## hw2-my-hdr-stack-Copy1

## October 4, 2022

```
[1]: import numpy as np
     import cv2
     # import skimage
     import matplotlib.pyplot as plt
     import src.cp_hw2
     # import src.cp exr
[2]: # Q1.2) Linearize Rendered Images
     # Read images
     image_files = ['data/gphoto-exposure-stack-no-noise-reduction-myroom/
      →exposure'+str(i)+'.jpg' for i in range(1,17)]
     images_stack_for_lin = []
     for imf in image_files :
         img = plt.imread(imf)
         img = img[::200, ::200]
         images_stack_for_lin.append(img)
     images_stack_for_lin = np.array(images_stack_for_lin)
     images_stack_for_lin_reshaped = images_stack_for_lin.
      →reshape(images_stack_for_lin.shape[0],-1).swapaxes(0,1)
[3]: \# t_filler = lambda x : 2.0 ** (x-1-12)
     \# t = [t_filler(i) \text{ for } i \text{ in } range(1,19)]
     t = [1/4000, 1/2000, 1/1000, 1/500, 1/250, 1/125, 1/60, 1/30, 1/15, 1/8, 1/4, 1/8]
      42,1,2,4,8,15,30
     # variable t used in general scope later on in the program
     def get_g(images_stack_reshaped, images_stack, w, t, r_l=1, is_w_photon=False) :
         n = 256:
         A = np.zeros((images_stack_reshaped.shape[0]*images_stack_reshaped.
      \hookrightarrowshape [1]+n+1,
                        n+images_stack_reshaped.shape[0]))
         b = np.zeros((A.shape[0],1))
         cur_row_A = 0
         for i in range(images_stack_reshaped.shape[0]) : # Corresponds to pixel in_
      ⇒image
```

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for j in range(images_stack_reshaped.shape[1]) : # Corresponds to image_
      →in sequence
         #
                   wt_ij = 1 \# placeholder
                 if is_w_photon :
                     wt_ij = w(images_stack_reshaped[i,j], t[j])
                 else :
                     wt_ij = w(images_stack_reshaped[i,j])
                   print(wt_ij)
                 A[cur_row_A, images_stack_reshaped[i,j]] = wt_ij
                 A[cur\_row\_A, n+i-1] = -wt\_ij
                 b[cur\_row\_A, 0] = wt\_ij * np.log(t[j])
                 cur_row_A = cur_row_A + 1
         # Adding the terms corresponding to the smoothing regularization
         for i in range(n) :
             if is_w_photon :
                 wt i = 1
             else :
                 wt i = w(i)
             A[cur\_row\_A,i-1] = r\_1 * wt\_i
             A[cur row A,i] = -2*r 1*wt i
             A[cur\_row\_A,i+1] = r\_l*wt\_i
             cur_row_A += 1
         # Normalize the curve by setting its middle value to O
         A[cur\_row\_A, 128] = 1 \# Corresponds to q128 in q0-q255
         v = np.linalg.lstsq(A, b, rcond=None)
         print(v)
         v_sol = v[0]
         g = v_sol[:n]
          L = v sol[n:]
           L = L.reshape(images\_stack.shape[1], images\_stack.shape[2], images\_stack.
      ⇔shape[3])
         return g
     w = lambda x, zmin=0.05, zmax=0.95 : 0.01
     g = get_g(images_stack_for_lin_reshaped, images_stack_for_lin, w, t, 10)
[6]: # Plotting q
     plt.plot(np.arange(0,256),g)
     plt.title('g plot')
     plt.show()
     # Linearizing the image
     # The other image is too small to make sense of, so looking at a larger image
```

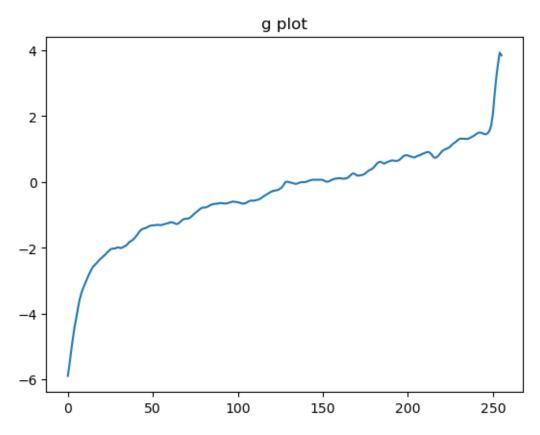
images\_stack = []

```
for imf in image_files :
    img = plt.imread(imf)
    img = img[::20, ::20]
    images_stack.append(img)
images_stack = np.array(images_stack)

def linearize_image(images_stack, g) :
    lin_images_stack = np.exp(g[images_stack])
    lin_images_stack = lin_images_stack.squeeze(-1)
    return lin_images_stack

