

COMP S265F Design and Analysis of Algorithms
Lab 12: Finite Automata and Regular Expressions

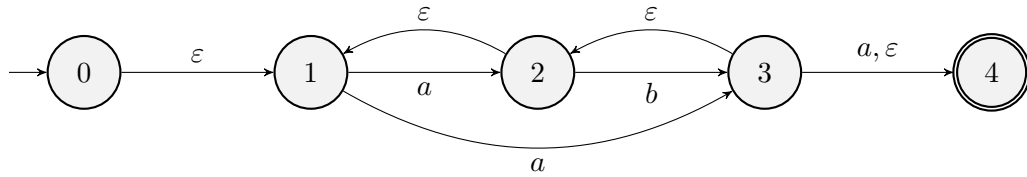
1 From NFA with ε moves to DFA

Given a NFA M_ε with ε moves, we can construct a DFA M_D using the subset construction technique, where each state of the DFA corresponds to a subset of states in the NFA. A challenge is that state transition may happen by some ε moves.

1.1 Lambda closure of a state

Given the NFA transition function f_ε , we can define the *lambda closure* $\lambda(s)$ of a state s to be the set of states which can be reached from s by zero or more ε moves (without consuming any input). More precisely, for any state s in M_ε , $s \in \lambda(s)$; if $p \in \lambda(s)$ and there is an ε move from p to q , then $q \in \lambda(s)$.

For example, the following NFA with ε moves has the transition table f_ε below:



f_ε	s	a	b	ε	$\lambda(s)$
start	0	\emptyset	\emptyset	$\{1\}$	
	1	$\{2, 3\}$	\emptyset	\emptyset	
	2	\emptyset	$\{3\}$	$\{1\}$	
final	3	$\{4\}$	\emptyset	$\{2, 4\}$	
	4	\emptyset	\emptyset	\emptyset	

Then, we can fill in the lambda closures of states 0, 1, 2, 3, 4, as follows:

- At a state s without any ε moves (i.e., $f_\varepsilon(s, \varepsilon) = \emptyset$), we can only stay there, so $\lambda(s) = \{s\}$.
In the example, $\lambda(1) = \{1\}$, $\lambda(4) = \{4\}$.
- At a state s' with ε moves to a state s in the previous step, $\lambda(s')$ includes s' and the lambda closure $\lambda(s)$.
In the example, $\lambda(0) = \{0\} \cup \lambda(1) = \{0, 1\}$, $\lambda(2) = \{2\} \cup \lambda(1) = \{1, 2\}$.
- The other steps continue similarly.
In the example, $\lambda(3) = \{3\} \cup \lambda(2) \cup \lambda(4) = \{1, 2, 3, 4\}$.

The completed transition table f_ε with lambda closures is:

f_ε	s	a	b	ε	$\lambda(s)$
start	0	\emptyset	\emptyset	$\{1\}$	$\{0, 1\}$
	1	$\{2, 3\}$	\emptyset	\emptyset	$\{1\}$
	2	\emptyset	$\{3\}$	$\{1\}$	$\{1, 2\}$
final	3	$\{4\}$	\emptyset	$\{2, 4\}$	$\{1, 2, 3, 4\}$
	4	\emptyset	\emptyset	\emptyset	$\{4\}$

We also extend the definition of lambda closure for a set of states:

$$\lambda(\{s_1, s_2, \dots, s_n\}) = \lambda(s_1) \cup \lambda(s_2) \cup \dots \cup \lambda(s_n) .$$

For example, $\lambda(\{2, 3\}) = \lambda(2) \cup \lambda(3) = \{1, 2, 3, 4\}$.

1.2 Construction steps

The construction of the transition function f_D of the DFA can be done, as follows:

Step 1. The DFA start state is $\lambda(s)$, where s is the NFA start state. It is also a DFA final state if $\lambda(s)$ contains any NFA final state.

Step 2. If $\{s_1, s_2, \dots, s_n\}$ is a DFA state and $a \in \Sigma$, then construct a next DFA state in either way below:

- **Closure of union:**

$$f_D(\{s_1, s_2, \dots, s_n\}, a) = \lambda(f_\varepsilon(s_1, a) \cup f_\varepsilon(s_2, a) \cup \dots \cup f_\varepsilon(s_n, a)) , \text{ or}$$

- **Union of closure:**

$$f_D(\{s_1, s_2, \dots, s_n\}, a) = \lambda(f_\varepsilon(s_1, a)) \cup \lambda(f_\varepsilon(s_2, a)) \cup \dots \cup \lambda(f_\varepsilon(s_n, a)) .$$

Step 3. If the next states in Step 2 are new DFA states, add them to the DFA table.

