

## 2. Convex sets

- affine and convex sets
- some important examples
- operations that preserve convexity
- generalized inequalities
- separating and supporting hyperplanes
- dual cones and generalized inequalities

# Affine Set, Convex Set, Convex Conic Set

$$x_1, x_2 \in C, \quad \theta_1 x_1 + \theta_2 x_2 \in C$$

Affine	Convex	Convex cone
$\theta_1 + \theta_2 = 1$	$\theta_1 + \theta_2 = 1$ $\theta_1, \theta_2 \geq 0$	$\theta_1, \theta_2 \geq 0$

① affine  $\Rightarrow$  convex

② convex cone  $\Rightarrow$  convex

③ convex  $\nRightarrow$  affine

④ convex  $\nRightarrow$  convex cone

# Positive semidefinite cone

notation:

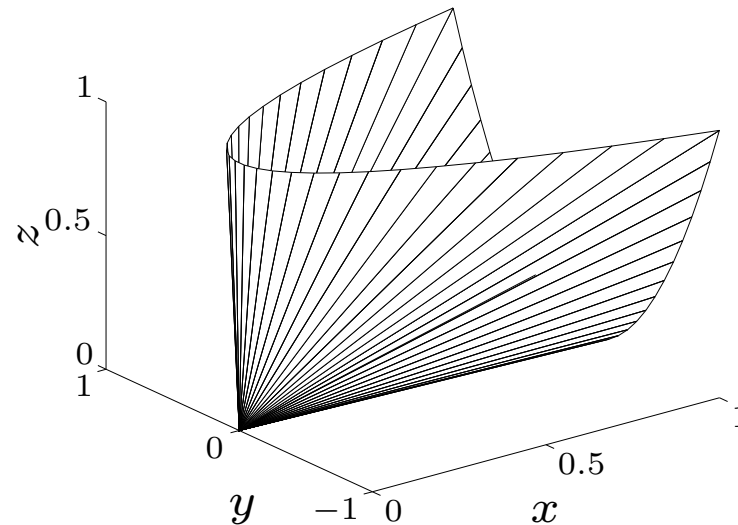
- $\mathbf{S}^n$  is set of symmetric  $n \times n$  matrices
- $\mathbf{S}_+^n = \{X \in \mathbf{S}^n \mid X \succeq 0\}$ : positive semidefinite  $n \times n$  matrices

$$X \in \mathbf{S}_+^n \iff z^T X z \geq 0 \text{ for all } z$$

$\mathbf{S}_+^n$  is a convex cone

- $\mathbf{S}_{++}^n = \{X \in \mathbf{S}^n \mid X \succ 0\}$ : positive definite  $n \times n$  matrices

example:  $\begin{bmatrix} x & y \\ y & z \end{bmatrix} \in \mathbf{S}_+^2$



# Operations that preserve convexity

practical methods for establishing convexity of a set  $C$

1. apply definition

$$x_1, x_2 \in C, \quad 0 \leq \theta \leq 1 \quad \implies \quad \theta x_1 + (1 - \theta)x_2 \in C$$

2. show that  $C$  is obtained from simple convex sets (hyperplanes, halfspaces, norm balls, . . . ) by operations that preserve convexity

- intersection
- affine functions
- perspective function
- linear-fractional functions

# Intersection

$$S_1, S_2, \quad \underline{S = S_1 \cap S_2}$$

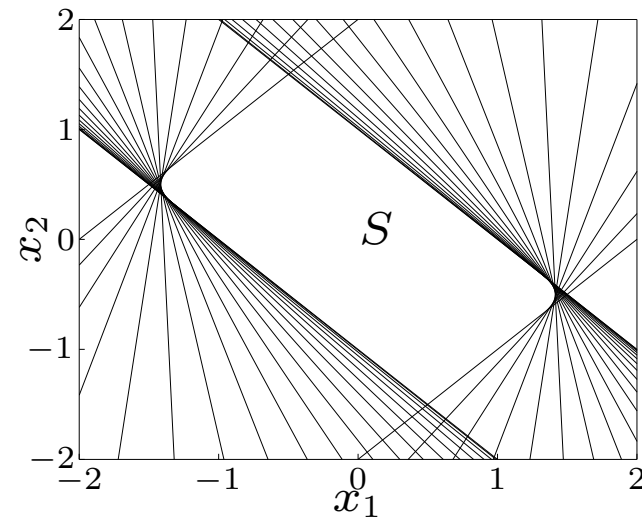
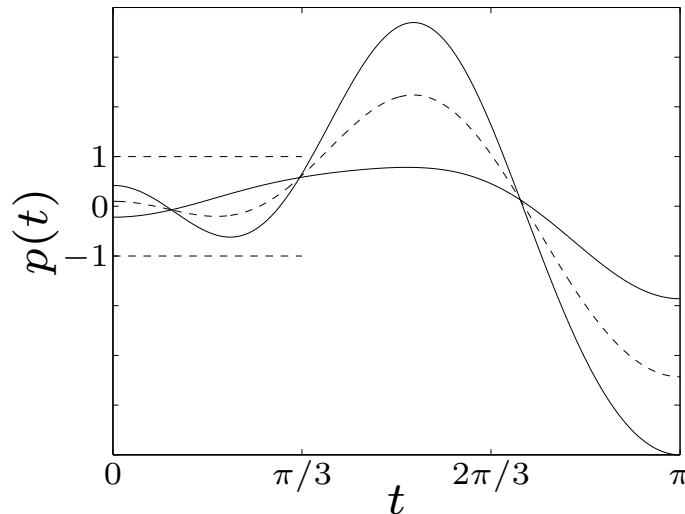
the intersection of (any number of) convex sets is convex

**example:**

$$S = \{x \in \mathbf{R}^m \mid |p(t)| \leq 1 \text{ for } |t| \leq \pi/3\}$$

where  $p(t) = x_1 \cos t + x_2 \cos 2t + \cdots + x_m \cos mt$

for  $m = 2$ :



$$\bigcap_{z \neq 0} \{x \in S^n \mid \underline{z^T x z \geq 0}\}$$

$$\underline{a^T x \geq b}$$

$\mathbf{R}^n$

# Affine function

suppose  $f : \mathbf{R}^n \rightarrow \mathbf{R}^m$  is affine ( $f(x) = Ax + b$  with  $A \in \mathbf{R}^{m \times n}$ ,  $b \in \mathbf{R}^m$ )

