

# Properties of Series RLC Network - $v(t)$

- Behavior captured by damping
  - Gradual **loss** of the initial stored energy
  - $\alpha$  determines the rate of damping

$$\alpha = \frac{R}{2L} \quad \omega_0 = \frac{1}{\sqrt{LC}}$$

- $\alpha > \omega_0$  , overdamped

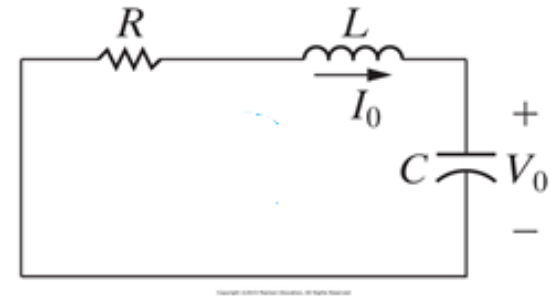
$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

- $\alpha = \omega_0$  , critically damped

$$v(t) = (A_1 t + A_2) e^{-\alpha t}$$

- $\alpha < \omega_0$  , underdamped

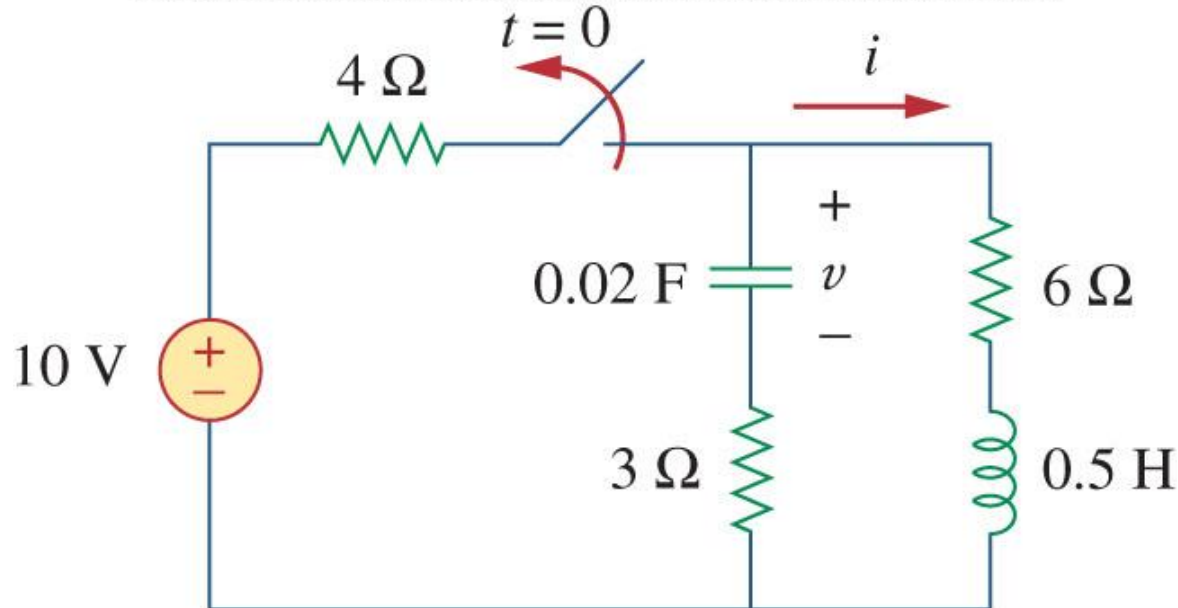
$$v(t) = e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t)$$



## Example

- Find  $v(t)$  in the circuit below. Assume the circuit has reached steady state at  $t = 0^-$ .

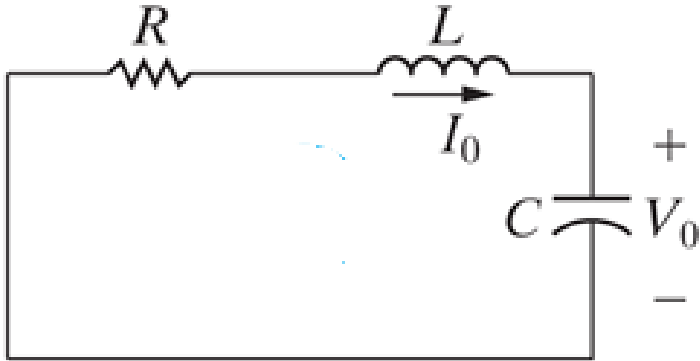
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# Source-Free Series RLC Circuit



# Properties of Series RLC Network - $i(t)$

- Behavior captured by damping
  - Gradual **loss** of the initial stored energy
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$$\alpha = \frac{R}{2L} \quad \omega_0 = \frac{1}{\sqrt{LC}}$$

