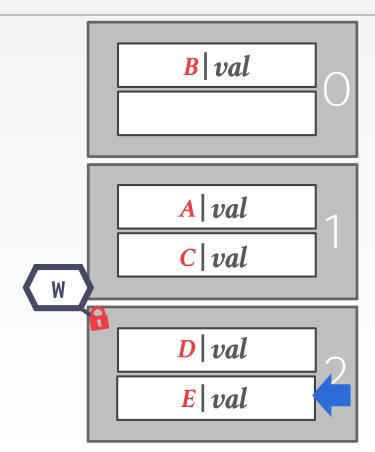


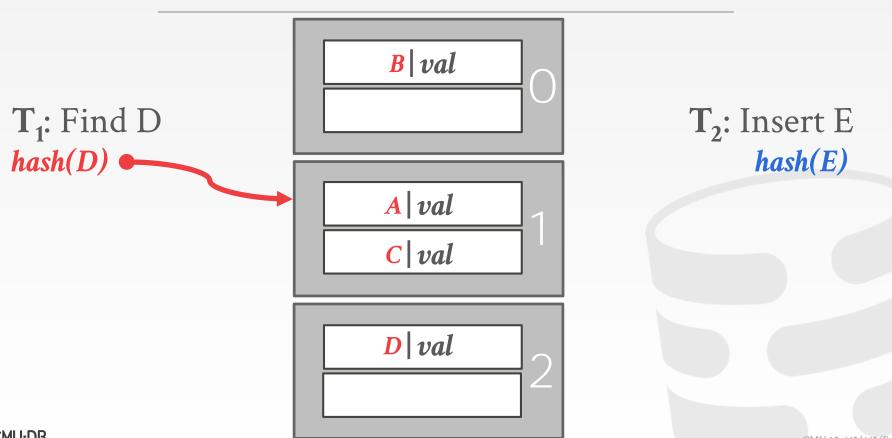
T₁: Find D hash(D)





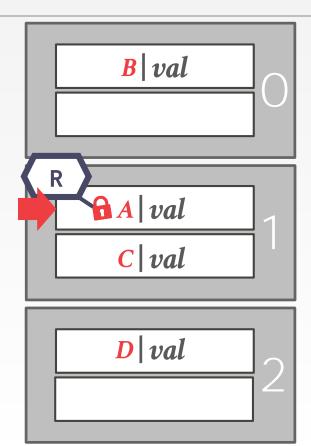
T₁: Find D hash(D)





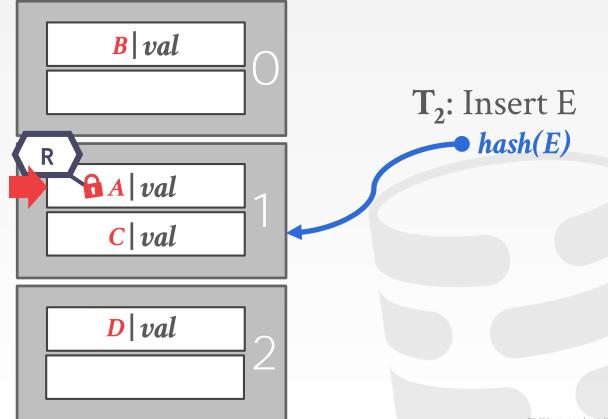


T₁: Find D hash(D)



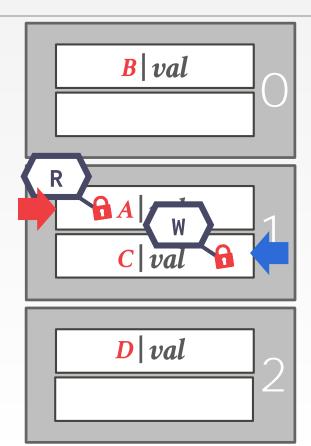


T₁: Find D hash(D)

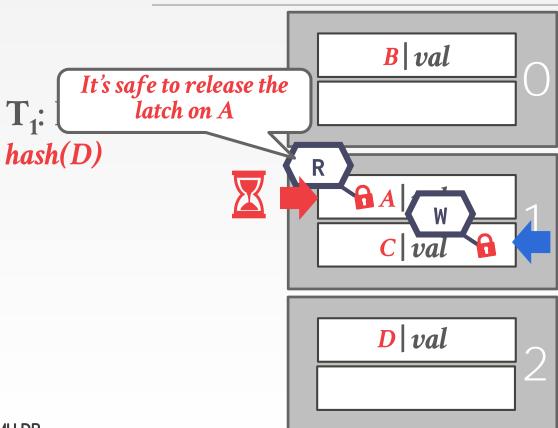




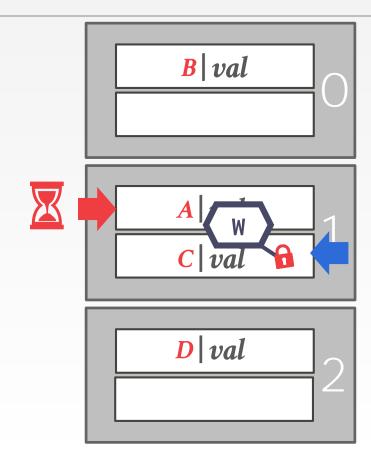
T₁: Find D hash(D)







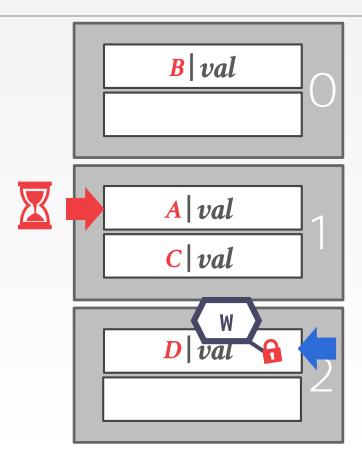
T₁: Find D hash(D)



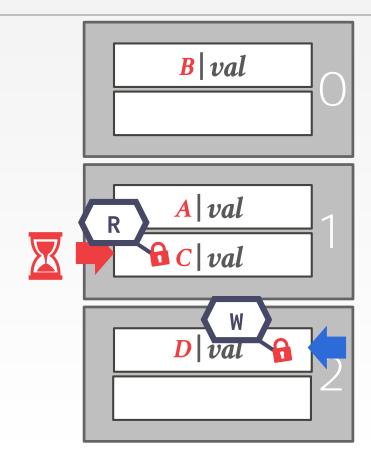
T₂: Insert E hash(E)



T₁: Find D hash(D)

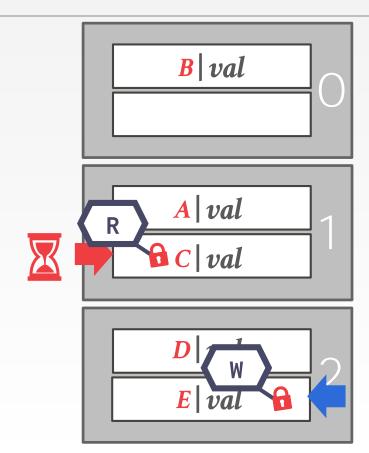


T₁: Find D hash(D)





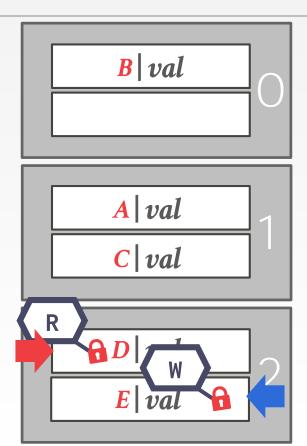
T₁: Find D hash(D)





HASH TABLE - SLOT LATCHES

T₁: Find D hash(D)



 T_2 : Insert E hash(E)



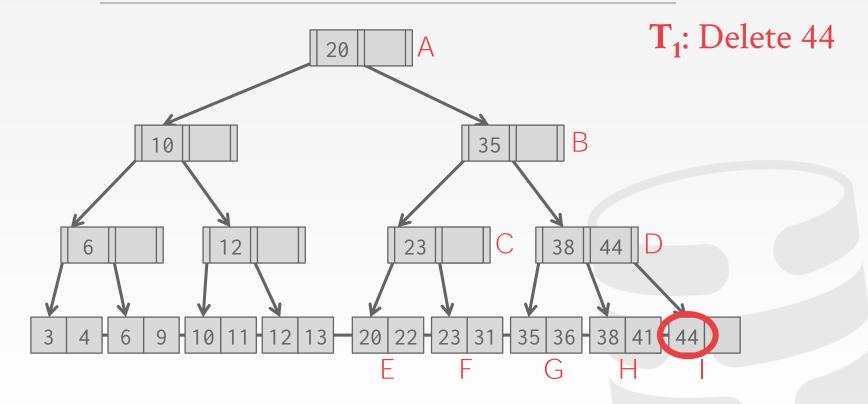
B+TREE CONCURRENCY CONTROL

We want to allow multiple threads to read and update a B+Tree at the same time.

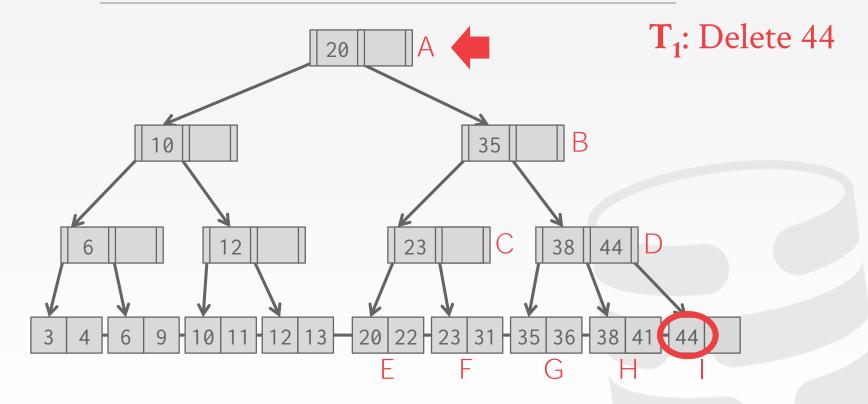
We need to protect from two types of problems:

- → Threads trying to modify the contents of a node at the same time.
- → One thread traversing the tree while another thread splits/merges nodes.

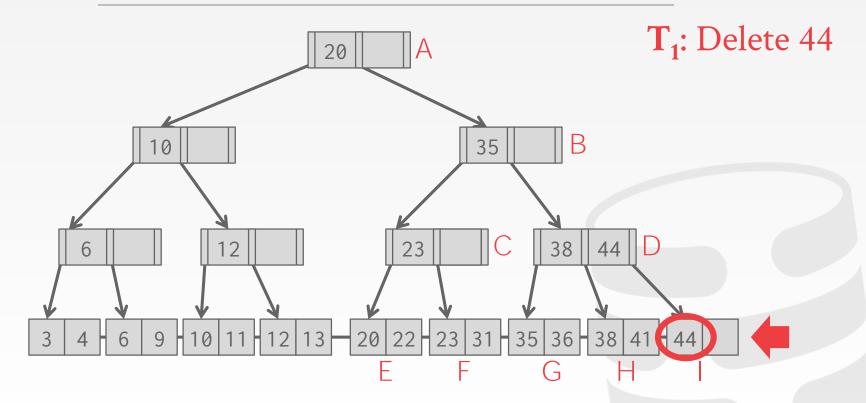




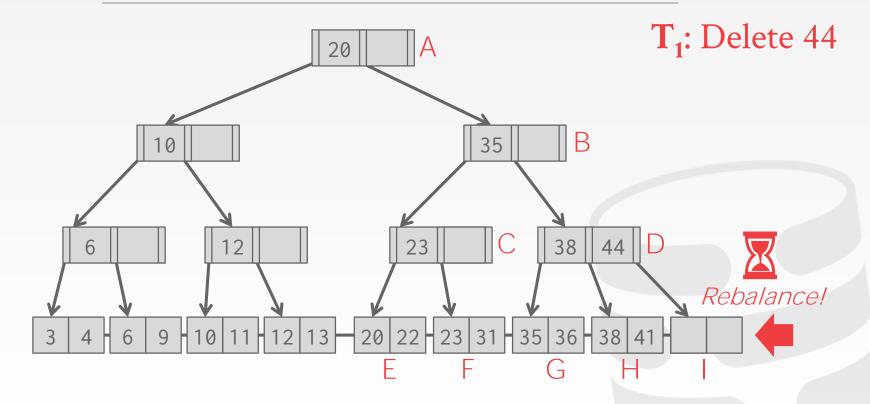




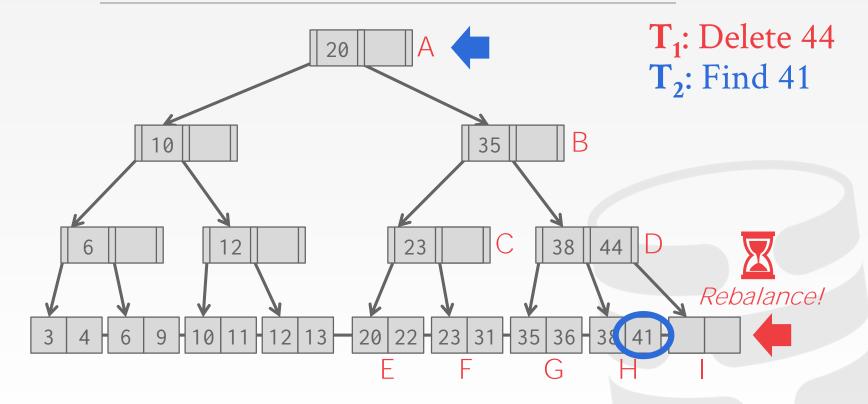




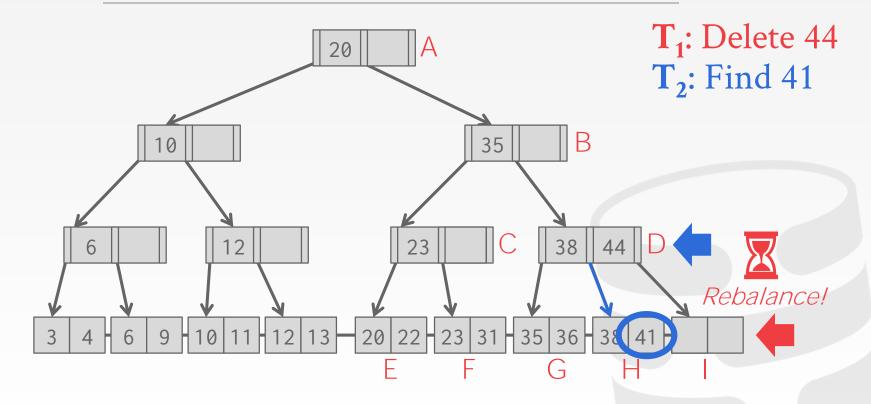




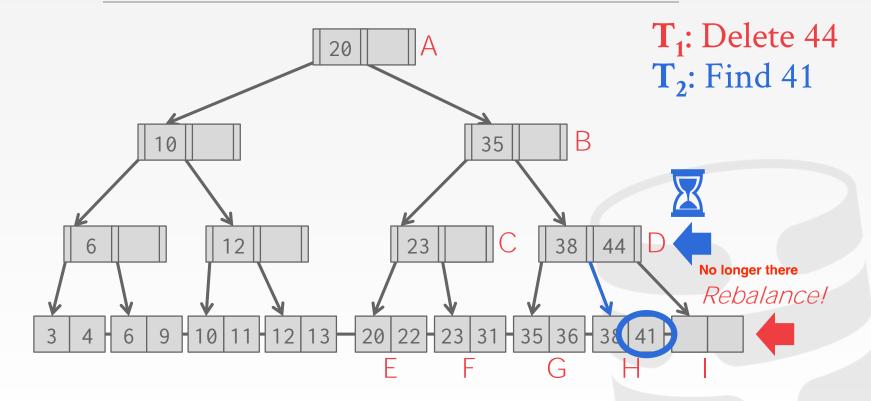




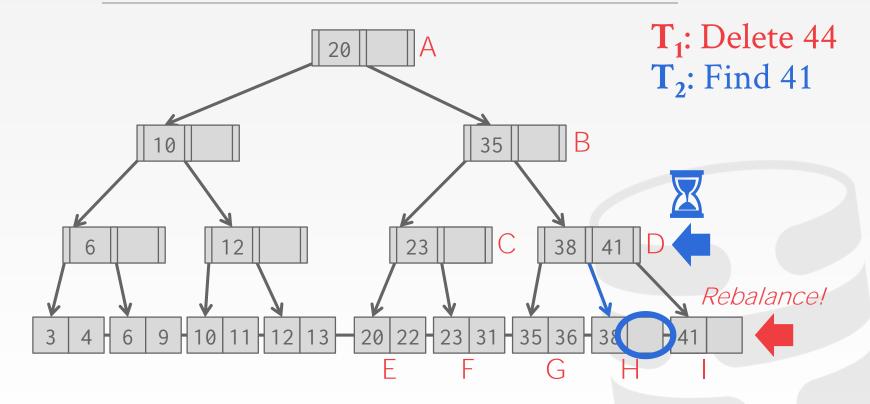




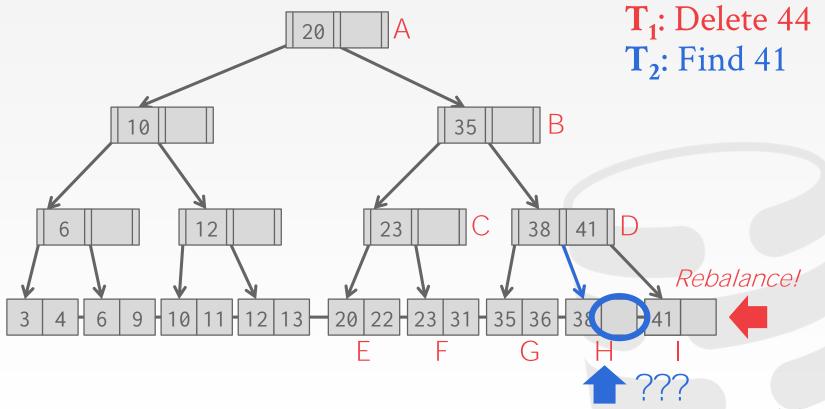














LATCH CRABBING/COUPLING

If we are doing a modification, the node we're sitting at will not have to do a split or merge no matter what happens below it in the tree

Protocol to allow multiple threads to access/modify B+Tree at the same time.

Basic Idea:

- \rightarrow Get latch for parent.
- → Get latch for child
- → Release latch for parent if "safe".

A <u>safe node</u> is one that will not split or merge when updated.

- → Not full (on insertion)
- → More than half-full (on deletion)



LATCH CRABBING/COUPLING

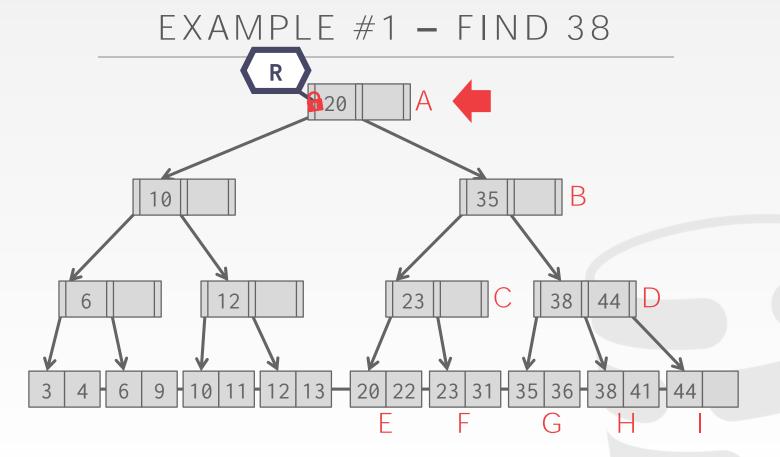
Find: Start at root and go down; repeatedly,

- → Acquire R latch on child
- → Then unlatch parent

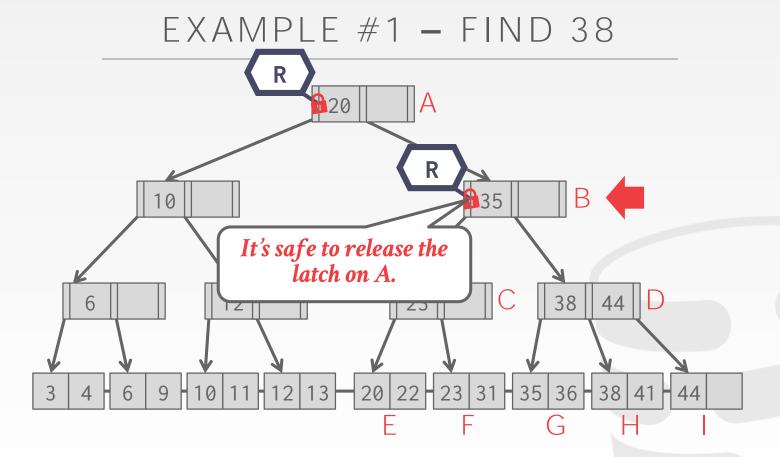
Insert/Delete: Start at root and go down, obtaining W latches as needed. Once child is latched, check if it is safe:

 \rightarrow If child is safe, release all latches on ancestors.

