# COMPSCI 589
# Lecture 9: KNN Regression, Regression Trees, and Feature Selection

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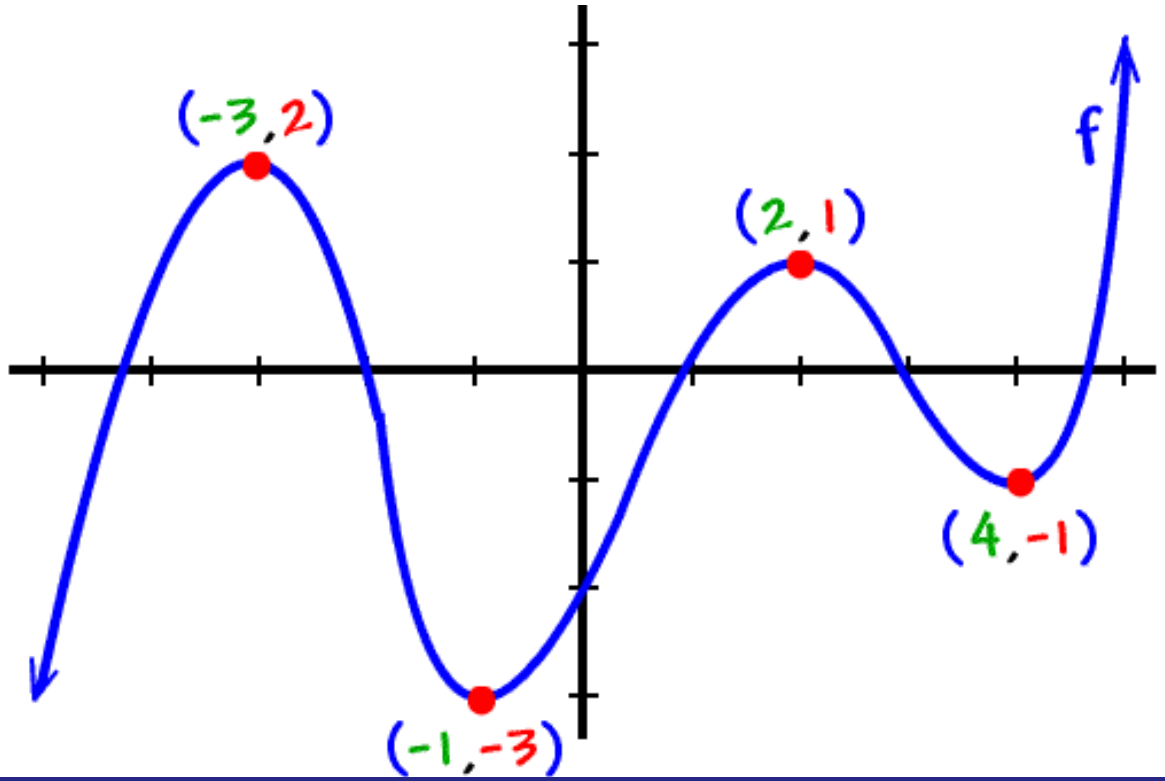
# The Regression Task

## Definition: The Regression Task

Given a feature vector $\mathbf{x} \in \mathbb{R}^D$, predict it's corresponding output value $y$.



# The Regression Learning Problem

## Definition: Regression Learning Problem

Given a data set of example pairs $\mathcal{D} = \{(\mathbf{x}_i, y_i), i = 1 : N\}$ where $\mathbf{x}_i \in \mathbb{R}^D$ is a feature vector and $y_i \in \mathbb{R}$ is the output, learn a function $f : \mathbb{R}^D \rightarrow \mathbb{R}$ that accurately predicts $y$ for any feature vector $\mathbf{x}$.

