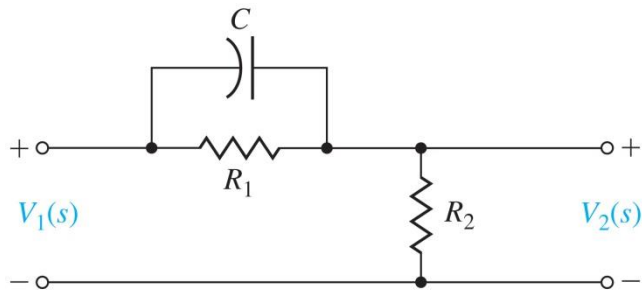


Circuit Implementation of Lead Compensator and Lag Compensator



For an RC circuit, current waveform leads in phase with reference to the waveform of the applied voltage.

Current $i(t)$ leads input voltage $v_1(t)$. The output voltage $v_2(t)$ is in-phase with the current. Therefore, voltage waveform at the output leads in phase the voltage waveform at the input.

In transfer function form:
$$G(s) = \frac{V_2(s)}{V_1(s)} = \frac{R_2}{R_2 + (R_1 \parallel \frac{1}{Cs})}$$

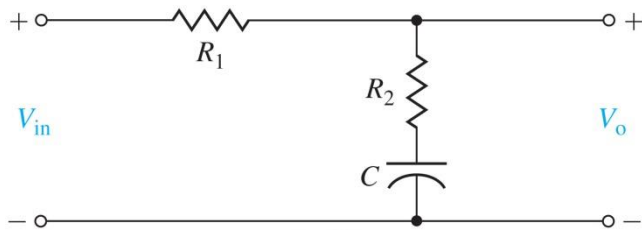
Substituting $(R_1 \parallel \frac{1}{Cs}) = \frac{R_1 \times \frac{1}{Cs}}{R_1 + \frac{1}{Cs}} = \frac{R_1}{R_1Cs + 1}$

$$\begin{aligned} G(s) &= \frac{R_2}{R_2 + \frac{R_1}{R_1Cs + 1}} \\ &= \frac{R_2(R_1Cs + 1)}{R_2R_1Cs + R_2 + R_1} \\ &= \left(\frac{R_2}{R_1 + R_2} \right) \left(\frac{R_1Cs + 1}{\left(\frac{R_2}{R_1 + R_2} \right) R_1Cs + 1} \right) \end{aligned}$$

Let, $R_1C = T$ & $\frac{R_2}{R_1 + R_2} = \alpha$

$$G(s) = \alpha \frac{(Ts + 1)}{(\alpha Ts + 1)} \quad \text{[It is obvious that } 0 < \alpha < 1, \text{ as in lead compensator.]}$$

This circuit's dc-gain is α . Putting an amplifier with gain $(1/\alpha)$ in cascade can bring the dc-gain to unity.



Current $i(t)$ leads input voltage $v_{in}(t)$ by $\theta_1 = \tan^{-1} \frac{1}{\omega\tau_{12}}$

τ_{12} is time constant of the whole circuit, i.e., $\tau_{12} = (R_1 + R_2)C$

Current $i(t)$ lead output voltage $v_o(t)$ by $\theta_2 = \tan^{-1} \frac{1}{\omega\tau_2}$

τ_2 is time constant of the vertical branch, i.e., $\tau_2 = R_2C$

Considering waveform of current $i(t)$ as reference, both $v_{in}(t)$ and $v_o(t)$ lags the current waveform. Input voltage lags current by θ_1 and output voltage by θ_2 .

$$\text{As } \tau_{12} > \tau_2, \quad \tan^{-1} \frac{1}{\omega\tau_{12}} < \tan^{-1} \frac{1}{\omega\tau_2} \Rightarrow \theta_1 < \theta_2$$

Waveform of $v_o(t)$ is more lagging than the waveform of $v_{in}(t)$ with reference to the current waveform. The output voltage lags the input voltage.

In transfer function form:

$$\begin{aligned} G(s) &= \frac{R_2 + \frac{1}{Cs}}{R_1 + R_2 + \frac{1}{Cs}} \\ &= \frac{R_2Cs + 1}{(R_1 + R_2)Cs + 1} \\ &= \frac{(R_2Cs + 1)}{\left(\frac{R_1 + R_2}{R_2} R_2Cs + 1\right)} \end{aligned}$$

Let, $R_2C = T$ & $\frac{R_1 + R_2}{R_2} = \alpha$

$$G(s) = \frac{(Ts + 1)}{(\alpha Ts + 1)} \quad [\text{It is obvious that } \alpha > 1, \text{ as in lag compensator.}]$$

This circuit's dc-gain is 1.