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1 Lecture 01 - 方程组的几何解释

 \mathbf{n} linear equations, \mathbf{n} unknowns

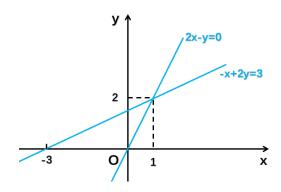
- row picture
- column picture ⋆
- matrix form

$$\begin{cases} 2x - y = 0 \\ -x + 2y = 3 \end{cases}$$
$$\begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}, i.e.$$

 $\mathbf{A} \text{ (matrix of coefficients)} = \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}, \mathbf{x} \text{ (vector of unknowns)} = \begin{bmatrix} x \\ y \end{bmatrix}, \mathbf{b} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}, \text{ such that}$

$$\mathbf{A}\mathbf{x} = \mathbf{b}$$

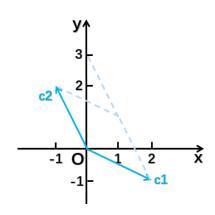
what's the **row** picture?



to find the point that lies on both two lines

what's the **column** picture?

$$x \begin{bmatrix} 2 \\ -1 \end{bmatrix} + y \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}$$



$$1\overrightarrow{c_1} + 2\overrightarrow{c_2} = \overrightarrow{b}$$

to find the linear combination of columns of A, such that it equals b

what linear combination gives **b**?
what do all the linear combinations give?
what are all the possible, achievable right-hand sides be?

$$\begin{cases} 2x - y &= 0 & 1 \\ -x + 2y - z &= -1 & 2 \\ &- 3y + 4z &= 4 & 3 \end{cases}$$

$$\begin{cases} \mathbf{1} &: \text{ the plot of all the points that solve it are a plane} \end{cases}$$

$$\begin{cases} \mathbf{2} &: \text{ two planes meet at a line} \end{cases}$$

$$\begin{cases} \mathbf{1} &: \text{ meet at a point} \end{cases}$$

$$\mathbf{A} = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -3 & 4 \end{bmatrix}, \mathbf{b} = \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix}$$

what's the **row** picture?

to find out all the points that satisfy all the equations

what's the **column** picture?

$$x \begin{bmatrix} 2 \\ -1 \\ 0 \end{bmatrix} + y \begin{bmatrix} -1 \\ 2 \\ -3 \end{bmatrix} + z \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 4 \end{bmatrix}$$

can I always solve $\mathbf{A}\mathbf{x} = \mathbf{b}$ for every right-hand side \mathbf{b} ? do the linear combinations of the columns fill 3-dimensional space? for this \mathbf{A} , the answer is \mathbf{YES} (non-singular, invertible) but for some others \mathbf{A} , the answer could be \mathbf{NO} (singular, not-invertible)

if the 3 columns all lie in the same plane, so I could solve it for some right-hand sides, when \overrightarrow{b} is in the plane, but most right-hand sides would be out of the plane and unreachable.

in some case, the combinations of **n** columns can only fill out **m**-D (m < n)

$$\begin{bmatrix} 2 & 5 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = 1 \begin{bmatrix} 2 \\ 1 \end{bmatrix} + 2 \begin{bmatrix} 5 \\ 3 \end{bmatrix} = \begin{bmatrix} 12 \\ 7 \end{bmatrix}$$

Ax means: Ax is a combination of columns of A

2 Lecture 02 - 矩阵消元

when solving equations-system,

Elimination, if it succeeds, it gets the answer.

It's always good to ask how could it fail.

$$\begin{cases} x + 2y + z = 2 \\ 3x + 8y + z = 12 \\ 4y + z = 2 \end{cases}$$

$$\begin{bmatrix} \mathbf{1} & 2 & 1 \\ \mathbf{1} & \mathbf{2} & 1 \\ 3 & 8 & 1 \\ 0 & 4 & 1 \end{bmatrix} \xrightarrow[row_3 - 0 \times row_1]{row_3 - 0 \times row_1} \begin{bmatrix} 1 & 2 & 1 \\ 0 & \mathbf{2} & -2 \\ 0 & 4 & 1 \end{bmatrix} \xrightarrow[row_3 - 2 \times row_2]{row_3 - 2 \times row_2} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & -2 \\ 0 & 0 & \mathbf{5} \\ \text{third-pivot} \end{bmatrix}$$

pivots can **NOT** be 0!

if there is a 0 in the pivot position, then try to switch lines if 0 is in the pivot position and no place to exchange, then failure

let's bring the right-hand side in (Augmented Matrix)

$$\begin{bmatrix} 1 & 2 & 1 & 2 \\ 3 & 8 & 1 & 12 \\ 0 & 4 & 1 & 2 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 2 & 1 & 2 \\ 0 & 2 & -2 & 6 \\ 0 & 4 & 1 & 2 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 2 & 1 & 2 \\ 0 & 2 & -2 & 6 \\ 0 & 0 & 5 & -10 \end{bmatrix} \Rightarrow \begin{cases} x + 2y + z = 2 \\ 2y - 2z = 6 \\ 5z = -10 \end{cases}$$
by back-substitution: $x = 2, y = 1, z = -2$

"elimination matrices"

$$\begin{bmatrix} \vdots & \vdots & \vdots \\ \operatorname{col}_1 & \operatorname{col}_2 & \operatorname{col}_3 \\ \vdots & \vdots & \vdots \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} \\ \\ \end{bmatrix} = 1 \times \operatorname{col}_1 + 2 \times \operatorname{col}_2 + 3 \times \operatorname{col}_3$$

the result of multiplying a matrix by some vectors, is a combination of columns of the matrix

the product of a row times a matrix, is a combination of rows of the matrix

when we do matrix multiplication, keep your eye on what it is doing with the whole vectors what does the matrix, which can subtract $3 \times row_1$ from row_2 look like?

i.e.
$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 \\ 3 & 8 & 1 \\ 0 & 4 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & -2 \\ 0 & 4 & 1 \end{bmatrix}$$
$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix}$$
$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix}$$

$$\frac{as \ R_{1}=1 \times row_{1}+0 \times row_{2}+0 \times row_{3}}{as \ R_{3}=0 \times row_{1}+0 \times row_{2}+1 \times row_{3}} = \begin{bmatrix} 1 & 0 & 0 \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \\
\frac{as \ R_{3}=0 \times row_{1}+0 \times row_{2}+1 \times row_{3}}{0 & 0 & 1} = \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
: elementary matrix (初等矩阵)

E_{i,j} means it's the matrix that we use to fix the (i, j) position

e.g.
$$\begin{bmatrix}
? & ? & ? \\
? & ? & ? \\
? & ? & ?
\end{bmatrix}
\xrightarrow{R_1 = row_1}
\begin{bmatrix}
1 & 0 & 0 \\
? & ? & ? \\
? & ? & ?
\end{bmatrix}
\xrightarrow{R_2 = row_2}
\begin{bmatrix}
1 & 0 & 0 \\
0 & 1 & 0 \\
? & ? & ?
\end{bmatrix}
\xrightarrow{R_3 = row_3 - 2 \times row_2}
\begin{bmatrix}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & -2 & 1
\end{bmatrix} = E_{3,2}$$

in elimination, we can use an elementary matrix to describe the change in each step

the next point in this lecture is to put these steps together, into a matrix that does these steps all in sequence, in another words, how could I create the matrix that does the whole job at once? i.e.

$$E_{3,2}(E_{2,1}A) = U \Longleftrightarrow ?A = U$$

Associative Law

$$(AB)C = A(BC)$$

permutation(置换):

• exchange rows, e.g.

$$\begin{bmatrix} ? & ? \\ ? & ? \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} c & d \\ a & b \end{bmatrix}$$

$$\mathbf{P} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \text{ is to exchange } row_1 \text{ and } row_2$$

• exchange columns, e.g.