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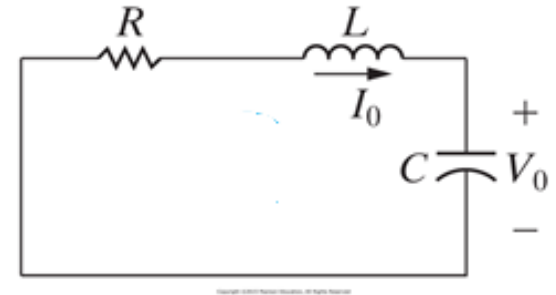
$$i(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

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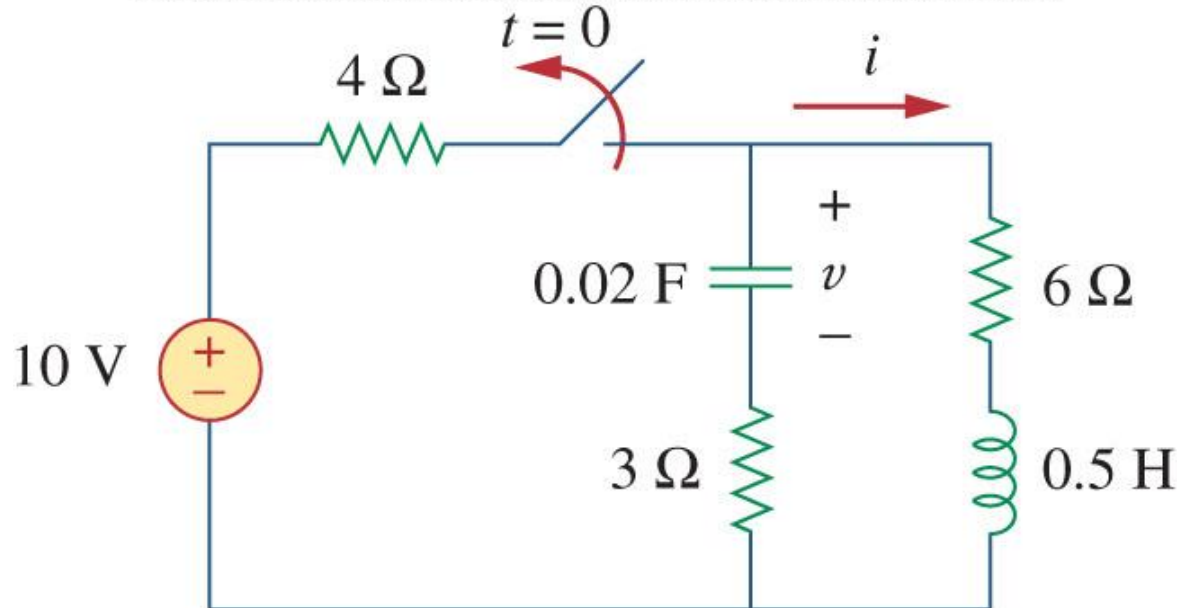
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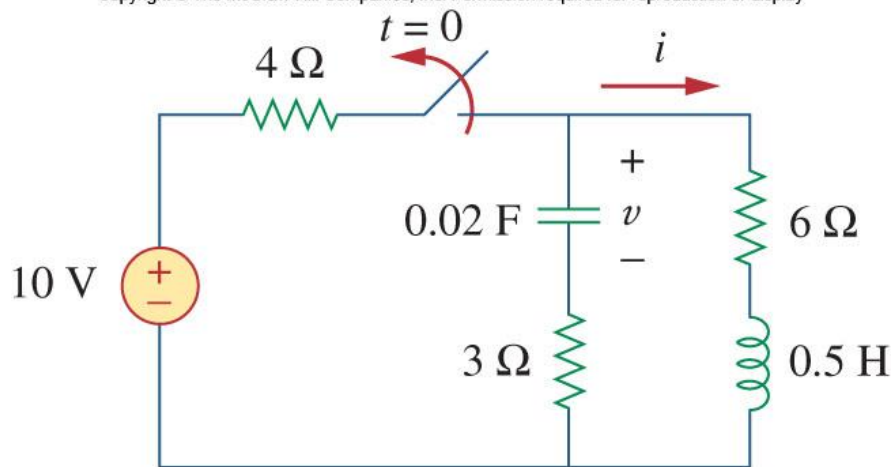
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## Example

