

Lecture 10 Wavelet Transform

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Course piazza link: piazza.com/shanghaitech.edu.cn/spring2021/cs270spring2021

Outline

- Discrete Wavelet Transform (DWT) (小波变换)
 - An example for 1D-DWT
 - Generalization of 1D-DWT
 - 2D-DWT

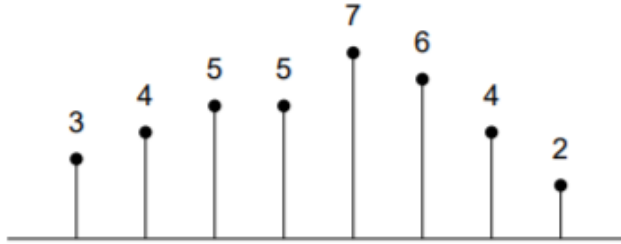


Discrete Wavelet Transform (DWT)

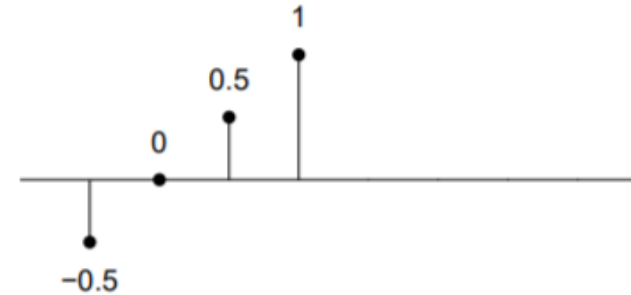
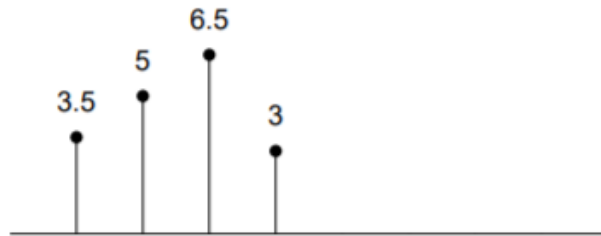
- Based on small waves called Wavelets-1) limited; 2) oscillation.
- Key idea: Translation & Scaling.
- Localized both time/space and frequency.
- Efficient for noise reduction and image compression.
- Two types of DWT one for image processing (easy invertible) and one for signal processing (invertible but computational expensive).

A simplest example

- We can decompose an eight-point signal $x(n]$:



into two four-point signals:

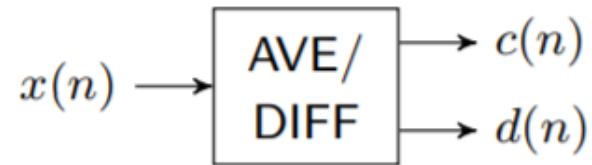


$$c(n) = 0.5 x(2n) + 0.5 x(2n + 1)$$

$$d(n) = 0.5 x(2n) - 0.5 x(2n + 1)$$

A simplest example

- The above process can be represented by a block diagram:



This decomposition can be easily reversed:

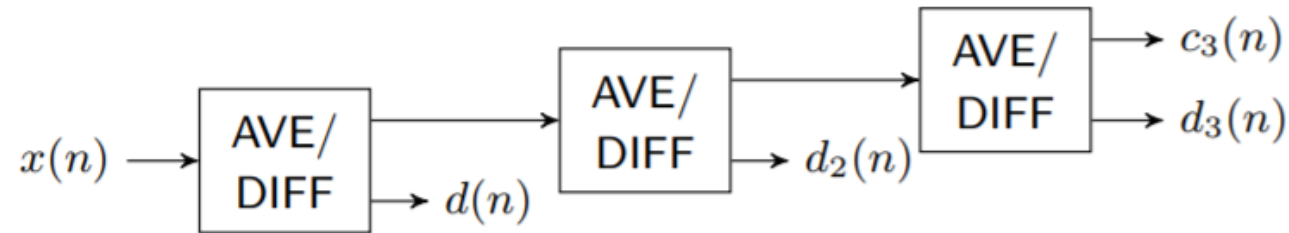
$$\begin{aligned}y(2n) &= c(n) + d(n) \\ y(2n + 1) &= c(n) - d(n)\end{aligned}$$

Which is also represented by a block diagram:



A simplest example

- When we repeat the simple AVE/DIFF signal decomposition:



The Haar wavelet representation of the eight-point signal $x[n]$ is simply the set of four output signals produced by this three-level operation :

$$c_3 = [4.5]$$

$$d_3 = [-0.25]$$

$$d_2 = [-0.75, \quad 1.75]$$

$$d = [-0.5, \quad 0, \quad 0.5, \quad 1]$$

$$\mathbf{H}_8 = \frac{1}{\sqrt{8}} \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & -1 & -1 & -1 & -1 \\ \sqrt{2} & \sqrt{2} & -\sqrt{2} & -\sqrt{2} & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \sqrt{2} & \sqrt{2} & -\sqrt{2} & -\sqrt{2} \\ 2 & -2 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & -2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2 & -2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 2 & -2 \end{bmatrix}$$

Haar Transform matrix

➤ When N=2 we have:
$$\mathbf{H}_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

➤ When N=4 we have:
$$\mathbf{H}_4 = \frac{1}{2} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & -1 & -1 \\ \sqrt{2} & -\sqrt{2} & 0 & 0 \\ 0 & 0 & \sqrt{2} & -\sqrt{2} \end{bmatrix}$$

➤ When N=8 we have
$$\mathbf{H}_8 = \frac{1}{\sqrt{8}} \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & -1 & -1 & -1 & -1 \\ \sqrt{2} & \sqrt{2} & -\sqrt{2} & -\sqrt{2} & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \sqrt{2} & \sqrt{2} & -\sqrt{2} & -\sqrt{2} \\ 2 & -2 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & -2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2 & -2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 2 & -2 \end{bmatrix}$$

Haar Transform matrix

- The family of N Haar functions $\mathbf{h}_k(\mathbf{t})$, ($\mathbf{k} = \mathbf{0}, \dots, \mathbf{N} - \mathbf{1}$) are defined on the interval $\mathbf{0} \leq \mathbf{t} \leq \mathbf{1}$. The shape of the specific function $\mathbf{h}_k(\mathbf{t})$ of a given index \mathbf{k} depends on two parameters \mathbf{p} and \mathbf{q} :

$$\mathbf{k} = 2^{\mathbf{p}} + \mathbf{q} - \mathbf{1}$$

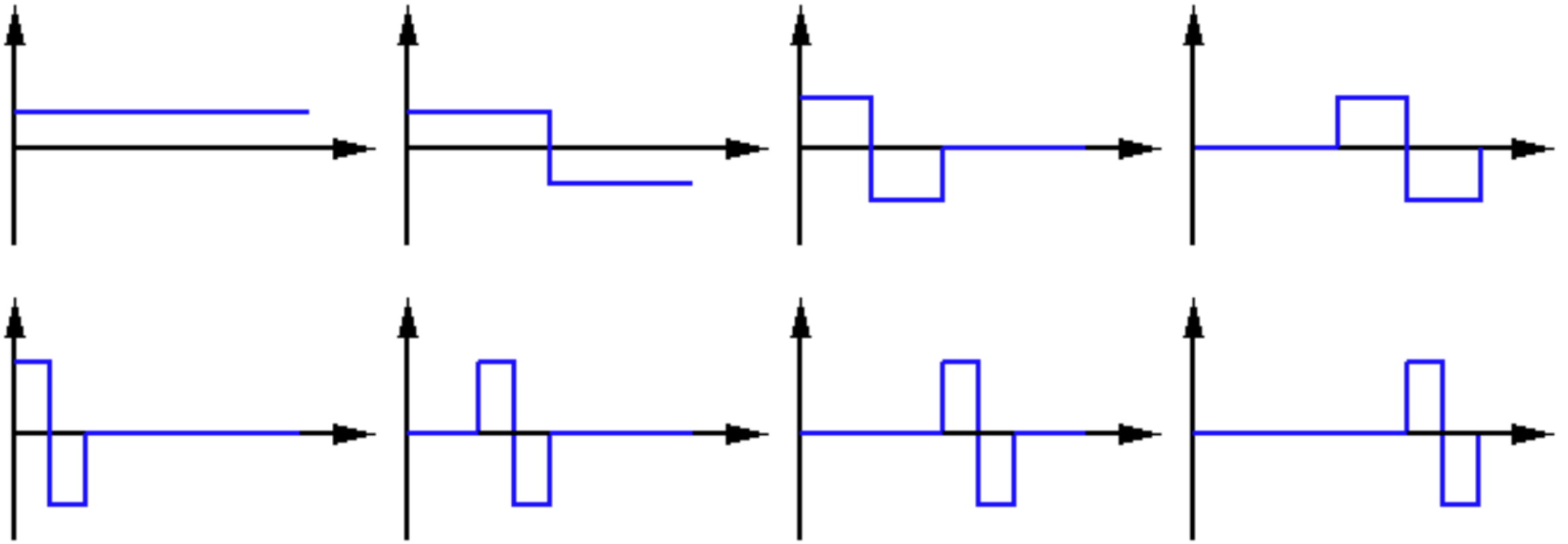
k	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
p	0	0	1	1	2	2	2	2	3	3	3	3	3	3	3	3
q	0	1	1	2	1	2	3	4	1	2	3	4	5	6	7	8