- the image of a convex set under  $f$  is convex

$$S \subseteq \mathbf{R}^n \text{ convex} \implies f(S) = \{f(x) \mid x \in S\} \text{ convex}$$

Proof:  $f(x), f(y) \in f(S)$

$$x, y \in S$$

$$\underline{\theta f(x) + (1-\theta) f(y)} \in f(S)$$

$$\theta x + (1-\theta)y \in S$$

$$= \theta (Ax + b) + (1-\theta) (Ay + b)$$

$$= A(\underline{\theta x + (1-\theta)y}) + b \in f(S)$$

# Affine function

suppose  $f : \mathbf{R}^n \rightarrow \mathbf{R}^m$  is affine ( $f(x) = Ax + b$  with  $A \in \mathbf{R}^{m \times n}$ ,  $b \in \mathbf{R}^m$ )

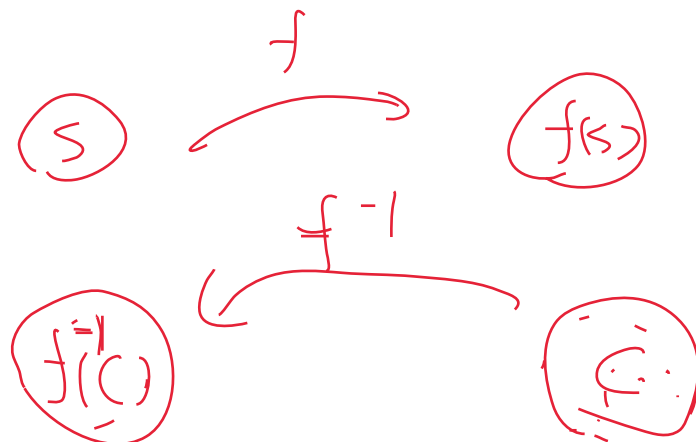
- the image of a convex set under  $f$  is convex

$$S \subseteq \mathbf{R}^n \text{ convex} \implies f(S) = \{f(x) \mid x \in S\} \text{ convex}$$

- the inverse image  $f^{-1}(C)$  of a convex set under  $f$  is convex

**Quiz**  $C \subseteq \mathbf{R}^m$  convex  $\implies f^{-1}(C) = \{x \in \mathbf{R}^n \mid f(x) \in C\}$  convex

$$x, y \in f^{-1}(C), \quad \underline{\theta x + (1-\theta)y \in f^{-1}(C)}$$



# Affine function

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## examples

$$\{ax \mid x \in S\}$$

$$\{a+x \mid x \in S\}$$

$$\{x_1 \mid (x_1, x_2) \in S\}$$

- scaling, translation, projection

$$f(x) = B - \frac{A(x)}{\sum_{i=1}^m x_i A_i}$$

$$\{x \in \mathbf{R}^n \mid B - Ax \geq 0\}$$

- solution set of linear matrix inequality  $\{x \mid x_1 A_1 + \dots + x_m A_m \preceq B\}$   
(with  $A_i, B \in \mathbf{S}^p$ ) (LMI)

- hyperbolic cone  $\{x \mid x^T P x \leq (c^T x)^2, c^T x \geq 0\}$  (with  $P \in \mathbf{S}_+^n$ )

$$\{ \begin{bmatrix} z \\ u \end{bmatrix} \mid \|z\|_2 \leq u, u > 0 \}$$

$$f(x) = \begin{bmatrix} p^{\frac{1}{2}} x \\ c^T x \end{bmatrix}$$



# Perspective and linear-fractional function

perspective function  $P : \mathbf{R}^{n+1} \rightarrow \mathbf{R}^n$ :

$$\begin{bmatrix} x_1 \\ x_2 \\ \textcircled{x_3} \\ \vdots \\ x_n \end{bmatrix} \xrightarrow{P} \begin{bmatrix} x_1/x_3 \\ x_2/x_3 \\ x_4/x_3 \\ \vdots \\ x_n/x_3 \end{bmatrix}$$

$n$

$$P(x, t) = x/t,$$

$$\text{dom } P = \{(x, t) \mid \underline{t} > 0\}$$

$$(x, t) = \begin{bmatrix} x_1 \\ \vdots \\ x_n \\ \textcircled{t} \end{bmatrix} \xrightarrow{P} \begin{bmatrix} x_1/t \\ \vdots \\ x_n/t \\ 1 \end{bmatrix} \xrightarrow{P} \begin{bmatrix} x_1/t \\ \vdots \\ x_n/t \end{bmatrix}$$

$\mathbf{R}^{n+1}$   $\mathbf{R}^n$

images and inverse images of convex sets under perspective are convex

$$f = \textcircled{P} \circ g$$

$$g(x) = \begin{bmatrix} A \\ \underline{c}^T \end{bmatrix} x + \begin{bmatrix} b \\ d \end{bmatrix}, \quad g: \mathbf{R}^n \rightarrow \mathbf{R}^{m+1}$$

$P: \mathbf{R}^{m+1} \rightarrow \mathbf{R}^m$

linear-fractional function  $f : \mathbf{R}^n \rightarrow \mathbf{R}^m$ :

$$f(x) = \frac{Ax + b}{c^T x + d},$$

$$\text{dom } f = \{x \mid c^T x + d > 0\}$$

$$f = P \circ g$$

images and inverse images of convex sets under linear-fractional functions are convex

$$\begin{bmatrix} \vdots \\ 1 \end{bmatrix} \xrightarrow{g} \begin{bmatrix} \vdots \\ 1 \end{bmatrix} \xrightarrow{P} \begin{bmatrix} \vdots \\ 1 \end{bmatrix}$$

