Fundamentals of Optimization

Subgradient method

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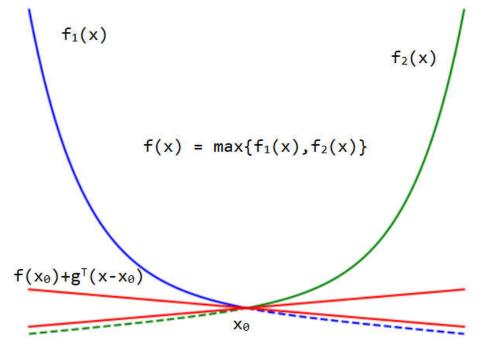
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Subgradient method

- For minimize nondifferentiable convex function
- Subgradient method is not a descent method: the function value can increase

Subgradient method

- Subgradient of f at x
 - Any vector g such that $f(x') \ge f(x) + g^T(x'-x)$
 - If f is differentiable, only possible choice is g^(k) = ∇f(x^(k)),
 → the subgradient method reduces to the gradient method



Basic subgradient method

$$x^{(k+1)} = x^{(k)} - \alpha_k g^{(k)}$$

- $x^{(k)}$: is at the k^{th} iteration
- $g^{(k)}$: any subgradient of f at $x^{(k)}$
- $\alpha_k > 0$ is the k^{th} step size
- Note: subgradient is not a descent method, thus $f_{best}^{(k)} = \min\{f(x^{(1)}), f(x^{(2)}), \dots, f(x^{(k)})\}$

- Notations: x* is a minimizer of f
- Assumptions
 - Norm of the subgradients is bounded (with a constant G): $||g^{(k)}||_2 \le G$ (this is the case if, for example, f satisfies the Lipschitz condition $|f(u) f(v)| \le G||u-v||_2$)
 - $||x^{(1)} x^*|| 2 \le R$ (with a known constant R)
- We have $||x^{(k+1)} x^*||_2^2 = ||x^{(k)} \alpha_k g^{(k)} x^*||_2^2$ = $||x^{(k)} - x^*||_2^2 - 2\alpha_k g^{(k)T}(x^{(k)} - x^*) + \alpha_k^2 ||g^{(k)}||_2^2$ $\leq ||x^{(k)} - x^*||_2^2 - 2\alpha_k (f(x^{(k)}) - f(x^*)) + \alpha_k^2 ||g^{(k)}||_2^2$ (due to the fact that $f(x^*) \geq f(x^{(k)}) + g^{(k)T}(x^* - x^{(k)})$) (1)

• Apply the inequality (1) recursively, we have $||x^{(k+1)} - x^*||_2^2 \le ||x^{(1)} - x^*||_2^2 - 2\sum_{i=1}^k \alpha_i (f(x^{(i)}) - f^*) + \sum_{i=1}^k \alpha_i^2 ||g^{(i)}||_2^2 \text{ (where } f^* = f(x^*))$ $\Rightarrow 2\sum_{i=1}^k \alpha_i (f(x^{(i)}) - f^*) \le R^2 + \sum_{i=1}^k \alpha_i^2 ||g^{(i)}||_2^2$ $\Rightarrow R^2 + \sum_{i=1}^k \alpha_i^2 ||g^{(i)}||_2^2 \ge 2\sum_{i=1}^k \alpha_i (f(x^{(i)}) - f^*) \ge$ $2(\sum_{i=1}^k \alpha_i) \min_{\substack{i=1,\ldots,k \\ j \text{ best}}} (f(x^{(i)}) - f^*) = 2\sum_{i=1}^k \alpha_i (f_{best}^{(k)} - f^*)$ $\Rightarrow f_{best}^{(k)} - f^* \le \frac{R^2 + \sum_{i=1}^k \alpha_i^2 ||g^{(i)}||_2^2}{2\sum_{i=1}^k \alpha_i}$ (2)

- Different cases
 - Constant step size $\alpha_k = \alpha$

- $\rightarrow f_{best}^{(k)} f^*$ converges to $G^2 \alpha / 2$ when $k \rightarrow \infty$
 - Constant step length $\alpha_k = \gamma / ||g^{(k)}||_2$

 $\rightarrow f_{best}^{(k)} - f^*$ converges to $G\gamma/2$ when $k \to \infty$

- Different cases
 - Square summable but not summable

$$||\alpha||_2^2 = \sum_{i=1}^{\infty} \alpha_i^2 < \infty$$
 and $\sum_{i=1}^{\infty} \alpha_i = \infty$

 $\rightarrow f_{best}^{(k)} - f^*$ converges to 0 as $k \rightarrow \infty$

Example

minimize
$$f(x) = \max_{i=1,...,m} (a_i^T x + b_i)$$

Finding subgradient: given x, the index j for which

$$a_j^T x + b_j = \max_{i=1,...,m} (a_i^T x + b_i)$$

 \rightarrow subgradient at x is $g = a_j$

Example

```
import numpy as np
def solve(A,b):
    f = lambda x: np.max(A.dot(x) + b)
    sg = lambda x: A[np.argmax(A.dot(x) + b)]
    x0 = [0,0,0,0]
    x = np.array(x0).T
    f best = f(x)
    for i in range(100000):
        alpha = 2
        x = x - alpha*sg(x)
        if f_best > f(x):
            f_best = f(x)
    return f_best
```

Example

```
def main():
    A = np.array([[1,-2,3,-5],[2,-2,1,1],[-3,2,-2,7]],dtype='double')
    b = np.array([3,4,5]).T
    rs = solve(A,b)
    print('rs = ',rs)

if __name__ == '__main__':
    main()
```