- When $\mathbf{k} > \mathbf{0}$, the Haar function is defined by:

$$h_k(t) = \frac{1}{\sqrt{N}} \begin{cases} 2^{p/2} & (q-1)/2^p \leq t < (q-0.5)/2^p \\ -2^{p/2} & (q-0.5)/2^p \leq t < q/2^p \\ 0 & \text{otherwise} \end{cases}$$

Haar Transform matrix

$$H_8 = \frac{1}{\sqrt{8}} \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & -1 & -1 & -1 & -1 \\ \sqrt{2} & \sqrt{2} & -\sqrt{2} & -\sqrt{2} & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \sqrt{2} & \sqrt{2} & -\sqrt{2} & -\sqrt{2} \\ 2 & -2 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & -2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2 & -2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 2 & -2 \end{bmatrix}$$



Generalization of 1D-DWT

- Discrete Wavelet Transform (DWT):

$$W_{\varphi}(j_0, k) = \frac{1}{\sqrt{M}} \sum_n f(n) \varphi_{j_0, k}(n)$$

$$W_{\psi}(j, k) = \frac{1}{\sqrt{M}} \sum_n f(n) \psi_{j, k}(n) \quad j \geq j_0$$

- Inverse Discrete Wavelet Transform (IDWT):

$$f(n) = \frac{1}{\sqrt{M}} \sum_k W_{\varphi}(j_0, k) \varphi_{j_0, k}(n) + \frac{1}{\sqrt{M}} \sum_{j=j_0}^{\infty} \sum_k W_{\psi}(j, k) \psi_{j, k}(n)$$

Where

$\varphi_{j_0, k}(n)$: scaling function (尺度函数)

$\psi_{j, k}(n)$: Wavelet (小波)

$W_{\varphi}(j_0, k)$: Approximation coefficients (近似系数) $W_{\psi}(j, k)$: detail coefficients (细节系数)

2D-DWT

- Define 2D wavelet function: Directionally sensitive wavelet

$$\psi^H(x, y) = \psi(x)\varphi(y) \quad \psi^V(x, y) = \varphi(x)\psi(y) \quad \psi^D(x, y) = \psi(x)\psi(y)$$

- 2D-DWT

$$W_\varphi(j_0, m, n) = \frac{1}{\sqrt{MN}} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) \varphi_{j_0, m, n}(x, y)$$

$$W_\psi(j, m, n) = \frac{1}{\sqrt{MN}} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) \psi_{j, m, n}^i(x, y) \quad i = \{H, V, D\}$$

- 2D-IDWT

$$f(x, y) = \frac{1}{\sqrt{MN}} \sum_m \sum_n W_\varphi(j_0, m, n) \varphi_{j_0, m, n}(x, y)$$

$$+ \frac{1}{\sqrt{MN}} \sum_{i=\{H, V, D\}} \sum_{j=j_0}^{\infty} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} W_\psi(j, m, n) \psi_{j, m, n}^i(x, y)$$

Haar Transform matrix

Input: image size 8X8 I_{in}

Generate a Haar matrix of 8X8 as shown right

Then clip it into 4 part:

$$H_{L1}(\text{dim} = 4 * 8); H_{L2}(\text{dim} = 2 * 8);$$

$$H_{L3}(\text{dim} = 1 * 8); L_{L3}(\text{dim} = 1 * 8);$$

$$H_8 = \frac{1}{\sqrt{8}} \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & -1 & -1 & -1 & -1 \\ \sqrt{2} & \sqrt{2} & -\sqrt{2} & -\sqrt{2} & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \sqrt{2} & \sqrt{2} & -\sqrt{2} & -\sqrt{2} \\ 2 & -2 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & -2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2 & -2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 2 & -2 \end{bmatrix} \begin{matrix} L_{L3} \\ H_{L3} \\ H_{L2} \\ H_{L1} \end{matrix}$$

For computing *level 1* components:

LL_1 is down-sample of I_{in} on both X and Y direction	$HL_1 = H_{L1} * I_{in}$ + downsample on Y direction
$LH_1 = I_{in} * H_{L1}$ + downsample on X direction	$HH_1 = H_{L1} * I_{in} * H_{L1}$

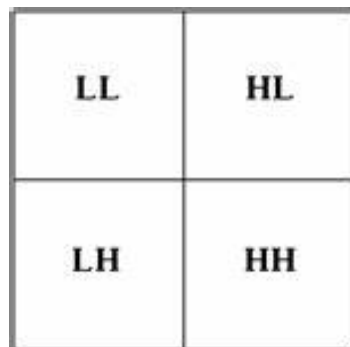
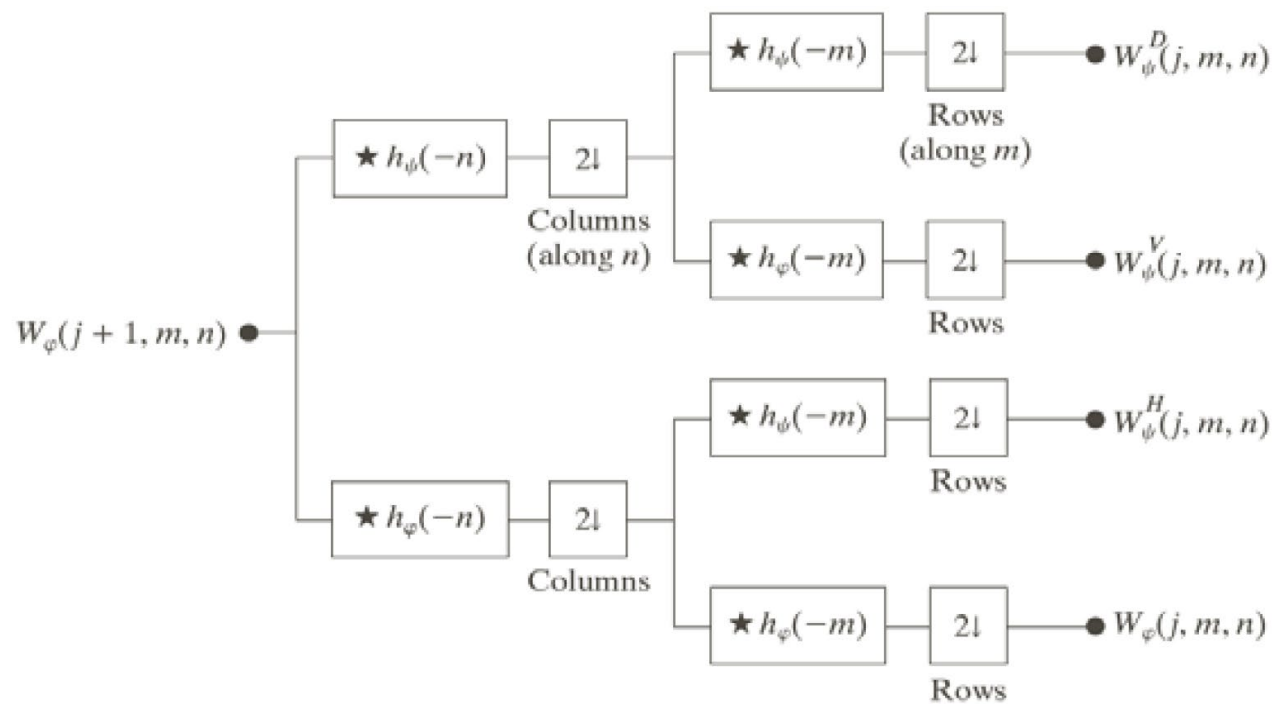
For computing *level 2* components:

LL_2 is down-sample of LL_1 on both X and Y direction	$HL_2 = H_{L2} * I_{in}$ + downsample twice on Y direction
$LH_2 = I_{in} * H_{L2}$ + downsample twice on X direction	$HH_2 = H_{L2} * I_{in} * H_{L2}$

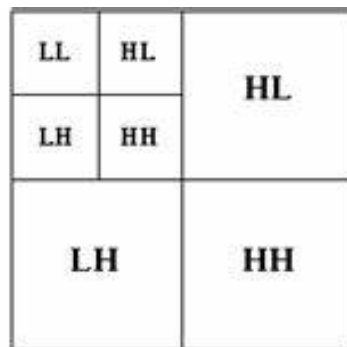
For computing *level 3* components:

LL_3 is down-sample of LL_2 on both X and Y direction	$HL_3 = H_{L3} * I_{in}$ + downsample 3 times on Y direction
$LH_3 = I_{in} * H_{L3}$ + downsample 3 times on X direction	$HH_3 = H_{L3} * I_{in} * H_{L3}$

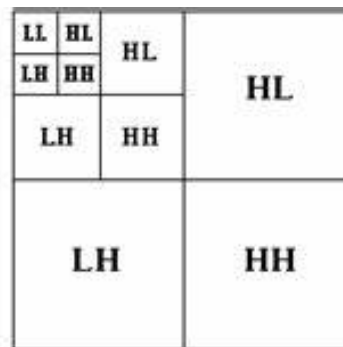
2D-DWT



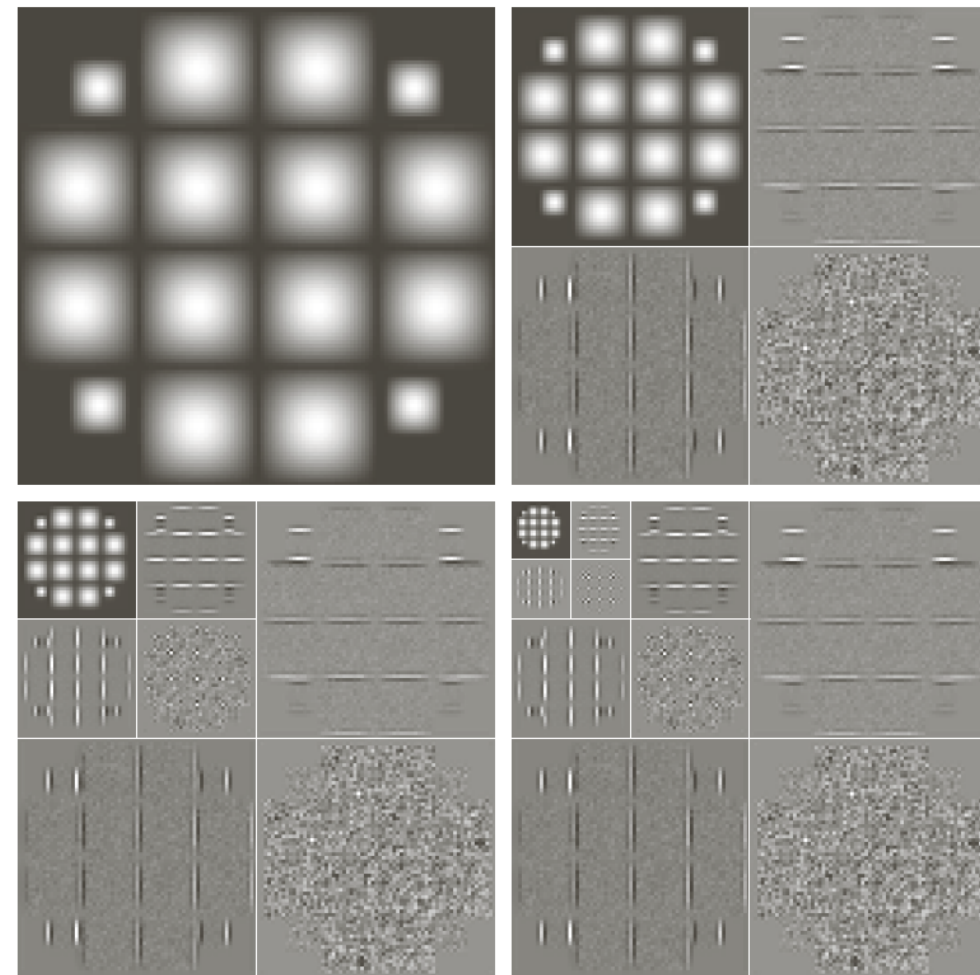
(a) Single Level Decomposition



(b) Two Level Decomposition



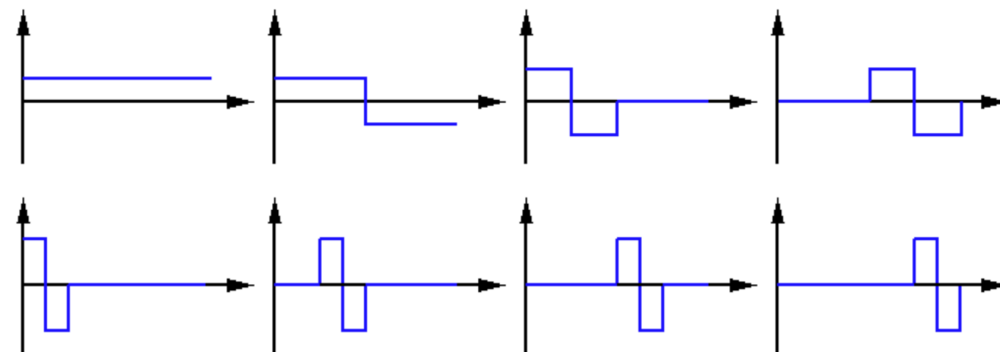
(c) Three Level Decomposition



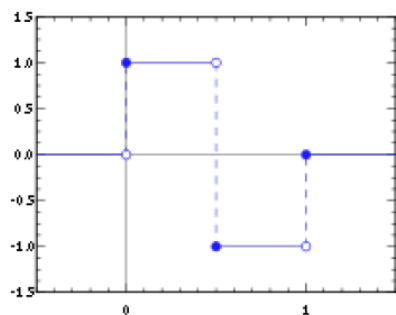
Mother Wavelet (母小波)

➤ Mother Wavelet should satisfy:

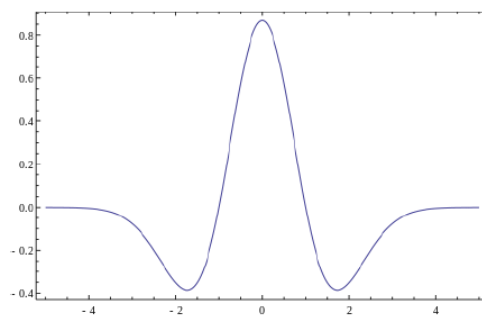
- $\int_{-\infty}^{\infty} |\psi(t)|^2 dt = 1$
- $\int_{-\infty}^{\infty} |\psi(t)| dt < \infty$
- $\int_{-\infty}^{\infty} \psi(t) dt = 0$



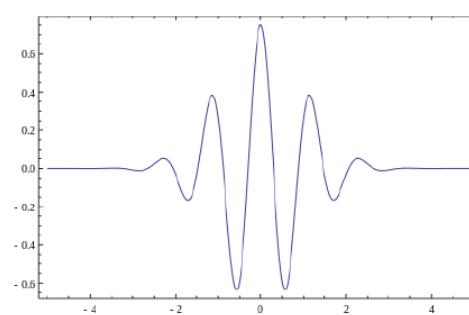
Haar



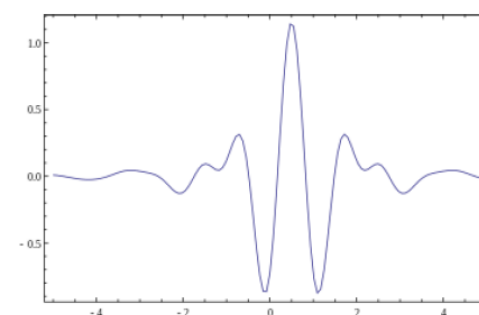
Mexican Hat



Morlet



Meyer



Take home message

- Based on small waves called Wavelets-1) limited; 2) oscillation.
- Key idea: Translation & Scaling.
- Localized both time/space and frequency.
- Efficient for noise reduction and image compression.
- JPEG2000, FBI finger printing databased.

