Convex functions

The **domain** dom f of a functional $f: \mathbb{R}^N \to \mathbb{R}$ is the subset of \mathbb{R}^N where f is well-defined.

A function(al) f is **convex** if dom f is a convex set, and

$$f(\theta x + (1 - \theta)y) \le \theta f(x) + (1 - \theta)f(y)$$

for all $\boldsymbol{x}, \boldsymbol{y} \in \text{dom } f \text{ and } 0 \leq \theta \leq 1$.

f is **concave** if -f is convex.

f is **strictly convex** if dom f is convex and

$$f(\theta \boldsymbol{x} + (1 - \theta)\boldsymbol{y}) < \theta f(\boldsymbol{x}) + (1 - \theta)f(\boldsymbol{y})$$

for all $\boldsymbol{x} \neq \boldsymbol{y} \in \text{dom } f \text{ and } 0 < \theta < 1.$

The domain matters. For example,

$$f(x) = x^3$$

is convex if dom $f = \mathbb{R}_+ = [0, \infty]$ but not if dom $f = \mathbb{R}$.

We define the **extension** of f from dom f to all of \mathbb{R}^N as

$$\tilde{f}(\boldsymbol{x}) = f(\boldsymbol{x}), \quad \boldsymbol{x} \in \text{dom } f, \quad \tilde{f}(\boldsymbol{x}) = +\infty, \quad \boldsymbol{x} \not\in \text{dom } f.$$

If f is convex on dom f, then its extension is also convex on \mathbb{R}^N .

Here are some standard examples for functions on \mathbb{R} :

- affine functions f(x) = ax + b are both convex and concave for $a, b \in \mathbb{R}$,
- exponentials $f(X) = e^{ax}$ are convex for all $a \in \mathbb{R}$,
- powers x^{α} are convex on \mathbb{R}_+ for $\alpha \geq 1$, concave for $0 \leq \alpha \leq 1$, and convex for $\alpha \leq 0$,
- $|x|^{\alpha}$ is convex on all of \mathbb{R} for $\alpha \geq 1$.
- the entropy function $x \log x$ is concave on \mathbb{R}_{++} ,
- logarithms: $\log x$ is concave on \mathbb{R}_{++} .

Here are some standard examples for functionals on \mathbb{R}^N :

- affine functions $f(\mathbf{x}) = \langle \mathbf{x}, \mathbf{a} \rangle + b$ are both convex and concave on all of \mathbb{R}^N ,
- any valid norm $f(\boldsymbol{x}) = \|\boldsymbol{x}\|$ is convex on all of \mathbb{R}^N
- etc

A functional $f: \mathbb{R}^N \to R$ is convex if and only if the function $g_v: \mathbb{R} \to \mathbb{R}$,

$$g_v(t) = f(\boldsymbol{x} + t\boldsymbol{v}), \quad \text{dom } g = \{t : \boldsymbol{x} + t\boldsymbol{v} \in \text{dom } f\}$$

is convex for every $\boldsymbol{x} \in \text{dom } f, \, \boldsymbol{v} \in \mathbb{R}^N$.

Example: Let $f(\mathbf{X}) = -\log \det \mathbf{X}$ with dom $f = S_{++}^N$. For any $\mathbf{X} \in S_{++}^N$, we know that

$$\boldsymbol{X} = \boldsymbol{U}\boldsymbol{\Lambda}\boldsymbol{U}^{\mathrm{T}},$$

for some diagonal, positive Λ , so we can define

$$\boldsymbol{X}^{1/2} = \boldsymbol{U} \boldsymbol{\Lambda}^{1/2} \boldsymbol{U}^{\mathrm{T}}, \quad \text{and} \quad \boldsymbol{X}^{-1/2} = \boldsymbol{U} \boldsymbol{\Lambda}^{-1/2} \boldsymbol{U}^{\mathrm{T}}.$$

