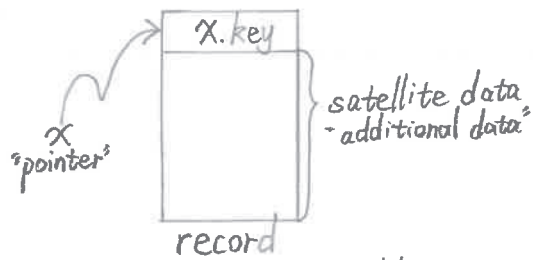


Lec 07 哈希表

symbol-table problem (in compilers):
table S holding n records



operations on this table

- insert (S, x): $S \leftarrow S \cup \{x\}$
"insert a record into this table"
 - delete (S, x): $S \leftarrow S - \{x\}$
 - search (S, k): return x such that $x.key = k$ or nil if no such x
"search for a given key"
- } dynamic set

direct access table

"it works when the keys are drawn from small distribution"
suppose keys are drawn from $U = \{0, 1, \dots, m-1\}$.
assume the keys are distinct,
set up an array $T[0 \dots m-1]$ to represent the dynamic set S ,
such that $T[k] = \begin{cases} x, & \text{if } x \in S \text{ and } x.key = k \\ \text{nil}, & \text{otherwise} \end{cases}$

相当于存放指针的数组

all operations take constant time in the worst case

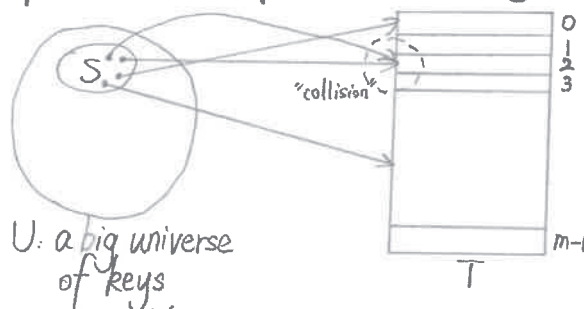
limitations: ① m should be small

② even worse, most of the table would be empty in some case

"我们希望在保存记录的同时,让表的规模可能的小,保留某些特性"

Hashing

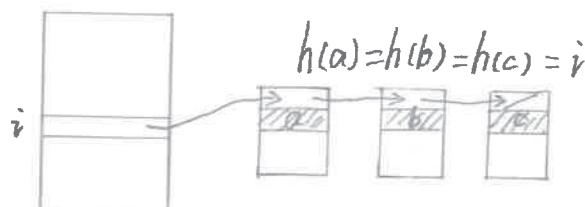
a hash function h maps keys "randomly" into slots of table T



when a record (to be inserted) maps to an already occupied slot, a collision occurs
"对每个槽创建一个链表,把所有映射到这个槽的元素都存放到这个槽的链表里面去"
resolving collisions by chaining!

the idea is to link records in the same slot into a list

Example:



Analysis:

worst-case: every key hashes to the same slot (所有键都哈希映射到同一个槽)
access takes $\Theta(n)$ time if $|S| = n$

average-case: assumption of simple uniform hashing

"each key $k \in S$ is equally likely to be hashed to any slot in T , independent of where other keys are hashed"

Def. the load factor of a hash table with n keys at m slots

is $\alpha = \frac{n}{m}$ = average number of keys per slot

expected unsuccessful search time = $\Theta(1 + \alpha)$

expected search time = $\Theta(1)$ if $\alpha = O(1)$, i.e., if $n = O(m)$

expected successful search time = $\Theta(1 + \alpha)$ too.

Choosing a Hash Function

- should distribute keys uniformly into slots
- regularity in key distribution should not affect uniformity

"键值分布的特点"

Example: division method, $h(k) = k \bmod m$

don't pick m (with small divisor d)!

if $d=2$ and all keys are even, then odd slots never used
(i.e. m is even)

"regularity in key distribution"

if $m = 2^r$, then hash doesn't depend on all bits of k

$k = 1011000111011010$ $r=6$
 $m=2^6$

pick $m = \text{prime (质数)}$ not too close to a power of 2 or 10 (有很多关于质数的定理)

