

Motor rotation through AVR-GCC

CONTENTS

1	Components	1
2	Rotation	1

Abstract—This manual shows how to rotate a motor using AVR-GCC.

1 COMPONENTS

- 1) Arduino board
- 2) DC Motor
- 3) Breadboard
- 4) Wires

2 ROTATION

- 1) Install **subversion**

```
sudo apt update
sudo apt install subversion
```

- 2) Refer the pin diagram of L293D motor driver IC

```
Arduino/IDE/MotorControl/Figures/pin.jpg
```

- 3) Connect external 9V battery to the Vcc2 pin of L293D motor driver IC
- 4) Connect Vcc1 and IN1 pins to 5V output on Arduino and IN2 pin to GND.
- 5) The enable pin(ENA) of the L293D IC are connected to Arduino digital output pin(2).
- 6) Connect a motor to across OUT1 & OUT2 pins of L293D motor driver IC.
- 7) Go to your working directory and download the folder titled **codes** using the following command.

```
Arduino/AVR_GCC/MotorControl/Codes
```

- 8) Connect your arduino to the computer and open a terminal.
- 9) Open a terminal and go to the **codes** directory. Type **make**.
- 10) Now you can see the motor rotation.
- 11) If you open **main.c** in **geany**, you can execute the code by **Shift+F9**.