

# Derivadas PARCIALES

$$\hookrightarrow \underbrace{f_x, f_y \dots}_{\dots}$$

## DERIVADAS ORDEN SUPERIOR

$$\frac{\partial^2}{\partial x^2} f \quad \dots \quad \left. \right\} \text{por qué es interesante?}$$

$$\rightarrow \text{DERIVADAS MIXTAS} \quad \underbrace{\frac{\partial}{\partial y \partial x} f}$$

Quiero comentar cosas sobre este objeto

Audiámos con orden

$$\stackrel{\text{def}}{=} f: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$f \in \mathcal{C} \quad \exists \frac{\partial f}{\partial x_i} \text{ continuas} \Rightarrow f \in C^1$$

$$\quad \quad \quad \frac{\partial^2}{\partial} \quad \quad \quad \Rightarrow f \in C^2$$

y así seguimos hasta  $C^\infty$

$$\hookrightarrow \frac{\partial^2}{\partial x^2} f = \frac{\partial}{\partial x} \left( \frac{\partial}{\partial x} f \right), \quad \underbrace{\frac{\partial}{\partial_{xy}} f = \frac{\partial}{\partial x} \frac{\partial}{\partial y} f}_{\text{Derivada mixta}}$$

$$\underline{E_1} \quad f(x,y) = xy + (x+2y)^2$$

$$\frac{\partial}{\partial x} f(x,y) = y + 2(x+2y)$$

$$\frac{\partial}{\partial y} f(x,y) = x + 4(x+2y)$$

Vamos a calcular la derivada MIXTA

$$\begin{aligned}\frac{\partial^2}{\partial x \partial y} f(x,y) &= \frac{\partial}{\partial x} \left( \frac{\partial}{\partial y} f \right) \\ &= \frac{\partial}{\partial x} (x + 4(x+2y)) \\ &= 1 + 4 = 5\end{aligned}$$

¿Qué pasa con la otra?

→ MISMO RESULTADO?    ¿QUÉ OS ESPERABIS?

$$\begin{aligned}\frac{\partial}{\partial y} f(x,y) &= \frac{\partial}{\partial y} \left( \frac{\partial}{\partial x} f \right) \\ &= \frac{\partial}{\partial y} (y + 2(x+2y)) \\ &= 1 + 4 = 5\end{aligned}$$

LA MISMA!

LA PREGUNTA QUE NOS HACENOS ES --

¿ BAJO QUÉ CONDICIÓN ESTO OCURRE ?

Teorema  $f : \mathbb{R}^n \rightarrow \mathbb{R}$

$f \in C^2$   $\Rightarrow \frac{\partial f}{\partial x_j} = \frac{\partial f}{\partial y^x}$

↳ ESTA ES LA CONDICIÓN

---

Ej)  $f(x, y) = x e^y + y x^2$  ) combinación de funciones  
siempre continuas

$$\frac{\partial f}{\partial x} = e^y + 2xy$$

$$\frac{\partial f}{\partial y} = xe^y + x^2$$

$$\frac{\partial f}{\partial y^x} = e^y + 2x$$

$$\frac{\partial f}{\partial x_j} = e^y + 2x$$

Son iguales

# CAMPOS VECTORIALES

def CAMPO VECTORIAL en  $\mathbb{R}^n$

$$F: A \subset \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$\bar{x} \mapsto F(\bar{x})$$

EJ  $\nabla f$  es un CAMPO VECTORIAL

def  $F = \nabla \varphi$  ( CAMPO EXPRESADO como GRADIENTE FUNCIÓN ESCALAR )

→  $F$  CAMPO CONSERVATIVO

$$\text{Ej } V(x, y) = -y\hat{i} + x\hat{j}$$

Vectoras  
Base  
Canónica

$$\left\{ \begin{array}{l} \text{con } \hat{i} = (1, 0) \\ \hat{j} = (0, 1) \end{array} \right\} \text{CAMPO VECTORIAL } \mathbb{R}^2$$