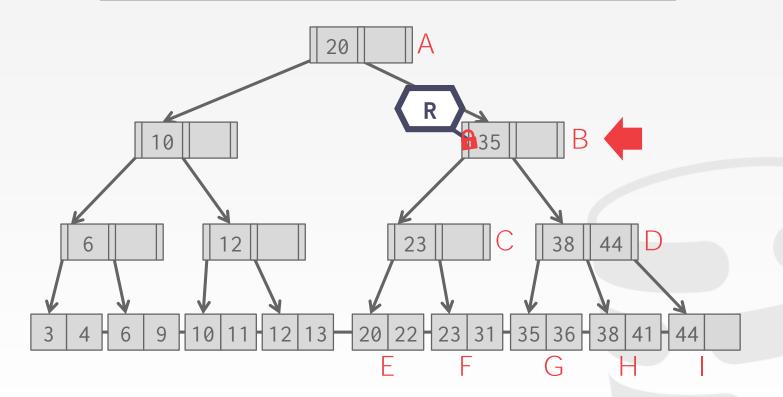




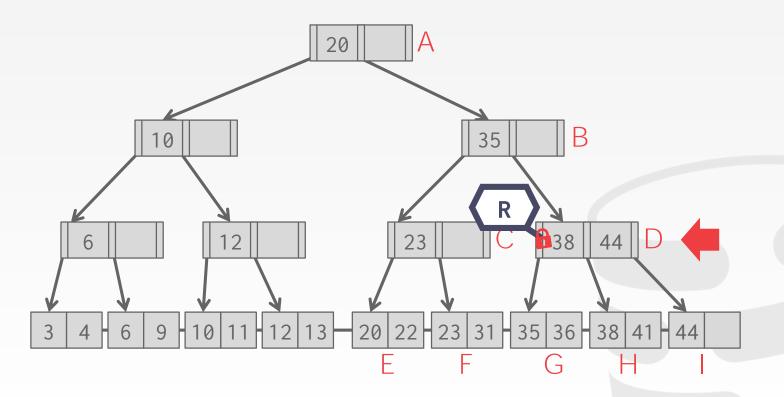




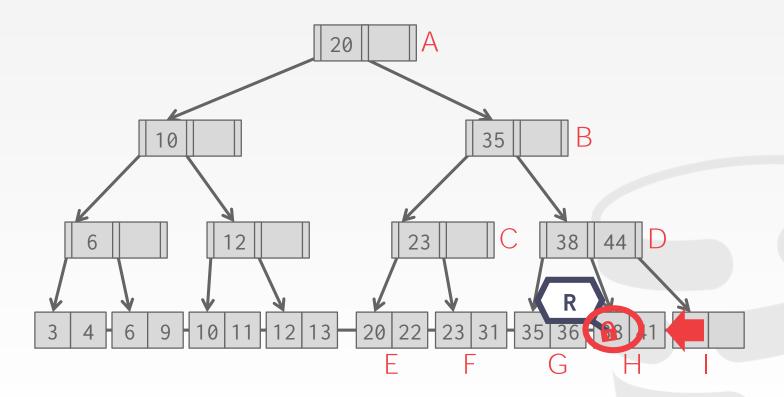




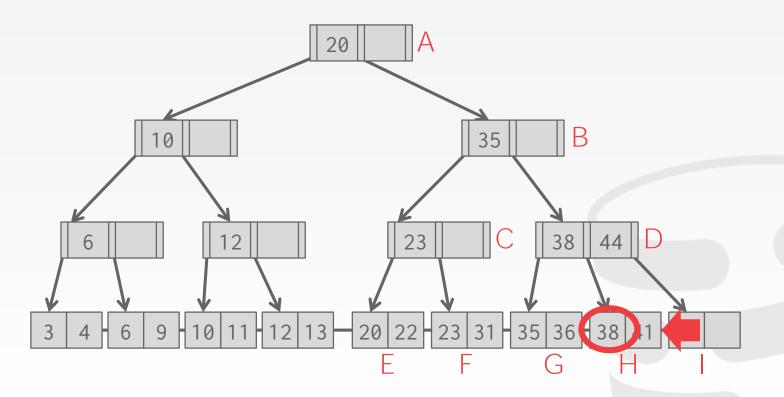




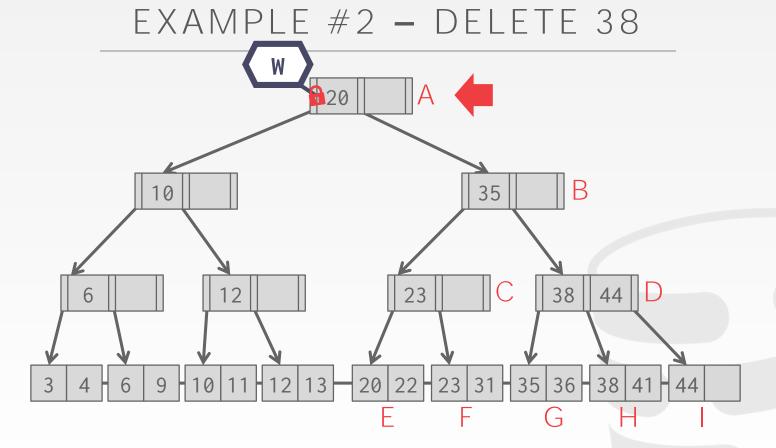




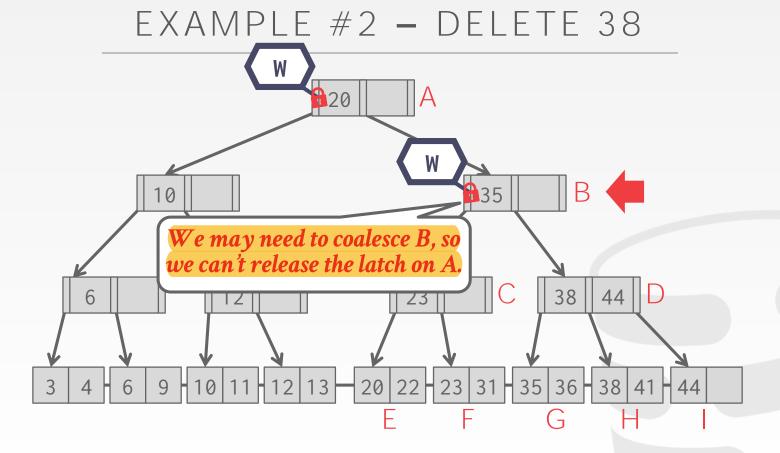






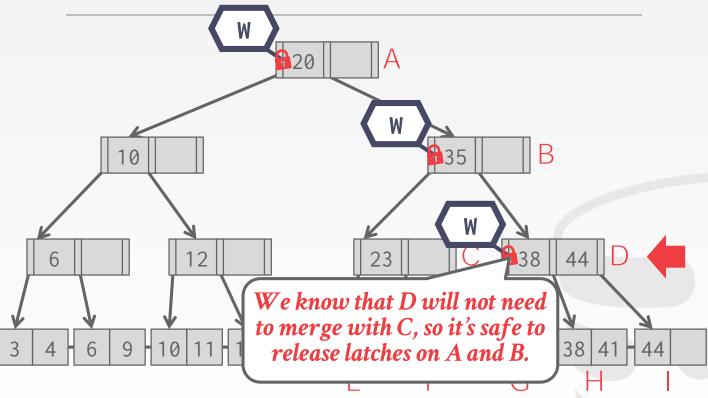






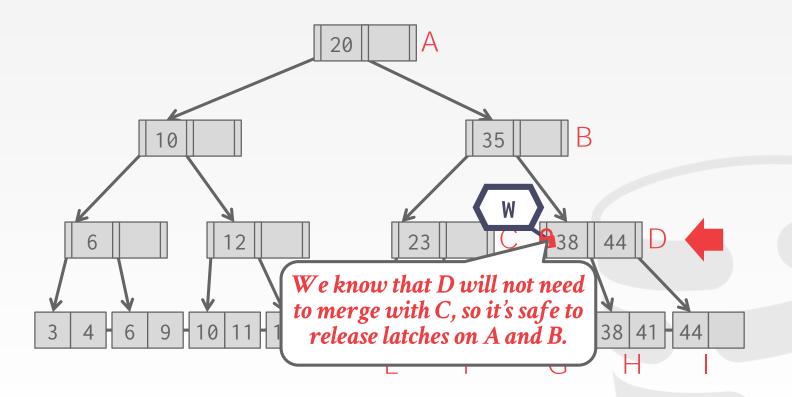






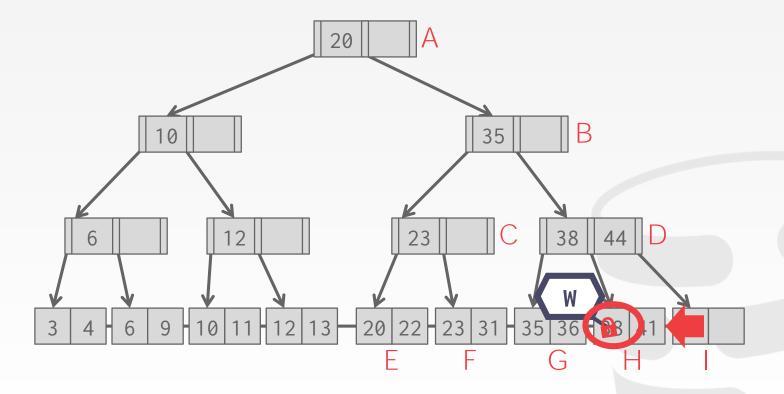


EXAMPLE #2 - DELETE 38



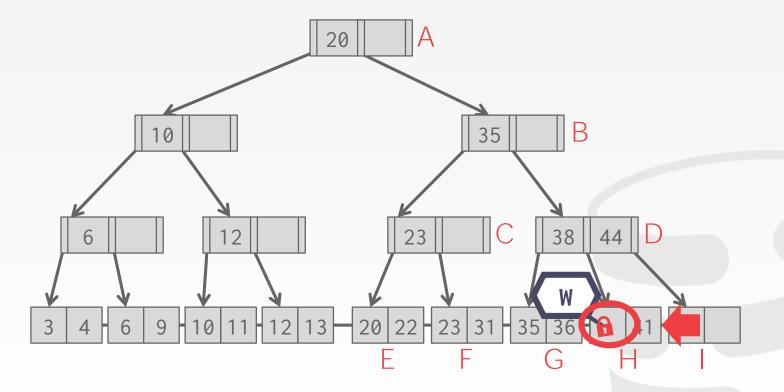