$\mathbf{R}^n$   $\mathbf{R}^{m+1}$   $\mathbf{R}^m$

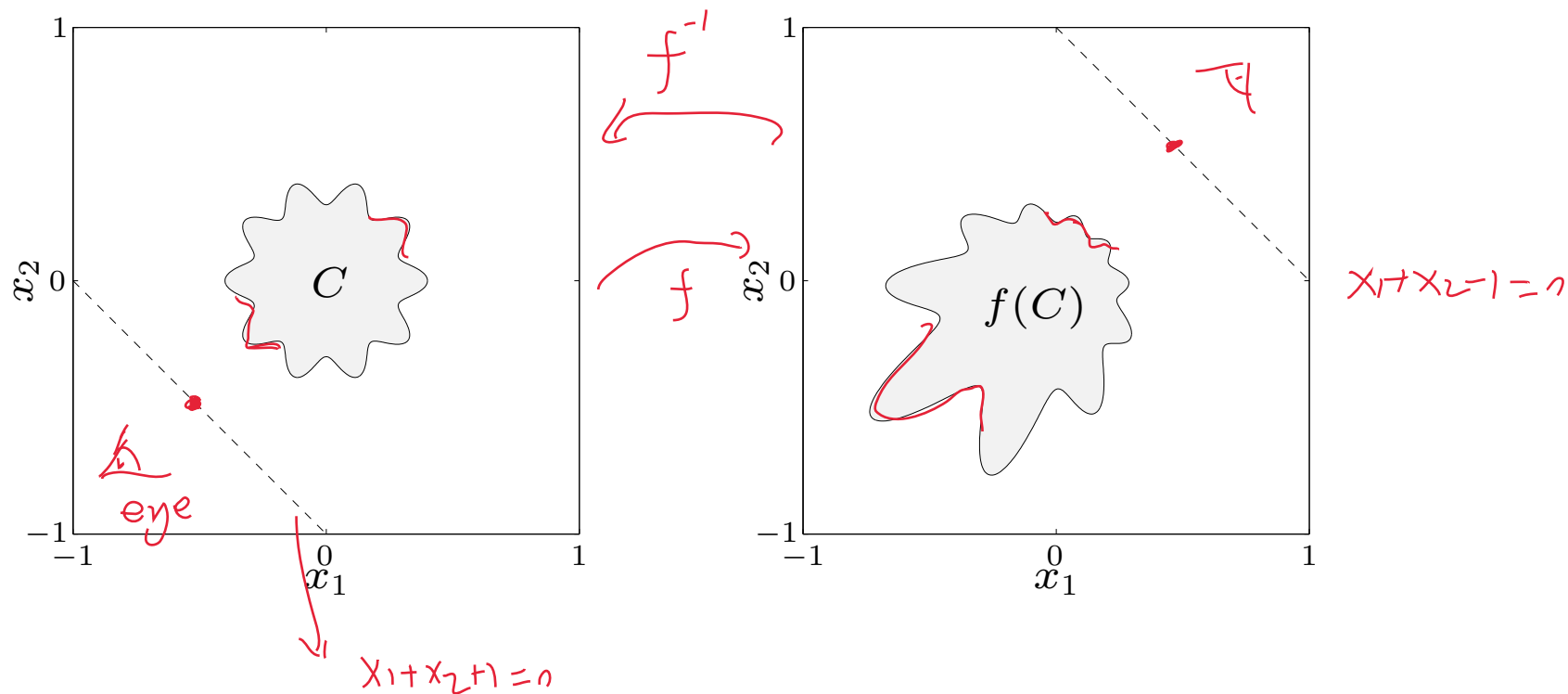
dom  $f$ :  $x_1 + x_2 + 1 > 0$

**example** of a linear-fractional function

$$f(x) = \frac{1}{x_1 + x_2 + 1} x$$

$$A = I, \quad b = 0$$

$$c = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \quad d = 1$$





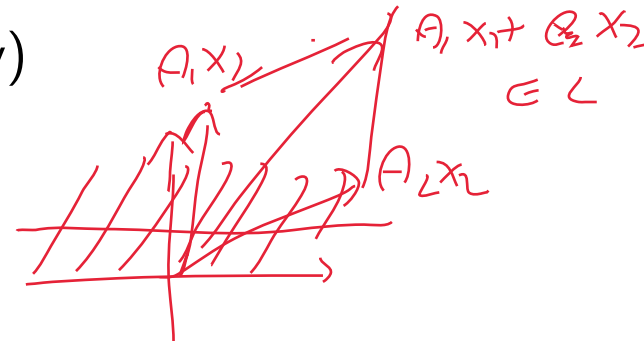
## Generalized inequalities

$C = \text{bdc} \cup \text{int} C$  (bdc  $\subset$  )  
boundary

$C = \text{int} C$  (int  $C$  )

a convex cone  $K \subseteq \mathbf{R}^n$  is a **proper cone** if

- $K$  is closed (contains its boundary)
- $K$  is solid (has nonempty interior)
- $K$  is pointed (contains no line)



examples



- nonnegative orthant  $K = \mathbf{R}_+^n = \{x \in \mathbf{R}^n \mid x_i \geq 0, i = 1, \dots, n\}$
- positive semidefinite cone  $K = \mathbf{S}_+^n$
- nonnegative polynomials on  $[0, 1]$ :

$$K = \{x \in \mathbf{R}^n \mid x_1 + x_2 t + x_3 t^2 + \dots + x_n t^{n-1} \geq 0 \text{ for } t \in [0, 1]\}$$

$$(x \succeq_K 0 \Leftrightarrow x \in K) \quad K = \mathbb{R}_+$$

**generalized inequality** defined by a proper cone  $K$ :

$$x \preceq_K y \iff y - x \in K, \quad x \prec_K y \iff y - x \in \text{int } K$$

$$x \leq y \iff y - x \geq 0, \quad y - x \in \mathbb{R}_+$$

**examples**

- componentwise inequality ( $K = \mathbb{R}_+^n$ )