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} ? & ? \\ ? & ? \end{bmatrix} = \begin{bmatrix} b & a \\ d & c \end{bmatrix}$$

$$\mathbf{P} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$
 is to exchange col_1 and col_2

when I multiply a matrix on the left, I am doing row operations if I want to do column operations, I should put a matrix on the right

if $\mathbf{?A} = \mathbf{U}$, then how can I "from \mathbf{U} back to \mathbf{A} "? this is about reversing steps, invertible, \cdots

$$\begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

"what steps can get me back?"

[&]quot;what matrix can bring me back?"

3 Lecture 03 - 乘法和逆矩阵

key words:

- matrix multiplication (4 ways)
- inverse of A, AB, A^T
- Gauss-Jordan, to find \mathbf{A}^{-1}

$$egin{bmatrix} oldsymbol{iggle} & oldsymbol{i$$

 $c_{i,j}$ comes from row_i of **A** and col_j of **B** e.g.

$$c_{3,4} = \begin{bmatrix} row_3 & of & \mathbf{A} \end{bmatrix} \begin{bmatrix} col_4 \\ of \\ \mathbf{B} \end{bmatrix}$$

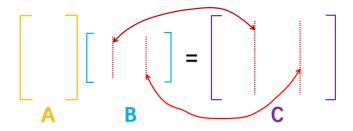
$$= a_{3,1}b_{1,4} + a_{3,2}b_{2,4} + \dots + a_{3,i}b_{i,4} + \dots + a_{3,n}b_{n,4}$$

$$= \sum_{k=1}^{n} a_{3,k}b_{k,4}$$

the number of columns of A has to match the number of rows of B

$$\mathbf{A}_{m\times n}\mathbf{B}_{n\times p}=\mathbf{C}_{m\times p}$$

the matrix times the $n^{\rm th}$ column is the $n^{\rm th}$ column of the answer



so I could think of multiplying a matrix by a vector, side by side I can just think of having several columns, multiplying by \mathbf{A} , and getting the columns of answer

the columns of C are combinations of columns of A

 \iff every column of **C** is a combination of columns of **A**, and numbers in **B** tell me what the combination is

in the same way, the rows of C are combinations of rows of B

what about "
$$\underbrace{col \ of \ \mathbf{A}}_{m \times 1} \times \underbrace{row \ of \ \mathbf{B}}_{1 \times p}$$
"?
e.g.
$$\begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} \begin{bmatrix} 1 & 6 \end{bmatrix} = \begin{bmatrix} 2 & 12 \\ 3 & 18 \\ 4 & 24 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 7 \\ 3 & 8 \\ 4 & 9 \end{bmatrix} \begin{bmatrix} 1 & 6 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} \begin{bmatrix} 1 & 6 \end{bmatrix} + \begin{bmatrix} 7 \\ 8 \\ 9 \end{bmatrix} \begin{bmatrix} 0 & 0 \end{bmatrix}$$

$$\mathbf{AB} = \text{sum of } (col_i \ of \ \mathbf{A}) \times (row_i \ of \ \mathbf{B})$$

$$= \sum_{i=1}^{n} (col_i \ of \ \mathbf{A}) \times (row_i \ of \ \mathbf{B})$$

the row space for $\begin{bmatrix} 2 & 12 \\ 3 & 18 \\ 4 & 24 \end{bmatrix}$, which is like all combinations of the rows, is the line through the row-vector $\begin{bmatrix} 1 & 6 \end{bmatrix}$, the same to the column space

you could also cut the matrix into blocks and do the multiplication by blocks, i.e.

$$\underbrace{\left[\begin{array}{c|c|c} A_1 & A_2 \\ \hline A_3 & A_4 \end{array} \right]}_{A} \underbrace{\left[\begin{array}{c|c|c} B_1 & B_2 \\ \hline B_3 & B_4 \end{array} \right]}_{B} = \underbrace{\left[\begin{array}{c|c|c} A_1B_1 + A_2B_3 & A_1B_2 + A_2B_4 \\ \hline A_3B_1 + A_4B_3 & A_3B_2 + A_4B_4 \end{array} \right]}_{AB}$$

Inverses (square matrices)

not all matrices have inverses, if a matrix is square, is it invertible or not? if A is invertible, non-singular, then

$$\mathbf{A}^{-1}\mathbf{A} = \mathbf{I} = \mathbf{A}\mathbf{A}^{-1}$$

in singular case, no inverse!

e.g.

$$\mathbf{A} = \begin{bmatrix} 1 & 3 \\ 2 & 6 \end{bmatrix}$$

thinking about columns here, if I multiply **A** by some other matrices, the columns of the results are all multiples of $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$, so no way to get the identity matrix **I**

there is another more important reason

a square matrix has no inverse if I can find a vector \boldsymbol{x} such that $\boldsymbol{A}\boldsymbol{x}=\boldsymbol{0}$ and $\boldsymbol{x}\neq\boldsymbol{0}$

but

$$\begin{bmatrix} 1 & 3 \\ 2 & 6 \end{bmatrix} \begin{bmatrix} 3 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

the matrix can't have an inverse if some columns give no contribution!

because

if
$$\mathbf{A} = \begin{bmatrix} 1 & 3 \\ 2 & 6 \end{bmatrix}$$
 has an inverse, named \mathbf{A}^{-1} , then $\mathbf{A}^{-1}\mathbf{A} \begin{bmatrix} 3 \\ -1 \end{bmatrix} = \mathbf{A}^{-1} \begin{bmatrix} 0 \\ 0 \end{bmatrix}$, and meanwhile, $\mathbf{A}^{-1}\mathbf{A} \begin{bmatrix} 3 \\ -1 \end{bmatrix} = \mathbf{I} \begin{bmatrix} 3 \\ -1 \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \end{bmatrix}$, so that $\begin{bmatrix} 3 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$, which is not True

our conclusion is that for non-invertible/singular matrices, some combinations of their columns give the zero column

let's take a matrix that does have an inverse for example

e.g.

