

Differential Equations Final Exam Solutions

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Differential Equations Final Exam Answer Key

1. (5 pts)

Α

В

С

2. (5 pts)

Α

В

D

E

E

3. (5 pts)

В

С

D

Е

4. (5 pts)

Α

В

С

Е

5. (5 pts)

Α

В

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Ε

6. (5 pts)

Α

В

D

E

7. (5 pts)

Α

В

С

D

Е

8. (5 pts)

Α





С



9. (15 pts)
$$\overrightarrow{x} = c_1 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} e^{-t} + c_2 \begin{bmatrix} 2\sin(2t) \\ \cos(2t) \\ 0 \end{bmatrix} + c_3 \begin{bmatrix} -2\cos(2t) \\ \sin(2t) \\ 0 \end{bmatrix}$$

$$+ \begin{bmatrix} 4e^t + 1 \\ e^t - t \\ \frac{1}{2}\sin t - \frac{1}{2}\cos t \end{bmatrix}$$

10. (15 pts)
$$y(t) = c_1 e^{-t} + c_2 + c_3 t + c_4 t^2 + c_5 e^{-3t} + c_6 t e^{-3t} + c_7 e^{-2t} \cos t + c_8 e^{-2t} \sin t + c_9 e^t \cos(\sqrt{2}t) + c_{10} e^t \sin(\sqrt{2}t)$$

$$+c_{11}te^{t}\cos(\sqrt{2}t) + c_{12}te^{t}\sin(\sqrt{2}t) + c_{13}t^{2}e^{t}\cos(\sqrt{2}t) + c_{14}t^{2}e^{t}\sin(\sqrt{2}t)$$

11. (15 pts)
$$f(x) = \frac{1}{6} - \frac{1}{4\pi^2} + \left(-\frac{1}{6} + \frac{7}{16\pi^2} \right) \cos(2\pi x) + \sum_{n=1}^{\infty} \frac{(-1)^n}{\pi^2} \left(\frac{2}{n^2} + \frac{1}{(n-2)^2} + \frac{1}{(n+2)^2} \right) \cos(n\pi x)$$

12. (15 pts)
$$u(x,t) = 10 - \frac{15}{L}x + \sum_{n=1}^{\infty} \frac{10}{n\pi} (2 - 5(-1)^n) \sin\left(\frac{n\pi x}{L}\right) e^{-k\left(\frac{n\pi}{L}\right)^2 t}$$



Differential Equations Final Exam Solutions

1. D. Change y' to dy/dx,

$$3xy' = y$$

$$3x\frac{dy}{dx} = y$$

then separate variables, collecting y terms on the left and x terms on the right.

$$\frac{3}{y} dy = \frac{1}{x} dx$$

Integrate both sides,

$$\int \frac{3}{y} \, dy = \int \frac{1}{x} \, dx$$

$$3\ln|y| = \ln|x| + C$$

$$\ln|y| = \frac{1}{3}\ln|x| + C$$

then solve for y.

$$e^{\ln|y|} = e^{\frac{1}{3}\ln|x|+C}$$

$$|y| = Ce^{\frac{1}{3}\ln|x|}$$

$$|y| = Ce^{\ln|x|^{\frac{1}{3}}}$$

$$|y| = C|x|^{\frac{1}{3}}$$

$$y = C|x|^{\frac{1}{3}}$$

2. C. Divide the equation by y^2 .

$$y' + 3y = \sin(t)y^2$$

$$\frac{1}{y^2}y' + \frac{3}{y} = \sin t$$

With the Bernoulli equation in standard form, we'll find

$$v = \frac{1}{y}$$

$$v' = -\frac{1}{v^2}y'$$

and then substitute these values into the Bernoulli equation.

$$-v' + 3v = \sin t$$

$$v' - 3v = -\sin t$$

Now we have a linear equation with an integrating factor of e^{-3t} , so we'll multiply this integrating factor through the linear equation.

$$v'e^{-3t} - 3ve^{-3t} = -e^{-3t}\sin t$$

$$\frac{d}{dx}(ve^{-3t}) = -e^{-3t}\sin t$$



$$\int \frac{d}{dx} (ve^{-3t}) \ dx = \int -e^{-3t} \sin t \ dt$$

$$ve^{-3t} = \int -e^{-3t} \sin t \ dt$$

Use integration by parts with $u_1 = \sin t$, $du_1 = \cos t \ dt$, $du_2 = -e^{-3t} \ dt$, and $u_2 = (1/3)e^{-3t}$.

$$ve^{-3t} = \frac{1}{3}e^{-3t}\sin t + \frac{1}{3}\int -e^{-3t}\cos t \ dt$$

Use integration by parts again with $u_1 = \cos t$, $du_1 = -\sin t \ dt$, $du_2 = -e^{-3t} \ dt$, and $u_2 = (1/3)e^{-3t}$.

$$ve^{-3t} = \frac{1}{3}e^{-3t}\sin t + \frac{1}{9}e^{-3t}\cos t - \frac{1}{9}\int -e^{-3t}\sin t \ dt$$

$$ve^{-3t} = \frac{1}{3}e^{-3t}\sin t + \frac{1}{9}e^{-3t}\cos t - \frac{1}{9}ve^{-3t} + C$$

$$\frac{10}{9}ve^{-3t} = \frac{1}{3}e^{-3t}\sin t + \frac{1}{9}e^{-3t}\cos t + C$$

$$10ve^{-3t} = 3e^{-3t}\sin t + e^{-3t}\cos t + C$$

$$ve^{-3t} = \frac{(3\sin t + \cos t + Ce^{3t})e^{-3t}}{10}$$

$$v = \frac{3\sin t + \cos t + Ce^{3t}}{10}$$

Use v = 1/y to back-substitute for v, then solve for y.

$$\frac{1}{y} = \frac{3\sin t + \cos t + Ce^{3t}}{10}$$

$$y = \frac{10}{3\sin t + \cos t + Ce^{3t}}$$

Substitute the initial condition y(0) = 1.

$$1 = \frac{10}{0 + 1 + C}$$

$$10 = 1 + C$$

$$9 = C$$

Then the solution to the Bernoulli equation initial value problem is

$$y = \frac{10}{3\sin t + \cos t + 9e^{3t}}$$

3. A. We'll use undetermined coefficients and set g(x) = 0 to find the associated homogeneous equation,

$$y'' + 4y' + 4y = 2e^{-2x} + 8x$$

$$y'' + 4y' + 4y = 0$$

then solve its associated characteristic equation.

$$r^2 + 4r + 4 = 0$$

$$(r+2)(r+2) = 0$$



$$r = -2, -2$$

These are equal real roots, so the complementary solution will be

$$y_c(x) = c_1 e^{r_1 x} + c_2 x e^{r_1 x}$$

$$y_c(x) = c_1 e^{-2x} + c_2 x e^{-2x}$$

Our guess for the particular solution will be

$$y_p(x) = Ae^{-2x} + Bx + C$$

The Ae^{-2x} term overlaps with the c_1e^{-2x} term from the complementary solution. If we multiply the term from our guess by x to eliminate the overlap, the new Axe^{-2x} term now overlaps with the other term from the complementary solution, c_2xe^{-2x} . So we'll multiply it by x again, and our guess will be

$$y_p(x) = Ax^2e^{-2x} + Bx + C$$

Take the first and second derivatives of the guess.

$$y_p'(x) = 2Axe^{-2x} - 2Ax^2e^{-2x} + B$$

$$y_p''(x) = 2Ae^{-2x} - 8Axe^{-2x} + 4Ax^2e^{-2x}$$

Plugging into the original differential equation, we get

$$y'' + 4y' + 4y = 2e^{-2x} + 8x$$

$$2Ae^{-2x} - 8Axe^{-2x} + 4Ax^2e^{-2x} + 8Axe^{-2x} - 8Ax^2e^{-2x} + 4B$$

$$+4Ax^2e^{-2x} + 4Bx + 4C = 2e^{-2x} + 8x$$

$$2Ae^{-2x} + 4B + 4Bx + 4C = 2e^{-2x} + 8x$$

Equating coefficients gives 2A = 2, 4B = 8, and 4B + 4C = 0, and we can solve that system of equations to find A = 1, B = 2, and C = -2. So the particular solution is

$$y_p(x) = Ax^2e^{-2x} + Bx + C$$

$$y_p(x) = x^2 e^{-2x} + 2x - 2$$

Putting this particular solution together with the complementary solution gives us the general solution to the nonhomogeneous differential equation.

$$y(x) = y_c(x) + y_p(x)$$

$$y(x) = c_1 e^{-2x} + c_2 x e^{-2x} + x^2 e^{-2x} + 2x - 2$$

4. D. Approximating $y(\pi)$ from y(0) = 0 using n = 4 steps gives us a step size of

$$\Delta t = \frac{\pi - 0}{4} = \frac{\pi}{4}$$

With $t_0 = 0$, $y_0 = 0$, and $\Delta t = \pi/4$, our table is

$$t_0 = 0 y_0 = 0$$

$$y_0 = 0$$

$$t_1 = \frac{\pi}{4}$$
 $y_1 = 0 + \left(\frac{\pi}{4}\right)(4\sin(0) + 2)$

$$y_1 = \frac{\pi}{2}$$

$$t_2 = \frac{\pi}{2}$$
 $y_2 = \frac{\pi}{2} + \left(\frac{\pi}{4}\right) \left(4\sin\left(\frac{\pi}{2}\right) + 2\right)$ $y_2 = 2\pi$

$$t_3 = \frac{3\pi}{4}$$
 $y_3 = 2\pi + \left(\frac{\pi}{4}\right) \left(4\sin(2\pi) + 2\right)$ $y_3 = \frac{5\pi}{2}$

$$t_4 = \pi$$
 $y_4 = \frac{5\pi}{2} + \left(\frac{\pi}{4}\right) \left(4\sin\left(\frac{5\pi}{2}\right) + 2\right)$ $y_4 = 4\pi$

After filling out the table, we can say that the value of $y(\pi)$ is approximately

$$y(\pi) \approx 4\pi$$

5. D. The autonomous differential equation has equilibrium solutions at

$$12 - 4y - y^2 = 0$$

$$-(y+6)(y-2) = 0$$

$$y = -6, 2$$

Given these two equilibrium solutions, we'll consider three intervals:

$$y < -6$$

$$-6 < y < 2$$

We'll choose a test value in each interval (y = -10 for the first interval, y = 0 for the second interval, and y = 3 for the third interval), then plug each test value into the equation $f(y) = 12 - 4y - y^2$.

$$f(-10) = 12 - 4(-10) - (-10)^2 = 12 + 40 - 100 = -48 < 0$$

$$f(0) = 12 - 4(0) - 0^2 = 12 > 0$$

$$f(3) = 12 - 4(3) - 3^2 = 12 - 12 - 9 = -9 < 0$$

The signs of these results tell us that solution curves are increasing in the intervals -6 < y < 2, and decreasing in the intervals y < -6 and 2 < y.

Interval	Sign of $f(y)$	Direction of $f(y)$
$(2,\infty)$	_	Decreasing/Falling
(-6,2)	+	Increasing/Rising
$(-\infty, -6)$.	Decreasing/Falling

Therefore, the equation has a stable equilibrium solution at y = 2, and an unstable equilibrium solution at y = -6.