$$x \preceq_{\mathbb{R}_+^n} y \iff x_i \leq y_i, \quad i = 1, \dots, n$$

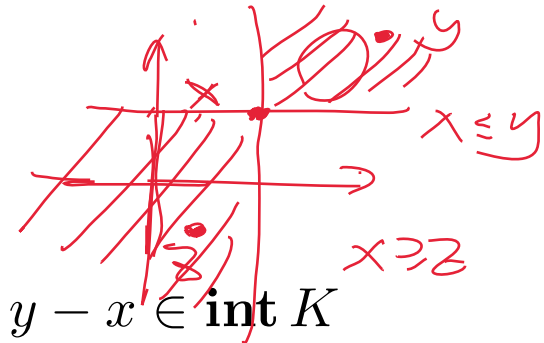
- matrix inequality ( $K = \mathbf{S}_+^n$ )

$$X \preceq_{\mathbf{S}_+^n} Y \iff Y - X \text{ positive semidefinite}$$

these two types are so common that we drop the subscript in  $\preceq_K$

**properties:** many properties of  $\preceq_K$  are similar to  $\leq$  on  $\mathbf{R}$ , e.g.,

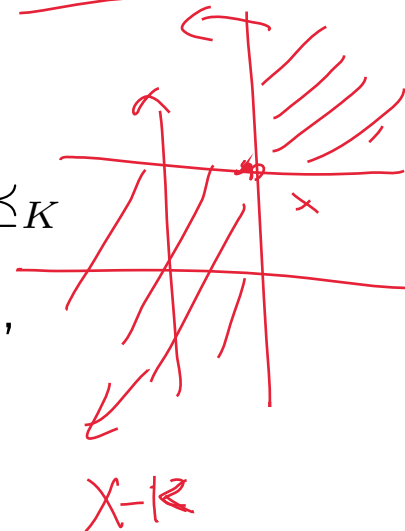
$$x \preceq_K y, \quad u \preceq_K v \implies x + u \preceq_K y + v$$



$$x \leq y \iff y - x \in \mathbb{R}_+$$

$$x \not\leq z, \quad x \not\leq \bar{z}$$

$$x + K$$



# Minimum and minimal elements

$\preceq_K$  is not in general a *linear ordering*: we can have  $x \not\preceq_K y$  and  $y \not\preceq_K x$

$x \in S$  is **the minimum element** of  $S$  with respect to  $\preceq_K$  if

$$\underline{y \in S \implies x \preceq_K y}$$

$$\underline{S \subseteq x+K}$$

$x \in S$  is a **minimal element** of  $S$  with respect to  $\preceq_K$  if

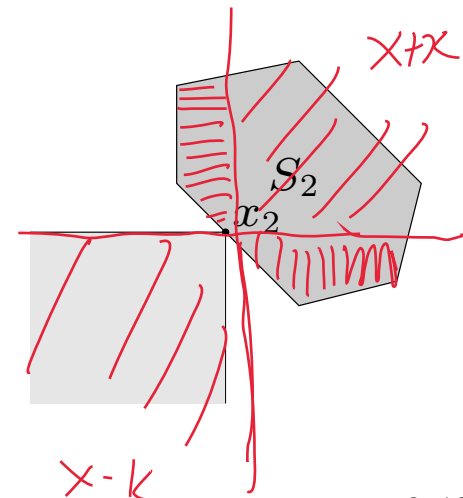
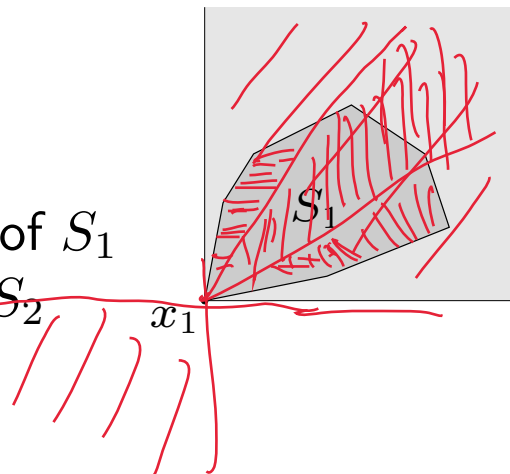
$$y \in S, \quad y \preceq_K x \implies y = x$$

$$S \cap (x-K) = \{x\}$$

**example** ( $K = \mathbf{R}_+^2$ )

$x_1$  is the minimum element of  $S_1$

$x_2$  is a minimal element of  $S_2$

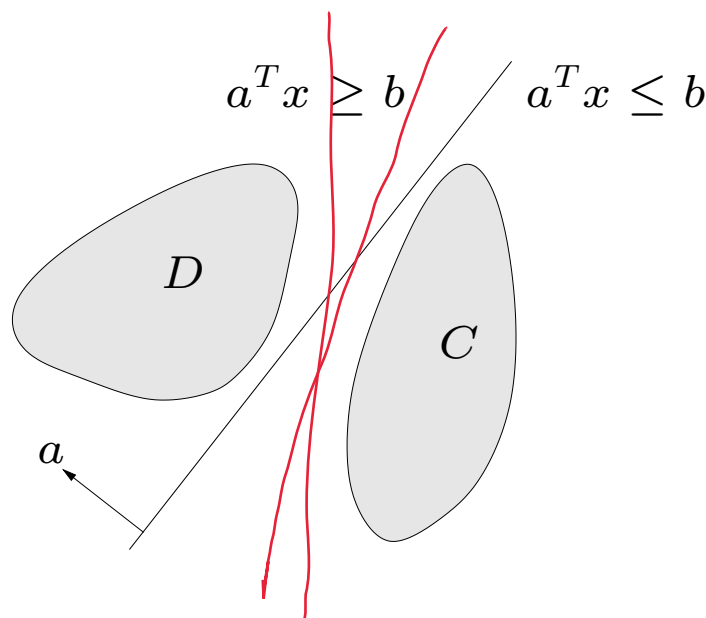


# Separating hyperplane theorem

$$C \cap D = \emptyset$$

if  $C$  and  $D$  are nonempty disjoint convex sets, there exist  $a \neq 0$ ,  $b$  s.t.

$$\underline{a^T x \leq b \text{ for } x \in C, \quad a^T x \geq b \text{ for } x \in D}$$



the hyperplane  $\{x \mid a^T x = b\}$  separates  $C$  and  $D$

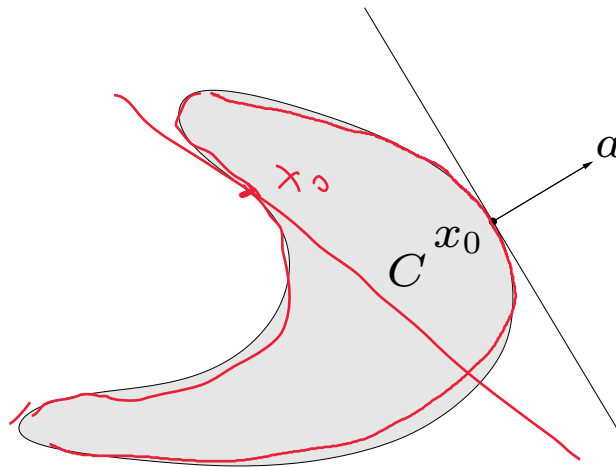
strict separation requires additional assumptions (e.g.,  $C$  is closed,  $D$  is a singleton)

# Supporting hyperplane theorem

supporting hyperplane to set  $C$  at boundary point  $x_0$ :

$$\{x \mid a^T x = a^T x_0\}$$

where  $a \neq 0$  and  $a^T x \leq a^T x_0$  for all  $x \in C$



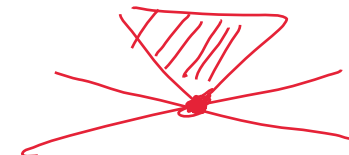
$C$  : convex

$x_0 \in \text{bd } C$

$\text{int } C$

$$\{x_0\} \cap \text{int } C = \emptyset$$

separating hyperplane



**supporting hyperplane theorem:** if  $C$  is convex, then there exists a supporting hyperplane at every boundary point of  $C$

$$\underline{x \succeq_K y \Rightarrow x - y \in K}$$

## Dual cones and generalized inequalities

$$x \in \mathbb{R}^n, A x \in \mathbb{C}, (A \succ 0)$$

dual cone of a cone  $K$ :

$$K^* = \{y \mid y^T x \geq 0 \text{ for all } x \in K\}$$

examples

- $K = \mathbf{R}_+^n$ :  $K^* = \mathbf{R}_+^n$
- $K = \mathbf{S}_+^n$ :  $K^* = \mathbf{S}_+^n$
- $K = \{(x, t) \mid \|x\|_2 \leq t\}$ :  $K^* = \{(x, t) \mid \|x\|_2 \leq t\}$
- $K = \{(x, t) \mid \|x\|_1 \leq t\}$ :  $K^* = \{(x, t) \mid \|x\|_\infty \leq t\}$

first three examples are **self-dual** cones ( $K^{**} = K$  if  $K$  is proper)

dual cones of proper cones are proper, hence define generalized inequalities:

$$\forall y \in S$$

$$x^T(y-x) \geq 0$$

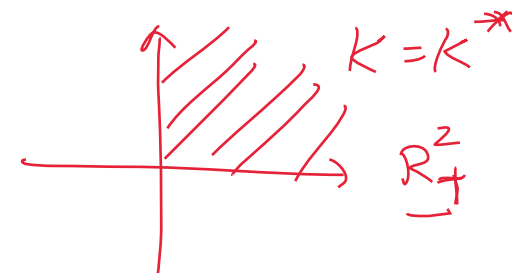
$$\lambda^T(y-x) = 0$$

Convex sets

$$y \succeq_{K^*} 0 \iff y^T x \geq 0 \text{ for all } x \succeq_K 0$$

$$y \succeq_{K^*} x \iff y^T \lambda \geq x^T \lambda, \forall \lambda \succeq_K 0$$

$$y \succeq_K x \iff y^T \lambda \geq x^T \lambda, \forall \lambda \succeq_{K^*} 0$$



$$\sup_{K^*} \lambda^T x$$

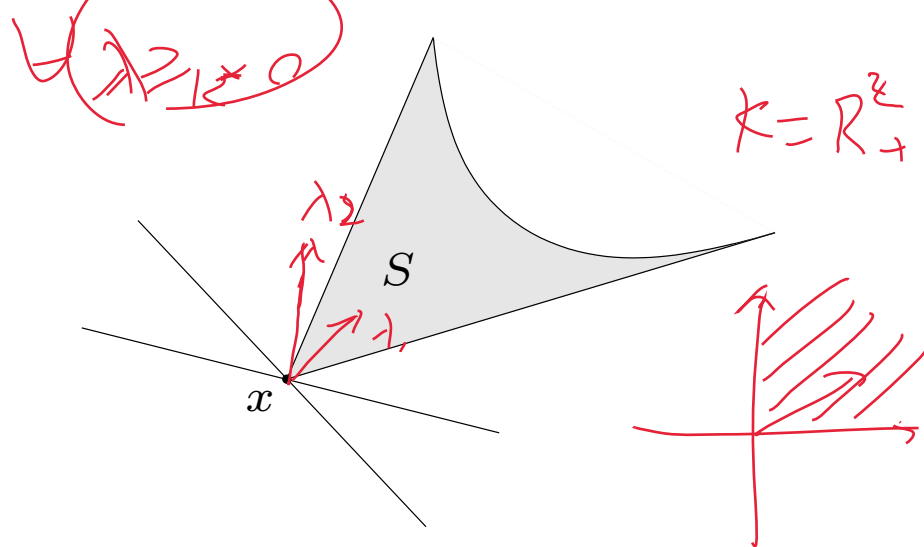


$$\forall y \in S, x \preceq_K y$$

## Minimum and minimal elements via dual inequalities

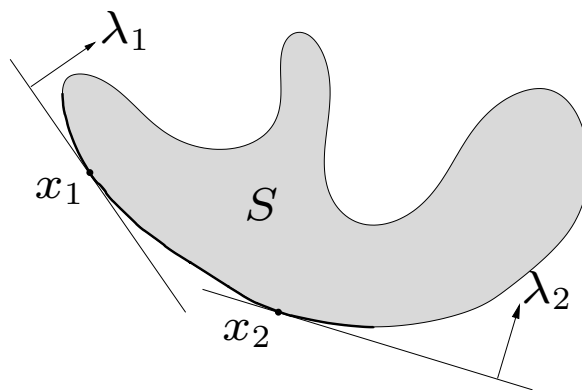
**minimum element** w.r.t.  $\preceq_K$

$x$  is minimum element of  $S$  iff for all  $\lambda \succ_{K^*} 0$ ,  $x$  is the unique minimizer of  $\lambda^T z$  over  $S$  ( $z \in S$ )