$$\underbrace{\begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix}}_{\mathbf{A}} \underbrace{\begin{bmatrix} a & b \\ c & d \end{bmatrix}}_{\mathbf{A}^{-1}} = \underbrace{\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}}_{\mathbf{I}}$$
then
$$\begin{cases} \mathbf{A} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\mathbf{A} \begin{bmatrix} c \\ d \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

generally,

$$\mathbf{A} \cdot (col_j \ of \ \mathbf{A}^{-1}) = (col_j \ of \ \mathbf{I})$$

then how to solve the inverse for an invertible matrix?

here is the Gauss-Jordan idea, to solve two equations at once

$$\begin{cases} \begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \\ \begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix} \begin{bmatrix} c \\ d \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$
"solve them together!"

$$\underbrace{\begin{bmatrix} 1 & 3 & 1 & 0 \\ 2 & 7 & 0 & 1 \end{bmatrix}}_{\begin{bmatrix} \mathbf{A} & \mathbf{I} \end{bmatrix}} \rightarrow \begin{bmatrix} 1 & 3 & 1 & 0 \\ 0 & 1 & -2 & 1 \end{bmatrix}}_{\begin{bmatrix} \mathbf{I} & \mathbf{A}^{-1} \end{bmatrix}} \rightarrow \underbrace{\begin{bmatrix} 1 & 0 & 7 & -3 \\ 0 & 1 & -2 & 1 \end{bmatrix}}_{\begin{bmatrix} \mathbf{I} & \mathbf{A}^{-1} \end{bmatrix}}$$

把单位矩阵当成草稿纸, 记录下对左侧矩阵的变换

相当于左右两边同时乘上逆矩阵,当左边变成单位矩阵时,右边即是该逆矩阵

i.e.

$$\begin{aligned} \mathbf{E}_{i_1,j_1} \mathbf{E}_{i_2,j_2} \cdots \mathbf{E}_{i_n,j_n} \left[\begin{array}{c|c} \mathbf{A} & \mathbf{I} \end{array} \right] &= \left[\begin{array}{c|c} \mathbf{E}_{i_1,j_1} \mathbf{E}_{i_2,j_2} \cdots \mathbf{E}_{i_n,j_n} \mathbf{A} & \mathbf{E}_{i_1,j_1} \mathbf{E}_{i_2,j_2} \cdots \mathbf{E}_{i_n,j_n} \mathbf{I} \end{array} \right] \\ &= \left[\begin{array}{c|c} \mathbf{I} & \mathbf{E}_{i_1,j_1} \mathbf{E}_{i_2,j_2} \cdots \mathbf{E}_{i_n,j_n} \end{array} \right] \end{aligned}$$

then $\mathbf{A}^{-1} = \mathbf{E}_{i_1,j_1} \mathbf{E}_{i_2,j_2} \cdots \mathbf{E}_{i_n,j_n}$ 注:

$$\mathbf{E}_{i_t,j_t}\left[\begin{array}{c|c}\mathbf{A} & \mathbf{I}\end{array}\right]$$
,即对 $\left[\begin{array}{c|c}\mathbf{A} & \mathbf{I}\end{array}\right]$ 做行变换 \Longleftrightarrow 对 \mathbf{A} 与 \mathbf{I} 同时、做同样的行变换同理,可以对 $\left[\begin{array}{c|c}\mathbf{A} & \mathbf{I}\end{array}\right]$ 做列变换,求得 \mathbf{A}^{-1}

4 Lecture 04 - 矩阵的 LU 分解

suppose **A** is invertible, and **B** is invertible, then what matrix gives me the inverse of **AB**?

$$AB(B^{-1}A^{-1})=I$$

$$(\mathbf{B}^{-1}\mathbf{A}^{-1})\mathbf{A}\mathbf{B} = \mathbf{I}$$

if I transpose a matrix (square, invertible), what's its inverse?

$$\mathbf{A}\mathbf{A}^{-1} = \mathbf{I}$$
 $(\mathbf{A}^{-1})^{\mathbf{T}}\mathbf{A}^{\mathbf{T}} = \mathbf{I}$ \updownarrow $(\mathbf{A}^{\mathbf{T}})^{-1} = (\mathbf{A}^{-1})^{\mathbf{T}}$

the $\mathbf{A} = \mathbf{L}\mathbf{U}$ is the most basic factorization of a matrix

think of the
$$2 \times 2$$
 case
$$\begin{bmatrix}
1 & 0 \\
-4 & 1
\end{bmatrix}
\begin{bmatrix}
2 & 1 \\
8 & 7
\end{bmatrix} = \begin{bmatrix}
2 & 1 \\
0 & 3
\end{bmatrix}$$
if $\mathbf{A} = \mathbf{L}\mathbf{U}$, then
$$\begin{bmatrix}
2 & 1 \\
8 & 7
\end{bmatrix} = \begin{bmatrix}
? & ? \\
? & ?
\end{bmatrix}
\begin{bmatrix}
2 & 1 \\
0 & 3
\end{bmatrix}$$
so $\mathbf{L} = \mathbf{E}^{-1} = \begin{bmatrix}
1 & 0 \\
4 & 1
\end{bmatrix}$

U stands for upper triangular matrix, L stands for lower triangular matrix

what's more,
$$\begin{bmatrix} 2 & 1 \\ 8 & 7 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 0 & 3 \end{bmatrix}$$

$$= \underbrace{\begin{bmatrix} 1 & 0 \\ 4 & 1 \end{bmatrix}}_{\mathbf{L}} \underbrace{\begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}}_{\mathbf{D}} \underbrace{\begin{bmatrix} 1 & \frac{1}{2} \\ 0 & 1 \end{bmatrix}}_{\mathbf{U}}$$

D stands for diagonal matrix

if
$$\mathbf{A} = \begin{bmatrix} & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ \mathbf{A} = \mathbf{E}_{3,1}^{-1}\mathbf{E}_{3,1}^{-1}\mathbf{E}_{3,2}^{-1}\mathbf{U} \\ & & \\$$

乘积的逆, 只需要分别求逆

we know how to invert, we should take the separate inverses, but they go in the opposite order

$$\begin{bmatrix}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & -5 & 1
\end{bmatrix}
\underbrace{\begin{bmatrix}
1 & 0 & 0 \\
-2 & 1 & 0 \\
0 & 0 & 1
\end{bmatrix}}_{\mathbf{Fat}} = \begin{bmatrix}
1 & 0 & 0 \\
-2 & 1 & 0 \\
10 & -5 & 1
\end{bmatrix}$$

