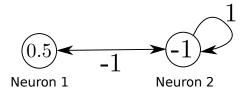
ECE/CS 559 - Fall 2016 - Final Exam.

Full Name: ID Number:

• Q0 (5 pts): Attach the e-mail/webpage confirming that you completed the instructor/TA evaluations.

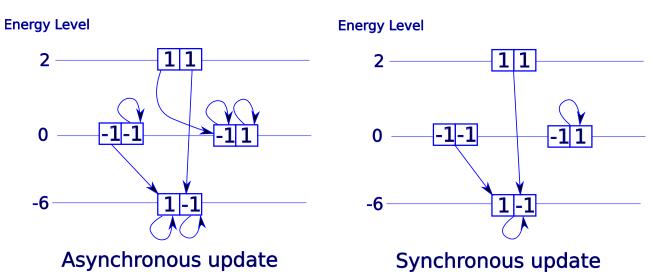
• Q1 (31 pts): Consider the Hopfield network below. The activation function is $\phi(x) = 1$ if $x \ge 0$, and $\phi(x) = -1$ if x < 0.



- (a) (9 pts): Draw the state transition diagram together with state energy levels for the asynchronous update rule. Indicate the steady state(s) of the network.
- (b) (7 pts): Does the network always converge to a steady state under the asynchronous update rule? Justify your answer.
- (c) (15 pts): Repeat (a) and (b) for the synchronous update rule.

(a) Let
$$W = \begin{bmatrix} 0 & -1 \\ -1 & 1 \end{bmatrix}$$
, $b = \begin{bmatrix} 0.5 \\ -1 \end{bmatrix}$, and $E(x) \triangleq -x^T W x - 2b^T x$. We calculate
$$\phi\left(W \begin{bmatrix} -1 \\ -1 \end{bmatrix} + b\right) = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \text{ with } E\left(\begin{bmatrix} -1 \\ -1 \end{bmatrix}\right) = 0.$$
$$\phi\left(W \begin{bmatrix} -1 \\ 1 \end{bmatrix} + b\right) = \begin{bmatrix} -1 \\ 1 \end{bmatrix} \text{ with } E\left(\begin{bmatrix} -1 \\ 1 \end{bmatrix}\right) = 0.$$
$$\phi\left(W \begin{bmatrix} 1 \\ -1 \end{bmatrix} + b\right) = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \text{ with } E\left(\begin{bmatrix} 1 \\ -1 \end{bmatrix}\right) = -6.$$
$$\phi\left(W \begin{bmatrix} 1 \\ 1 \end{bmatrix} + b\right) = \begin{bmatrix} -1 \\ -1 \end{bmatrix} \text{ with } E\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right) = 2.$$

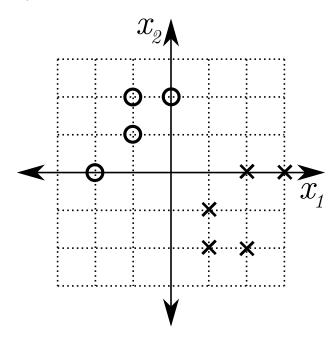
From these calculations, we obtain the diagrams below:



The steady states for the synchronous and asynchronous update rules are the same and are $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$ and $\begin{bmatrix} -1 \\ 1 \end{bmatrix}$.

- (b) From the diagrams, we observe that the network converges under both synchronous and asynchronous update rules.
- (c) Already solved.

- Q2 (30 pts): This problem will be on SVMs. Note that neither of the two parts (a) and (b) of this question require solving complex optimization problems.
 - (a) **(15 pts):** Consider the figure below. Each small dotted square is 1×1 . Members of C^+ are represented by crosses while members of C^- are represented by hollow disks. According to this description, we thus have $C^+ = \{ \begin{bmatrix} 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ -2 \end{bmatrix}, \begin{bmatrix} 2 \\ -2 \end{bmatrix} \}$, and $C^- = \{ \begin{bmatrix} -2 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \end{bmatrix} \}$.



