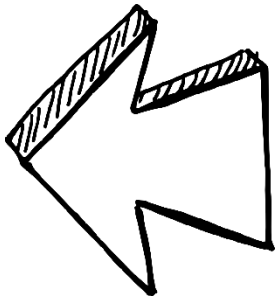
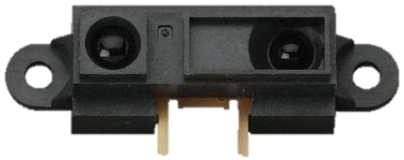
Robot Layout



Frontwards

Sensor Right



Sensor Front

Sensor Left

Right side

Motor #1A

Motor #1B
Encoder #1

Motor #2B

Motor #2A
Encoder #2

Left side

INGENIARIUS