CHAPTER 5 MATRICES AND THEIR USES

5.1 What is a Matrix?

A system of linear algebraic equations in two variables might look like this:

$$2x + 7y = 3$$

$$4x + 8y = 11$$

- \rightarrow LINEAR because it just involves constant multiples of x and y, no x^2 , no $\sin(y)$, etc.
- → ALGEBRAIC because no differentiation.

It's cool to write these systems using the following notation:

$$\begin{bmatrix} 2 & 7 \\ 4 & 8 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 3 \\ 11 \end{bmatrix}.$$

Here $\begin{bmatrix} x \\ y \end{bmatrix}$ and $\begin{bmatrix} 3 \\ 11 \end{bmatrix}$ are familiar - they are VEC-

TORS. But $\begin{bmatrix} 2 & 7 \\ 4 & 8 \end{bmatrix}$ is something new, called a MATRIX. We say that the PRODUCT of $\begin{bmatrix} 2 & 7 \\ 4 & 8 \end{bmatrix}$ with $\begin{bmatrix} x \\ y \end{bmatrix}$ gives you $\begin{bmatrix} 3 \\ 11 \end{bmatrix}$.

Every matrix has ROWS and COLUMNS. In this case, the rows are $\begin{bmatrix} 2 \\ 4 \end{bmatrix}$, $\begin{bmatrix} 7 \\ 8 \end{bmatrix}$. We call $\begin{bmatrix} 2 \\ 4 \end{bmatrix}$ a ROW VECTOR and $\begin{bmatrix} 2 \\ 4 \end{bmatrix}$ a column vector. We say that $\begin{bmatrix} 2 & 7 \\ 4 & 8 \end{bmatrix}$ is a 2 by 2 matrix since it has two rows and two columns. You can regard $\begin{bmatrix} 2 & 7 \end{bmatrix}$ as having one row and 2 columns, etc. You can also have 3 by 3 matrices like $\begin{bmatrix} 1 & 7 & 9 \\ 7 & 8 & 2 \\ 4 & 10 & 12 \end{bmatrix}$ or even 2 by 3 matrices like $\begin{bmatrix} 1 & 2 & 4 \\ 6 & 8 & 9 \end{bmatrix}$ two rows, three columns.

A general 3 by 3 matrix can be written as

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

so a_{ij} is the number in the *i*-th row and *j*-th column, Note $a_{ij} \neq a_{ji}$ usually!

Engineers and physicists like to talk about "the matrix a_{ij} ". Strictly speaking, they mean "the matrix with entries a_{ij} " but we will talk in this sloppy way too! In the same way, any column vector can be written as $\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}$.

5.2 Matrix Arithmetic

[a] Addition and Subtraction.

Just add up or subtract the entries, as you would for a vector.

$$\begin{bmatrix} 1 & 2 \\ 4 & 8 \end{bmatrix} + \begin{bmatrix} 7 & 3 \\ 6 & 9 \end{bmatrix} = \begin{bmatrix} 8 & 5 \\ 10 & 17 \end{bmatrix}$$
$$\begin{bmatrix} 1 & 2 \\ 4 & 8 \end{bmatrix} - \begin{bmatrix} 7 & 3 \\ 6 & 9 \end{bmatrix} = \begin{bmatrix} -6 & -1 \\ -2 & -1 \end{bmatrix}$$

In general, if a_{ij} and b_{ij} are matrices (both m by n, that is, both have m rows and n columns) then the sum is $a_{ij} + b_{ij}$ and the difference is $a_{ij} - b_{ij}$.

[b] Multiplying By a Number.

Just multiply every entry, as you would for a vector. $2 \cdot \begin{bmatrix} 1 & 2 \\ 4 & 8 \end{bmatrix} = \begin{bmatrix} 2 & 4 \\ 8 & 16 \end{bmatrix}$. The product of the number c with the matrix a_{ij} is $c \cdot a_{ij}$.

[c] Transposition.

If you take a matrix and SWITCH THE FIRST ROW INTO THE FIRST COLUMN, second row into second column, and so on, the result is called the TRANSPOSE. We write $\begin{bmatrix} 1 & 2 \\ 4 & 8 \end{bmatrix}^T = \begin{bmatrix} 1 & 4 \\ 2 & 8 \end{bmatrix}$.

$$\begin{bmatrix} 1 & 7 & 9 \\ 6 & 8 & 2 \\ 4 & 10 & 12 \end{bmatrix}^{T} = \begin{bmatrix} 1 & 6 & 4 \\ 7 & 8 & 10 \\ 9 & 2 & 12 \end{bmatrix}$$
$$\begin{bmatrix} 1 & 2 & 4 \\ 6 & 8 & 9 \end{bmatrix}^{T} = \begin{bmatrix} 1 & 6 \\ 2 & 8 \\ 4 & 9 \end{bmatrix}$$
$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}^{T} = \begin{bmatrix} a_{11} & a_{21} \\ a_{12} & a_{22} \end{bmatrix}$$

and by looking at this example you can see $a_{ij}^T = a_{ji} \rightarrow$ the order of the indices is reversed. Notice that

$$((a_{ij})^T)^T = (a_{ji})^T = a_{ij}$$
$$(a_{ij} + b_{ij})^T = a_{ji} + b_{ji} = a_{ij}^T + b_{ij}^T$$
$$(c a_{ij})^T = c a_{ji} = c (a_{ij})^T.$$

[d] Multiplying Matrices.

We started by declaring that it was cool to write

$$2x + 7y = 3$$
 as $\begin{bmatrix} 2 & 7 \\ 4x + 8y = 11 \end{bmatrix}$ as $\begin{bmatrix} 2 & 7 \\ 4 & 8 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 3 \\ 11 \end{bmatrix}$. Clearly this

is a way of saying that the vector $\begin{bmatrix} 2x + 7y \\ 4x + 8y \end{bmatrix}$ equals $\begin{bmatrix} 3 \\ 11 \end{bmatrix}$, so $\begin{bmatrix} 2 & 7 \\ 4 & 8 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2x + 7y \\ 4x + 8y \end{bmatrix}$. Notice that ROWS of $\begin{bmatrix} 2 & 7 \\ 4 & 8 \end{bmatrix}$ multiply the COLUMN $\begin{bmatrix} x \\ y \end{bmatrix}$. We adopt this as our GENERAL RULE:

ROWS MULTIPLY COLUMNS!

$$\begin{bmatrix} 2 & 7 \\ 4 & 8 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 2+0 \\ 4+0 \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$$
$$\begin{bmatrix} 2 & 7 \\ 4 & 8 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0+7 \\ 0+8 \end{bmatrix} = \begin{bmatrix} 7 \\ 8 \end{bmatrix}$$
$$\begin{bmatrix} 2 & 7 \\ 4 & 8 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 2 & -1 \end{bmatrix} = \begin{bmatrix} 16 & -1 \\ 20 & 4 \end{bmatrix}$$

 $\begin{bmatrix} 1 & 2 \end{bmatrix} \begin{bmatrix} 3 \\ 4 \end{bmatrix} = 11$, a 1 by 1 matrix! Also called a NUMBER!

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix}$$

$$= \begin{bmatrix} a_{11}b_{11} + a_{12}b_{21} & a_{11}b_{12} + a_{12}b_{22} \\ a_{21}b_{11} + a_{22}b_{21} & a_{21}b_{12} + a_{22}b_{22} \end{bmatrix}$$

$$= \begin{bmatrix} c_{11} & c_{12} \\ c_{21} & c_{22} \end{bmatrix} \text{ so we have}$$

$$c_{11} = a_{11}b_{11} + a_{12}b_{21} = \sum_{j} a_{1j}b_{j1}$$

$$c_{12} = a_{11}b_{12} + a_{12}b_{22} = \sum_{j} a_{1j}b_{j2}$$

$$c_{21} = a_{21}b_{11} + a_{22}b_{21} = \sum_{j} a_{2j}b_{j1}$$

$$c_{22} = a_{21}b_{12} + a_{22}b_{22} = \sum_{j} a_{2j}b_{j2}$$
Can you see the pattern?

$$c_{mn} = \sum_{j} a_{mj} b_{jn}.$$

This is true for all matrices, not just 2 by 2 matrices.

NOTE that

$$\begin{bmatrix} 2 & 7 \\ 4 & 8 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 2 & -1 \end{bmatrix} = \begin{bmatrix} 16 & -1 \\ 20 & 4 \end{bmatrix}$$
$$\begin{bmatrix} 1 & 3 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} 2 & 7 \\ 4 & 8 \end{bmatrix} = \begin{bmatrix} 14 & 31 \\ 0 & 6 \end{bmatrix}$$
 completely different!

So the ORDER OF MATRIX MULTIPLICATION

is IMPORTANT. If A and B are matrices, USU-ALLY $AB \neq BA$.

[e] Transposition and Matrix Multiplication. According to our rules,

$$\begin{bmatrix} 1 & 2 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ 3 & 1 \end{bmatrix} = \begin{bmatrix} 8 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 3 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 8 \\ 1 \end{bmatrix}.$$

But

$$\begin{bmatrix} 8 \\ 1 \end{bmatrix} = \begin{bmatrix} 8 & 1 \end{bmatrix}^T,$$

$$\begin{bmatrix} 2 & 3 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 2 & -1 \\ 3 & 1 \end{bmatrix}^T \text{ and } \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 & 2 \end{bmatrix}^T.$$

In general, if A and B are matrices of any kind, the rule is

$$(AB)^T = B^T A^T$$

DON'T FORGET TO REVERSE THE ORDER!