EXAMPLE #2 - DELETE 38

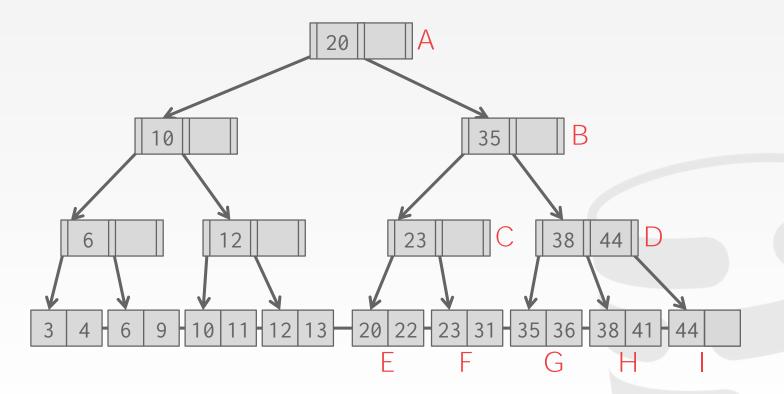




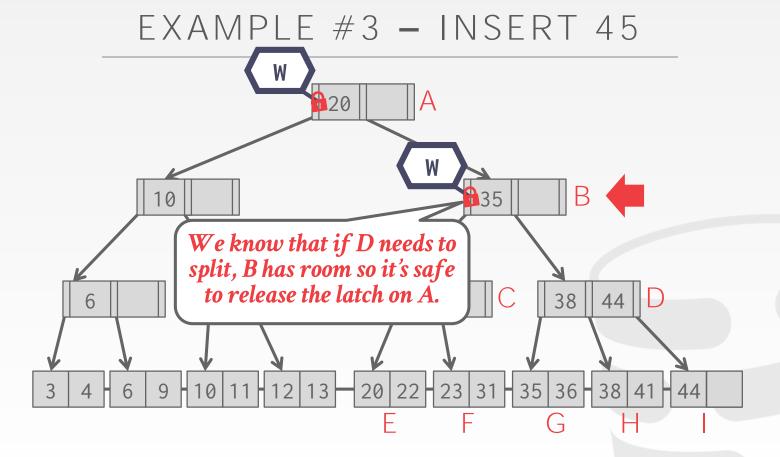
EXAMPLE #2 - DELETE 38



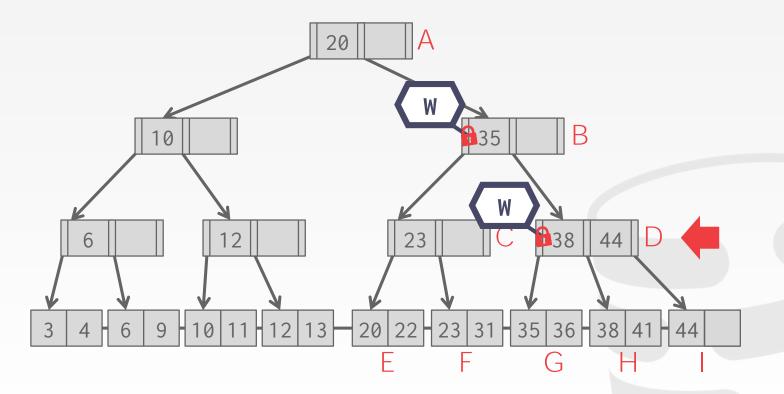




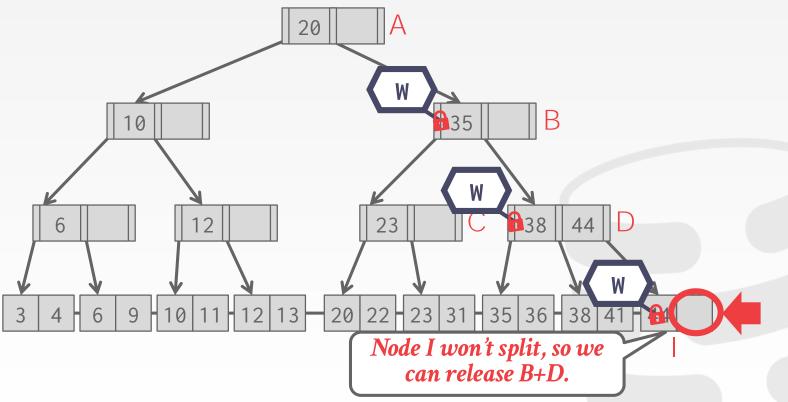




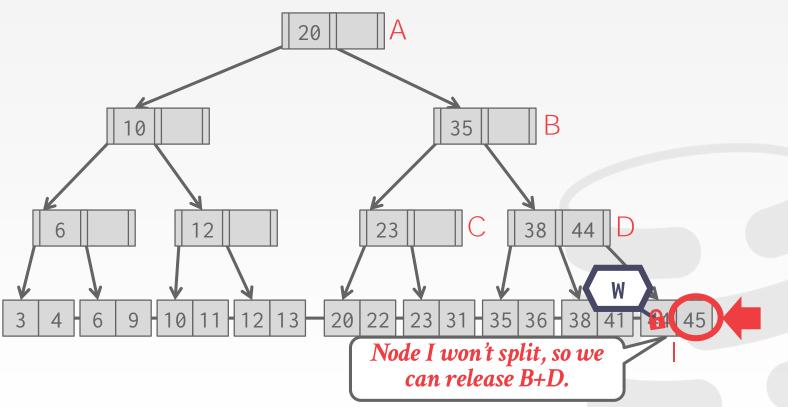




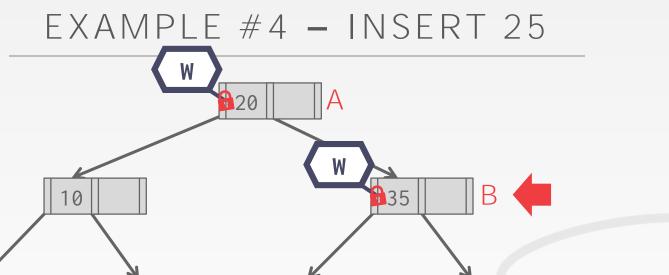








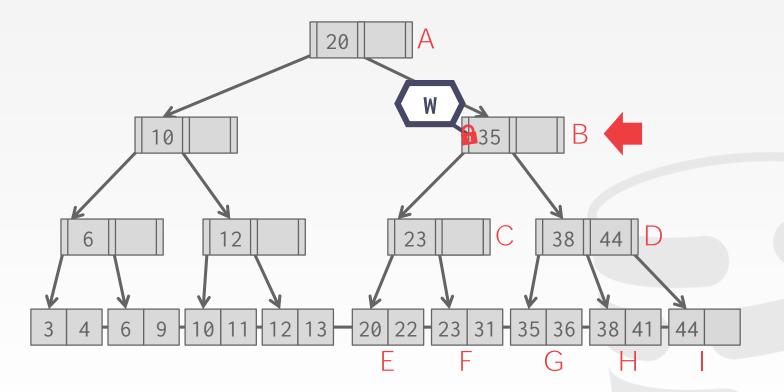




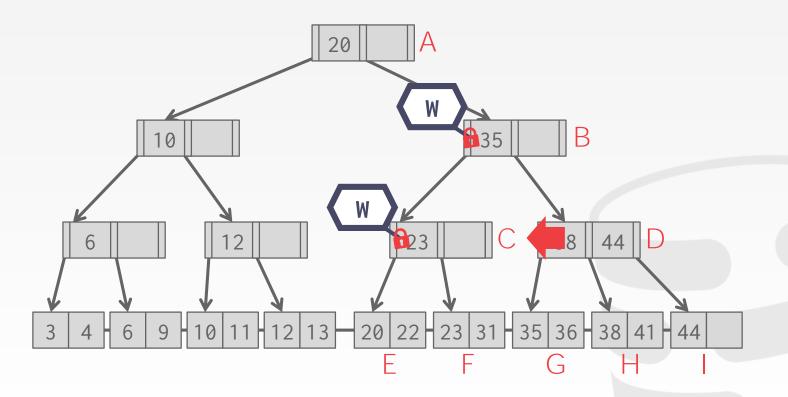
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35 | 36 |

