

Import Required Libraries

```
In [1]: import numpy as np
import matplotlib.pyplot as plt
```

1. (Perceptron) Using the make blobs function in sklearn generate a dataset of 100 points with two classes. Write the perceptron algorithm by scratch and show the intermediate hyperplanes generated.

```
In [2]: from sklearn.datasets import make_blobs
```

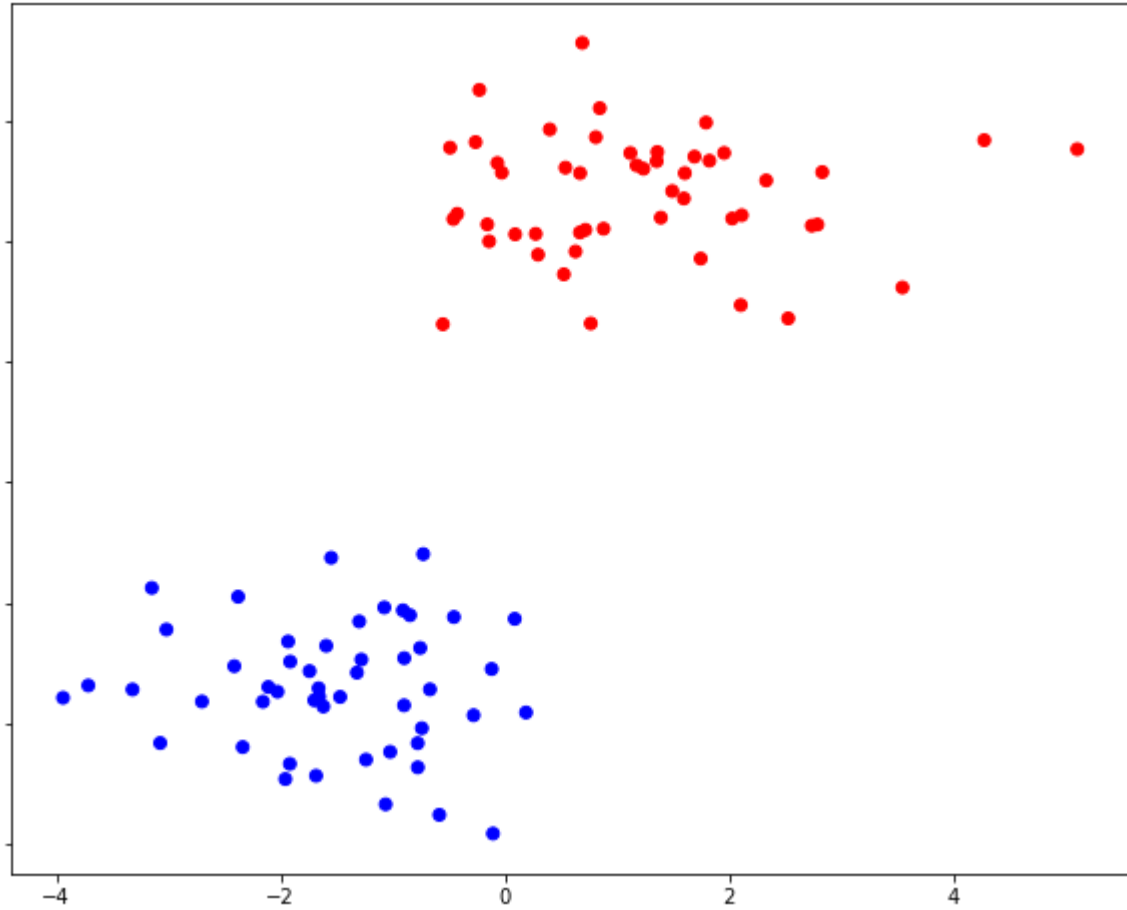
```
In [3]: #generating dataset with 100 points with two different classes.
```

```
X, y = make_blobs(n_samples = 100, centers = 2, n_features = 2, random_state = 2)
```

```
In [4]: #initial plot for two classes
```

```
plt.figure(figsize = (10,8))
c = ['r' if i == 1 else 'b' for i in y]
plt.scatter(X[:,0], X[:,1], color = c)
```

```
Out[4]: <matplotlib.collections.PathCollection at 0x25eed789cc8>
```



```
In [5]: X_aug = np.ones((100,3))
X_aug[:, 1:] = X #augmented matrix with bias
```

```
In [6]: W = np.random.normal(0,1,3) #initial weights (random)
xmin = min(X_aug[:, 1])
xmax = max(X_aug[:, 1])
```