A new DFA state is a final state if its set contains a NFA final state.

Repeat Step 2 for these new DFA states.

Continuing on the previous example, we complete the DFA transition table f_D row by row, as follows:

- Step 1:

$$\text{start state} = \lambda(0) = \{0, 1\}$$

- Step 2 on state $\{0, 1\}$:

$$\begin{aligned} f_D(\{0, 1\}, a) &= \lambda(f_\varepsilon(0, a)) \cup \lambda(f_\varepsilon(1, a)) \quad (\text{union of closure}) \\ &= \lambda(\emptyset) \cup \lambda(\{2, 3\}) \\ &= \lambda(2) \cup \lambda(3) = \{1, 2\} \cup \{1, 2, 3, 4\} = \{1, 2, 3, 4\} \end{aligned}$$

Therefore, we have the following table:

	f_D	a	b
start	$\{0, 1\}$	$\{1, 2, 3, 4\}$	\emptyset

- Step 3:

There are two new states: $\{1, 2, 3, 4\}$ and \emptyset .

$\{1, 2, 3, 4\}$ is also a DFA final state, as 4 is a NFA final state.

- Step 2 on state $\{1, 2, 3, 4\}$ (and on state \emptyset , which is trivial):

$$\begin{aligned} f_D(\{1, 2, 3, 4\}, a) &= \lambda(f_\varepsilon(1, a) \cup f_\varepsilon(2, a) \cup f_\varepsilon(3, a) \cup f_\varepsilon(4, a)) \quad (\text{closure of union}) \\ &= \lambda(\emptyset \cup \{2, 3\} \cup \emptyset \cup \{4\}) = \lambda(\{2, 3, 4\}) \\ &= \lambda(2) \cup \lambda(3) \cup \lambda(4) = \{1, 2\} \cup \{1, 2, 3, 4\} \cup \{4\} = \{1, 2, 3, 4\} \\ f_D(\{1, 2, 3, 4\}, b) &= \lambda(f_\varepsilon(1, b) \cup f_\varepsilon(2, b) \cup f_\varepsilon(3, b) \cup f_\varepsilon(4, b)) \quad (\text{closure of union}) \\ &= \lambda(\{3\}) \\ &= \{1, 2, 3, 4\} \end{aligned}$$

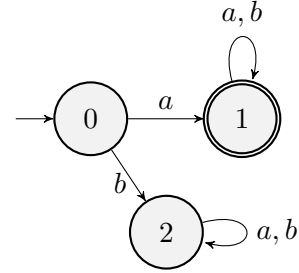
Therefore, we have the following table:

	f_D	a	b
start	$\{0, 1\}$	$\{1, 2, 3, 4\}$	\emptyset
final	$\{1, 2, 3, 4\}$	$\{1, 2, 3, 4\}$	$\{1, 2, 3, 4\}$
	\emptyset	\emptyset	\emptyset

1.3 Renaming the states

For clarity of presentation, we can assign a unique name to each DFA state. In the previous example, the renamed transition table f_D and the resultant DFA are shown below:

f_D	s	a	b
start	0	1	2
final	1	1	1
	2	2	2



1.4 Reducing the number of states

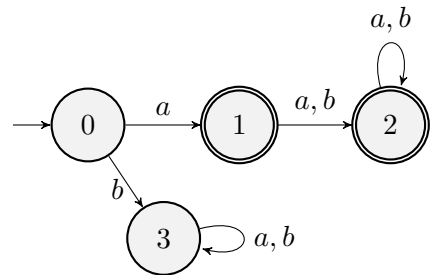
Sometimes, we can easily observe unnecessary states in our solution and can reduce the number of states:

If two states are **both final** or **both non-final**, and their transitions for all inputs are exactly the same, these two states can be merged as one state.

Note that if one of these two states is a start state, the merged state is also a start state.

Consider the following example:

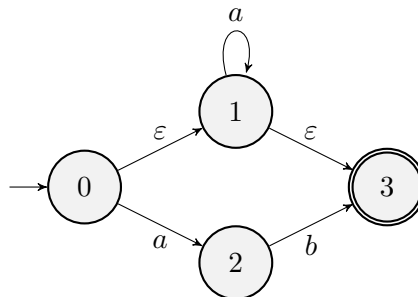
f_D	s	a	b
start	0	1	3
final	1	2	2
final	2	2	2
	3	3	3



We can merge states 1 and 2 to a merged state (named state 1), and rename state 3 to state 2. Then the resultant DFA is the same as the DFA in Section 1.3.

