

Introduction to PyTorch

What is PyTorch?

- A library to process tensors in an optimized manner.
- It is an open-source library developed by Facebook Al research team.
- It is mostly used library used for machine learning/deep learning application development, as tensorflow and keras.
- Official Website: https://pytorch.org/



PyTorch Installation

- Go to the official website of PyTorch: https://pytorch.org/
- Select the configurations and get the installation command.
- Installation using Conda
 - conda create –n pytorch_env
 - conda activate pytorch_env
 - conda install jupyter notebook
 - o conda install pytorch torchvision -c pytorch
- Installation using pip
 - Pip install torch

Working with PyTorch

- Import the package
- Import the Pytorch
 - import torch
- Checking the version of torch
 - torch.__version__
- Check CUDA availability
 - torch.cuda.is_available()

Basics of Tensor

- Tensors are scalar, vector or n-dimensional arrays.
- Defining a scalar in torch
 - a=torch.tensor(10)
- Checking the datatype
 - a.dtype
- Defining a vector
 - b=torch.tensor([1,2,3,4])
- Defining 2-dimensional array
 - c=torch.tensor([[1,2,3,4],[5,6,7,8],[9,8,7,7]])

Basics of Tensor

- Defining 3-dimensional array
 - o c=torch.tensor([[[1,2,3,4],[5,6,7,8],[9,8,7,7]],[[1,2,3,4],[5,6,7,8],[9,8,7,7]]])
- Checking the Shape
 - o a.shape
- Checking the size
 - a.size()

PyTorch with Numpy

- From Numpy to Tensor
 - o import numpy as np
 - \circ a1 = np.array([[1,2],[3,4]])
 - a2=torch.from_numpy(a1)
 - o a2.dtype
- From Tensor to Numpy
 - a3= a2.numpy()
 - o a3.dtype

PyTorch Arrays

- Initializing the array using PyTorch
 - \circ x = torch.empty(2,3)
 - y=torch.rand(2,2)
 - x=torch.zeros(2,2)
 - x=torch.ones(2,2)
 - o x.dtype

Python Basics

- Initializing the datatype using PyTorch
 - x=torch.ones(2,2, dtype=torch.int)
 - x.dtype
- Arithmetic Operations in PyTorch
 - x= torch.rand(2,2)
 - y=torch.rand(2,2)
 - z= x+y

Addition

```
\circ z = torch.add(x,y)
```

0 **Z**

OR

```
\circ z = y.add_(x)
```

0 7

Sutraction

```
\circ z = x-y
```

0 **Z**

OR

```
o z=torch.sub(x,y)
```

0 **Z**

OR

```
o z =x.sub_(y)
```

O Z

Multiplication

```
○ z = x*y
```

0 **Z**

OR

```
c z=torch.mul(x,y)
```

0 **Z**

OR

```
o z =x.mul_(y)
```

0 **Z**

Division

- \circ z = x/y
- 0 **Z**

OR

- o z=torch.div(x,y)
- 0 **Z**

OR

- o z =x.div_(y)
- 0 **Z**

PyTorch Basics

- Array Reshaping
 - y=x.view(4)
 - z=x.view(-1, 4)

Working with CUDA

- if torch.cuda.is_available():
- device = torch.device("cuda")
- x= torch.ones(5,5, device=device)
- #or
- y=torch.ones(5,5)
- y=y.to(device)
- z=x + y
- # A GUP tensor is not convertible to numpy array
- z= z.to("cpu")
- z.numpy()

Working with Gradient

- w=torch.tensor(10.)
- x=torch.tensor(5., requires_grad=True)
- b=torch.tensor(2., requires_grad=True)
- y = w * x + b
- y
- y.backward()
- print("dy/dx:", x.grad)
- print("dy/db:", b.grad)
- print("dy/dw:", w.grad)

Thank You