

**Problem 1** Note that

$$H(j\omega) = \begin{cases} \frac{j\omega}{3\pi}, & -3\pi \leq \omega \leq 3\pi \\ 0, & \text{otherwise} \end{cases}$$

- (a) Since  $x(t) = \cos(2\pi t + \theta)$ ,  $X(j\omega) = e^{j\theta}\pi\delta(\omega - 2\pi) + e^{-j\theta}\pi\delta(\omega + 2\pi)$ . This is zero outside the region  $-3\pi < \omega < 3\pi$ . Thus,  $Y(j\omega) = H(j\omega)X(j\omega) = (j\omega/3\pi)X(j\omega)$ . This implies that  $y(t) = (1/3\pi)dx(t)/dt = (-2/3)\sin(2\pi t + \theta)$ .
- (b) Since  $x(t) = \cos(4\pi t + \theta)$ ,  $X(j\omega) = e^{j\theta}\pi\delta(\omega - 4\pi) + e^{-j\theta}\pi\delta(\omega + 4\pi)$ . Therefore, the nonzero portions of  $X(j\omega)$  lie outside the range  $-3\pi < \omega < 3\pi$ . This implies that  $Y(j\omega) = X(j\omega)H(j\omega) = 0$ . Therefore,  $y(t) = 0$ .
- (c) The Fourier series coefficients of the signal  $x(t)$  are given by

$$a_k = \frac{1}{T_0} \int_{\langle T_0 \rangle} x(t) e^{-jk\omega_0 t} dt,$$

where  $T_0 = 1$  and  $\omega_0 = 2\pi/T_0 = 2\pi$ . Also,

$$X(j\omega) = 2\pi \sum_{k=-\infty}^{+\infty} a_k \delta(\omega - k\omega_0)$$

The only impulses of  $X(j\omega)$  which lie in the region  $-3\pi < \omega < 3\pi$  are at  $\omega = 0, -2\pi$ , and  $2\pi$ . Defining the signal  $x_{tp}(t) = a_0 + a_1 e^{j2\pi t} + a_{-1} e^{-j2\pi t}$ , we note that  $y(t) = (1/3\pi)dx_{tp}(t)/dt$ . We can also easily show that  $a_0 = 1/\pi, a_1 = 1/(4j), a_{-1} = -1/(4j)$ . Putting these into the expression for  $x_{tp}(t)$  we obtain  $x_{tp}(t) = (1/\pi) + (1/2)\sin(2\pi t)$ .

Finally,  $y(t) = (1/3\pi)dx_{tp}(t)/dt = (1/3)\cos(2\pi t)$ .

**Problem 2** (a) Taking the Fourier transform of both sides of the given differential equation, we obtain

$$H(j\omega) = \frac{Y(j\omega)}{X(j\omega)} = \frac{1}{2 + j\omega}$$

The Bode plot is as shown in **Figure 2**.

# First-order systems



**Bold Plots (Continuous time)**  $H(j\omega) = \frac{1}{j\omega\tau + 1}$

□  $20\log_{10}|H(j\omega)| = -10\log_{10}[(\omega\tau)^2 + 1]$

$$\simeq \begin{cases} 0, & \omega \ll 1/\tau \\ -20\log_{10}(\omega) - 20\log_{10}(\tau), & \omega \gg 1/\tau \end{cases}$$