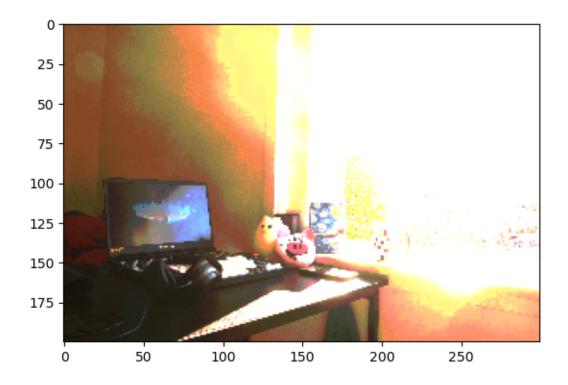
lin_images_stack = linearize_image(images_stack, g)
plt.imshow(lin_images_stack[8])

# display_hdr_image(lin_images_stack[8],0.05)
```



Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or [0..255] for integers).

[6]: <matplotlib.image.AxesImage at 0x7f9e07a95de0>



```
[8]: images_stack_normalized = images_stack / 255.0
images_stack_tiff_normalized = images_stack_tiff / (2**16 - 1)

#
# Over-exposure vs under-exposed pixel selection is still off. Fix later!
def linear_merging(im_s, lin_im_s, t, w_v, is_w_photon=False) :

I_hdr_num = np.zeros(im_s[0].shape)
I_hdr_den = np.zeros(im_s[0].shape)
for k in range(len(im_s)) :
    if is_w_photon :
```

```
if np.max(lin_im_s) > 256:
               w_v_{imk} = w_v(im_s[k], t[k], 0.0001, 0.995)
           else :
               w_v_{imk} = w_v(im_s[k], t[k], 0.00001, 0.92)
       else :
           if np.max(lin_im_s) > 256:
               w_v_{imk} = w_v(im_s[k], 0.02, 0.98)
           else :
               w \ v \ imk = w \ v(im \ s[k])
       I_hdr_num += (w_v_imk * lin_im_s[k] / t[k])
       I_hdr_den += (w_v_imk)
  I_hdr = I_hdr_num / I_hdr_den
  # where num is zero, hdr final should also be zero
  I_hdr_num_zero = np.where(I_hdr_num == 0)
  if len(I_hdr_num_zero) == 3 :
       I_hdr_num_zero = np.vstack((np.

¬vstack((I_hdr_num_zero[0],I_hdr_num_zero[1])), I_hdr_num_zero[2])).T
  else :
       I_hdr_num_zero = np.vstack((I_hdr_num_zero[0],I_hdr_num_zero[1])).T
   # where num is not zero, but den is zero, all hdr final values should be \Box
\hookrightarrow max val
  I_hdr_den_zero = np.where(I_hdr_den == 0)
  if len(I hdr den zero) == 3 :
       I hdr den zero = np.vstack((np.
ovstack((I_hdr_den_zero[0],I_hdr_den_zero[1])), I_hdr_den_zero[2])).T
  else :
       I_hdr_den_zero = np.vstack((I_hdr_den_zero[0],I_hdr_den_zero[1])).T
  I_hdr_max_val = []
  if I_hdr_num_zero.size > 0 :
       if len(I_hdr.shape) == 3 :
           I_hdr[I_hdr_num_zero[:,0],I_hdr_num_zero[:,1],I_hdr_num_zero[:,2]]__
→= 0
       else :
           I_hdr[I_hdr_num_zero[:,0],I_hdr_num_zero[:,1]] = 0
  if I_hdr_den_zero.size > 0 :
       for index in I_hdr_den_zero :
           if len(I_hdr.shape) == 3 :
               if I_hdr_num[index[0],index[1],index[2]] != 0 :
                   I_hdr_max_val.append(index)
           else :
```

```
if I_hdr_num[index[0],index[1]] != 0 :
                    I_hdr_max_val.append(index)
        I_hdr_max_val = np.array(I_hdr_max_val)
        if I_hdr_max_val.size > 0 :
            I_hdr_max_val = np.stack(I_hdr_max_val)
            if len(I_hdr.shape) == 3 :
                I_hdr[I_hdr_max_val[:,0],I_hdr_max_val[:,1],I_hdr_max_val[:,2]]__
 →= np.nanmax(I_hdr)
            else :
                I_hdr[I_hdr_max_val[:,0],I_hdr_max_val[:,1]] = np.nanmax(I_hdr)
    return I_hdr
def linear_merging_channelwise(im_s, lin_im_s, t, w_v, is_w_photon=False) :
    I_hdr = np.zeros(im_s[0].shape)
    I_{\text{hdr}}[\ldots,0] = linear_merging(im_s[\ldots,0], lin_im_s[\ldots,0], t, w_v_u
 ⇔is_w_photon)
    I_hdr[...,1] = linear_merging(im_s[...,1], lin_im_s[...,1], t, w_v,_u
 →is_w_photon)
    I_hdr[...,2] = linear_merging(im_s[...,2], lin_im_s[...,2], t, w_v,_u
 →is_w_photon)
    return I_hdr
def log_merging(im_s, lin_im_s, t, w_v, is_w_photon=False) :
    eps = 1e-8
    I_hdr_num = np.zeros(im_s[0].shape)
    I_hdr_den = np.zeros(im_s[0].shape)
    for k in range(len(im_s)) :
        if is_w_photon :
            if np.max(lin_im_s) > 256:
                w_v_{imk} = w_v(im_s[k],t[k],0.0001, 0.995)
            else :
                w_v_{imk} = w_v(im_s[k], t[k], 0.00001, 0.92)
            if np.max(lin_im_s) > 256:
                w_v_{imk} = w_v(im_s[k], 0.02, 0.98)
            else :
                w_v_{imk} = w_v(im_s[k])
        I_hdr_num += (w_v_imk * (np.log(lin_im_s[k] + eps) - np.log(t[k])))
        I_hdr_den += w_v_imk
    I_hdr = I_hdr_num / I_hdr_den
    # where num is zero, hdr final should also be zero (regardless of den)
```

