```
In [ ]: import os
        small dataset = ['CNV', 'DME', 'DRUSEN', 'NORMAL']
        small dataset dir = '/lambda/nfs/main-filesystem/OCT by class' ## change this based on your own google driv
        #small dataset dir = '/content/drive/MyDrive/Third Year/Summer/APS360/APS360 Project - Group 7/Code/small (
        #small dataset dir = '/content/drive/MyDrive/APS360 Project - Group 7/Code/small dataset'
In [ ]: def num images(dir, folders):
            print(f"Number of images in each folder:")
            for folder in folders:
                path = os.path.join(dir, folder)
                if os.path.isdir(path):
                    num files = len(os.listdir(path))
                    print(f"{folder}: {num files}")
                else:
                    print(f"Folder '{folder}' does not exist in the dataset directory.")
In [ ]: | num_images(small_dataset_dir, small_dataset)
       Number of images in each folder:
       CNV: 3000
       DME: 3000
       DRUSEN: 3000
       NORMAL: 3000
In [ ]: import numpy as np
        import torch
        device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
In []: from torchvision import models, transforms, datasets
        from torch import nn
        resnet model = models.resnet152(pretrained=True)
        resnet model = nn.Sequential(*list(resnet model.children())[:-1]) # remove last classification layers
        resnet model.to(device)
        resnet model.eval()
```

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In [ ]: from PIL import Image
        import cv2
        import numpy as np
        import torch
        def local_binary_pattern(image, P, R): # manual LBP function because LBP package from scikit-learn was not
            height, width = image.shape
            lbp = np.zeros like(image, dtype=np.uint8)
            for i in range(R, height - R):
                for j in range(R, width - R):
                    center pixel = image[i, j]
                    binary code = []
                    for p in range(P):
                        theta = 2 * np.pi * p / P
                        x = int(i + R * np.cos(theta))
                        y = int(j - R * np.sin(theta))
                        if image[x, y] >= center_pixel:
                            binary code.append(1)
                        else:
                            binary code.append(0)
                    lbp[i, j] = sum([binary_code[k] * (2**k) for k in range(len(binary_code))])
            return lbp
        def extract texture and edges(image path):
            img = cv2.imread(image_path, cv2.IMREAD_GRAYSCALE)
            # edge detection using Sobel filter, https://how.dev/answers/sobel-operator-in-digital-image-processing
            sobel_x = cv2.Sobel(img, cv2.CV_64F, 1, 0, ksize=3) # Sobel in x-direction
            sobel_y = cv2.Sobel(img, cv2.CV_64F, 0, 1, ksize=3) # Sobel in y-direction
            edges = np.hypot(sobel x, sobel y) # combine gradients
            # https://scikit-image.org/docs/0.25.x/auto examples/features detection/plot local binary pattern.html
            lbp = local_binary_pattern(img, P=8, R=1) # texture descriptors using Uniform Local Binary Pattern (LL
            edges flat = edges.flatten()
            lbp flat = lbp.flatten()
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combined features = np.concatenate((edges flat, lbp flat), axis=0) # combine all features
            return combined features
        def extract features(image path, model, transform, device):
            image = Image.open(image path).convert('RGB') # convert to rgb because resnet works with rgb
            image = transform(image).unsqueeze(0)
            image = image.to(device)
            with torch.no grad():
                features = model(image) # extract features from resnet
                features = features.view(features.size(0), -1) # flatten to vector
            return features.cpu().numpy() # convert to numpy for svm
        def extract combined features(image path, resnet model, transform, device):
            resnet features = extract features(image path, resnet model, transform)
            texture edge features = extract texture and edges(image path)
            # combine features (flatten resnet + texture/edge)
            combined features = np.concatenate((resnet features.flatten(), texture edge features), axis=0)
            return combined_features
In [ ]: data transform = transforms.Compose([
            transforms.Resize((224, 224)),
            transforms.ToTensor(),
            transforms.Normalize(mean=[0.485, 0.456, 0.406], std=[0.229, 0.224, 0.225]) # normalization for resnet
        1)
        dataset = datasets.ImageFolder(small dataset dir, transform=data transform)
In [ ]: import os
        import torch
        import numpy as np
        from tgdm import tgdm
        device = torch.device("cuda" if torch.cuda.is available() else "cpu")
        features = []
        labels = []
```

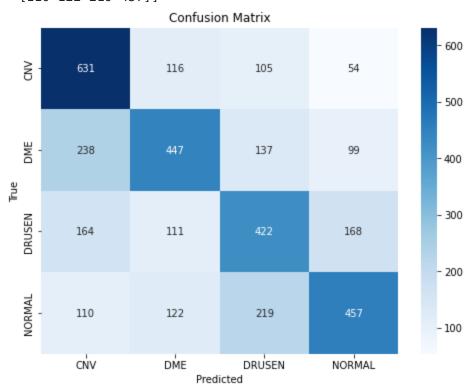
```
# extract features in batches to save RAM
batch size = 256
diseases = os.listdir(small dataset dir)
for disease in diseases:
    disease dir = os.path.join(small dataset dir, disease)
    image paths = [
        os.path.join(disease_dir, img) for img in os.listdir(disease_dir)
        if os.path.isfile(os.path.join(disease dir, img))
    1
   for i in tqdm(range(0, len(image_paths), batch_size), desc=f"Processing {disease} Images", leave=False
        batch_paths = image_paths[i:i+batch_size]
        batch features = []
       batch_labels = []
        for image path in batch paths:
            resnet feature = extract features(image path, resnet model, data transform, device)
            texture edge feature = extract texture and edges(image path)
            combined_features = np.concatenate((resnet_feature.flatten(), texture_edge_feature), axis=0)
            batch features.append(combined features)
            batch labels.append(disease)
        features.extend(batch features)
        labels.extend(batch labels)
        torch.cuda.empty cache()
features = np.array(features)
labels = np.array(labels)
```

```
In []: from sklearn.svm import SVC
    from sklearn.model_selection import train_test_split
    from sklearn.metrics import accuracy_score, confusion_matrix, classification_report, roc_curve, auc
    import matplotlib.pyplot as plt
    import seaborn as sns
    from sklearn.preprocessing import StandardScaler
```

```
from sklearn.decomposition import PCA
        from sklearn.model selection import train test split
        X_train, X_test, y_train, y_test = train_test_split(features, labels, test_size=0.3, random_state=42) # sp
        scaler = StandardScaler()
        X train scaled = scaler.fit transform(X train)
        X test scaled = scaler.transform(X test)
In [ ]: pca = PCA(n components=20)
        X_train_pca = pca.fit_transform(X_train_scaled)
        X_test_pca = pca.transform(X_test_scaled)
In []: svm rbf = SVC(kernel='rbf', C=10, gamma='scale', class weight='balanced') # rbf based on proposal
In [ ]: svm_rbf.fit(X_train_pca, y_train)# train SVM
Out[]:
         ▼ SVC <sup>1</sup>
         ► Parameters
In [ ]: y_pred = svm_rbf.predict(X_test_pca)
In [ ]: # accuracy test
        accuracy = accuracy score(y test, y pred)
        print(f"Accuracy: {accuracy:.4f}")
       Accuracy: 0.5436
In []: # confusion matrix test
        cm = confusion_matrix(y_test, y_pred)
        print(f"Confusion Matrix:\n{cm}")
        plt.figure(figsize=(8, 6))
        sns.heatmap(cm, annot=True, fmt='d', cmap='Blues', xticklabels=diseases, yticklabels=diseases)
        plt.xlabel('Predicted')
        plt.ylabel('True')
```

```
plt.title('Confusion Matrix')
plt.show()
```

```
Confusion Matrix:
[[631 116 105 54]
[238 447 137 99]
[164 111 422 168]
[110 122 219 457]]
```



```
In []: report = classification_report(y_test, y_pred, target_names=diseases)
print(f"Classification Report:\n{report}")
```

Classification Report: precision

	precision	recall	f1-score	support
CNV DME DRUSEN	0.55 0.56 0.48	0.70 0.49 0.49	0.62 0.52 0.48	906 921 865
NORMAL	0.59	0.50	0.54	908
accuracy	0.54	0.54	0.54	3600
macro avg weighted avg	0.54 0.55	0.54 0.54	0.54 0.54	3600 3600