

## Research Objective

- Generative models (e.g. **ChatGPT**, **DALLE-2**) produce samples from a learned distribution
- Evaluation metrics for generative models compare  $p$ , the ground truth distribution, to  $q$ , the learned distribution
- Current metrics are approximate, insensitive to nuances in failures, and task-specific. **Better metrics**  $\rightarrow$  **better models**
- Propose new evaluation metric with **statistical guarantees** in high-dim. probability space settings  $|\Omega| \geq 10^9$  [1] which is **scalable**, **robust** to mismatches in  $p, q$  and provides **interpretable results**
- Synthetic experiments are conducted to verify claims. Current experiments in **protein sequence modeling**

## Introduction

### Problem Statement

- Given  $p$  evaluate **which generative model**  $q_1, q_2$  **is closer to**  $p$
- Closeness classically determined by total variation error  $d_{TV} = \frac{1}{2} ||p - q||$  but estimating  $d_{TV}$  scales with  $|\Omega|$ . (Intractable for many machine learning applications) [2]

### Existing Evaluation Metrics

- Negative Log-Likelihood**: not always accessible, doesn't guarantee good sample generation [3]
- Task-oriented**: good sample evaluation but not general [4]
- Coverage-based**: compares distribution coverage,  $p, q$ , does not consider sample complexity or stat. significance [5] [6]

### Proposed Method

- Partition**  $\Omega$  into smaller spaces called **bins** of size  $k$ ,  $\mathcal{B}^k$ , and perform statistical tests on the smaller probability distributions,  $p^{\mathcal{B}^k}$ , on these smaller spaces  $\mathcal{B}^k$