6. C. To start, we'll substitute y and y' into the differential equation.

$$y' + y = e^x$$

$$\sum_{n=1}^{\infty} c_n n x^{n-1} + \sum_{n=0}^{\infty} c_n x^n = \sum_{n=0}^{\infty} \frac{1}{n!} x^n$$



The series are in phase, so we'll just make the indices match.

$$\sum_{k=0}^{\infty} c_{k+1}(k+1)x^k + \sum_{k=0}^{\infty} c_k x^k = \sum_{k=0}^{\infty} \frac{1}{k!} x^k$$

$$\sum_{k=0}^{\infty} \left[c_{k+1}(k+1) + c_k \right] x^k = \sum_{k=0}^{\infty} \frac{1}{k!} x^k$$

Rewrite the recurrence relation.

$$c_{k+1}(k+1) + c_k = \frac{1}{k!}$$

$$k = 0, 1, 2, 3, \dots$$

$$c_{k+1} = \frac{1}{(k+1)!} - \frac{c_k}{k+1}$$

Now we'll start plugging in values $k = 0, 1, 2, 3, \ldots$

$$k = 0 c_1 = \frac{1}{1!} (1 - c_0)$$

$$k = 1$$

$$k = 1$$
 $c_2 = \frac{1}{2!}c_0$

$$k = 2$$
 $c_3 = \frac{1}{3!}(1 - c_0)$

$$c_3 = \frac{1}{3!}(1 - c_0)$$

$$k = 3$$

$$k = 3 c_4 = \frac{1}{4!}c_0$$

$$k = 4$$

$$k = 4 c_5 = \frac{1}{5!} (1 - c_0)$$

$$k = 5$$

$$k = 5$$
 $c_6 = \frac{1}{6!}c_0$

$$c_k = \frac{1}{k!}(1 - c_0)$$

$$c_k = \frac{1}{k!}c_0$$

Using these values, the solution is

$$y = c_0 + c_1 x + c_2 x^2 + c_3 x^3 + c_4 x^4 + c_5 x^5 + c_6 x^6 + \dots$$

$$y = c_0 + \frac{1}{1!}(1 - c_0)x + \frac{1}{2!}c_0x^2 + \frac{1}{3!}(1 - c_0)x^3$$

$$+ \frac{1}{4!}c_0x^4 + \frac{1}{5!}(1 - c_0)x^5 + \frac{1}{6!}c_0x^6 + \dots$$

$$y = c_0 + \frac{1}{1!}x - \frac{1}{1!}c_0x + \frac{1}{2!}c_0x^2 + \frac{1}{3!}x^3 - \frac{1}{3!}c_0x^3$$

$$+ \frac{1}{4!}c_0x^4 + \frac{1}{5!}x^5 - \frac{1}{5!}c_0x^5 + \frac{1}{6!}c_0x^6 + \dots$$

$$y = c_0 - \frac{1}{1!}c_0x + \frac{1}{2!}c_0x^2 - \frac{1}{3!}c_0x^3 + \frac{1}{4!}c_0x^4 - \frac{1}{5!}c_0x^5 + \frac{1}{6!}c_0x^6$$

$$+ \frac{1}{1!}x + \frac{1}{3!}x^3 + \frac{1}{5!}x^5 + \dots$$

$$y = c_0 \left(\frac{1}{0!}x^0 - \frac{1}{1!}x^1 + \frac{1}{2!}x^2 - \frac{1}{3!}x^3 + \frac{1}{4!}x^4 - \frac{1}{5!}x^5 + \frac{1}{6!}x^6 - \dots \right)$$

$$+ x \left(\frac{1}{1!}x^0 + \frac{1}{3!}x^2 + \frac{1}{5!}x^4 + \dots \right)$$

And the pattern that seems to be emerging is

$$y = c_0 \sum_{k=0}^{\infty} \frac{(-x)^k}{k!} + x \sum_{k=1}^{\infty} \frac{1}{k!} x^{k-1}$$

$$y = c_0 \sum_{k=0}^{\infty} \frac{(-x)^k}{k!} + \sum_{k=1}^{\infty} \frac{x^k}{k!}$$

$$y = c_0 + c_0 \sum_{k=1}^{\infty} \frac{(-1)^k x^k}{k!} + \sum_{k=1}^{\infty} \frac{x^k}{k!}$$



$$y = c_0 + c_0 \sum_{k=1}^{\infty} \frac{x^k + (-1)^k x^k}{k!}$$

$$y = c_0 + c_0 \sum_{k=1}^{\infty} \frac{x^k (1 + (-1)^k)}{k!}$$

7. E. Apply the Laplace transform to both sides of the differential equation.

$$y'' - 5y' + 6y = 4xe^x$$

$$s^{2}Y(s) - sy(0) - y'(0) - 5[sY(s) - y(0)] + 6Y(s) = 4\left(\frac{1}{(s-1)^{2}}\right)$$

Plug in the initial conditions y(0) = 1 and y'(0) = 0.

$$s^{2}Y(s) - 5sY(s) + 6Y(s) = \frac{4}{(s-1)^{2}} + s - 5$$

$$(s^2 - 5s + 6)Y(s) = \frac{4 + s(s-1)^2 - 5(s-1)^2}{(s-1)^2}$$

$$Y(s) = \frac{4 + s(s-1)^2 - 5(s-1)^2}{(s-1)^2(s^2 - 5s + 6)}$$

$$Y(s) = \frac{s^3 - 7s^2 + 11s - 1}{(s - 1)^2(s - 2)(s - 3)}$$

Use a partial fractions decomposition.

$$\frac{s^3 - 7s^2 + 11s - 1}{(s - 1)^2(s - 2)(s - 3)} = \frac{A}{s - 1} + \frac{B}{(s - 1)^2} + \frac{C}{s - 2} + \frac{D}{s - 3}$$