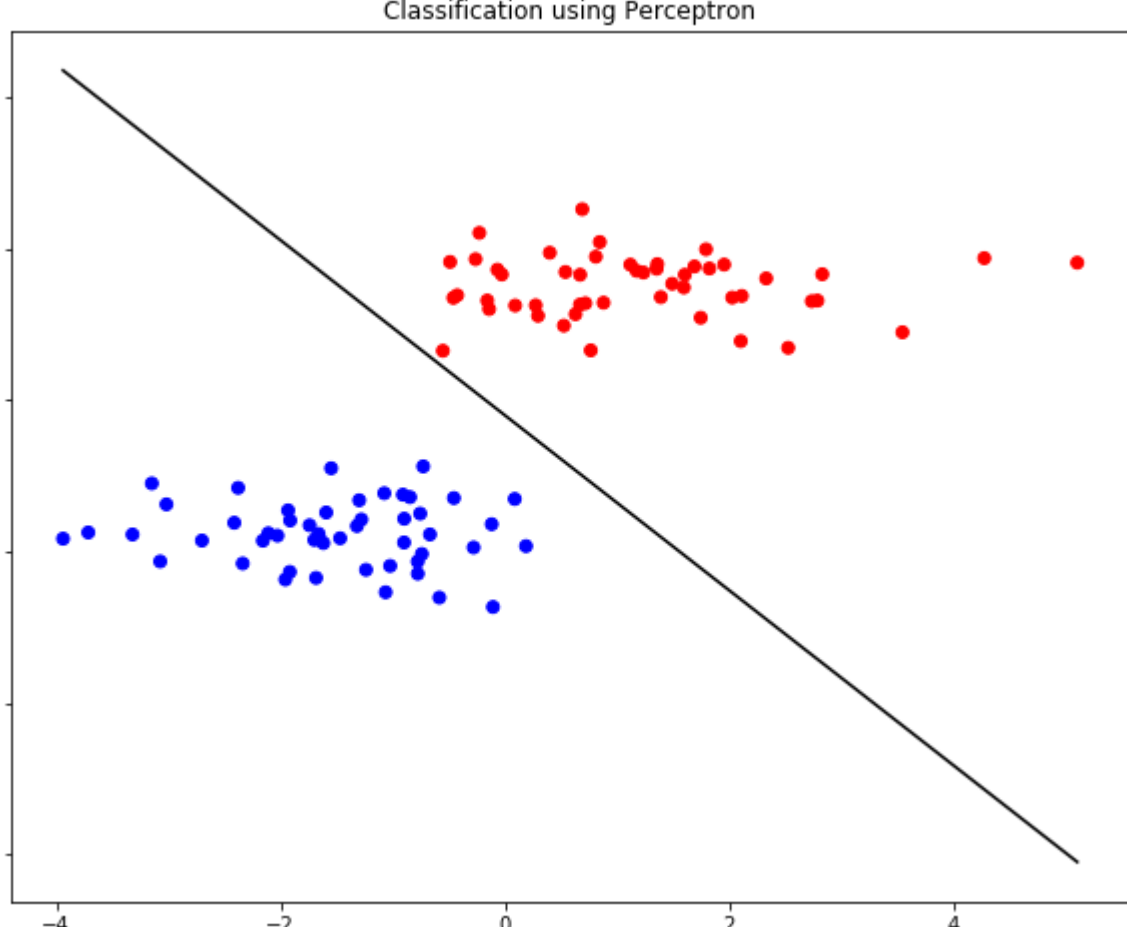
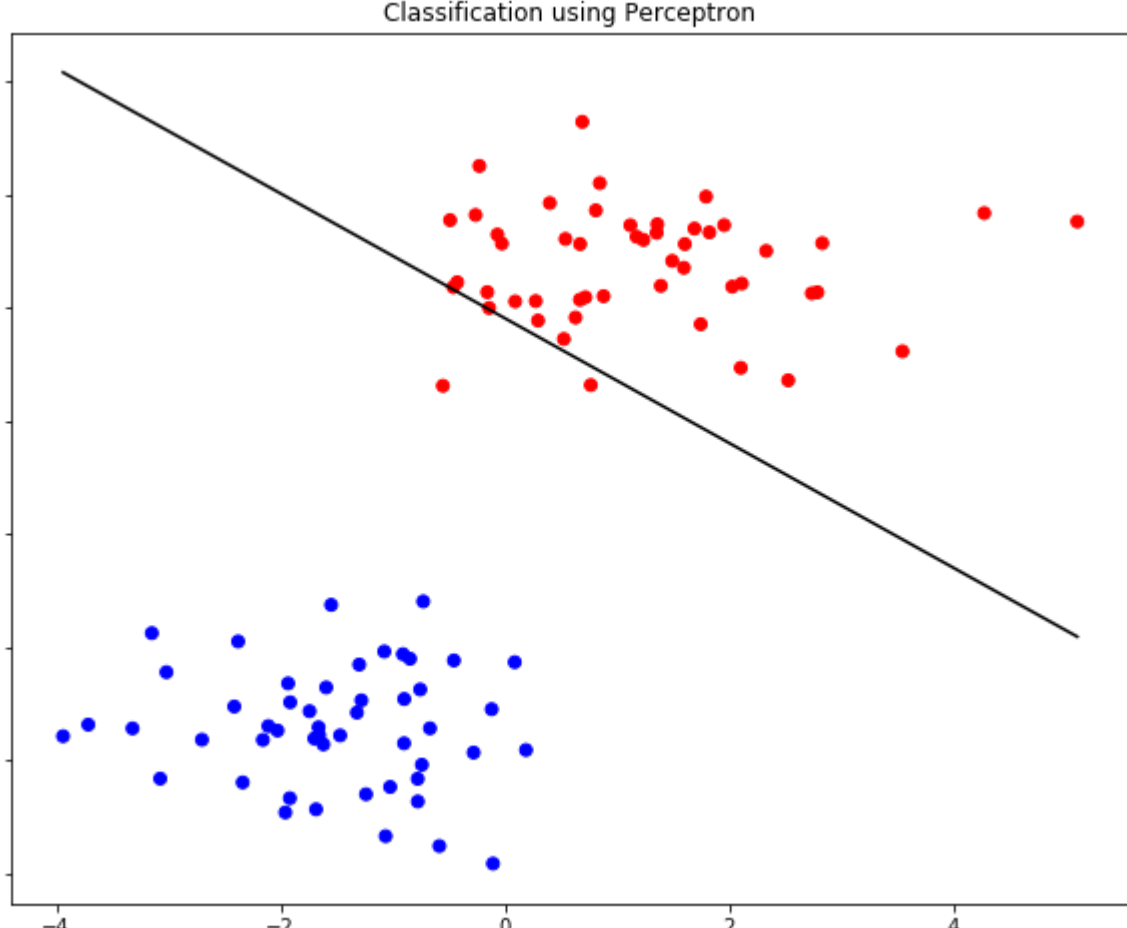
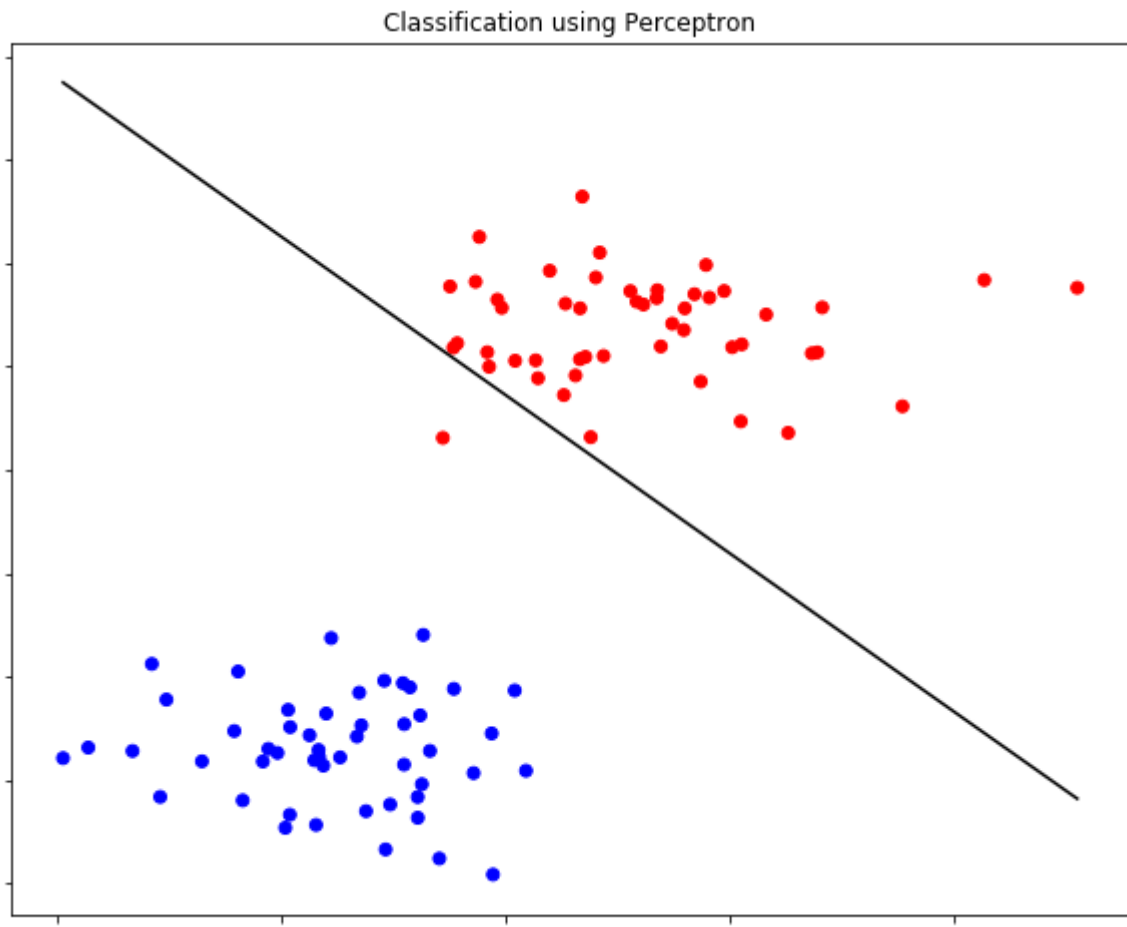
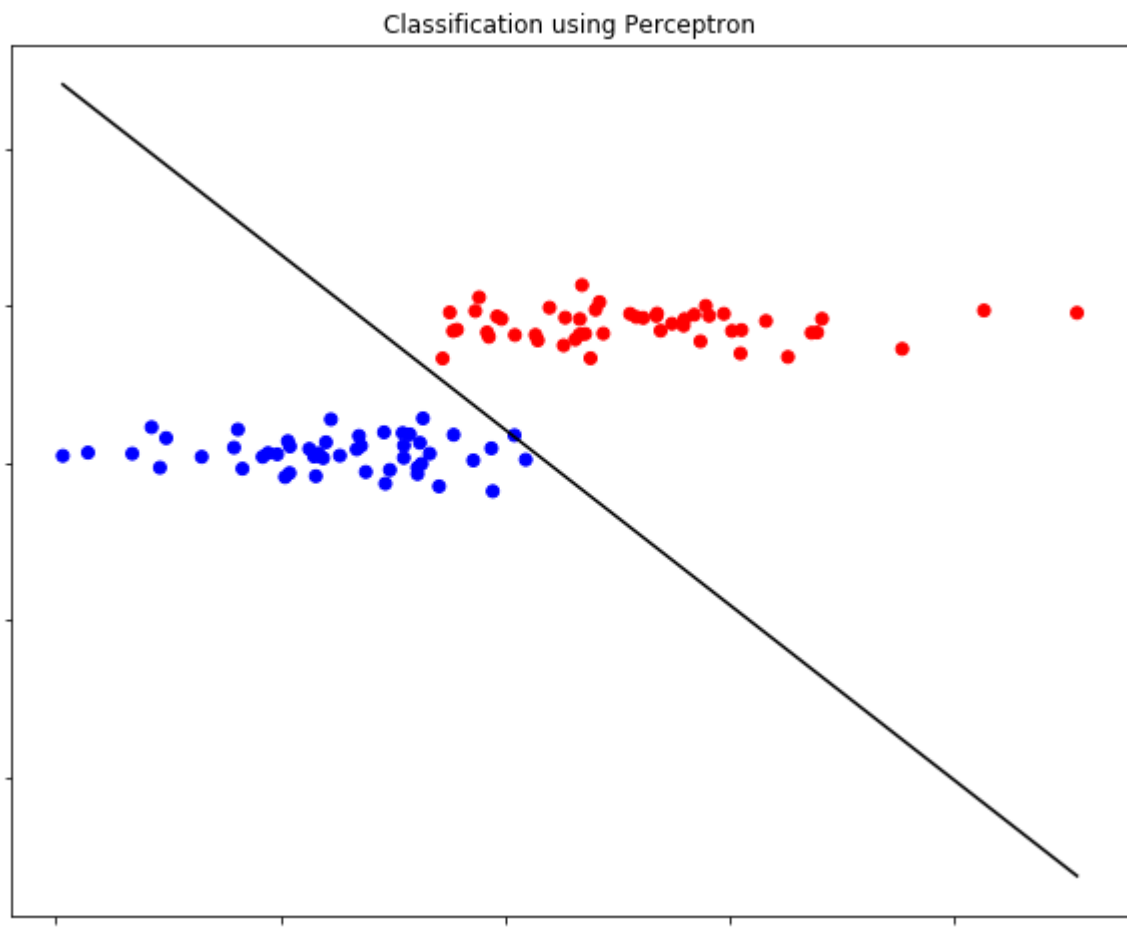
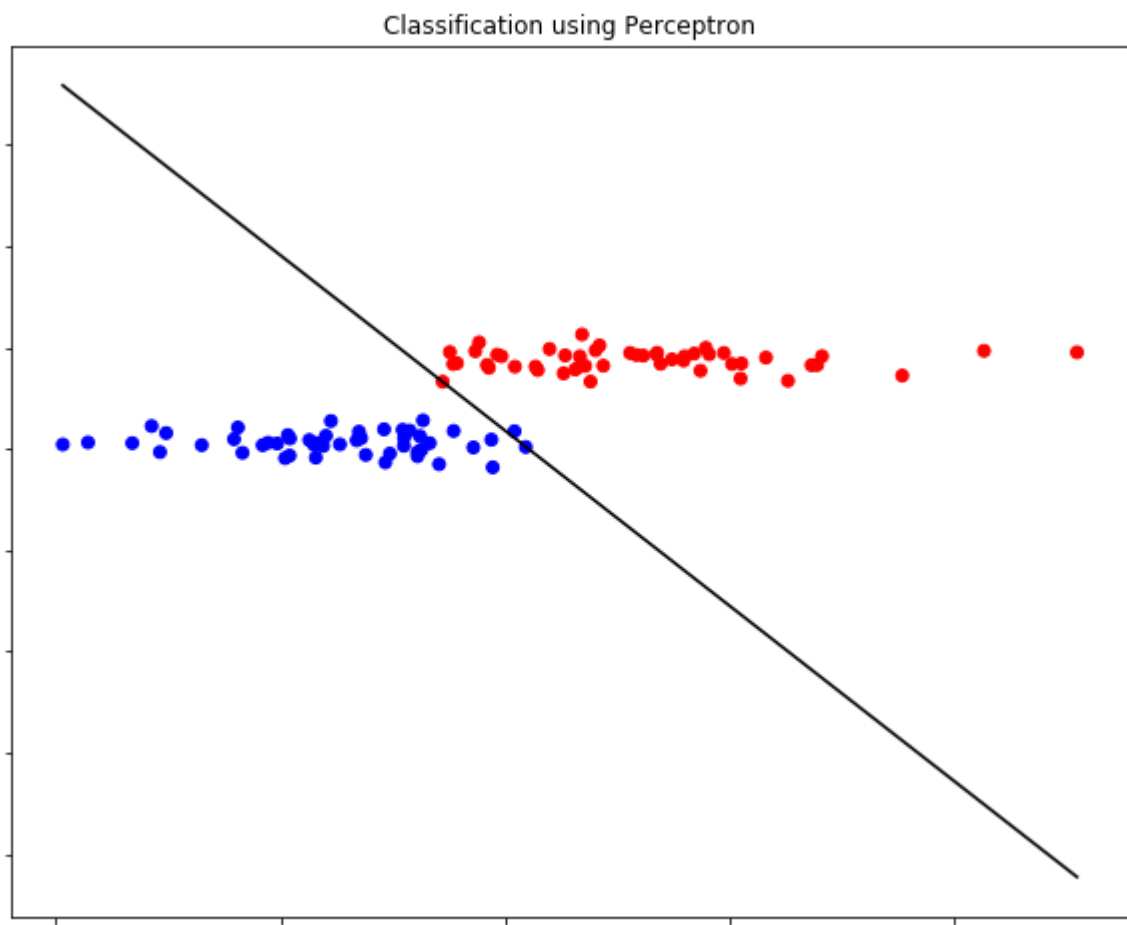
```
In [7]: #perceptron algorithm:
```

```
while(True):
    for j in range(len(y)):
        temp = 0.0
        temp = np.dot(X_aug[j], W)
        if(y[j] == 1 and temp < 0):
            W = W + X_aug[j]
        elif(y[j] == 0 and temp >= 0):
            W = W - X_aug[j]

    #condition to stop while-loop:
    flag = 0
    for j in range(len(y)):
        temp = 0.0
        temp = np.dot(X_aug[j], W)
        if(y[j] == 1 and temp < 0):
            flag = 1
        elif(y[j] == 0 and temp >= 0):
            flag = 1

    xx = np.linspace(xmin,xmax)
    yy = (-W[0] - W[1]*xx) / W[2]

    plt.figure(figsize = (10,8))
    c = ['r' if i == 1 else 'b' for i in y]
    plt.scatter(X[:,0], X[:,1], color = c)
    plt.plot(xx, yy, color = 'black')
    plt.title('Classification using Perceptron')
    if(flag == 0):
        break
```