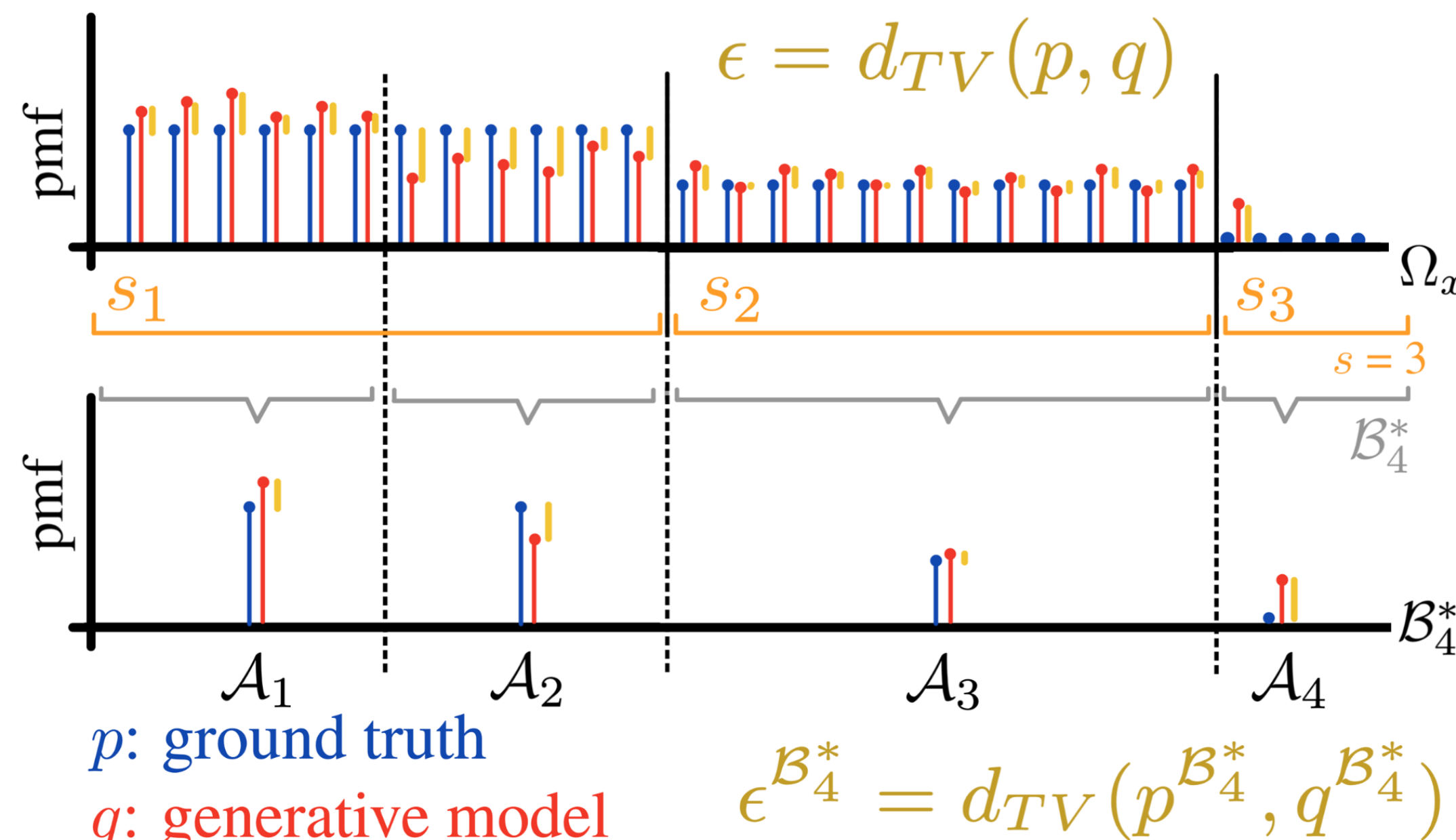


Figure 1: Overview of Proposed Procedure [1]

## Methodology

**Preliminaries:**  $\Omega$  is partitioned into bins of size  $k$  inducing new probability distributions on the smaller partitions

$$\rho(\Omega) = \{\{\mathcal{A}_1, \dots\} \mid \cup_i \mathcal{A}_i = \Omega, \mathcal{A}_j \cap \mathcal{A}_i = \emptyset \forall i \neq j\}$$

$$\rho^k(\Omega) = \{\mathcal{B} \in \rho(\Omega), |\mathcal{B}| = k\}$$

$$p_{\mathcal{A}_i}^{\mathcal{B}^k} \triangleq \sum_{x \in \mathcal{A}_i} p_x$$

By the triangle inequality,  $d_{TV}$  is constrained and increases with the granularity  $|\mathcal{B}|$ .

$$\mathcal{B} \in \rho(\Omega) \implies d_{TV}^{(p^{\mathcal{B}}, q^{\mathcal{B}})} \leq d_{TV}^{(p, q)}$$

$$d_{TV}(p^{\mathcal{B}^{i-1}}, q^{\mathcal{B}^{i-1}}) \leq d_{TV}(p^{\mathcal{B}^i}, q^{\mathcal{B}^i}) \dots \leq d_{TV}(p, q)$$

**Binning:** Bin the space, identifying sets where the masses associated with any two elements in the set do not differ by much.

**Setting an Error Tolerance:** Error tolerance  $\epsilon_{test}$  is a function of the cardinality of the probability space  $|\mathcal{B}|$ , number of samples  $m$ , and probability significance  $\delta$ . Given a set of  $m$  samples from  $q$  ( $\{\tilde{x}_i\}_{i=1}^m, \tilde{x}_i \sim q$ ), the empirical total variation estimator  $B^m$  is estimated as follows:

$$d_{TV}(p, \tilde{q}) \triangleq B^m = \frac{1}{2} \sum_{x \in \Omega} |p_x - \tilde{q}_x|, \text{ where } \tilde{q}_x = \frac{1}{m} \sum_{i=1}^m \mathbb{1}[\tilde{x}_i = x].$$

Provided that

$$\epsilon_{test} \geq \max\left(\sqrt{\frac{|\mathcal{B}|}{m}}, \sqrt{\frac{2 \ln(2/\delta)}{m}}\right),$$

we can be at least  $1 - \delta$  confident that the true total variation  $d_{TV}(p, q)$  is within the interval  $[B^m - \epsilon_{test}, B^m + \epsilon_{test}]$

