

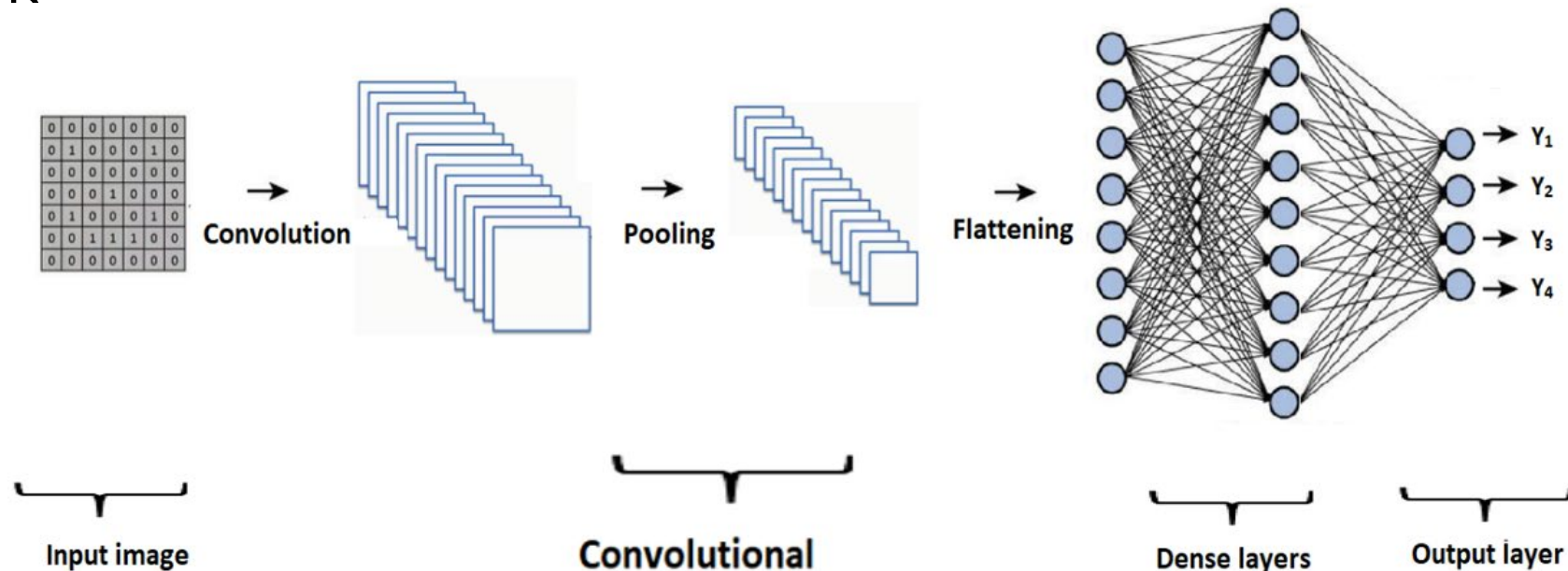
# Convolutional layer & GPUs



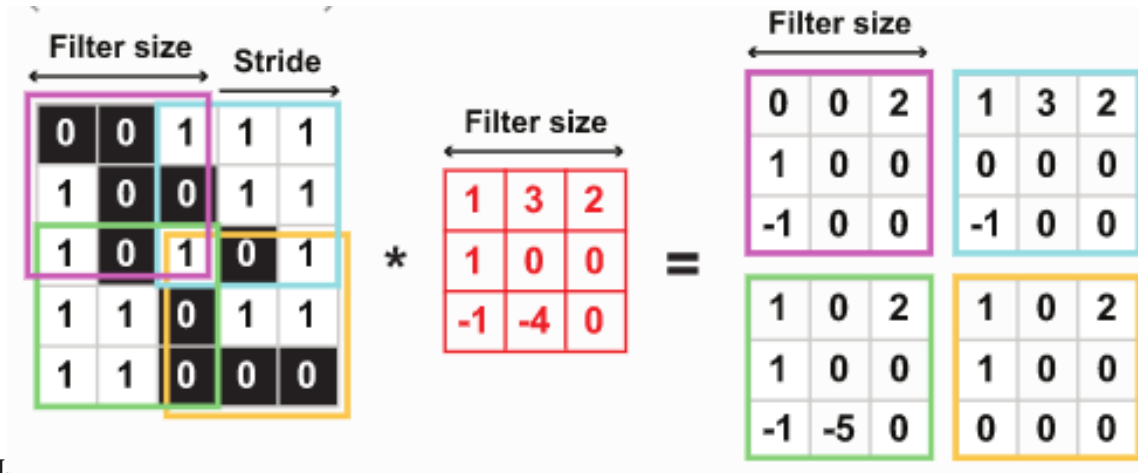
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# Convolutional layer