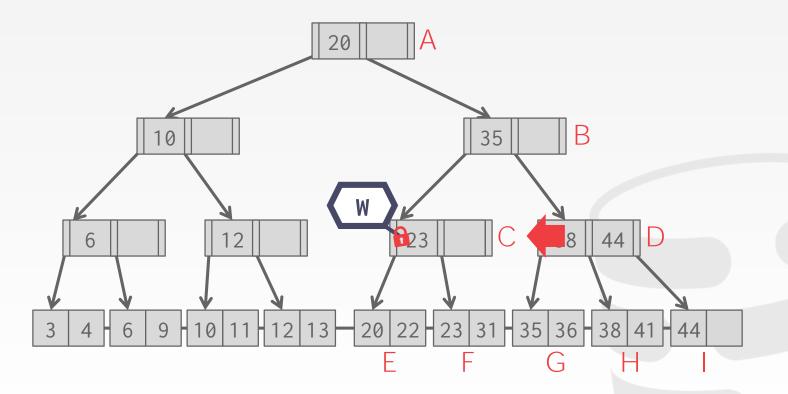




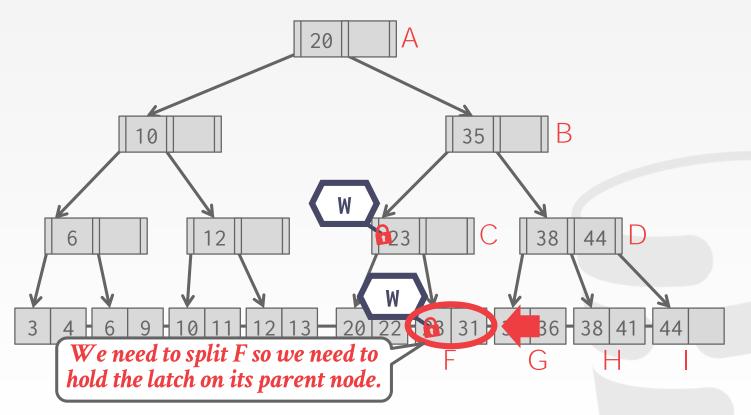




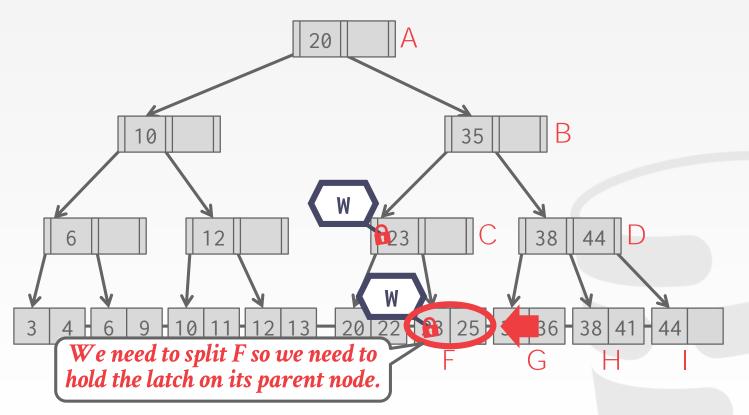




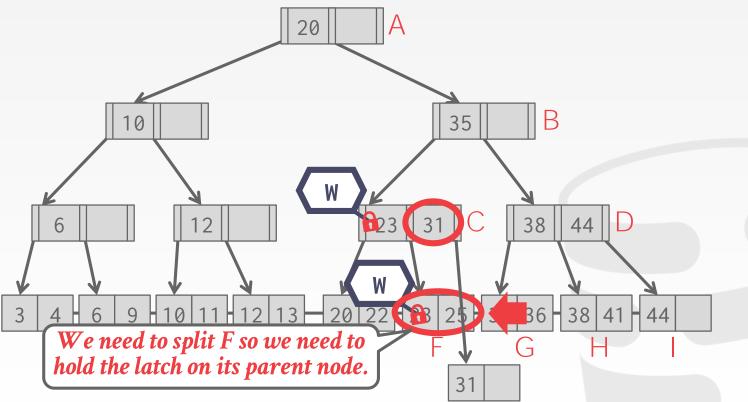








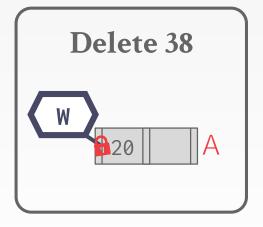


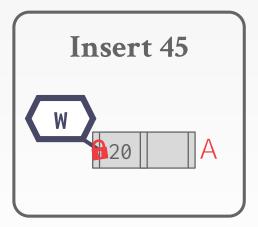


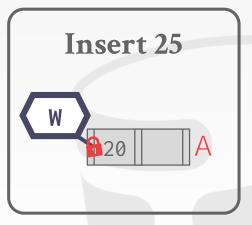


OBSERVATION

What was the first step that all the update examples did on the B+Tree?









OBSERVATION

What was the first step that all the update examples did on the B+Tree?

Taking a write latch on the root every time becomes a bottleneck with higher concurrency.

Can we do better?



BETTER LATCHING ALGORITHM

Assume that the leaf node is safe.

Use read latches and crabbing to reach it, and then verify that it is safe.

If leaf is not safe, then do previous algorithm using write latches.

Make an optimistic assumption that most threads are not going to do split / merge on leaf nodes

Acta Informatica 9, 1-21 (1977)



Concurrency of Operations on B-Trees

R. Bayer* and M. Schkolnick

IBM Research Laboratory, San José, CA 95193, USA

Summary. Concurrent operations on B-trees pose the problem of insuring that each operation can be carried out without interfering with other operations being performed simultaneously by other users. This problem can become critical if these structures are being used to support access paths, like indexes, to data base systems. In this case, serializing access to one of these indexes can create an unacceptable bottleneck for the entire system. Thus, there is a need for locking protocols that can assure integrity for each access while at the same time providing a maximum possible degree of concurrency. Another feature required from these protocols is that they be deadlock free, since the cost to resolve a deadlock may be high.

Recently, there has been some questioning on whether B-tree structures can support concurrent operations. In this paper, we examine the problem of concurrent access to B-trees. We present a deadlock free solution which can be tuned to specific requirements. An analysis is presented which allows the selection of parameters so as to satisfy these requirements.

The solution presented here uses simple locking protocols. Thus, we conclude that B-trees can be used advantageously in a multi-user environment.

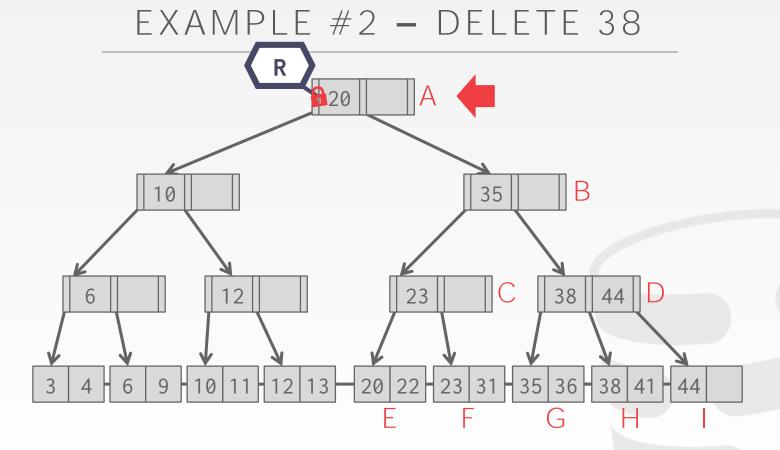
1. Introduction

In this paper, we examine the problem of concurrent access to indexes which are maintained as B-trees. This type of organization was introduced by Bayer and McCreight [2] and some variants of it appear in Knuth [10] and Wedekind [13]. Performance studies of it were restricted to the single user environment. Recently, these structures have been examined for possible use in a multi-user (concurrent) environment. Some initial studies have been made about the feasibility of their use in this type of situation [1, 6], and [11].

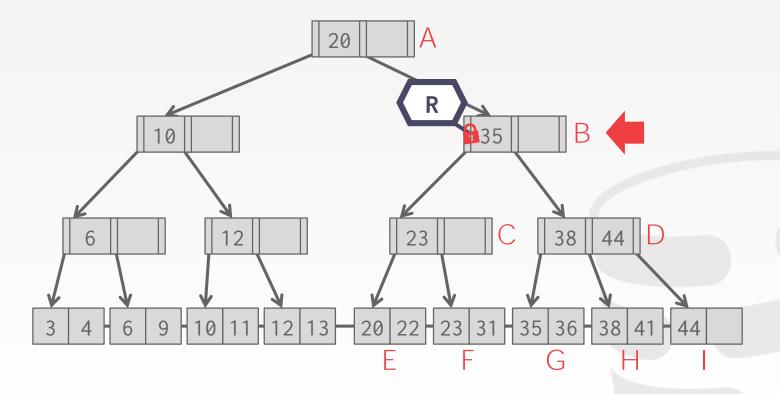
An accessing schema which achieves a high degree of concurrency in using the index will be presented. The schema allows dynamic tuning to adapt its performance to the profile of the current set of users. Another property of the

Permanent address: Institut f
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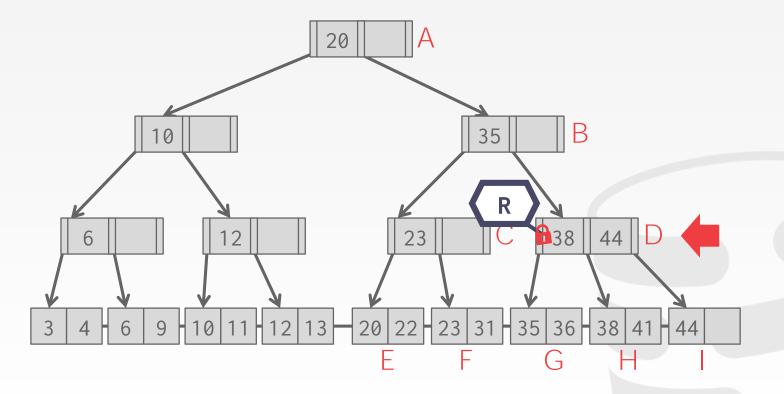




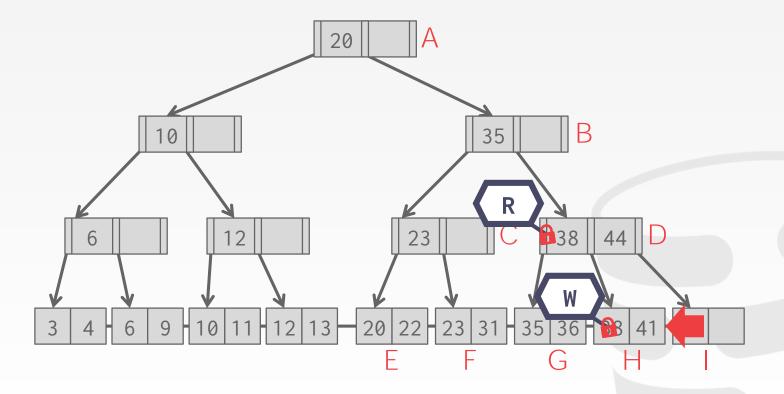




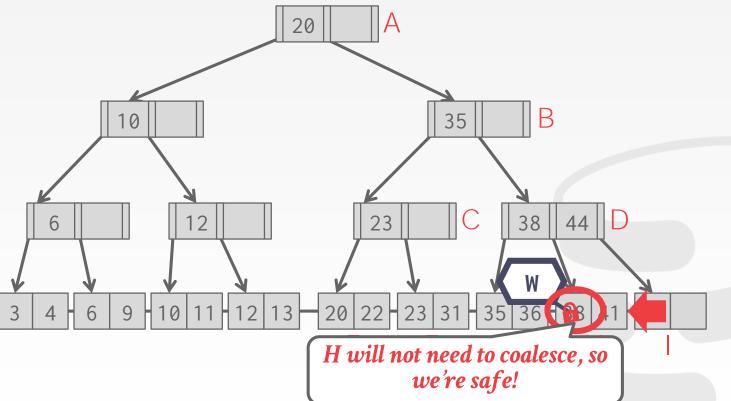




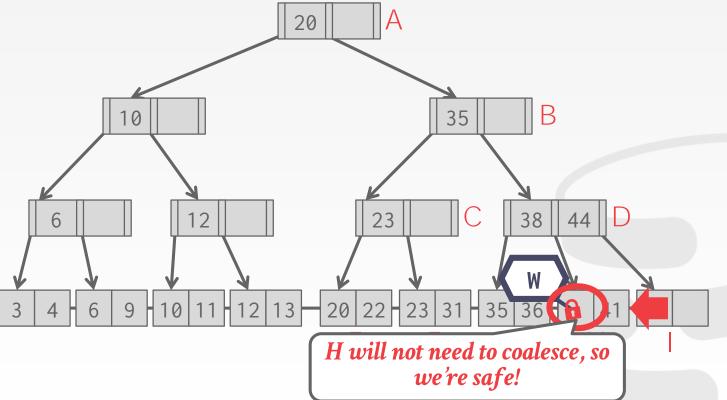




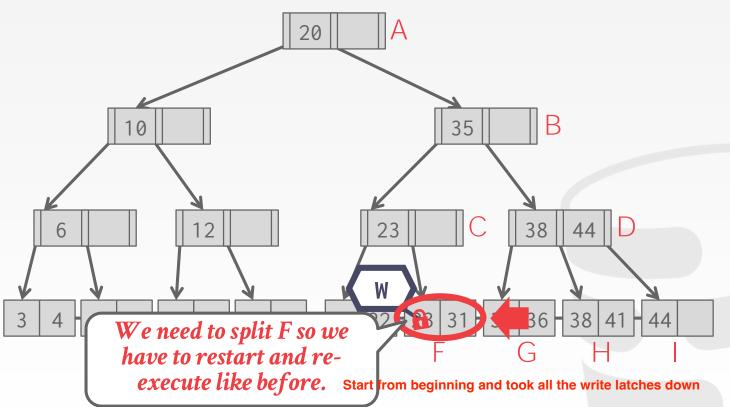














BETTER LATCHING ALGORITHM

Search: Same as before.

Insert/Delete:

- → Set latches as if for search, get to leaf, and set W latch on leaf.
- → If leaf is not safe, release all latches, and restart thread using previous insert/delete protocol with write latches.

This approach optimistically assumes that only leaf node will be modified; if not, R latches set on the first pass to leaf are wasteful.



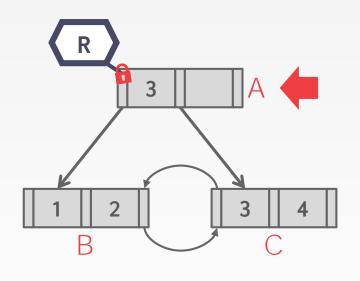
OBSERVATION

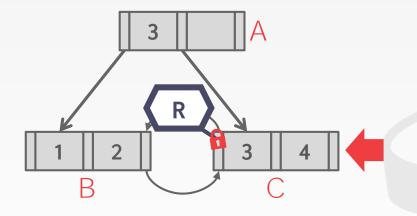
The threads in all the examples so far have acquired latches in a "top-down" manner.

- → A thread can only acquire a latch from a node that is below its current node.
- → If the desired latch is unavailable, the thread must wait until it becomes available.

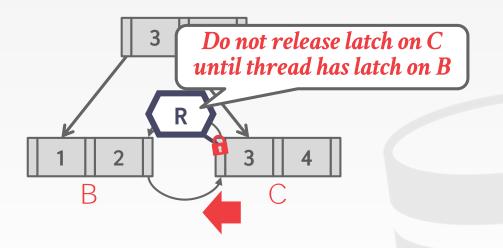
But what if we want to move from one leaf node to another leaf node?



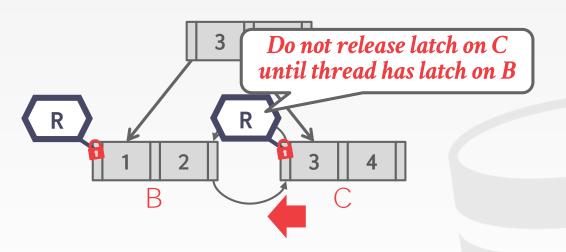




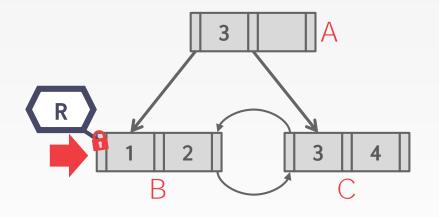




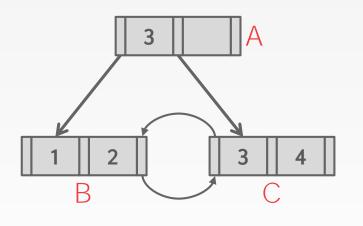






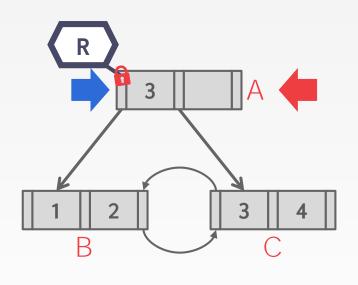






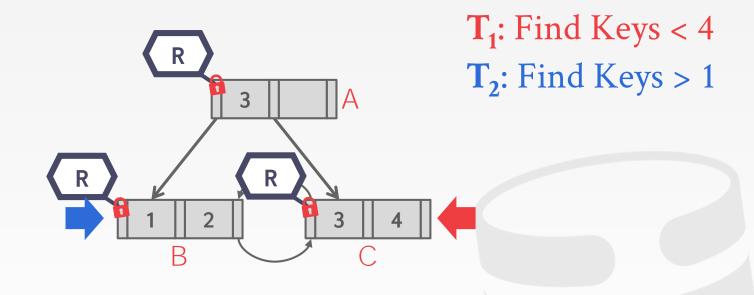
 T_1 : Find Keys < 4

 T_2 : Find Keys > 1



 T_1 : Find Keys < 4

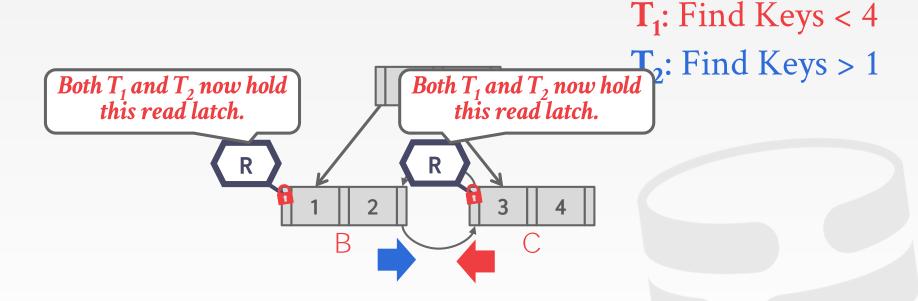
 T_2 : Find Keys > 1



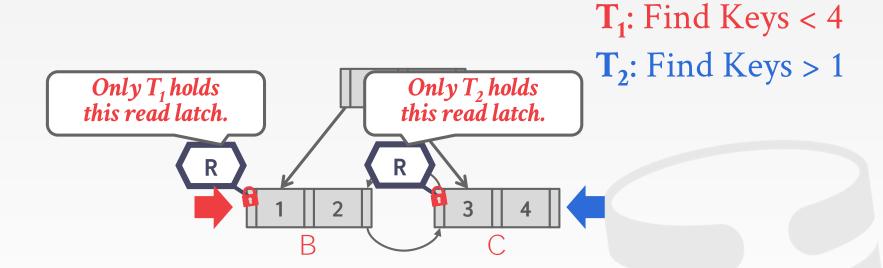


 T_1 : Find Keys < 4 T_2 : Find Keys > 1

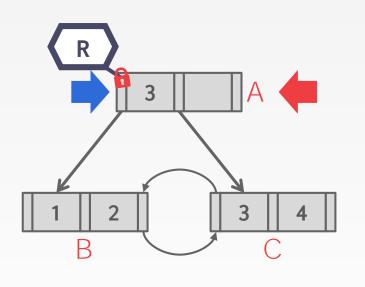




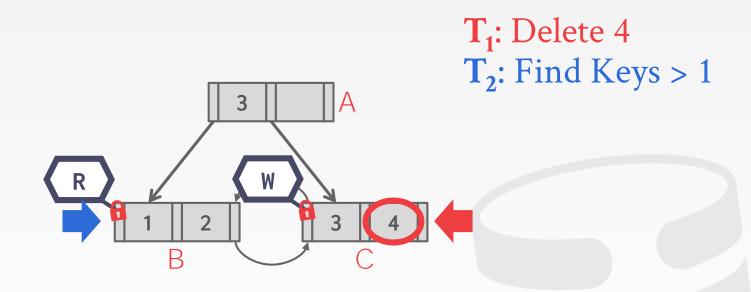




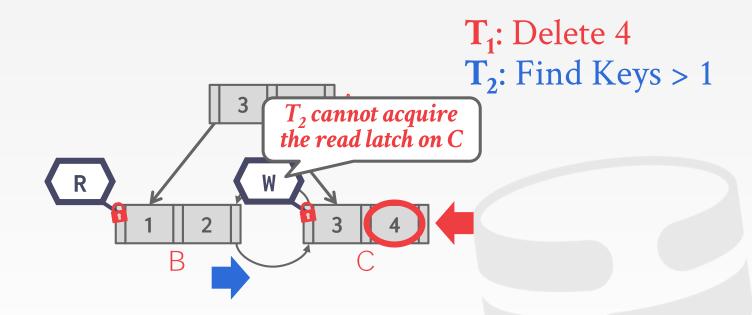




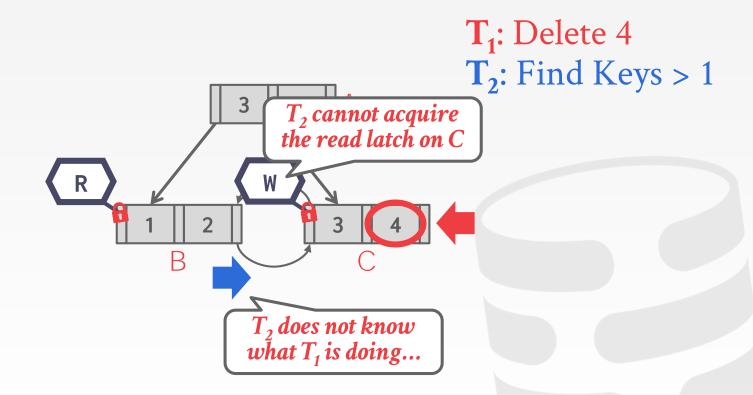
T₁: Delete 4 T₂: Find Keys > 1



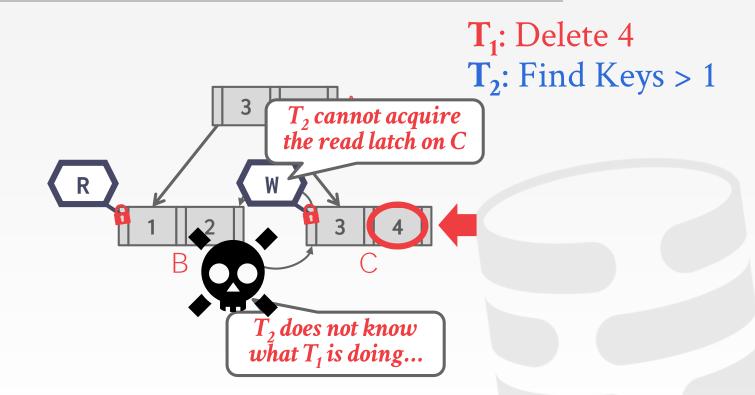














LEAF NODE SCANS

Latches do <u>not</u> support deadlock detection or avoidance. The only way we can deal with this problem is through coding discipline.

The leaf node sibling latch acquisition protocol must support a "no-wait" mode.

The DBMS's data structures must cope with failed latch acquisitions.



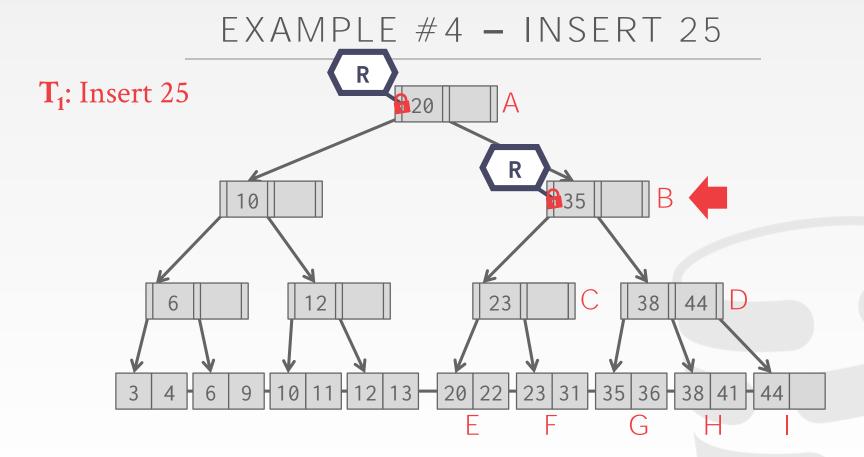
DELAYED PARENT UPDATES

Every time a leaf node overflows, we must update at least three nodes.

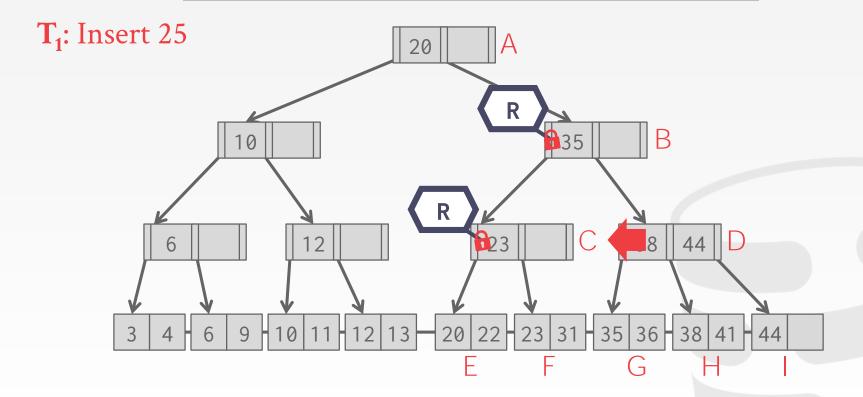
- \rightarrow The leaf node being split.
- \rightarrow The new leaf node being created.
- \rightarrow The parent node.

B^{link}-**Tree Optimization:** When a leaf node overflows, delay updating its parent node.

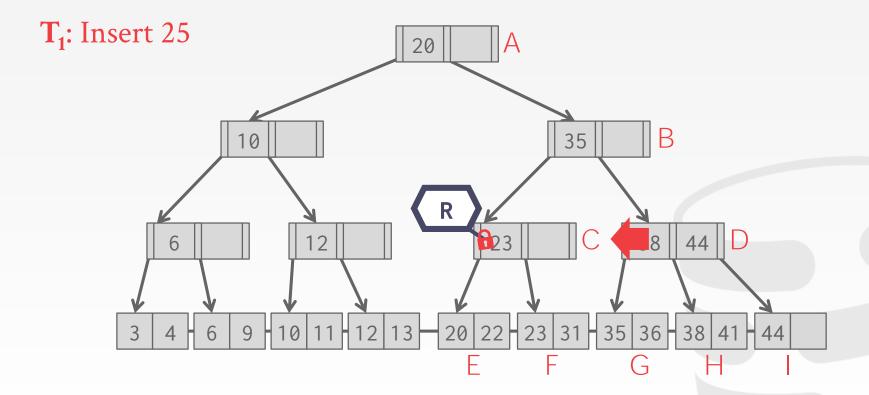




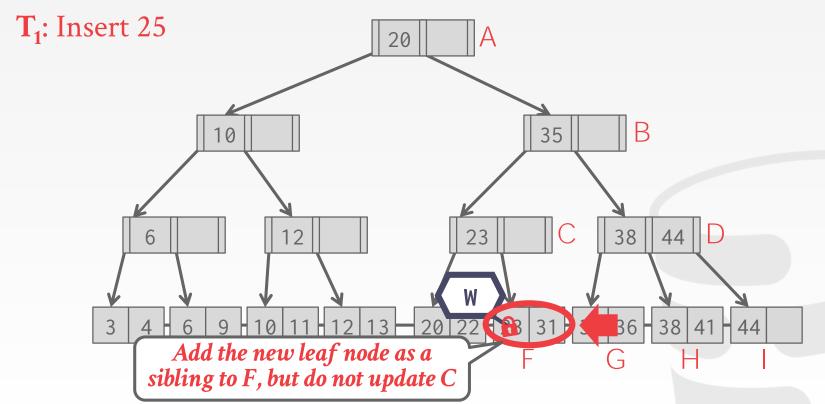




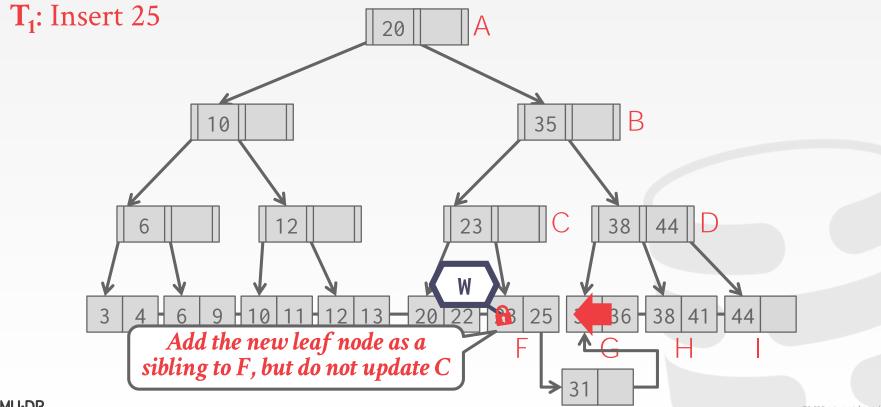




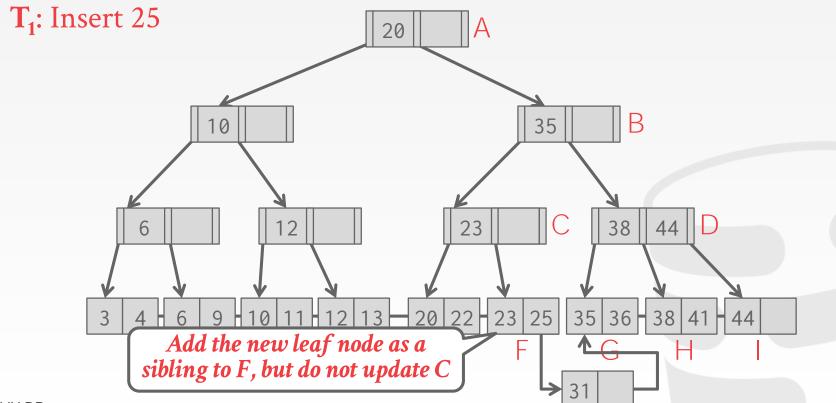




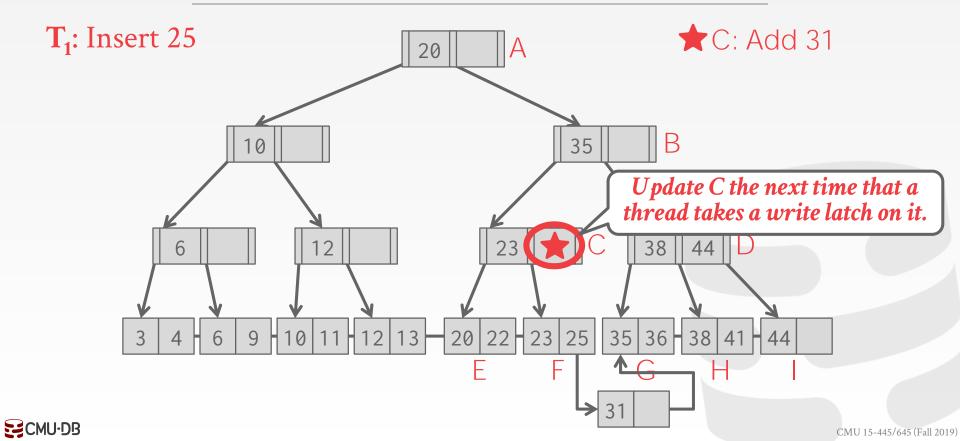


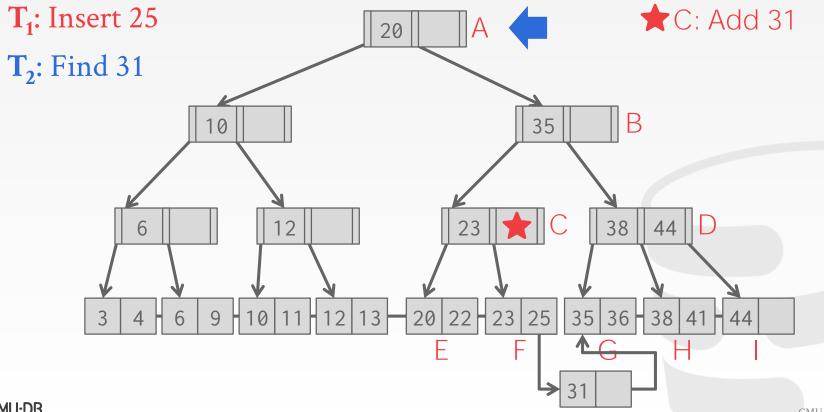




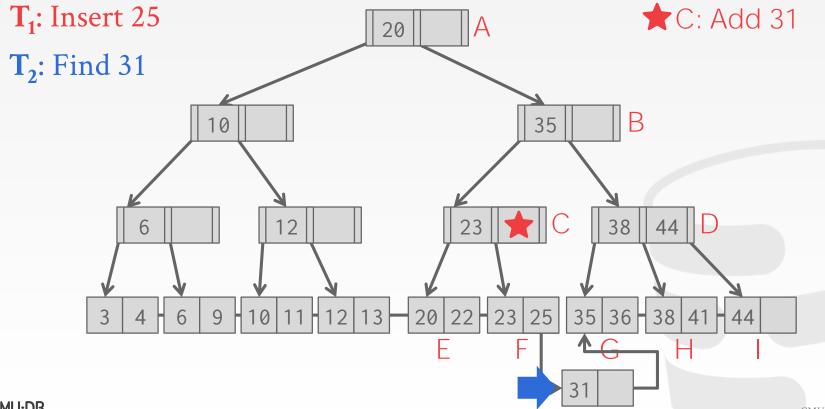




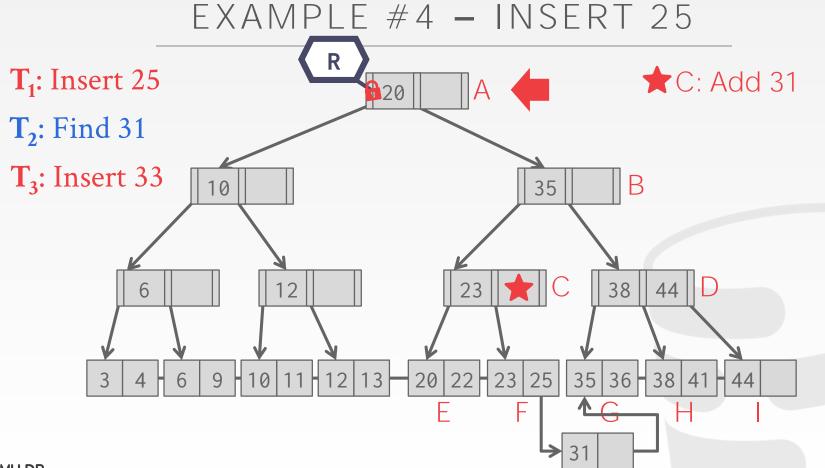




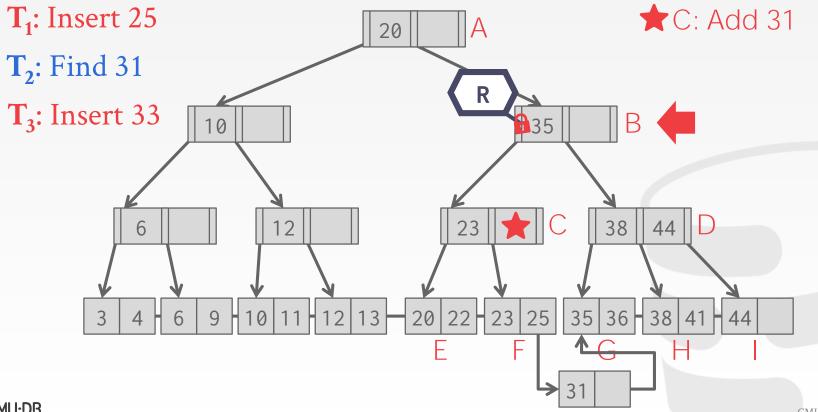




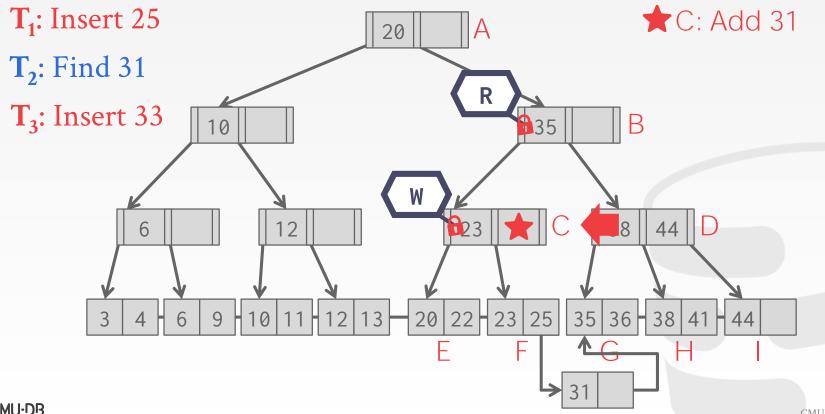




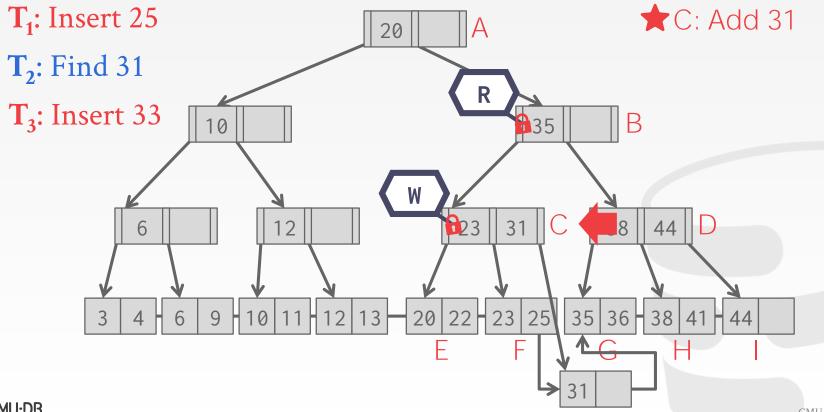




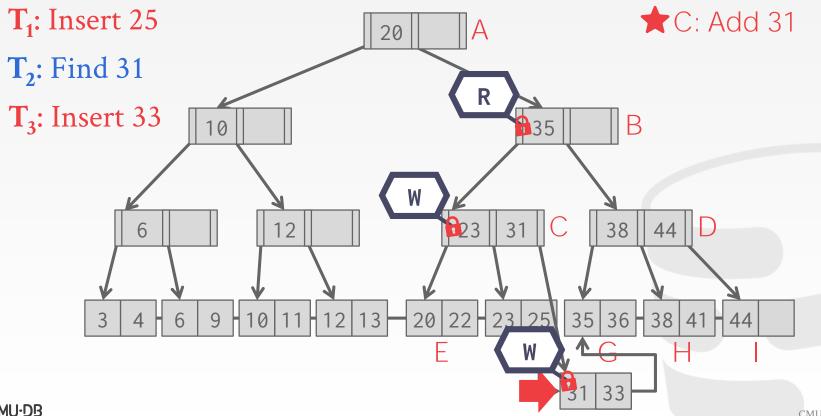














CONCLUSION

Making a data structure thread-safe is notoriously difficult in practice.

We focused on B+Trees but the same high-level techniques are applicable to other data structures.



NEXT CLASS

We are finally going to discuss how to execute some queries...