→ MOVIMIENTO ROTACIONAL

(Figura 5.2 en las notas)

→ COORDENADAS POLARES

$$V(x, y) = r \cos \theta \hat{j} - r \sin \theta \hat{i}$$

Introducimos un operador en el CAMPO VECTORIAL

def  $\mathbb{F}: A \subset \mathbb{R}^n \rightarrow \mathbb{R}^n$  (CAMPO VECTORIAL  $\mathbb{R}^n$ )

$$\operatorname{div} \mathbb{F} = \sum_{i=1}^n \frac{\partial F_i}{\partial x_i} = \frac{\partial F_1}{\partial x_1} + \dots + \frac{\partial F_n}{\partial x_n}$$

deriva la componente  $i$ -esima con respecto a la variable  $i$ -esima

→ Lo hago con respecto a TODAS LAS VARIABLES

→ Y sumo

Ej  $\mathbb{F} = x^2 y \hat{i} + z \hat{j} + x y z \hat{k}$

$$\begin{aligned}\operatorname{div} \mathbb{F} &= \frac{\partial}{\partial x} (x^2 y) + \frac{\partial}{\partial y} (z) + \frac{\partial}{\partial z} (xyz) \\ &= 2xy + 0 + xyz \\ &= 3xy\end{aligned}$$

OBSERVACIÓN : Se puede indicar TB

$$\operatorname{div} \mathbb{F} = \underbrace{\nabla \cdot \mathbb{F}}$$

Producto escalar entre  $\nabla$  y  $\mathbb{F}$

## DIVERGENCIA

→ SIGNIFICADO FÍSICO

$\vec{F} \rightarrow$  velocidad fluido



A CADA Punto espacio ( $x, y, z$ )  
ASOCIA vector velocidad

→ ¿Qué me dice la divergencia?

div  $\vec{F}$  → TASA EXPANSIÓN FLUIDO



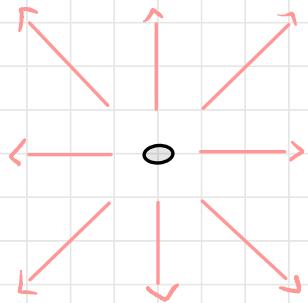
div  $\vec{F} < 0 \rightarrow$  FLUIDO se comprime

div  $\vec{F} > 0 \rightarrow$  FLUIDO se EXPANDE

div  $\vec{F} = 0 \rightarrow$  ni se comprime,  
ni se expande

$$\underline{E_1} \quad F = x\hat{i} + y\hat{j}$$

→ Líneas rectas que se alejan el uno del otro



$$\text{div } F = ?$$

¿Qué os esperáis?

POSITIVA? NEGATIVA?

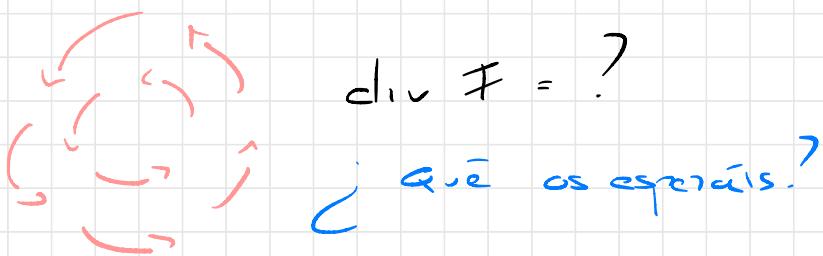
¿Por qué?

$$\begin{aligned}\text{div } F &= \frac{\partial}{\partial x} x + \frac{\partial}{\partial y} y \\ &= 1 + 1 = 2 > 0\end{aligned}$$