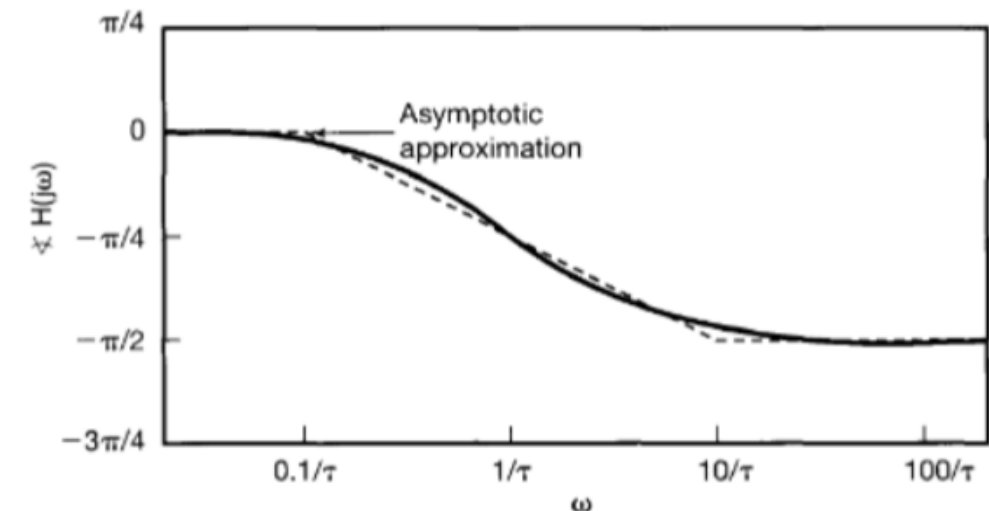
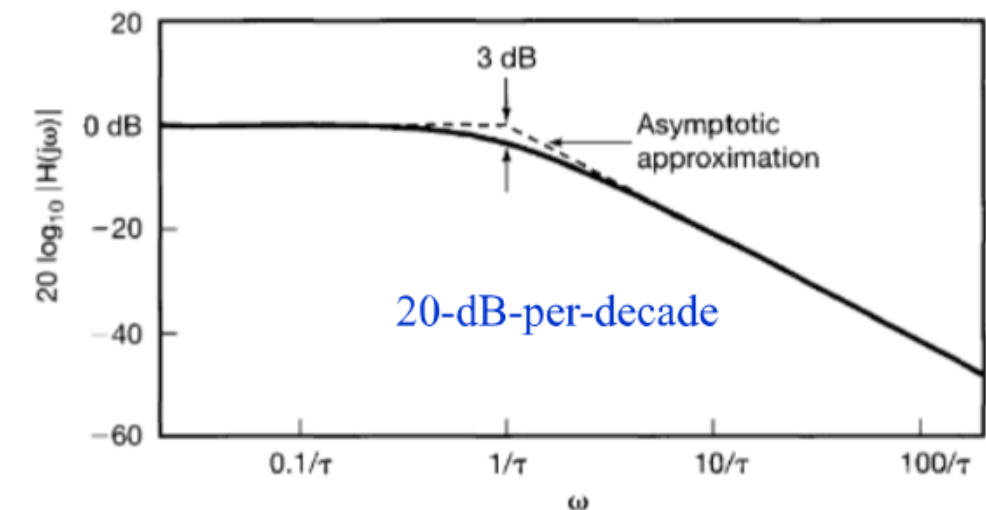
$\omega = 1/\tau, 20\log_{10}|H(j\omega)| = -10\log_{10}(2) \simeq -3dB$

$\omega = 1/\tau$ : break frequency

□  $\angle H(j\omega) = -\tan^{-1}(\omega\tau)$

$$\simeq \begin{cases} 0, & \omega \leq 0.1/\tau \\ -\frac{\pi}{4}[\log_{10}(\omega\tau) + 1], & 0.1/\tau \leq \omega \leq 10/\tau \\ -\pi/2, & \omega \geq 10/\tau \end{cases}$$

$\omega = 1/\tau, \angle H(j\omega) = -\pi/4$



$\tau \downarrow, h(t)$  and  $s(t)$  more sharply, break frequency  $\uparrow$ .

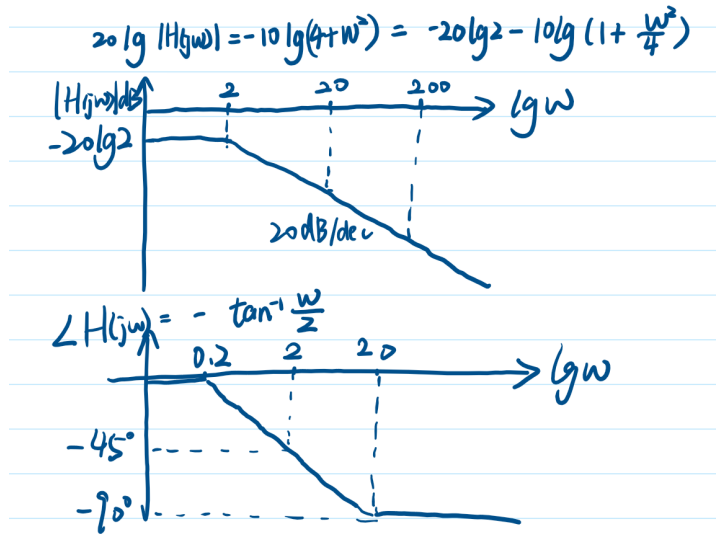


Figure 2

(b) From the expression for  $H(j\omega)$  we obtain

$$\angle H(j\omega) = -\tan^{-1}(\omega/2).$$

Therefore,

$$\tau(\omega) = \frac{d\angle H(j\omega)}{d\omega} = \frac{2}{4 + \omega^2}.$$

(c) (i) Here,

$$Y(j\omega) = \frac{1 + j\omega}{(2 + j\omega)^2}.$$

Taking the inverse Fourier transform of the partial fraction expansion of  $Y(j\omega)$ , we obtain

$$y(t) = e^{-2t}u(t) - te^{-2t}u(t).$$

(ii) Here,

$$Y(j\omega) = \frac{1}{(1 + j\omega)}$$

Taking the inverse Fourier transform of  $Y(j\omega)$ , we obtain

$$y(t) = e^{-t}u(t)$$

(iii) Here,

$$Y(j\omega) = \frac{1}{(1 + j\omega)(2 + j\omega)^2}.$$

Taking the inverse Fourier transform of the partial fraction expansion of  $Y(j\omega)$ , we obtain

$$y(t) = e^{-t}u(t) - e^{-2t}u(t) - te^{-2t}u(t).$$

### Problem 3

(10 points) Consider the discrete-time sequence  $x[n] = \cos[n\pi/5]$ , find two different continuous-time signals that would produce this sequence when sampled at a frequency of  $f_s = 500\text{Hz}$ .

#### Solution

A continuous-time sinusoid

$$x_a(t) = \cos(w_0 t) = \cos(2\pi f_0 t) \quad (8)$$

that is sampled with a sampling frequency of  $f_s$  results in the discrete-time sequence

$$x[n] = x_a(nT_s) = \cos(2\pi \frac{f_0}{f_s} n) \quad (9)$$

However, note that for any integer  $k$ ,

$$\cos(2\pi \frac{f_0}{f_s} n) = \cos(2\pi \frac{f_0 + kf_s}{f_s} n) \quad (10)$$

Therefore, any sinusoid with a frequency

$$f = f_0 + kf_s \quad (11)$$

will produce the same sequence of samples  $x[n]$  when sampled with a sampling frequency  $f_s$ . With  $x[n] = \cos(n\pi/5)$ , we want

$$2\pi \frac{f_0}{f_s} = \frac{\pi}{5} \quad (12)$$

or

$$f_0 = \frac{1}{10} f_s = 50\text{Hz} \quad (13)$$

Therefore, two signals that produce the given sequence are

$$x_1(t) = \cos(100\pi t) \quad (14)$$

and

$$x_2(t) = \cos(1100\pi t) \quad (15)$$

# Problem4

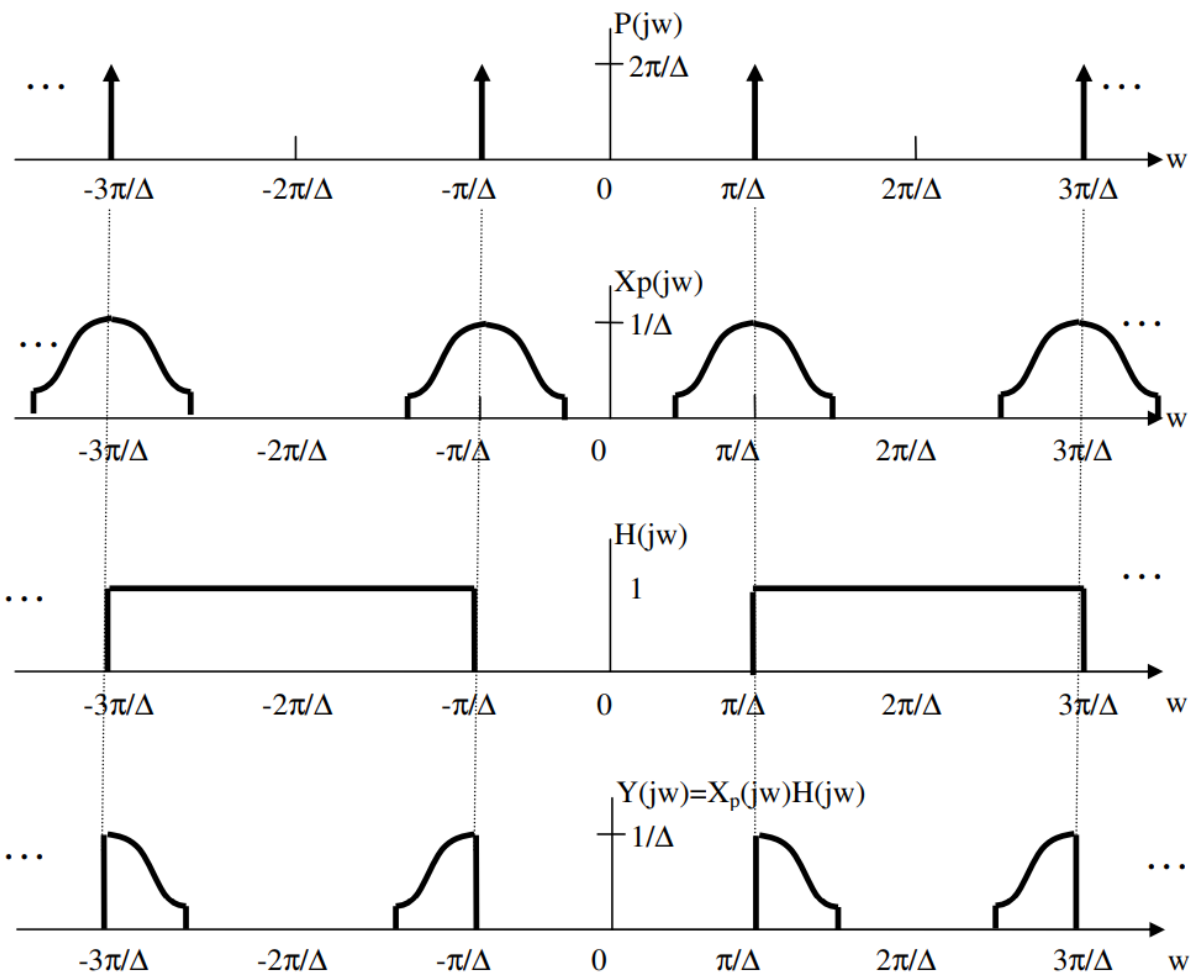
a) We can write  $p(t) = p_1(t) - p_1(t-\Delta)$  where  $p_1(t) = \sum_{k=-\infty}^{\infty} \delta(t - k2\Delta) \Rightarrow P_1(j\omega) = \frac{\pi}{\Delta} \sum_{k=-\infty}^{\infty} \delta(\omega - \frac{k\pi}{\Delta})$

using the above information and the time shifting property we can write  $P(j\omega)$  as:

$$P(j\omega) = P_1(j\omega) - e^{-j\omega\Delta} P_1(j\omega)$$

$$P(j\omega) = \frac{\pi}{\Delta} \left\{ \sum_{k=-\infty}^{\infty} \delta(\omega - \frac{k\pi}{\Delta}) - \sum_{k=-\infty}^{\infty} \delta(\omega - \frac{k\pi}{\Delta}) e^{-j\omega\Delta} \right\} \text{ where } e^{-j\omega\Delta} = e^{-j\pi k} = (-1)^k \text{ where } \omega = \pi k / \Delta$$

$$x_p(t) = x(t)p(t) \xrightarrow{FT} X_p(j\omega) = \frac{1}{2\pi} [X(j\omega) * P(j\omega)]$$

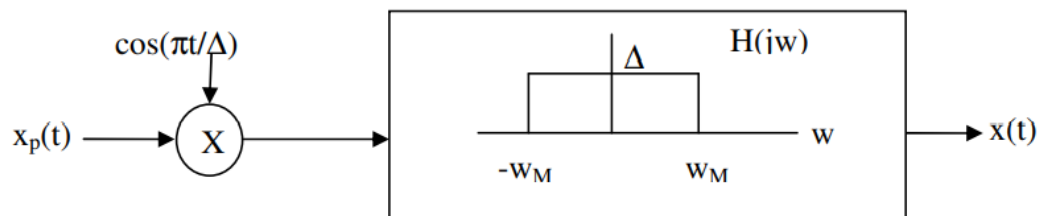


b) recovering  $x(t)$  from  $x_p(t)$

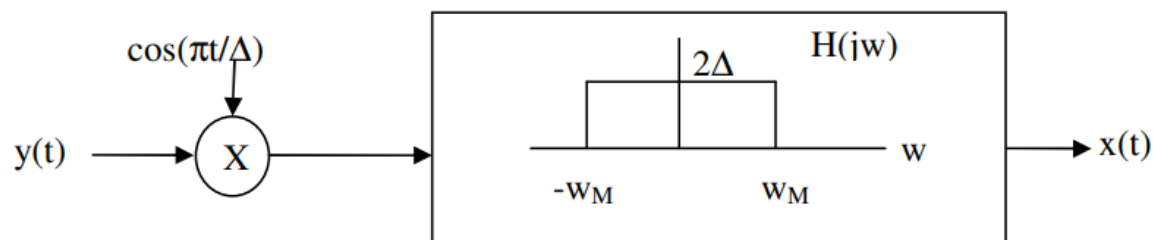
Let's use:

1)  $FT\{\cos(w_0 t)\} = \pi[\delta(w-w_0) + \delta(w-w_0)]$

2) Convolutions  $FT\{x_p(t)\cos(\pi t/\Delta)\} = (1/2\pi)X_p(jw)*\{\pi[\delta(w-\pi/\Delta) + \delta(w-\pi/\Delta)]\}$

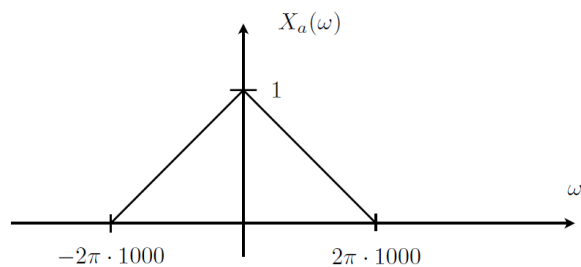


c) recovering  $x(t)$  from  $y(t)$  – use similar process as b.



### Problem5

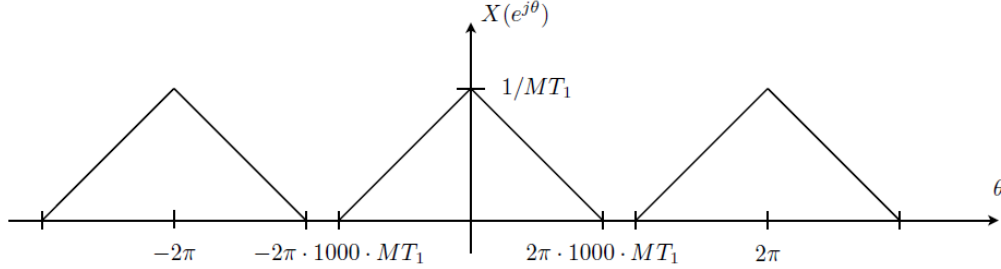
(a) Suppose that  $x_a(t)$  has a Fourier transform as shown in the figure below. Because  $y(n) =$



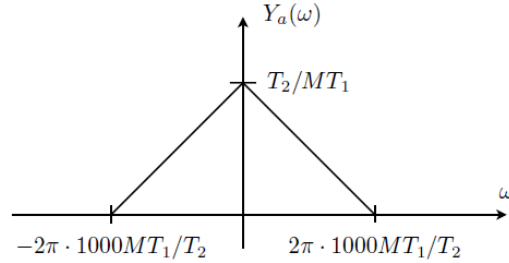
$x(Mn) = x_a(nMT_1)$ , in order to prevent  $x(n)$  from being aliased, it is necessary that

$$MT_1 < \frac{1}{2000}$$

If this constraint is satisfied, the output of the down-sampler has a FTD as shown below.



Going through the D/C converter produces signal  $y_a(t)$ , which has the Fourier transform shown below.



1.  $MT_1 \leq 1/2000$  in order to avoid aliasing.
  2.  $T_2 = MT_1$  to prevent frequency scaling.
- (b) With  $T_1 = T_2 = 1/20000$  and  $M = 4$ , note that

$$MT_1 = \frac{1}{5000} < \frac{1}{2000}$$

Therefore, there is no aliasing. Thus, as we see from the figure above,

$$Y_a(\omega) = \frac{1}{4} X_a\left(\frac{\omega}{4}\right)$$

or

$$y_a(t) = x_a(4t)$$