```
I_hdr_num_zero = np.where(I_hdr_num == 0)
    I_hdr_num_zero = np.vstack((np.
 ovstack((I hdr num zero[0], I hdr num zero[1])), I hdr num zero[2])).T
    # where num is not zero, but den is zero, all hdr final values should be _{f L}
 ⊶max val
    I_hdr_den_zero = np.where(I_hdr_den == 0)
    I_hdr_den_zero = np.vstack((np.
 ovstack((I_hdr_den_zero[0],I_hdr_den_zero[1])), I_hdr_den_zero[2])).T
    I hdr max val = []
    if I_hdr_num_zero.size > 0 :
        I_hdr[I_hdr_num_zero[:,0],I_hdr_num_zero[:,1],I_hdr_num_zero[:,2]] = 0
    if I_hdr_den_zero.size > 0 :
        for index in I hdr den zero :
            if I_hdr_num[index[0],index[1],index[2]] != 0 :
                I_hdr_max_val.append(index)
        I_hdr_max_val = np.array(I_hdr_max_val).T
        if I_hdr_max_val.size > 0 :
            I_hdr_max_val = np.stack(I_hdr_max_val)
            I_hdr[I_hdr_max_val[:,0],I_hdr_max_val[:,1],I_hdr_max_val[:,2]] =__
 →np.nanmax(I hdr)
    return np.exp(I_hdr)
# setting w for merging testing
\# w_v = np.vectorize(w)
\# I_hdr_lin_merged = linear_merging(images_stack_normalized, lin_images_stack, u)
\hookrightarrow t, w v)
# I_hdr_tiff_lin_merged = linear_merging(images_stack_tiff_normalized,_
\hookrightarrow images stack tiff, t, w v)
# I hdr log merged = log merging(images stack normalized, lin images stack, t, L
# I_hdr_tiff_log_merged = log_merging(images_stack_tiff_normalized,_
\hookrightarrow images\_stack\_tiff, t, w\_v)
# src.cp_hw2.writeHDR('I_jpq_lin_merged.HDR', I_hdr_lin_merged)
# src.cp_hw2.writeHDR('I_tiff_lin_merged.HDR', I_hdr_tiff_lin_merged)
# src.cp_hw2.writeHDR('I_jpg_log_merged.HDR', I_hdr_log_merged)
# src.cp_hw2.writeHDR('I_tiff_log_merged.HDR', I_hdr_tiff_log_merged)
```

```
def w_uniform(z, Z_min = 0.05, Z_max=0.95) :
          if isinstance(z,np.uint8) or isinstance(z,int):
               z = z / 255.0
          if Z_{\min} \le z \le Z_{\max}:
              return 1
          return 0
      def w_tent(z, Z_min = 0.001, Z_max=0.999) :
          if isinstance(z,np.uint8) or isinstance(z,int) :
               z = z / 255.0
          Z \min = 0.001
          Z_{max} = 0.995
          if Z_{min} \le z \le Z_{max}:
              return np.min([z, 1.0-z])
          return 0
      def w_gaussian(z, Z_min = 0.001, Z_max=0.999) :
          if isinstance(z,np.uint8) or isinstance(z,int):
              z = z / 255.0
          Z_{\min} = 0.001
          Z \max = 0.999
          if Z_{min} \le z \le Z_{max}:
              return np.exp(-4 * (((z-0.5)**2) / ((0.5)**2)))
          return 0
      def w_{photon}(z, tk, Z_{min} = 0.05, Z_{max}=0.95) :
      # for tiff
      #
                Z \min = 0.0001
                Z_{max} = 0.995
      # # for jpeg
                Z_{min} = 0.00001
      #
                Z_max = 0.92
          if isinstance(z,np.uint8) or isinstance(z,int):
               z = z / 255.0
          if Z_{min} \le z \le Z_{max}:
              return tk
          return 0
[32]: # HDR display util functions
      def linear_scaling(img_cc, scale, should_plot=False):
            img_scaled = np.clip(skimage.color.rgb2gray(img_cc) * scale, 0, 1)
```

[31]: # Weighting Schemes

img\_scaled = np.clip(img\_cc \* scale, 0, 1)

plt.imshow(img\_scaled)

if should\_plot :

```
plt.title('linear scaling')
        plt.show()
    return img_scaled
# Gamma Encoding
def gamma_encoding(val) :
    if val <= 0.0031308 :</pre>
        return 12.92 * val
    else :
        return (1+0.055) * np.power(val, 1/2.4) - 0.055
def display_hdr_image(img, scale, title='', should_plot=True) :
    img scaled = linear scaling(img, scale)
    ge_f = np.vectorize(gamma_encoding)
    image_ge = ge_f(img_scaled)
    if should_plot :
        plt.imshow(image_ge)
        plt.title(title)
        plt.show()
    return image_ge
```