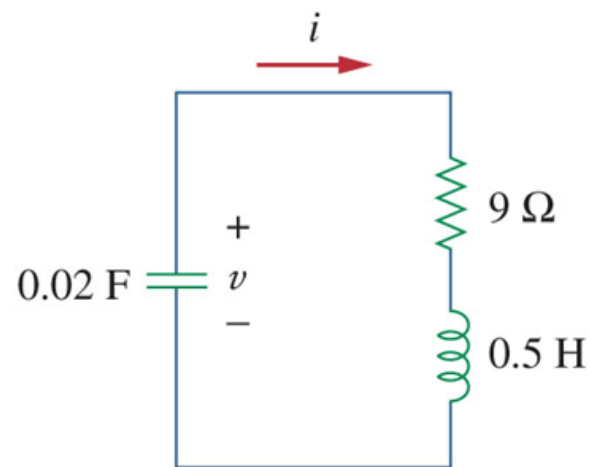
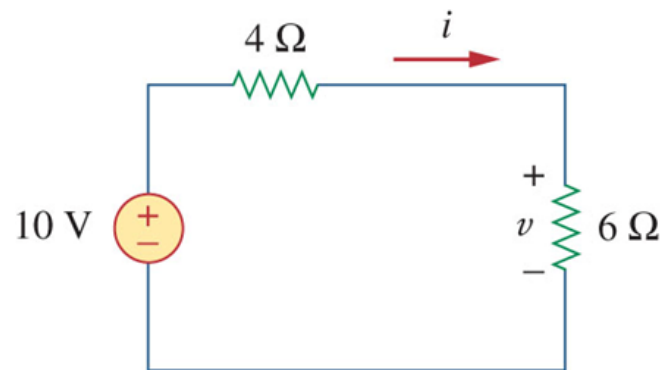
- Find  $i(t)$  in the circuit below. Assume the circuit has reached steady state at  $t = 0^-$ .

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$$\alpha = \frac{R}{2L} = 9 \quad \omega_0 = \frac{1}{\sqrt{LC}} = 10$$

$$s_{1,2} = -\alpha \mp \sqrt{\alpha^2 - \omega_0^2} = -9 \mp j4.359$$



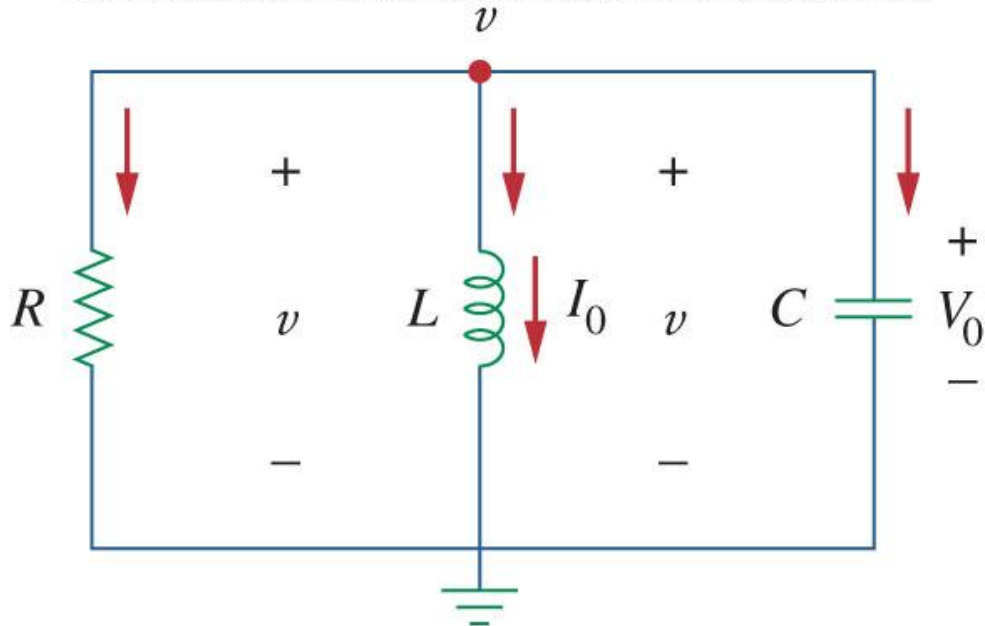






# Source-Free Parallel RLC Network

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# Source-Free Parallel RLC Network - $v(t)$

$$\frac{d^2v}{dt^2} + \frac{1}{RC} \frac{dv}{dt} + \frac{1}{LC} v = 0$$

- The characteristic equation is:

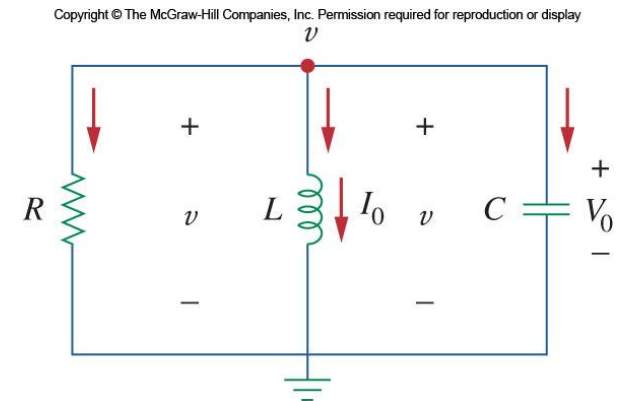
$$s^2 + \frac{1}{RC} s + \frac{1}{LC} = 0$$

From this, we can find the roots of the characteristic equation to be:

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

$$\alpha = \frac{1}{2RC} \quad \omega_0 = \frac{1}{\sqrt{LC}}$$

As in last time, there are three scenarios to consider.