**minimal element** w.r.t.  $\preceq_K$

- if  $x$  minimizes  $\lambda^T z$  over  $S$  for some  $\lambda \succ_{K^*} 0$ , then  $x$  is minimal



$$K = \mathbb{R}_+^2$$

- if  $x$  is a minimal element of a *convex* set  $S$ , then there exists a nonzero  $\lambda \succeq_{K^*} 0$  such that  $x$  minimizes  $\lambda^T z$  over  $S$



### 3. Convex functions

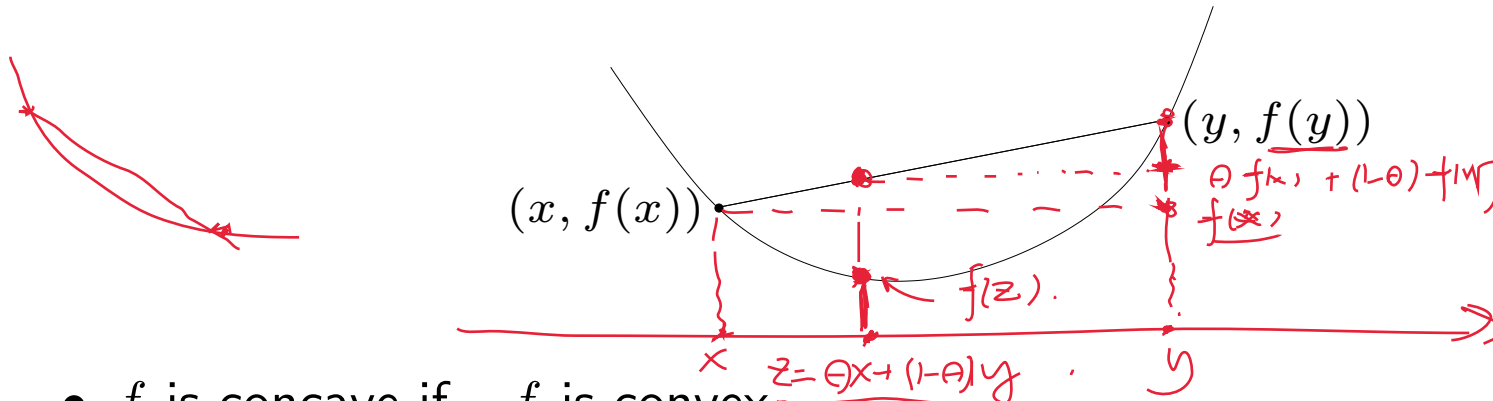
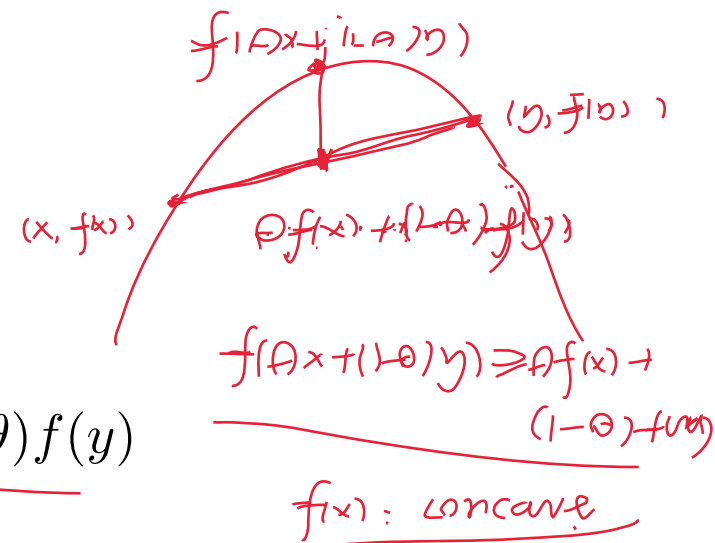
- basic properties and examples
- operations that preserve convexity
- the conjugate function
- quasiconvex functions
- log-concave and log-convex functions
- convexity with respect to generalized inequalities

# Definition

$f : \mathbf{R}^n \rightarrow \mathbf{R}$  is convex if dom  $f$  is a convex set and

$$\underline{f(\theta x + (1 - \theta)y)} \leq \underline{\theta f(x) + (1 - \theta)f(y)}$$

for all  $x, y \in \text{dom } f$ ,  $0 \leq \theta \leq 1$



- $f$  is concave if  $-f$  is convex
- $f$  is strictly convex if dom  $f$  is convex and

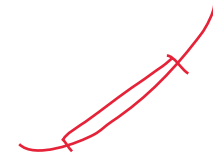
$$f(\theta x + (1 - \theta)y) < \theta f(x) + (1 - \theta)f(y)$$

for  $x, y \in \text{dom } f$ ,  $x \neq y$ ,  $0 < \theta < 1$




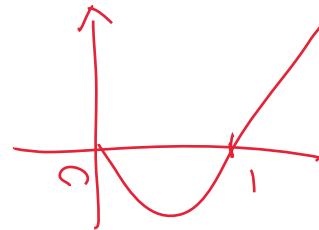
## Examples on $\mathbf{R}$

convex:

- affine:  $ax + b$  on  $\mathbf{R}$ , for any  $a, b \in \mathbf{R}$
  - exponential:  $e^{ax}$ , for any  $a \in \mathbf{R}$
  - powers:  $x^\alpha$  on  $\mathbf{R}_{++}$ , for  $\alpha \geq 1$  or  $\alpha \leq 0$
  - powers of absolute value:  $|x|^p$  on  $\mathbf{R}$ , for  $p \geq 1$
  - ~~negative entropy~~:  $x \log x$  on  $\mathbf{R}_{++}$
- 

concave:

- affine:  $ax + b$  on  $\mathbf{R}$ , for any  $a, b \in \mathbf{R}$
  - powers:  $x^\alpha$  on  $\mathbf{R}_{++}$ , for  $0 \leq \alpha \leq 1$
  - logarithm:  $\log x$  on  $\mathbf{R}_{++}$
- 



## Examples on $\mathbf{R}^n$ and $\mathbf{R}^{m \times n}$

affine functions are convex and concave; all norms are convex

### examples on $\mathbf{R}^n$

- affine function  $f(x) = \underbrace{a^T x}_{\langle a, x \rangle} + b$
- norms:  $\|x\|_p = (\sum_{i=1}^n |x_i|^p)^{1/p}$  for  $p \geq 1$ ;  $\|x\|_\infty = \max_k |x_k|$

### examples on $\mathbf{R}^{m \times n}$ ( $m \times n$ matrices)

- affine function

$$f(X) = \underbrace{\text{tr}(A^T X)}_{\langle A, X \rangle} + b = \sum_{i=1}^m \sum_{j=1}^n A_{ij} X_{ij} + b$$

- spectral (maximum singular value) norm

$$f(X) = \|X\|_2 = \sigma_{\max}(X) = (\lambda_{\max}(X^T X))^{1/2}$$

# Restriction of a convex function to a line

$f : \mathbf{R}^n \rightarrow \mathbf{R}$  is convex if and only if the function  $g : \mathbf{R} \rightarrow \mathbf{R}$ ,

$$g(t) = f(x + tv), \quad \text{dom } g = \{t \mid x + tv \in \text{dom } f\}$$

$\mathbf{R}^n$        $v \in \mathbf{R}^n$ , direction (arbitrary).  
 $\mathbf{R}$

is convex (in  $t$ ) for any  $x \in \text{dom } f$ ,  $v \in \mathbf{R}^n$

can check convexity of  $f$  by checking convexity of functions of one variable

**example.**  $f : \mathbf{S}^n \rightarrow \mathbf{R}$  with  $f(X) = \log \det X$ ,  $\text{dom } f = \mathbf{S}_{++}^n$

$$g(t) = \log \det(X + tV) = \log \det X + \log \det(I + tX^{-1/2}VX^{-1/2})$$

$$\log \det X + \sum_{i=1}^n \log(1 + t\lambda_i)$$

*Handwritten notes:*  
 $\det(AB) = \det(A) \cdot \det(B)$   
 $X^{1/2} (I + tX^{-1/2}VX^{-1/2}) X^{1/2} = X + tV$

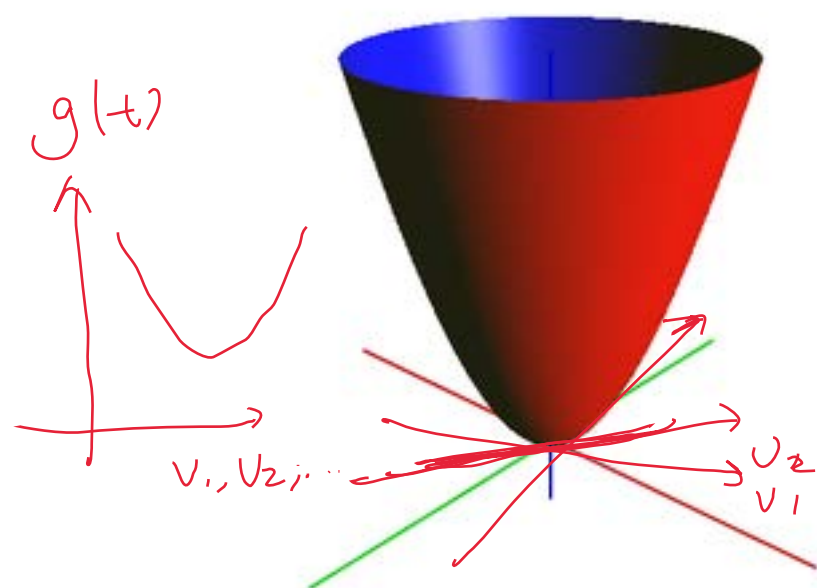
where  $\lambda_i$  are the eigenvalues of  $X^{-1/2}VX^{-1/2}$

$g$  is concave in  $t$  (for any choice of  $X \succ 0$ ,  $V$ ); hence  $f$  is concave

# Restriction of a convex function to a line

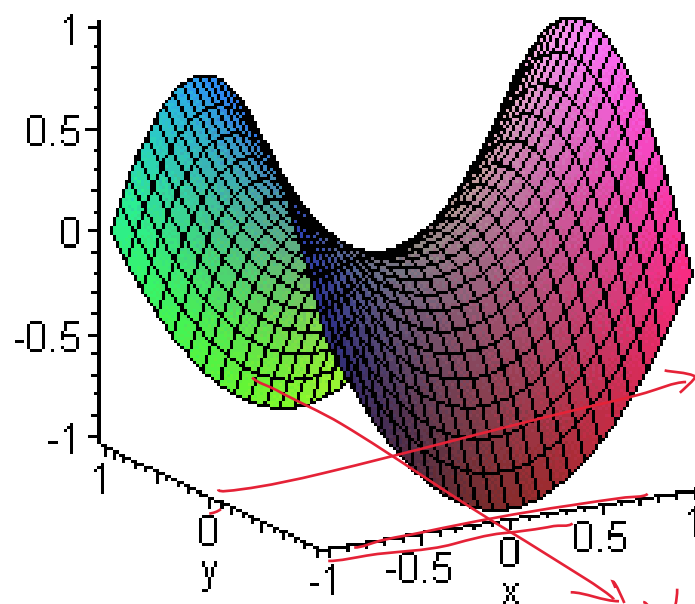
## Restricting a function to a line

Draw a line in the domain of the function, and evaluate the function only along that line.



