Unit -3 Greedy Technique Lab Notes

Program-11 Write a program to implement the Knapsack problem using the greedy method

```
import java.util.Scanner;
import java.util.Arrays;
import java.util.Comparator;
// Greedy approach for Fractional Knapsack
public class FractionalKnapSack {
  // ItemValue class represents an item with profit and weight.
  static class ItemValue {
     int profit, weight;
     public ItemValue(int profit, int weight) {
       this.profit = profit;
       this.weight = weight;
     }
  }
  // Function to calculate maximum value for the fractional knapsack.
  private static double getMaxValue(ItemValue[] arr, int capacity) {
     // Sorting items by profit/weight ratio in descending order.
     Arrays.sort(arr, new Comparator<ItemValue>() {
       @Override
       public int compare(ItemValue item1, ItemValue item2) {
          double ratio1 = (double) item1.profit / item1.weight;
          double ratio2 = (double) item2.profit / item2.weight;
          return ratio1 < ratio2 ? 1 : -1;
     });
     double total Value = 0d;
     // Iterate over the sorted items
     for (ItemValue item : arr) {
       int curWt = item.weight;
       int curVal = item.profit;
       if (capacity - curWt >= 0) {
          // If the entire item can be taken, subtract its weight and add its profit.
          capacity -= curWt;
          totalValue += curVal;
       } else {
```

```
// Only a fraction of the item can be taken.
          double fraction = (double) capacity / curWt;
          totalValue += (curVal * fraction);
          capacity = 0; // Knapsack is now full.
          break;
       }
     }
    return totalValue;
  }
  // Main method that takes input from the user.
  public static void main(String[] args) {
    Scanner sc = new Scanner(System.in);
    // Input number of items.
    System.out.print("Enter the number of items: ");
    int n = sc.nextInt();
    // Create an array to hold the items.
    ItemValue[] items = new ItemValue[n];
    // Read each item's profit and weight.
    for (int i = 0; i < n; i++) {
       System. out. print ("Enter profit and weight for item" + (i + 1) + ":");
       int profit = sc.nextInt();
       int weight = sc.nextInt();
       items[i] = new ItemValue(profit, weight);
     }
    // Input the knapsack capacity.
    System.out.print("Enter the knapsack capacity: ");
    int capacity = sc.nextInt();
    // Calculate and display the maximum profit.
    double maxValue = getMaxValue(items, capacity);
    System.out.println("Maximum profit: " + maxValue);
    sc.close();
  }
}
```

```
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<terminated> FractionalKnapSack [Java Application] C:\Program Files\Java\jre1.8.0_181\bin\javaw.exe (25-Feb-2025, 12:28:02 pm)

Enter the number of items: 3

Enter profit and weight for item 1: 60

10

Enter profit and weight for item 2: 100

20

Enter profit and weight for item 3: 120

30

Enter the knapsack capacity: 50

Maximum profit: 240.0
```

Program-12 By applying Greedy Technique, write a program to implement a Minimum cost-spanning tree using Prims and Kruskal.

```
import java.util.*;
class KruskalSimple {
  static class Edge implements Comparable<Edge> {
     int src, dest, weight;
     Edge(int src, int dest, int weight) {
       this.src = src;
       this.dest = dest;
       this.weight = weight;
     }
     // Sorting edges based on weight (for PriorityQueue)
     public int compareTo(Edge other) {
       return this.weight - other.weight;
     }
  }
  static int findParent(int[] parent, int node) {
     if (parent[node] != node)
       parent[node] = findParent(parent, parent[node]); // Path Compression
     return parent[node];
  static void union(int[] parent, int[] rank, int u, int v) {
     int rootU = findParent(parent, u);
     int rootV = findParent(parent, v);
     if (rootU!=rootV) {
       if (rank[rootU] > rank[rootV])
          parent[rootV] = rootU;
       else if (rank[rootU] < rank[rootV])
          parent[rootU] = rootV;
```

```
else {
       parent[rootV] = rootU;
       rank[rootU]++;
  }
}
static void kruskalMST(int V, List<Edge> edges) {
  PriorityQueue<Edge> pq = new PriorityQueue<>(edges); // Min-heap of edges
  int[] parent = new int[V];
  int[] rank = new int[V];
  // Initialize disjoint set (each node is its own parent)
  for (int i = 0; i < V; i++) {
     parent[i] = i;
     rank[i] = 0;
  }
  List<Edge> mst = new ArrayList<>();
  int totalCost = 0;
  while (!pq.isEmpty() && mst.size() < V - 1) {
     Edge edge = pq.poll(); // Get the edge with minimum weight
     int rootU = findParent(parent, edge.src);
     int rootV = findParent(parent, edge.dest);
     if (rootU != rootV) { // If adding this edge does NOT form a cycle
       mst.add(edge);
       totalCost += edge.weight;
       union(parent, rank, rootU, rootV);
     }
  }
  // Print the MST
  System.out.println("Minimum Spanning Tree (MST) Edges:");
  for (Edge e: mst) {
     System.out.println(e.src + " - " + e.dest + " (Weight: " + e.weight + ")");
  System.out.println("Total Minimum Cost: " + totalCost);
public static void main(String[] args) {
  int V = 5; // Number of vertices
  List<Edge> edges = Arrays.asList(
     new Edge(0, 1, 2),
     new Edge(0, 3, 6),
     new Edge(1, 2, 3),
     new Edge(1, 3, 8),
     new Edge(1, 4, 5),
     new Edge(2, 4, 7),
```

```
new Edge(3, 4, 9)
);

kruskalMST(V, edges);
}

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<terminated> KruskalSimple [Java Application] C:\Program Files\Java\jre1.8.0_181\bin\javaw.exe (04-Mar-2025, 9:36:53 am)

Minimum Spanning Tree (MST) Edges:
0 - 1 (Weight: 2)
1 - 2 (Weight: 3)
1 - 4 (Weight: 5)
0 - 3 (Weight: 6)

Total Minimum Cost: 16
```

