#### Feedback — Final Exam

Help Center

You submitted this exam on **Wed 11 Mar 2015 5:00 PM IST**. You got a score of **40.00** out of **40.00**.

### **Question 1**

Recall the Partition subroutine that we used in both QuickSort and RSelect. Suppose that the following array has just been partitioned around some pivot element: 3, 1, 2, 4, 5, 8, 7, 6, 9

Which of these elements could have been the pivot element? (Hint: Check all that apply, there could be more than one possibility!)

Your Answer		Score	Explanation
9	<b>~</b>	0.40	All numbers to the left of it are less than it; all numbers to the right of it are bigger than it; so it could have been the pivot.
<b>5</b>	<b>~</b>	0.40	All numbers to the left of it are less than it; all numbers to the right of it are bigger than it; so it could have been the pivot.
_ 2	<b>~</b>	0.40	Because there is a "3" to the left of it, "2" could not have been the pivot.
<b>4</b>	~	0.40	All numbers to the left of it are less than it; all numbers to the right of it are bigger than it; so it could have been the pivot.
<b>3</b>	~	0.40	Because there is a "1" and "2" to the right of it, "3" could not have been the pivot.
Total		2.00 / 2.00	

## **Question 2**

Here is an array of ten integers: 5 3 8 9 1 7 0 2 6 4

Suppose we run MergeSort on this array. What is the number in the 7th position of the partially sorted array after the outermost two recursive calls have completed (i.e., just before the very last Merge step)? (When we say "7th" position, we're counting positions starting at 1; for example, the input array has a "0" in its 7th position.)

Your Answer		Score	Explanation
<u>3</u>			
<u> </u>			
2	<b>~</b>	2.00	The array at this point of the algorithm is 1 3 5 8 9 0 2 4 6 7
_ 4			
Total		2.00 / 2.00	

#### **Question 3**

What is the asymptotic worst-case running time of MergeSort, as a function of the input array length n?

Your Answer		Score	Explanation
$\theta(n \log n)$	<b>✓</b>	2.00	As discussed in lecture.
$ heta(\log n)$			
$ heta(n^2)$			
heta(n)			
- otal		2.00 / 2.00	

Consider a directed graph G=(V,E) with non-negative edge lengths and two distinct vertices s and t of V. Let P denote a shortest path from s to t in G. If we add 10 to the length of every edge in the graph, then: [Check all that apply.]

Your Answer		Score	Explanation
If $P$ has only one edge, then $P$ definitely remains a shortest $s-t$ path.	<b>~</b>	0.50	Every path $P$ goes up in length by at least as much as $P$ does, so $P$ remains the shortest.
$\begin{subarray}{ c c c c c }\hline P & { m might} & { m or} & { m might} & { m not} & { m remain} \\ { m a shortest} & s-t & { m path} \\ { m (depending on the graph)}. \\ \end{subarray}$	<b>~</b>	0.50	As discussed in lecture, adding a constant to every edge can change the shortest path. (Built might not, if you get lucky.)
$\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $	<b>~</b>	0.50	If you get lucky (e.g., $P$ has only one edge) then $P$ might remain a shortest path.
$\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ $	<b>~</b>	0.50	As discussed in lecture, adding a constant to every edge can change the shortest path.
Total		2.00 / 2.00	

## **Question 5**

What is the running time of depth-first search, as a function of n and m, if the input graph G=(V,E) is represented by an adjacency matrix (i.e., NOT an adjacency list), where as usual n=|V| and m=|E|?

Your Answer	Score	Explanation	
heta(n*m)			

$ heta(n^2\log m)$							
$igorphi$ $ heta(n^2)$	<b>✓</b> 2.00	For the lower bound, in the worst case you have to look at every entry twice. For the upper bound, one easy approach is construct the adjacency list from the adjacency matrix (this is easy to do with a scan over the matrix) and then use the subroutine from the video lectures.					
Total	2.00 / 2.00						

What is the asymptotic running time of the Insert and Extract-Min operations, respectively, for a heap with n objects?

Your Answer		Score	Explanation
$igoplus\Theta(\log n)$ and $\Theta(1)$			
$igoplus \Theta(1)$ and $\Theta(\log n)$			
$igoplus \Theta(\log n)$ and $\Theta(\log n)$	<b>~</b>	2.00	
$igoplus\Theta(n)$ and $\Theta(1)$			
Total		2.00 / 2.00	

# **Question 7**

On adding one extra edge to a directed graph G, the number of strongly connected components...?

Your Answer		Score	Explanation
might or might not remain the same (depending on the graph).	<b>~</b>	2.00	That's correct!

2.00 /	
2.00	

What is the asymptotic running time of Randomized QuickSort on arrays of length n, in expectation (over the choice of random pivots) and in the worst case, respectively?