Example: multiplication method

槽的数量 $m = 2^r$, and computer has w bit words

$h(k) = (A \cdot k \bmod 2^w) \text{ rsh } (w-r)$
"right shifted"

an odd integer in the range $2^{w-r} < A < 2^w$

fast method! (faster than division)

if $m = 8 = 2^3$, $w = 7$, $A = 1011001$, $k = 1101011$

then $A \cdot k = 10010100110011$

$A \cdot k \bmod 2^w = (\text{忽略前几位, 只取后 } w \text{ 位}) 0110011$

$(A \cdot k \bmod 2^w) \text{ rsh } (w-r) = 011 = h(k)$

"times" $\begin{array}{r} 1011001 = A \\ \otimes 1101011 = k \\ \hline 10010100110011 \end{array}$
high-order ignored $\quad h(k) \quad \text{rsh} \rightarrow$

modular wheel for intuition:

$$\begin{array}{r} 1011001 = A \\ \times 1101011 = k \end{array} \rightarrow \begin{array}{r} 1011001 = A' \\ \times 1101011 = k \end{array}$$

小数点



resolving collisions by open addressing - no storage for links

回到一开始那个问题

the idea is that to probe the table systematically, until an empty slot is found

$$h: U \times \{0, 1, \dots, m-1\} \rightarrow \{0, 1, \dots, m-1\}$$

\uparrow universe of keys \uparrow probe number \uparrow slot

- the probe sequence should be permutation of 0 to $m-1$
- the table may actually fill up in the end ($n \leq m$, n is #elements, m is #slots)
- deletion is difficult, yet not impossible

有人按照探查序列来查找另一个键，他本应先发现这里不是他要的键，然而再向下查找，然而现在却发现这个槽是空的

Example: insert $k=496$ into table as below

586
133
204
481

0-step: probe $h(496, 0)$

假设哈希映射到 204 这个槽，发现已经被占。

1-step: 则再探查一次， $h(496, 1)$

假设哈希映射到 586 这个槽，发现已经被占。

2-step: $h(496, 2)$

假设哈希映射到一个空槽，则把键放入这个槽。

search is the same probe sequence.

if successful, it finds the record.

if unsuccessful, it finds nil

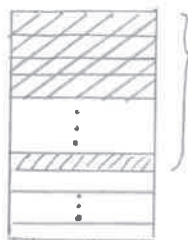
probing strategies for open addressing

• linear probing

$$h(k, i) = (h(k, 0) + i) \bmod m$$

“一个个地查找”

“primary clustering”: long runs of filled slots



如果一连块区域都被占用了, 那接下来都得先遍历到这个区域的底部

• double hashing probing

$$h(k, i) = (h_1(k) + i \cdot h_2(k)) \bmod m$$

excellent!

usually pick $m = 2^r$ and $h_2(k)$ to be odd

Analysis of open addressing

assumption of uniform hashing: each key is equally likely to have any one of the $m!$ permutations as its probe sequence is independent of other keys

Theorem: the expected number of probes is at most $\frac{1}{1-\alpha}$ if $\alpha < 1$

proof: (unsuccessful search)

1st probe always necessary,

with $\frac{n}{m}$ probability, we have a collision \Rightarrow 2nd probe necessary

(you are not going to hit the same slot) with probability $\frac{n-1}{m-1}$, collision \Rightarrow 3rd probe nec.

..... $\frac{n-2}{m-2}$

note $\frac{n-i}{m-i} < \frac{n}{m} = \alpha$ for $i = 1, 2, \dots, n-1$

$$E(\# \text{ probes}) = 1 + \frac{n}{m} \left(1 + \frac{n-1}{m-1} \left(1 + \frac{n-2}{m-2} \left(\dots \left(1 + \frac{1}{m-n} \right) \dots \right) \right) \right)$$

$$\leq 1 + \alpha (1 + \alpha (1 + \alpha (\dots (1 + \alpha) \dots)))$$

每一步有连锁的影响

$$\leq 1 + \alpha + \alpha^2 + \alpha^3 + \dots$$

$$= \sum_{i=0}^{\infty} \alpha^i$$

$$= \frac{1}{1-\alpha} \quad \text{geometric series}$$

const $\alpha < 1 \Rightarrow O(1)$ probes

if $\alpha = 0.5$ (i.e. 50% full), then 2 probes, if 90% full, then 10 probes (急剧上升)