2. (Perceptron) Repeat the above exercise with batch gradients instead. Step size might need to be adjusted for convergence.

```
In [20]: W_batch_gradient = np.random.normal(0,1,3)
epsilon = 10**(-2)
```

```
Out[20]: array([ 0.0971456 ,  0.86656983, -0.48994649])
```

```
In [21]: # Perceptron using Batch gradient:
error = 3
while(error >= epsilon):
    eta = 0.03 #step_size
    for j in range(len(y)):
        temp = 0.0
        temp = np.dot(X_aug[j], W_batch_gradient)
        if(y[j] == 1 and temp < 0):
            W_batch_gradient = W_batch_gradient + eta*X_aug[j]
        elif(y[j] == 0 and temp >= 0):
            W_batch_gradient = W_batch_gradient - eta*X_aug[j]

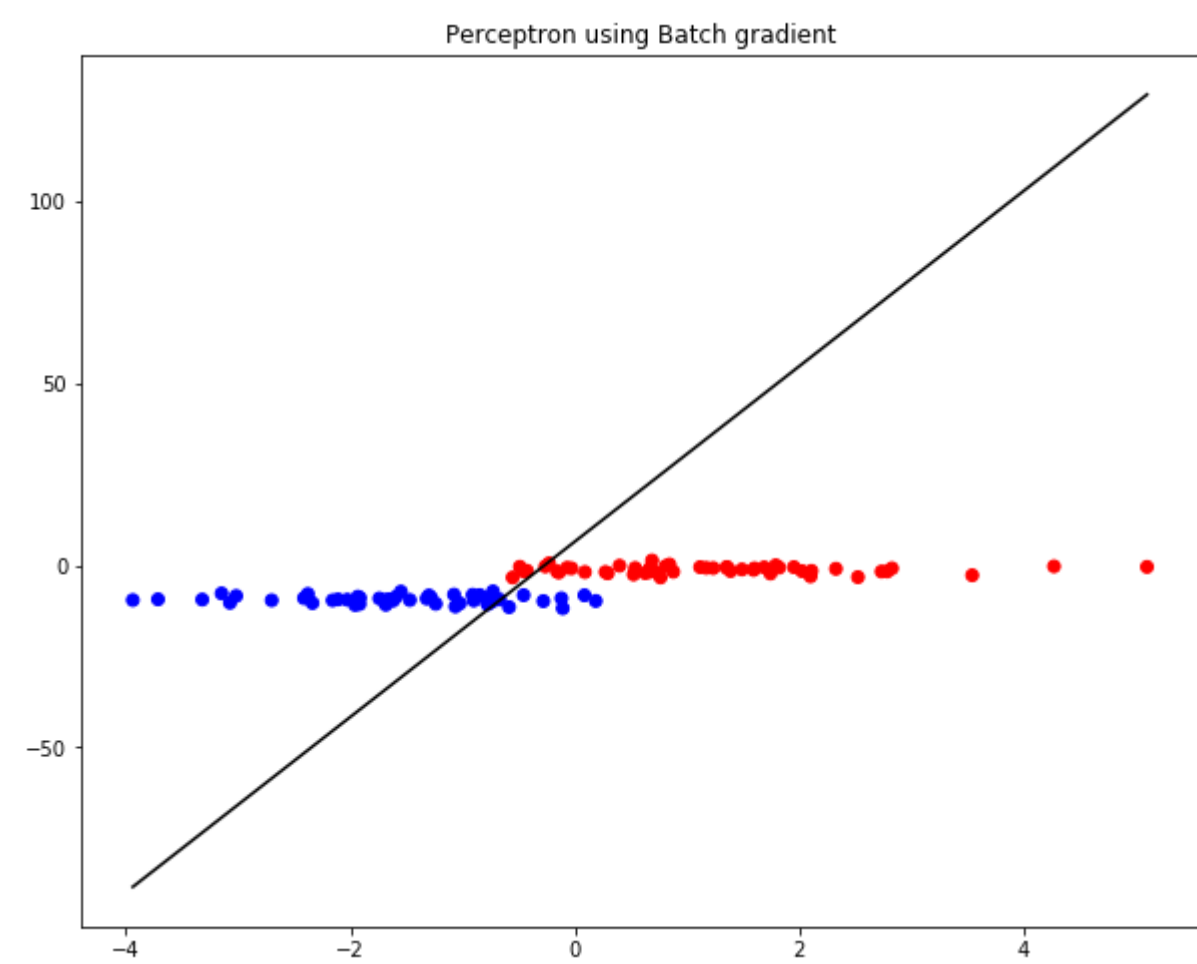
    error = 0
    for j in range(len(y)):
        temp = 0.0
        temp = np.dot(X_aug[j], W_batch_gradient)
        if(y[j] == 1 and temp < 0):
            error = error - (temp)
        elif(y[j] == 0 and temp >= 0):
            error = error + (temp)

#condition to stop while-Loop:
flag = 0
for j in range(len(y)):
    temp = 0.0
    temp = np.dot(X_aug[j], W_batch_gradient)
    if(y[j] == 1 and temp < 0):
        flag = 1
    elif(y[j] == 0 and temp >= 0):
        flag = 1

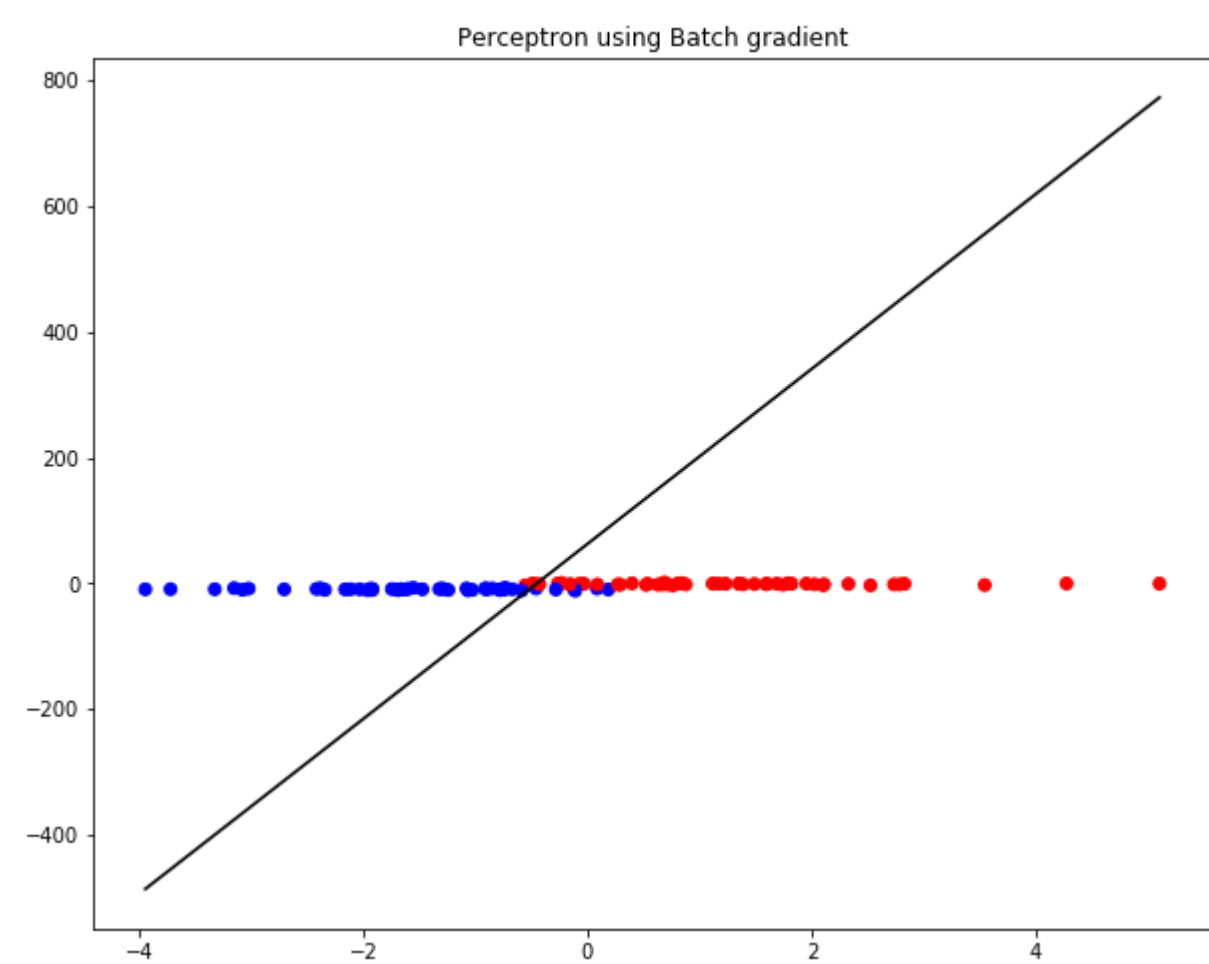
print(error)
print(W_batch_gradient)
xx_batch_gradient = np.linspace(xmin,xmax)
yy_batch_gradient = (-W_batch_gradient[0] - W_batch_gradient[1]*xx_batch_gradient) / W_batch_gradient[2]

plt.figure(figsize = (10,8))
c = ['r' if i == 1 else 'b' for i in y]
plt.scatter(X[:,0], X[:,1], color = c)
plt.plot(xx_batch_gradient, yy_batch_gradient, color = 'black')
plt.title('Perceptron using Batch gradient')
plt.show()
if(flag == 0):
    break
```

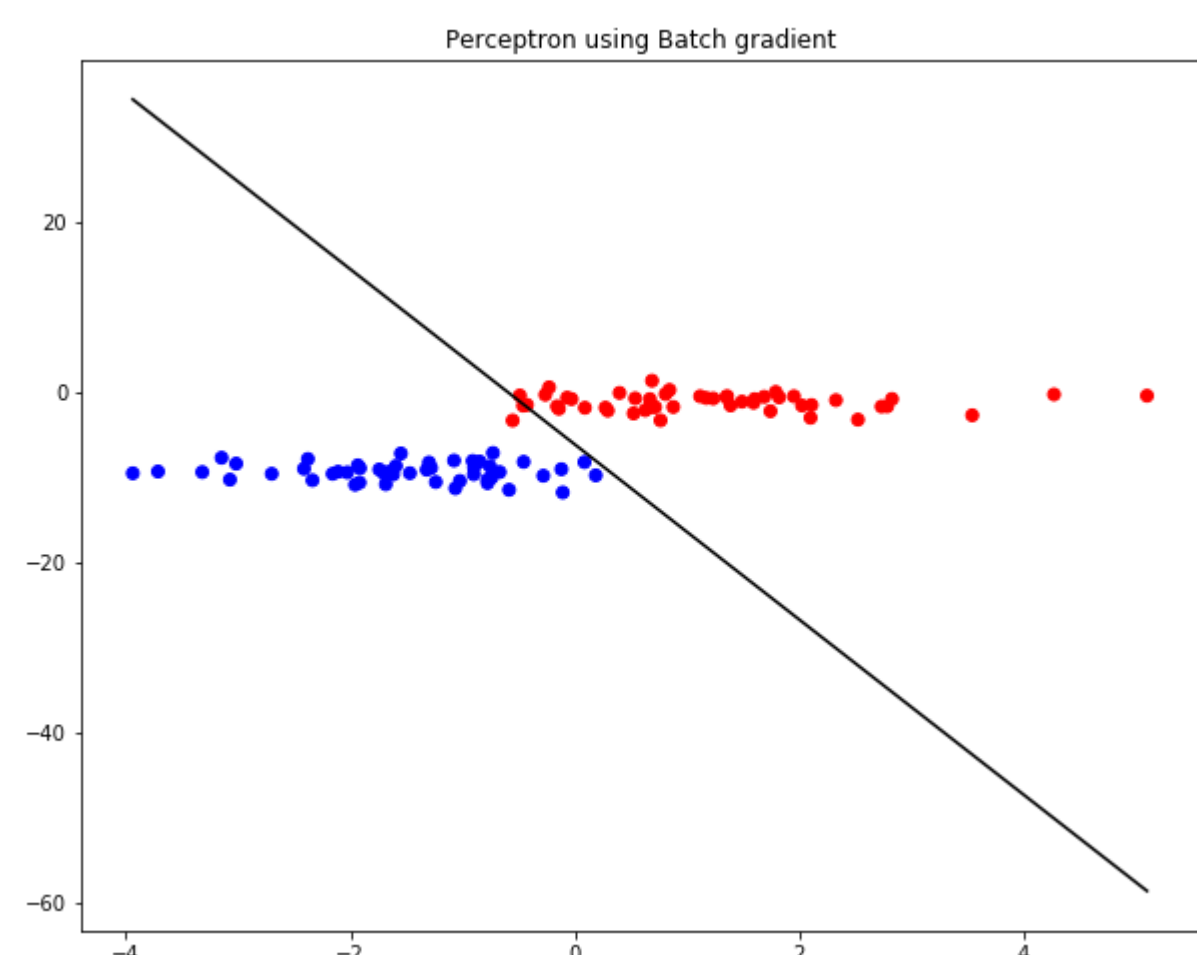
3.2534336403613477
[0.2171456 0.8082146 -0.03360383]



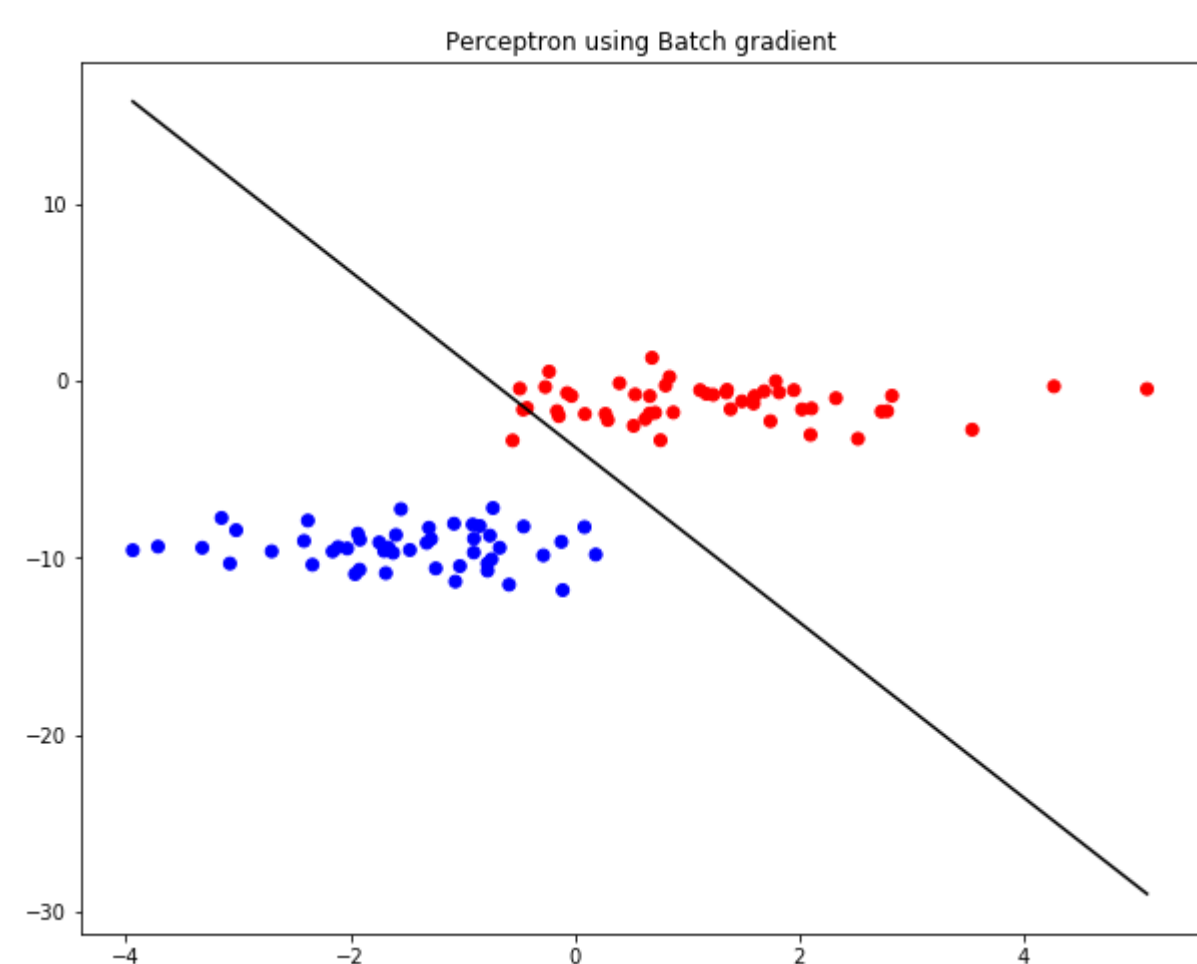
1.9868423636728192
[0.3371456 0.75295768 -0.00540846]