# Error Measures: MSE

## Definition: Mean Squared Error

Given a data set of example pairs $\mathcal{D} = \{(\mathbf{x}_i, y_i), i = 1 : N\}$ and a function $f : \mathbb{R}^D \to \mathcal{Y}$, the mean squared error of $f$ on $\mathcal{D}$ is:

$$MSE(f, \mathcal{D}) = \frac{1}{N} \sum_{i=1}^{N} (y_i - f(\mathbf{x}_i))^2$$

Related measures include:
Sum of Squared Errors: $SSE(f, \mathcal{D}) = N \cdot MSE(f, \mathcal{D})$
Risidual Sum of Squares: $RSS(f, \mathcal{D}) = N \cdot MSE(f, \mathcal{D})$
Root Mean Squared Error: $RMSE(f, \mathcal{D}) = \sqrt{MSE(f, \mathcal{D})}$

# K Nearest Neighbors Regression

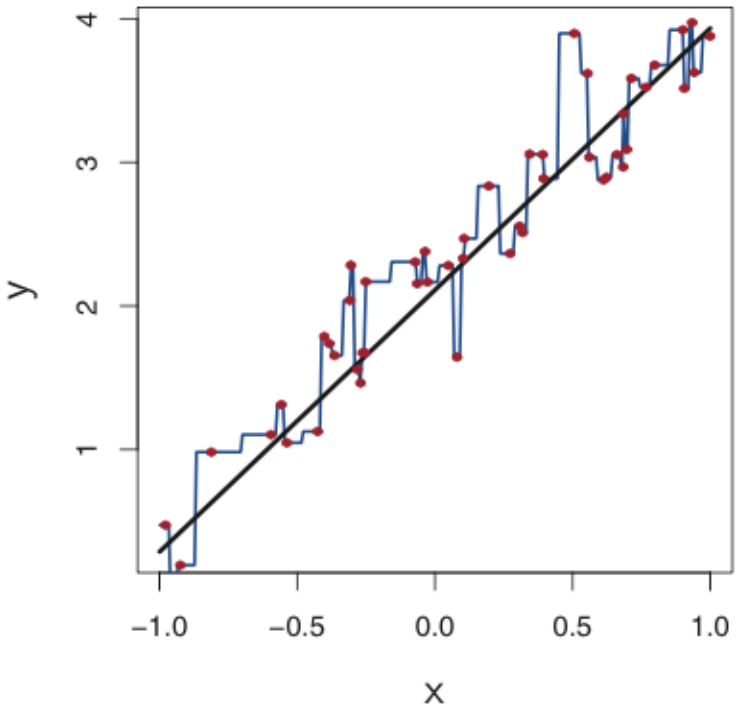
The KNN regression is a non-parametric regression method that simply stores the training data $\mathcal{D}$ and makes a prediction for each new instance $\mathbf{x}$ using an average over it's set of $K$ nearest neighbors $\mathcal{N}_K(\mathbf{x})$ computed using any distance function $d : \mathbb{R}^D \times \mathbb{R}^D \rightarrow \mathbb{R}$.