If we multiply both sides by s-2 and then set s=2, we get

$$\frac{2^3 - 7(2)^2 + 11(2) - 1}{(1)^2(-1)} = A(0) + B(0) + C + D(0)$$

$$C = -1$$

If we multiply both sides by s-3 and then set s=3, we get

$$\frac{3^3 - 7(3)^2 + 11(3) - 1}{4 \cdot 1} = A(0) + B(0) + C(0) + D$$

$$D = -1$$

If we multiply both sides by $(s-1)^2$ and then set s=1, we get

$$\frac{1^3 - 7(1)^2 + 11(1) - 1}{(-1)(-2)} = B$$

$$B=2$$

We've set $s=1,\,2,\,3$, so we'll choose a different value and set s=0 to get

$$\frac{-1}{(-1)^2(-2)(-3)} = -\frac{A}{1} + \frac{2}{1} + \frac{1}{2} + \frac{1}{3}$$

$$A = 3$$

Plugging these into the decomposition gives

$$Y(s) = \frac{3}{s-1} + \frac{2}{(s-1)^2} - \frac{1}{s-2} - \frac{1}{s-3}$$

Applying an inverse transform gives us the solution to the second order nonhomogeneous differential equation.

$$y(x) = 3e^x + 2xe^x - e^{2x} - e^{3x}$$

8. B. From a table of Laplace transforms, we know

$$\mathcal{L}(y'') = s^2 Y(s) - sy(0) - y'(0)$$

$$\mathcal{L}(y') = sY(s) - y(0)$$

$$\mathcal{L}(y) = Y(s)$$

$$\mathcal{L}(g(t)) = G(s)$$

Substitute these into the differential equation.

$$y'' + 4y' + 13y = g(t)$$

$$s^{2}Y(s) - sy(0) - y'(0) + 4(sY(s) - y(0)) + 13Y(s) = G(s)$$

$$s^{2}Y(s) - sy(0) - y'(0) + 4sY(s) - 4y(0) + 13Y(s) = G(s)$$

Plug in the initial conditions y(0) = 0 and y'(0) = 0.

$$s^{2}Y(s) + 4sY(s) + 13Y(s) = G(s)$$

$$(s^2 + 4s + 13)Y(s) = G(s)$$

$$Y(s) = \frac{G(s)}{s^2 + 4s + 13}$$

Complete the square.

$$Y(s) = \frac{G(s)}{(s+2)^2 + 9}$$

$$Y(s) = \frac{1}{3}G(s)\left(\frac{3}{(s - (-2))^2 + 3^2}\right)$$

This is similar to the transform formula

$$\mathcal{L}(e^{at}\sin(bt)) = \frac{b}{(s-a)^2 + b^2}$$

Now we can identify a = -2 and b = 3. So the inverse transform is

$$\mathcal{L}^{-1}\left(\frac{3}{(s-(-2))^2+3^2}\right) = e^{-2t}\sin(3t)$$

The inverse transform of G(s) is g(t), so for the convolution integral we'll use the functions

$$f(t) = e^{-2t} \sin(3t)$$

$$g(t) = g(t)$$

Plugging these into the convolution integral, we get

$$f(t) * g(t) = \int_0^t f(\tau)g(t - \tau) d\tau$$



$$f(t) * g(t) = \int_0^t e^{-2\tau} \sin(3\tau)g(t - \tau) d\tau$$

Plugging all of these values back into the equation for Y(s) gives us the inverse transform, which is the general solution to the second order differential equation initial value problem.

$$y(t) = \frac{1}{3} \int_0^t e^{-2\tau} \sin(3\tau) g(t - \tau) d\tau$$

9. Start by working on the complementary solution. Find $|A - \lambda I|$.

$$\begin{vmatrix} -\lambda & 4 & 0 \\ -1 & -\lambda & 0 \\ 0 & 0 & -1 - \lambda \end{vmatrix}$$

$$(-1-\lambda)\begin{vmatrix} -\lambda & 4\\ -1 & -\lambda \end{vmatrix}$$

$$(-1 - \lambda)[(-\lambda)(-\lambda) - (4)(-1)]$$

$$(-1-\lambda)(\lambda^2+4)$$

Solve the characteristic equation.

$$(-1 - \lambda)(\lambda^2 + 4) = 0$$

$$(\lambda + 1)(\lambda^2 + 4) = 0$$

Then for these Eigenvalues, $\lambda_1 = -1$ and $\lambda_2 = \lambda_3 = \pm 2i$, we find

$$A - (-1)I = \begin{bmatrix} 1 & 4 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$A - (2i)I = \begin{bmatrix} -2i & 4 & 0 \\ -1 & -2i & 0 \\ 0 & 0 & -1 - 2i \end{bmatrix}$$

Put these matrices in reduced row-echelon form.

$$\begin{bmatrix} 1 & 4 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} -2i & 4 & 0 \\ -1 & -2i & 0 \\ 0 & 0 & -1 - 2i \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2i & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

If we turn these back into systems of equations, we get

$$k_1 = 0$$

$$k_1 + 2ik_2 = 0$$

$$k_2 = 0$$

$$k_3 = 0$$

For the first system, we can choose $k_3 = 1$. For the second system, we can choose $k_2 = 1$, so $k_1 = -2i$. For the third system, we can choose $k_2 = 1$.

$$\vec{k_1} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\vec{k_2} = \begin{bmatrix} -2i \\ 1 \\ 0 \end{bmatrix}$$

Then the solutions to the system are

$$\overrightarrow{x_1} = \overrightarrow{k_1} e^{\lambda_1 t}$$

$$\overrightarrow{x_2} = \overrightarrow{k_2} e^{\lambda_2 t}$$

$$\overrightarrow{x_1} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} e^{-t}$$

$$\overrightarrow{x_2} = \begin{bmatrix} -2i \\ 1 \\ 0 \end{bmatrix} e^{2it}$$

Write the imaginary solution vector as separate real and imaginary parts.

$$\overrightarrow{k_2} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + i \begin{bmatrix} -2 \\ 0 \\ 0 \end{bmatrix}$$