→ EL FLUIDO SALE

$$\underline{Ej} \quad \mathbf{F} = -y\hat{i} + x\hat{j}$$

→ MOVIMIENTO ROTACIONAL



$$\begin{aligned} \text{div } \mathbf{F} &= + \frac{\partial}{\partial x} (-y) + \frac{\partial}{\partial y} (x) \\ &= 0 - 0 = 0 \end{aligned}$$

EL FLUIDO da VUELTAS, NO SALE

Vamos a ver otra operación

def  $\mathcal{F} = F_1 \hat{i} + F_2 \hat{j} + F_3 \hat{k}$  CAMPO VECTORIAL  $\mathbb{R}^3$

Rotor / Rotacional  $\mathcal{F}$  (curl, inglés)

$$\nabla \times \mathcal{F} = \nabla \wedge \mathcal{F} = \det \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix}$$

$$= \left( \frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \hat{i} + \left( \frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) \hat{j} + \left( \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \hat{k}$$

$\rightarrow \mathcal{F}(x, y, z) = x \hat{i} + xy \hat{j} + \hat{k}$

$$\nabla \wedge \mathcal{F} = \det \begin{pmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & xy & 1 \end{pmatrix}$$

$$= \left( \frac{\partial}{\partial y} 1 - \frac{\partial}{\partial z} xy \right) \hat{i} + \left( \frac{\partial}{\partial x} 1 - \frac{\partial}{\partial z} x \right) \hat{j}$$

$$+ \left( \frac{\partial}{\partial x} xy - \frac{\partial}{\partial y} x \right) \hat{k} = 0 \hat{i} + 0 \hat{j} + \hat{k}$$

## SIGNIFICADO FÍSICO

→ CAPACIDAD DESARROLLAR ROTACIÓN  
alrededor de un punto

→ Será más clara cuando se establece el teorema de STOKES

Teorema  $\nabla f \in C^1(\mathbb{R}^3)$

$$\nabla \times \nabla f = 0$$

dim  $\nabla f = \left( \frac{\partial}{\partial x} f, \frac{\partial}{\partial y} f, \frac{\partial}{\partial z} f \right)$

$$\nabla \times \nabla f = \det \begin{pmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} & \frac{\partial f}{\partial z} \end{pmatrix}$$

$$= i \left( \frac{\partial^2 f}{\partial y \partial z} - \frac{\partial^2 f}{\partial z \partial y} \right) + j \left( \frac{\partial^2 f}{\partial x \partial z} - \frac{\partial^2 f}{\partial z \partial x} \right)$$

$$+ k \left( \frac{\partial^2 f}{\partial x \partial y} - \frac{\partial^2 f}{\partial y \partial x} \right) = 0$$

$$\Rightarrow C^1$$

COR  $\nabla \times \mathbf{F}$  CAMPO CONSERVATIVO

$$\Rightarrow \nabla \times \mathbf{F} = \mathbf{0}$$

$\rightarrow V(x, y, z) = y\hat{i} - x\hat{j}$   
CONSERVATIVO?

$$\rightarrow \nabla \times \mathbf{F} = \operatorname{det} \begin{pmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y & -x & 0 \end{pmatrix} = -2\hat{k} \neq \mathbf{0}$$

$\rightarrow$  NO ES CONSERVATIVO

---

Teorema  $\nabla \cdot (\nabla \times \mathbf{F}) = 0 \quad (\mathbf{F} \in C^2(\mathbb{R}^3))$

dem CALCULAR EXPLÍCITAMENTE Y USAR HECHOS  
de que las derivadas mixtas son iguales

$\rightarrow V(x, y, z) = x\hat{i} + y\hat{j} + z\hat{k}$

$\exists \tilde{V} : V = \nabla \times \tilde{V} ?$

$$\operatorname{div} V = \frac{\partial}{\partial x} x + \frac{\partial}{\partial y} y + \frac{\partial}{\partial z} z = 3 \neq 0$$

