

Tutorial 4

TA: Mengyun Liu, Hongtu Xu

Agenda

- **B-Spline Curve**

- Formulation
- Point evaluation
- Target evaluation

- **B-Spline Surface**

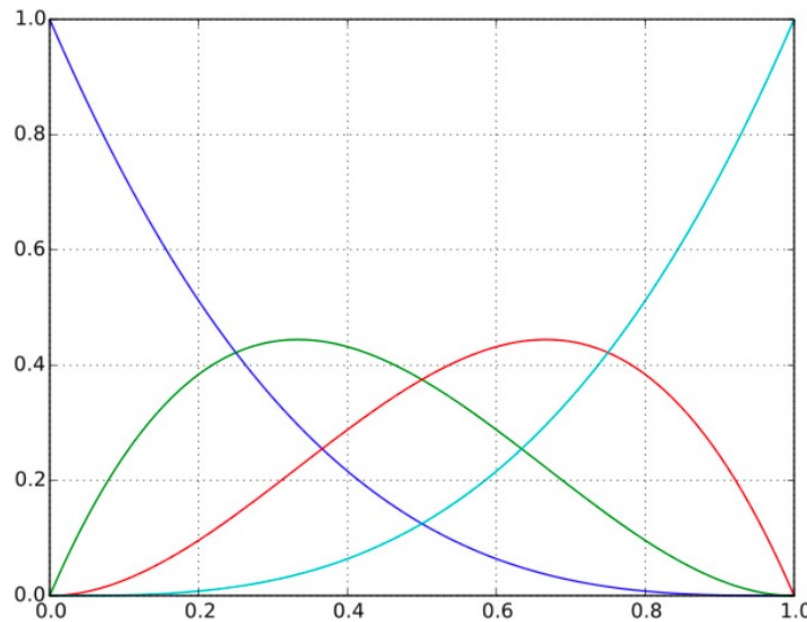
- Formulation
- Point evaluation based on curve formulation
- Normal evaluation

B-spline Curve

Motivation

- **Drawback of Bézier curve**

- Editing one single point will effect the evaluation of the whole curve
- Basis functions are global over the definition domain



blue: $y_0 = (1 - t)^3$
green: $y_1 = 3(1 - t)^2 t$
red: $y_2 = 3(1 - t) t^2$
cyan: $y_3 = t^3$

Basis functions of Cubic Bézier Curves for t in $[0, 1]$

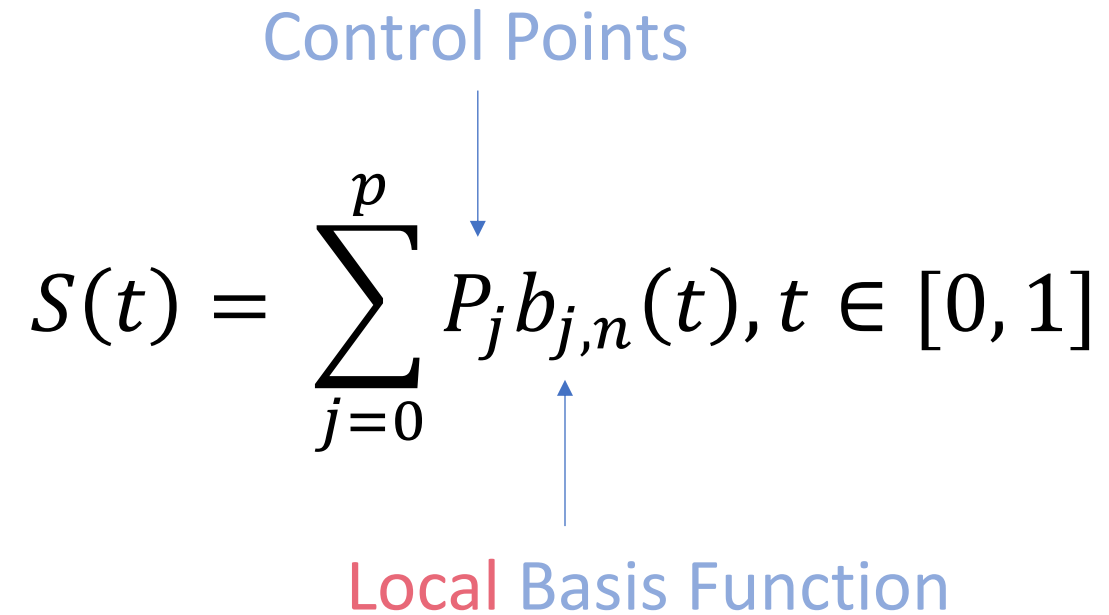
B-spline Curve

- n -order B-spline curve with $p+1$ control points

Control Points

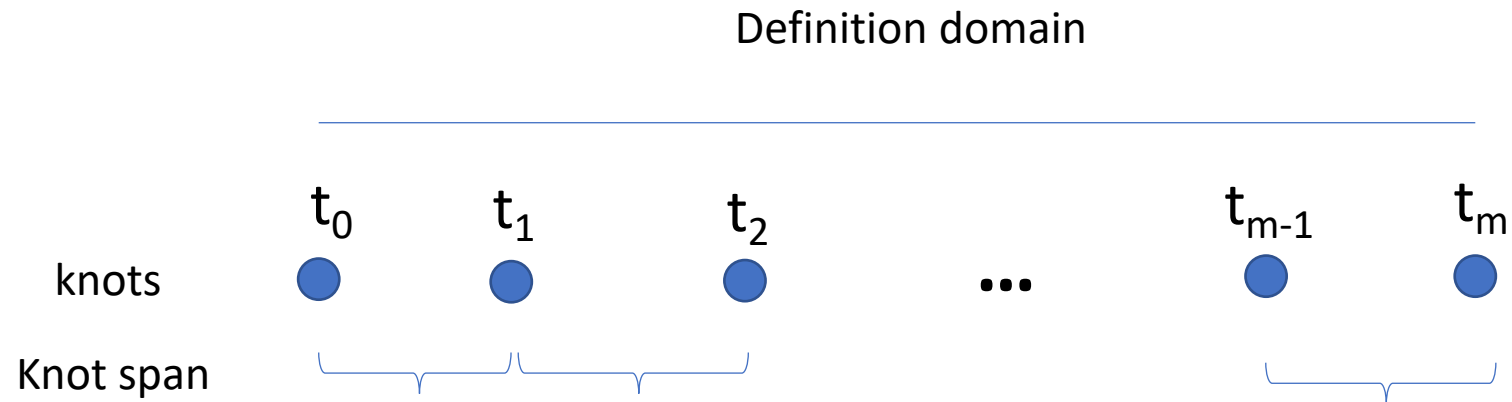
$$S(t) = \sum_{j=0}^p P_j b_{j,n}(t), t \in [0, 1]$$

Local Basis Function



Basis Function of B-Spline Curve

- $m + 1$ Knots

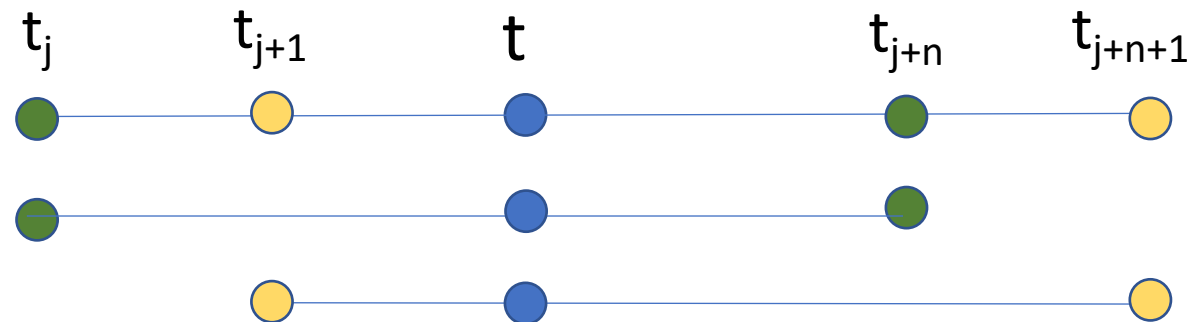


Basis Function of B-Spline Curve

- Recursive definition of $b_{j,n}(t)$

$$b_{j,0}(t) := \begin{cases} 1 & t_j < t < t_{j+1} \\ 0 & \dots \end{cases}$$

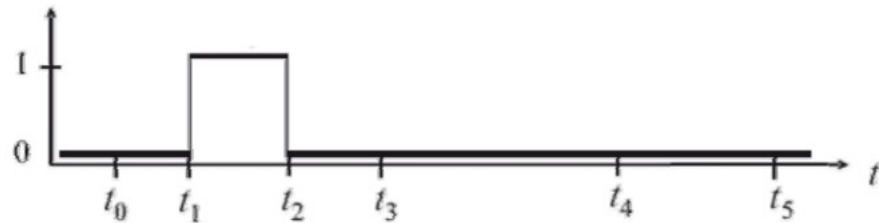
$$b_{j,n}(t) := \frac{t - t_j}{t_{j+n} - t_j} b_{j,n-1}(t) + \frac{t_{j+n+1} - t}{t_{j+n+1} - t_{j+1}} b_{j+1,n-1}(t).$$



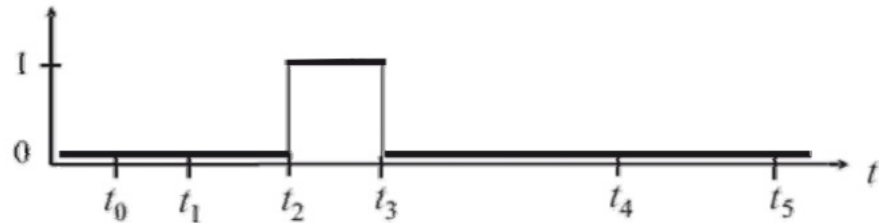
Basis Function of B-Spline Curve

- **A simple example**

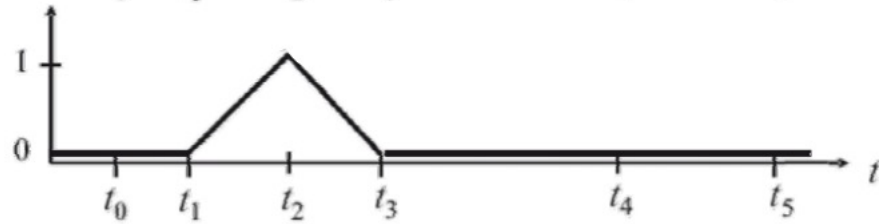
- $b_{1,0}(t)$ is non-zero in $[t_1, t_2]$, and $b_{2,0}(t)$ is non-zero in $[t_2, t_3]$
- $b_{1,1}(t)$ is non-zero in $[t_1, t_3]$



$b_{1,0}(t)$



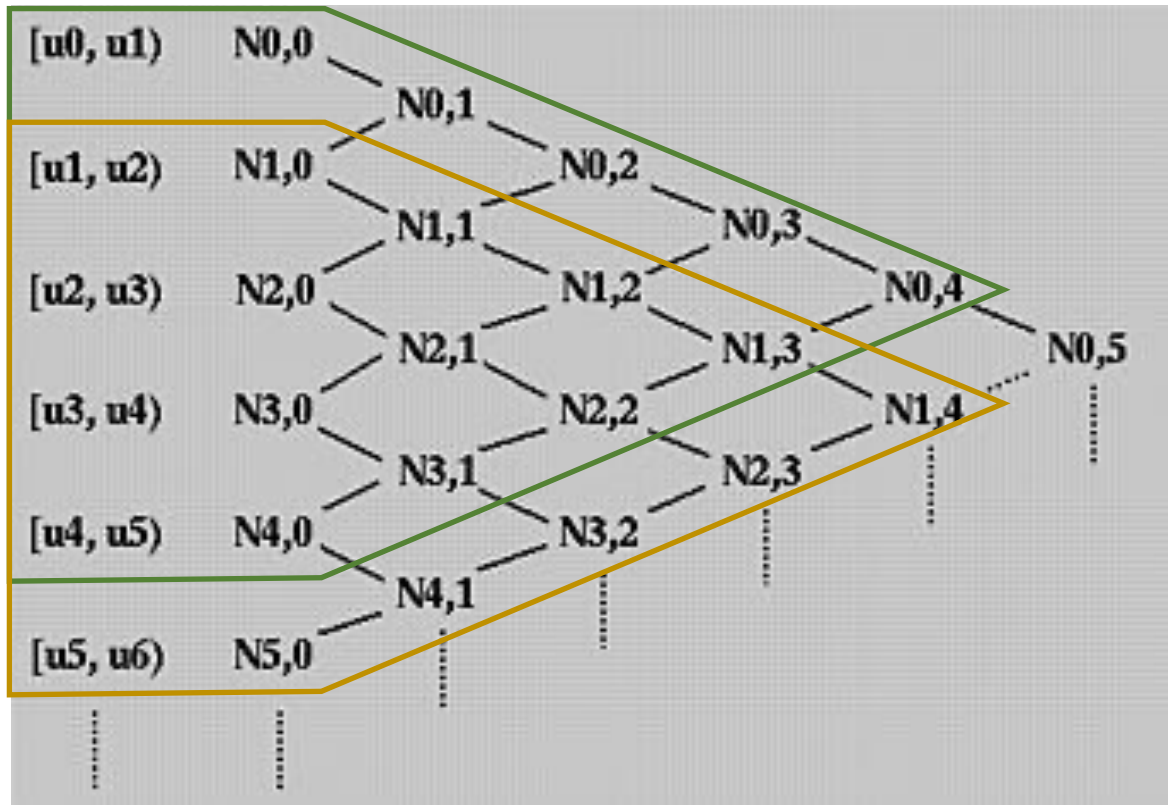
$b_{2,0}(t)$



$b_{1,1}(t)$

Basis Function of B-Spline Curve

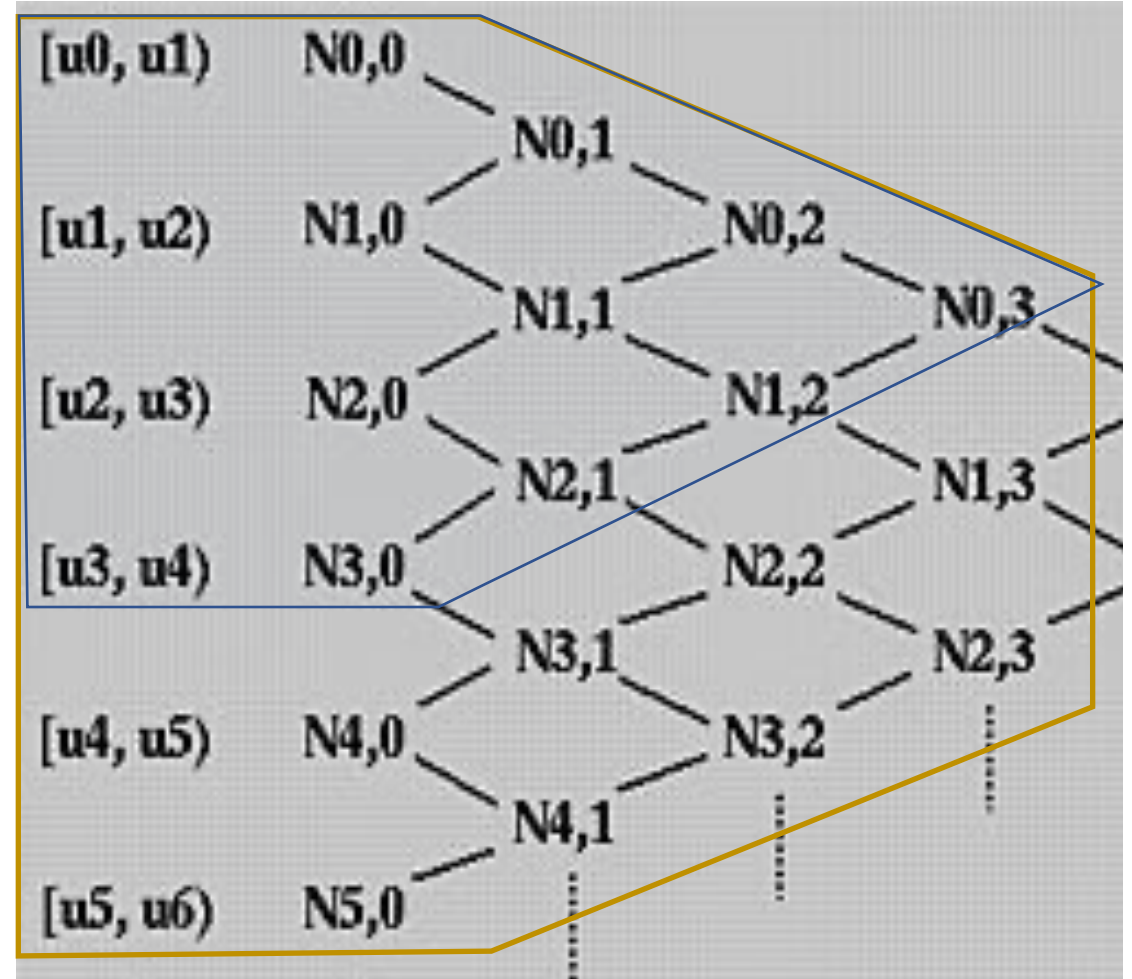
- An illustration on how to compute $b_{0,5}(t)$



- $b_{0,5}(t) = \frac{t-t_0}{t_5-t_0} b_{0,4}(t) + \frac{t_6-t}{t_6-t_1} b_{1,4}(t)$
- Its support is $[t_0, t_6]$

Relationship between $p+1, m+1, n$

- $p+1$: number of control points
- n : order of basis function
- $m+1$: number of knots
- Relationship: $m = p + n + 1$



Derivative of a B-spline Curve

- Formulation

$$\mathbf{C}(u) = \sum_{i=0}^n N_{i,p}(u) \mathbf{P}_i$$

$$\frac{d}{du} N_{i,p}(u) = N'_{i,p}(u) = \frac{p}{u_{i+p} - u_i} N_{i,p-1}(u) - \frac{p}{u_{i+p+1} - u_{i+1}} N_{i+1,p-1}(u)$$

$$\frac{d}{du} \mathbf{C}(u) = \mathbf{C}'(u) = \sum_{i=0}^{n-1} N_{i+1,p-1}(u) \mathbf{Q}_i$$

$$\mathbf{Q}_i = \frac{p}{u_{i+p+1} - u_{i+1}} (\mathbf{P}_{i+1} - \mathbf{P}_i)$$

The derivative of a B-spline curve is another B-spline curve of degree $p - 1$ on the original knot vector with a new set of n control points $\mathbf{Q}_0, \mathbf{Q}_1, \dots, \mathbf{Q}_{n-1}$

Derivative of a B-spline Curve

- Finite difference method

$$\mathbf{C}'(u) = \frac{\mathbf{C}(u + \delta u) - \mathbf{C}(u)}{\delta u}$$

B-spline Surface

B-spline Surfaces: Construction

- **What we needs**

- a set of $m+1$ rows and $n+1$ control points $\mathbf{p}_{i,j}$
 - where $0 \leq i \leq m$ and $0 \leq j \leq n$;
- a knot vector of $h + 1$ knots in the u -direction, $U = \{ u_0, u_1, \dots, u_h \}$;
- a knot vector of $k + 1$ knots in the v -direction, $V = \{ v_0, v_1, \dots, v_k \}$;
- the degree p in the u -direction;
- the degree q in the v -direction;

- **We also have**

- $h = m + p + 1$
- $k = n + q + 1$

Evaluation position

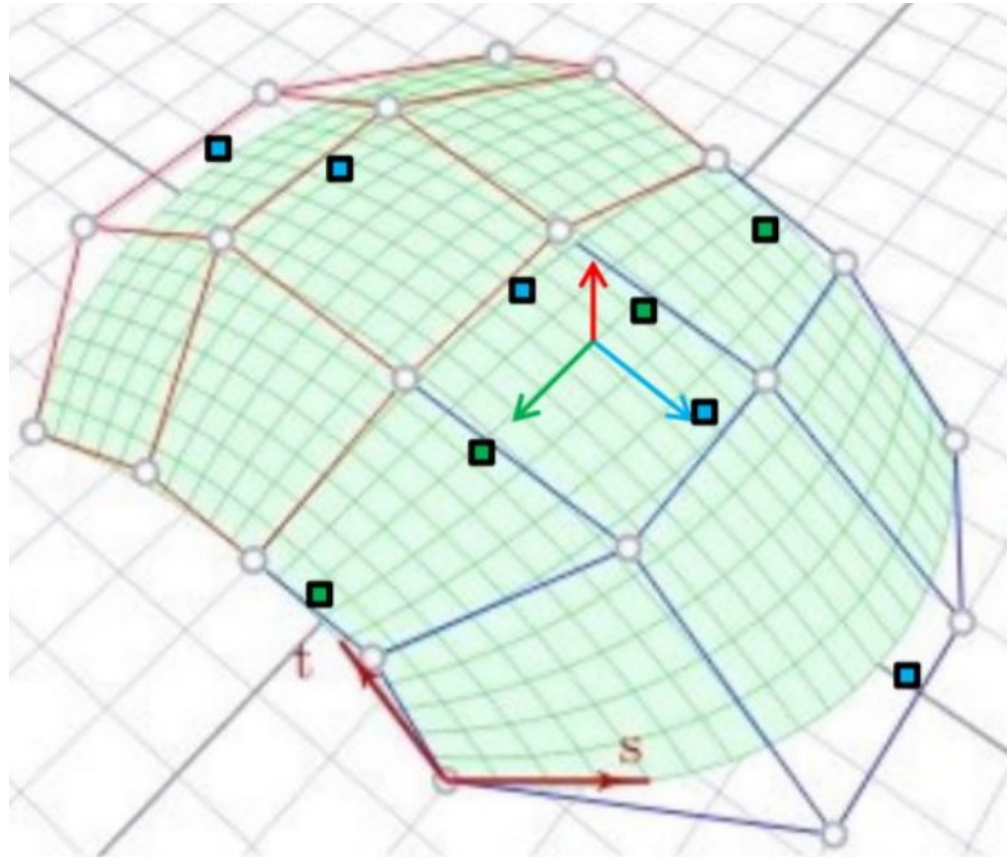
- Evaluate points in B-spline surface

$$\mathbf{p}(u, v) = \sum_{i=0}^m \sum_{j=0}^n N_{i,p}(u) N_{j,q}(v) \mathbf{k}_{i,j}$$

- First evaluate along u direction,
- Then evaluate along v direction

Normal Evaluation

- Similar to the normal evaluation of Bézier surface



Thanks