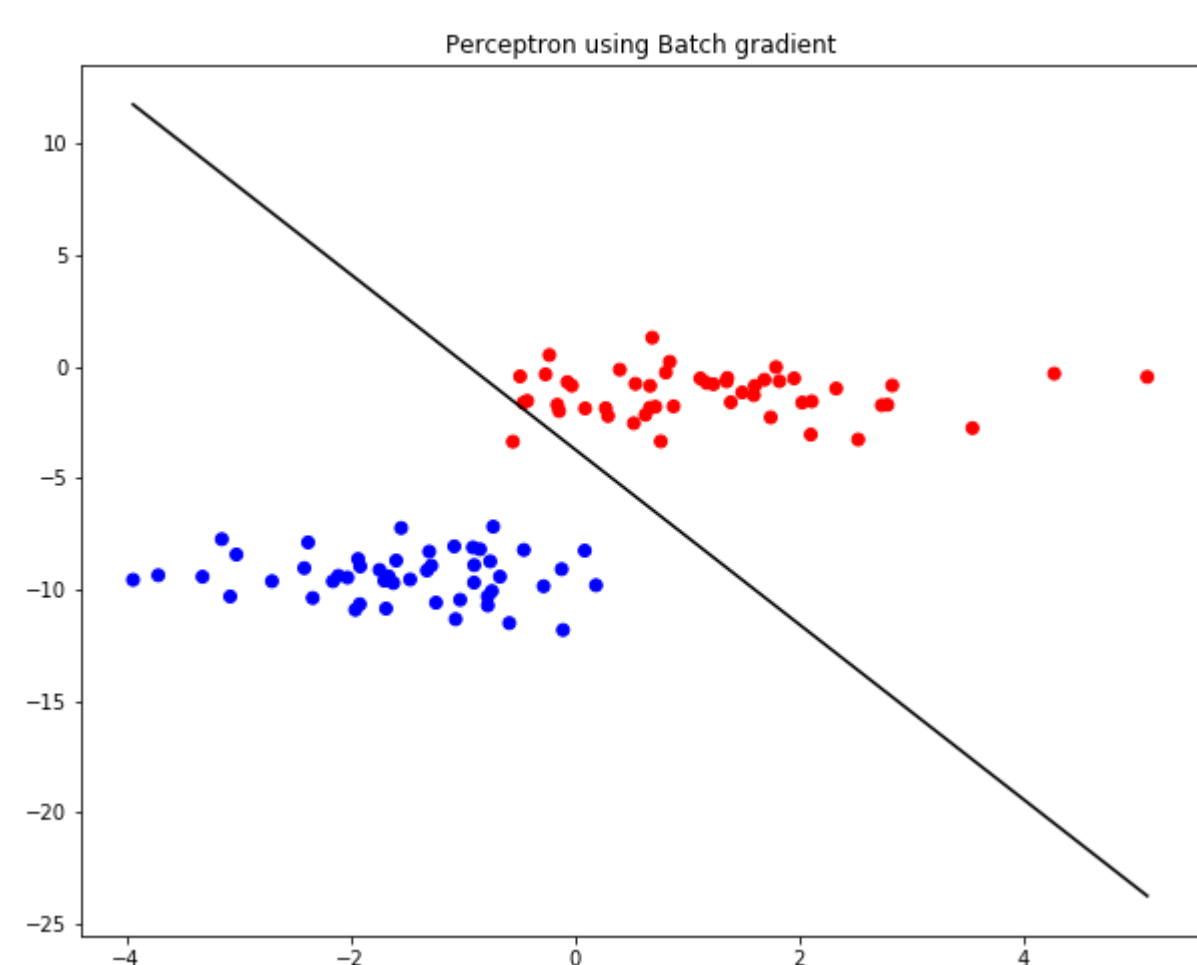
0.21206699601516277
[0.4271456 0.7104676 0.06914669]



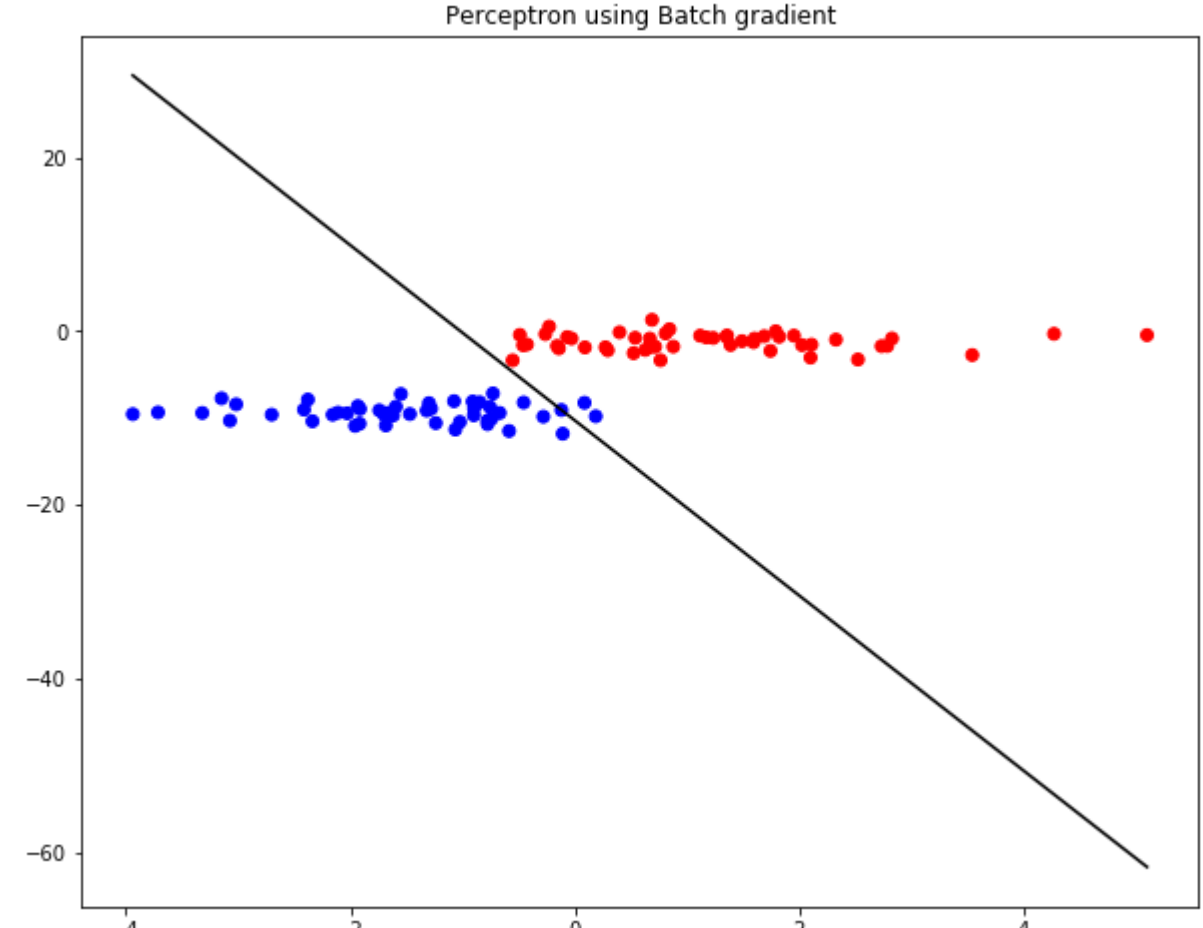
0.3543378967696936
[0.5171456 0.6845225 0.13856375]



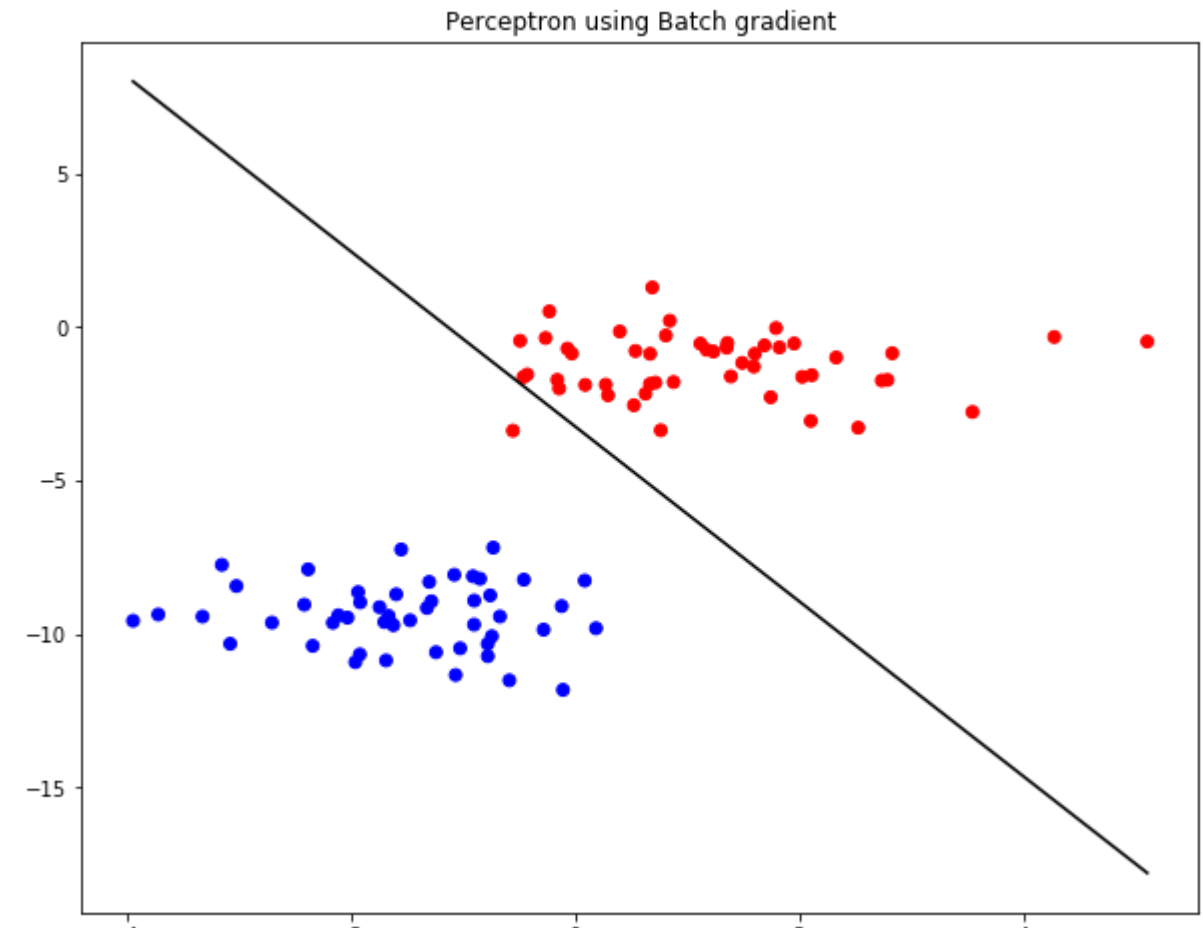
0.2987566460987987
[0.6071456 0.64110403 0.16323042]