NO, o si NO  $\operatorname{div} V = 0$

## ULTIMO OPERADOR

LAPLACIANO

$$f : \mathbb{R}^n \rightarrow \mathbb{R}$$

$$\Delta f = \nabla^2 f = \nabla \cdot \nabla f$$

SABRÍAS decirme la  
fórmula sabiendo que se  
puede escribir así?

$$\Delta f = \sum_{i=1}^n \frac{\partial^2 f}{\partial x_i^2}$$

## COORDENADAS POLARES

$$f : A \subset \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$x = r \cos \theta, \quad y = r \sin \theta$$

$$r = \sqrt{x^2 + y^2}, \quad \theta = \arctan \left( \frac{y}{x} \right)$$

def LAPLACIANO  $\Delta f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2}$

Transforma la derivada en coordenadas polares

$$\frac{\partial}{\partial x} f = \frac{\partial r}{\partial x} \frac{\partial f}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial f}{\partial \theta}$$

$$\frac{\partial}{\partial y} f = \frac{\partial r}{\partial y} \frac{\partial f}{\partial r} + \frac{\partial \theta}{\partial y} \frac{\partial f}{\partial \theta}$$

$$\left( \frac{\partial r}{\partial x} \right) = \frac{2x}{2\sqrt{x^2+y^2}} = \frac{r \cos \theta}{r} = \cos \theta$$

$$\left( \frac{\partial r}{\partial y} \right) = \frac{2y}{2\sqrt{x^2+y^2}} = \frac{r \sin \theta}{r} = \sin \theta$$

$$\left( \frac{\partial \theta}{\partial x} \right) = -\frac{x^2}{x^2+y^2} \frac{y}{x^2} = -\frac{\sin \theta}{r}$$

$$\left( \frac{\partial \theta}{\partial y} \right) = +\frac{x}{x^2+y^2} = \frac{\cos \theta}{r}$$

Se obtiene

$$\frac{\partial F}{\partial x} = \cos \theta \frac{\partial f}{\partial r} - \frac{\sin \theta}{r} \frac{\partial f}{\partial \theta}$$

$$\frac{\partial F}{\partial y} = \sin \theta \frac{\partial f}{\partial r} + \frac{\cos \theta}{r} \frac{\partial f}{\partial \theta}$$

Ahora tenemos que calcular las derivadas segundas

$$\frac{\partial^2 F}{\partial x^2} = \frac{\partial}{\partial x} \frac{\partial f}{\partial x} = \cos \theta \frac{\partial}{\partial x} \frac{\partial f}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial x} \frac{\partial f}{\partial \theta}$$

$$\frac{\partial}{\partial x} \frac{\partial f}{\partial r} = \frac{\partial r}{\partial x} \frac{\partial^2 f}{\partial r^2} + \frac{\partial \theta}{\partial x} \frac{\partial^2 f}{\partial \theta \partial r}$$

$$= \cos \theta \frac{\partial^2 f}{\partial r^2} - \frac{\sin \theta}{r} \frac{\partial^2 f}{\partial \theta \partial r}$$

$$\frac{\partial}{\partial x} \frac{\partial f}{\partial \theta} = \frac{\partial r}{\partial x} \frac{\partial^2 f}{\partial \theta \partial r} + \frac{\partial \theta}{\partial x} \frac{\partial^2 f}{\partial \theta^2}$$
$$= \cos \theta \frac{\partial^2 f}{\partial \theta \partial r} - \frac{\sin \theta}{r} \frac{\partial^2 f}{\partial \theta^2}$$

$$\frac{\partial^2 F}{\partial x^2} = \cos^2 \theta \frac{\partial^2 f}{\partial r^2} - \frac{\sin 2\theta}{r} \frac{\partial^2 f}{\partial \theta \partial r}$$
$$- \frac{\sin 2\theta}{2r} \frac{\partial^2 f}{\partial \theta \partial r} + \left( \frac{\sin \theta}{r} \right)^2 \frac{\partial^2 f}{\partial \theta^2}$$

(incompl.)