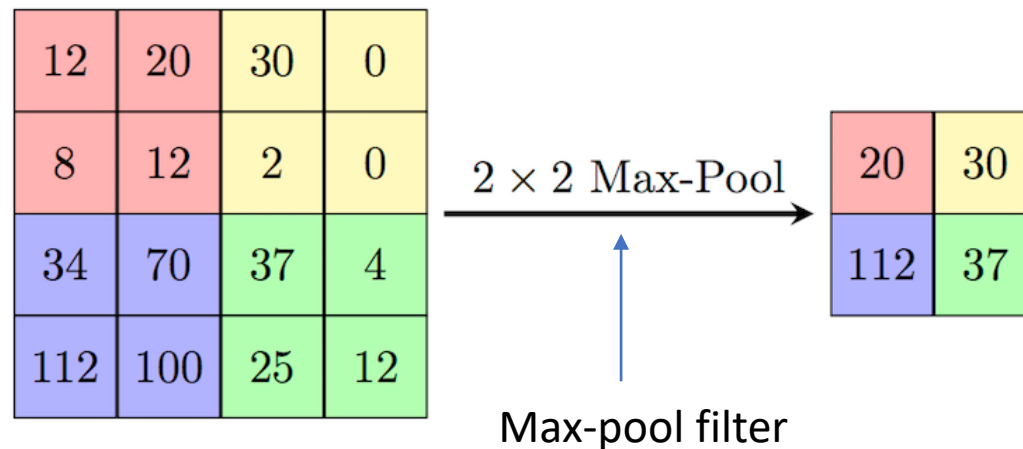
- The convolutional layer prepares the input data for the fully connected neurons (hidden layers)
- Procedures happening the convolutional layer:
  - Filtering
  - Pooling
  - Flatten &  $\sim$

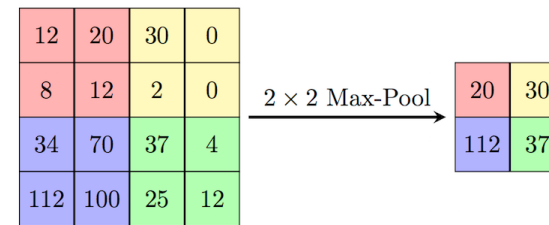
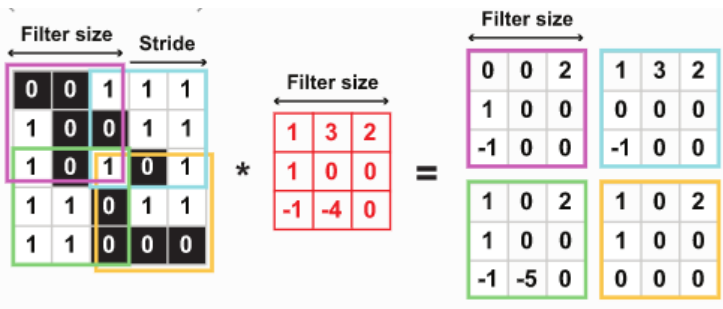


- Filters (kernel):
  - In charge to detect features
    - In images:
      - Can detect for example, lines, corners
      - Can also be specific: eyes, hair, etc.
  - Is a matrix of  $m * n$ . Size of the matrix depends on the application
    - Initialized randomly
    - Stride: how many “cells” the filter moves for a dot product
  - Operation:
    - A dot product operation is executed between the input data and the filter



