# Insert Markov pun here A talk on Probabilistic Automata and Markov Chains

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A **Stochastic Vector**  $\vec{a}$  is a vector in  $\mathbb{R}^n$  which satisfies the following conditions:

- if  $s \in \vec{a}$ , then 0 < s < 1
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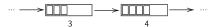
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Stochastic vectors can be thought of as a form of **discrete probability distribution**: given a finite number of possible states,  $\vec{a}$  gives the probability of transitioning to the ith state.

### A short recap of NFA's

#### Deterministic and Nondeterministic Finite State Machines

Combining both these concepts, a **Deterministic Finite State Automata** (**DFA**) is one whose next state is uniquely determined by the current state. As an example, a loading bar at n% can only progress to a state at n+1%



In contrast, a **Nondeterministic Finite State Automata (NFA)** is one whose next state is not uniquely determined by it's current state. An example would be the output of a dice roll: it's a NFA, because the number of states are finite, and the next state is independent of the current state





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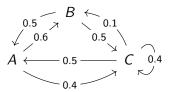


#### Probabilistic Automata

A **Probabilistic Automata** (PA) generalizes the concept of a NFA, so that the transition probabilities are given by the transition function (the transition function for such an automata is a stochastic matrix / markov matrix)

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### Modeling PA's: Markov Processes

PA's lend themselves to being modeled by markov matrices very well. As an example, the process in the previous slide can be modeled as follows:

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$$\vec{a}_A = \begin{bmatrix} 0 \\ 0.6 \\ 0.4 \end{bmatrix} \vec{a}_B = \begin{bmatrix} 0.5 \\ 0 \\ 0.5 \end{bmatrix} \vec{a}_C = \begin{bmatrix} 0.5 \\ 0.1 \\ 0.4 \end{bmatrix}$$
$$\mathcal{S} = \begin{bmatrix} 0 & 0.5 & 0.5 \\ 0.6 & 0 & 0.1 \\ 0.4 & 0.5 & 0.4 \end{bmatrix}$$

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PA's lend themselves to being modeled by markov matrices very well. As an example, the process in the previous slide can be modeled as follows:

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$$A \leftarrow 0.5 \rightarrow C \quad 0.4$$

$$S = \begin{bmatrix} 0 & 0.5 & 0.5 \\ 0.6 & 0 & 0.1 \\ 0.4 & 0.5 & 0.4 \end{bmatrix}$$

Now, given an initial state a, Sa would give the final state after one transition. By induction,  $S^na$  would give the final state after n transitions.

#### More on Markov Matrices

• A markov matrix S multiplied by a stochastic vector  $\vec{a}$  gives a stochastic vector

<u>Proof:</u> Consider the row vector  $T = \begin{bmatrix} 1 & 1 & ... & 1 \end{bmatrix}$ . This acts like a map from  $\mathbb{R}^n \to \mathbb{R}$  defined as  $T\vec{a} = a_1 + a_2 + ... + a_n$ . For a stochastic vector  $\vec{a}$ ,  $T\vec{a} = 1$ . If we apply this map on  $\mathcal{S}\vec{a}$ , then we get

$$\begin{bmatrix} 1 & 1 & \dots & 1 \end{bmatrix} \mathcal{S} \vec{a} = \begin{bmatrix} 1 & 1 & \dots & 1 \end{bmatrix} \vec{a} = 1$$

(Since every column vector of a stochastic matrix is a stochastic vector,  $\mathcal{TS} = \mathcal{T}$ )

Hence,  $\vec{a^1} = \mathcal{S}\vec{a}$  is a stochastic vector. By induction,  $\vec{a^n} = \mathcal{S}^n\vec{a}$  is also a stochastic vector.

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ullet 1 is an eigenvalue of every stochastic matrix  ${\cal S}$ 

<u>Proof:</u> we need to show |S - I| = 0. Notice that since every column of S sums to 1, every column of S - I would sum to 0. Hence |S - I| = 0.

ullet All other eigenvalues of  ${\cal S}$  are less than 1

<u>Proof:</u> Suppose there exists  $\lambda>1$  such that  $\mathcal{S}\vec{a}=\lambda\vec{a}$ . let  $a_L$  be the largest element of  $\vec{a}$ . Every entry in  $\lambda\vec{a}$  can be written as

$$a_i = \sum_{j=1}^n a_j \mathcal{S}_{ij} < a_L \sum_{j=1}^n \mathcal{S}_{ij} = a_L$$

but since  $\lambda a_L \in \lambda \vec{a}$  and  $\lambda > 1$ , we have a contradiction. Hence, all the eigenvalues of  $\mathcal{S}$  are less than 1.  $\blacksquare$ 

# Analysing the steady state

What is a steady state? When the PA reaches a state that does not change in the next iteration, we call it a steady state. Using a markov matrix, we can define it as:

$$\mathcal{S}\vec{\tau} = \vec{\tau}$$

It's easy to see that  $\vec{\tau}$  is the eigenvector corresponding to the eigenvalue 1. The question then arises Proof: