343 OPERATIONS RESEARCH

Introduction to Operations Research

Autumn Term - 2016-2017

Course Information

- Lecturers:
 - ► Giuliano Casale (Huxley 432, g.casale@imperial.ac.uk)
 - Ruth Misener (Huxley 379, r.misener@imperial.ac.uk)
- Tutorial Helpers:
 - Andreea-Ingrid Funie (aif109@doc.ic.ac.uk)
 - ► Miten Mistry (miten.mistry11@imperial.ac.uk)
- Lectures: Mon 9:00-11:00, Thurs 14:00-15:00 (both in LT145)
- Weekly tutorial: Thurs 15:00-16:00 (LT145)
- ► CATE:
 - ▶ Slides: do not use pre-2014 lecture notes.
 - Basic Linear Algebra refresher
 - Information for external students
- Other teaching aids:
 - Lecture videos on Panopto
 - ► Tutorial hours *not* on Panopto
 - ► Course forum on Piazza
- ▶ Two assessed courseworks (weeks $5\rightarrow6$ and $7\rightarrow8$)



Some Books (Optional Readings)

- ► F. Hillier & J. Lieberman: Introduction to Operations Research.
- H.Taha: Operations Research.
- ▶ D.G.Luenberger & Y.Ye: Linear and Nonlinear Programming.
- W. Winston: Operations Research: Applications and Algorithms.

Changes in 2016

- Based on SOLE 2015-16 feedback, we will make an effort to increase the feedback provided with the coursework. (No other requests were raised in the last SOLE.)
- Course now taught by two lecturers.
 - ▶ One coursework on the first part, the other on the second part.
 - ▶ I will answer all questions on Piazza that deal with the first part of the course, even if they are asked after I hand over lectures.

What is Operations Research?

- ► OR is a multidisciplinary branch of mathematics involving
 - ► mathematical modelling
 - mathematical optimisation
 - statistical analysis

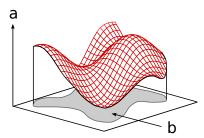
in order to find "good" solutions for complex decision problems.

- Typical objectives in OR are:
 - maximise profit
 - minimise cost
 - minimise risk
 - minimise completion time
 - maximise efficiency
 - etc.

Mathematical Programming

OR solves mathematical programming models:

$$\begin{array}{ll}
\text{minimise} & z = f(x) \\
\text{subject to} & x \in \mathcal{X},
\end{array}$$



where

- $\triangleright x \in \mathbb{R}^n$ are the decision variables
- ▶ $f : \mathbb{R}^n \to \mathbb{R}$ is the objective function (e.g., cost)
- $ightharpoonup \mathcal{X} \subseteq \mathbb{R}^n$ is the feasible set (set of admissible decisions)
- ▶ any vector x that minimises f is an optimal solution of the program and is denoted by x*
- $ightharpoonup z^* = f(x^*)$ is the optimal value achieved by x^*



Scope of OR

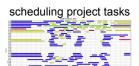
OR techniques are ubiquitous in operations management, industrial engineering, economics and finance, ICT management, machine learning, health care, security, etc.

Designing the layout of a factory

road traffic management



Determining the routes of city buses



Constructing a telecommunication network



Designing the layout of a computer chip





Financial planning

History of OR

19th century: Industrial Revolution



Efficiency of production processes

World War II: Birth of Modern OR



Allocate scarce resources to various military operations in an effective manner

Optimal design of convoy system

Where to add armour in RAF bombers?

1947 Simplex Algorithm



1953 Dynamic Programming



1970's Personal Computers



Industry-size problems can be solved efficiently

Phases of an OR Study

Hillier and Lieberman p. 8:

- 1. Define the problem of interest and gather relevant data.
- 2. Formulate a mathematical model to represent the problem.
- 3. Develop a computer-based procedure for deriving solutions to the problem from the model.
- 4. Test the model and refine as needed.
- Prepare for the ongoing application of the model as prescribed by management.
- 6. Implement.