```
[28]: w uniform vectorized = np.vectorize(w uniform)
      w_tent_vectorized = np.vectorize(w_tent)
      w_gaussian_vectorized = np.vectorize(w_gaussian)
      w_photon_vectorized = np.vectorize(w_photon)
      # Creating all merged raw images
      I hdr tiff lin merged w uniform = linear merging(images_stack_tiff_normalized,
       →images_stack_tiff, t, w_uniform_vectorized)
      I hdr tiff lin merged w uniform channelwise = ____
       ⇔linear_merging_channelwise(images_stack_tiff_normalized, images_stack_tiff, u
       ⇔t, w uniform vectorized)
      I_hdr_tiff_log_merged_w_uniform = log_merging(images_stack_tiff_normalized,_
       →images_stack_tiff, t, w_uniform_vectorized)
      I_hdr_tiff_lin_merged_w_tent = linear_merging(images_stack_tiff_normalized,_
       →images_stack_tiff, t, w_tent_vectorized)
      I_hdr_tiff_log_merged_w_tent = log_merging(images_stack_tiff_normalized,_
       simages_stack_tiff, t, w_tent_vectorized)
      I_hdr_tiff_lin_merged_w_gaussian = linear_merging(images_stack_tiff_normalized,_
       →images_stack_tiff, t, w_gaussian_vectorized)
      I hdr_tiff_log_merged_w_gaussian = log_merging(images_stack_tiff_normalized,_
       →images_stack_tiff, t, w_gaussian_vectorized)
```

