

Gradient Boosting

Gradient Boosting is a **supervised learning** algorithm used for **classification and regression**. It is an **ensemble technique** that builds multiple weak learners (usually decision trees) in a sequential manner, where each new tree **corrects the errors** of the previous ones using gradient descent.

How Gradient Boosting Works

1. **Train an initial weak learner** (usually a decision tree).
2. **Calculate residuals (errors)** between actual and predicted values.
3. **Fit a new weak learner** to predict the residuals.
4. **Update the model** by adding this new learner to minimize error.
5. **Repeat** steps 2–4 for a fixed number of iterations or until errors are minimized.

Popular Variants of Gradient Boosting

1. **XGBoost (Extreme Gradient Boosting)** → Faster and more regularized version.
 2. **LightGBM (Light Gradient Boosting Machine)** → Optimized for large datasets.
 3. **CatBoost (Categorical Boosting)** → Designed for handling categorical features efficiently.
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When to Use Gradient Boosting?

- ✓ When you need **high accuracy** and are okay with longer training times.
- ✓ When working with **structured/tabular data** (like Kaggle competitions).
- ✓ When **feature importance** is useful for interpretability.

Day-8 Gradient Boosting

⇒ Gradient boosting is a type of ensemble supervised machine learning algorithm that combines multiple weak learners to create a final model. It can be used for both classification and regression problems.

Gradient Boosting:

idea! • Predictor F_k at stage k incurs loss $L(F_k(x), y)$

- Train h_{k+1} to approximate negative gradient:

$$h_{k+1}(x) \approx \frac{-\partial L(F_k(x), y)}{\partial F_k(x)}$$

- Update predictor by adding a multiple η_{k+1} of h_{k+1} :

$$F_{k+1}(x) \leftarrow F_k(x) + \eta_{k+1} h_{k+1}(x)$$

⇒ • Consider squared loss

$$L(F_k(x_n), y_n) = \frac{1}{2} (F_k(x_n) - y_n)^2$$

- Negative gradient corresponds to residual r

$$-\frac{\partial L(F_k(x_n), y_n)}{\partial F_k(x_n)} = y_n - F_k(x_n) = r_n$$

- Train base learner h_{k+1} with residual dataset $\{(x_n, r_n)\}_{n=1}^N$

- Base learner h_{k+1} can be any non-linear predictor (often a small decision tree)

⇒ Pseudo Code: GBA:

- Initialize predictor with a constant c :

$$f_0(x_n) = \arg \min_c \sum_n L(c, y_n)$$

- for $k=1$ to K do

→ compute pseudo residual $r_n = -\frac{\partial L(F_{k-1}(x_n), y_n)}{\partial F_{k-1}(x_n)}$
difference between prediction and target

~ Train a base learner h_k with residual dataset $\{(x_n, r_n)\}$

~ Optimize step length

$$\eta_k = \underset{\eta}{\operatorname{argmin}} \sum_n w(f_k(x_n) + \eta h_k(x_n), y_n)$$

~ Update predictor: $f_k(x) \leftarrow f_{k-1}(x) + \eta_k h_k(x)$