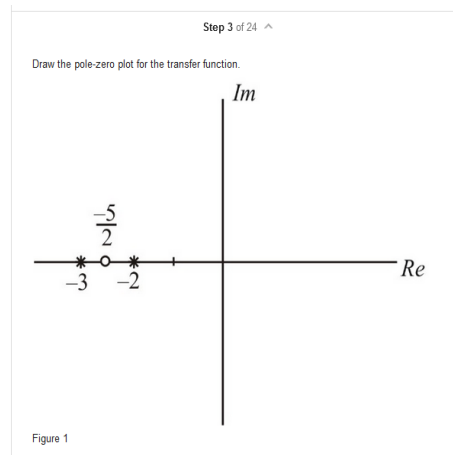


T1.(a) The Laplace transform of $x(t)$ is

$$\begin{aligned} X(s) &= \int_0^{\infty} (e^{-2t} + e^{-3t})e^{-st} dt \\ &= \left[\frac{-e^{-(s+2)t}}{s+2} \right]_0^{\infty} + \left[\frac{-e^{-(s+3)t}}{s+3} \right]_0^{\infty} \\ &= \frac{1}{s+2} + \frac{1}{s+3} = \frac{2s+5}{s^2+5s+6}, \text{ROC: } \text{Re}\{s\} > -2 \end{aligned}$$

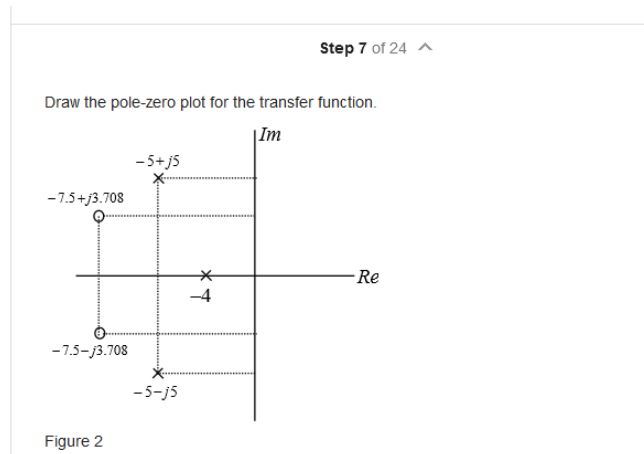


(b)

$$\because [\sin \omega_0 t]u(t) \xleftrightarrow{L} \frac{\omega_0}{s^2 + \omega_0^2}, \text{ROC: } \text{Re}\{s\} > 0$$

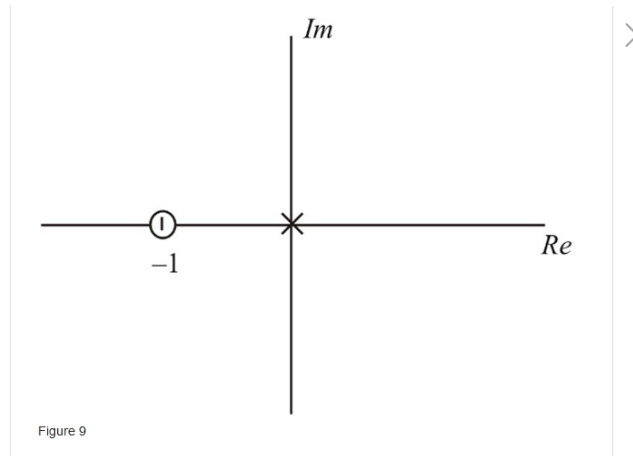
$$\because e^{s_0 t} x(t) \xleftrightarrow{L} X(s - s_0)$$

$$\therefore X(s) = \frac{1}{s+4} + \frac{5}{(s+5)^2 + 25} = \frac{s^2 + 15s + 70}{s^3 + 14s^2 + 90s + 200} \text{ROC: } \text{Re}\{s\} > -4$$



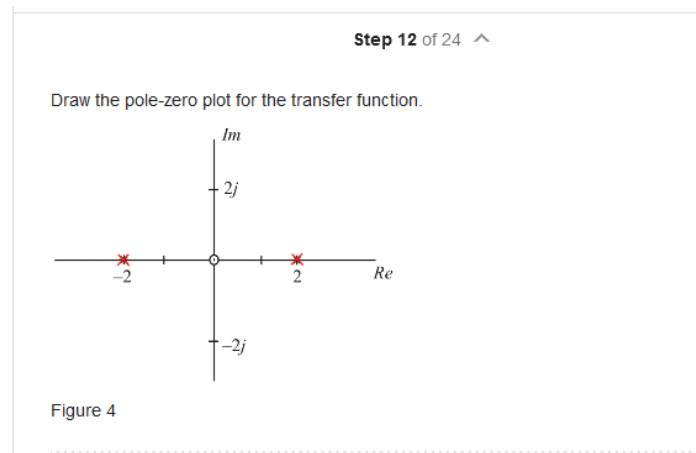
(c)

$$X(s) = 1 + \frac{1}{s}, \text{ROC: } \text{Re}\{s\} > 0$$



(d)