```
⇔images_stack_tiff, t, w_photon_vectorized, is_w_photon=True)
     I_hdr_tiff_log_merged_w_photon = log_merging(images_stack_tiff_normalized,_
       →images_stack_tiff, t, w_photon_vectorized, is_w_photon=True)
[29]: # # Creating all merged jpeg images
     g uniform = get_g(images_stack_for_lin_reshaped, images_stack_for_lin,_
      →w_uniform_vectorized,t, 10)
     g_tent = get_g(images_stack_for_lin_reshaped, images_stack_for_lin,_u
      →w_tent_vectorized,t, 10)
     g_gaussian = get_g(images_stack_for_lin_reshaped, images_stack_for_lin,_u
       →w_gaussian_vectorized,t, 10)
     g_photon = get_g(images_stack_for_lin_reshaped, images_stack_for_lin,_u
      →w_photon_vectorized,t, 10, is_w_photon=True)
     lin_images_stack_uniform = linearize_image(images_stack, g_uniform)
     lin_images_stack_tent = linearize_image(images_stack, g_tent)
     lin_images_stack_gaussian = linearize_image(images_stack, g_gaussian)
     lin_images_stack_photon = linearize_image(images_stack, g_photon)
     I_hdr_jpeg_lin_merged_w_uniform = linear_merging(images_stack_normalized,_
      olin_images_stack_uniform, t, w_uniform_vectorized)
     I_hdr_jpeg_log_merged_w_uniform = log_merging(images_stack_normalized,_u
      olin_images_stack_uniform, t, w_uniform_vectorized)
     I hdr jpeg lin merged w tent = linear merging(images stack normalized,
      I hdr jpeg log merged w tent = log merging(images stack normalized,
      →lin_images_stack_tent, t, w_tent_vectorized)
     I_hdr_jpeg_lin_merged_w_gaussian = linear_merging(images_stack_normalized,_
      olin_images_stack_gaussian, t, w_gaussian_vectorized)
     I_hdr_jpeg_log_merged_w_gaussian = log_merging(images_stack_normalized,__
      →lin_images_stack_gaussian, t, w_gaussian_vectorized)
     I_hdr_jpeg_lin_merged_w_photon = linear_merging(images_stack_normalized,__
      →lin_images_stack_photon, t, w_photon_vectorized, is_w_photon=True)