## Three Damping Cases - $v(t)$

$$\frac{d^2v}{dt^2} + \frac{1}{RC} \frac{dv}{dt} + \frac{1}{LC} v = 0$$

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$
$$\alpha = \frac{1}{2RC} \quad \omega_0 = \frac{1}{\sqrt{LC}}$$

- For the overdamped case, the roots are real and negative,

$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

- For critically damped, the roots are real and equal

$$v(t) = (A_1 t + A_2) e^{-\alpha t}$$

- In the underdamped case, the roots are complex

$$v(t) = e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t)$$



## Three Damping Cases - $i(t)$

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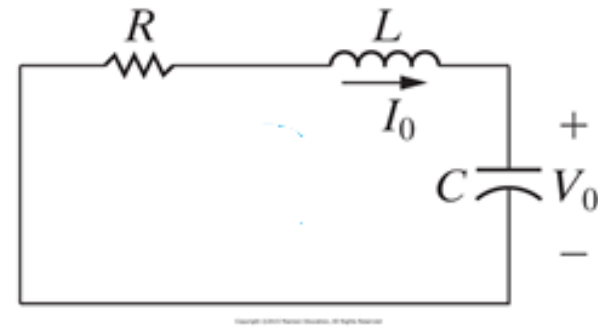
# Series vs. Parallel (Source-Free RLC Circuit)

- Series  $\alpha = \frac{R}{2L} \quad \omega_0 = \frac{1}{\sqrt{LC}}$

$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$$v(t) = (A_1 t + A_2) e^{-\alpha t}$$

$$v(t) = e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t)$$

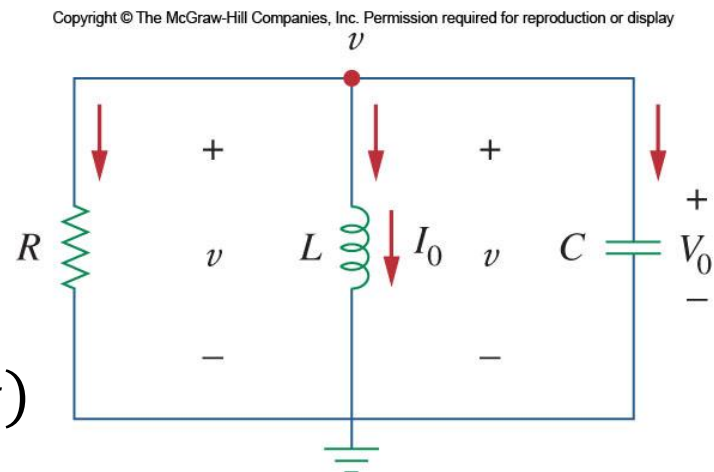


- Parallel  $\alpha = \frac{1}{2RC} \quad \omega_0 = \frac{1}{\sqrt{LC}}$

$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

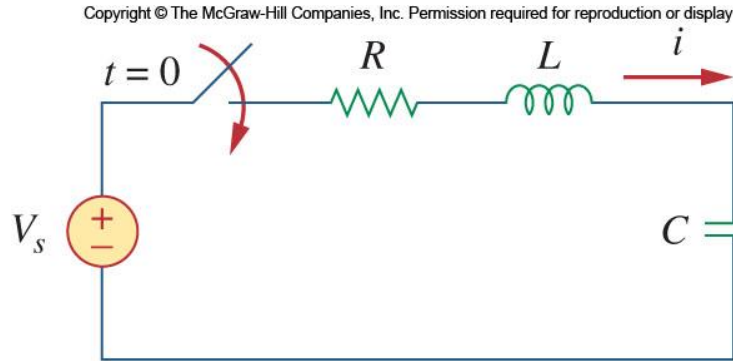
$$v(t) = (A_1 t + A_2) e^{-\alpha t}$$

$$v(t) = e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t)$$





# Step Response of a Series RLC Circuit



$$\frac{d^2v}{dt^2} + \frac{R}{L} \frac{dv}{dt} + \frac{v}{LC} = \frac{V_s}{LC}$$

- The solution

$$v(t) = v_t(t) + v_{ss}(t)$$

- The complete solutions for the three conditions of damping are:

$$v(t) = V_s + (A_1 e^{s_1 t} + A_2 e^{s_2 t}) \quad (\text{Overdamped})$$

$$v(t) = V_s + (A_1 + A_2 t) e^{-\alpha t} \quad (\text{Critically Damped})$$

$$v(t) = V_s + (B_1 \cos \omega_d t + B_2 \sin \omega_d t) e^{-\alpha t} \quad (\text{Underdamped})$$

## Example

- Find  $v(t)$  and  $i(t)$  for  $t > 0$ .

