# NATIONAL UNIVERSITY OF SINGAPORE

# ${\tt EE3206/EE3206E-INTRODUCTION\ TO} \\ {\tt COMPUTER\ VISION\ AND\ IMAGE\ PROCESSING} \\$

# $\underline{\text{INSTRUCTIONS TO CANDIDATES}}$ :

- 1. This paper contains FOUR (4) questions and comprises FIVE (5) pages.
- 2. Answer all questions.
- 3. All questions carry equal marks.
- 4. This is a CLOSED BOOK examination.
- 5. This question paper is NOT to be taken out of the examination hall.

(a) The discrete Fourier transform (DFT) of

Obtain the DFT of

(9 marks)

- (b) Compare the use of a Butterworth low-pass filter (LPF) and an ideal LPF to reduce noise in an image.

  (4 marks)
- (c) Discuss the suitability of using a Butterworth LPF to reduce noise in an image that has been contaminated by
  - (i) Gaussian noise
  - (ii) Salt-and-pepper noise

State clearly the reasons for your answer.

(8 marks)

(d) Apply  $3 \times 3$  median filtering to the binary image in Figure 1 and show the result.

(4 marks)

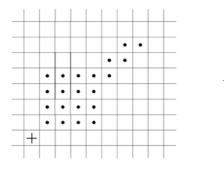


Figure 1

Origin

Image  $I_1$  is a 3-bit image with the gray level distribution given in the table below:

Gray level: 0 1 2 3 4 5 6 7Number of pixels: 100 100 200 200 300 300 400 400

(a) The transformation function

$$s_k = 2r_k - 2$$

is applied to image  $I_1$ , where  $r_k$  and  $s_k$  denote the gray levels of the input and output images, respectively. Obtain the histogram of the output image.

(5 marks)

(b) Determine the transformation function that can be applied to image  $I_1$  to obtain the histogram-equalized image  $I_2$ . Obtain and sketch the histogram of image  $I_2$ .

(9 marks)

(c) Obtain the Huffman code for the gray levels in image  $I_1$ . What is the coding efficiency?

(7 marks)

(d) With respect to this image, explain what is meant by coding the second extension of the source.

(4 marks)

(a) Figure 2 shows part of an image. Use the Sobel operator to determine the gradient magnitude and direction at the shaded pixel in the centre of the sub-image.

(6 marks)

(b) Compare the Sobel and Roberts operators for the detection of edges.

(5 marks)

(c) Compare and contrast the suitability of edge-based methods and global thresholding for segmentation when scene illumination is significantly uneven.

(5 marks)

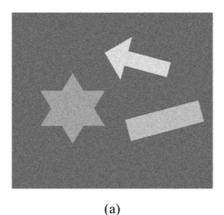
(d) Consider the image of Figure 3(a) and its histogram in Figure 3(b). Describe clearly the image processing steps that you would implement to obtain the area of each object.

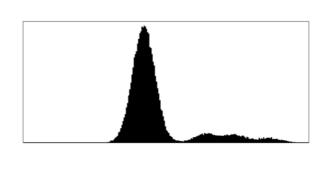
(9 marks)

10	10	10	10	10	
10	10	10	20	45	
10	10	35	50	50	
10	30	50	50	50	
10	45	50	50	50	



Figure 2





(b)

Figure 3

(a) Compute the moments  $m_{00}$ ,  $m_{11}$ ,  $m_{20}$  and  $m_{02}$  for the binary image shown in Figure 4.

(7 marks)

(b) The principal axis of an object may be defined as the straight line passing through the object centroid with slope  $\theta_A$  given by

$$\tan 2\theta_A = \frac{2\mu_{11}}{\mu_{20} - \mu_{02}}$$

where  $\mu_{pq}$  is the central moment of order p+q. Calculate  $\theta_A$  for the object in Figure 4 and sketch the principal axis.

(10 marks)

(d) A definition of eccentricity is

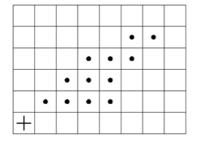
$$\epsilon = \frac{\text{maximum radial distance}}{\text{minimum radial distance}}$$

Compute eccentricity for the object in Figure 4.

(4 marks)

(a) Sketch the bounding box for the object in Figure 4.

(4 marks)





+ Origin

Figure 4