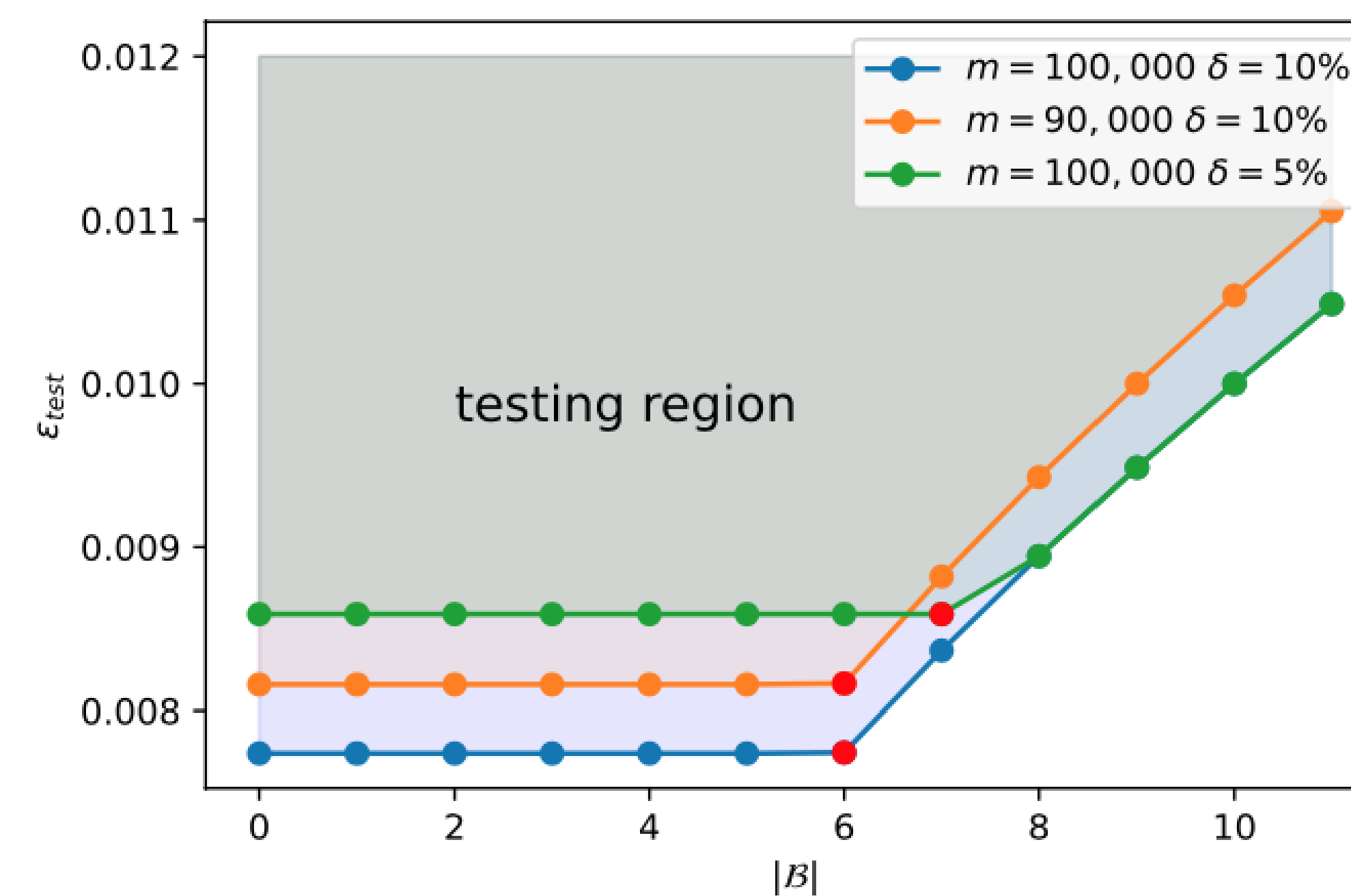


Figure 2: Error threshold that we can obtain over varying  $k = |\mathcal{B}|$ ,  $\delta$  and  $m$ .

### Evaluation Procedure

- If we have e.g.  $d_{TV}(p^{\mathcal{B}^i}, q_1^{\mathcal{B}^i}) \leq \epsilon_{thresh}$ , but model  $q_2$  is not:  $d_{TV}(p^{\mathcal{B}^i}, q_2^{\mathcal{B}^i}) \geq \epsilon_{thresh}$ , we can say  $q_1$  is better than  $q_2$  in  $\mathcal{B}^i$ .