Consider three cases:

- $R = 5\Omega$
- $R = 4\Omega$
- $R = 1\Omega$

When  $R = 5\Omega$ ,

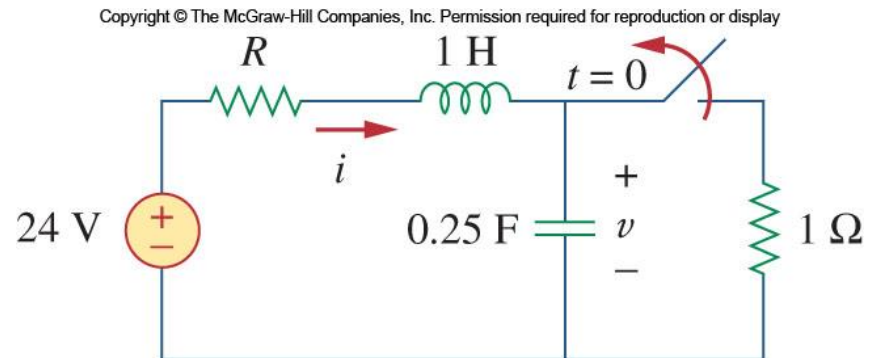
- For  $t < 0$ , switch closed, capacitor open, inductor shorted.

$$i(0) = 4A = C \frac{dv(0)}{dt}, \quad v(0) = 4V, \quad \frac{dv(0)}{dt} = 16$$

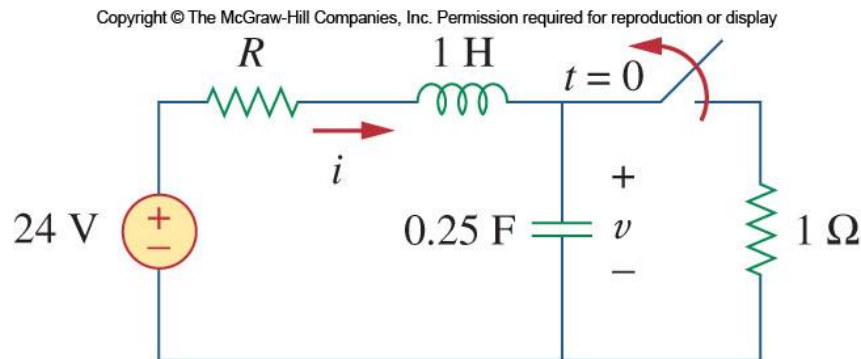
- For  $t > 0$ , switch open, a series RLC network

$$\alpha = \frac{R}{2L} = 2.5, \quad \omega_0 = \frac{1}{\sqrt{LC}} = 2, \quad s_{1,2} = -1, -4 \quad \text{Overdamped.}$$

$$v(t) = v_s + (A_1 e^{-t} + A_2 e^{-4t})$$







When  $R = 4\Omega$ ,

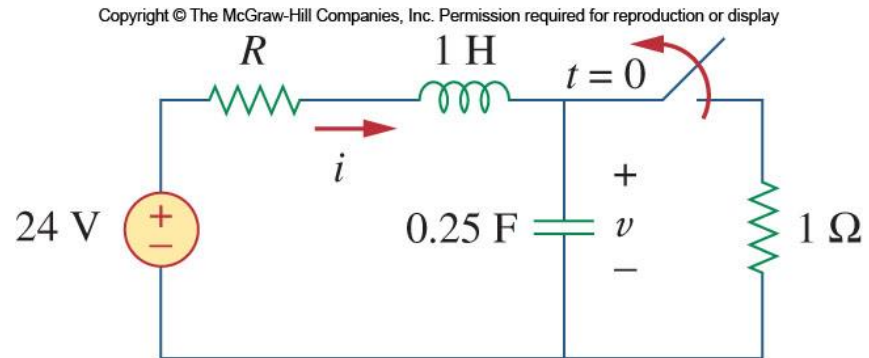
- For  $t < 0$ , switch closed, capacitor open, inductor shorted.

$$i(0) = 4.8A = C \frac{dv(0)}{dt}, \quad v(0) = 4.8V, \quad \frac{dv(0)}{dt} = 19.2$$