Program 13 Write a program to implement a Single source shortest path (Dijkstra's algorithm) using the greedy method

```
import java.util.*;
public class Dijkstra {
  static final int INF = Integer.MAX_VALUE; // Represents infinity
  // Function to find the vertex with the minimum distance
  static int minDistance(int[] dist, boolean[] visited, int V) {
     int min = INF, minIndex = -1;
     for (int v = 0; v < V; v++) {
       if (!visited[v] &\& dist[v] < min) {
          min = dist[v];
          minIndex = v;
       }
     }
     return minIndex;
  }
  // Dijkstra's algorithm using adjacency matrix
  static void dijkstra(int[][] graph, int src) {
     int V = graph.length;
     int[] dist = new int[V]; // Stores the shortest distance from source
     boolean[] visited = new boolean[V]; // Marks processed nodes
     // Initialize distances with INF and source distance as 0
     Arrays.fill(dist, INF);
     dist[src] = 0;
     // Find the shortest path for all vertices
     for (int count = 0; count < V - 1; count++) {
```

```
int u = minDistance(dist, visited, V); // Pick the min distance node
     visited[u] = true; // Mark as processed
     // Update distances for adjacent vertices
     for (int v = 0; v < V; v++) {
        if (!visited[v] && graph[u][v] != 0 && dist[u] != INF &&
             dist[u] + graph[u][v] < dist[v]) {
          dist[v] = dist[u] + graph[u][v];
        }
     }
  }
  // Print the shortest path distances
  printSolution(dist, src);
}
// Function to print the shortest distances
static void printSolution(int[] dist, int src) {
  System.out.println("Vertex \t Distance from Source " + src);
  for (int i = 0; i < dist.length; i++) {
     System.out.println(i + " \ t " + (dist[i] == INF ? "INF" : dist[i]));
  }
}
public static void main(String[] args) {
  int[][] graph = {
     \{0, 10, 0, 30, 100\},\
     \{10, 0, 50, 0, 0\},\
     \{0, 50, 0, 20, 10\},\
     \{30, 0, 20, 0, 60\},\
     \{100, 0, 10, 60, 0\}
  };
  int source = 0; // Starting node
  dijkstra(graph, source);
```

}

```
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<terminated > Dijkstra [Java Application] C:\Program Files\Java\jre1.8.0_181\bin\javaw.exe (04-Mar-2025, 1:07:05 pm)

Vertex Distance from Source 0

0 0

1 10

2 50

3 30

4 60
```

Working:

1□ Graph Representation (Adjacency Matrix)

```
int[][] graph = {
    {0, 10, 0, 30, 100},
    {10, 0, 50, 0, 0},
    {0, 50, 0, 20, 10},
    {30, 0, 20, 0, 60},
    {100, 0, 10, 60, 0}
};
```

- The graph is represented as a 2D matrix (graph [V] [V]).
- If graph[i][j] = weight, then there is an edge from vertex i to j with that weight.
- If graph[i][j] = 0, no direct edge exists.

2□ Initializing the Algorithm

```
int[] dist = new int[V]; // Stores shortest distances boolean[] visited = new boolean[V]; // Marks visited nodes Arrays.fill(dist, INF); // Set all distances to Infinity dist[src] = 0; // Distance to the source is 0
```

- dist[] holds the shortest distance from the source vertex to every other vertex.
- visited[] tracks which nodes have been processed.
- All distances are initially set to Infinity (INF), except for the source node (dist[src] = 0).

3 ☐ Finding the Minimum Distance Node (minDistance function)

```
static int minDistance(int[] dist, boolean[] visited, int V) {
   int min = INF, minIndex = -1;
   for (int v = 0; v < V; v++) {
      if (!visited[v] && dist[v] < min) {
        min = dist[v];
        minIndex = v;
      }
   }
  return minIndex;
}</pre>
```

- Finds the unvisited vertex with the smallest distance.
- This ensures that we always process the closest vertex first (Greedy approach).

4 □ Processing Each Vertex

```
for (int count = 0; count < V - 1; count++) {</pre>
```

```
int u = minDistance(dist, visited, V); // Pick the closest vertex visited[<math>u] = true; // Mark it as visited
```

- Selects the closest unvisited vertex (u).
- Marks it as **visited**, so we don't process it again.

5 □ Updating Adjacent Nodes

- Conditions for updating a vertex v:
 - 1. v is not visited.
 - 2. There is an edge from u to v (graph [u] $[v] \neq 0$).
 - 3. The distance to u is not INF (so it's reachable).
 - 4. The new distance (dist[u] + graph[u][v]) is smaller than the current dist[v], so we update it.

6 □ Printing the Shortest Distances

```
static void printSolution(int[] dist, int src) {
    System.out.println("Vertex \t Distance from Source " + src);
    for (int i = 0; i < dist.length; i++) {
        System.out.println(i + " \t " + (dist[i] == INF ? "INF" : dist[i]));
    }
}</pre>
```

• Prints the **shortest distances** from the **source vertex** to all other vertices