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SUBJECT:	FOSIP
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AIM: - Study Image Enhancement using Spatial Filtering

OBJECTIVES:

- (I) Image Enhancement using Spatial Filtering based on recent published technique based
- (II) Download the research paper from IEEE Xplorer published after 2018
- (III) Develop the algorithm and process the following types of images
- 1. Low Contrast Photograph (Your Picture)
- 2. Raw X-Ray Image
- 3. Raw Satellite Image downloaded from standard database
- (IV) Evaluate the efficiency of algorithm using Objective Evaluation Test and Subjective evaluation Test.
- (V) Give your conclusion based on results obtained.

INTRODUCTION:

Spatial filters are convolution kernels that are used to perform operations like blurring, sharpening, and edge detection on images. Here are examples of full spatial filters for three common operations: smoothing (low-pass filter), sharpening (high-pass filter), and edge detection.

- 1. Low-Pass (Smoothing) Filter (Gaussian Filter):
 - A Gaussian filter is commonly used for smoothing and noise reduction.
 - Gaussian Kernel:

1/16	1	2	1
	2	4	2
	1	2	1

- 2. High-Pass Filter (Laplacian Filter):
 - The Laplacian filter enhances edges and details in an image.
 - Laplacian Kernel:

- 3. Edge Detection (Sobel Operator):
 - The Sobel operator is commonly used for edge detection.

X – Direction Kernel

-1	0	1
-2	0	2
-1	0	1

Y – Direction Kernel

-1	-2	-1
0	0	0
1	2	1

EXPERIMENTATION:

CODE:

```
def compute_metrics(original, enhanced):
    if len(original.shape) == 2:
        psnr_value = psnr(original, enhanced, data_range=original.max() - original.min())
        ssim_value = ssim(original, enhanced, data_range=original.max() - original.min())
    elif len(original.shape) == 3:
        channels_original = cv2.split(original)
        channels_enhanced = cv2.split(enhanced)
        psnr_values = [psnr(channels_original[i], channels_enhanced[i], data_range=original.max() - original.min()) for i in range(3)]
        ssim_values = [ssim(channels_original[i], channels_enhanced[i], data_range=original.max() - original.min()) for i in range(3)]
        psnr_value = np.mean(psnr_values)
        ssim_value = np.mean(ssim_values)
    else:
        raise ValueError("Unsupported image format")

return psnr_value, ssim_value
```

```
def display_image_filters(image_path):
    img = cv2.imread(image_path, cv2.IMREAD_GRAYSCALE) / 255.0

gaussian_kernel = np.array([[1, 2, 1], [2, 4, 2], [1, 2, 1]]) / 16.0
laplacian_kernel = np.array([[9, -1, 0], [-1, 4, -1], [0, -1, 0]])
sobel_kernel_x = np.array([[-1, 0, 1], [-2, 0, 2], [-1, 0, 1]])
sobel_kernel_y = np.array([[-1, -2, -1], [0, 0, 0], [1, 2, 1]])

smoothed_img = cv2.filter2D(img, -1, gaussian_kernel)
sharpened_img = cv2.filter2D(img, -1, laplacian_kernel)
edge_x_img = cv2.filter2D(img, -1, sobel_kernel_x)
edge_y_img = cv2.filter2D(img, -1, sobel_kernel_y)

psnr_smoothed, ssim_smoothed = compute_metrics(img, smoothed_img)
psnr_sharpened, ssim_sharpened = compute_metrics(img, sharpened_img)
psnr_edge_x_, ssim_edge_x = compute_metrics(img, edge_x_img)
psnr_edge_y_, ssim_edge_y = compute_metrics(img, edge_y_img)

plt.figure(figsize=(12, 8))

plt.subplot(2, 3, 1)
plt.imshow(img, cmap='gray')
plt.title('original lmage')
plt.subplot(2, 3, 2)
plt.subplot(2, 3, 2)
plt.imshow(smoothed_img, cmap='gray')
plt.title('Smoothed_img, cmap='gray')
```

```
plt.subplot(2, 3, 3)
plt.imshow(sharpened_img, cmap='gray')
plt.title('Sharpened Image (Laplacian Filter):\nPSNR: {:.2f}, SSIM: {:.2f}'.format(psnr_sharpened, ssim_sharpened))
plt.axis('off')

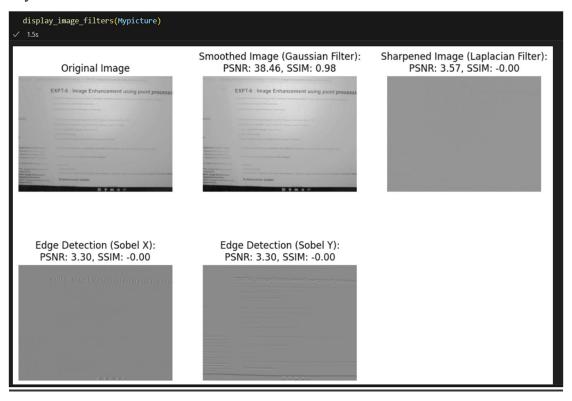
plt.subplot(2, 3, 4)
plt.imshow(edge_x_img, cmap='gray')
plt.title('Edge Detection (Sobel X):\nPSNR: {:.2f}, SSIM: {:.2f}'.format(psnr_edge_x, ssim_edge_x))
plt.axis('off')

plt.subplot(2, 3, 5)
plt.imshow(edge_y_img, cmap='gray')
plt.title('Edge Detection (Sobel Y):\nPSNR: {:.2f}, SSIM: {:.2f}'.format(psnr_edge_y, ssim_edge_y))
plt.title('Edge Detection (Sobel Y):\nPSNR: {:.2f}, SSIM: {:.2f}'.format(psnr_edge_y, ssim_edge_y))
plt.axis('off')

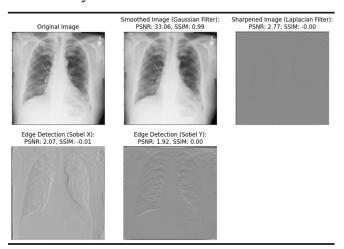
plt.show()
```

RESULT:

1. My Picture



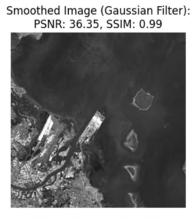
2. Raw X-Ray



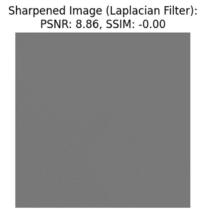
3. Satellite Image



Edge Detection (Sobel X): PSNR: 6.97, SSIM: 0.01



Edge Detection (Sobel Y): PSNR: 7.02, SSIM: 0.01





CONCLUSION:

- 1. Successfully performed image enhancement using spatial filtering.
- 2. Gaussian Filter showed good results.