

Q.4(a)

The specifications for this problem have no requirement involving system type or error constant. ~~Our~~ Concern for changing system type and error constant by introducing compensator is not valid here. We can choose K as the last parameter.

$$G(s) = \frac{1}{s(s+2)}$$

$$G(j\omega) = \frac{1}{j\omega(2+j\omega)}$$

$$\text{at } \omega = 6.6 \text{ rad/s, } G(j6.6) = \frac{1}{(j6.6)(2+j6.6)}$$

$$\begin{aligned}\phi(6.6) &= -90^\circ - \tan^{-1} \frac{6.6}{2} \\ &= -163^\circ\end{aligned}$$

$$PM_u = 17^\circ$$

$$\text{Target PM : } 50^\circ$$

$$\text{Required phase lead} \Rightarrow 50^\circ - 17^\circ = 33^\circ$$

Let $\phi_m = 33^\circ$ [No allowance is required as we can ensure 6.6 to be ω_{cg} by adjusting K in the end].

$$\text{Then } \alpha = \frac{1 - \sin 33^\circ}{1 + \sin 33^\circ} = 0.29 \approx 0.3$$

$$\omega_m = 6.6 \text{ rad/s}$$

$$T = \frac{1}{6.6 \sqrt{0.3}} = 0.28$$

$$C(s) = \frac{0.28s + 1}{0.3 \times 0.28s + 1}$$

$$|C(j6.6)| = \frac{1}{\sqrt{0.3}} = 1.8$$

$$|G(j6.6)| = \frac{1}{6.6 \sqrt{6.6^2 + 4}} = 0.02$$

$$K |C(j6.6)| |G(j6.6)| = 1 \Rightarrow K = 27.8$$

$$G_c(s) = 27.8 \frac{(0.28s+1)}{(0.3 \times 0.28s+1)}$$

Verify

$$|K C(j\omega) G(j\omega)|_{\omega=6.6} = 1.$$

$$\angle K C(j\omega) G(j\omega)_{\omega=6.6} = -90^\circ - \tan^{-1} \frac{6.6}{2} + \tan^{-1}(0.28 \times 6.6) - \tan^{-1}(0.3 \times 0.28 \times 6.6)$$

$$= -90^\circ - 73^\circ + 61.6^\circ - 29^\circ$$

$$= -130.4^\circ$$

$$PM \approx 50^\circ$$