A matrix is said to be SYMMETRIC if

$$A^T = A$$
.

 $\begin{bmatrix} 1 & 3 \\ 3 & 2 \end{bmatrix}$, $\begin{bmatrix} 0 & 16 \\ 16 & 10^9 \end{bmatrix}$, $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ are all symmetric. Any matrix of the form $B+B^T$, where B is ANY matrix, is symmetric. [Proof: $(B+B^T)^T=B^T+(B^T)^T=B^T+B$.] If A is symmetric, so is BAB^T for any B [Proof: $(BAB^T)^T=(B^T)^TA^TB^T=BA^TB^T=BAB^T$.] A matrix is said to be ANTISYMMETRIC if

$$A^T = -A.$$

 $\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 16 \\ -16 & 0 \end{bmatrix}, \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \text{ are all antisymmetric.}$ ric. Any matrix of the form $B-B^T$ is antisymmetric, and BAB^T is antisymmetric if A is antisymmetric.

[f] SCALAR AND VECTOR PRODUCTS IN TERMS OF MATRICES.

You are familiar with the scalar or dot product,

$$\vec{u} \cdot \vec{v} = \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} \cdot \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = u_1 v_1 + u_2 v_2 + u_3 v_3.$$

This is actually a MATRIX PRODUCT, because you can write it as

$$\vec{u}^T \vec{v} = \begin{bmatrix} u_1 & u_2 & u_3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$$
$$= u_1 v_1 + u_2 v_2 + u_3 v_3 = \vec{u} \cdot \vec{v}.$$

Thus, in particular, the length of a vector can be expressed as

$$\left| \overrightarrow{u} \right| = \sqrt{\overrightarrow{u} \cdot \overrightarrow{u}} = \sqrt{\overrightarrow{u}^T \overrightarrow{u}}.$$

You are also familiar with the VECTOR or CROSS product of two vectors, $\overrightarrow{u} \times \overrightarrow{v}$. This is also a ma-

trix product! To see this, notice that any threedimensional vector can be used to define an antisymmetric three by three matrix as follows:

$$\vec{u} = \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}$$
 defines $\begin{bmatrix} 0 & -u_3 & u_2 \\ u_3 & 0 & -u_1 \\ -u_2 & u_1 & 0 \end{bmatrix}$.

Let's call this matrix A. Then you can check that, for any vector \overrightarrow{v} ,

$$\overrightarrow{u} \times \overrightarrow{v} = A\overrightarrow{v}.$$

So the vector product is really just a special kind of matrix multiplication. Notice that A is always antisymmetric.

[g] ORTHOGONAL MATRICES.

A matrix B is said to be ORTHOGONAL if it satisfies

$$B^TB = I$$
,

where
$$I$$
 is the IDENTITY MATRIX, $I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ in

two dimensions,
$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
 in three, etc. Note that

IA = A = AI for any matrix A. In two dimensions, $\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$ is orthogonal for any θ . Since

$$\begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

$$= \begin{bmatrix} \cos^2 \theta + \sin^2 \theta & 0 \\ 0 & \sin^2 \theta + \cos^2 \theta \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Another example is
$$\begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{bmatrix}$$
.

5.3 Application: Markov Chains.

Let's construct a simple MODEL of weather forecasting. We assume that each day is either RAINY or SUNNY. Rainy today \rightarrow probably rainy tomorrow (probability 60%).

Sunny today \rightarrow probably sunny tomorrow (probability 70%).

Since probabilities have to add up to 100%, you can easily see that Rainy \rightarrow Sunny has probability 40% and Sunny \rightarrow Rainy has probability 30%. We can organise these data into a matrix

$$M = \begin{bmatrix} \text{Rainy} \to \text{Rainy} & \text{Sunny} \to \text{Rainy} \\ \text{Rainy} \to \text{Sunny} & \text{Sunny} \to \text{Sunny} \end{bmatrix}$$
$$= \begin{bmatrix} 0.6 & 0.3 \\ 0.4 & 0.7 \end{bmatrix}.$$

Question: Suppose today is sunny. What is the probability that it will be rainy 4 days from now? To see how to proceed, we make a "tree" like this: [R = rain, S = sun] for the first two days:

We have, similarly, that the probability of Rainy \rightarrow Sunny over 2 days is

$$RS_2 = 0.6 \times 0.4 + 0.4 \times 0.7$$

By constructing a tree starting with S, you will find that the probability of rain 2 days after a sunny day is

$$SR_2 = 0.6 \times 0.3 + 0.3 \times 0.7$$

and similarly

$$SS_2 = 0.4 \times 0.3 + 0.7 \times 0.7$$

So now the matrix of probabilities is

$$\begin{bmatrix} RR_2 & SR_2 \\ RS_2 & SS_2 \end{bmatrix}$$

$$= \begin{bmatrix} 0.6 \times 0.6 + 0.3 \times 0.4 & 0.6 \times 0.3 + 0.3 \times 0.7 \\ 0.6 \times 0.4 + 0.4 \times 0.7 & 0.4 \times 0.3 + 0.7 \times 0.7 \end{bmatrix}.$$

But this is exactly
$$\begin{bmatrix} 0.6 & 0.3 \\ 0.4 & 0.7 \end{bmatrix} \begin{bmatrix} 0.6 & 0.3 \\ 0.4 & 0.7 \end{bmatrix} = M^2$$
.

So matrix multiplication actually allows you to compute all of the probabilities in this "Markov Chain". To predict the weather 4 days from now, we need

$$\begin{bmatrix} RR_4 & SR_4 \\ RS_4 & SS_4 \end{bmatrix} = M^4 = M^2 M^2 = \begin{bmatrix} 0.43 & 0.43 \\ 0.57 & 0.57 \end{bmatrix}.$$

So if it is rainy today, the probability of rain in 4 days is 0.43=43%. If you want 20 days, just compute M^{20} . A very complicated problem without matrix multiplication!

5.4 Application: Leontief Model of Manufacturing

The Leontief model describes the economics of IN-TERDEPENDENT companies. For example, the electric company MUST sell electricity to the factory that makes generators, which in turn MUST sell generators to the electric company. Let x be the number of dollars' worth of electricity generated, and let y be the number of dollars' worth of generators made by the factory. Assume

- [a] The electric company has to sell \$150 of electricity to the city, and the generator factory wants to sell \$100 to outsiders.
- [b] Each dollar of electricity costs 30 cents to make [fuel].
- [c] Each dollar's worth of generator needs 40 cents of electricity.
- [d] Each dollar's worth of generator costs 30 cents [parts].
- [e] Each dollar's worth of electricity needs 50 cents' worth of generator.

Then x splits into 3 parts:

- 0.3 x for fuel
- 0.4 y goes to the generator factory

150 goes for sale

So we have

$$x = 0.3x + 0.4y + 150$$

and similarly

$$y = 0.5x + 0.3y + 100$$

or

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0.3 & 0.4 \\ 0.5 & 0.3 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} 150 \\ 100 \end{bmatrix}$$
$$\vec{u} = T\vec{u} + \vec{c}$$

where
$$\overrightarrow{u} = \begin{bmatrix} x \\ y \end{bmatrix}$$
, $T = \begin{bmatrix} 0.3 & 0.4 \\ 0.5 & 0.3 \end{bmatrix}$, $\overrightarrow{c} = \begin{bmatrix} 150 \\ 100 \end{bmatrix}$.

The matrix T contains all of the INTERNAL INFORMATION about the two companies and their contractual relationship. It is called the TECHNOLOGY MATRIX. An easy way to construct the matrix is as follows: think of the COLUMNS as the costs of making a unit of something. For example, in this case the first column refers to electricity, so

the costs of making one dollar of electricity go down that column [30 cents to MAKE one dollar of electricity, and 50 cents to pay for the generator needed to MAKE one dollar of electricity.] Similarly the costs of making one dollar's worth of generator go down the second column. In a more complicated problem the matrix may be much larger, but this idea of using the columns to keep track of costs will always work.

Write $\overrightarrow{u} = I\overrightarrow{u}$ where I is the identity matrix. Then

$$(I-T)\overrightarrow{u} = \overrightarrow{c}.$$

Now if these were NUMBERS, I could easily solve this for $\overrightarrow{u} \to \text{just}$ divide both sides by I-T, or multiply both sides by $(I-T)^{-1}$. But can we do that for matrices? In our case, $I-T=\begin{bmatrix} 0.7 & -0.4 \\ -0.5 & 0.7 \end{bmatrix}$. CAN WE FIND A MATRIX S such that S(I-T)=I?? Actually you can $\to S=\frac{1}{29}\begin{bmatrix} 70 & 40 \\ 50 & 70 \end{bmatrix}$ Check it!

So multiplying both sides of our equation by S, we get

$$S(I-T)\overrightarrow{u} = S\overrightarrow{c} \rightarrow \overrightarrow{u} = \frac{1}{29} \begin{bmatrix} 70 & 40 \\ 50 & 70 \end{bmatrix} \begin{bmatrix} 150 \\ 100 \end{bmatrix}$$

 $\overrightarrow{u} = \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 500 \\ 500 \end{bmatrix} \rightarrow x = y = \500 , both companies should produce \$500 worth of their products

\$500 electricity = \$150 fuel + \$200 to factory + \$150 sold.

\$500 generators = \$150 parts + \$250 to electric + \$100 sold.

Given a matrix M, how do you find another matrix S such that SM = I? We need a systematic way of doing that! Come back to this later.