     I_hdr_jpeg_log_merged_w_photon = log_merging(images_stack_normalized,_
       Glin_images_stack_photon, t, w_photon_vectorized, is_w_photon=True)
```

I hdr\_tiff\_lin merged w photon = linear merging(images\_stack\_tiff\_normalized,\_\_

/tmp/ipykernel 5075/2109691339.py:23: RuntimeWarning: invalid value encountered

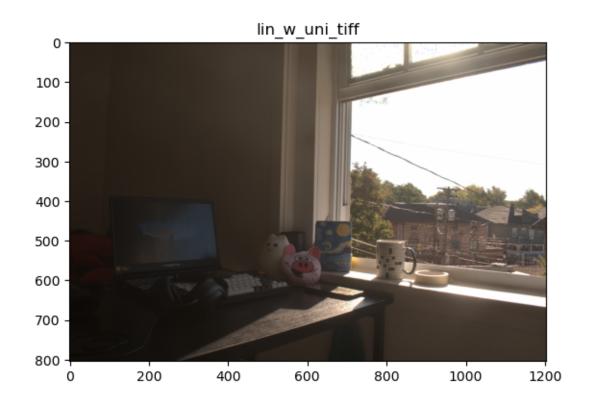
/tmp/ipykernel 5075/2109691339.py:95: RuntimeWarning: invalid value encountered

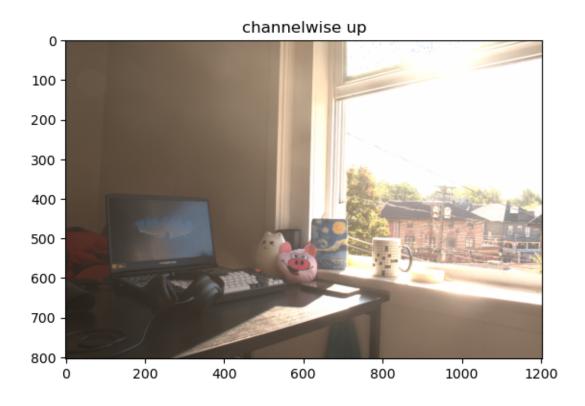
in divide

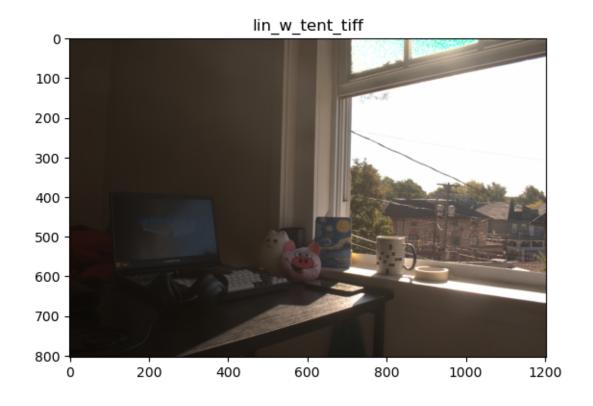
in divide

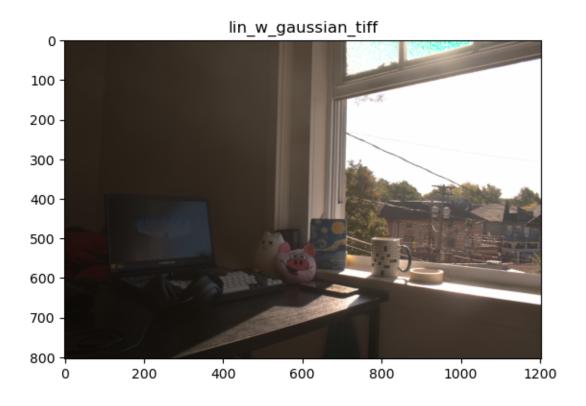
I\_hdr = I\_hdr\_num / I\_hdr\_den

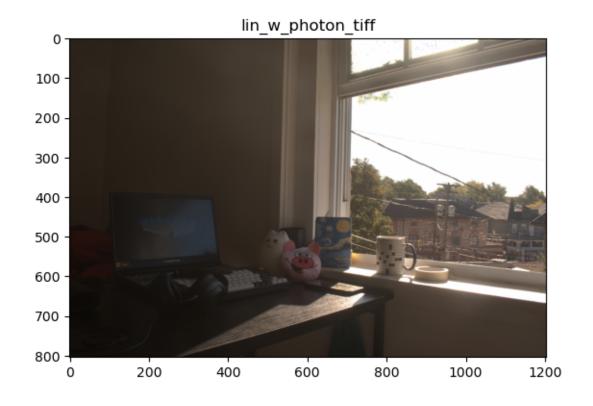
```
[33]: # Displaying images
      # Displaying RAW source generated images
      _ = display_hdr_image(I_hdr_tiff_lin_merged_w_uniform,0.
      ⇔0000004,'lin_w_uni_tiff')
      _ = display_hdr_image(I_hdr_tiff_lin_merged_w_uniform_channelwise, 0.000002,__
      _ = display_hdr_image(I_hdr_tiff_lin_merged_w_tent,0.0000004,'lin_w_tent_tiff')
      _ = display_hdr_image(I_hdr_tiff_lin_merged_w_gaussian,0.
      ⇔0000004, 'lin_w_gaussian_tiff')
      _ = display_hdr_image(I_hdr_tiff_lin_merged_w_photon,0.
       ⇔0000004, 'lin_w_photon_tiff')
      _ = display_hdr_image(I_hdr_tiff_log_merged_w_uniform,0.
      ⇔0000006,'log_w_uni_tiff')
      = display hdr image(I hdr tiff log merged w tent, 0.0000006, 'log w tent tiff')
      _ = display_hdr_image(I_hdr_tiff_log_merged_w_gaussian,0.
      →0000006, 'log_w_gaussian_tiff')
      _ = display_hdr_image(I_hdr_tiff_log_merged_w_photon,0.
      ⇔0000006,'log w photon tiff')
      # Displaying JPEG source generated images
      _ = display_hdr_image(I_hdr_jpeg_lin_merged_w_uniform,0.002,'lin_w_uni_jpeg')
      _ = display_hdr_image(I_hdr_jpeg_lin_merged_w_tent,0.002,'lin_w_tent_jpeg')
      _ = display_hdr_image(I_hdr_jpeg_lin_merged_w_gaussian,0.