I subtracted 2 of row_1 from row_2 , and then I subtracted 5 of that new row_2 from row_3 . So doing it in that order, how did row_1 affect row_3 ? Because 2 of row_1 got removed from row_2 and then 5 of those got removed from row_3 , so altogether 10 of row_1 got thrown into row_3 .

$$\mathbf{E}\mathbf{A}=\mathbf{U}$$
 (elimination) \downarrow $\mathbf{A}=\mathbf{E}^{-1}\mathbf{U}=\mathbf{L}\mathbf{U}$ (A 的信息包含于 $\mathbf{L}\mathbf{U}$)

if no row exchanges, the multipliers go directly into ${f L}$

how many operations on $n \times n$ matrix **A**?

e.g. $\begin{bmatrix} * & \cdots & \cdots & \cdots \\ 0 & & & \\ 0 & & & \\ \vdots & & & \\ 0 & & & \end{bmatrix}_{100\times100}$ $\begin{bmatrix} * & \cdots & \cdots & \cdots \\ 0 & & & \\ \vdots & & & \\ 0 & & & \end{bmatrix}_{100\times100}$ $\begin{bmatrix} * & \cdots & \cdots & \cdots \\ 0 & * & \cdots & \cdots \\ 0 & * & \cdots & \cdots \\ 0 & 0 & & \\ \vdots & \vdots & & \\ 0 & 0 & & \end{bmatrix}_{100\times100}$

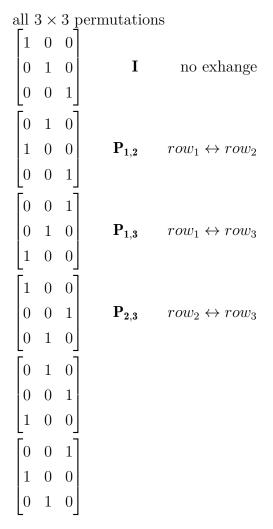
generally,

$$\sum_{i=1}^{n} i(i-1) = \frac{n(n+1)(2n+1)}{6} - \frac{n(n+1)}{2} = O(n^3)$$

I am ready to allow row exchanges.

There are some matrices that I will use to do row exchanges.

这些矩阵就是互换单位阵各行的所有的可能的情况。 e.g.



how about multiplying two of them together?
the answer is still in the list!
and if I invert, the inverses are all there too!
it's a little family of matrices there

$$\mathbf{P}^{-1} = \mathbf{P}$$

 4×4 case $\longrightarrow 24 \mathbf{P}'s$

5 Lecture 05 - 转置、置换、向量空间

书接上回 those are matrices **P** and they execute row exchanges

 $\mathbf{A} = \mathbf{L}\mathbf{U}$: assume no row exchanges

 $\mathbf{PA} = \mathbf{LU}$: **P** gets the rows into the right order

permutations \mathbf{P} is the identity matrix with reordered rows

$$\mathbf{P}^{-1} = \mathbf{P}^{\mathrm{T}}$$

$$\mathbf{P}^{\mathrm{T}}\mathbf{P}=\mathbf{I}$$

we'll be interested in matrices that have $\mathbf{P}^{T}\mathbf{P} = \mathbf{I}$, there are more of them than just permutations

$$\begin{bmatrix} 1 & 3 \\ 2 & 3 \\ 4 & 1 \end{bmatrix}^T = \begin{bmatrix} 1 & 2 & 4 \\ 3 & 3 & 1 \end{bmatrix}$$

Transpose: $(\mathbf{A}^{\mathsf{T}})_{i,j} = \mathbf{A}_{j,i}$

Symmetric Matrices: $\mathbf{A}^{\mathrm{T}} = \mathbf{A}$

 $\mathbf{R}^T\mathbf{R}$ is always symmetric

e.g.
$$\begin{bmatrix} 1 & 3 \\ 2 & 3 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 4 \\ 3 & 3 & 1 \end{bmatrix} = \begin{bmatrix} 10 & 11 & 7 \\ 11 & 13 & 11 \\ 7 & 11 & 17 \end{bmatrix}$$
$$\therefore (\mathbf{R}^{T}\mathbf{R})^{T} = \mathbf{R}^{T} (\mathbf{R}^{T})^{T} = \mathbf{R}^{T} \mathbf{R}$$

what are vector spaces? what are sub-spaces?

Example:

$$\mathbb{R}^2 \to \text{all 2-dim Real vectors}, \begin{bmatrix} 3 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} \pi \\ e \end{bmatrix}, \cdots$$

the whole plane is \mathbb{R}^2 , so \mathbb{R}^2 is the plane (xy plane)

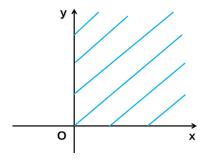
but the point is, it's a vector space

Every vector space has to ensure that zero vector in it.

 $\mathbb{R}^3 \to \text{all 3-dim Real vectors}$

 $\mathbb{R}^n \to \text{all vectors with } n \text{ real components}$

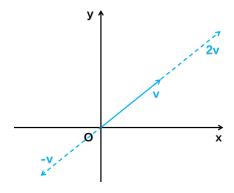
can we do additions and do we stay in the space?



in this figure, it's NOT a vector space, because it's not closed, for example, under multiplication by real numbers

a vector space has to be closed under multiplication and addition of vectors, in other words, linear combination

 \mathbb{R}^n is the most important, but we will be interested in vector spaces that are inside \mathbb{R}^n , vector spaces that follow the rules



this is a vector space inside \mathbb{R}^2 (sub-space of \mathbb{R}^2)

what are the possible sub-spaces of \mathbb{R}^2 ?

1. the whole space, \mathbb{R}^2 itself

- 2. lines through $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$ (not the same as \mathbb{R}^1)
- 3. zero vector only

what are the possible sub-spaces of \mathbb{R}^3 ?

- $1. \mathbb{R}^3$
- 2. plane through the origin
- 3. line through the origin
- 4. zero vector only

how do sub-spaces come from matrices?

I want to create some sub-spaces out of this matrix: $\mathbf{A} = \begin{bmatrix} 1 & 3 \\ 2 & 3 \\ 4 & 1 \end{bmatrix}$ all linear combinations of its columns (from \mathbb{R}^3) form a sub-space, called "column space", $C(\mathbf{A})$

the key idea is, we have to be able to take their combinations, still in the sub-space if $col_1//col_2$, then the column space is only a line through the origin

6 Lecture 06 - 列空间和零空间

vector space requirements

 \iff **v** + **w** and c**v** are in the space

 \iff all combinations $c\mathbf{v} + d\mathbf{w}$ are in the space

notice that these two requirements mean

the sum and the scale of multiplication combine into linear combinations

Example: \mathbb{R}^3

2 subspaces: P - a plane, L - a line

lacktriangled the union of those, $P \cup L$, has all vectors in P or L or both, is that a subspace? NO!

2 the intersection, $P \cap L$, has all vectors that are in both, is that a subspace?