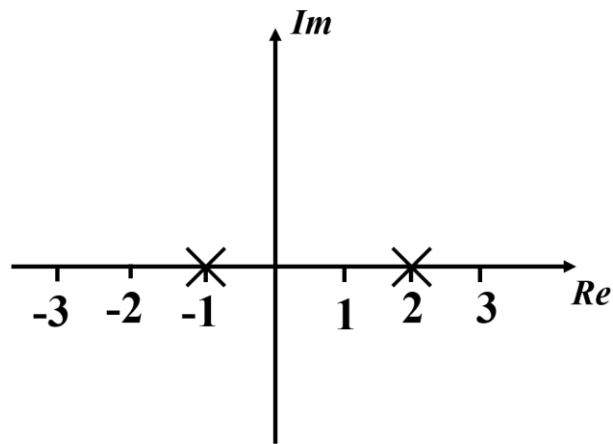
$$te^{-2|t|} = te^{-2t}u(t) + te^{2t}u(-t) \xleftrightarrow{L} \frac{1}{(s+2)^2} - \frac{1}{(s-2)^2} = \frac{-8s}{(s^2-4)^2}, \text{ROC: } -2 < \text{Re}\{s\} < 2$$



T2.(a)

$$s^2Y(s) - sY(s) - 2Y(s) = X(s)$$

$$H(s) = \frac{Y(s)}{X(s)} = \frac{1}{s^2 - s - 2}$$



(b)

(i) Stable \rightarrow $ROC: -1 < \text{Re}\{s\} < 2$, $h(t) = -\frac{1}{3}e^{2t}u(-t) - \frac{1}{3}e^{-t}u(t)$

(i) Causal \rightarrow $ROC: \text{Re}\{s\} > 2$, $h(t) = \frac{1}{3}e^{2t}u(t) - \frac{1}{3}e^{-t}u(t)$

(i) Neither stable nor causal \rightarrow $ROC: \text{Re}\{s\} < -1$, $h(t) = -\frac{1}{3}e^{2t}u(-t) + \frac{1}{3}e^{-t}u(-t)$

T3. From 2, $\because u(t) \xleftrightarrow{L} \frac{1}{s}$

$\therefore H(s) = 0$ when $s = 0$

also, from 3, $tu(t) \xleftrightarrow{L} \frac{1}{s^2}$

$\therefore H(s)$ has only 1 zero at $s = 0$

from 4, $p(t) = \frac{d^2 h(t)}{dt^2} + 2 \frac{dh(t)}{dt} + 2h(t)$ is finite duration,

$\therefore P(s)$ has no poles, in other words, there's no s in the denominator of $P(s)$

use Laplace transformation, $P(s) = s^2 H(s) + 2sH(s) + 2H(s)$

$$H(s) = \frac{P(s)}{s^2 + 2s + 2}$$

$\therefore P(s)$ has no poles, and from 5, the order of s in numerator is one less than the s in denominator

$$\therefore H(s) = \frac{As}{s^2 + 2s + 2}$$

where A is a constant,

from 1, $H(1) = 0.2$

$$\therefore A = 1$$

$$\therefore H(s) = \frac{s}{s^2 + 2s + 2}$$

\therefore poles are $-1 \pm j$

$\therefore h(t)$ is stable and causal

$\therefore \text{ROC: } \text{Re}\{s\} > -1$

T4. (a)

$$\begin{aligned}
 H(s) &= (2s^2 + 4s - 6)H_1(s) \\
 \therefore Y(s) &= (2s^2 + 4s - 6)Y_1(s) \\
 \therefore y(t) &= 2\frac{d^2y_1(t)}{dt^2} + 4\frac{dy_1(t)}{dt} - 6y_1(t)
 \end{aligned}$$

(b)

$$\therefore Y_1(s) = \frac{F(s)}{s}, f(t) = dy_1(t)/dt$$

(c)

$$\therefore F(s) = \frac{E(s)}{s}, e(t) = \frac{df(t)}{dt} = \frac{d^2y_1(t)}{dt^2}$$

(d)

$$y(t) = 2e(t) + 4f(t) - 6y_1(t)$$

T5.

$$\frac{d^2y(t)}{dt^2} + 5\frac{dy}{dt} + 6y(t) = x(t)$$

Use Laplace transformation, we get $s^2Y(s) - sy(0^-) - y'(0^-) + 5sY(s) - 5y(0^-) + 6Y(s) = X(s)$

(a)

$$X(s) = \frac{1}{s+4}$$

$$Y_{zs}(s) = \frac{X(s)}{s^2 + 5s + 6} = \frac{1}{(s+2)(s+3)(s+4)} = \frac{1/2}{s+2} - \frac{1}{s+3} + \frac{1/2}{s+4}$$

$$y_{zs}(t) = \frac{1}{2}e^{-2t}u(t) - e^{-3t}u(t) + \frac{1}{2}e^{-4t}u(t)$$

(b)

$$Y_{zi}(s) = \frac{(s+5)y(0^-) + y'(0^-)}{s^2 + 5s + 6} = \frac{1}{s+2}$$

$$y_{zi}(t) = e^{-2t}u(t)$$

(c)

$$y(t) = y_{zi}(t) + y_{zs}(t) = \frac{3}{2}e^{-2t}u(t) - e^{-3t}u(t) + \frac{1}{2}e^{-4t}u(t)$$