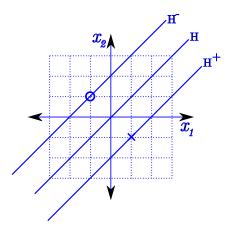
Design a linear SVM that separates the classes C^+ and C^- .

Recall that the result of the SVM will be a discriminant function $g(\mathbf{x}) = g(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix})$ with the property that $g(\mathbf{x}) \geq 1$ for every $\mathbf{x} \in C^+$, and $g(\mathbf{x}) \leq -1$ for every $\mathbf{x} \in C^-$. A pattern $\mathbf{x} \in C^+$ with $g(\mathbf{x}) = 1$ is called a support vector for class C^+ , while a pattern $\mathbf{x} \in C^-$ and $g(\mathbf{x}) = -1$ is called a support vector for class C^- . In your solution, you should clearly indicate

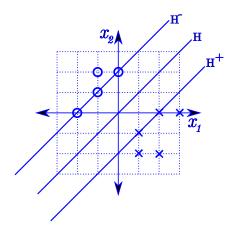
- The steps and justifications of your solution to the corresponding SVM design problem.
- The resulting discriminant function $g(\mathbf{x})$.
- The support vectors for class C^+ , and the support vectors for class C^- .
- A sketch of the decision boundaries

$$\mathcal{H} = \{ \mathbf{x} : g(\mathbf{x}) = 0 \}, \ \mathcal{H}^+ = \{ \mathbf{x} : g(\mathbf{x}) = 1 \}, \ \text{and} \ \mathcal{H}^- = \{ \mathbf{x} : g(\mathbf{x}) = -1 \}.$$

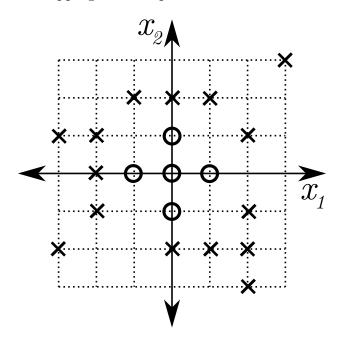
As illustrated in the figure below, consider an alternate SVM design problem where we have one member from each class as $C^+ = \{\begin{bmatrix} 1 \\ -1 \end{bmatrix}\}$, and $C^- = \{\begin{bmatrix} -1 \\ 1 \end{bmatrix}\}$. In this case, as derived in class, the best separating hyperplane (the SVM) passes between the points $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$ and $\begin{bmatrix} -1 \\ 1 \end{bmatrix}$ and is perpendicular to the line that connects $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$ and $\begin{bmatrix} -1 \\ 1 \end{bmatrix}$. The support vector for class C^+ is $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$ and the support vector for class C^- is $\begin{bmatrix} -1 \\ 1 \end{bmatrix}$. Since $g(\mathbf{x})$ should vanish whenever $x_1 = x_2$, we have $g(\mathbf{x}) = c(x_1 - x_2)$. By $g(\begin{bmatrix} 1 \\ -1 \end{bmatrix}) = 1$ (note that $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$ is a support vector for C^+), we obtain $c = \frac{1}{2}$.



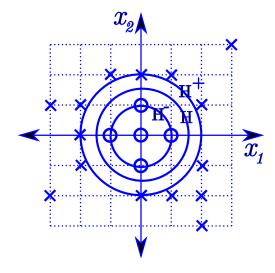
Now, in our simple problem, each pattern is at least $\sqrt{2}$ -far to the separating hyperplane \mathcal{H} . We observe that if we use the same hyperplane in our original problem, then, again, each pattern is at least $\sqrt{2}$ -far to the separating hyperplane, and each pattern will be classified correctly. There cannot be a better hyperplane for the original problem, as that would imply a better hyperplane for the simple problem as well! Hence, the discriminant function for the original problem will be $g(\mathbf{x}) = \frac{1}{2}(x_1 - x_2)$. The sets \mathcal{H}^+ , \mathcal{H} , and \mathcal{H}^- will be the same as in the figure above. The support vectors for class C^+ are $\{\begin{bmatrix} 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \end{bmatrix}\}$. Support vectors for class C^- are $\{\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \end{bmatrix}\}$.