YES!

the general question is, I have subspaces S and T, is their intersection $S \cap T$ a subspace?

ı Lo.

proof:

if
$$\mathbf{v} \in S \cap T$$
, $\mathbf{w} \in S \cap T$
then $\mathbf{v} + \mathbf{w} \in S$ and $\mathbf{v} + \mathbf{w} \in T$
so $\mathbf{v} + \mathbf{w} \in S \cap T$
if $\mathbf{v} \in S \cap T$
then $c\mathbf{v} \in S$ and $c\mathbf{v} \in T$
so $c\mathbf{v} \in S \cap T$

in other words, when you take the intersection of two subspaces, you get probably a smaller subspace, but it is still a subspace

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \\ 3 & 1 & 4 \\ 4 & 1 & 5 \end{bmatrix}$$

the column space of \mathbf{A} , $C(\mathbf{A})$, is a subspace of \mathbb{R}^4

what's in that subspace?

not only the columns of A, but also their linear combinations

so $C(\mathbf{A})$ is all linear combinations of \mathbf{A} 's columns

so I would like to know $\begin{cases} \text{ what's in that space?} \\ \text{ how big is that space?} \\ \text{ is that the whole of 4-dim space? or is it a subspace inside?} \end{cases}$

取三个四维向量进行线性组合,怎么也得不到整个四维空间嘛!

let's make this question connected with linear equations,

does $\mathbf{A}\mathbf{x} = \mathbf{b}$ always have a solution for every \mathbf{b} ?

NO, $\mathbf{A}\mathbf{x} = \mathbf{b}$ does not have a solution for every \mathbf{b} !

for example, 4 equations and 3 unknowns,

(the combinations of 3 columns cannot always fill the 4-dim space)

there's going to be some b, are not linear combinations of the 3 columns, but sometimes can

what **b**'s allow me to solve $\mathbf{A}\mathbf{x} = \mathbf{b}$?

I can solve $\mathbf{A}\mathbf{x} = \mathbf{b}$ exactly when $\mathbf{H} \mathbf{K} \mathbf{H}$ the right-hand side \mathbf{b} is a vector in $C(\mathbf{A})$. (OR \mathbf{b} is a linear combination of \mathbf{A} 's columns.)

so, $C(\mathbf{A})$ consists of all vectors $\mathbf{A}\mathbf{x}$ ($\forall \mathbf{x}$)

if **b** is not a combination of **A**'s columns, then there is no "x", there is no way to solve $\mathbf{A}\mathbf{x} = \mathbf{b}$

Example:
$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \\ 3 & 1 & 4 \\ 4 & 1 & 5 \end{bmatrix}$$

Question: Are those columns independent?

if I take the linear combinations of **A**'s columns, does each column contributes something new or not? do I get a 3-D subspace?

NO!

can I throw away any column, and will get the same column space? YES!

so for this **A**, $C(\mathbf{A})$ is a 2-D subspace of \mathbb{R}^4

the null space 零空间, is going to be a totally different subspace

the null space of **A**, what's in it?

- it contains not right-hand side **b**
- it contains x's
- it contains all \mathbf{x} 's that solve " $\mathbf{A}\mathbf{x} = \mathbf{0}$ "

$$\begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \\ 3 & 1 & 4 \\ 4 & 1 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

the null space certainly contains zero (:: the null space is a vector space as well) for this \mathbf{A} ,

$$N(\mathbf{A}) \text{ contains } \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} -4 \\ -4 \\ 4 \end{bmatrix}, \cdots, \begin{bmatrix} c \\ c \\ -c \end{bmatrix}$$

$$N(\mathbf{A}) = c \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}$$

the null space is a line in \mathbb{R}^3

to check that the solutions to $\mathbf{A}\mathbf{x} = \mathbf{0}$ always give a subspace proof:

if
$$\mathbf{A}\mathbf{x} = \mathbf{0}$$
 and $\mathbf{A}\mathbf{x}^* = \mathbf{0}$
then $\mathbf{A}(\mathbf{x} + \mathbf{x}^*) = \mathbf{0}$
what's more, $\mathbf{A}(c\mathbf{x}) = c(\mathbf{A}\mathbf{x})$

$$\begin{bmatrix} 1 & 1 & 2 \\ 2 & 1 & 3 \\ 3 & 1 & 4 \\ 4 & 1 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$$

I would like to know all the solutions to this equation, and if these solutions form a subspace? NO! As zero vector is not a solution, and subspaces have to go through the origin.

the solutions is a plane/line that does not go through the origin

Lecture 07 - 求解 Ax=0: 主变量与特解

what's the algorithm for solving $\mathbf{A}\mathbf{x} = \mathbf{0}$?

that's the null space that I'm interested in

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 2 & 2 \\ 2 & 4 & 6 & 8 \\ 3 & 6 & 8 & 10 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 2 & 2 & 2 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 2 & 4 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 2 & 2 & 2 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix} = \mathbf{U}$$

I am not changing the solutions \Longrightarrow I am not changing the null space

$$\begin{bmatrix} 1 & 2 & 2 & 2 \\ = = = = & & & \\ 0 & 0 & || & 2 & 4 \\ & = = = = & = \\ 0 & 0 & 0 & 0 \end{bmatrix} : echelon form, staircase form$$

the number of pivots = the rank of the matrix = the number of pivot variables

 $Ax = 0 \Longrightarrow Ux = 0$ same solutions, same null space

how do I describe the solutions?

四个三维向量一定线性相关

$$\begin{bmatrix} 1 & 2 & 2 & 2 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$
 2 free columns, 2 pivot columns

free means that we can assign values freely, and we can find the other values accordingly

for convenient purpose, we choose 1 and 0 to those free variables

$$\mathbf{x_1} = \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \ \mathbf{x_2} = \begin{bmatrix} 2 \\ 0 \\ -2 \\ 1 \end{bmatrix}$$
 2 special solutions (I gave special numbers to free variables)

$$\mathbf{x} = c \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + d \begin{bmatrix} 2 \\ 0 \\ -2 \\ 1 \end{bmatrix} = c\mathbf{x_1} + d\mathbf{x_2}$$

I am taking all the linear combinations of my 2 special solutions, and they are null space.

how many special solution are there? 每个自由变量对应一个特解

with rank
$$r$$
, $(n-r)$ free variables

we get r pivot variables, so there are really r equations there, only r independent equations, and there are (n-r) variables that we can choose freely

Algorithms to Solve Ax = 0

- 1. do elimination
- 2. decide which are pivot columns and which are free columns
- 3. give values to free variables
- 4. complete pivot values accordingly
- 5. do linear combinations

reduced row echelon form (U 还可以简化)

$$\mathbf{U} = \begin{bmatrix} 1 & 2 & 2 & 2 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 2 & 0 & -2 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix} \longrightarrow \begin{bmatrix} \boxed{1} & 2 & 0 & -2 \\ 0 & 0 & \boxed{1} & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} = \mathbf{R}$$

in rref, it has zeros above and below the pivots

$$\begin{bmatrix}
1 & 2 & 0 & -2 \\
0 & 0 & 1 & 2 \\
0 & 0 & 0 & 0
\end{bmatrix}$$

notice that there is an identity sitting in the pivot rows and pivot columns!

$$Ax = 0 \Longrightarrow Ux = 0 \Longrightarrow Rx = 0$$

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 2 & 2 \\ 2 & 4 & 6 & 8 \\ 3 & 6 & 8 & 10 \end{bmatrix}$$

$$\mathbf{A}^{\mathbf{T}} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 2 & 6 & 8 \\ 2 & 8 & 10 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 2 & 2 \\ 0 & 4 & 4 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

so the rank is 2 again!

the number of special solutions is 1

the fact: the number of pivot columns of A and A^T is the same

8 Lecture 08 - 可解性与解的结构

$$\begin{cases} 1x_1 + 2x_2 + 2x_3 + 2x_4 = b_1 \\ 2x_1 + 4x_2 + 6x_3 + 8x_4 = b_2 \\ 3x_1 + 6x_2 + 8x_3 + 10x_4 = b_3 \end{cases}$$

there is a condition on b_1 , b_2 , b_3 for this system to have a solution

$$\underbrace{\begin{bmatrix} 1 & 2 & 2 & 2 & b_1 \\ 2 & 4 & 6 & 8 & b_2 \\ 3 & 6 & 8 & 10 & b_3 \end{bmatrix}}_{3} \longrightarrow \begin{bmatrix} 1 & 2 & 2 & 2 & b_1 \\ 0 & 0 & 2 & 4 & b_2 - 2b_1 \\ 0 & 0 & 2 & 4 & b_3 - 3b_1 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 2 & 2 & 2 & b_1 \\ 0 & 0 & 2 & 4 & b_2 - 2b_1 \\ 0 & 0 & 0 & 0 & b_3 - b_2 - b_1 \end{bmatrix}$$

augmented matrix=
$$\left[egin{array}{c|c} \egin{array}{c|c} \egin{ar$$

 $b_3 - b_2 - b_1 = 0$, this is the condition for solvability

suppose that
$$\mathbf{b} = \begin{bmatrix} 1 \\ 5 \\ 6 \end{bmatrix}$$
,
$$\begin{bmatrix} \mathbf{A} \mid \mathbf{b} \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 2 & 2 & 2 \mid 1 \\ 0 & 0 & 2 & 4 \mid 3 \\ 0 & 0 & 0 & 0 \mid 0 \end{bmatrix}$$

what are the conditions on \mathbf{b} that make the equation system solvable?

Solvability Condition on **b**

表述一

当且仅当 \mathbf{b} 属于 \mathbf{A} 的列空间时成立

或者 b 必须是 A 各列的线性组合

• 表述二

if a combination of the rows of A gives the zero row,

the same combination of the components of b has to give zero

what's the algorithm to find the solutions?

1. a particular solution, $\mathbf{x}_{particular}$

to set all free variables to zero,

since those free variables can be anything,

then solve $\mathbf{A}\mathbf{x} = \mathbf{b}$ to get the pivot variables

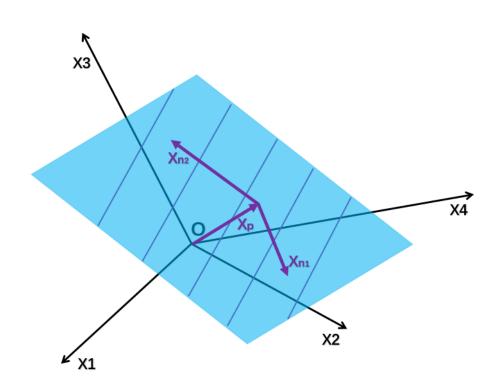
in this case,
$$\mathbf{x}_p = \begin{bmatrix} -2\\0\\3/2\\0 \end{bmatrix}$$

2. **x** from null space, $\mathbf{x}_{null space}$

in this case,
$$\mathbf{x}_n = c_1 \begin{bmatrix} -2\\1\\0\\0 \end{bmatrix} + c_2 \begin{bmatrix} 2\\0\\-2\\1 \end{bmatrix}$$

3. $\mathbf{x}_c = \mathbf{x}_p + \mathbf{x}_n, \, \mathbf{x}_{complete}$

in this case,
$$\mathbf{x}_c = \begin{bmatrix} -2\\0\\3/2\\0 \end{bmatrix} + c_1 \begin{bmatrix} -2\\1\\0\\0 \end{bmatrix} + c_2 \begin{bmatrix} 2\\0\\-2\\1 \end{bmatrix}$$



"由零空间这个子空间从原点平移过来得到的平面"

think of a $m \times n$ matrix **A** of rank r, $\begin{cases} r \leq m \\ r \leq n \end{cases}$

• full column rank (r = n) 意味着全部向量撑开全部的维数 there's a pivot in every column, no free variables

there are no free variables to give values, so the null space is only the zero vector

i.e.
$$N(\mathbf{A}) = \{\mathbf{0}\}$$

the complete solution to $\mathbf{A}\mathbf{x} = \mathbf{b}$ is just \mathbf{x}_p , it's the unique solution if \mathbf{x}_p exists "列满秩时,如果解存在($\mathbf{b} \in C(\mathbf{A})$),那么解唯一""此时只有零个解或一个解"

- full row rank (r = m)
 every row has a pivot
 I can solve Ax = b for any b
 "在消元时没有得到零行!"
 number(free-variables) = n m
- r = m = n
 invertible!
 此时 Ax = b 必定有解且解唯一
- r < m and r < n0 solution or ∞ solutions

9 Lecture 09 - 线性相关性、基、维数

key words:

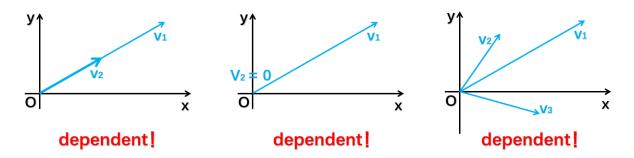
- linear independence
- spanning a space
- basis for a subspace / basis for a vector space
- the dimension of a subspace

we talk about a bunch of vectors $\begin{cases} \text{being independent} \\ \text{spanning a space} \\ \text{being a basis} \end{cases}$

suppose **A** is a $m \times n$ (m < n) matrix, (#unknowns > #equations) then there are non-zero solutions to $\mathbf{A}\mathbf{x} = \mathbf{0}$ \implies 在 **A** 的零空间中,除了零向量之外,还包含了其他一些向量

the reason is, there will be free variables, at least one, which I can assign non-zero values to

vectors $\mathbf{x_1}, \, \mathbf{x_2}, \, \cdots, \, \mathbf{x_n}$ are independent if no combination, except the "zero combination", gives the zero vector



corollary

- if the zero vector is in there, "independent is dead"
- 如果零空间 $N(\mathbf{A})$ 里存在非零向量,那么各列相关

when $\mathbf{v_1}, \mathbf{v_2}, \cdots, \mathbf{v_n}$ are columns of \mathbf{A} ,

they are independent if null space of **A** is only the zero vector, rank = n, NO free variables, they are dependent if there exists non-zero **c**, such that $\mathbf{Ac} = \mathbf{0}$, rank < n, YES free variables

vectors $\mathbf{v_1}$, $\mathbf{v_2}$, \cdots , $\mathbf{v_l}$ span a space means, the space consists of all combinations of those vectors,

the space will be the smallest space with those combinations in it the column space of a matrix, is the space spanned by its columns a basis for a vector space is a sequence of vectors, $\mathbf{v_1}, \mathbf{v_2}, \cdots, \mathbf{v_d}$, with 2 properties: (向量的个数例例好)

- they are independent
- they can span the space

Example: space is
$$\mathbb{R}^3$$
 one basis is $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ another basis is $\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$, $\begin{bmatrix} 2 \\ 3 \\ 4 \\ 5 \end{bmatrix}$

for \mathbb{R}^n , n vectors give a basis if the $n \times n$ matrix with those columns is invertible the basis is not unique, for \mathbb{R}^3 , any invertible 3×3 matrix, its columns are a basis for \mathbb{R}^3 but there is a common character of those bases, that's the number of vectors!

Given a space, every basis for the space has the same number of vectors.

Example:
$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 1 & 1 & 2 & 1 \\ 1 & 2 & 3 & 1 \end{bmatrix}$$
 one of the bases for $C(\mathbf{A})$ is $\left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix} \right\}$ one of the bases for $N(\mathbf{A})$ is $\left\{ \begin{bmatrix} -1 \\ -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$

the rank of **A** is 2 = the number of pivot columns = the dimension of $C(\mathbf{A})$

$$dim\ C(\mathbf{A}) = rank(\mathbf{A}) = r$$
 $dim\ N(\mathbf{A}) = the\ number\ of\ free\ variables = n-r$

¹Def. dimension of the space

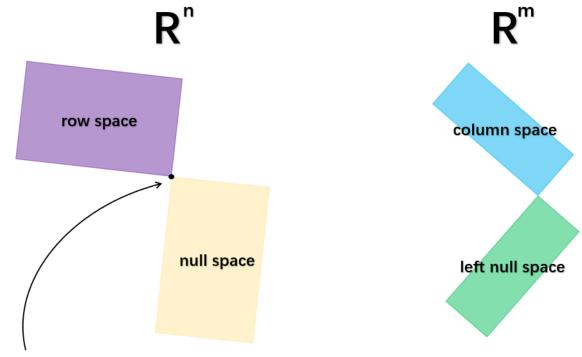
行秩等于列秩!

standard basis for
$$\mathbb{R}^3$$
 is $\left\{ \begin{bmatrix} 1\\0\\0 \end{bmatrix}, \begin{bmatrix} 0\\1\\0 \end{bmatrix}, \begin{bmatrix} 0\\0\\1 \end{bmatrix} \right\}$

10 Lecture 10 - 四个基本子空间

4 fundamental subspaces of $\mathbf{A}_{m \times n}$

- the column space, $C(\mathbf{A})$, $C(\mathbf{A}) \subset \mathbb{R}^m$
- the null space, $N(\mathbf{A})$, $N(\mathbf{A}) \subset \mathbb{R}^n$
- the row space, it's all the combinations of the rows, $C(\mathbf{A}^T)$, $C(\mathbf{A}^T) \subset \mathbb{R}^n$
- the null space of $\mathbf{A}^{\mathbf{T}}$, $N(\mathbf{A}^{\mathbf{T}})$, the left null space of \mathbf{A} , $N(\mathbf{A}^{\mathbf{T}}) \subset \mathbb{R}^m$



行空间与零空间正交。 行空间与零空间只会有一个交点,那就是零向量。

	$C(\mathbf{A})$	$C(\mathbf{A^T})$	$N(\mathbf{A})$	$N(\mathbf{A^T})$
basis	the pivot columns	the first r rows of \mathbf{R}	the special solutions	
dimension	$\mathrm{rank}\ r$	$\mathrm{rank}\ r$	n-r	m-r

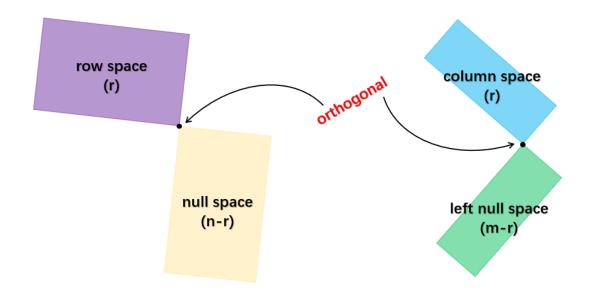
the row space and the column space have the same dimension!

 $\mathbf{A} \xrightarrow{rref()} \mathbf{R}$ different column space, same row space 因为 \mathbf{R} 是由 \mathbf{A} 经过行变化而来,所以它们共享同一个行空间。

11 Lecture 14 - 正交向量与子空间

key words:

- orthogonal vectors
- orthogonal subspaces
- orthogonal bases



orthogonal (perpendicular) vectors: $\mathbf{x}^T\mathbf{y} = \mathbf{0}$ proof:

subspace S is orthogonal to subspace T,

means that every vector in S is orthogonal to every vector in T



row space is orthogonal to null space, why?

$$\mathbf{A}\mathbf{x} = \mathbf{0}$$

$$\begin{bmatrix} row_1 \\ row_2 \\ \cdots \\ row_m \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ x_n \end{bmatrix}$$
therefore,
$$c_1(\mathbf{row}_1)^{\mathbf{T}}\mathbf{x} = 0$$

$$c_2(\mathbf{row}_2)^{\mathbf{T}}\mathbf{x} = 0$$

$$\cdots \cdots$$

$$c_m(\mathbf{row}_m)^{\mathbf{T}}\mathbf{x} = 0$$

$$\vdots [c_1(\mathbf{row}_1)^{\mathbf{T}} + c_2(\mathbf{row}_2)^{\mathbf{T}} + \cdots + c_m(\mathbf{row}_m)^{\mathbf{T}}] \mathbf{x} = \mathbf{0}$$

$$\vdots [c_1\mathbf{row}_1 + c_2\mathbf{row}_2 + \cdots + c_m\mathbf{row}_m]^{\mathbf{T}} \mathbf{x} = \mathbf{0}$$

$$Q.E.D.$$

正交子空间可以不同维!

null space and row space are orthogonal complements (补集) in \mathbb{R}^n 注: 空间的正交补,包含了所有与之正交的向量,而不只是部分。 null space contains all, not just some, vectors that are perpendicular to row space

[&]quot;non-zero vectors are not orthogonal to themselves"

[&]quot;if two subspaces meet at some non-zero vectors, they are not orthogonal"

12 Lecture 15 - 子空间投影

"如何求一个无解的方程组的解?"(回归问题、拟合、坏数据)

"solve" $\mathbf{A}\mathbf{x} = \mathbf{b}$ when there is no solution, what's the best solution?

$\mathbf{A}^{\mathbf{T}}\mathbf{A}$ is symmetric

proof:

$$(\mathbf{A}^{\mathsf{T}}\mathbf{A})^{\mathsf{T}} = \mathbf{A}^{\mathsf{T}}\mathbf{A}^{\mathsf{TT}} = \mathbf{A}^{\mathsf{T}}\mathbf{A}$$

$$rank(\mathbf{A}^{\mathbf{T}}\mathbf{A}) = rank(\mathbf{A})$$

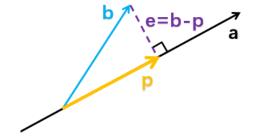
 $rank(\mathbf{AB}) \leq min\{rank(\mathbf{A}), rank(\mathbf{B})\}$

$$\mathbf{A}\mathbf{x} = \mathbf{b} \longrightarrow \mathbf{A}^T \mathbf{A} \widehat{\mathbf{x}} = \mathbf{A}^T \mathbf{b}$$

 $\mathbf{A^TA}$ 不一定是可逆的 ,例如零矩阵,或者 $\begin{bmatrix} 1 & 3 \\ 1 & 3 \\ 1 & 3 \end{bmatrix}$

 $\mathbf{A}^{\mathbf{T}}\mathbf{A}$ is invertible exactly if \mathbf{A} has independent columns

考虑二维的情况



$$\begin{aligned} \mathbf{a}^{\mathbf{T}}\mathbf{e} &= \mathbf{a}^{\mathbf{T}}(\mathbf{b} - \mathbf{p}) = \mathbf{a}^{\mathbf{T}}(\mathbf{b} - \lambda \mathbf{a}) = 0 \\ \Longrightarrow \lambda \mathbf{a}^{\mathbf{T}}\mathbf{a} &= \mathbf{a}^{\mathbf{T}}\mathbf{b} \\ \Longrightarrow \lambda &= \frac{\mathbf{a}^{\mathbf{T}}\mathbf{b}}{\mathbf{a}^{\mathbf{T}}\mathbf{a}} \in \mathbb{R} \\ \Longrightarrow \mathbf{p} &= \lambda \cdot \mathbf{a} = \mathbf{a} \cdot \lambda = \mathbf{a} \cdot \frac{\mathbf{a}^{\mathbf{T}}\mathbf{b}}{\mathbf{a}^{\mathbf{T}}\mathbf{a}} = \frac{\mathbf{a}\mathbf{a}^{\mathbf{T}}}{\mathbf{a}^{\mathbf{T}}\mathbf{a}} \cdot \mathbf{b} = \mathbf{P}\mathbf{b} \end{aligned}$$

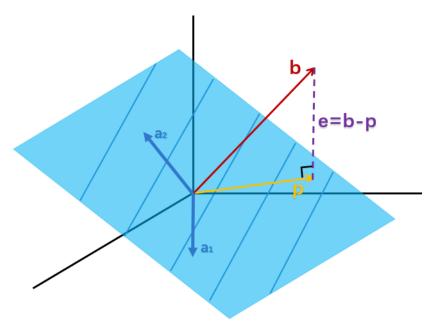
 ${f P}$ is the projection matrix acting on the input, ${f P}^2 = {f P}, \, {f P}^T = {f P}$ if ${f b}$ is doubled, ${f p}$ will be doubled if ${f a}$ is doubled, ${f p}$ will not change at all

为什么这里要引入投影矩阵?

 \therefore **Ax** = **b** may have no solutions

- ... I turn to solve the closest problem that I can solve
- ∴ **Ax** will always be in the column space of **A**, but **b** is probably not (所以我要怎么微调 **b**?)
- \therefore solve $\mathbf{A}\hat{\mathbf{x}} = \mathbf{p}$ instead, where \mathbf{p} is the projection of \mathbf{b} onto the column space

考虑三维的情况



 $\{\mathbf{a_1}, \mathbf{a_2}\}$ is a basis for the plane, plane is the column space of **A** 若 **b** 不在列空间中,则投影到列空间里,若 **b** 在列空间中,则投影结果就是 **b** 自己 **e** is perpendicular to the plane 投影 **p** 是基向量 $\{\mathbf{a_1}, \mathbf{a_2}\}$ 的线性组合, $\mathbf{p} = \hat{x_1}\mathbf{a_1} + \hat{x_2}\mathbf{a_2}$ (在 $\mathbf{a_1}$ 方向和 $\mathbf{a_2}$ 方向的投影之和)

如前文所说,我们改为求解 $\mathbf{A}\hat{\mathbf{x}} = \mathbf{p}$ (to find $\hat{\mathbf{x}}$)

key: $\mathbf{e} = \mathbf{b} - \mathbf{p} = \mathbf{b} - \mathbf{A}\hat{\mathbf{x}}$ is perpendicular to the plane

$$:: \mathbf{A}^{\mathrm{T}} \mathbf{e} = \mathbf{0}$$

$$\therefore \mathbf{A}^{\mathrm{T}}(\mathbf{b} - \mathbf{A}\widehat{\mathbf{x}}) = \mathbf{0}$$

$$\hat{\mathbf{x}} = (\mathbf{A}^{\mathrm{T}}\mathbf{A})^{-1}\mathbf{A}^{\mathrm{T}}\mathbf{b} \iff$$
 这就是方程的近似解

$$\mathbf{p} = \mathbf{A}\widehat{\mathbf{x}} = \mathbf{A}(\mathbf{A}^T\mathbf{A})^{-1}\mathbf{A}^T\mathbf{b}$$

$$\mathbf{P} = \mathbf{A}(\mathbf{A}^{\mathrm{T}}\mathbf{A})^{-1}\mathbf{A}^{\mathrm{T}}$$

if **A** is invertible, then $\mathbf{A}(\mathbf{A}^{T}\mathbf{A})^{-1}\mathbf{A}^{T} = \mathbf{I}$

注意,以上对一般的情况不成立,毕竟 A 甚至不是方阵!

if **A** is square and invertible,

此时 $C(\mathbf{A})$ 为整个 \mathbb{R}^{\times} 空间,则 $\mathbf{P} = \mathbf{I}$!

"汝即此间人,不借此间物。"