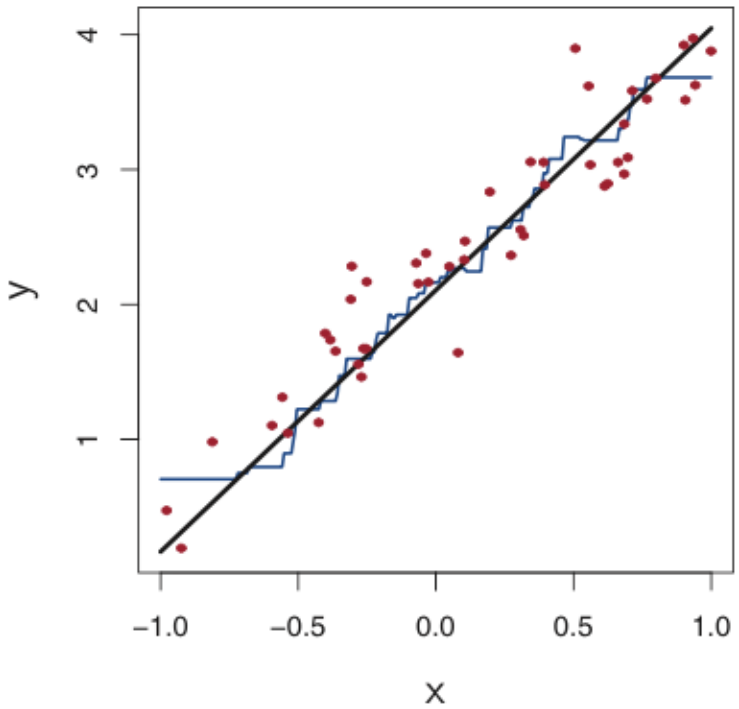
## KNN Regression Function

$$f_{KNN}(\mathbf{x}) = \frac{1}{K} \sum_{i \in \mathcal{N}_K(\mathbf{x})} y_i$$

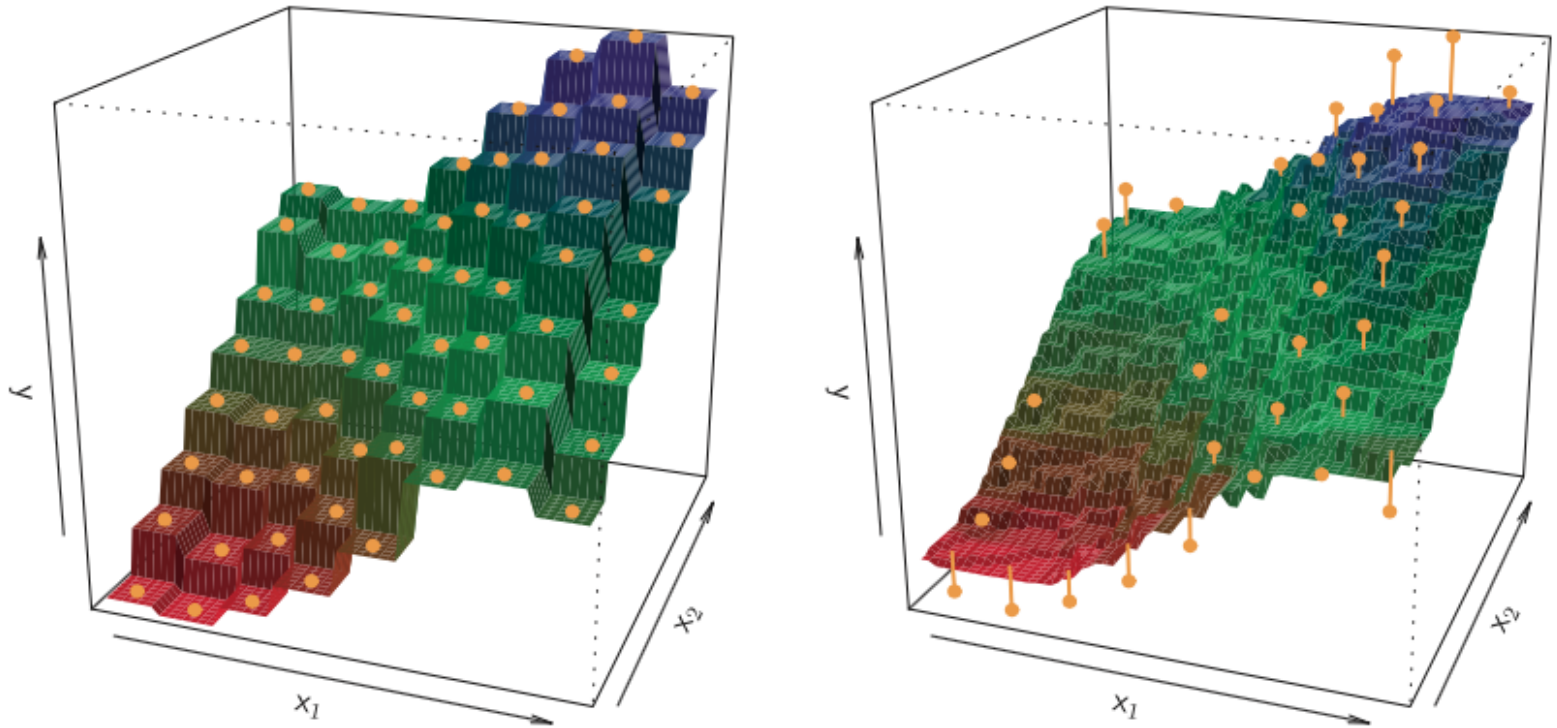
As with classification, use of KNN requires choosing the distance function $d$ and the number of neighbors $K$.

# Example: 1D KNN (K=1 vs K=9)



# Example: 2D KNN (K=1 vs K=9)



# Weighted KNN Regression

- Instead of giving all of the $K$ neighbors equal weight in the average, a distance-weighted average can be used:

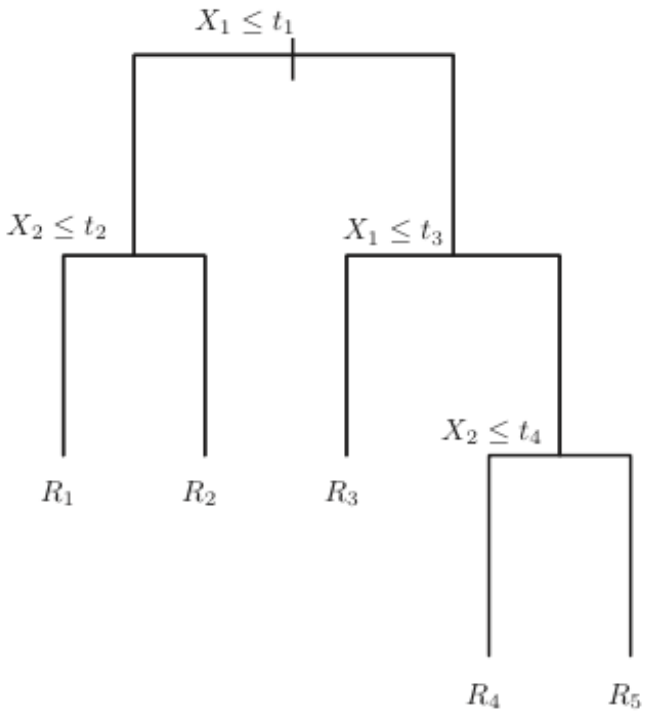
$$f_{KNN}(\mathbf{x}) = \frac{\sum_{i \in \mathcal{N}_K(\mathbf{x})} w_i y_i}{\sum_{i \in \mathcal{N}_K(\mathbf{x})} w_i}$$

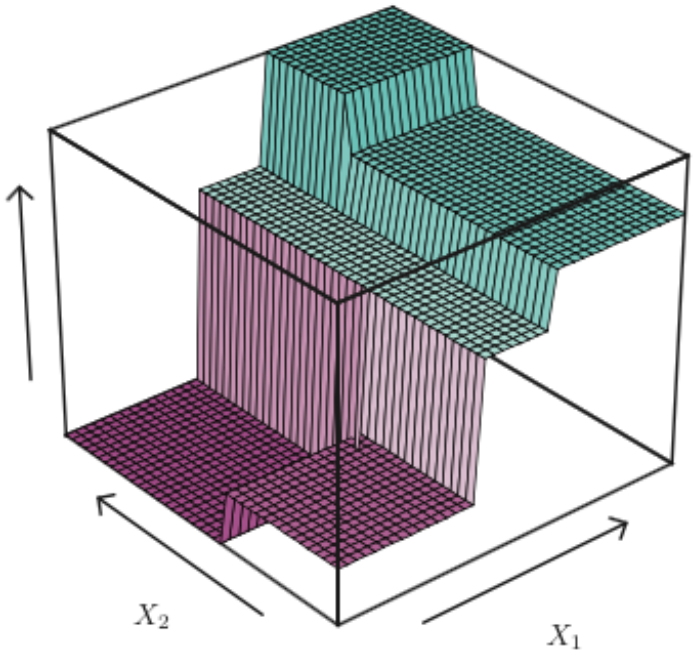
$$w_i = \exp(-\alpha d_i)$$

# Regression Trees

- A regression tree makes predictions using a conjunction of rules organized into a binary tree structure.
- Each internal node in a regression tree contains a rule of the form $(x_d < t)$ or $(x_d = t)$ that tests a single data dimension $d$ against a single threshold value $t$ and assigns the data case to it's left or right sub-tree according to the result.
- A data case is routed through the tree from the root to a leaf. Each leaf node is associated with a predicted output, and a data case is assigned the output of the leaf node it is routed to.

