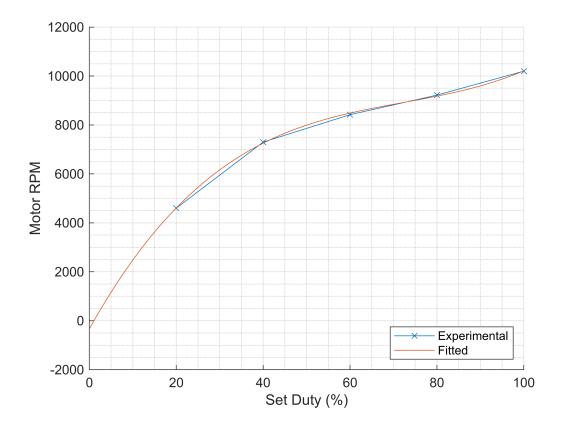
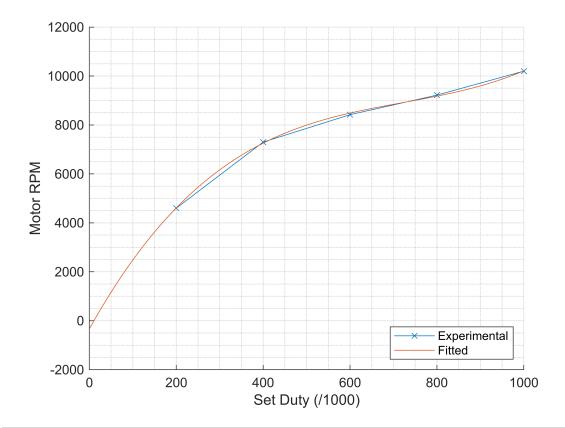
```
clearvars
format shortEng
freq = 50;
T = 1/freq;
percents = [20 40 60 80 100] % corresponding to the measurements
percents = 1 \times 5
                 40.0000e+000
                                60.0000e+000
                                                            100.0000e+000
   20.0000e+000
                                              80.0000e+000
% experimental RPM measurement with HTI HT522 Tachometer
rpms = [4600, 7300, 8420, 9220, 10200]
rpms = 1 \times 5
    4.6000e+003
                  7.3000e+003
                                 8.4200e+003
                                               9.2200e+003
                                                             10.2000e+003
fittedPoly = polyfit(percents, rpms, 3)
fittedPoly = 1 \times 4
   18.3333e-003
                 -3.9714e+000
                               319.2381e+000 -332.0000e+000
theoPercents = 0:2:100;
theoRpms = polyval(fittedPoly, theoPercents);
figure()
hold on
grid on
grid minor
plot(percents, rpms, "x-")
plot(theoPercents, theoRpms)
xlabel("Set Duty (%)")
ylabel("Motor RPM")
legend("Experimental", "Fitted", Location="southeast")
hold off
saveas(gcf, "graph_duty.png")
```



```
%% Expected RPM at maximum using KV
motorKV = 1100;
appliedvoltage = 9;
expectedMaxRPM = motorKV*appliedvoltage
expectedMaxRPM =
    9.9000e+003
thousands = percents*10 % corresponding to the measurements
thousands = 1 \times 5
  200.0000e+000
                 400.0000e+000
                                600.0000e+000
                                               800.0000e+000
                                                                1.0000e+003
% experimental RPM measurement with HTI HT522 Tachometer
rpms = [4600, 7300, 8420, 9220, 10200]
rpms = 1 \times 5
    4.6000e+003
                   7.3000e+003
                                  8.4200e+003
                                                 9.2200e+003
                                                               10.2000e+003
fittedPoly = polyfit(thousands, rpms, 3)
fittedPoly = 1 \times 4
                 -39.7143e-003
                                 31.9238e+000 -332.0000e+000
   18.3333e-006
theoThosands = 0:2:1000;
```

theoRpms = polyval(fittedPoly, theoThosands);

```
figure()
hold on
grid on
grid minor
plot(thousands, rpms, "x-")
plot(theoThosands, theoRpms)
xlabel("Set Duty (/1000)")
ylabel("Motor RPM")
legend("Experimental", "Fitted", Location="southeast")
hold off
saveas(gcf, "graph_duty_thosand.png")
```



```
%% Expected RPM at maximum using KV
motorKV = 1100;
appliedvoltage = 9;
expectedMaxRPM = motorKV*appliedvoltage
```

expectedMaxRPM =
 9.9000e+003

```
syms x y
y = poly2sym(fittedPoly)
```

y =

```
\frac{5411044928288123 \ x^3}{295147905179352825856} - \frac{139 \ x^2}{3500} + \frac{3352 \ x}{105} - \frac{1460151441686411}{4398046511104}
```

```
% fittedPolyInverse = polyfit(rpms, thousands, 3)
% theoRpms = 0:50:10e3
% theoThosands = polyval(fittedPolyInverse, theoRpms)
% figure()
% hold on
grid on
grid minor
% plot(thousands, rpms, "x-")
% plot(theoThosands, theoRpms)
% xlabel("Set Duty (/1000)")
% ylabel("Motor RPM")
% legend("Experimental", "Fitted", Location="southeast")
% hold off
% saveas(gcf, "graph_duty_thosand_inverse.png")
```