(b) (15 pts): Repeat (a) for classes C^+ and C^- illustrated in the figure below. This time, instead of a linear SVM, you have to design a non-linear SVM by picking an appropriate feature mapping/kernel. Your feature mapping $\phi(\mathbf{x})$ should depend only on the norm $\|\mathbf{x}\|$ of \mathbf{x} . For example, $\phi(\mathbf{x}) = \begin{bmatrix} \|\mathbf{x}\| + 1 \\ \|\mathbf{x}\|^2 \end{bmatrix}$ would be a valid feature mapping for this question.



Choose, e.g. $\phi(\mathbf{x}) = \|\mathbf{x}\|$. Samples in the feature space are then the scalars $\phi(C^+) = \{2, \sqrt{5}, \sqrt{8}, \sqrt{10}, \sqrt{13}, \sqrt{18}\}$ and $\phi(C^-) = \{0, 1\}$. Using the same arguments as in (a), the discriminant function in the feature space is g'(x) = 2x - 3. The discriminant function in the original space is then $g(\mathbf{x}) = 2\|\mathbf{x}\| - 3$. The support vectors and the separating hyperplanes are as shown below.



• Q4 (34 pts): Let $\mathbf{x}_1 = \begin{bmatrix} 1 & 1 \end{bmatrix}$, $\mathbf{x}_2 = \begin{bmatrix} 2 & 1 \end{bmatrix}$, $\mathbf{x}_3 = \begin{bmatrix} -1 & -1 \end{bmatrix}$. We wish to design a one-dimensional SOM with 2 neurons. Let $\mathbf{w}_{1,0} = \begin{bmatrix} -1 & 0 \end{bmatrix}$ and $\mathbf{w}_{2,0} = \begin{bmatrix} 0 & 1 \end{bmatrix}$ be the initial weights of the first neuron and the second neuron, respectively.

We recall the standard online learning phase. The patterns are shown sequentially as

$$x_1, x_2, x_3, x_1, x_2, x_3, \dots$$

resulting in the sequence of weights

$$\mathbf{w}_{1,0} = \begin{bmatrix} -1 & 0 \end{bmatrix}, \mathbf{w}_{1,1}, \mathbf{w}_{1,2}, \mathbf{w}_{1,3}, \mathbf{w}_{1,4}, \mathbf{w}_{1,5}, \dots$$

for the first neuron, and the sequence of weights

$$\mathbf{w}_{2,0} = [0 \ 1], \mathbf{w}_{2,1}, \mathbf{w}_{2,2}, \mathbf{w}_{2,3}, \mathbf{w}_{2,4}, \mathbf{w}_{2,5}, \dots$$

for the second neuron. Thus, for $n \in \{1, 2, ...\}$, the vectors $\mathbf{w}_{1,n}$ and $\mathbf{w}_{2,n}$ denote the updated weights after n patterns are shown to the network. For notational convenience, we let \mathbf{x}_n denote the nth pattern shown to the network. For example, $\mathbf{x}_n = \mathbf{x}_3$ whenever n is a multiple of 3.

When the nth pattern \mathbf{x}_n is shown, we define the winning neuron

$$i_n = \arg\min_{i \in \{1,2\}} \|\mathbf{x}_n - \mathbf{w}_{i,n-1}\|, n \in \{1,2,\ldots\}$$

as the neuron whose weight vector is closest to \mathbf{x}_n in terms of the Euclidean distance.

(a) (9 pts): When \mathbf{x}_n is shown, suppose that we update the winning neuron as

$$\mathbf{w}_{i_n,n} = \mathbf{w}_{i_n,n-1} + \frac{1}{2}(\mathbf{x}_n - \mathbf{w}_{i_n,n-1}),$$

while keeping the loser neuron weights the same (i.e. $\mathbf{w}_{i,n} = \mathbf{w}_{i,n-1}$ if $i \neq i_n$). Find the weights of both neurons after one epoch of training.