- For  $t > 0$ , switch open, a series RLC network

$$\alpha = \frac{R}{2L} = 2, \quad \omega_0 = \frac{1}{\sqrt{LC}} = 2, \quad s_{1,2} = -2 \quad \text{Critically damped}$$

$$v(t) = v_s + (A_1 + A_2 t)e^{-2t}$$



When  $R = 1\Omega$ ,

- For  $t < 0$ , switch closed, capacitor open, inductor shorted.

$$i(0) = 12A = C \frac{dv(0)}{dt}, \quad v(0) = 12V, \quad \frac{dv(0)}{dt} = 48$$

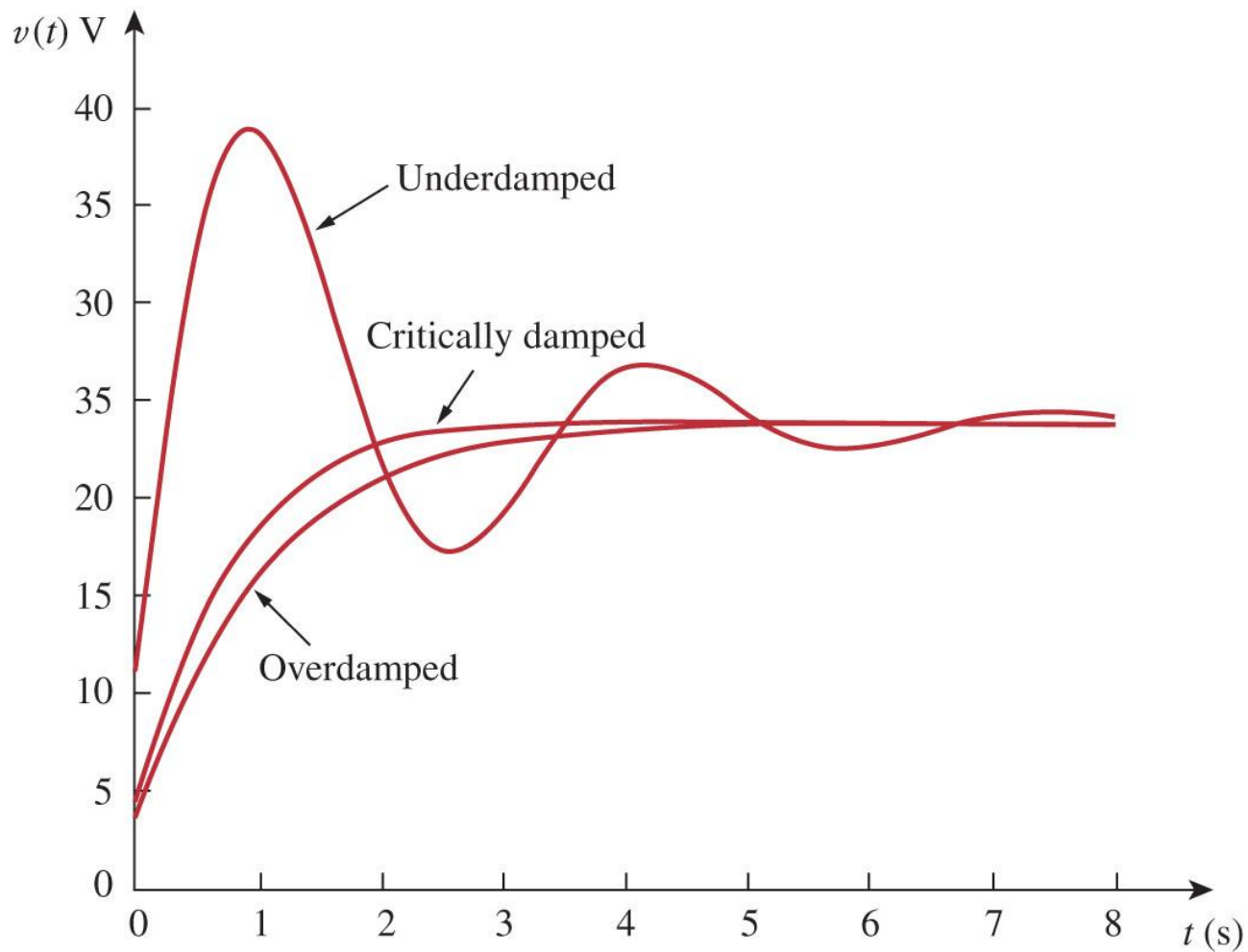
- For  $t > 0$ , switch open, a series RLC network

$$\alpha = \frac{R}{2L} = 0.5, \quad \omega_0 = \frac{1}{\sqrt{LC}} = 2, \quad s_{1,2} = -0.5 \pm j1.936 \quad \text{Underdamped}$$