Your Answer	Score	Explanation
$igoplus \Theta(n\log n)$ [expected] and $\Theta(n\log n)$ [worst case]		
$igoplus \Theta(n^2)$ [expected] and $\Theta(n^2)$ [worst case]		
$\Theta(n)$ [expected] and $\Theta(n\log n)$ [worst case]		
$igoplus \Theta(n\log n)$ [expected] and $\Theta(n^2)$ [worst case]	✔ 2.00	The expected case was shown to be $O(n\log n)$ in lecture. In the worst case, you might repeatedly pick the minumum remaining element as the pivot.
Total	2.00 / 2.00	

# **Question 9**

Let f and g be two increasing functions, defined on the natural numbers, with  $f(1),g(1)\geq 1$ .

Assume that f(n)=O(g(n)). Is  $2^{f(n)}=O(2^{g(n)})$  ? (Multiple answers may be correct, check all that apply.)

Your Answer		Score	Explanation
Never	~	0.50	Yes if $f(n)=g(n)=n.$
Yes if $f(n) \leq g(n)$ for all sufficiently large $n$	<b>~</b>	0.50	Take $c=1$ and $n_0$ sufficiently large.
$\begin{tabular}{ll} \hline & Maybe, maybe not \\ (depends on the functions $f$ \\ and $g$). \\ \hline \end{tabular}$	<b>~</b>	0.50	For a positive example, take $f(n)=g(n)=n$ For a negative example, take $f(n)=2n$ and $g(n)=n.$
Always	~	0.50	Not if $f(n)=2n$ and $g(n)=n$ .
Total		2.00 / 2.00	

## **Question 10**

Let  $0<\alpha<.5$  be some constant. Consider running the Partition subroutine on an array with no duplicate elements and with the pivot element chosen uniformly at random (as in QuickSort and RSelect). What is the probability that, after partitioning, both subarrays (elements to the left of the pivot, and elements to the right of the pivot) have size at least  $\alpha$  times that of the original array?

Your Answer		Score	Explanation
$\bigcirc$ $1-2lpha$	~	2.00	That's correct!
$\bigcirc 2-2lpha$			
<u>α</u>			
$\bigcirc$ 1 – $\alpha$			
Total		2.00 / 2.00	

Which of the following statements hold? (As usual n and m denote the number of vertices and edges, respectively, of a graph.) [Check all that apply.]

Your Answer		Score	Explanation
Depth-first search can be used to compute a topological ordering of a directed acyclic graph in $O(m+n)$ time.	•	0.50	As covered in lecture.
Breadth-first search can be used to compute the connected components of an undirected graph in $O(m+n)$ time.	<b>~</b>	0.50	As covered in lecture.
Breadth-first search can be used to compute shortest paths in $O(m+n)$ time (when every edge has unit length).	<b>~</b>	0.50	As covered in lecture.
Depth-first search can be used to compute the strongly connected components of a directed graph in $O(m+n)$ time.	<b>~</b>	0.50	As covered in lecture.
Total		2.00 / 2.00	

# **Question 12**

When does a directed graph have a unique topological ordering?

Your Answer	Score	Explanation
Whenever it is a complete directed graph		
Whenever it has a unique cycle		
Whenever it is directed acyclic		
None of the other options	<b>✓</b> 2.00	That's correct!

Total 2.00 / 2.00

#### **Question 13**

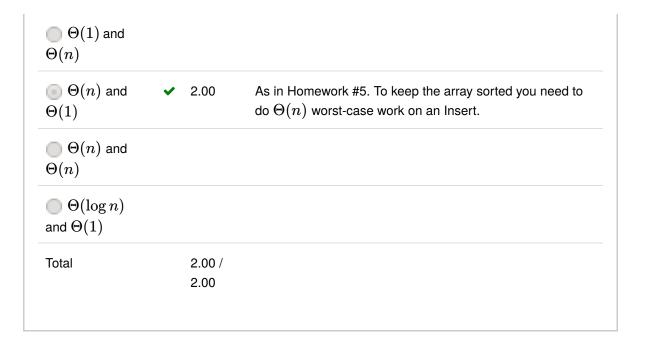
Suppose that a randomized algorithm succeeds (e.g., correctly computes the minimum cut of a graph) with probability p (with  $0 ). Let <math>\epsilon$  be a small positive number (less than 1). How many independent times do you need to run the algorithm to ensure that, with probability at least  $1-\epsilon$ , at least one trial succeeds?

Your Answer		Score	Explanation
$\frac{\log \epsilon}{\log (1-p)}$	<b>~</b>	2.00	The failure probability after $i$ independent trials is $(1-p)^i$ . To get the correct answer, set this equal to the desired failure probability $\epsilon$ , take logarithms (the base doesn't matter) and solve for $i$ .
$\frac{\log(1{-}p)}{\log\epsilon}$			
$\bigcirc \ \frac{\log(p)}{\log \epsilon}$			
$\bigcirc \ \frac{\log \epsilon}{\log(p)}$			
Total		2.00 /	
		2.00	

### **Question 14**

Suppose you implement the operations Insert and Extract-Min using a *sorted* array (from biggest to smallest). What is the worst-case running time of Insert and Extract-Min, respectively? (Assume that you have a large enough array to accommodate the Insertions that you face.)

Your Answer Score Explanation



Which of the following patterns in a computer program suggests that a heap data structure could provide a significant speed-up (check all that apply)?

	Sco	re Explanation
Repeated maximum computations	✔ 0.50	Heaps are just as useful for these as for minimum computations (e.g., just store the negative of each key, so the Extract Min winds up extracting the max).
None of the other options	✔ 0.50	Useful in, e.g., in Dijkstra's shortest-path algorithm or in HeapSort.
Repeated lookups	<b>✓</b> 0.50	Heaps do not generally support fast lookups (unless you happen to be looking for the minimum).
Repeated minimum computations	✔ 0.50	E.g., in Dijkstra's shortest-path algorithm or in HeapSort.
Total	2.00	1
	2.00	

Which of the following patterns in a computer program suggests that a hash table could provide a significant speed-up (check all that apply)?

Your Answer		Score	Explanation
Repeated maximum computations	<b>~</b>	0.50	Hash tables don't support fast queries that reference the ordering of the keys (just lookups).
Repeated minimum computations	<b>~</b>	0.50	Hash tables don't support fast queries that reference the ordering of the keys (just lookups).
None of the other options	<b>~</b>	0.50	Hash tables are super-useful for repeated lookups
Repeated lookups	~	0.50	The raison d'etre of a hash table.
Total		2.00 / 2.00	

## **Question 17**

Which of the following statements about Dijkstra's shortest-path algorithm are true for input graphs that might have some negative edge lengths? [Check all that apply.]

Your Answer		Score	Explanation
It is guaranteed to correctly compute shortest-path distances (from a given source vertex to all other vertices).	<b>~</b>	0.50	We gave a counterexample in lecture.
It may or may not correctly compute shortest-path distances (from a given source vertex to all other vertices), depending on the graph.	<b>~</b>	0.50	
It is guaranteed to terminate.	<b>~</b>	0.50	
It may or may not terminate (depending on	<b>~</b>	0.50	

the graph).		
Total	2.00 /	
	2.00	

Suppose you are given k sorted arrays, each with n elements, and you want to combine them into a single array of kn elements. Consider the following approach. Divide the k arrays into k/2 pairs of arrays, and use the Merge subroutine taught in the MergeSort lectures to combine each pair. Now you are left with k/2 sorted arrays, each with 2n elements. Repeat this approach until you have a single sorted array with kn elements. What is the running time of this procedure, as a function of k and n?

Your Answer	Score	Explanation
$\bigcirc \; \theta(nk^2)$		
$\theta(n\log k)$		
$ heta(nk\log n)$		
$egin{aligned} egin{aligned} & & & & \ & & & \ & & & \ & & & \ & & & \ & & \ & & \ & & \ & & \ & & \ & $	✔ 2.00	There are $\Theta(\log k)$ iterations (you terminate once you've divided $k$ by two enough times to get to 1), and each iteration takes $\Theta(nk)$ time.
Total	2.00 / 2.00	

## **Question 19**

Running time of Strassen's matrix multiplication algorithm: Suppose that the running time of an algorithm is governed by the recurrence  $T(n)=7*T(n/2)+n^2$ . What's the overall

Your Answer		Score	Explanation
$igraphi(n^2)$			
$\theta(n^2 \log n)$			
$ hilde{ hilde{ hilde{ hilde{0}}}}  hilde{ hilde{ hilde{0}}}  hilde{ hilde{0}}  hilde{ hilde{1}}$			
$ hilde{ hilde{$	<b>~</b>	2.00	That's correct!
Total		2.00 / 2.00	

Recall the Master Method and its three parameters $a,b,d$ . Which interpretation of $b^d$ , in the context of divide-and-conquer algorithm	`	g is the best
Your Answer	Score	Explanation
The rate at which the total work is growing (per level of recursion).		
The rate at which the number of subproblems is growing (per level of recursion).		
The rate at which the subproblem size is shrinking (per level of recursion).		
The rate at which the work-per-subproblem is shrinking	<b>v</b> 2.00	That's

2.00 / 2.00

correct!

(per level of recursion).

Total