      ⇔002, 'lin_w_gaussian_jpeg')
      = display_hdr_image(I_hdr_jpeg_lin_merged_w_photon,0.002,'lin_w_photon_jpeg')
      _ = display_hdr_image(I_hdr_jpeg_log_merged_w_uniform,0.002,'log_w_uni_jpeg')
      _ = display_hdr_image(I_hdr_jpeg_log_merged_w_tent,0.002,'log_w_tent_jpeg')
      _ = display_hdr_image(I_hdr_jpeg_log_merged_w_gaussian,0.
      →002, 'log_w_gaussian_jpeg')
      _ = display_hdr_image(I_hdr_jpeg_log_merged_w_photon,0.002,'log_w_photon_jpeg')
      print('log with gaussian and tent hyper params, zmin and zmax need to be tuned, ⊔
       \hookrightarrowbut we are happy with some of the other images so we arent going down this\sqcup
       ⇔route.')
      print('lin w uni tiff and lin w photon tiff are the two best images, out of u
       →which the uniform weighing scheme image is picked.')
      print('lin_w_uni_jpeg and lin_w_photon_jpeg come right after these only because⊔
       ⇔the colors seem too highlighty near the lights.')
```

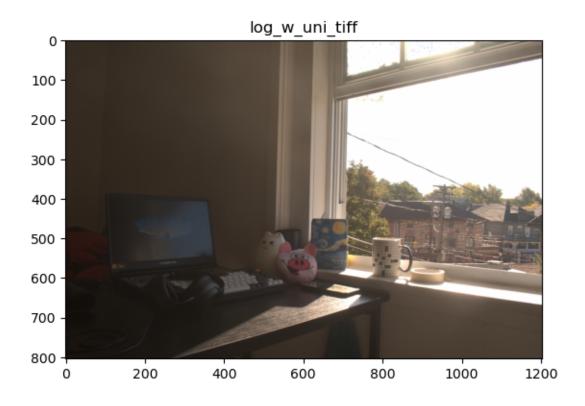


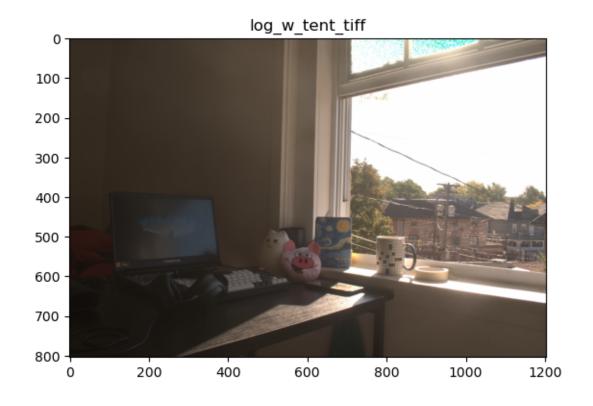




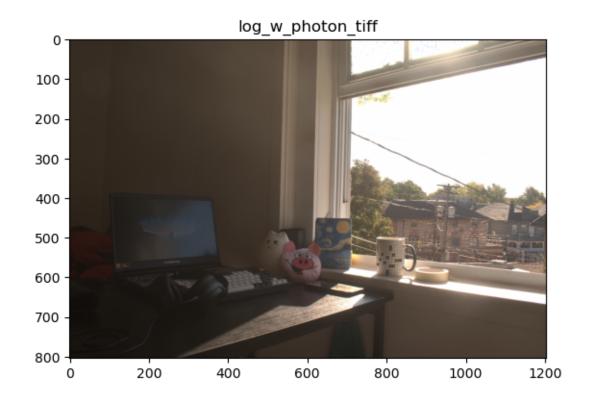


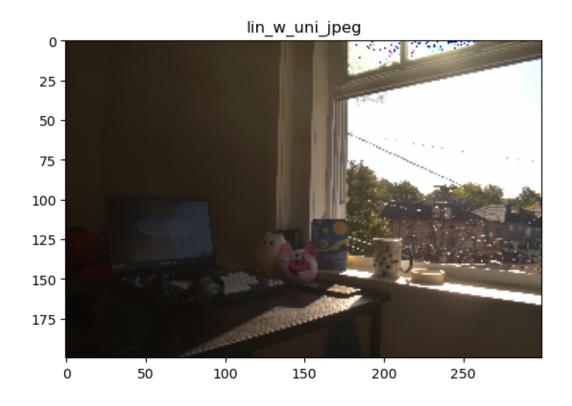


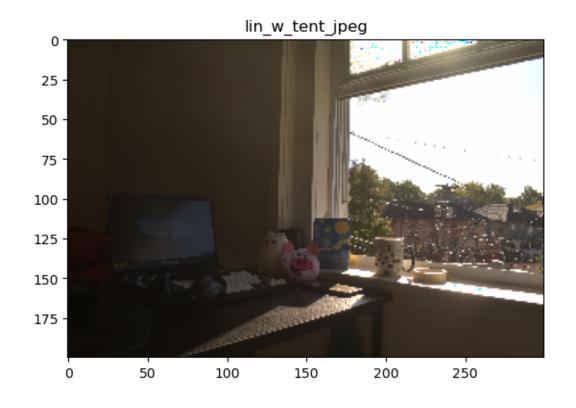


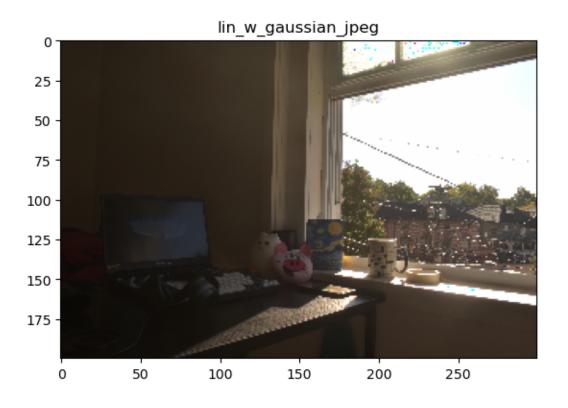


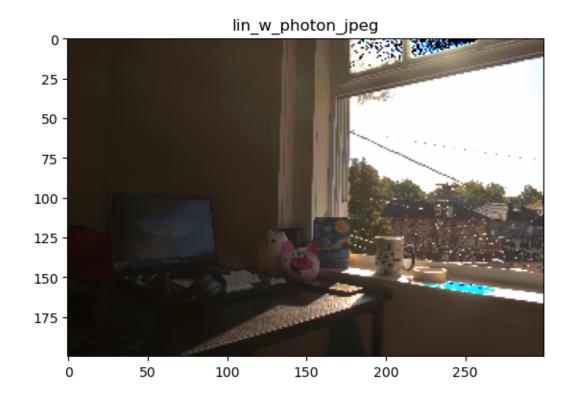


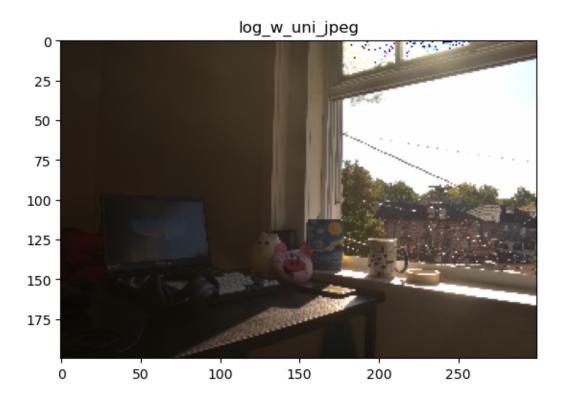


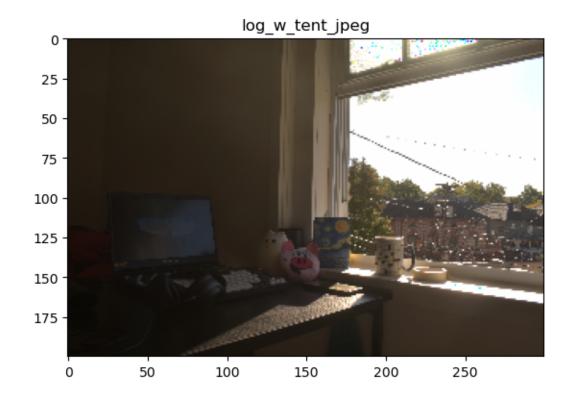


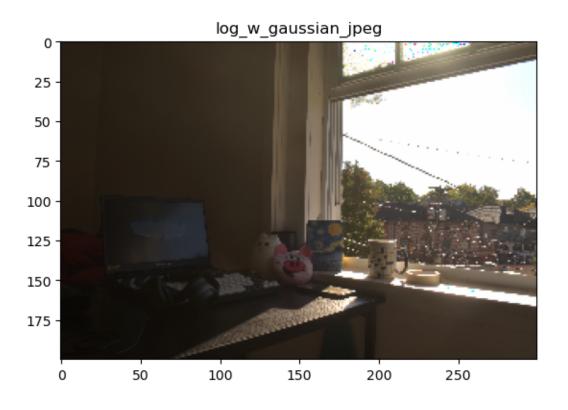


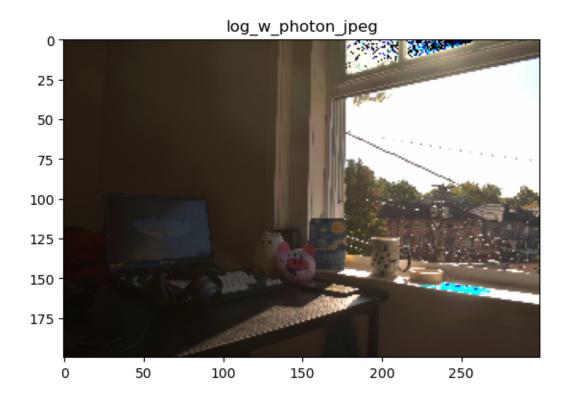












log with gaussian and tent hyper params, zmin and zmax need to be tuned, but we are happy with some of the other images so we arent going down this route. lin\_w\_uni\_tiff and lin\_w\_photon\_tiff are the two best images, out of which the uniform weighing scheme image is picked.

lin\_w\_uni\_jpeg and lin\_w\_photon\_jpeg come right after these only because the
colors seem too highlighty near the lights.