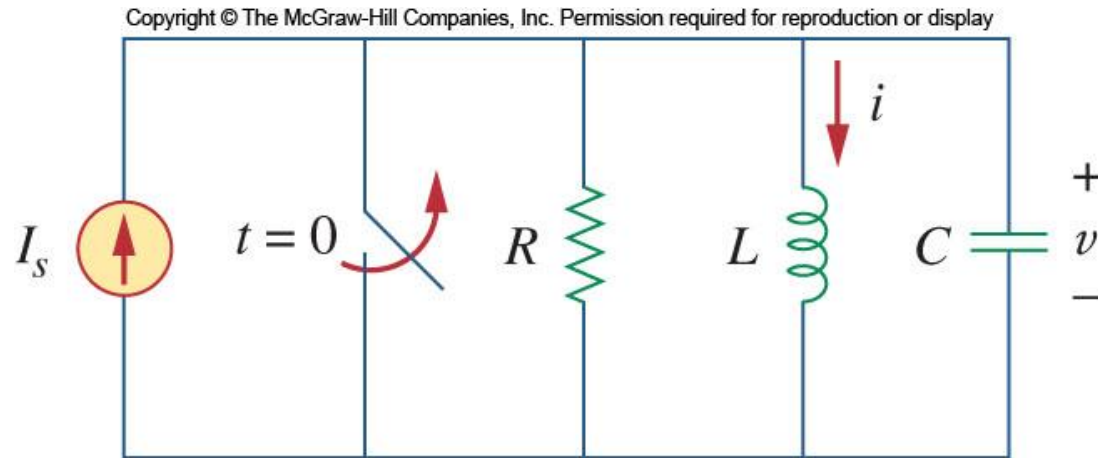
$$v(t) = v_s + (B_1 \cos 1.936t + B_2 \sin 1.936t)e^{-0.5t}$$



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# Step Response of a Parallel RLC Circuit



Apply KCL,

$$\frac{v}{R} + i + C \frac{dv}{dt} = I_s$$

$$\& \quad v = L \frac{di}{dt}$$

So we get

$$\frac{d^2 i}{dt^2} + \frac{1}{RC} \frac{di}{dt} + \frac{i}{LC} = \frac{I_s}{LC}$$

## Step Response of a Parallel RLC Circuit

$$\frac{d^2 i}{dt^2} + \frac{1}{RC} \frac{di}{dt} + \frac{i}{LC} = \frac{I_s}{LC}$$

- The total response is a combination of **steady state responses and transient response**:

$$i(t) = I_s + (A_1 e^{s_1 t} + A_2 e^{s_2 t}) \text{ (Overdamped)}$$

$$i(t) = I_s + (A_1 + A_2 t) e^{-\alpha t} \text{ (Critically Damped)}$$

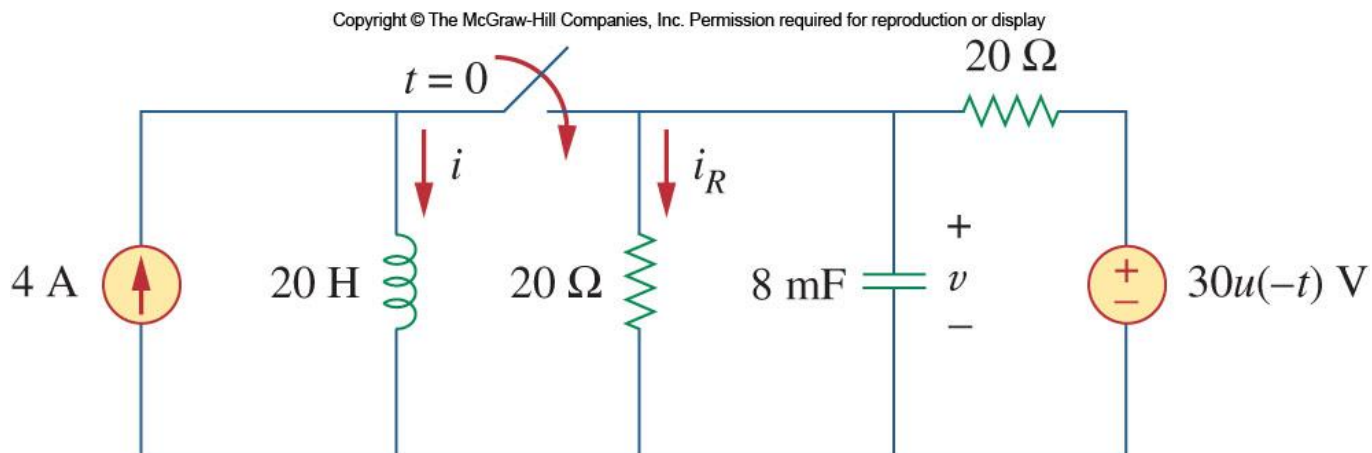
$$i(t) = I_s + (B_1 \cos \omega_d t + B_2 \sin \omega_d t) e^{-\alpha t} \text{ (Underdamped)}$$

Here the variables  $A_1/A_2$   $B_1/B_2$  are obtained from the initial conditions,  $i(0)$  and  $di(0)/dt$ .