Now consider

$$g_{V}(t) = -\log \det(\boldsymbol{X} + t\boldsymbol{V}) = -\log \det(\boldsymbol{X}^{1/2}(\boldsymbol{I} + t\boldsymbol{X}^{-1/2}\boldsymbol{V}\boldsymbol{X}^{-1/2})\boldsymbol{X}^{1/2})$$

$$= -\log \det \boldsymbol{X} - \log \det(\boldsymbol{I} + t\boldsymbol{X}^{-1/2}\boldsymbol{V}\boldsymbol{X}^{-1/2})$$

$$= -\log \det \boldsymbol{X} - \sum_{n=1}^{N} \log(1 + \sigma_{i}t),$$

where the σ_i are the (positive) eigenvalues of $\boldsymbol{X}^{-1/2}\boldsymbol{V}\boldsymbol{X}^{-1/2}$. The function $-\log(1+\sigma_i t)$ is convex, so the above is a sum of convex functions, which is convex.

First-order conditions for convexity

We say that f is **differentiable** if dom f is an open set (all of \mathbb{R}^N , for example), and the gradient

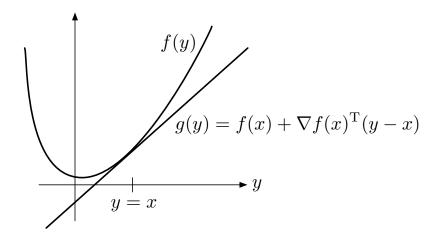
$$abla f(oldsymbol{x}) = egin{bmatrix} rac{\partial f(oldsymbol{x})}{\partial x_1} \ rac{\partial f(oldsymbol{x})}{\partial x_2} \ dots \ rac{\partial f(oldsymbol{x})}{\partial x_N} \end{bmatrix}$$

exists for each $x \in \text{dom } f$.

If f is differentiable, then it is convex if and only if

$$f(\boldsymbol{y}) \geq f(\boldsymbol{x}) + \nabla f(\boldsymbol{x})^{\mathrm{T}}(\boldsymbol{y} - \boldsymbol{x})$$
 (1)

for all $\boldsymbol{x}, \boldsymbol{y} \in \text{dom } f$.



This means that the linear approximation $g(\boldsymbol{y}) = f(\boldsymbol{x}) + \nabla f(\boldsymbol{x})^{\mathrm{T}}(\boldsymbol{y} - \boldsymbol{x})$ is a **global underestimator** of $f(\boldsymbol{y})$.

It is easy to show that f convex, differentiable \Rightarrow (1). Since f is convex,

$$f(\boldsymbol{x} + t(\boldsymbol{y} - \boldsymbol{x})) \leq (1 - t)f(\boldsymbol{x}) + tf(\boldsymbol{y}), \quad 0 \leq t \leq 1,$$

and so

$$f(\boldsymbol{y}) \geq f(\boldsymbol{x}) + \frac{f(\boldsymbol{x} + t(\boldsymbol{y} - \boldsymbol{x})) - f(\boldsymbol{x})}{t}, \quad \forall 0 < t \leq 1.$$

Taking the limit as $t \to 0$ on the right yields (1).

It is also true that $(1) \Rightarrow f$ convex. For a proof, see [BV04, p. 70].

Second-order conditions for convexity

We say that $f: \mathbb{R}^N \to \mathbb{R}$ is **twice differentiable** if dom f is an open set, and the $N \times N$ Hessian matrix

$$\nabla^2 f(\boldsymbol{x}) = \begin{bmatrix} \frac{\partial^2 f(\boldsymbol{x})}{\partial x_1^2} & \frac{\partial^2 f(\boldsymbol{x})}{\partial x_1 \partial x_2} & \cdots & \frac{\partial^2 f(\boldsymbol{x})}{\partial x_1 \partial x_N} \\ \vdots & \ddots & & \vdots \\ \frac{\partial^2 f(\boldsymbol{x})}{\partial x_N \partial x_1} & \cdots & \frac{\partial^2 f(\boldsymbol{x})}{\partial x_N^2} \end{bmatrix}$$

exists for every $x \in \text{dom } f$.

