## Minimum Spanning Tree: (for Directed Graphs)

## Kruskal's Algorithm: Consider edges in ascending order of cost.

## Add the next edge to T unless doing so would create a cycle.

```
Initialize MSI to be empty;
Place each vertex in its own set;
Sort edges of 6 in increasing-order;
for each edge e = (u,v) in order
if u and v are not in the same set
Add e to MST;
Compute the union of the two sets;
```

Output: A minimum spanning tree for the graph G.

## Analysis: (adjacency matrix)

- One union-find operation for each edge:  $O(E \log(V))$ .
- Total:  $O(V^2) + O(E \log(E)) + O(E \log(V))$  $\Rightarrow O(V^2)$ , for sparse graphs  $\Rightarrow O(V^2)\log V$ , for dense graphs

## Analysis: (adjacency list)

- To place edges in list: simply scan each vertex list once
   ⇒ O(E) time.
- Total: O(E)+ O(E log(E)) + O(E log(V))
   ⇒ O(E log(E))
   ⇒ O(E log(V)) (same for sparse or dense)

Kruskal's algorithm is a greedy algorithm used to obtain MST using a direct generic method. Here, all the edges are considered in non-decreasing (increasing) order and the edges to be included are based on the order.

## Procedure for Kruskal's approach to MST:

- Step 02: Pick one edge at a time from the list starting from the least cost edge.
- > Step 03: Check if the inclusion of the edge causes a cycle or a loop in the output.
- Step 04: If it causes a cycle, discard it. If it does not generate a cycle, include it into the tree.
- Step 05: Repeat the steps 2-4 until a tree is generated with all nodes of the graph.

Algorithm: Kruskal-MST (adjMatrix)
Input: Adjacency matrix: adjMatrix[i][j] = weight of edge (i,j) (if nonzero)

```
Initialize MST to be empty:
 // Initialize union-find algorithm
// place each vertex in its own set
for i=0 to numVertices-1
makeSingleElementSet (i)
```

sortedEdgeList = sort edges in increasing-order;

# Initialize treeMatrix to store MST;

14. return treeMatrix

Output: adjacency matrix represention of tree.

## Prim's Algorithm:

Prim's algorithm is a greedy strategy used to obtain the MST from a graph edge by edge. The edge to be included is chosen according to the optimization criteria i.e., to chose an edge that results in a minimum increases in the sum of costs of the edges included so far. If A is the set of edges selected so far, then A forms a tree, the next edge (u, v) to be included in A is a minimum cost edge not in A, with the property that  $\Lambda \cup \{(u,v)\}$  is also tree.

- Steps in Prim's Algorithm:

  > Step 01: Select any vertex (or alphabetically or given vertex) as the source.

  > Step 02: Compute the distances from the source to each other vertices of the
- Step 03: Choose the vertex which leads to a minimum increase in the sum of costs of the edges included. Add the vertex to the tree iff the addition does not lead to a

Step 04: Repeat the steps 2 and 3 until a tree is generated with all the vertices of

```
graph.
thm: Prim-MST (adjMatrix)
Adjacency matrix: adjMatrix[i][j] = weight of edge (i,j) (if nonzero)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             Output: A minimum spanning tree of the graph G.
                // inMST[i] = true once vertex i is in the MS
Initialize inMST[i] = false for all i;
Initialize priority[i] = infinity for all i;
priority[0] = 0
numVerticesAdded = 0
            // Process vertices one by one. Note: priorities change as we proceed.
while numVerticesAdded / Cartact best vertex.
v = vertex with lowest priority that is not in MST;
v = vertex with lowest priority that is not in MST;
inMST[v] = True
numVerticeAdded = numCerticeAdded + 1
// Explore adges going out from v.
for in0 to numVertices-1
// If there's an edge and it's not a self-loop.
if if priority[i] > adjMatrix[v][i]
// If there's an edge and it's not a self-loop.
if if priority[i] > adjMatrix[v][i]
// New priority
and it's not a

priority[v][1] 0 0

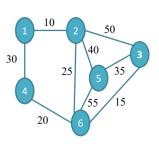
priority[v][1] 1 0 0

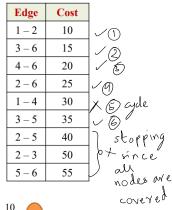
priority[v][1] 1 0 0

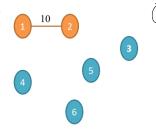
priority[v][1] 2 0 0

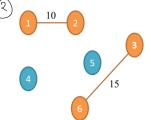
predecessor[v][1] 2
```

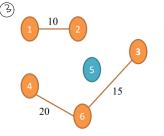
## Edge List E in Increasing Order

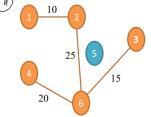


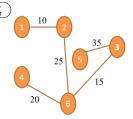












## Example:

Algorithm: Prim-MST (G)
Input: Graph G=(V,E) with edge-weights.

Initialize MSI to vertex 0.

priority[0] = 0

For all other vertices, set priority[i] = infinity

Initialize prioritySet to all vertices;

while prioritySet.notEmpty()

y = remove minimal-priority vertex from prioritySet;

for each neighbor u of v

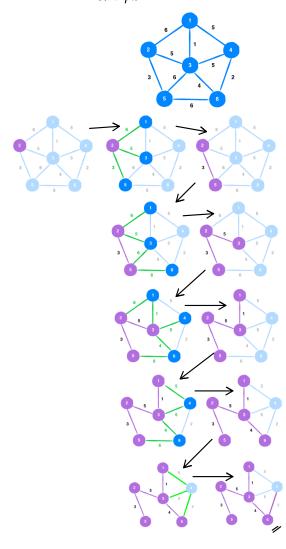
w = weight of edge (v, u)

if w < priority[u]

priority[u] = w

endif

endfor



https://iq.opengenus.org/time-and-space-complexity-of-prims-algorithm/

https://iq.opengenus.org/time-and-space-complexity-of-kruskal-algorithm/ using union & find:

explaination: https://www.youtube.com/watch?v=JZBQLXgSGfs

code: https://gist.github.com/DanilAndreev/e519d77eff91f03f09616c9170db7941

https://stackoverflow.com/questions/53389594/given-an-edge-find-a-minimum-spanning-tree-if-exist (gist: when there is a node with no edges in graph then MST doesn't exist) https://www2.seas.gwu.edu/~simhaweb/alg/modules/module8/module8.html (pseudo code and run time analysis)

https://users.cs.northwestern.edu/~agupta/\_projects/algorithms/Fibonacci%20Heaps/Doc/Design%20Document%20%231.pdf