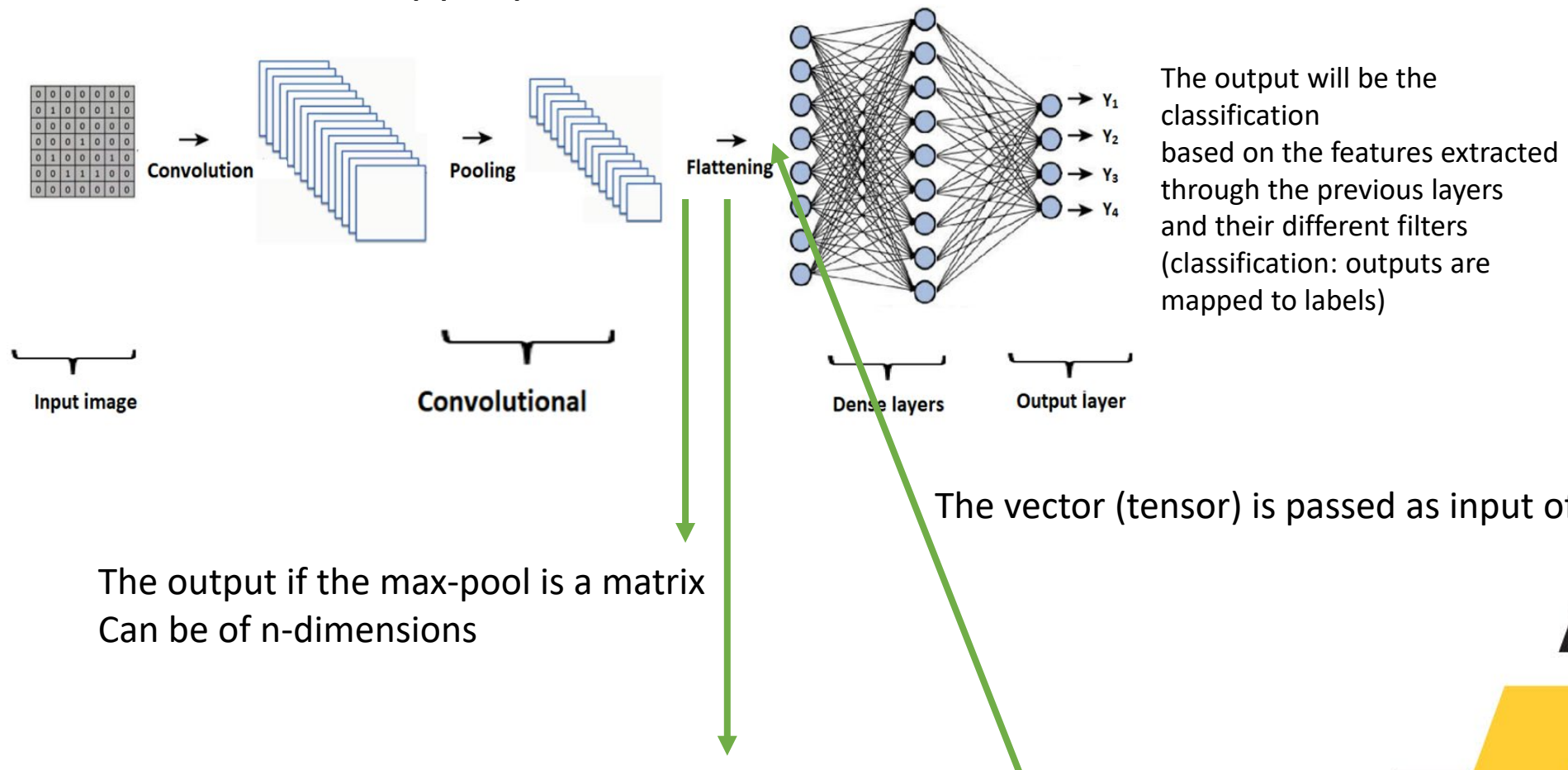
- Pooling:
  - To reduce dimensionality
  - Eliminates noise from data
- Max pooling: after the dot product of the filter and input is executed
  - A max pooling filter (of  $m \times n$ ) selects the max value and creates a new max pool.