## Results

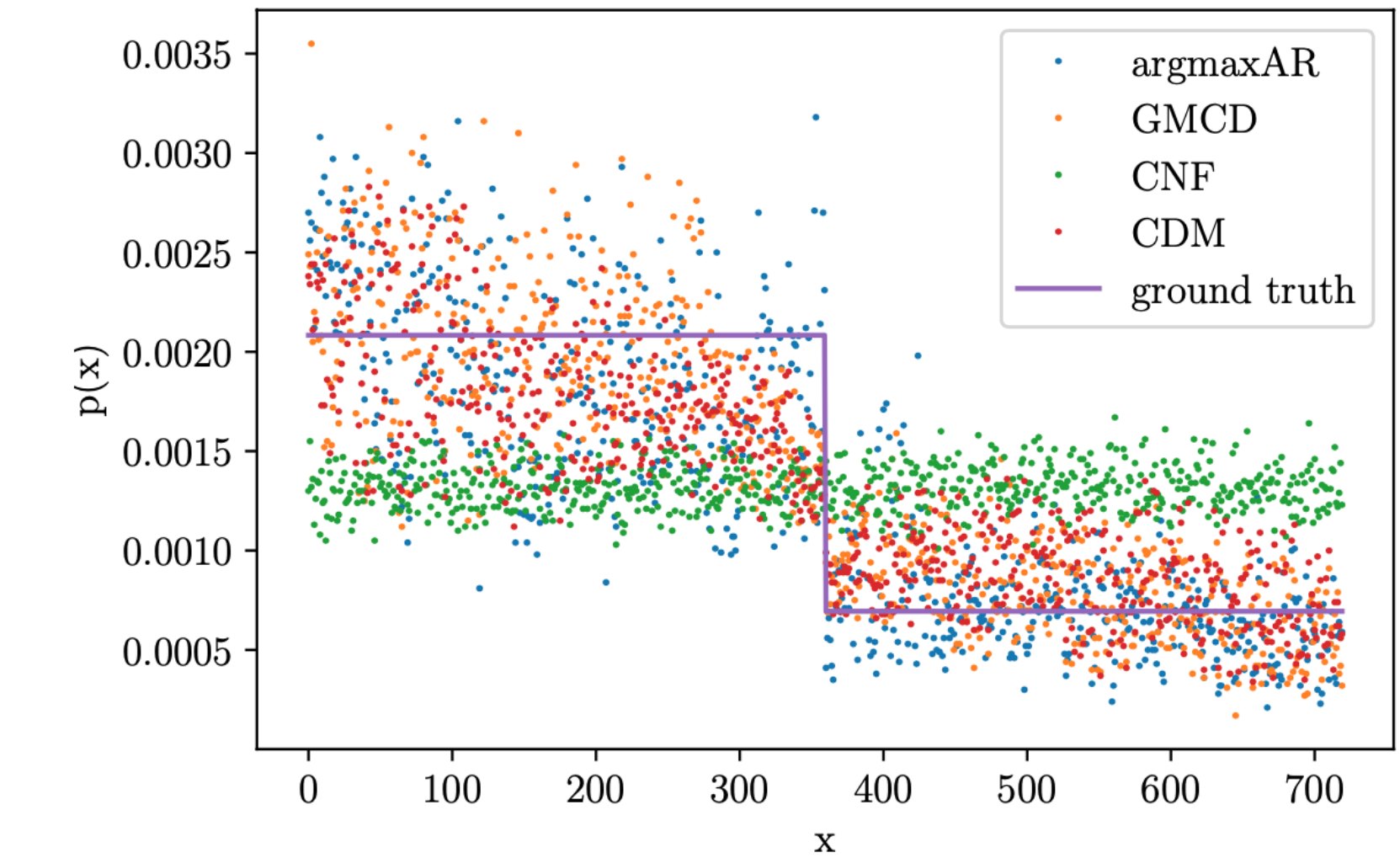


Figure 3: Empirical pmf  $q$  ( $m = 100,000$ ) of generative models on  $\Omega^+$  with sorted ground truth. Only 700 samples are non-zero. 10k samples are used for model training. 10k samples are used for model testing.