The vectors $\overrightarrow{b_1} = \text{Re}(\overrightarrow{k})$ and $\overrightarrow{b_2} = \text{Im}(\overrightarrow{k})$ are

$$\overrightarrow{b_1} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$\overrightarrow{b_2} = \begin{bmatrix} -2\\0\\0 \end{bmatrix}$$

Therefore, the complementary solution will be

$$\overrightarrow{x_c} = c_1 \overrightarrow{x_1} + c_2 \overrightarrow{x_2} + c_3 \overrightarrow{x_3}$$

$$\overrightarrow{x_c} = c_1 \overrightarrow{x_1} + c_2 [\overrightarrow{b_1} \cos(\beta t) - \overrightarrow{b_2} \sin(\beta t)] e^{\alpha t}$$

$$+c_3[\overrightarrow{b_2}\cos(\beta t) + \overrightarrow{b_1}\sin(\beta t)]e^{\alpha t}$$

$$\overrightarrow{x_c} = c_1 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} e^{-t} + c_2 \begin{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \cos(2t) - \begin{bmatrix} -2 \\ 0 \\ 0 \end{bmatrix} \sin(2t) \end{bmatrix} e^{0t}$$

$$+c_3\begin{bmatrix} -2\\0\\0\end{bmatrix}\cos(2t) + \begin{bmatrix} 0\\1\\0\end{bmatrix}\sin(2t) e^{0t}$$



$$\vec{x_c} = c_1 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} e^{-t} + c_2 \begin{bmatrix} 2\sin(2t) \\ \cos(2t) \\ 0 \end{bmatrix} + c_3 \begin{bmatrix} -2\cos(2t) \\ \sin(2t) \\ 0 \end{bmatrix}$$

Now solve for the particular solution. Rewrite the forcing function vector as

$$\vec{F} = \begin{bmatrix} 4t \\ 5e^t \\ \sin t \end{bmatrix}$$

$$F = \begin{bmatrix} 4 \\ 0 \\ 0 \end{bmatrix} t + \begin{bmatrix} 0 \\ 5 \\ 0 \end{bmatrix} e^t + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \sin t$$

The guess for the particular solution can be

$$\overrightarrow{x_p} = \begin{bmatrix} e_1 \\ e_2 \\ e_3 \end{bmatrix} \sin t + \begin{bmatrix} d_1 \\ d_2 \\ d_3 \end{bmatrix} \cos t + \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} e^t + \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} t + \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix}$$

We'll break the guess into three pieces, one each for the polynomial, exponential, and trigonometric parts of the solution.

$$\overrightarrow{x_p} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} t + \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix}$$

$$\overrightarrow{x_p} = \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} e^t$$



$$\overrightarrow{x_p} = \begin{bmatrix} e_1 \\ e_2 \\ e_3 \end{bmatrix} \sin t + \begin{bmatrix} d_1 \\ d_2 \\ d_3 \end{bmatrix} \cos t$$

Starting with the polynomial part, we get

$$\overrightarrow{x_p}' = A\overrightarrow{x_p} + F$$

$$\begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \begin{bmatrix} 0 & 4 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} t + \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} \end{bmatrix} + \begin{bmatrix} 4 \\ 0 \\ 0 \end{bmatrix} t$$

$$\begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \begin{bmatrix} 0 & 4 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} b_1 t + a_1 \\ b_2 t + a_2 \\ b_3 t + a_3 \end{bmatrix} + \begin{bmatrix} 4 \\ 0 \\ 0 \end{bmatrix} t$$

This matrix equation can be rewritten as a system of equations.

$$b_1 = 0(b_1t + a_1) + 4(b_2t + a_2) + 0(b_3t + a_3) + 4t$$

$$b_2 = -1(b_1t + a_1) + 0(b_2t + a_2) + 0(b_3t + a_3) + 0t$$

$$b_3 = 0(b_1t + a_1) + 0(b_2t + a_2) - 1(b_3t + a_3) + 0t$$

The system simplifies to

$$b_1 = 4b_2t + 4a_2 + 4t$$

$$b_2 = -b_1 t - a_1$$

$$b_3 = -b_3t - a_3$$



These equations can each be broken into its own system.

$$4b_2 + 4 = 0$$

$$-b_1 = 0$$

$$-b_3 = 0$$

$$b_1 = 4a_2$$

$$b_2 = -a_1$$

$$b_3 = -a_3$$

This system gives $\overrightarrow{a}=(a_1,a_2,a_3)=(1,0,0)$ and $\overrightarrow{b}=(b_1,b_2,b_3)=(0,-1,0)$. Now solve the exponential part of the particular solution.

$$\overrightarrow{x_p}' = A \overrightarrow{x_p} + F$$

$$\begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} e^t = \begin{bmatrix} 0 & 4 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} e^t + \begin{bmatrix} 0 \\ 5 \\ 0 \end{bmatrix} e^t$$

$$\begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 0 & 4 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} + \begin{bmatrix} 0 \\ 5 \\ 0 \end{bmatrix}$$

This matrix equation can be rewritten as a system of equations.

$$c_1 = 0c_1 + 4c_2 + 0c_3 + 0$$

$$c_2 = -1c_1 + 0c_2 + 0c_3 + 5$$

$$c_3 = 0c_1 + 0c_2 - 1c_3 + 0$$

The system simplifies to

$$c_1 = 4c_2$$

$$c_2 = -c_1 + 5$$

$$c_3 = -c_3$$

This system gives $\overrightarrow{c} = (c_1, c_2, c_3) = (4,1,0)$. Now solve the trigonometric part of the particular solution.

$$\overrightarrow{x_p}' = A\overrightarrow{x_p} + F$$

$$\begin{bmatrix} e_1 \\ e_2 \\ e_3 \end{bmatrix} \cos t - \begin{bmatrix} d_1 \\ d_2 \\ d_3 \end{bmatrix} \sin t = \begin{bmatrix} 0 & 4 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} e_1 \\ e_2 \\ e_3 \end{bmatrix} \sin t + \begin{bmatrix} d_1 \\ d_2 \\ d_3 \end{bmatrix} \cos t + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \sin t$$

$$\begin{bmatrix} e_1 \cos t - d_1 \sin t \\ e_2 \cos t - d_2 \sin t \\ e_3 \cos t - d_3 \sin t \end{bmatrix} = \begin{bmatrix} 0 & 4 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} e_1 \sin t + d_1 \cos t \\ e_2 \sin t + d_2 \cos t \\ e_3 \sin t + d_3 \cos t \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ \sin t \end{bmatrix}$$

This matrix equation can be rewritten as a system of equations.

$$e_{1}\cos t - d_{1}\sin t = 0(e_{1}\sin t + d_{1}\cos t)$$

$$+4(e_{2}\sin t + d_{2}\cos t) + 0(e_{3}\sin t + d_{3}\cos t) + 0$$

$$e_{2}\cos t - d_{2}\sin t = -1(e_{1}\sin t + d_{1}\cos t)$$

$$+0(e_{2}\sin t + d_{2}\cos t) + 0(e_{3}\sin t + d_{3}\cos t) + 0$$

$$e_{3}\cos t - d_{3}\sin t = 0(e_{1}\sin t + d_{1}\cos t)$$

$$+0(e_{2}\sin t + d_{2}\cos t) - 1(e_{3}\sin t + d_{3}\cos t) + \sin t$$

The system simplifies to

$$e_1 \cos t - d_1 \sin t = 4e_2 \sin t + 4d_2 \cos t$$

$$e_2\cos t - d_2\sin t = -e_1\sin t - d_1\cos t$$

$$e_3\cos t - d_3\sin t = -e_3\sin t - d_3\cos t + \sin t$$

These equations can each be broken into its own system.

$$e_1 = 4d_2$$
 $e_2 = -d_1$ $e_3 = -d_3$
$$-d_1 = 4e_2$$
 $-d_2 = -e_1$ $-d_3 = -e_3 + 1$

This system gives $\overrightarrow{d}=(d_1,d_2,d_3)=(0,0,-1/2)$ and $\overrightarrow{e}=(e_1,e_2,e_3)=(0,0,1/2).$ So the particular solution is

$$\overrightarrow{x_p} = \begin{bmatrix} 0\\0\\\frac{1}{2} \end{bmatrix} \sin t + \begin{bmatrix} 0\\0\\-\frac{1}{2} \end{bmatrix} \cos t + \begin{bmatrix} 4\\1\\0 \end{bmatrix} e^t + \begin{bmatrix} 0\\-1\\0 \end{bmatrix} t + \begin{bmatrix} 1\\0\\0 \end{bmatrix}$$

$$\overrightarrow{x_p} = \begin{bmatrix} 4e^t + 1 \\ e^t - t \\ \frac{1}{2}\sin t - \frac{1}{2}\cos t \end{bmatrix}$$

Summing the complementary and particular solutions gives the general solution to the nonhomogeneous system of differential equations.

$$\overrightarrow{x} = \overrightarrow{x_c} + \overrightarrow{x_p}$$

$$\vec{x} = c_1 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} e^{-t} + c_2 \begin{bmatrix} 2\sin(2t) \\ \cos(2t) \\ 0 \end{bmatrix} + c_3 \begin{bmatrix} -2\cos(2t) \\ \sin(2t) \\ 0 \end{bmatrix} + \begin{bmatrix} 4e^t + 1 \\ e^t - t \\ \frac{1}{2}\sin t - \frac{1}{2}\cos t \end{bmatrix}$$



10. If the characteristic equation associated with the homogeneous differential equation is

$$r^{3}(r+1)(r+3)^{2}(r^{2}+4r+5)(r^{2}-2r+3)^{3}=0$$

then we know the equation has

Distinct real roots
$$r_1 = -1$$

Equal real roots
$$r_2 = r_3 = r_4 = 0$$

$$r_5 = r_6 = -3$$

Complex roots
$$r_7 = r_8 = -2 \pm i$$

$$r_9 = r_{10} = 1 \pm \sqrt{2}i$$

$$r_{11} = r_{12} = 1 \pm \sqrt{2}i$$

$$r_{13} = r_{14} = 1 \pm \sqrt{2}i$$

For the complex roots $r_7 = r_8 = -2 \pm i$ associated with $(r^2 + 4r + 5)$, we know $\alpha = -2$ and $\beta = 1$, so the complex conjugate solution pairs will be

$$e^{-2t}\cos t$$
 and $e^{-2t}\sin t$

The complex roots associated with $(r^2 - 2r + 3)^3$ have multiplicity three, which means we'll have three pairs of complex roots,

$$e^{\alpha t}\cos(\beta t)$$
 and $e^{\alpha t}\sin(\beta t)$

$$te^{\alpha t}\cos(\beta t)$$
 and $te^{\alpha t}\sin(\beta t)$

$$t^2 e^{\alpha t} \cos(\beta t)$$
 and $t^2 e^{\alpha t} \sin(\beta t)$

With $\alpha = 1$ and $\beta = \sqrt{2}$, the complex conjugate solution pairs will be

$$e^t \cos(\sqrt{2}t)$$
 and $e^t \sin(\sqrt{2}t)$

$$te^t \cos(\sqrt{2}t)$$
 and $te^t \sin(\sqrt{2}t)$

$$t^2 e^t \cos(\sqrt{2}t)$$
 and $t^2 e^t \sin(\sqrt{2}t)$

The distinct real roots portion of the solution will be c_1e^{-t} , and the equal real roots portion will be $c_2e^{0t}+c_3te^{0t}+c_4t^2e^{0t}$, or $c_2+c_3t+c_4t^2$, and $c_5e^{-3t}+c_6te^{-3t}$. The complex conjugate roots portion will be

$$c_{7}e^{-2t}\cos t + c_{8}e^{-2t}\sin t$$

$$+c_{9}e^{t}\cos(\sqrt{2}t) + c_{10}e^{t}\sin(\sqrt{2}t)$$

$$+c_{11}te^{t}\cos(\sqrt{2}t) + c_{12}te^{t}\sin(\sqrt{2}t)$$

$$+c_{13}t^{2}e^{t}\cos(\sqrt{2}t) + c_{14}t^{2}e^{t}\sin(\sqrt{2}t)$$

Therefore the general solution of the homogeneous linear differential equation is

$$y(t) = c_1 e^{-t} + c_2 + c_3 t + c_4 t^2 + c_5 e^{-3t} + c_6 t e^{-3t} + c_7 e^{-2t} \cos t + c_8 e^{-2t} \sin t$$

$$+ c_9 e^t \cos(\sqrt{2}t) + c_{10} e^t \sin(\sqrt{2}t)$$

$$+ c_{11} t e^t \cos(\sqrt{2}t) + c_{12} t e^t \sin(\sqrt{2}t)$$

$$+c_{13}t^2e^t\cos(\sqrt{2}t) + c_{14}t^2e^t\sin(\sqrt{2}t)$$

11. The function $f(x) = x^2 \sin^2(\pi x)$ is an even function, which means the Fourier sine series will be 0. Therefore, we don't need to calculate B_n , only A_0 ,

$$A_0 = \frac{1}{L} \int_0^L f(x) \ dx$$

$$A_0 = \int_0^1 x^2 \sin^2(\pi x) \ dx$$

$$A_0 = \frac{1}{2} \int_0^1 x^2 (1 - \cos(2\pi x)) \ dx$$

$$A_0 = \frac{1}{2} \int_0^1 x^2 \ dx - \frac{1}{2} \int_0^1 x^2 \cos(2\pi x) \ dx$$

$$A_0 = \frac{x^3}{6} \Big|_0^1 - \frac{1}{2} \int_0^1 x^2 \cos(2\pi x) \ dx$$

Use integration by parts with $u = x^2$, $du = 2x \ dx$, $dv = \cos(2\pi x) \ dx$, and $v = (1/2\pi)\sin(2\pi x)$.

$$A_0 = \frac{1}{6} - \frac{1}{2} \left(\frac{x^2}{2\pi} \sin(2\pi x) \Big|_0^1 - \frac{1}{\pi} \int_0^1 x \sin(2\pi x) \ dx \right)$$

$$A_0 = \frac{1}{6} - \frac{1}{4\pi} \sin(2\pi) + \frac{1}{2\pi} \int_0^1 x \sin(2\pi x) \ dx$$



Use integration by parts with u = x, du = dx, $dv = \sin(2\pi x) dx$, and $v = (-1/2\pi)\cos(2\pi x)$.

$$A_0 = \frac{1}{6} - \frac{1}{4\pi} \sin(2\pi) + \frac{1}{2\pi} \left(-\frac{x}{2\pi} \cos(2\pi x) \Big|_0^1 + \frac{1}{2\pi} \int_0^1 \cos(2\pi x) \ dx \right)$$

$$A_0 = \frac{1}{6} - \frac{1}{4\pi} \sin(2\pi) - \frac{1}{(2\pi)^2} \cos(2\pi) + \frac{1}{(2\pi)^2} \int_0^1 \cos(2\pi x) \ dx$$

$$A_0 = \frac{1}{6} - \frac{1}{4\pi} \sin(2\pi) - \frac{1}{(2\pi)^2} \cos(2\pi) + \left(\frac{1}{(2\pi)^3} \sin(2\pi x)\right|_0^1$$

$$A_0 = \frac{1}{6} - \frac{1}{4\pi} \sin(2\pi) - \frac{1}{(2\pi)^2} \cos(2\pi) + \frac{1}{(2\pi)^3} \sin(2\pi)$$

$$A_0 = \frac{1}{6} - \frac{1}{4\pi^2}$$

and A_n .

$$A_n = \frac{2}{L} \int_0^L f(x) \cos\left(\frac{n\pi x}{L}\right) dx$$

$$A_n = 2\int_0^1 x^2 \sin^2(\pi x) \cos(n\pi x) \ dx$$

$$A_n = 2 \int_0^1 x^2 (1 - \cos(2\pi x)) \cos(n\pi x) \ dx$$

$$A_n = 2\int_0^1 x^2 (\cos(n\pi x) - \cos(2\pi x)\cos(n\pi x)) \ dx$$



$$A_n = \int_0^1 x^2 \left(\cos(n\pi x) - \frac{1}{2} \cos \pi x (n-2) - \frac{1}{2} \cos \pi x (n+2) \right) dx$$

Use integration by parts with

$$u = x^2$$

$$du = 2x dx$$

$$dv = \cos(n\pi x) - \frac{1}{2}\cos\pi x(n-2) - \frac{1}{2}\cos\pi x(n+2) \ dx$$

$$v = \frac{1}{n\pi} \sin(n\pi x) - \frac{1}{2\pi(n-2)} \sin \pi x (n-2) - \frac{1}{2\pi(n+2)} \sin \pi x (n+2)$$

$$A_n = x^2 \left(\frac{1}{n\pi} \sin(n\pi x) - \frac{1}{2\pi(n-2)} \sin\pi x (n-2) - \frac{1}{2\pi(n+2)} \sin\pi x (n+2) \right) \Big|_0^1$$

$$-\frac{2}{\pi} \int_0^1 x \left(\frac{1}{n} \sin(n\pi x) - \frac{1}{2(n-2)} \sin \pi x (n-2) - \frac{1}{2(n+2)} \sin \pi x (n+2) \right)$$

Use integration by parts with

$$u = x$$

$$du = dx$$

$$dv = \frac{1}{n}\sin(n\pi x) - \frac{1}{2(n-2)}\sin\pi x(n-2) - \frac{1}{2(n+2)}\sin\pi x(n+2) dx$$

$$v = -\frac{1}{n^2 \pi} \cos(n\pi x) + \frac{1}{2\pi (n-2)^2} \cos \pi x (n-2) + \frac{1}{2\pi (n+2)^2} \cos \pi x (n+2)$$

$$A_n = -\frac{2}{\pi}x \left(-\frac{1}{n^2\pi} \cos(n\pi x) + \frac{1}{2\pi(n-2)^2} \cos\pi x (n-2) + \frac{1}{2\pi(n+2)^2} \cos\pi x (n+2) \right) \Big|_0^1$$



$$+\frac{2}{\pi}\int_{0}^{1}\left(\frac{1}{n^{2}\pi}\cos(n\pi x)-\frac{1}{2\pi(n-2)^{2}}\cos\pi x(n-2)-\frac{1}{2\pi(n+2)^{2}}\cos\pi x(n+2)\right)dx$$

$$A_n = -\frac{2}{\pi} \left(-\frac{(-1)^n}{n^2 \pi} + \frac{(-1)^n}{2\pi (n-2)^2} + \frac{(-1)^n}{2\pi (n+2)^2} \right)$$

$$+\frac{2}{\pi}\left(\frac{1}{n^3\pi^2}\sin(n\pi x)-\frac{1}{2\pi^2(n-2)^3}\sin\pi x(n-2)-\frac{1}{2\pi^2(n+2)^3}\sin\pi x(n+2)\right)\Big|_0^1$$

$$A_n = \frac{(-1)^n}{\pi^2} \left(\frac{2}{n^2} + \frac{1}{(n-2)^2} + \frac{1}{(n+2)^2} \right)$$
, with $n \neq 2$

So for n = 2, we find

$$A_2 = 2 \int_0^1 x^2 \sin^2(\pi x) \cos(2\pi x) \ dx$$

$$A_2 = \int_0^1 x^2 (1 - \cos(2\pi x))\cos(2\pi x) \ dx$$

$$A_2 = \int_0^1 x^2 \left(\cos(2\pi x) - \frac{1}{2} - \frac{\cos(4\pi x)}{2} \right) dx$$

$$A_2 = -\int_0^1 \frac{x^2}{2} dx + \int_0^1 x^2 \left(\cos(2\pi x) - \frac{\cos(4\pi x)}{2} \right) dx$$

$$A_2 = -\frac{x^3}{6} \Big|_0^1 + \left(\frac{x \cos(2\pi x)}{2\pi^2} - \frac{x \cos(4\pi x)}{16\pi^2} \right) \Big|_0^1$$

$$A_2 = -\frac{1}{6} + \frac{7}{16\pi^2}$$

Then the Fourier series for $f(x) = x^2 \sin^2(\pi x)$ on $-1 \le x \le 1$ is



$$f(x) = A_0 + \sum_{n=1}^{\infty} A_n \cos\left(\frac{n\pi x}{L}\right)$$

$$f(x) = \frac{1}{6} - \frac{1}{4\pi^2} + \left(-\frac{1}{6} + \frac{7}{16\pi^2}\right)\cos(2\pi x)$$

$$+\sum_{n=1}^{\infty} \frac{(-1)^n}{\pi^2} \left(\frac{2}{n^2} + \frac{1}{(n-2)^2} + \frac{1}{(n+2)^2} \right) \cos(n\pi x)$$

12. We're solving the heat equation with two boundary conditions and an initial condition.

$$\frac{\partial u}{\partial t} = k \frac{\partial^2 u}{\partial x^2}$$

with
$$u(0,t) = 10$$
 and $u(L,t) = -5$

$$u(x,0) = 20$$

Equilibrium temperature is

$$u_E(x) = T_1 + \frac{T_2 - T_1}{L}x$$

$$u_E(x) = 10 + \frac{-5 - 10}{L}x$$

$$u_E(x) = 10 - \frac{15}{L}x$$

Next, we'll find the coefficients B_n .

$$B_n = \frac{2}{L} \int_0^L (f(x) - u_E(x)) \sin\left(\frac{n\pi x}{L}\right) dx$$

$$B_n = \frac{2}{L} \int_0^L \left(10 + \frac{15}{L} x \right) \sin \left(\frac{n\pi x}{L} \right) dx$$

Use integration by parts with u = 10 + (15/L)x,

$$du = (15/L) dx$$
, $dv = \sin(n\pi x/L) dx$, and $v = -(L/n\pi)\cos(n\pi x/L)$.

$$B_n = -\frac{2}{\pi n} \left(10 + \frac{15}{L} x \right) \cos \left(\frac{n\pi x}{L} \right) \Big|_0^L + \frac{30}{Ln\pi} \int_0^L \cos \left(\frac{n\pi x}{L} \right) dx$$

$$B_n = -\frac{2}{\pi n} (25(-1)^n - 10) + \frac{30}{n^2 \pi^2} \sin\left(\frac{n\pi x}{L}\right) \Big|_0^L$$

$$B_n = -\frac{2}{\pi n} (25(-1)^n - 10)$$

$$B_n = \frac{2}{\pi n} (10 - 25(-1)^n)$$

Then the solution to this heat equation is

$$u(x,t) = u_E + \sum_{n=1}^{\infty} B_n \sin\left(\frac{n\pi x}{L}\right) e^{-k\left(\frac{n\pi}{L}\right)^2 t}$$

$$u(x,t) = 10 - \frac{15}{L}x + \sum_{n=1}^{\infty} \frac{10}{n\pi} (2 - 5(-1)^n) \sin\left(\frac{n\pi x}{L}\right) e^{-k\left(\frac{n\pi}{L}\right)^2 t}$$