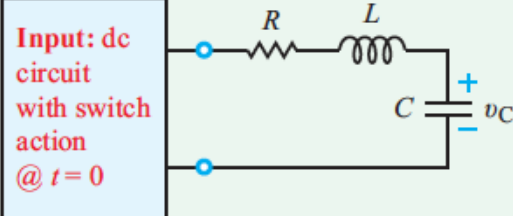
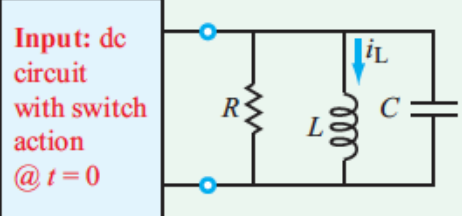


## Example

- Find  $i(t)$  and  $i_R(t)$  for  $t > 0$ .





<p style="text-align: center;"><b>Series RLC</b></p> 	<p style="text-align: center;"><b>Parallel RLC</b></p> 
<p style="text-align: center;">Total Response</p>	<p style="text-align: center;">Total Response</p>
<p><b>Overdamped</b> (<math>\alpha &gt; \omega_0</math>)</p> $v_C(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t} + v_C(\infty)$ $A_1 = \frac{\frac{1}{C} i_C(0) - s_2 [v_C(0) - v_C(\infty)]}{s_1 - s_2}$ $A_2 = \left[ \frac{\frac{1}{C} i_C(0) - s_1 [v_C(0) - v_C(\infty)]}{s_2 - s_1} \right]$	<p><b>Overdamped</b> (<math>\alpha &gt; \omega_0</math>)</p> $i_L(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t} + i_L(\infty)$ $A_1 = \frac{\frac{1}{L} v_L(0) - s_2 [i_L(0) - i_L(\infty)]}{s_1 - s_2}$ $A_2 = \left[ \frac{\frac{1}{L} v_L(0) - s_1 [i_L(0) - i_L(\infty)]}{s_2 - s_1} \right]$
<p><b>Critically Damped</b> (<math>\alpha = \omega_0</math>)</p> $v_C(t) = (B_1 + B_2 t) e^{-\alpha t} + v_C(\infty)$ $B_1 = v_C(0) - v_C(\infty)$ $B_2 = \frac{1}{C} i_C(0) + \alpha [v_C(0) - v_C(\infty)]$	<p><b>Critically Damped</b> (<math>\alpha = \omega_0</math>)</p> $i_L(t) = (B_1 + B_2 t) e^{-\alpha t} + i_L(\infty)$ $B_1 = i_L(0) - i_L(\infty)$ $B_2 = \frac{1}{L} v_L(0) + \alpha [i_L(0) - i_L(\infty)]$
<p><b>Underdamped</b> (<math>\alpha &lt; \omega_0</math>)</p> $v_C(t) = e^{-\alpha t} (D_1 \cos \omega_d t + D_2 \sin \omega_d t) + v_C(\infty)$ $D_1 = v_C(0) - v_C(\infty)$ $D_2 = \frac{\frac{1}{C} i_C(0) + \alpha [v_C(0) - v_C(\infty)]}{\omega_d}$	<p><b>Underdamped</b> (<math>\alpha &lt; \omega_0</math>)</p> $i_L(t) = e^{-\alpha t} (D_1 \cos \omega_d t + D_2 \sin \omega_d t) + i_L(\infty)$ $D_1 = i_L(0) - i_L(\infty)$ $D_2 = \frac{\frac{1}{L} v_L(0) + \alpha [i_L(0) - i_L(\infty)]}{\omega_d}$
<p style="text-align: center;"><b>Auxiliary Relations</b></p> <div style="display: flex; justify-content: space-around;"> <div style="text-align: left;"> <math display="block">\alpha = \begin{cases} \frac{R}{2L} &amp; \text{Series RLC} \\ \frac{1}{2RC} &amp; \text{Parallel RLC} \end{cases}</math> <math display="block">s_1 = -\alpha + \sqrt{\alpha^2 - \omega_0^2}</math> </div> <div style="text-align: left;"> <math display="block">\omega_0 = \frac{1}{\sqrt{LC}}</math> <math display="block">\omega_d = \sqrt{\omega_0^2 - \alpha^2}</math> <math display="block">s_2 = -\alpha - \sqrt{\alpha^2 - \omega_0^2}</math> </div> </div>	