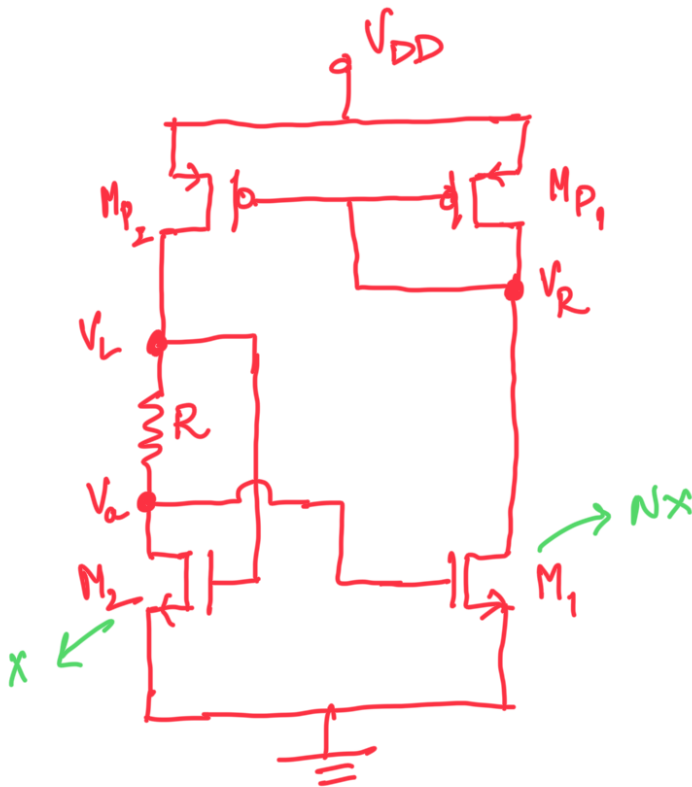
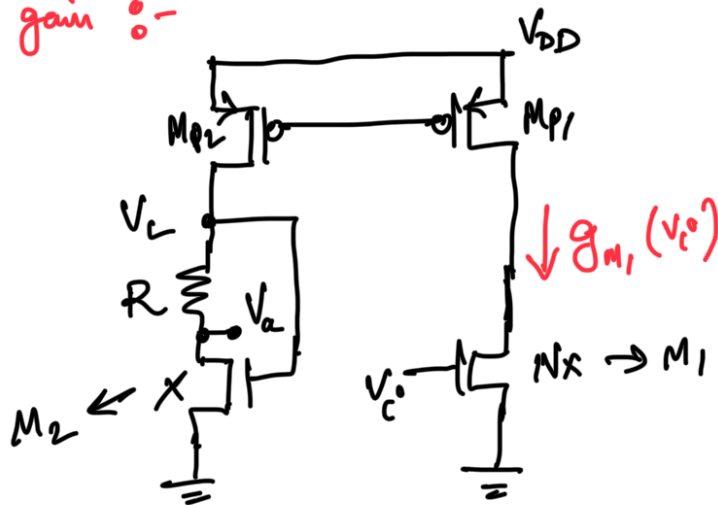


# Analysis of Beta-Multiplier [Variant - II]



Assume,  
PMOS current mirrors  
identical -  
 $\lambda = 0$  for all devices

open loop gain :-



$$I_{M_{P1}} = g_{m1}(v_i)$$

$$I_{M_{P2}} = g_{m1}(v_i) \quad (\text{since identical PMOS-current mirrors})$$

$$V_L = \frac{1}{g_{m2}} \cdot I_{M_{P2}} = \frac{g_{m1} \cdot v_i}{g_{m2}}$$

$$V_L = \frac{g_{m1}}{g_{m2}} \cdot v_i$$

$$V_a = V_L - I_{MP_2} R$$

$$= \frac{g_{m1}}{g_{m2}} v_i - g_{m1} v_i R$$

$$V_a = g_{m1} v_i \left[ \frac{1}{g_{m2}} - R \right]$$

$$= g_{m1} \left[ \frac{1 - g_{m2} R}{g_{m2}} \right]$$

$$= \frac{g_{m2} \sqrt{N} [1 - g_{m2} R]}{g_{m2}}$$

$$\left( \text{Since, } \left( \frac{W}{L} \right)_{M_1} = N \left( \frac{W}{L} \right)_{M_2} \right)$$

$$\left[ \frac{V_a}{v_i} = \sqrt{N} [1 - g_{m2} R] \right]$$

(b)

$$\left[ \frac{V_a}{v_i} = \sqrt{N} - g_{m1} R \right]$$

The primary focus of this topology is to servo the  $g_m$  of the mosfet with precise off-chip resistor 'R' in the circuit.

If the topology is stable,  
then  $I_{MP1} = I_{MP2}$ .

•) Let  $V_{OD,M1}$  is the overdrive voltage of  $M_1$

$$V_a = V_{OD,M1}$$

$$\Rightarrow V_L = \sqrt{N} [V_{OD,M1}]$$

$$V_L - V_a = \sqrt{N} [V_{OD,M1}] - V_{OD,M1}$$

$$V_L - V_a = I R$$

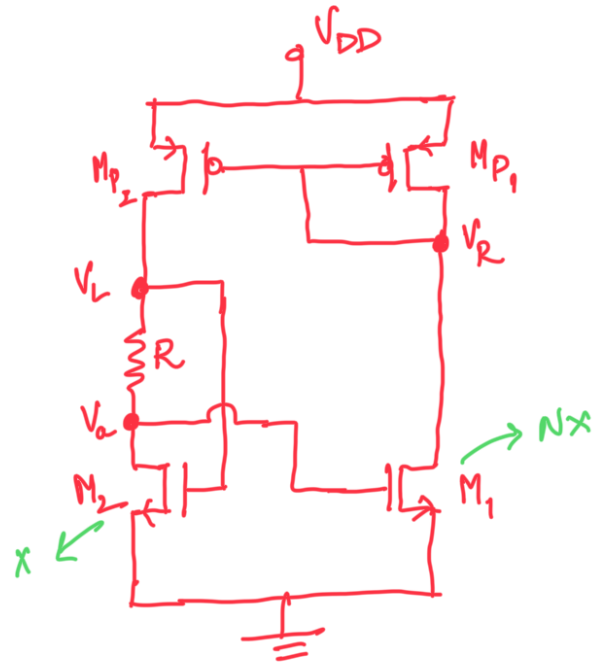
$$V_{OD,M1} [\sqrt{N} - 1] = I R$$

$$\frac{[\sqrt{N} - 1]}{R} = \frac{I}{V_{OD,M1}}$$

$$\frac{2 [\sqrt{N} - 1]}{R} = \frac{2 I}{V_{OD,M1}}$$

$$\frac{2 [\sqrt{N} - 1]}{R} = g_{m1}$$

$$g_{m1} R = 2 [\sqrt{N} - 1] \quad \text{Constant}$$



$$g_{m2}R = \frac{2[\sqrt{N}-1]}{\sqrt{N}} \rightarrow \text{Constant}$$

For a given,  $N$ , if the topology is stabilized,  
then the  $A_{OL}$  is,

$$\begin{aligned} A_{OL} &= \sqrt{N} [1 - g_{m2}R] \\ &= \sqrt{N} \left[ 1 - \frac{2[\sqrt{N}-1]}{\sqrt{N}} \right] \end{aligned}$$

$$= \sqrt{N} - 2\sqrt{N} + 2$$

$$[A_{OL} = 2 - \sqrt{N}]$$

This can be,

+ve feedback with  $A_{OL} > 1$

+ve feedback with  $A_{OL} < 1$

-ve feedback [but low gain]

depending on  $N$ , nothing but how we size

If  $N$  is increased from  $N=1$  ( $N=1$  means size of  $M_1$  and  $M_2$  are same),  
then the open loop gain greater than 1 (unstable)  
and then it will be  $< 1$  (stable) to very  
low open loop gain (negative feedback)