```
[]:
```

```
[48]: # Photographic ToneMapping

# kinda sus, make sure its right
def calc_geometric_mean_log(im) :
    if im.min() < 0 :</pre>
```

```
# clipping out negative values and raising them to be over 0
        g_{mean} = np.exp(np.log(im - (1.00000001) * im.min()).mean())
    else :
        # else
        g_{mean} = np.exp(np.log(im + 1e5).mean())
    return g_mean
def calc geometric mean(im) :
def place_key(g_mean, im, K) :
    im_keyed= K * (im) / g_mean
    return im_keyed
def set_white(im_keyed, B) :
    im_white = B * np.max(im_keyed)
    return im_white
# Note: don't really understand what the difference
# would be upon applying tonemapping for the 3 channels separately
# in the case mentioned in the hints. That would be same as this right?
def complete_photographic_tonemap(im, K, B) :
    g_mean = calc_geometric_mean_log(im)
    im_keyed = place_key(g_mean, im, K)
    im_white = set_white(im_keyed, B)
    im_tonemapped_num = im_keyed * (1 + im_keyed / (im_white**2))
    im_tonemapped_den = 1 + im_keyed
    im_tonemapped = im_tonemapped_num / im_tonemapped_den
    return im_tonemapped
def complete_photographic_tonemap_throughxyY(im, K, B) :
    im_XYZ = src.cp_hw2.1RGB2XYZ(im)
    x = im_XYZ[...,0].copy() / im_XYZ.sum(2)
    y = im_XYZ[...,1].copy() / im_XYZ.sum(2)
    Y = im_XYZ[...,1].copy()
    Y_tonemapped = complete_photographic_tonemap(Y, K, B)
    X = (x * Y_tonemapped) / y
    Y = Y_{tonemapped}
    Z = (1 - x - y) * Y_tonemapped / y
```

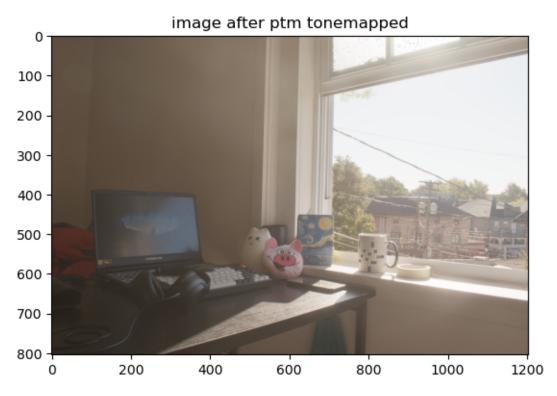
```
im_XYZ_tonemapped = np.concatenate((np.stack((X,Y),-1),np.
expand_dims(Z,-1)),-1)
im_RGB_tonemapped = src.cp_hw2.XYZ21RGB(im_XYZ_tonemapped)

return im_RGB_tonemapped

im_hdr_selected_cc_wb_ptm = complete_photographic_tonemap(im_hdr_selected, K=0.
472, B=0.95)
im_hdr_selected_cc_wb_ptm_tonemapped = display_hdr_image(im_hdr_selected_cc_wb_ptm, 1, 'image after ptm tonemapped')

im_hdr_selected_cc_wb_ptm_xyY = display_hdr_image(im_hdr_selected_cc_wb_ptm, 1, 'image after ptm tonemapped')

im_hdr_selected_cc_wb_ptm_tonemap_throughxyY(im_hdr_selected, K=0.72, B=0.95)
im_hdr_selected_cc_wb_ptm_tonemapped = display_hdr_image(im_hdr_selected_cc_wb_ptm_xyY, 1, 'image after ptm_display_hdr_image(im_hdr_selected_cc_wb_ptm_xyY, 1, 'image after ptm_display_hdr_image(im_hdr_selected_cc_wb_ptm_xyY-part4a.HDR', display_hdr_selected_cc_wb_ptm_xyY-part4a.HDR', display_hdr_selected_cc_wb_ptm_xyY)
```

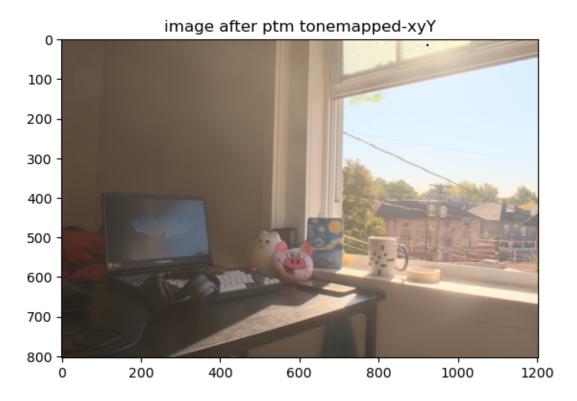


/tmp/ipykernel\_5075/2361107979.py:45: RuntimeWarning: invalid value encountered in divide

```
x = im_XYZ[...,0].copy() / im_XYZ.sum(2)
```

 $\label{tmpip} $$ $$ /tmp/ipykernel_5075/2361107979.py:46: RuntimeWarning: invalid value encountered in divide $$$ 

y = im\_XYZ[...,1].copy() / im\_XYZ.sum(2)



## 0.1 []: []: []: []: