#### 343 OPERATIONS RESEARCH

Basic Linear Algebra

Autumn Term - 2016-2017

## Part I

# Basic Linear Algebra

### Matrix

#### Rectangular array of (real) numbers:

$$A = \left[ egin{array}{cccc} a_{11} & a_{12} & \dots & a_{1n} \ a_{21} & a_{22} & \dots & a_{2n} \ dots & dots & \ddots & dots \ a_{m1} & a_{m2} & \dots & a_{mn} \end{array} 
ight] \in \mathbb{R}^{m \times n}$$

#### Example:

$$A = \begin{bmatrix} 1.0 & 5.5 & 6.3 \\ 3.1 & 2.4 & 8.9 \end{bmatrix} \in \mathbb{R}^{2 \times 3}$$

## Matrix Equality

Two matrices A and B are equal, i.e.,

$$A = B$$

if and only if (iff):

$$a_{ij}=b_{ij}$$

$$\forall i, i = 1, \dots, m$$
  
 $\forall j, j = 1, \dots, n$ 

#### Vector

#### Matrix with only one column:

$$v = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_m \end{bmatrix} \in \mathbb{R}^{m \times 1} = \mathbb{R}^m$$

#### Example:

$$v = \begin{bmatrix} 1.0 \\ 2.5 \end{bmatrix} \in \mathbb{R}^2$$

#### Scalar Product

The scalar product of two vectors v and u is:

$$u = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix} \qquad v = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$$

$$v^T u = u^T v = u_1 v_1 + u_2 v_2 + \ldots + u_n v_n$$

## Multiplication by a Scalar

For a  $m \times n$  Matrix A:

$$3 A = \begin{bmatrix} 3 a_{11} & 3 a_{12} & \dots & 3 a_{1n} \\ 3 a_{21} & 3 a_{22} & \dots & 3 a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 3 a_{m1} & 3 a_{m2} & \dots & 3 a_{mn} \end{bmatrix}$$

#### Matrix Addition

For two  $m \times n$  Matrices A and B:

$$A + B = \begin{bmatrix} a_{11} + b_{11} & a_{12} + b_{12} & \dots & a_{1n} + b_{1n} \\ a_{21} + b_{21} & a_{22} + b_{22} & \dots & a_{2n} + b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} + b_{m1} & a_{m2} + b_{m2} & \dots & a_{mn} + b_{mn} \end{bmatrix}$$

## Matrix Transpose

For a  $m \times n$  Matrix A, its transpose is

$$A^{T} = \left[ egin{array}{ccccc} a_{11} & a_{21} & \dots & a_{m1} \ a_{12} & a_{22} & \dots & a_{m2} \ dots & dots & \ddots & dots \ a_{1n} & a_{2n} & \dots & a_{mn} \end{array} 
ight]$$

that is a  $n \times m$  Matrix with:

$$(A^T)^T = A$$

For a Matrix  $A(m \times r)$  and a Matrix  $B(r \times n)$ , their product is the matrix

$$A B = C = \begin{bmatrix} c_{11} & c_{12} & \dots & c_{1n} \\ c_{21} & c_{22} & \dots & c_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ c_{m1} & c_{m2} & \dots & c_{mn} \end{bmatrix}$$

that is a  $m \times n$  Matrix with

$$c_{ij} = (\text{row } i \text{ of } A)^T (\text{column } j \text{ of } B).$$

$$A = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 1 \\ 2 & 3 \\ 1 & 2 \end{bmatrix}$$

$$c_{11} = \left[\begin{array}{ccc} 1 & 1 & 2\end{array}\right] \left[\begin{array}{c} 1 \\ 2 \\ 1 \end{array}\right] = 5$$

$$A = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 1 \\ 2 & 3 \\ 1 & 2 \end{bmatrix}$$

$$c_{12} = \left[\begin{array}{ccc} 1 & 1 & 2 \end{array}\right] \left|\begin{array}{c} 1 \\ 3 \\ 2 \end{array}\right| = 8$$

$$A = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 1 \\ 2 & 3 \\ 1 & 2 \end{bmatrix}$$

$$c_{21} = \left[ \begin{array}{ccc} 2 & 1 & 3 \end{array} \right] \left[ \begin{array}{c} 1 \\ 2 \\ 1 \end{array} \right] = 7$$

$$A = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 1 \\ 2 & 3 \\ 1 & 2 \end{bmatrix}$$

$$c_{22} = \left[ \begin{array}{ccc} 2 & 1 & 3 \end{array} \right] \left[ \begin{array}{c} 1 \\ 3 \\ 2 \end{array} \right] = 11$$

$$A = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 1 \\ 2 & 3 \\ 1 & 2 \end{bmatrix}$$

$$AB = C = \begin{bmatrix} 5 & 8 \\ 7 & 11 \end{bmatrix}$$

## Properties: C = A B

Associative:

$$A(BC) = (AB)C$$

Distributive:

$$A(B+C) = (AB) + (AC)$$

$$(A+B) C = (A C) + (B C)$$

In general, matrix product is not commutative:

$$AB \neq BA$$

## Part II

# Matrices and Systems of Linear Equations

## Linear Equations

$$a_{11}x_1 + a_{12}x_2 + \ldots + a_{1n}x_n = b_1$$
  
 $a_{21}x_1 + a_{22}x_2 + \ldots + a_{2n}x_n = b_2$   
 $\vdots$   $\vdots$   $\vdots$   $\vdots$   $\vdots$   $\vdots$   $a_{m1}x_1 + a_{m2}x_2 + \ldots + a_{mn}x_n = b_m$ 

m Equations in n Variables

#### Matrix Notation

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix} \quad b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix} \quad x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

$$A x = b$$

Sometimes denoted:

$$[A \mid b]$$

## Example

$$x_1 + 2x_2 = 5$$
  
 $2x_1 - x_2 = 0$ 

Matrices: 
$$\begin{bmatrix} 1 & 2 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 5 \\ 0 \end{bmatrix}$$

## Example

$$x_1 + 2x_2 = 5$$
  
 $2x_1 - x_2 = 0$ 

Compact: 
$$\begin{bmatrix} 1 & 2 & 5 \\ 2 & -1 & 0 \end{bmatrix}$$

Solution: 
$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

#### Gauss-Jordan Method

A System of Linear Equations

$$A x = b$$

#### may have:

- no solutions;
- a unique solution;
- infinitely many solutions.

Commonly solved by the Gauss-Jordan Method, which uses *Elementary Row Operations (ERO)* to progressively simplify the coefficient matrix A.

## ERO 1

Multiplying any row by a non-zero scalar  $c \neq 0$ :

$$(row i of A') = c (row i of A)$$

$$A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 3 & 5 & 6 \\ 0 & 1 & 2 & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 & 4 \\ 3 & 9 & 15 & 18 \\ 0 & 1 & 2 & 3 \end{bmatrix} = A'$$

## ERO 2

Multiplying any row by a non-zero scalar  $c \neq 0$  and add it to another one  $(i \neq j)$ :

$$(row j of A') = c (row i of A) + (row j of A)$$

$$A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 3 & 5 & 6 \\ 0 & 1 & 2 & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 3 & 5 & 6 \\ 4 & 13 & 22 & 27 \end{bmatrix} = A'$$

$$4 \begin{bmatrix} 1 & 3 & 5 & 6 \end{bmatrix} + \begin{bmatrix} 0 & 1 & 2 & 3 \end{bmatrix} = \begin{bmatrix} 4 & 13 & 22 & 27 \end{bmatrix}$$



## ERO 3

#### Interchange any two rows i and j:

$$(row j of A') = (row i of A)$$
  
 $(row i of A') = (row j of A)$ 

$$A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 3 & 5 & 6 \\ 0 & 1 & 2 & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 0 & 1 & 2 & 3 \\ 1 & 3 & 5 & 6 \\ 1 & 2 & 3 & 4 \end{bmatrix} = A'$$

Use ERO1 and ERO2 to simplify Equations.

$$x_1 + x_2 = 2 2x_1 + 4x_2 = 7$$

Use ERO1 and ERO2 to simplify Equations.

$$x_1 + x_2 = 2$$
  $x_1 + x_2 = 2$   
 $2x_1 + 4x_2 = 7$   $2x_2 = 3$ 

$$(row \ 2 \ of \ A') = -2 \ (row \ 1 \ of \ A) + (row \ 2 \ of \ A)$$



Use ERO1 and ERO2 to simplify Equations.

$$x_1 + x_2 = 2$$
  $x_1 + x_2 = 2$   
 $2x_1 + 4x_2 = 7$   $2x_2 = 3$ 

$$x_1 + x_2 = 2$$

$$x_2 = \frac{3}{2}$$

$$(\text{row 2 of } A') = \frac{1}{2} (\text{row 2 of } A)$$



Use ERO1 and ERO2 to simplify Equations.

$$x_1 + x_2 = 2$$
  $x_1 + x_2 = 2$   
 $2x_1 + 4x_2 = 7$   $2x_2 = 3$ 

$$x_1 + x_2 = 2$$
  $x_1 = \frac{1}{2}$   $x_2 = \frac{3}{2}$ 

(row 1 of A') = -1 (row 2 of A) + (row 1 of A)



# Solving Equations (cont)

#### In Compact Form:

$$\begin{bmatrix} 1 & 1 & 2 \\ 2 & 4 & 7 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 2 \\ 0 & 2 & 3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & \frac{3}{2} \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & \frac{1}{2} \\ 0 & 1 & \frac{3}{2} \end{bmatrix}$$

## Basic Principle

lf

$$\begin{bmatrix} A' \mid b' \end{bmatrix}$$

is obtained by ERO1, ER02, and ER03 from

$$[A \mid b]$$

Then:

$$A' x = b'$$
 and  $A x = b$ 

are equivalent.

## Example

$$2x_1 + 2x_2 + x_3 = 9$$
  

$$2x_1 - x_2 + 2x_3 = 6$$
  

$$x_1 - x_2 + 2x_3 = 5$$

Gauss-Jordan Method: Solve by systematically applying the ERO

$$\left[\begin{array}{c|ccc} A & b \end{array}\right] = \left[\begin{array}{cccc} 2 & 2 & 1 & 9 \\ 2 & -1 & 2 & 6 \\ 1 & -1 & 2 & 5 \end{array}\right]$$

$$\begin{bmatrix} 2 & 2 & 1 & 9 \\ 2 & -1 & 2 & 6 \\ 1 & -1 & 2 & 5 \end{bmatrix}$$
ERO 1
$$(\text{row 1}) = \frac{1}{2}(\text{row 1})$$

$$\left[\begin{array}{ccc|c}
1 & 1 & \frac{1}{2} & \frac{9}{2} \\
2 & -1 & 2 & 6 \\
1 & -1 & 2 & 5
\end{array}\right]$$

$$\begin{bmatrix} 1 & 1 & \frac{1}{2} & \frac{9}{2} \\ 2 & -1 & 2 & 6 \\ 1 & -1 & 2 & 5 \end{bmatrix}$$

$$ERO 2$$

$$(row 2) = -2 (row 1) + (row 2)$$

$$\left[\begin{array}{ccc|c}
1 & 1 & \frac{1}{2} & \frac{9}{2} \\
0 & -3 & 1 & -3 \\
1 & -1 & 2 & 5
\end{array}\right]$$

$$\begin{bmatrix} 1 & 1 & \frac{1}{2} & \frac{9}{2} \\ 0 & -3 & 1 & -3 \\ 1 & -1 & 2 & 5 \end{bmatrix}$$
ERO 2
$$(\text{row 3}) = -1 (\text{row 1}) + (\text{row 3})$$