- (b) (8 pts): Do the limits $\lim_{n\to\infty} \mathbf{w}_{1,n}$ and $\lim_{n\to\infty} \mathbf{w}_{2,n}$ exist? In other words, do the weight vectors converge? Justify your answer.
- (c) **(9 pts):** For any real number x, let $\lfloor x \rfloor$ denote the largest integer that is less than or equal to x. For example, $\lfloor 2.1 \rfloor = 2$, $\lfloor 3 \rfloor = 3$, $\lfloor -1.1 \rfloor = -2$, $\lfloor -5 \rfloor = -5$. For a vector $\mathbf{x} = \begin{bmatrix} x_1 & x_2 \end{bmatrix}$, we let $\lfloor \mathbf{x} \rfloor = \begin{bmatrix} \lfloor x_1 \rfloor & \lfloor x_2 \rfloor \end{bmatrix}$.

Now suppose that, when \mathbf{x}_n is shown, we update the winning neuron as

$$\mathbf{w}_{i_n,n} = \left[\mathbf{w}_{i_n,n-1} + \frac{1}{2} (\mathbf{x}_n - \mathbf{w}_{i_n,n-1}) \right],$$

while keeping the loser neuron weights the same (i.e. $\mathbf{w}_{i,n} = \mathbf{w}_{i,n-1}$ if $i \neq i_n$). Find the weights of both neurons after one epoch of training.

(d) (8 pts): Repeat (b) for the setup in (c).

I will use a slightly different notation.

- (a) Let $\mathbf{w}_1 = \begin{bmatrix} -1 & 0 \end{bmatrix}$ and $\mathbf{w}_2 = \begin{bmatrix} 0 & 1 \end{bmatrix}$. Show $\mathbf{x}_1 = \begin{bmatrix} 1 & 1 \end{bmatrix}$ to the network. We have $\|\mathbf{w}_1 \mathbf{x}_1\| = \sqrt{5}$ and $\|\mathbf{w}_2 \mathbf{x}_1\| = 1$. So, the second neuron wins, and its weights are updated as $\mathbf{w}_2 \leftarrow \mathbf{w}_2 + \frac{1}{2}(\mathbf{x}_1 \mathbf{w}_2) = \frac{1}{2}(\mathbf{x}_1 + \mathbf{w}_2) = \begin{bmatrix} 0.5 & 1 \end{bmatrix}$. The weight \mathbf{w}_1 remains the same.
 - Now, show $\mathbf{x}_2 = \begin{bmatrix} 2 & 1 \end{bmatrix}$ to the network. We have $\|\mathbf{w}_1 \mathbf{x}_2\| = \sqrt{10}$ and $\|\mathbf{w}_2 \mathbf{x}_2\| = \sqrt{(2-0.5)^2 + (1-1)^2} = 1.5$ (note that we are using the updated weights). So, again, the second neuron wins, and its weights are updated as $\mathbf{w}_2 \leftarrow \frac{1}{2}(\mathbf{x}_2 + \mathbf{w}_2) = \frac{1}{2}(\begin{bmatrix} 2 & 1 \end{bmatrix} + \begin{bmatrix} 0.5 & 1 \end{bmatrix}) = \begin{bmatrix} 1.25 & 1 \end{bmatrix}$.
 - Show $\mathbf{x}_3 = \begin{bmatrix} -1 & -1 \end{bmatrix}$ to the network. We have $\|\mathbf{w}_1 \mathbf{x}_3\| = 1$ and $\|\mathbf{w}_2 \mathbf{x}_3\| = \sqrt{(1.25+1)^2 + (1+1)^2} > 1$. So, the first neuron wins, and its weights are updated as $\mathbf{w}_1 \leftarrow \frac{1}{2}(\mathbf{x}_3 + \mathbf{w}_1) = \begin{bmatrix} -1 & -0.5 \end{bmatrix}$
 - Hence, after one epoch of training, the updated weights are $\mathbf{w}_{1,3} = \begin{bmatrix} -1 & -0.5 \end{bmatrix}$ and $\mathbf{w}_{2,3} = \begin{bmatrix} 1.25 & 1 \end{bmatrix}$.
- (b) First observe that in all later epochs, the second neuron will be the winner for patterns \mathbf{x}_1 and \mathbf{x}_2 , and the first neuron will be the winner for pattern \mathbf{x}_3 . It then easily follows that $\lim_{n\to\infty}\mathbf{w}_{1,n}=\mathbf{x}_3$. Consider now the weights of the second neuron. The y-component will always remain equal to 1. The x-component at the end of the first epoch was equal to 1.25. At the second epoch, when \mathbf{x}_1 is shown, the x-component will be updated to $\frac{1+1.25}{2}=1.125$. Then, when \mathbf{x}_2 is shown, the x-component will be updated to $\frac{2+1.125}{2}$. This defines the sequence $1.25, 1.125, 1.5625, \ldots$ where we sequentially apply the functions $x\mapsto \frac{1+x}{2}$ and $x\mapsto \frac{2+x}{2}$ to the initial value 1.25. It is not difficult to show that the sequence converges to the "oscillatory limit" $\frac{5}{3}, \frac{4}{3}, \frac{5}{3}, \frac{4}{3}, \ldots$ Hence, $\lim_{n\to\infty}\mathbf{w}_{2,n}$ does not exist. Instead, $\mathbf{w}_{2,n}$ oscillates between the points $\left[\frac{4}{3} \quad 1\right]$ and $\left[\frac{5}{3} \quad 1\right]$.
- (c) Let $\mathbf{w}_1 = \begin{bmatrix} -1 & 0 \end{bmatrix}$ and $\mathbf{w}_2 = \begin{bmatrix} 0 & 1 \end{bmatrix}$. Show $\mathbf{x}_1 = \begin{bmatrix} 1 & 1 \end{bmatrix}$ to the network. We have $\|\mathbf{w}_1 \mathbf{x}_1\| = \sqrt{5}$ and $\|\mathbf{w}_2 \mathbf{x}_1\| = 1$. So, the second neuron wins, and its weights are updated as $\mathbf{w}_2 \leftarrow \lfloor \mathbf{w}_2 + \frac{1}{2}(\mathbf{x}_1 \mathbf{w}_2) \rfloor = \begin{bmatrix} 0 & 1 \end{bmatrix}$. The weight \mathbf{w}_1 remains the same.
 - Now, show $\mathbf{x}_2 = \begin{bmatrix} 2 & 1 \end{bmatrix}$ to the network. We have $\|\mathbf{w}_1 \mathbf{x}_2\| = \sqrt{10}$ and $\|\mathbf{w}_2 \mathbf{x}_2\| = 2$. The second neuron wins, and its weights are updated as $\mathbf{w}_2 \leftarrow \lfloor \frac{1}{2}(\mathbf{x}_2 + \mathbf{w}_2) \rfloor = \lfloor \begin{bmatrix} 1 & 1 \end{bmatrix} \rfloor = \begin{bmatrix} 1 & 1 \end{bmatrix}$.
 - Show $\mathbf{x}_3 = \begin{bmatrix} -1 & -1 \end{bmatrix}$ to the network. We have $\|\mathbf{w}_1 \mathbf{x}_3\| = 1$ and $\|\mathbf{w}_2 \mathbf{x}_3\| = \sqrt{8}$. So, the first neuron wins, and its weights are updated as $\mathbf{w}_1 \leftarrow \lfloor \frac{1}{2}(\mathbf{x}_3 + \mathbf{w}_1) \rfloor = \lfloor -1 & -0.5 \rfloor \rfloor = \lfloor -1 & -1 \rfloor$.
 - Hence, after one epoch of training, the updated weights are $\mathbf{w}_{1,3} = \begin{bmatrix} -1 & -1 \end{bmatrix}$ and $\mathbf{w}_{2,3} = \begin{bmatrix} 1 & 1 \end{bmatrix}$.
- (d) It is easy to see that there will be no more updates on the weights and we have $\lim_{n\to\infty} \mathbf{w}_{1,n} = \mathbf{x}_3$ and $\lim_{n\to\infty} \mathbf{w}_{2,n} = \mathbf{x}_1$.