Course focuses on phases 2 and 3.

Topics of this Course

- Linear Programming
- Integer Programming
- Game Theory
- Modelling, skill mostly acquired through:
 - Exercises: verify your solutions with the GNU GLPK solver
 - ► Case studies: in tutorials (one exam question about this)

Linear Programming

- ▶ A Linear program (LP) is a mathematical program that
 - optimises (maximises or minimises) a linear objective function
 - over a feasible set described by linear equality and/or inequality constraints.
- Optimal decision tool
- Widely adopted, many success stories (see Hillier & Lieberman)
- ▶ LPs are much simpler to cope with than non-linear programs
 - CO477 Computational Optimisation deals with the theory of non-linear optimization.

LP Running Case: Example 1

Resource Allocation Problem: A manufacturer produces A (acid) and C (caustic) and wants to decide a production plan.

Ingredients used for producing A and C are: X (e.g., a sulphate) and Y (e.g., sodium).

- ► Each ton of A requires: 2ton of X; 1ton of Y
- Each ton of C requires: 1ton of X; 3ton of Y
- Supply of X limited to: 11ton/week
- ► Supply of Y limited to: 18ton/week
- ► A sells for: £1000/ton
- ► C sells for: £1000/ton
- ▶ Market research: max 4 tons of A/week can be sold.

Maximize weekly value of sales of A and C.



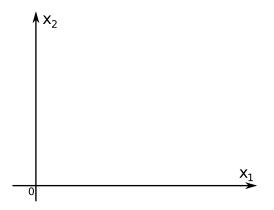
Example 1 (Modelling)

How much A and C to produce?

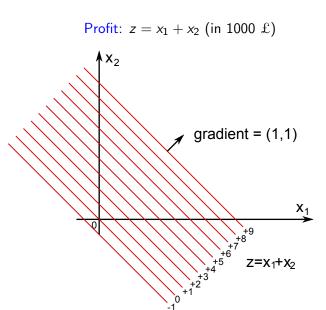
- ⇒ Formulate a mathematical programming model!
- Decision variables
 - $ightharpoonup x_1 = \text{weekly production of A (in tons)}$
 - x_2 = weekly production of C (in tons)
- Objective function
 - $ightharpoonup z = f(x_1, x_2) = \text{weekly profit (in 1000 £)}$
- ► Feasible set
 - $\mathcal{X} = \text{set of all implementable/admissible production plans}$ $x = (x_1, x_2)$
 - e.g., x = (27, 2) is not possible (not enough supply!)

Example 1 (Decision Variables)

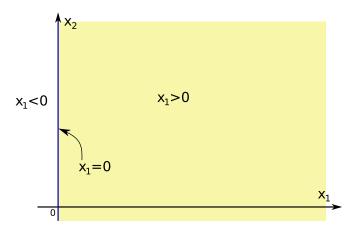
A production plan is representable as $x = (x_1, x_2)$



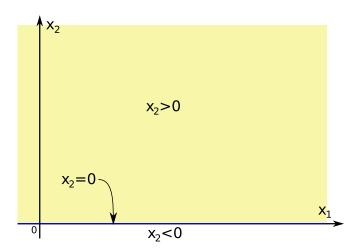
Example 1 (Objective Function)



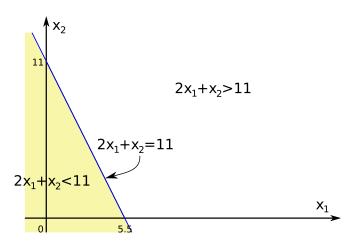
Amount of A produced is non-negative: $x_1 \ge 0$



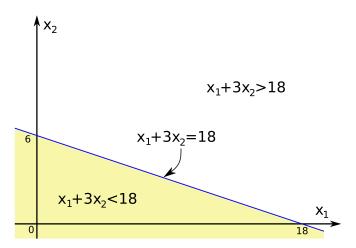
Amount of C produced is non-negative: $x_2 \ge 0$



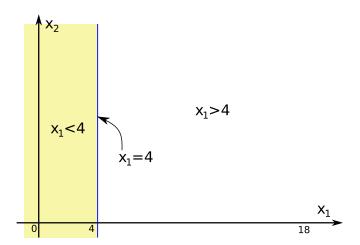
 x_1 tons of A & x_2 tons of C require $2x_1 + x_2$ ton of X X is limited to 11ton/week: $2x_1 + x_2 \le 11$



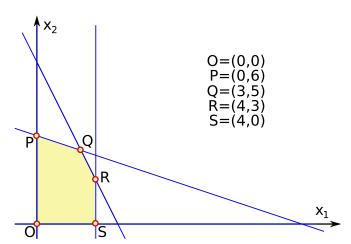
 x_1 tons of A & x_2 tons of C require $x_1 + 3x_2$ ton of Y Y is limited to 18 ton/week: $x_1 + 3x_2 \le 18$



Cannot sell more than 4 tons of A/week: $x_1 \le 4$



To obtain the overall feasible set, intersect the feasible sets of all individual constraints



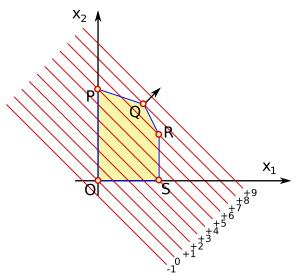
- ► The feasible set is a convex polygon
- ► The corner points O,P,Q,R,S of the feasible set are termed vertices
- ► Each vertex is given by the intersection of two blue lines
 - its coordinates can be computed by jointly solving the two linear equations defining the blue lines
- ► We obtain O=(0,0), P=(0,6), Q=(3,5), R=(4,3), S=(4,0)

Example 1 (Summary)

The best production plan is obtained by solving the following mathematical problem:

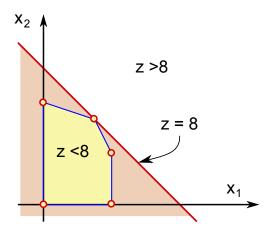
This is a linear program.

Example 1 (Graphical Solution)



Example 1 (Graphical Solution)

All feasible points satisfy $z \le 8$ Q is the only feasible point (x_1, x_2) with $z = x_1 + x_2 = 8$



Linear Programming

- Assume feasible set X bounded and nonempty
- We can prove that LPs have an optimal vertex solution
 - ▶ LPs may be solved by inspecting all vertices, but ...
 - The number of vertices grows exponentially with the number of constraints and variables in the LP
- How to program a computer to efficiently solve LPs?
 - Simplex Algorithm finds an optimal vertex
 - Vertices inspected by the Simplex algorithm are often a small subset of the total
 - What made the Simplex algorithm famous is that it works well on most instances

Variants of Example 1

▶ Minimise $z = 3x_1 - x_2$ over feasible set of Example 1

Examine the objective function at all vertices:

O = (0,0)	P=(0,6)	Q = (3,5)	R=(4,3)	S=(4,0)
0	-6	4	9	12

 \Rightarrow P: $x_1 = 0$, $x_2 = 6$ is optimal.

▶ Maximise $z = 2x_1 + x_2$ over feasible set of Example 1:

Any point on the line segment QR is optimal.

 \Rightarrow points other than vertices can be optimal, but there is at least one optimal vertex



Variants of Example 1

▶ Set a minimum weekly production goal of 7 tons of C

We add a new constraint $x_1 \ge 7$. The the feasible set becomes empty, because we previously imposed $x_1 \le 4$

 \Rightarrow the LP is infeasible

Remove constraints on availability of X and Y

Objective function can now grow to $+\infty$ on the feasible set. There is no maximum!

⇒ the LP is unbounded