1.5 Example

Example 1. Transform the following NFA with ε moves to a DFA:



Solution. The transition table f_ε for the NFA with lambda closures is:

f_ε	s	a	b	ε	$\lambda(s)$
start	0	$\{2\}$	\emptyset	$\{1\}$	$\{0, 1, 3\}$
	1	$\{1\}$	\emptyset	$\{3\}$	$\{1, 3\}$
	2	\emptyset	$\{3\}$	\emptyset	$\{2\}$
final	3	\emptyset	\emptyset	\emptyset	$\{3\}$

Now, we construct the transition table f_D of the DFA, as follows:

- start state = $\lambda(0) = \{0, 1, 3\}$ (also final state as it contains NFA final state 3)
- $f_D(\{0, 1, 3\}, a) = \lambda(f_\varepsilon(0, a) \cup f_\varepsilon(1, a) \cup f_\varepsilon(3, a))$ (closure of union)
 $= \lambda(\{1, 2\})$
 $= \{1, 2, 3\}$
- $f_D(\{0, 1, 3\}, b) = \lambda(f_\varepsilon(0, b) \cup f_\varepsilon(1, b) \cup f_\varepsilon(3, b))$ (closure of union)
 $= \lambda(\emptyset)$
 $= \emptyset$

Therefore, we have the following table:

	f_D	a	b
start, final	$\{0, 1, 3\}$	$\{1, 2, 3\}$	\emptyset

- There are two new states: $\{1, 2, 3\}$ (final state as it contains NFA final state 3) and \emptyset .
- $f_D(\{1, 2, 3\}, a) = \lambda(f_\varepsilon(1, a) \cup f_\varepsilon(2, a) \cup f_\varepsilon(3, a))$ (closure of union)
 $= \lambda(\{1\})$
 $= \{1, 3\}$
- $f_D(\{1, 2, 3\}, b) = \lambda(f_\varepsilon(1, b) \cup f_\varepsilon(2, b) \cup f_\varepsilon(3, b))$ (closure of union)
 $= \lambda(\{3\})$
 $= \{3\}$

Therefore, we have the following table:

	f_D	a	b
start, final	$\{0, 1, 3\}$	$\{1, 2, 3\}$	\emptyset
final	$\{1, 2, 3\}$	$\{1, 3\}$	$\{3\}$
	\emptyset	\emptyset	\emptyset

- There are two new final states (as they contain NFA final state 3): $\{1, 3\}$ and $\{3\}$.
- $f_D(\{1, 3\}, a) = \lambda(f_\varepsilon(1, a) \cup f_\varepsilon(3, a))$ (closure of union)
 $= \lambda(\{1\})$
 $= \{1, 3\}$
- $f_D(\{1, 3\}, b) = \lambda(f_\varepsilon(1, b) \cup f_\varepsilon(3, b))$ (closure of union)
 $= \lambda(\emptyset)$
 $= \emptyset$

Therefore, we have the following table:

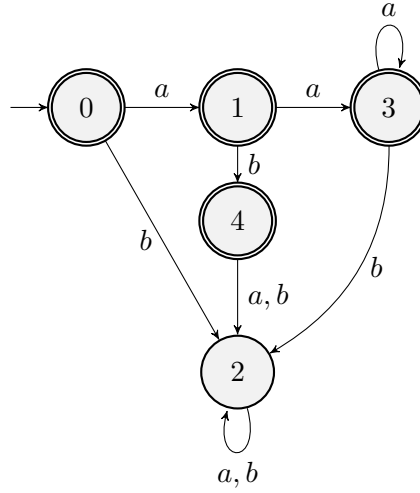
	f_D	a	b
start, final	$\{0, 1, 3\}$	$\{1, 2, 3\}$	\emptyset
final	$\{1, 2, 3\}$	$\{1, 3\}$	$\{3\}$
	\emptyset	\emptyset	\emptyset
final	$\{1, 3\}$	$\{1, 3\}$	\emptyset
final	$\{3\}$	\emptyset	\emptyset

- We rename the five states to 0, 1, 2, 3, 4:

	f_D	a	b
start, final	0	1	2
final	1	3	4
	2	2	2
final	3	3	2
final	4	2	2

- States 2 and 4 have the same transitions for all inputs, but state 2 is non-final while state 4 is final. Therefore, we cannot merge these two states.

