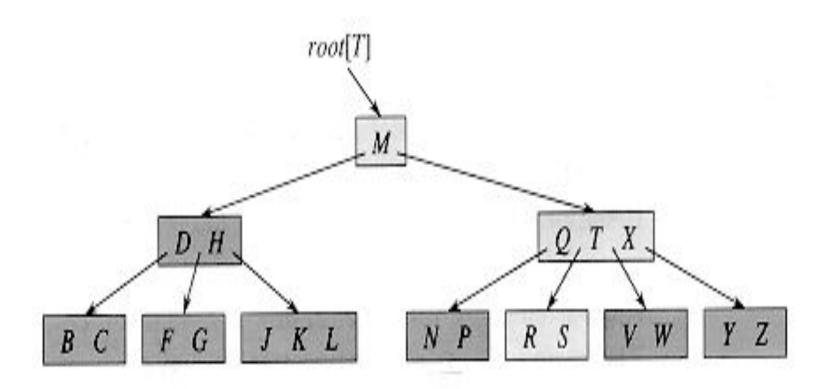


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 B-trees are balanced search trees designed to work well on magnetic disks or other direct-access secondary storage devices.





# Properties of B Tree

- A **B-tree** T is a rooted tree (with root root[T]) having the following properties.
- 1. Every node *x* has the following fields:
  - a. n[x], the number of keys currently stored in node x,
  - b. the n[x] keys themselves, stored in nondecreasing order:  $key_1[x] \le key_2[x] \le \dots \le key_n[x]$
  - c. *leaf* [x], a boolean value that is TRUE if x is a leaf and FALSE if x is an internal node.
- 2. If x is an internal node, it also contains n[x] + 1 pointers  $c_1[x]$ ,  $c_2[x]$ , ...,  $c_n[x] + 1[x]$  to its children. Leaf nodes have no children, so their  $c_i$  fields are undefined.
- 3. The keys  $key_i[x]$  separate the ranges of keys stored in each subtree: if  $k_i$  is any key stored in the subtree with root  $c_i[x]$ , then

$$k_1 \le key_1[x] \le k_2 \le key_2[x] \le \dots \le key_{n[x]}[x] \le k_n[x] + 1$$
.



# Properties of B Tree

- 4. Every leaf has the same depth, which is the tree's height h.
- 5. There are lower and upper bounds on the number of keys a node can contain. These bounds can be expressed in terms of a fixed integer t >= 2 called the **minimum degree** of the B-tree:
  - a. Every node other than the root must have at least t 1 keys. Every internal node other than the root thus has at least t children. If the tree is nonempty, the root must have at least one key.
  - b. Every node can contain at most 2t 1 keys. Therefore, an internal node can have at most 2t children. We say that a node is **full** if it contains exactly 2t 1 keys.

.







#### B Tree Search

#### B-TREE-SEARCH(x, k)

$$1 i = 1$$

2 while  $i \le n[x]$  and  $k \le key_i[x]$ 

3 do 
$$i = i + 1$$

4 if 
$$i \le n[x]$$
 and  $k = key_i[x]$ 

5 then return (x, i)

7 then return NIL

8 else DISK-READ( $c_i[x]$ )

9 return B-TREE-SEARCH( $c_i[x], k$ )



# Creating an empty B-tree

#### B-TREE-CREATE(*T*)

$$1 x = ALLOCATE-NODE()$$

$$2 leaf[x] = TRUE$$

$$3 n[x] = 0$$

4 DISK-WRITE(
$$x$$
)

$$5 \ root[T] = x$$



# Splitting a node in a B-tree

#### B-TREE-SPLIT-CHILD(x,i,y)

- 1 z = ALLOCATE-NODE()
- $2 ext{leaf}[z] = ext{leaf}[y]$
- $3 \ n[z] = t 1$
- 4 **for** j = 1 **to** t 1
- $\mathbf{do} \ key_{j}[z] = key_{j+t}[y]$
- 6 **if** not leaf[y]
- 7 then for j = 1 to t
- 8 **do**  $c_{i}[z] = c_{i+t}[y]$
- 9 n[y] = t 1
- 10 **for** j = n/x/ + 1 **downto** i + 1
- 11 **do**  $c_{j+1}[x] = c_j[x]$



### Splitting a node in a B-tree

```
12 c_{i+1}[x] = z

13 for j = n[x] downto i

14 do key_{j+1}[x] = key_{j}[x]

15 key_{i}[x] = key_{t}[y]

16 n[x] = n[x] + 1

17 DISK-WRITE(y)

18 DISK-WRITE(z)

19 DISK-WRITE(x)
```



# Inserting a key into a B-tree

#### B-TREE-INSERT(*T,k*)

$$1 r = root[T]$$

$$2 \text{ if } n[r] = 2t - 1$$

3 **then** 
$$s = ALLOCATE-NODE()$$

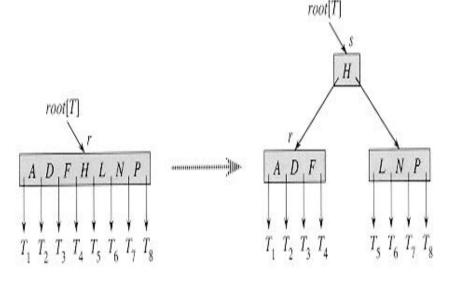
4 
$$root[T] = s$$

$$5 leaf[s] = FALSE$$

6 
$$n[s] = 0$$

$$7 \quad c_1[s] = r$$

- 8 B-TREE-SPLIT-CHILD(s, 1, r)
- 9 B-TREE-INSERT-NONFULL(*s*,*k*)
- 10 **else** B-TREE-INSERT-NONFULL(*r,k*)





# Inserting a key into a B-tree

```
B-TREE-INSERT-NONFULL(x,k)
1 i = n[x]
2 if leaf[x]
    then while i = 1 and k < key_i[x]
          \mathbf{do} \ key_{i+1} [x] = key_i[x]
          i = i - 1
  key_{i+1}[x] = k
6
  n[x] = n/x/ + 1
   DISK-WRITE(x)
9 else while i \ge 1 and k \le key_i[x]
10
           do i = i - 1
11 i = i + 1
   DISK-READ(c_i[x])
12
     if n[c_i[x]] = 2t - 1
13
14
         then B-TREE-SPLIT-CHILD(x,i,c_i[x])
         if k > key_i[x]
15
             then i = i + 1
16
      B-TREE-INSERT-NONFULL (c.[x],k)
17
```



# Deleting a key from a B-tree

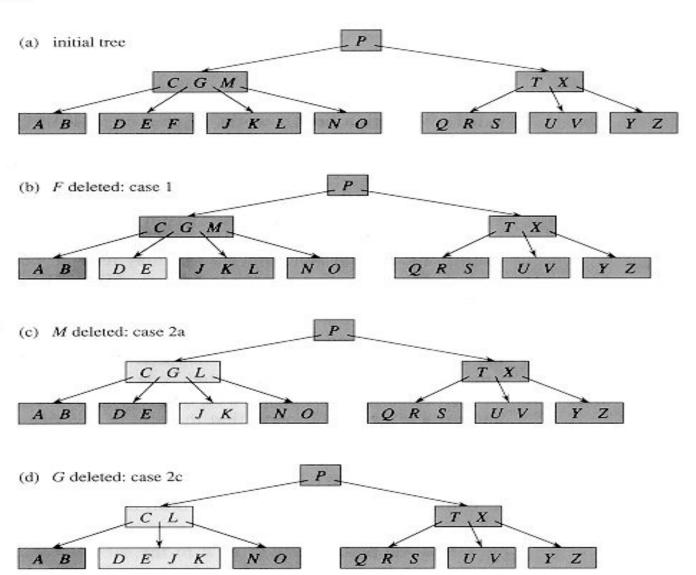
- 1. If the key *k* is in node *x* and *x* is a leaf, delete the key *k* from *x*.
- 2. If the key k is in node x and x is an internal node, do the following.
- a. If the child y that precedes k in node x has at least t keys, then find the predecessor k' of k in the subtree rooted at y. Recursively delete k', and replace k by k' in x. (Finding k' and deleting it can be performed in a single downward pass.)
- b. Symmetrically, if the child z that follows k in node x has at least t keys, then find the successor k' of k in the subtree rooted at z. Recursively delete k', and replace k by k' in x. (Finding k' and deleting it can be performed in a single downward pass.)
- c. Otherwise, if both y and z have only t- 1 keys, merge k and all of z into y, so that x loses both k and the pointer to z, and y now contains 2t 1 keys. Then, free z and recursively delete k from y.



# Deleting a key from a B-tree

- 3. If the key k is not present in internal node x, determine the root  $c_i[x]$  of the appropriate sub tree that must contain k, if k is in the tree at all. If  $c_i[x]$  has only t-1 keys, execute step 3a or 3b as necessary to guarantee that we descend to a node containing at least t keys. Then, finish by recursing on the appropriate child of x.
- a. If  $c_i[x]$  has only t-1 keys but has a sibling with t keys, give  $c_i[x]$  an extra key by moving a key from x down into  $c_i[x]$ , moving a key from  $c_i[x]$ 's immediate left or right sibling up into x, and moving the appropriate child from the sibling into  $c_i[x]$ .
- b. If  $c_i[x]$  and all of  $c_i[x]$ 's siblings have t-1 keys, merge  $c_i$  with one sibling, which involves moving a key from x down into the new merged node to become the median key for that node.

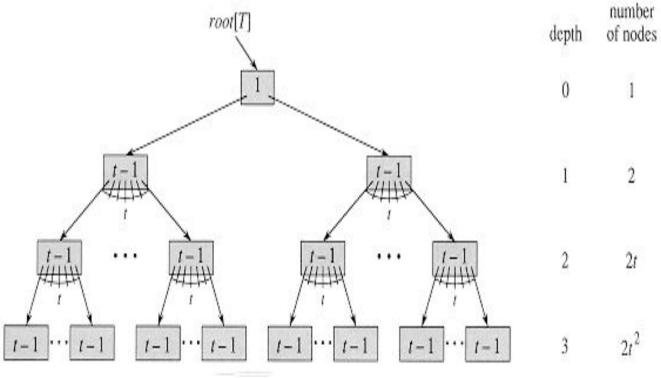






If  $n \ge 1$ , then for any *n*-key B-tree *T* of height *h* and minimum degree  $t \ge 2$ ,

$$h \leq \log_i \frac{n+1}{2} \cdot$$





#### **B-tree**

**Proof** If a B-tree has height h, the number of its nodes is minimized when the root contains one key and all other nodes contain t - 1 keys. In this case, there are 2 nodes at depth 1, 2t nodes at depth 2,  $2t^2$  nodes at depth 3, and so on, until at depth h there are  $2t^{h-1}$  nodes.

$$n \geq 1 + (t-1) \sum_{i=1}^{h} 2t^{i-1}$$

$$= 1 + 2(t-1) \left(\frac{t^{h} - 1}{t - 1}\right)$$

$$= 2t^{h} - 1,$$