$$\left[\begin{array}{ccc|c}
1 & 1 & \frac{1}{2} & \frac{9}{2} \\
0 & -3 & 1 & -3 \\
0 & -2 & \frac{3}{2} & \frac{1}{2}
\end{array}\right]$$

$$\left[\begin{array}{cc|cc|c}
1 & 1 & \frac{1}{2} & \frac{9}{2} \\
0 & -3 & 1 & -3 \\
0 & -2 & \frac{3}{2} & \frac{1}{2}
\end{array}\right]$$

ERO 1

$$(\text{row 2}) = -\frac{1}{3} (\text{row 2})$$

$$\begin{bmatrix} 1 & 1 & \frac{1}{2} & \frac{9}{2} \\ 0 & 1 & -\frac{1}{3} & 1 \\ 0 & -2 & \frac{3}{2} & \frac{1}{2} \end{bmatrix}$$

$$\begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{2} & \frac{9}{2} \\ 0 & 1 & -\frac{1}{3} & 1 \\ 0 & -2 & \frac{3}{2} & \frac{1}{2} \end{bmatrix}$$

$$ERO \ 2$$

$$(row \ 1) = -1 \ (row \ 2) + (row \ 1)$$

$$\begin{bmatrix}
1 & 0 & \frac{5}{6} & \frac{7}{2} \\
0 & 1 & -\frac{1}{3} & 1 \\
0 & -2 & \frac{3}{2} & \frac{1}{2}
\end{bmatrix}$$

$$\left[\begin{array}{ccc|c}
1 & 0 & \frac{5}{6} & \frac{7}{2} \\
0 & 1 & -\frac{1}{3} & 1 \\
0 & -2 & \frac{3}{2} & \frac{1}{2}
\end{array}\right]$$

ERO 2

$$(row 3) = 2 (row 2) + (row 3)$$

$$\left[\begin{array}{ccc|c}
1 & 0 & \frac{5}{6} & \frac{7}{2} \\
0 & 1 & -\frac{1}{3} & 1 \\
0 & 0 & \frac{5}{6} & \frac{5}{2}
\end{array}\right]$$

$$\left[\begin{array}{ccc|c}
1 & 0 & \frac{5}{6} & \frac{7}{2} \\
0 & 1 & -\frac{1}{3} & 1 \\
0 & 0 & \frac{5}{6} & \frac{5}{2}
\end{array}\right]$$

ERO 1

$$(row 3) = \frac{6}{5} (row 3)$$

$$\left[\begin{array}{ccc|c} 1 & 0 & \frac{5}{6} & \frac{7}{2} \\ 0 & 1 & -\frac{1}{3} & 1 \\ 0 & 0 & 1 & 3 \end{array}\right]$$

$$\begin{bmatrix} 1 & 0 & \frac{5}{6} \\ 0 & 1 & -\frac{1}{3} \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \frac{7}{2} \\ 1 \\ 3 \end{bmatrix}$$
ERO 2

$$(row 1) = -\frac{5}{6} (row 3) + (row 1)$$

$$\left[\begin{array}{ccc|c}
1 & 0 & 0 & 1 \\
0 & 1 & -\frac{1}{3} & 1 \\
0 & 0 & 1 & 3
\end{array}\right]$$

$$\left[\begin{array}{ccc|c}
1 & 0 & 0 & 1 \\
0 & 1 & -\frac{1}{3} & 1 \\
0 & 0 & 1 & 3
\end{array}\right]$$

ERO 2

$$(row 2) = \frac{1}{3} (row 3) + (row 2)$$

```
\left[\begin{array}{ccc|c}
1 & 0 & 0 & 1 \\
0 & 1 & 0 & 2 \\
0 & 0 & 1 & 3
\end{array}\right]
```

$$\left[\begin{array}{ccc|c}
1 & 0 & 0 & 1 \\
0 & 1 & 0 & 2 \\
0 & 0 & 1 & 3
\end{array}\right]$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

The solution is now straightforward:

$$x_1 = 1$$
,  $x_2 = 2$ , and  $x_3 = 3$ 

## Remark (ER03)

ERO3 can be used to re-arrange rows such that ERO1 and ERO2 can be applied systematically.

$$\begin{array}{rcl}
2x_2 + x_3 &= 6 \\
x_1 + x_2 - x_3 &= 2 \\
2x_1 + x_2 + x_3 &= 4
\end{array}$$

$$\begin{bmatrix} 0 & 2 & 1 & | & 6 \\ 1 & 1 & -1 & | & 2 \\ 2 & 1 & 1 & | & 4 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1 & -1 & | & 2 \\ 0 & 2 & 1 & | & 6 \\ 2 & 1 & 1 & | & 4 \end{bmatrix}$$

## Part III

# Basic Variables and Solutions

#### Basic Variables

For any system of linear equations

$$A x = b$$

a variable  $x_i$  with:

- one coefficient  $a_{ij}$  equal to 1, and
- ► all other coefficients in row *i* equal to 0 is called a *Basic Variable*

All other variables are called Non-Basic Variables.

#### Solutions I

Condition 1:

$$A' \ x = b'$$
 has at least one row of the form 
$$\left[ \begin{array}{cccc} 0 & 0 & \dots & 0 & | & c \end{array} \right]$$
 with  $c \neq 0$ .

Condition  $I \implies A x = b$  has no solution.

e.g. 
$$\begin{bmatrix} 1 & 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 & 1 \\ 0 & 0 & 1 & 3 & -1 \\ 0 & 0 & 0 & 0 & 2 \end{bmatrix}$$
 has no solution!

#### Solutions II

Suppose Condition I does not hold and the set of non-basic variables is empty, NBV=  $\emptyset$ . Then A' x = b' and hence A x = b has a unique solution.

e.g. 
$$\begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 3 \end{bmatrix}$$

has a unique solution:

$$x_1 = 1, x_2 = 2, x_3 = 3$$

#### Solutions III

Suppose Condition I does not hold but the set of non-basic variables is non-empty, NBV $\neq \emptyset$ .

Then A' x = b' and A x = b have an infinite number of solutions.

In order to obtain these solutions, set each NBV to an arbitrary value. Then solve for the BVs in terms of the NBVs.

$$x_1$$
 +  $x_4$  +  $x_5$  = 3  
 $x_2$  +  $2x_4$  = 2  
 $x_3$  +  $x_5$  = 1

```
\left[\begin{array}{cccc|cccc}
1 & 0 & 0 & 1 & 1 & 3 \\
0 & 1 & 0 & 2 & 0 & 2 \\
0 & 0 & 1 & 0 & 1 & 1 \\
0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0
\end{array}\right]
```

$$\left[\begin{array}{cccc|cccc}
1 & 0 & 0 & 1 & 1 & 3 \\
0 & 1 & 0 & 2 & 0 & 2 \\
0 & 0 & 1 & 0 & 1 & 1
\end{array}\right]$$

Condition I does not apply, and:

$$BV = \{x_1, x_2, x_3\}$$
 and  $NBV = \{x_4, x_5\}$ 

Set:  $x_4 = a$  and  $x_5 = b$ , for any value of a and b we get:

$$x_1 = 3 - a - b$$

$$x_2 = 2 - a$$

$$x_3 = 1 - b$$

## Gauss-Jordan: Summary

Does 
$$[A \mid b]$$
 have a row  $[0 \ 0 \ \dots \ 0 \mid c]$  with  $c \neq 0$ ?

- YES: ∄ solution
- NO: Find BV and NBV. Is NBV= ∅?
  - YES: ∃! solution
  - NO: ∃ solutions (infinite)

## Part IV

## Linear Combinations

#### **Linear Combinations**

Let V be a set of (column) vectors,

$$V = \{v_1, v_2, v_3, \dots, v_k\}$$

all of the same dimension.

A *linear combination* of vectors in V is any vector of the form:

$$v=c_1v_1+c_2v_2+\ldots+c_kv_k.$$
 with  $c_1,c_2,\ldots,c_k\in\mathbb{R}.$ 

$$V = \left\{ v_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, v_2 = \begin{bmatrix} 2 \\ 1 \end{bmatrix} \right\}$$

$$2v_1 - v_2 = 2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} - \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}$$

$$v_1 + 3v_2 = \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 3 \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 7 \\ 5 \end{bmatrix}$$

$$0v_1 + 3v_2 = 3 \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ 3 \end{bmatrix}$$

## Linear Independence I

Let V be a set of (column) vectors in  $\mathbb{R}^m$ 

$$V = \{v_1, v_2, v_3, \dots, v_k\}.$$

and the null vector

$$N = \begin{bmatrix} 0 & 0 & \dots & 0 \end{bmatrix}^T$$
.

In order to determine if V is *linearly independent* (l.i.), we try to find a linear combinations of vectors in V which results in N.

Clearly the trivial linear combination always works:

$$0v_1 + 0v_2 + \ldots + 0v_k = N.$$



## Linear Independence II

- A set of vectors *V* is *linearly independent* iff the only linear combination which gives the null vector is the trivial linear combination.
- Otherwise the vectors in V are said to be linearly dependent.
- Any V containing N is linearly dependent (for  $c \neq 0$ )

e.g. 
$$c \begin{bmatrix} 0 \\ 0 \end{bmatrix} + 0 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 0 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = N.$$

The vectors  $e_1 = \begin{bmatrix} 1 & 0 \end{bmatrix}^T$  and  $e_2 = \begin{bmatrix} 0 & 1 \end{bmatrix}^T$  are l.i.:

$$c_1 \left[ egin{array}{c} 1 \ 0 \end{array} 
ight] + c_2 \left[ egin{array}{c} 0 \ 1 \end{array} 
ight] = extbf{ extit{N}} \quad \Rightarrow \quad c_1 = 0 = c_2.$$

The vectors  $e_1 = \begin{bmatrix} 1 & 2 \end{bmatrix}^T$  and  $e_2 = \begin{bmatrix} 2 & 4 \end{bmatrix}^T$  are l.d.:

$$2\left[\begin{array}{c}1\\2\end{array}\right]-1\left[\begin{array}{c}2\\4\end{array}\right]=N.$$

#### Rank of a Matrix

Take a  $m \times n$  matrix A. Consider its column vectors:

$$C = \{c_1, c_2, \ldots, c_n\}.$$

The rank of A is the maximal number of linear independent vectors in C.

e.g. 
$$rank \left( \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \right) = 0$$
 e.g.  $rank \left( \begin{bmatrix} 1 & 2 \\ 1 & 2 \end{bmatrix} \right) = 1$  e.g.  $rank \left( \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) = 2$ 

#### Inverse of a Matrix

Let A be an  $m \times m$  square matrix.

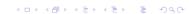
The  $m \times m$  identity matrix is given by:

$$I = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix}$$

A matrix  $A^{-1}$  for which the following holds:

$$A A^{-1} = A^{-1} A = I$$

is called the *inverse* matrix of A.



#### Inverse of a Matrix II

- ▶ The inverse of a matrix may not exist!
- ▶ An invertible matrix A is called non-singular.
- ▶ The inverse of an  $m \times m$  matrix does not exist if rank(A) < m.

Matrix inversion can be used to solve linear systems:

$$A x = b$$

$$A^{-1} A x = A^{-1} b$$

$$I x = A^{-1} b$$

$$x = A^{-1} b$$

The Gauss-Jordan process computes  $A^{-1}$  indirectly.