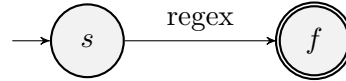
As a result, we obtain the following DFA:



2 From regular expression to NFA with ε moves

2.1 The four rules

Given a regular expression, we can construct the corresponding NFA with ε moves by starting with a start state, a single final state, and an edge labeled with the given regular expression (regex):



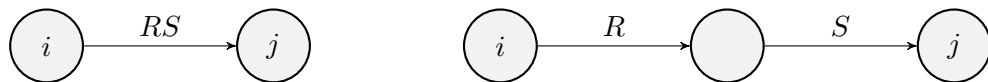
Then, we can repeatedly apply the following rules until all edges are labeled with an input symbol or ε :

Rule 1. If an edge is labeled with \emptyset , then remove the edge.

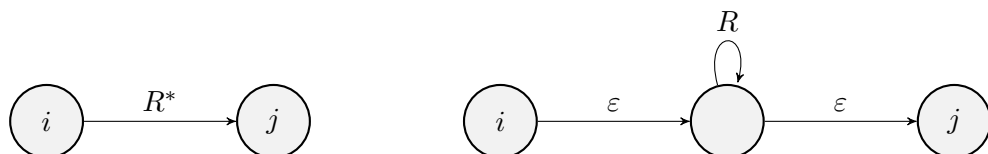
Rule 2. Transform the diagram on the left to that on the right:



Rule 3. Transform the diagram on the left to that on the right:



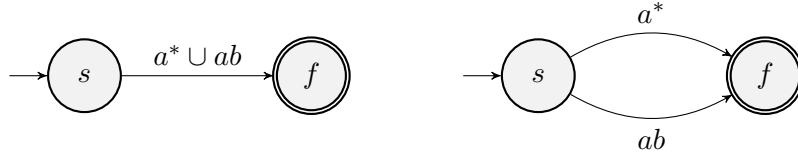
Rule 4. Transform the diagram on the left to that on the right:



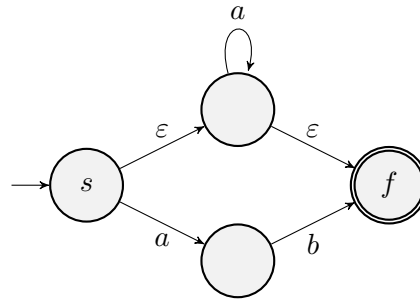
2.2 Example

Example 2. Construct an NFA with ε moves for the regular expression $a^* \cup ab$.

Solution. We start with the diagram on the left. Next, we can apply Rule 2 to obtain the diagram on the right:

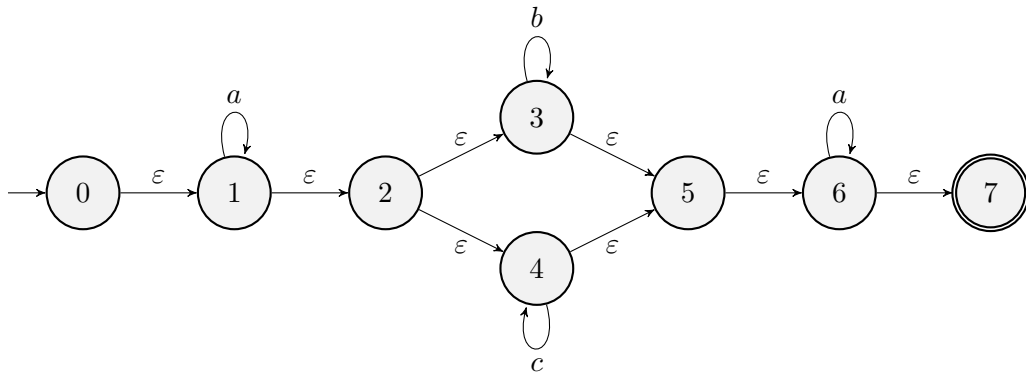


Then, we apply Rule 4 on the upper edge, and Rule 3 on the lower edge to obtain the following answer:



3 Exercises

Question 1. Let $\Sigma = \{a, b, c\}$. Consider the following NFA with ε moves:



- (i) Write down the transition table of the above NFA including the lambda closure of the states.
- (ii) Transform the above NFA to a DFA. Write down the transition table of the DFA.
- (iii) Reduce the number of states of the DFA in (ii), and write down the new transition table.
- (iv) Draw the diagram of the DFA in (iii).

Question 2. A *regular* language is a language that can be described by a regular expression. Using the pumping lemma to prove that the following languages are not regular:

- (i) $L = \{a^n b c^n \mid n \in \mathbb{N}\}$
- (ii) $M = \{a^m b^n \mid m, n \in \mathbb{N} \text{ and } |m - n| < 10\}$

Question 3. Let $\Sigma = \{a, b, c\}$. Construct a NFA with ε moves for the regular expression

$$a^*(b^* \cup c^*)a^*$$