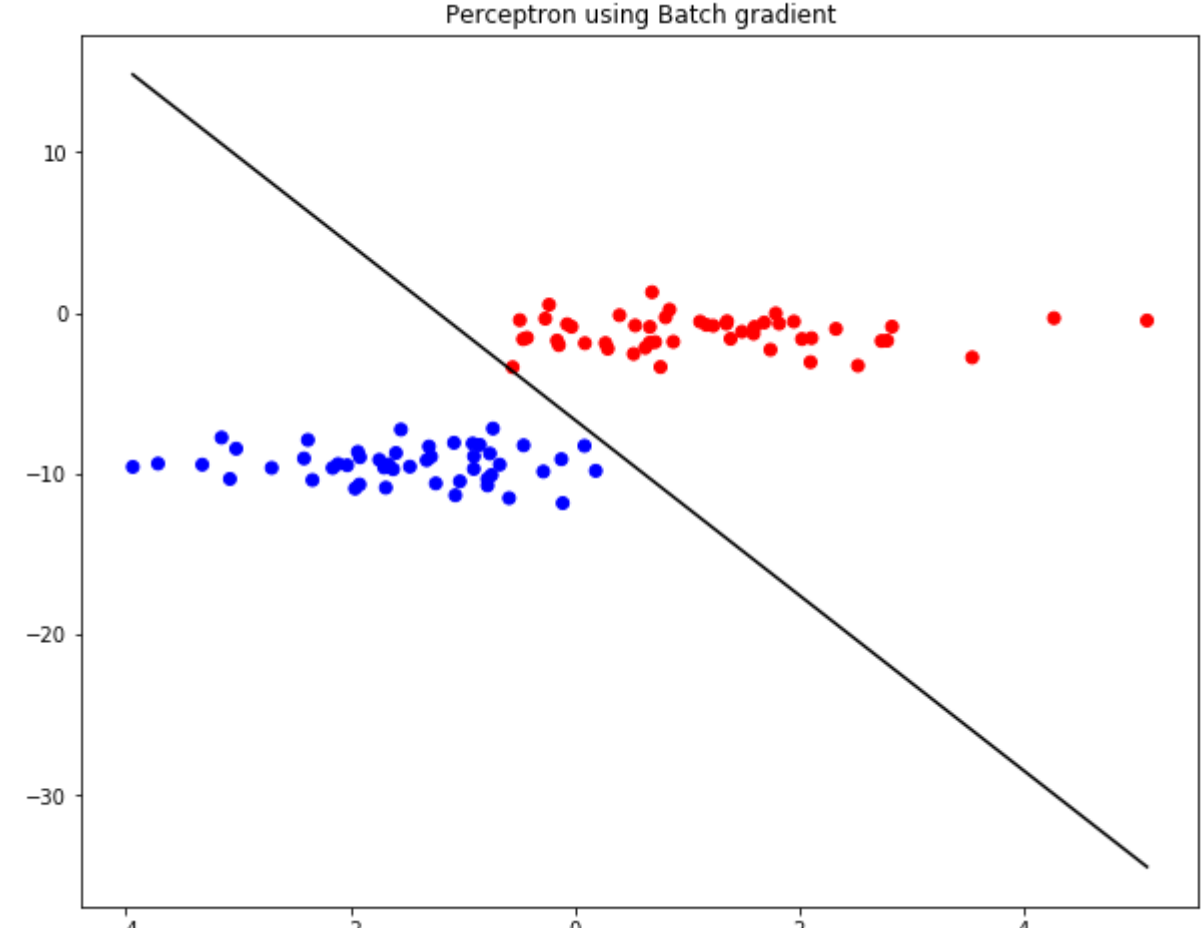
0.32584873160294925
[0.6371456 0.62450128 0.0619443]



0.35478713810363605
[0.6671456 0.5884678 0.20622566]



0
[0.6971456 0.57186595 0.10493954]



3. (Perceptron) Using the make_circles function in sklearn generate two classes so that they form different concentric circles. Generate 100 points. Create second order features and train the perceptron. Using the contour function show the final decision boundary in the original two dimensional space.

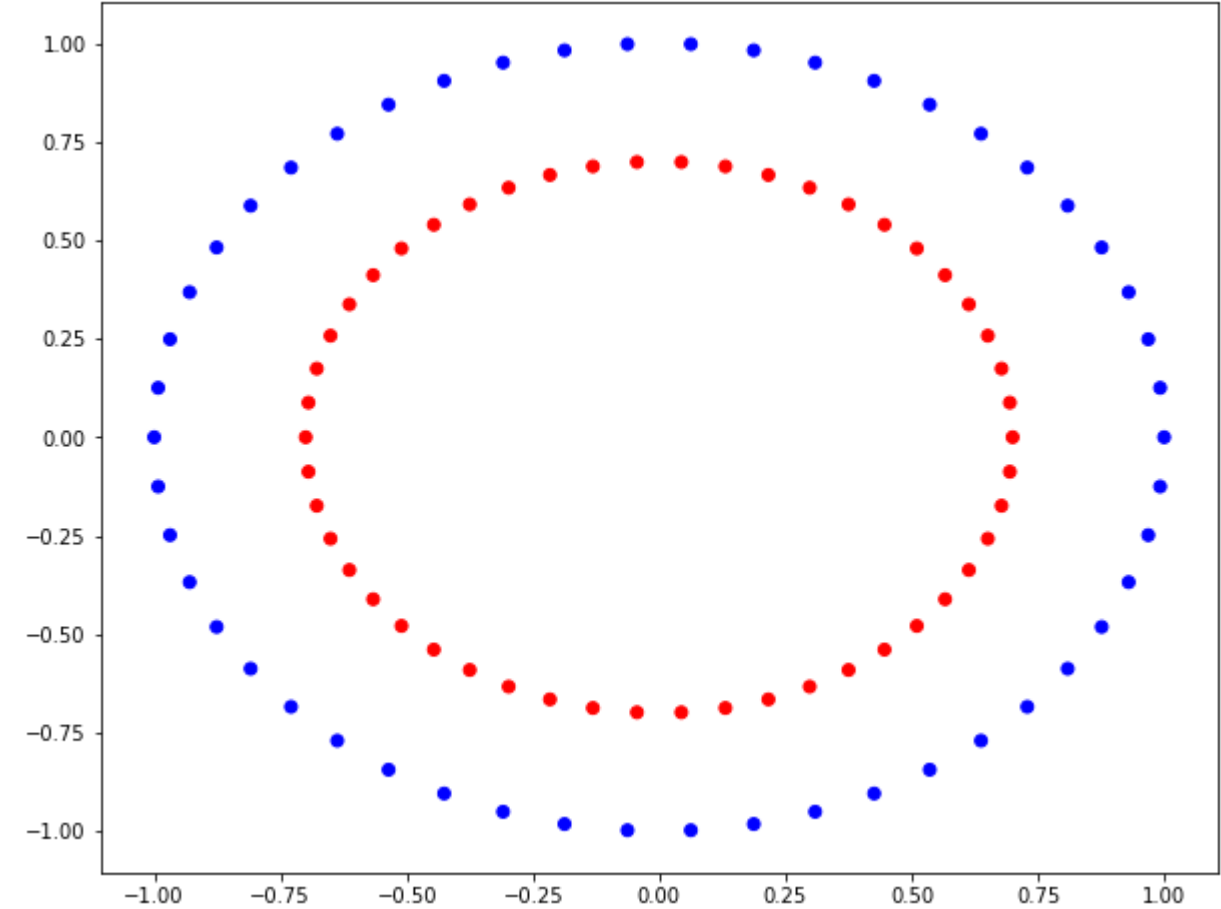
```
In [79]: from sklearn.datasets import make_circles
```

```
In [80]: X_circle, y_circle = make_circles(n_samples = 100, random_state = 2, factor = 0.7)
```

```
In [81]: #initial plot for two classes
```

```
plt.figure(figsize = (10,8))  
c = ['r' if i == 1 else 'b' for i in y_circle]  
plt.scatter(X_circle[:,0], X_circle[:,1], color = c)
```

```
Out[81]: <matplotlib.collections.PathCollection at 0x25eee4bec8>
```



```
In [106]: # Creating second order features:  
data = np.ones((len(y_circle), 6))
```

```
In [107]: data[:, 1:3] = X_circle
```

```
In [108]: data[:,3] = X_circle[:,0]**2  
data[:,4] = X_circle[:,1]**2  
data[:,5] = X_circle[:,0]*X_circle[:,1]
```

```
In [109]: W_nisp = np.random.normal(0,1,6) #initial weights (random)  
error_nisp = 1  
eps = 10**(-2)
```

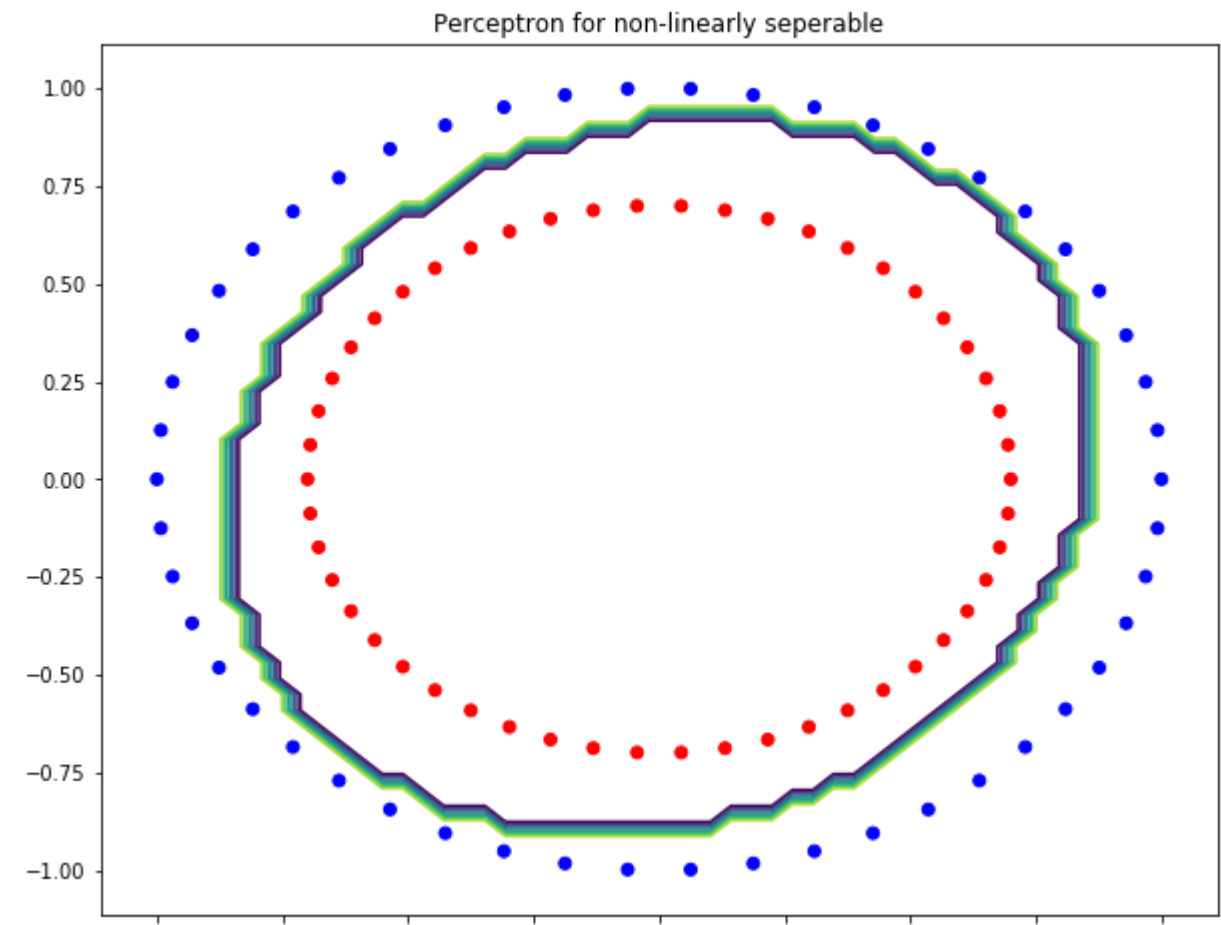
```
In [110]: #perceptron algorithm for non-linearly sepearable data:
```

```
while(error_nisp >= eps):  
    eta = 0.03 #step_size  
    for j in range(len(y_circle)):  
        temp = 0.0  
        temp = np.dot(data[j], W_nisp)  
        if(y_circle[j] == 1 and temp < 0):  
            W_nisp = W_nisp + eta*data[j]  
        elif(y_circle[j] == 0 and temp >= 0):  
            W_nisp = W_nisp - eta*data[j]  
  
    error_nisp = 0  
    for j in range(len(y_circle)):  
        temp = 0.0  
        temp = np.dot(data[j], W_nisp)  
        if(y_circle[j] == 1 and temp < 0):  
            error_nisp = error_nisp + (temp)  
        elif(y_circle[j] == 0 and temp >= 0):  
            error_nisp = error_nisp + (temp)  
  
    #condition to stop while-loop:  
    flag = 0  
    for j in range(len(y_circle)):  
        temp = 0.0  
        temp = np.dot(data[j], W_nisp)  
        if(y_circle[j] == 1 and temp < 0):  
            error_nisp = error_nisp + (temp)  
        elif(y_circle[j] == 0 and temp >= 0):  
            flag = 1  
    if(flag == 1):  
        print(error_nisp)
```