If f is twice differentiable, then it is convex if and only if

$$\nabla^2 f(\boldsymbol{x}) \succeq \mathbf{0}$$
 (i.e. $\nabla^2 f(\boldsymbol{x}) \in S_+^N$).

for all $x \in \text{dom } f$. It is strictly convex if an only if

$$\nabla^2 f(\boldsymbol{x}) \succ \mathbf{0}$$
 (i.e. $\nabla^2 f(\boldsymbol{x}) \in S_{++}^N$).

You will prove this on the next homework.

Standard examples (from [BV04]) Quadratic functionals:

$$f(\boldsymbol{x}) = \frac{1}{2} \boldsymbol{x}^{\mathrm{T}} \boldsymbol{P} \boldsymbol{x} + \boldsymbol{q}^{\mathrm{T}} \boldsymbol{x} + r,$$

where \boldsymbol{P} is symmetric, has

$$abla f(\boldsymbol{x}) = \boldsymbol{P} \boldsymbol{x} + \boldsymbol{q}, \quad
abla^2 f(\boldsymbol{x}) = \boldsymbol{P},$$

so $f(\boldsymbol{x})$ is convex iff $\boldsymbol{P} \succeq \boldsymbol{0}$.

Least-squares:

$$f(\boldsymbol{x}) = \|\boldsymbol{A}\boldsymbol{x} - \boldsymbol{b}\|_2^2,$$

where \boldsymbol{A} is an arbitrary $M \times N$ matrix, has

$$\nabla f(\boldsymbol{x}) = 2\boldsymbol{A}^{\mathrm{T}}(\boldsymbol{A}\boldsymbol{x} - \boldsymbol{b}), \quad \nabla^2 f(\boldsymbol{x}) = 2\boldsymbol{A}^{\mathrm{T}}\boldsymbol{A},$$

and is convex for any \boldsymbol{A} .

Quadratic-over-linear: In \mathbb{R}^2 , if

$$f(\boldsymbol{x}) = x_1^2 / x_2,$$

then

$$\nabla f(\boldsymbol{x}) = \begin{bmatrix} 2x_1/x_2 \\ -x_1^2/x_2^2 \end{bmatrix}, \quad \nabla^2 f(\boldsymbol{x}) = \frac{2}{x_2^3} \begin{bmatrix} x_2^2 & -x_1x_2 \\ -x_1x_2 & x_1 \end{bmatrix}$$

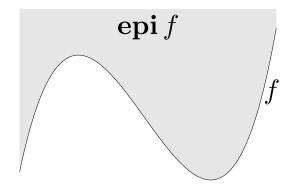
$$= \frac{2}{x_2^3} \begin{bmatrix} x_2 \\ -x_1 \end{bmatrix} \begin{bmatrix} x_2 & -x_1 \end{bmatrix},$$

and so f is convex on $[0, \infty] \times \mathbb{R}$ $(x_1 \ge 0, x_2 \in \mathbb{R})$.

Epigraph

The *epigraph* of a functional $f: \mathbb{R}^N \to \mathbb{R}$ is the subset of \mathbb{R}^{N+1} created by filling in the space above f:

$$\operatorname{epi} f = \left\{ \begin{bmatrix} \boldsymbol{x} \\ t \end{bmatrix} \in \mathbb{R}^{N+1} \ : \ \boldsymbol{x} \in \operatorname{dom} f, \ f(\boldsymbol{x}) \leq t \right\}.$$



f is convex if and only if epi f is a convex set.

The gradient of f at \boldsymbol{x} , when it exists, is a supporting hyperplane of epi f at $\begin{bmatrix} \boldsymbol{x} \\ f(\boldsymbol{x}) \end{bmatrix}$.

References

[BV04] S. Boyd and L. Vandenberghe. *Convex Optimization*. Cambridge University Press, 2004.