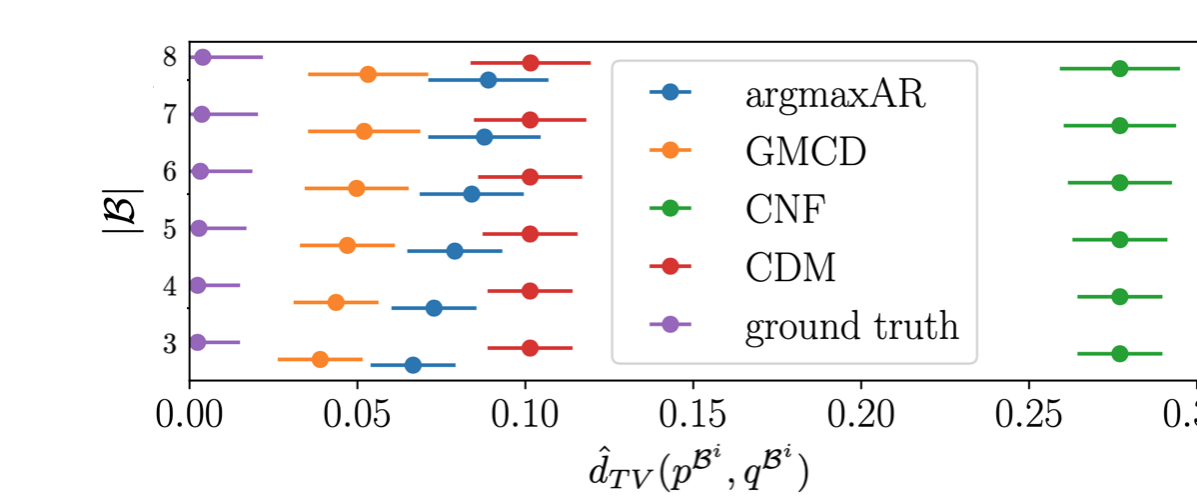


Figure 4:  $d_{TV}(p^{\mathcal{B}^i}, q^{\mathcal{B}^i})$  metric reported for the generative models. Left leaning means better performance.

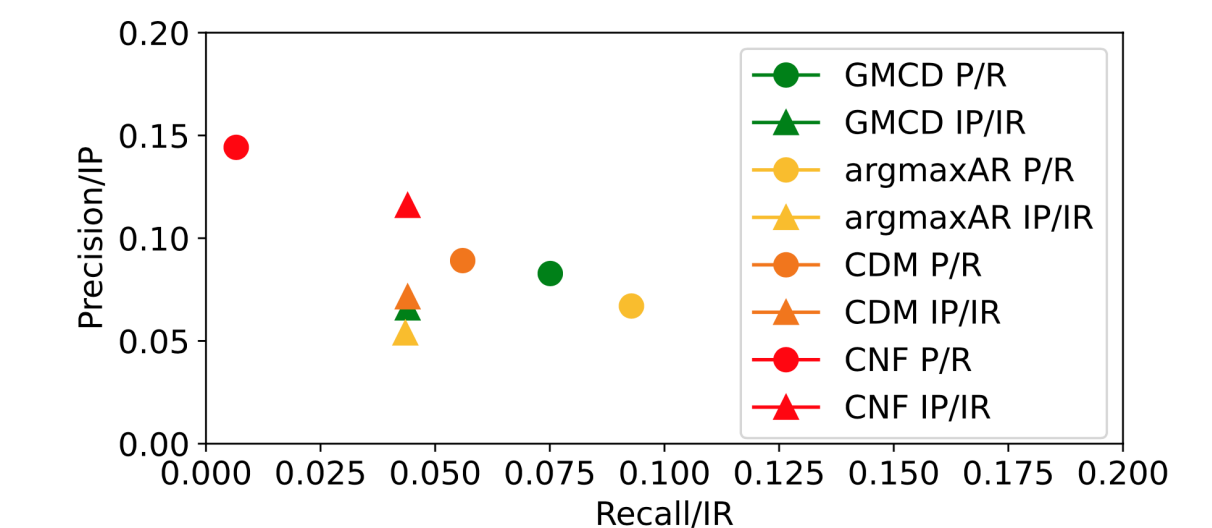


Figure 5: Coverage-based metrics, precision, recall,  $IP_\alpha$ ,  $IR_\beta$  for generative models [5] [6]

### Discussion

- Figure 4 provides interpretable understanding  $\rightarrow$  models closer to the ground truth are better models
- Figure 5 provides the less interpretable existing coverage metrics  $\rightarrow$  no clear better model

## Conclusion

- The proposal provides **interpretable results** with **statistical guarantees**, is **scalable to high dimensions** and offers a comparative performance evaluation.
- Current and future work** involves applying the proposed metric to the real-task of **protein sequence modelling** on the order of  $|\Omega| = 21^{100}$  (21 amino acids and sequence length 100).

## References

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