# CS528 Common Sense Opt. and Data Access Optimization

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#### **Outline**

- CSO: Prev Part
- Machine Balance
- Application Balance
- Performance: Roofline Model
- Benchmark: Data Access
- Test Cases

#### **Common sense of Optimizations**

- Do less work
- Avoid expensive operations
  - Strength reduction: Convert costly to cheaper OPS
  - LUT
- Shrink the working set

#### **CSO:** Do less work

```
bool Flag=false;
for (i=0; i<N; i++) {
   if (complex_func(A[i]) < THRESHOLD )
     Flag=true;
}</pre>
```

#### **CSO:** Avoid expensive operations

```
int L, R, U, O, S, N; //can be +1 or -1
double tt=0.83;
for (i=0; i<ALargeN; i++) {
   GetNxtValOfSpin(i,&L,&R,&U,&O, &S,&N);
BF[i]=0.5*(1+tanh((L+R+U+O+S+N)/tt));//Costly
}</pre>
```

```
int L, R, U, O, S, N; //can be +1 or -1
double tt=0.83, BTanhLUT[14];
for (i=-6;i<=6;i++)
         BTanhLUT[i+6]=0.5*(1+tanh(i/tt));
for (i=0; i<ALargeN; i++) {
    GetNxtValOfSpin(i,&L,&R,&U,&O, &S,&N);
    BF[i]=BTanhLUT[L+R+U+O+S+N+6]; //Cheaper
}</pre>
```

### **CSO:** Shrink the working set

- Working set of a memory is amount of memory it uses
- Use less memory, it may fit into cache, less misses
- Example Histogram Equalization of X-ray Image (generally a 8-bit/pixel Gray image)

```
// Large M, N
unsigned int Image[M][N];

// Large M, N
unsigned char Image[M][N];
```

#### Simple measures, large impact

- Elimination of Common Sub-expressions
- Avoid Branches:
  - Code Can be SIMdized by compiler/gcc
  - Effective use of pipeline for loop code
- Use of SIMD Instruction sets
  - 512 bit AVX SIMD in modern processor
  - ML/Al app use 8 bit Ops, can be speed up
     512/8=64 time by simply SIMD-AVX

### Elimination of Common Subexpressions

```
//value of s, r, x don't change in this loop
for (i=0; i<ALargeN; i++) {
    A[i]=A[i]+s+r+sinx(x);
}</pre>
```

```
//value of s, r, x don't change in this loop
Tmp=s+r+sinx(x);
for (i=0; i<ALargeN; i++) {
    A[i]=A[i]+Tmp;
}</pre>
```

#### **Avoid Branches**

```
for (i=0; i<N; i++)
  for(j=0; j<N; j++) {
    if(i<j) S=1; else S=-1;
    C[i] =C[i]+S*A[i][j]*B[i];
}</pre>
```

```
for (i=0; i<N; i++)
    for(j=i; j<N; j++)
        C[i] =C[i] +A[i][j]*B[i];
for (i=0; i<N; i++)
    for(j=0; j<i; j++)
        C[i] =C[i] -A[i][j]*B[i];</pre>
```

```
for (i=0; i<ALargeN; i++){
    A[i]=A[i]+B[i]*D[i];
}
All iterations in this loop are
independent : gcc SIMD utilize very
nicely
//ML application uses 8 bit OPS, 512
bit AVX SIMD 512/8=64 OPS can be done
in parallel.</pre>
```

The ith iteration access: A[i], B[i], D[i]

```
for (i=0; i<N; i++) {
    A[i]=A[i]+B[i]; //S1
    B[i+1]=C[i]+D[i]; //S2
}</pre>
```

The ith iteration access: A[i], B[i], B[i+1], C[i] D[i]

Dependent loop iteration: i and i+1

```
A[0]=A[0]+B[0];
for (i=0; i<N; i++) {
    B[i+1]=C[i]+D[i]; //S2
    A[i+1]=A[i+1]+B[i+1];//S1
}
B[N]=C[N-1]+D[N-1];</pre>
```

The ith iteration access: A[i+1], B[i+1], C[i], D[i]

```
for (i=0; i<N; i++) {
    A[i]=A[i]+B[i]; //S1
    B[i+1]=C[i]+D[i]; //S2
}</pre>
```



```
A[0]=A[0]+B[0];
for (i=0; i<N; i++) {
    B[i+1]=C[i]+D[i]; //S2
    A[i+1]=A[i+1]+B[i+1];//S1
}
B[N]=C[N-1]+D[N-1];</pre>
```

Affine access: index a.x+b form

```
for (i=0; i<N; i++) {
    X[a*i+b]=X[c*i+d];
    //where a,b,c,d are integer
}</pre>
```

 GCD(c,a) divides (d-b) for loop dependence

#### **GCD** test Example

```
for (i=0; i<N; i++) {
    X[2*i+3]=X[2*i]+5.0;
    //X[a*i+b]=X[c*i+d];
}</pre>
```

- GCD(c,a) must divides (d-b) for loop dependence
- Value of a=2, b=3, c=2, d=0;
- GCD(a,c)=2, d-b=-3
- 2 does not divide -3 → No dependence Possible

### **Role of Compilers**

- General Compiler Optimization Options
- Inlining
- Aliasing
- Computational Accuracy

# General Compiler Optimization Options

- GCC optimization: -00, -01, -02,-03
- \$man gcc
- At –00 level:
  - Compiler refrain from most of the opt.
  - It is correct choice for analyzing the code with debugger
- At high level
  - Mixed up source lines, eliminate redundant variable, rearrange arithmetic expressions
  - Debugger has a hard tome to give user a consistent view on code and data

# General Compiler Optimization Options

#### Level 1

 fauto-inc-dec, -fmove-loop-invarient, -fmergeconstants, -ftree-copy-prop, -finline-fun-called-once

#### Level 2

 - falign-functions, -falign-loops, level, -finlining-smallfun, -finling-indirect-fun, -freorder-fun, -fstrictaliasing

#### Level 3

- -ftree-slp-vectorize, -fvect-cost-model

### **Inlining**

- Inlining
  - Tries to save overhead by inserting the complete code of function
  - At the place where it called
- Saves time and resources by
  - not using function call, stack
  - All complier to use registers
  - Allows compiler to views a larger portion of code and employ OPTimization
- Auto inline or hint in program to function to be inlined

#### **Aliasing**

- Assuming a and b don't overlap
  - double \_\_\_restrict \*a, double \_\_\_restrict \*b
  - restrict say no overlap
- Load and stores in the loop can be rearranged by compiler
- Apply software-pipeling, unrollling, group load/store, SIMD, etc

### **Computational Accuracy**

- Compiler some time refrain from rearranging arithmetic expression
- FP domain associative rule a+(b+c)≠(a+b)+c
- If accuracy need to be maintained
  - Compared to non optimized code
  - Associative rules must not be used by compiler
  - Should be left to programmer to regroup safely
- FP underflow are push to zero

#### **Computational Accuracy**

FP domain associative rule a+(b+c)≠(a+b)+c

-Let 
$$a=1.0x10^{38}$$
,  $b=-1.0x10^{38}$ ,  $c=1$ 

-Result of a+(b+c)

$$= 1.0 \times 10^{38} + (-1.0 \times 10^{38} + 1)$$

$$=1.0x10^{38} + (-1.0x10^{38}) = 0 //Big+Small=Big$$

-Result of (a+b)+c

$$= (1.0 \times 10^{38} + -1.0 \times 10^{38}) + 1$$

$$=0+1 = 1$$

#### **Computational Accuracy**

- Why it happened for FP
  - FP format use 32 bit represent number up to  $\pm 2^{127}$ 
    - Int use 32 bit represent up to  $\pm 2^{31}$
  - Used same 32 bit for large numbers, numbers are not equal-spaced
  - From 36000ft, both IITG and Amingoan are not distinguishable [Resolution:]
  - Going by Air: Delhi, Noida, Gurgaon use the same Airport

#### **C++ Optimizations**

- Temporaries
- Dynamic Memory Management
- Loop Kernel and Iterators

#### C++ Opt: Temporaries

C++: operator overloading uses

```
class vec3d{
       double x,y,z;
public: vec3d( double _x=0.0, _y=0.0, _z=0.0):x(_x),y(-y),z(_z){}
       vec3d operator+(const vect3d &oth){
              vec3d tmp; tmp.x=x+oth.x; ...for y, and z
              return tmp
       vec3d operator*(double s, const vec3d &v){
       vec3d tmp(s*v.x, s*v.y,s*v.z); return tmp;}
main() {
       vec3d a, b(2,2), c(3); double u=1.0,v=2.0;
       a=u*b + v*c;
```

#### C++ Opt: Temporaries

- C++: operator overloading uses
- In this prev statements
  - Constructor get called for a,b,c
  - Operator\*, constructor for tmp, destructor for tmp
  - Operator\*, constructor for tmp, destructor for tmp
  - Operator+, constructor for tmp, destructor for tmp
  - Copy constrtor called with tmp
- Simply we could have write
  - a.x=u\*b.x+v\*c.x; a.y=u\*b.y+v\*c.y; a.z=u\*b.z+v\*c.z;

# C++ Opt: Dynamic Memory Management

```
void func(double Th, int Len) {
  vector<double> v(Len);
  if(rand()>Th*RAND_MAX) {
    v=obtain_data(Len);
    sort(v.begin(),v.end());
    process_data(v);
  }
}
```

This creation is Costly

# C++ Opt: Dynamic Memory Management

```
void func(double Th, int Len) {
  if(rand()>Th*RAND_MAX) {
    vector<double> v(Len);
    v=obtain_data(Len);
    sort(v.begin(), v.end());
    process_data(v);
  }
}
This creation is
  Costly, so make it
  Lazy
}
```

- Lazy construction: if the probability of requirement is low
  - Post pone the construction if the condition become true

# C++ Opt: Dynamic Memory Management

```
void func(double Th, int Len) {
  static vector<double> v(LargeLen);
  if(rand()>Th*RAND_MAX) {
    v=obtain_data(Len);
    sort(v.begin(),v.end());
    process_data(v);
  }
}
One time
construction for
all calls
```

- Static Construction: if the probability of requirement is high or always required
  - one time Construction: for all call/invocation
  - Take sufficient largeLen

#### C++ Opt: Loop Kernel and Iterators

- Runtime of scientific application dominated by loops or loops nest
- Compiler ability to optimize loops is pivotal for getting performance
- Operator overloading and template may hinders good loop optimization

#### C++ Opt: Loop Kernel and Iterators

 Non-SIMDized code: operator[] called twice for a and b, compiler refuse to SIMDize

```
template<class T>
T Sprod(cosnt vector<T> &A,
        const vector<T> &B) {
    T result=T(0);
    int s=A.size();
    for (int i=0;i<s;i++)</pre>
         result += A[i]*B[i]; //Access
    return result;
```

#### C++ Opt: Loop Kernel and Iterators

SIMDized

```
template<class T>
T Sprod(cosnt vector<T> &A,
        const vector<T> &B) {
vector<T>::const_iterator
        iA=A.begin(), iB=B.begin();
    T result=T(0);
    int s=A.size();
    for (int i=0; i < s; i++)</pre>
        result += iA[i]*iB[i];//Access
    return result;
```

### **Data Access Optimization**

# Performance of System: Modeling Customer Dispatch in a Bank

Resolving door
Throughput:
b<sub>s</sub>[customer/sec]















Processing
Capabilty:
P<sub>peak</sub> [task/sec]



Intensity:

I [task/customer]



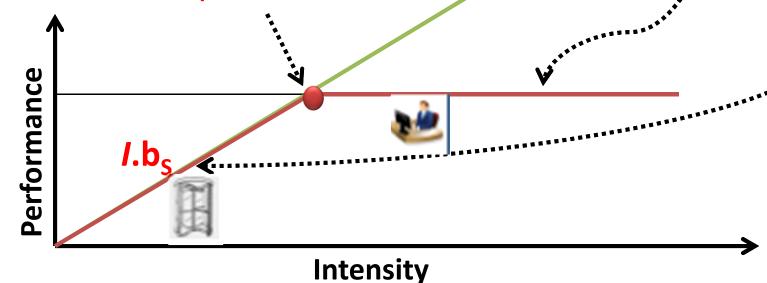


#### **Modeling Customer Dispatch in a Bank**

- How fast can tasks be processed? P[tasks/sec]
- The bottleneck is either
  - The service desks (peak. tasks/sec):  $P_{peak}$
  - The revolving door (max. customers/sec):  $I \cdot b_S$
- Performance  $P=\min(P_{peak}, I \cdot b_S)$
- This is the "Roofline Model"
  - High intensity: P limited by "execution"
  - Low intensity: P limited by "bottleneck"

#### **Modeling Customer Dispatch in a Bank**

- Performance =min( peak, · )
- This is the "Roofline Model"
  - High intensity: P limited by "execution"
  - Low intensity: P limited by "bottleneck" .....
  - "Knee" at peak : Best use of resources



Roofline is an "optimistic" model

#### The Roofline Model

- $P_{\text{max}}$ = Peak performance of the machine
- *I*= Computational intensity ("work" per byte transferred) over the slowest data path utilized ("the bottleneck")
- b<sub>s</sub>= Applicable peak bandwidth of the slowest data path utilized

Expected performance:

$$P = \min(P_{\text{peak'}})$$

[F/B] [B/s] 
$$I \cdot b_S$$

#### **Apply Roof line to Machine and Code**

- Machine Parameter 1 : P<sub>peak</sub> [F/s]=4 G F/S
- Machine Parameter 2 : b<sub>s</sub> [B/s] =10 G B/s
- Application Properties: I [F/B] = 2F/8B=0.25F/B for(i=0;i<N;i++) s=s+a[i]\*a[i]; // double s, a[]</li>
- Performance = P = min(P<sub>peak</sub>, I\*b<sub>s</sub>)
   =min(4 GF/s, 0.25 F/B \*10 G.B/s)
   =min(4 GF/s, 2.5 GF/s)
   =2.5 G F/s