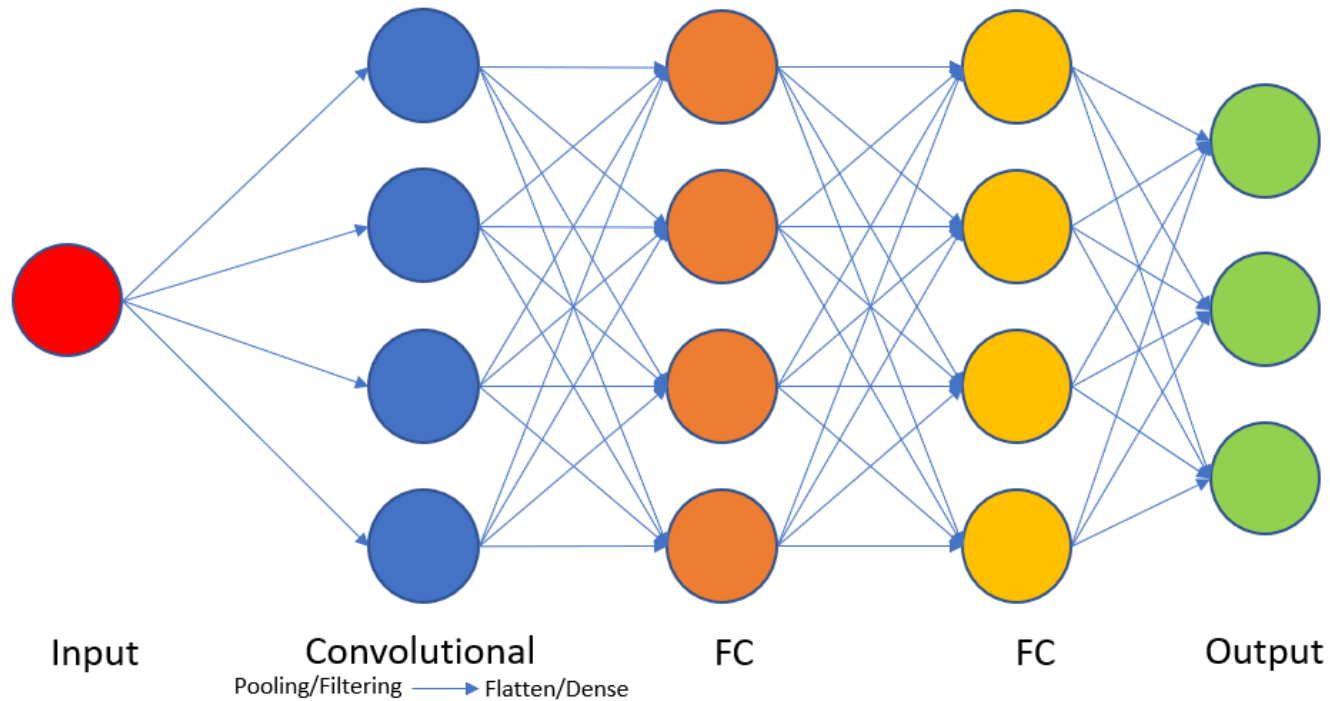
- Flatten & Dense:

- Flatten: For the neurons to perform their own operations, the input data needs to be an appropriate format:



**Flattening:** “Converts” n-dimension into a “readable” vector (tensor)

- Dense:
  - Method to create a fully connected neural network
  - Specifies the number of neurons per layer and activation method





- How is a CNN processed when GPUs are available?

## GPU ARCHITECTURE

Streaming Multiprocessor (SM)

Many CUDA Cores per SM

Architecture dependent

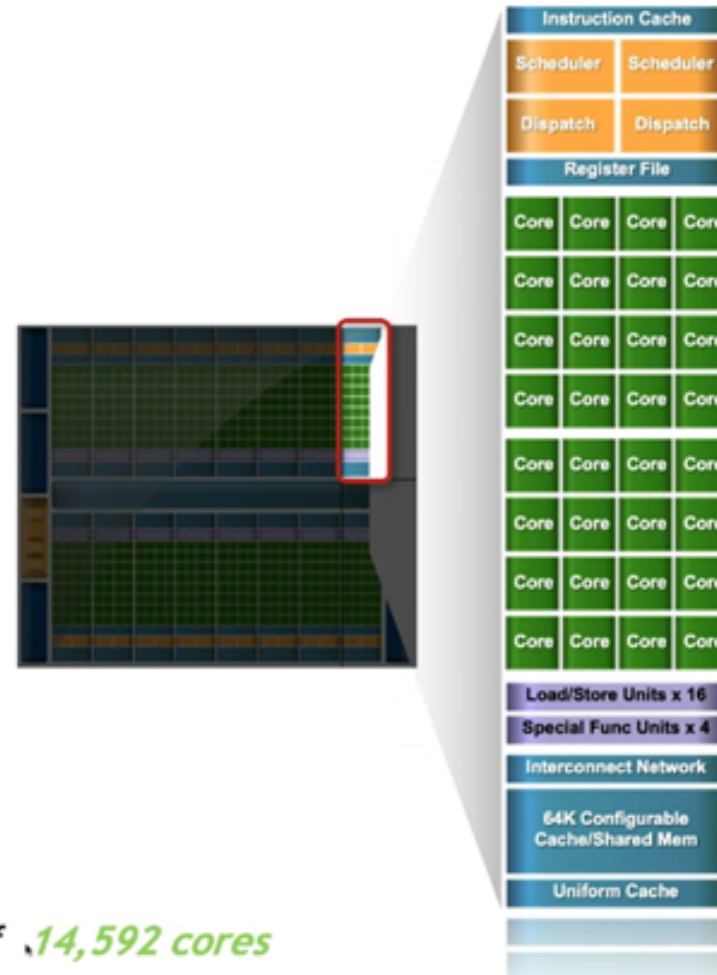
*H100 SM has 128 cores*

Special-function units

cos/sin/tan, etc.

Shared mem + L1 cache

Thousands of 32-bit registers

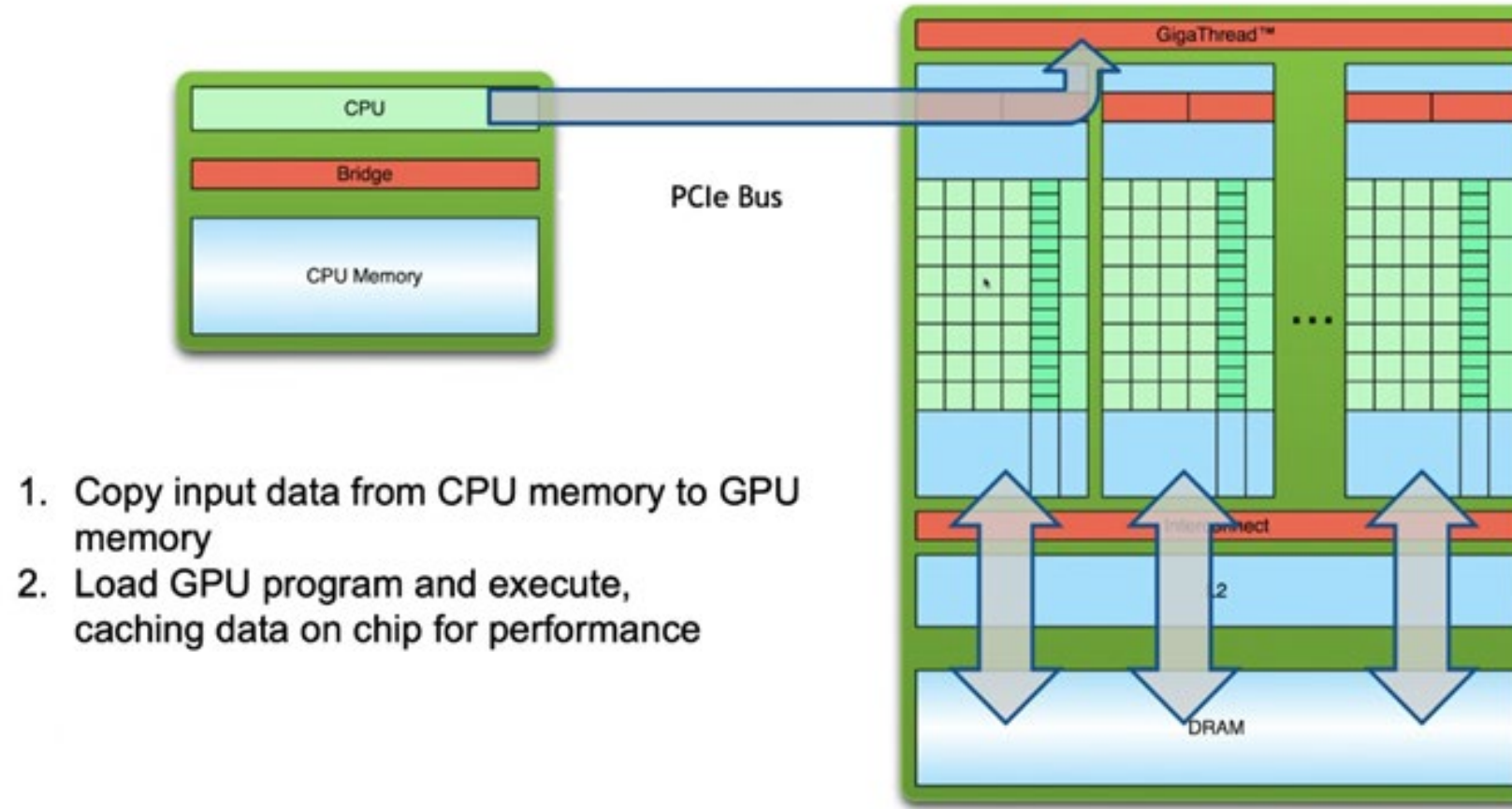


*H100 PCIe has a total of 14,592 cores*



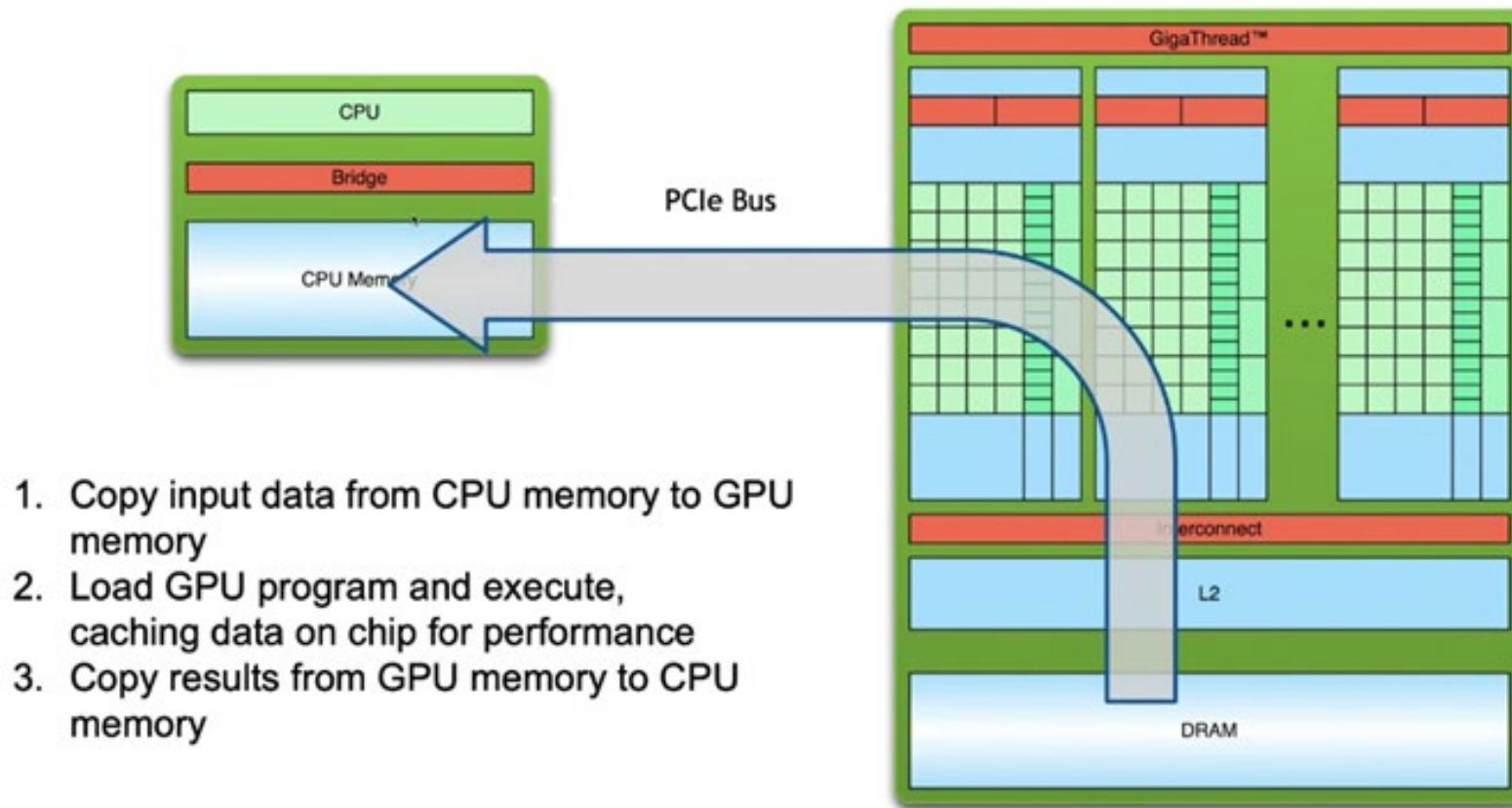
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## PROCESSING FLOW



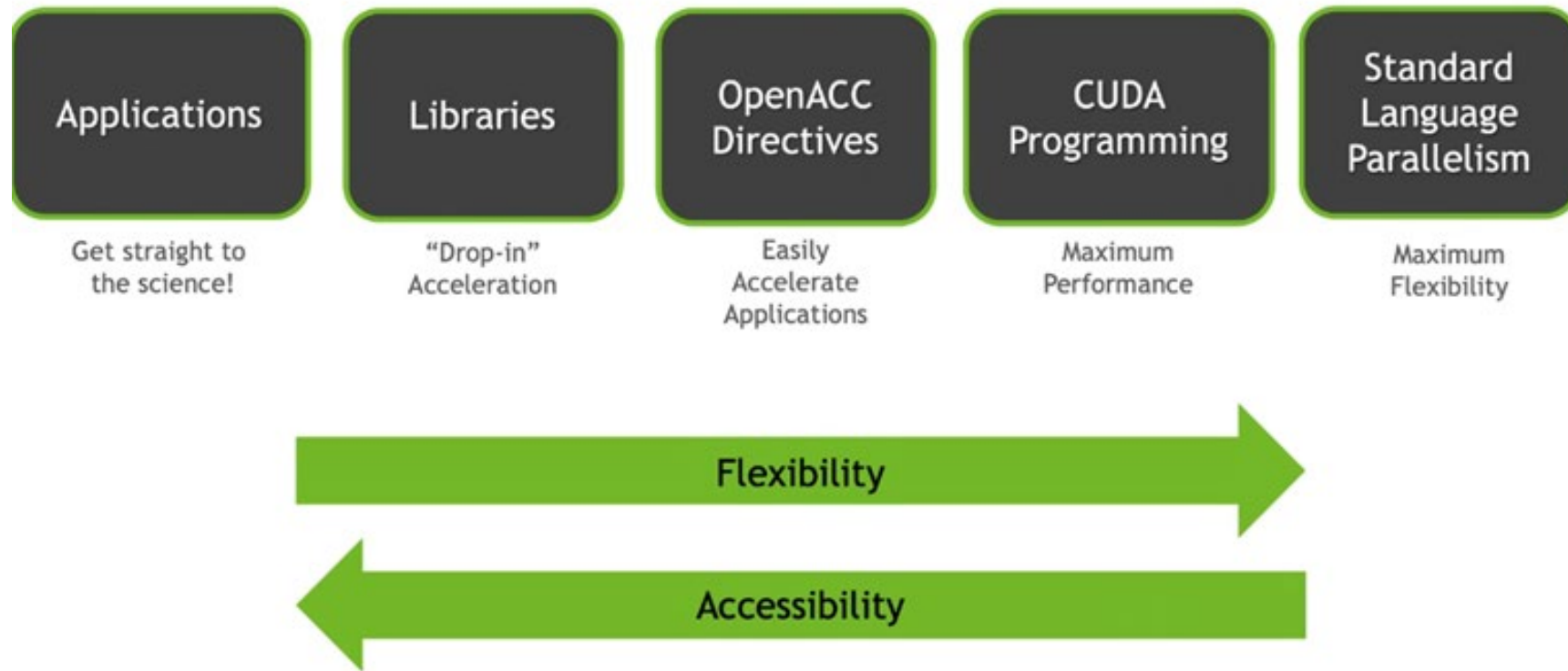
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## PROCESSING FLOW



- How is a CNN processed when GPUs are available?

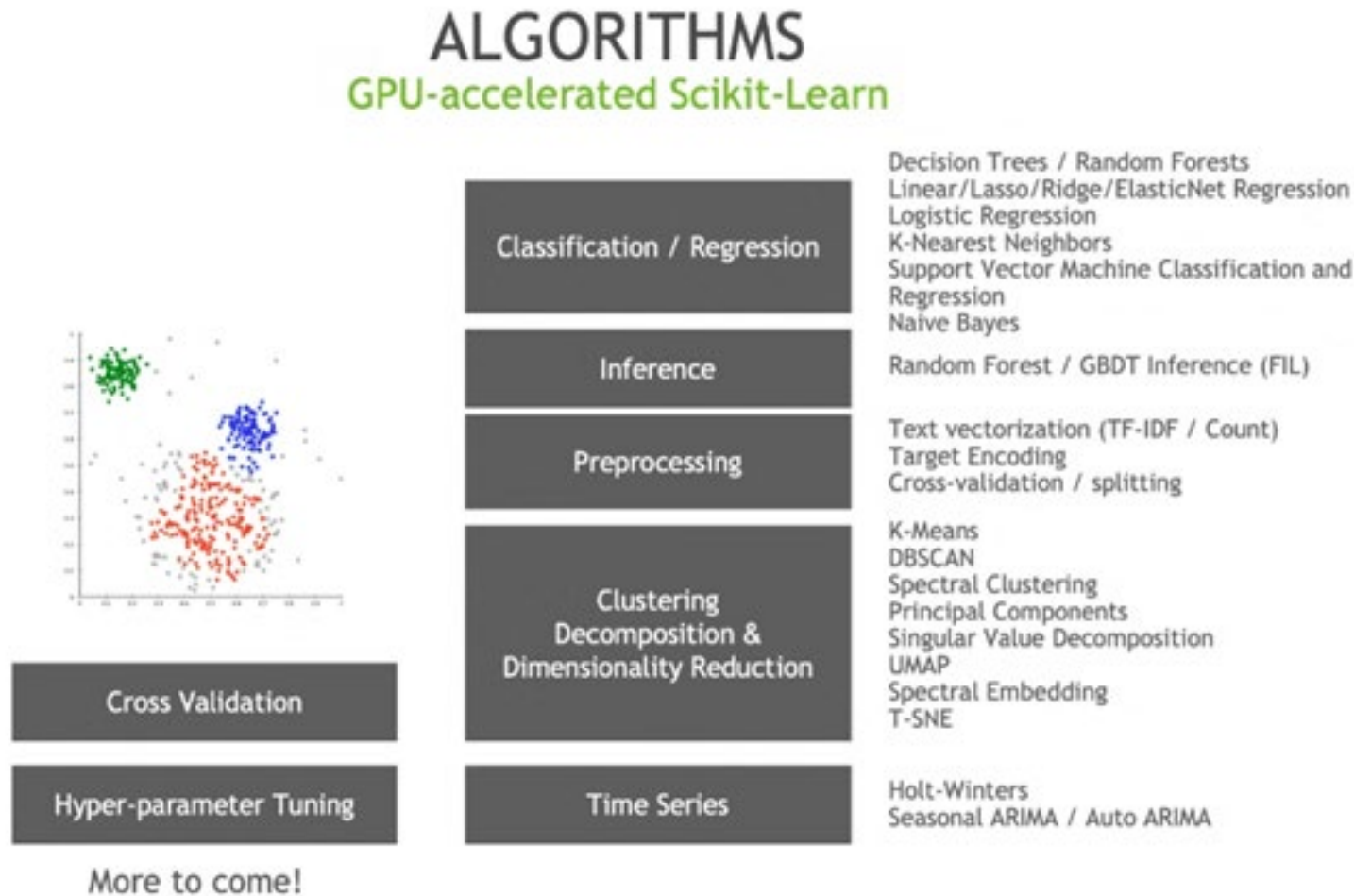
## 5 WAYS TO ACCELERATE WITH GPUS



- How is a CNN processed when GPUs are available?



- How is a CNN processed when GPUs are available?





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