22.111645217939056
10.365483572271625
3.0130380369282515
0.1124895959215786
0

```
In [111]: def J(x, y):  
    t = -(W_nisp[0] + W_nisp[1]*x + W_nisp[2]*y + W_nisp[3]*(x)**2 + W_nisp[4]*(y)**2 + W_nisp[5]*(x*y))  
    return(t >= 0)
```

```
xmin = min(data[:, 1])  
xmax = max(data[:, 1])  
ymin = min(data[:, 2])  
ymax = max(data[:, 2])  
xx = np.linspace(xmin, xmax)  
yy = np.linspace(ymin, ymax)  
P, Q = np.meshgrid(xx, yy)  
zz = J(P, Q)  
  
plt.figure(figsize = (10,8))  
plt.contour(xx, yy, zz)  
c = ['r' if i == 1 else 'b' for i in y_circle]  
plt.scatter(X_circle[:,0], X_circle[:,1], color = c)  
plt.title('Perceptron for non-linearly sepearable')  
plt.show()
```



4. (Perceptron) Repeat the two perceptron example above (make blobs and make circles) generating 1000 points. We are not interested to see the plots now. We instead want to split the dataset into test (50%) and train(50%). Report the test accuracy of perceptron in each case.


```
In [124]: #generating dataset with 1000 points with two different classes.

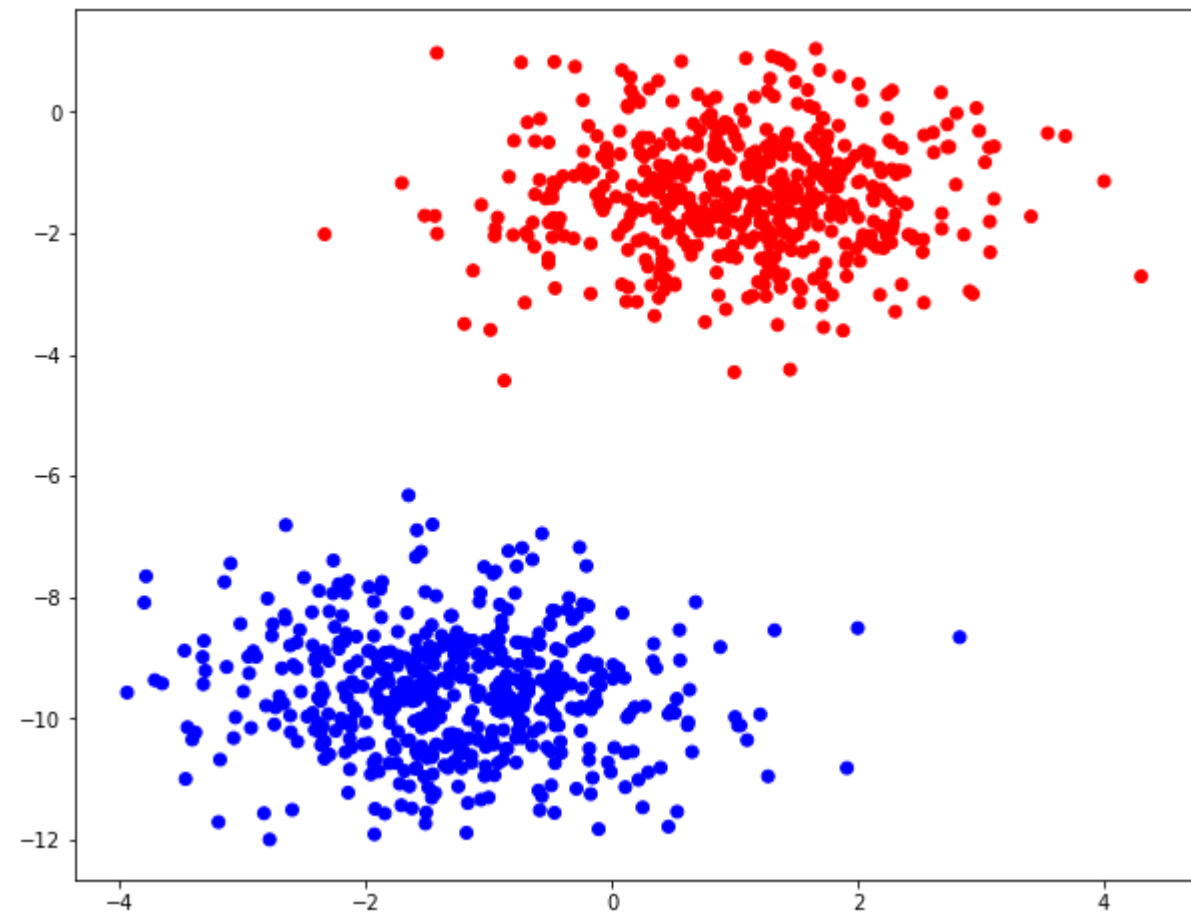
mb, y_4 = make_blobs(n_samples = 1000, centers = 2, n_features = 2, random_state = 2)
```

```
In [125]: X_4 = np.ones((1000,2))
X_4[:, 1:] = mb #augmented matrix with bias
X_4_train = X_4[:500,:]
X_4_test = X_4[500:,:]
y_4_train = y_4[:500]
y_4_test = y_4[500:]
```

```
In [128]: #initial plot for two classes

plt.figure(figsize = (10,8))
c = ['r' if i == 1 else 'b' for i in y_4]
plt.scatter(mb[:,0], mb[:,1], color = c)
```

Out[128]: <matplotlib.collections.PathCollection at 0x25ef022e788>



```
In [140]: W_4_train = np.random.normal(0,1,3)
W_4_train
```

Out[140]: array([-1.25275883, 0.62857382, 0.32795775])

```
In [141]: #training:

# Perceptron using Batch gradient:
error = 0
while(error >= epsilon):
    eta = 0.03 #step_size
    for j in range(len(y_4_train)):
        temp = 0.0
        temp = np.dot(X_4_train[j], W_4_train)
        if(y_4_train[j] == 1 and temp < 0):
            W_4_train = W_4_train + eta*X_4_train[j]
        elif(y_4_train[j] == 0 and temp >= 0):
            W_4_train = W_4_train - eta*X_4_train[j]

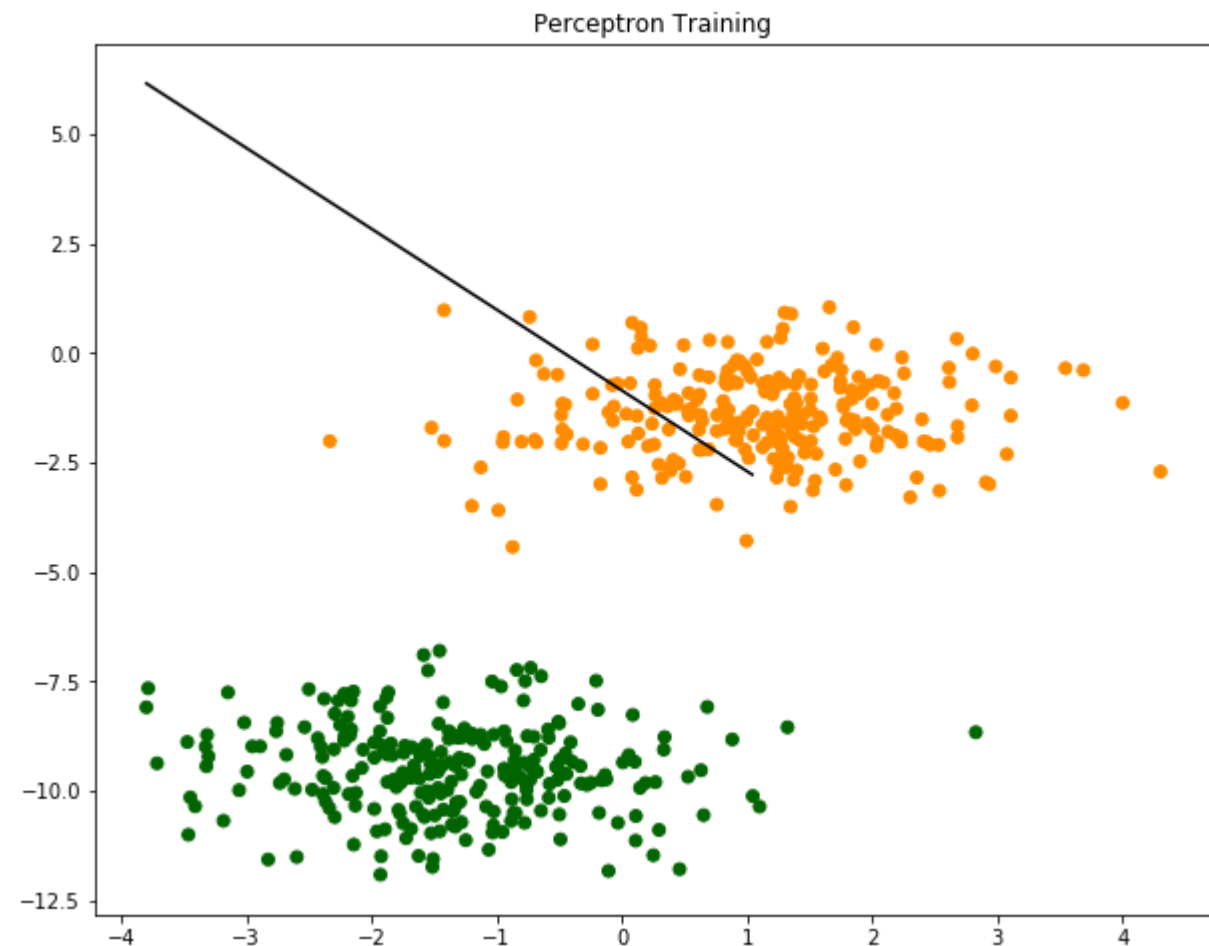
    error = 0
    for j in range(len(y_4_train)):
        temp = 0.0
        temp = np.dot(X_4_train[j], W_4_train)
        if(y_4_train[j] == 1 and temp < 0):
            error = error - (temp)
        elif(y_4_train[j] == 0 and temp >= 0):
            error = error + (temp)

#condition to stop while-loop:
flag = 0
for j in range(len(y_4_train)):
    temp = 0.0
    temp = np.dot(X_4_train[j], W_4_train)
    if(y_4_train[j] == 1 and temp < 0):
        flag = 1
    elif(y_4_train[j] == 0 and temp >= 0):
        flag = 1

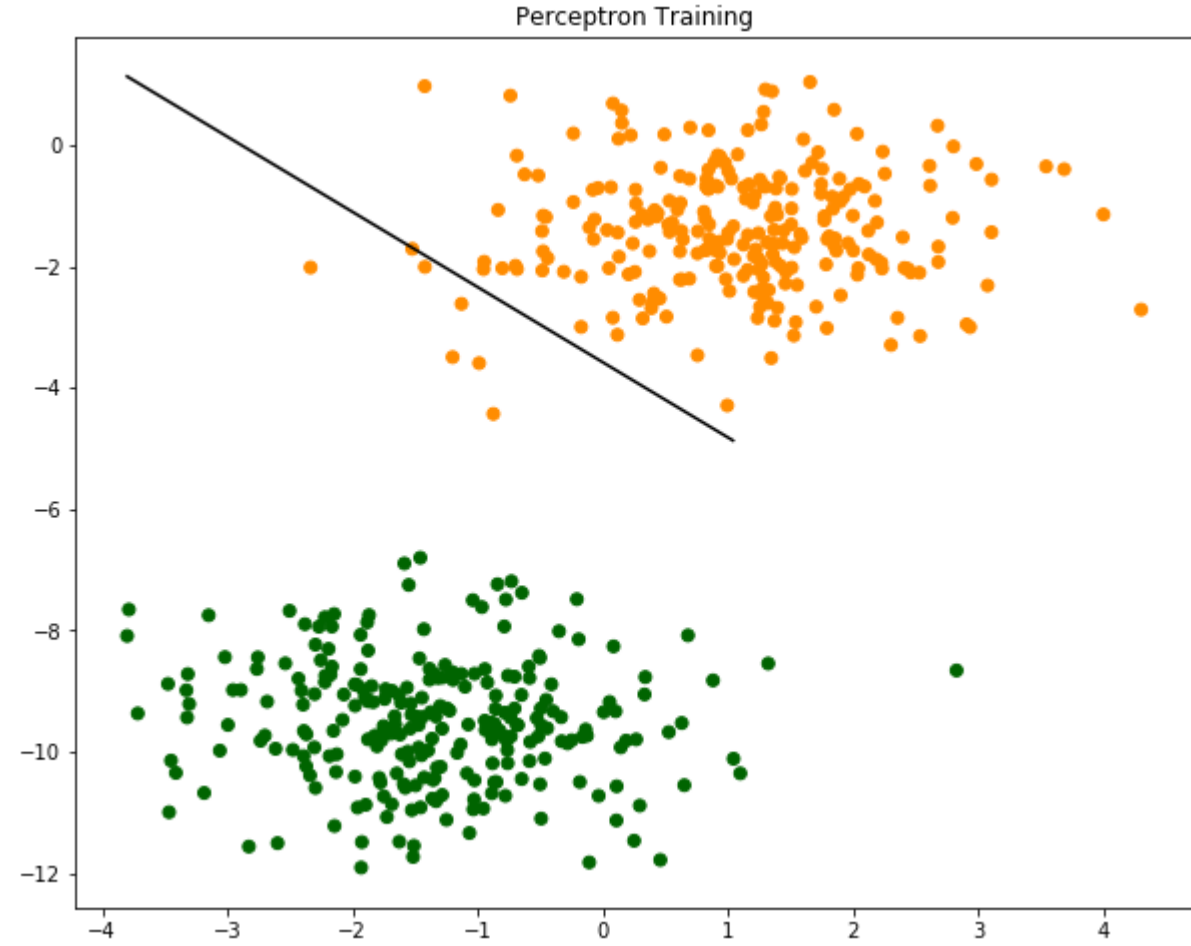
print(error)
print(W_4_train)
xmin_4 = min(X_4_train[:,1])
xmax_4 = max(X_4_train[:,2])
xx_4_train = np.linspace(xmin_4,xmax_4)
yy_4_train = (-W_4_train[0] - W_4_train[1]*xx_4_train) / W_4_train[2]

#train-
plt.figure(figsize = (10,8))
c = ['darkorange' if i == 1 else 'darkgreen' for i in y_4_train]
plt.scatter(X_4_train[:,1], X_4_train[:,2], color = c)
plt.plot(xx_4_train, yy_4_train, color = 'black')
plt.title('Perceptron Training')
plt.show()
if(flag == 0):
    break
```

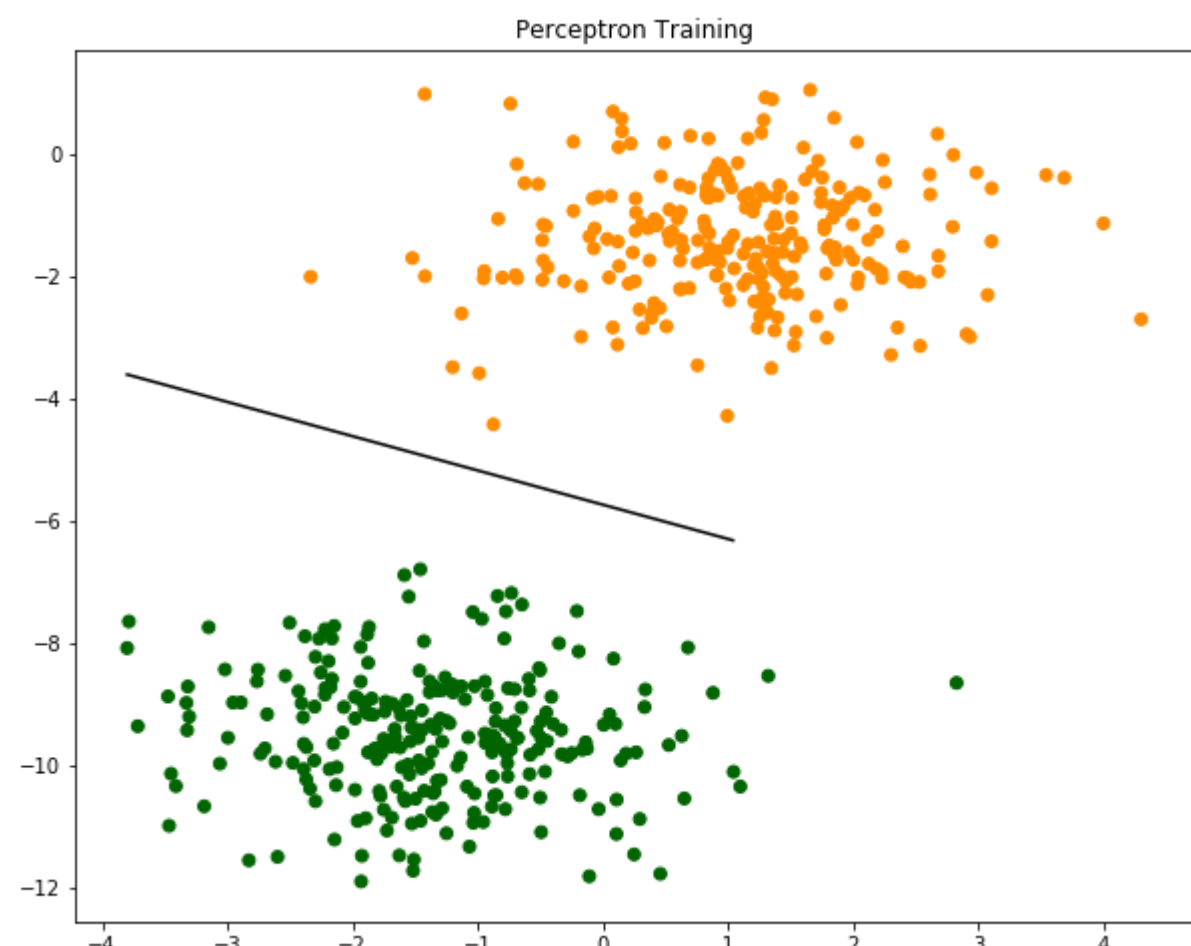
27.90416640319539
[0.27724917 0.5958287 0.32308549]



1.3326758640308132
[0.72724917 0.2520721 0.20333318]

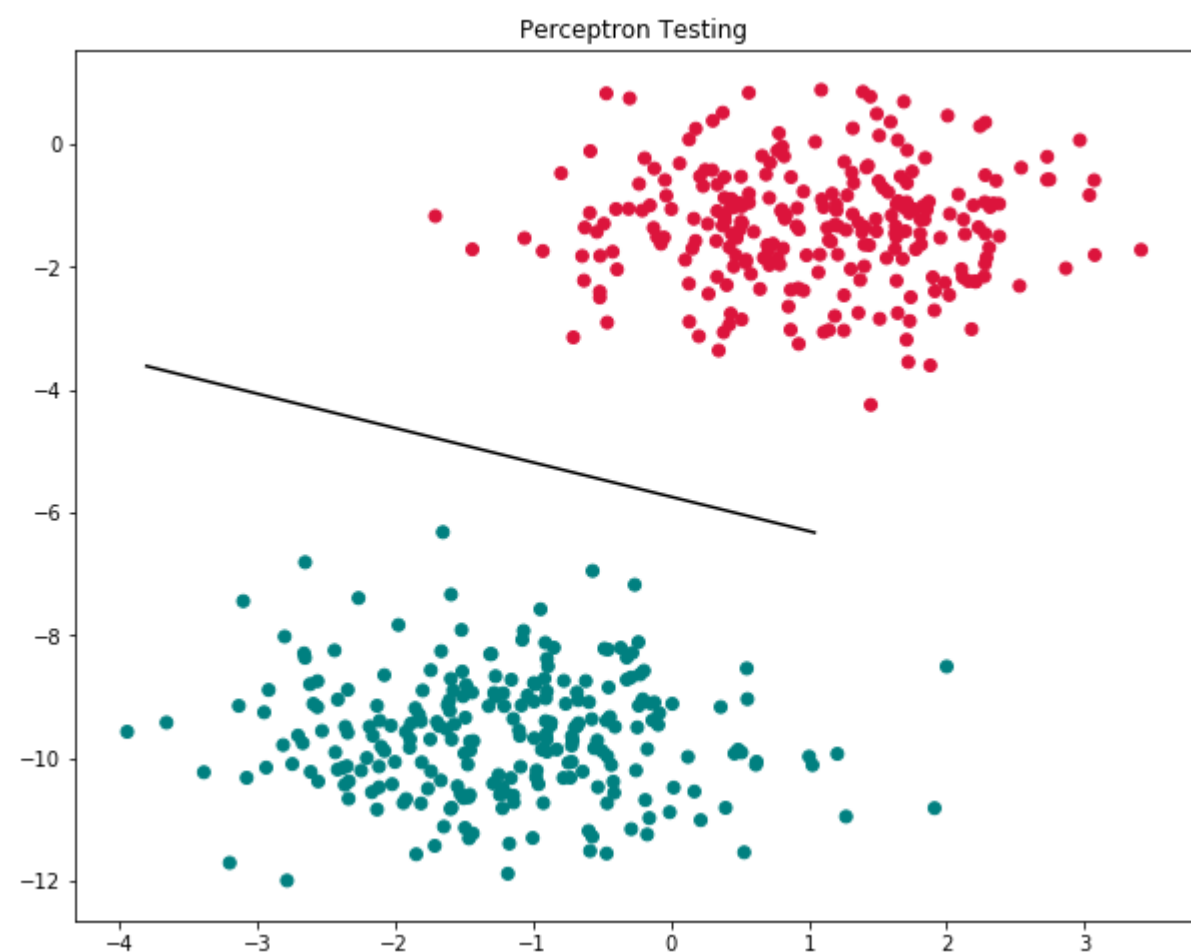


0
[0.81724917 0.07973263 0.14228689]



```
In [143]: #testing:

plt.figure(figsize = (10,8))
c = ['crimson' if i == 1 else 'teal' for i in y_4_test]
plt.scatter(X_4_test[:,1], X_4_test[:,2], color = c)
plt.plot(xx_4_train, yy_4_train, color = 'black') #trained hyperPlane
plt.title('Perceptron Testing')
plt.show()
```

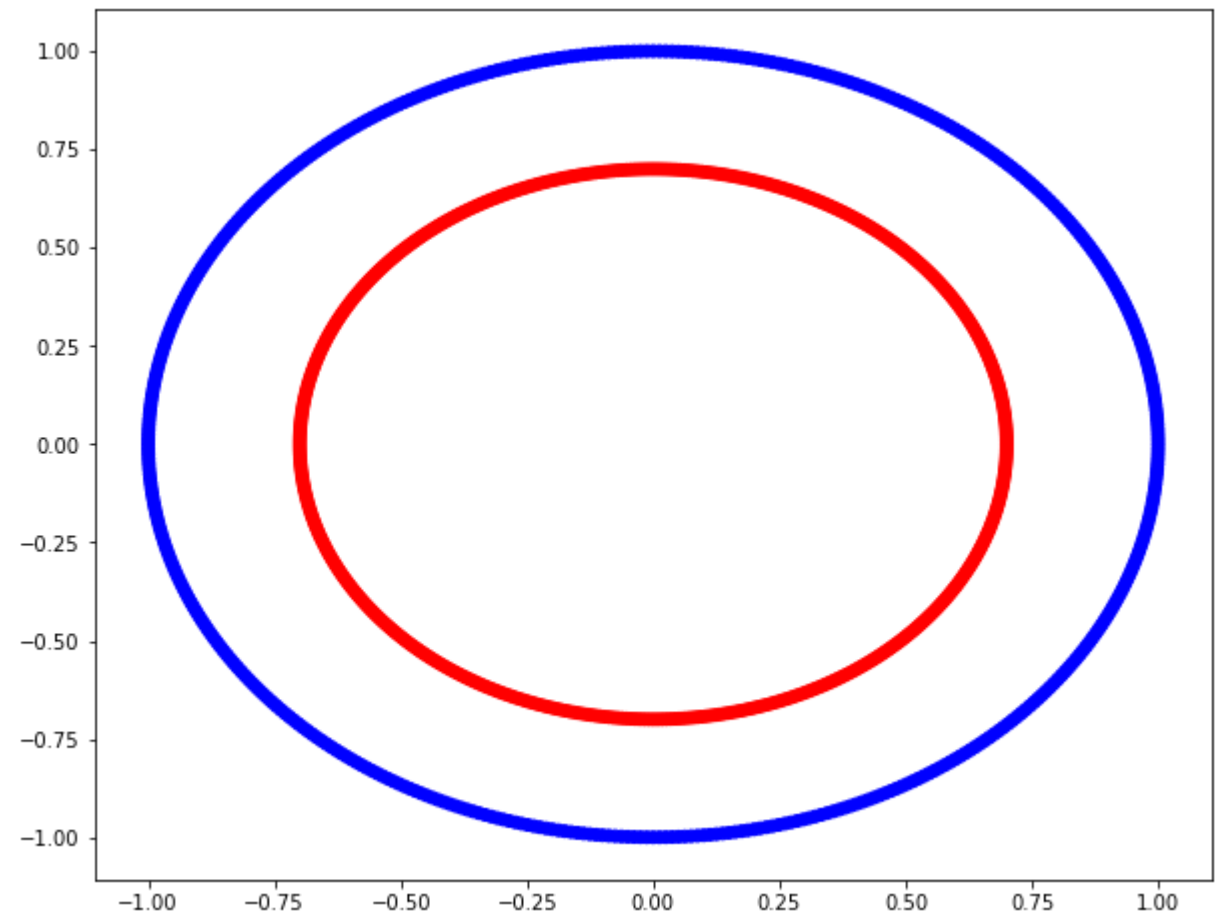


From the plot, we can see that testing accuracy is 100%.(as each point is correctly labeled)

```
In [144]: X_circle_4, y_circle_4 = make_circles(n_samples = 1000, random_state = 2, factor = 0.7)
```

```
In [145]: #initial plot for two classes
plt.figure(figsize = (10,8))
c = ['r' if i == 1 else 'b' for i in y_circle_4]
plt.scatter(X_circle_4[:,0], X_circle_4[:,1], color = c)
```

Out[145]: <matplotlib.collections.PathCollection at 0x25ef25bd848>



```
In [153]: # Creating second order features:
data_4 = np.ones((len(y_circle_4), 6))
```

```
In [154]: data_4[:,1:3] = X_circle_4
```

```
In [155]: data_4[:,3] = X_circle_4[:,0]**2
data_4[:,4] = X_circle_4[:,1]**2
data_4[:,5] = X_circle_4[:,0]*X_circle_4[:,1]
```

```
In [156]: data_4_train = data_4[:500,:]
data_4_test = data_4[500:,:]
y_circle_4_train = y_circle_4[:500]
y_circle_4_test = y_circle_4[500:]
```

```
In [167]: W_nisp_4 = np.random.normal(0,1,6) #initial weights (random)
error_nisp_4 = 3
eps_4 = 10**(-2)
```

```
In [168]: #perceptron algorithm training for non-linearly sepearble data:
```

```
while(error_nisp_4 >= eps_4):
    eta = 0.03 #step_size
    for j in range(len(y_circle_4_train)):
        temp = 0.0
        temp = np.dot(data_4_train[j], W_nisp_4)
        if(y_circle_4_train[j] == 1 and temp < 0):
            W_nisp_4 = W_nisp_4 + eta*data_4_train[j]
        elif(y_circle_4_train[j] == 0 and temp >= 0):
            W_nisp_4 = W_nisp_4 - eta*data_4_train[j]

    error_nisp_4 = 0
    for j in range(len(y_circle_4_train)):
        temp = 0.0
        temp = np.dot(data_4_train[j], W_nisp_4)
        if(y_circle_4_train[j] == 1 and temp < 0):
            error_nisp_4 = error_nisp_4 - (temp)
        elif(y_circle_4_train[j] == 0 and temp >= 0):
            error_nisp_4 = error_nisp_4 + (temp)

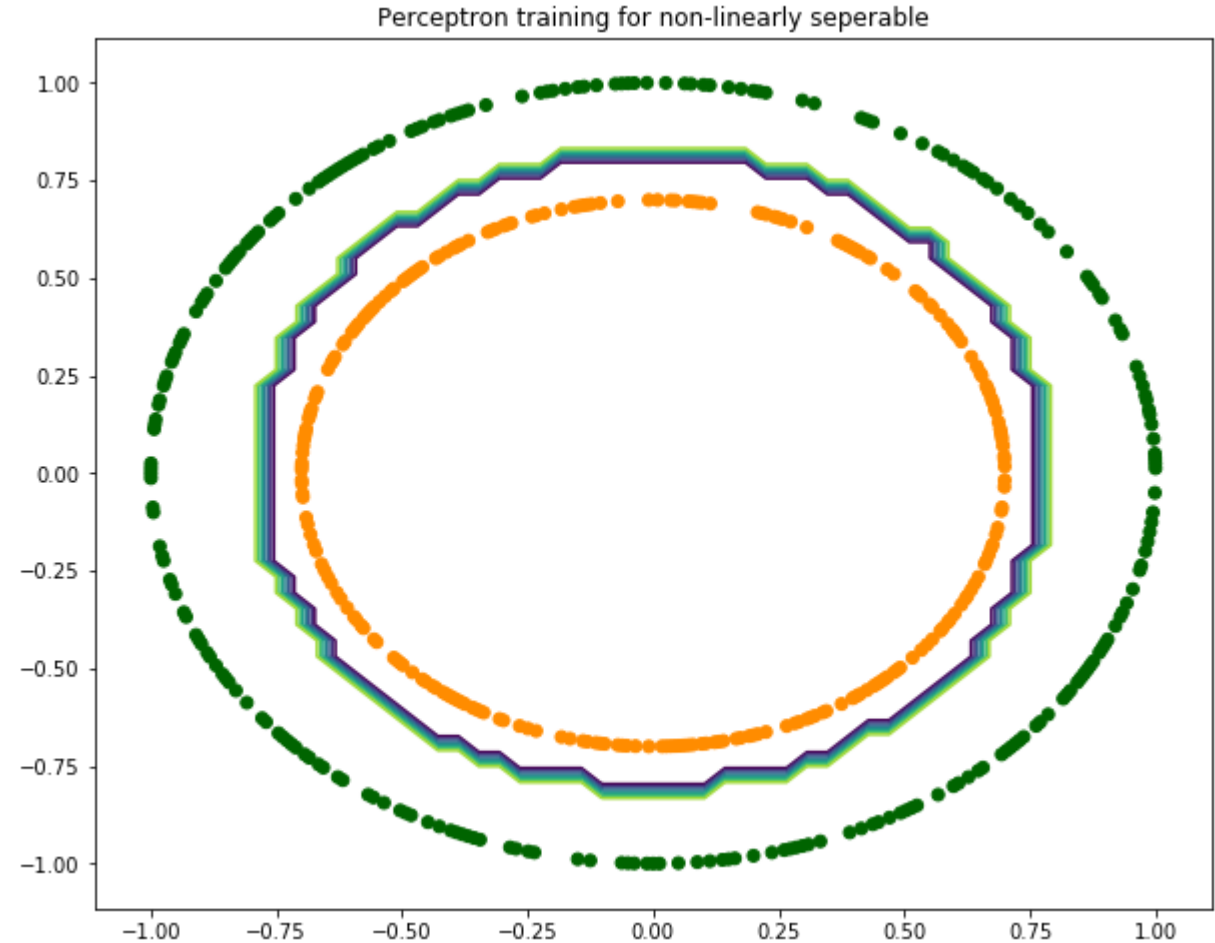
    #condition to stop while-loop:
    flag = 0
    for j in range(len(y_circle_4_train)):
        temp = 0.0
        temp = np.dot(data_4_train[j], W_nisp_4)
        if(y_circle_4_train[j] == 1 and temp < 0):
            flag = 1
        elif(y_circle_4_train[j] == 0 and temp >= 0):
            flag = 1
    print(error_nisp_4)
```

10.92404033893237
0

```
In [169]: def J(x, y):
t = -(W_nisp_4[0] + W_nisp_4[1]*x + W_nisp_4[2]*y + W_nisp_4[3]*(x)**2 + W_nisp_4[4]*(y)**2 + W_nisp_4[5]*(x*y))
return(t >= 0)
```

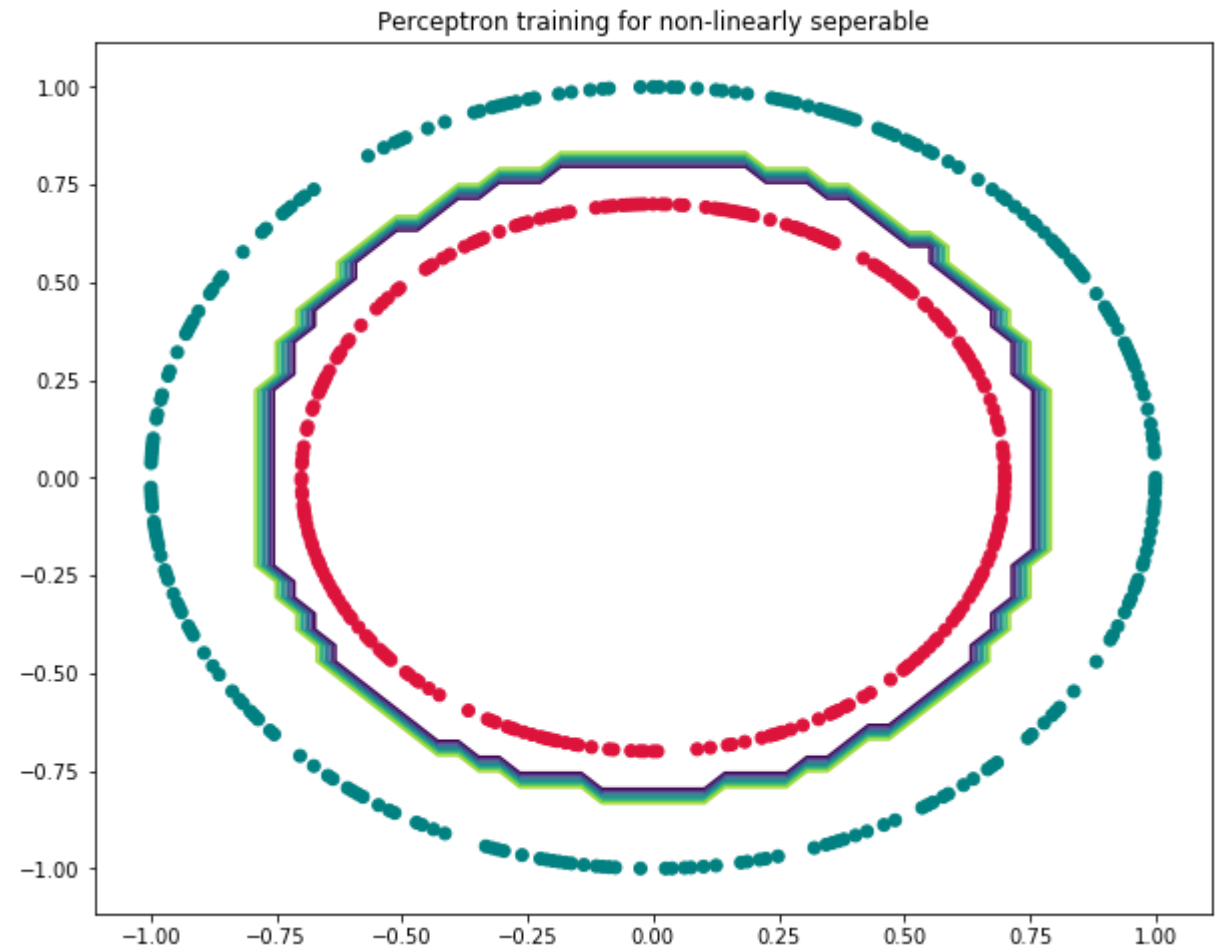
```
xmin_4 = min(data_4_train[:, 1])
xmax_4 = max(data_4_train[:, 1])
ymin_4 = min(data_4_train[:, 2])
ymax_4 = max(data_4_train[:, 2])
xx_4 = np.linspace(xmin_4,xmax_4)
yy_4 = np.linspace(ymin_4,ymax_4)
P_4,Q_4 = np.meshgrid(xx_4, yy_4)
zz_4 = J(P_4, Q_4)
```

```
plt.figure(figsize = (10,8))
plt.contour(xx_4, yy_4, zz_4)
c = ['darkorange' if i == 1 else 'darkgreen' for i in y_circle_4_train]
plt.scatter(X_circle_4[:500,0], X_circle_4[:500,1], color = c)
plt.title('Perceptron training for non-linearly sepearble')
plt.show()
```



```
In [172]: #testing:
```

```
plt.figure(figsize = (10,8))
plt.contour(xx_4, yy_4, zz_4) #trained contour
c = ['crimson' if i == 1 else 'teal' for i in y_circle_4_test]
plt.scatter(X_circle_4[500:,0], X_circle_4[500:,1], color = c)
plt.title('Perceptron training for non-linearly sepearble')
plt.show()
```



We can see that her also, our testing accuracy is 100% (as contour seperates the two circles)