# Example: 2D Regression Trees



# Building Regression Trees

**Algorithm 1** $BuildTree(Root, \mathcal{D}, h, minS, maxD)$

$d, t = BestSplit(\mathcal{D})$
$\mathcal{D}_1 = \{(y_i, \mathbf{x}_i) | x_{di} \leq t\}$, $\mathcal{D}_2 = \{(y_i, \mathbf{x}_i) | x_{di} > t\}$
**if** $|\mathcal{D}_1| <= minS$ or $h + 1 \geq maxD$ **then**
  $Root.RightChild.Prediction = \frac{1}{|\mathcal{D}_1|} \sum_{y \in \mathcal{D}_1} y$
**else**
  $BuildTree(Root.RightChild, \mathcal{D}_1, h + 1, minS, maxD)$
**if** $|\mathcal{D}_2| <= minS$ or $h + 1 \geq maxD$ **then**
  $Root.LeftChild.Prediction = \frac{1}{|\mathcal{D}_2|} \sum_{y \in \mathcal{D}_2} y$
**else**
  $BuildTree(Root.LeftChild, \mathcal{D}_2, h + 1, minS, maxD)$
$Root.d = d$,$Root.t = t$
**return** $Root$

# Finding the Best Split

**Algorithm 2** *BestSplit*($\mathcal{D}$)

**for** $d$ from 1 to $D$ **do**

$\mathbf{s} = sort(\{x_{d1}, ..., x_{dN}\})$

**for** $t$ in $\{(s_i + s_{i+1})/2 | i = 1...N-1\}$ **do**

$\mathcal{D}_1 = \{(y_i, \mathbf{x}_i) | x_{di} \leq t\}$

$\mathcal{D}_2 = \{(y_i, \mathbf{x}_i) | x_{di} > t\}$

$\bar{y}_1 = \frac{1}{|\mathcal{D}_1|} \sum_{y \in \mathcal{D}_1} y$

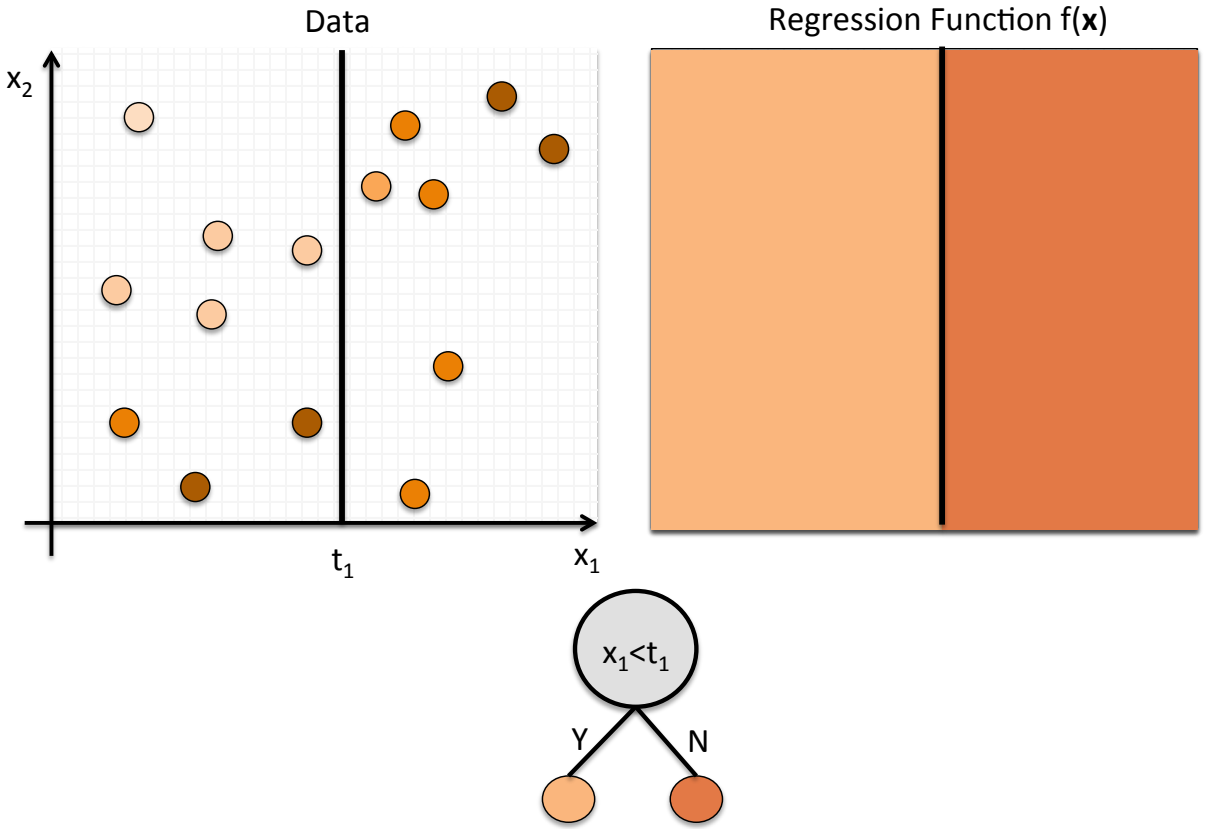
$\bar{y}_2 = \frac{1}{|\mathcal{D}_2|} \sum_{y \in \mathcal{D}_2} y$

$Score(d,t) = \sum_{y \in \mathcal{D}_1} (y - \bar{y}_1)^2 + \sum_{y \in \mathcal{D}_2} (y - \bar{y}_2)^2$

$d, t = \arg\min_{d',t'} Score(d,t)$

**return** $(d,t)$

# Example: Building Regression Trees



# Best Subset Selection

**Algorithm 6.1** *Best subset selection*

1. Let $\mathcal{M}_0$ denote the *null model*, which contains no predictors. This model simply predicts the sample mean for each observation.
2. For $k = 1, 2, \ldots p$:
   (a) Fit all $\binom{p}{k}$ models that contain exactly $k$ predictors.
   (b) Pick the best among these $\binom{p}{k}$ models, and call it $\mathcal{M}_k$. Here *best* is defined as having the smallest RSS, or equivalently largest $R^2$.
3. Select a single best model from among $\mathcal{M}_0, \ldots, \mathcal{M}_p$ using cross-validated prediction error, $C_p$ (AIC), BIC, or adjusted $R^2$.

# Forward Stepwise Selection

**Algorithm 6.2** *Forward stepwise selection*

1. Let $\mathcal{M}_0$ denote the *null* model, which contains no predictors.
2. For $k = 0, \ldots, p-1$:
   (a) Consider all $p-k$ models that augment the predictors in $\mathcal{M}_k$ with one additional predictor.
   (b) Choose the *best* among these $p-k$ models, and call it $\mathcal{M}_{k+1}$. Here *best* is defined as having smallest RSS or highest $R^2$.
3. Select a single best model from among $\mathcal{M}_0, \ldots, \mathcal{M}_p$ using cross-validated prediction error, $C_p$ (AIC), BIC, or adjusted $R^2$.

# Backward Stepwise Selection

**Algorithm 6.3** *Backward stepwise selection*

1. Let $\mathcal{M}_p$ denote the *full* model, which contains all $p$ predictors.
2. For $k = p, p-1, \ldots, 1$:
   (a) Consider all $k$ models that contain all but one of the predictors in $\mathcal{M}_k$, for a total of $k-1$ predictors.
   (b) Choose the *best* among these $k$ models, and call it $\mathcal{M}_{k-1}$. Here *best* is defined as having smallest RSS or highest $R^2$.
3. Select a single best model from among $\mathcal{M}_0, \ldots, \mathcal{M}_p$ using cross-validated prediction error, $C_p$ (AIC), BIC, or adjusted $R^2$.