$$z = \frac{x^2}{a^2} + \frac{y^2}{b^2}.$$

Paraboloid



$$z = \frac{x^2}{a^2} - \frac{y^2}{b^2}$$

Hyperbolic paraboloid





## Extended-value extension

extended-value extension  $\tilde{f}$  of  $f$  is  
 $\text{dom } f = [a, b]$

$$\tilde{f}(x) = \begin{cases} f(x), & x \in \text{dom } f \\ \infty, & x \notin \text{dom } f \end{cases}$$

$$\tilde{f}(x) = f(x), \quad x \in \text{dom } f, \quad \tilde{f}(x) = \infty, \quad x \notin \text{dom } f$$

often simplifies notation; for example, the condition

$$0 \leq \theta \leq 1 \implies \tilde{f}(\theta x + (1 - \theta)y) \leq \theta \tilde{f}(x) + (1 - \theta) \tilde{f}(y)$$

(as an inequality in  $\mathbf{R} \cup \{\infty\}$ ), means the same as the two conditions

- $\text{dom } f$  is convex
- for  $x, y \in \text{dom } f$ ,

$$0 \leq \theta \leq 1 \implies f(\theta x + (1 - \theta)y) \leq \theta f(x) + (1 - \theta)f(y)$$

# First-order condition

$f$  is differentiable if  $\text{dom } f$  is open and the gradient

$$\nabla f(x) = \left( \frac{\partial f(x)}{\partial x_1}, \frac{\partial f(x)}{\partial x_2}, \dots, \frac{\partial f(x)}{\partial x_n} \right) \in \mathbb{R}^n$$

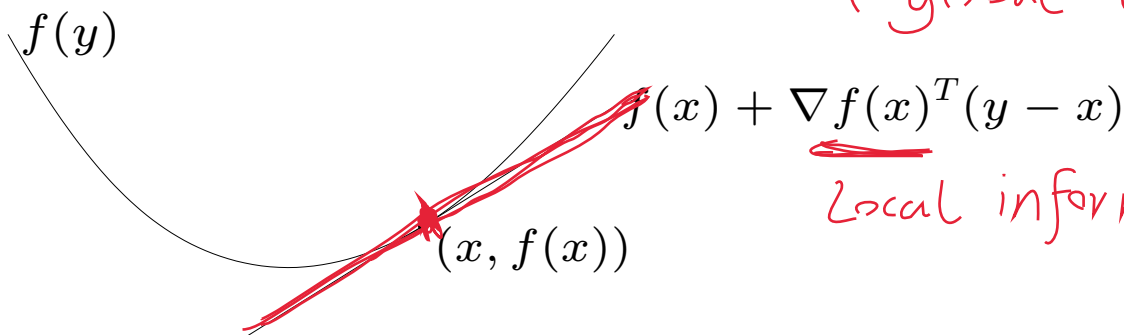
exists at each  $x \in \text{dom } f$

**1st-order condition:** differentiable  $f$  with convex domain is convex iff

$$f(y) \geq \underbrace{f(x) + \nabla f(x)^T(y - x)}_{\text{first-order Taylor approximation.}}$$

for all  $x, y \in \text{dom } f$

↑ global underestimator



Local information.

first-order approximation of  $f$  is global underestimator

## Second-order conditions

$f$  is twice differentiable if  $\text{dom } f$  is open and the Hessian  $\nabla^2 f(x) \in \mathbf{S}^n$ ,

$$\underline{\nabla^2 f(x)_{ij} = \frac{\partial^2 f(x)}{\partial x_i \partial x_j}}, \quad i, j = 1, \dots, n,$$

exists at each  $x \in \text{dom } f$

**2nd-order conditions:** for twice differentiable  $f$  with convex domain

- $f$  is convex if and only if  
 $(\nabla^2 f(x) \in \mathbf{S}_+^n)$   
 $\Rightarrow$  Hessian matrix is PSD  
 $\nabla^2 f(x) \succeq 0$  for all  $x \in \text{dom } f$

- if  $\nabla^2 f(x) \succ 0$  for all  $x \in \text{dom } f$ , then  $f$  is strictly convex

## Examples

**quadratic function:**  $f(x) = (1/2)x^T P x + q^T x + r$  (with  $P \in \mathbf{S}^n$ )

$$\nabla f(x) = Px + q, \quad \nabla^2 f(x) = P$$

convex if  $P \succeq 0$

**least-squares objective:**  $f(x) = \|Ax - b\|_2^2$

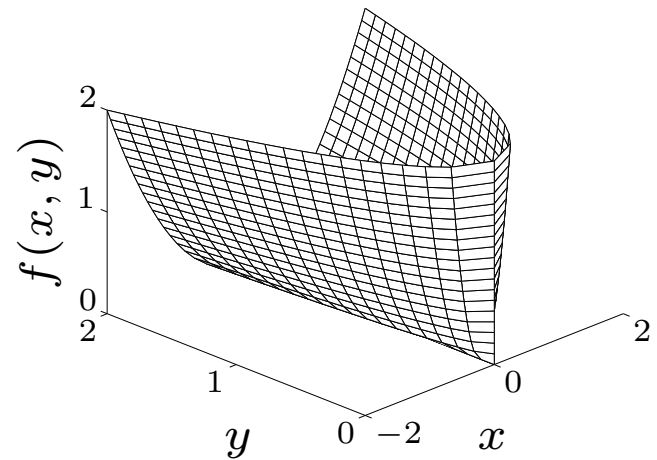
$$\nabla f(x) = 2A^T(Ax - b), \quad \nabla^2 f(x) = 2A^T A$$

convex (for any  $A$ )

**quadratic-over-linear:**  $f(x, y) = x^2/y$

$$\nabla^2 f(x, y) = \frac{2}{y^3} \begin{bmatrix} y \\ -x \end{bmatrix} \begin{bmatrix} y \\ -x \end{bmatrix}^T \succeq 0$$

convex for  $y > 0$



**log-sum-exp:**  $f(x) = \log \sum_{k=1}^n \exp x_k$  is convex

$$\nabla^2 f(x) = \frac{1}{\mathbf{1}^T z} \mathbf{diag}(z) - \frac{1}{(\mathbf{1}^T z)^2} z z^T \quad (z_k = \exp x_k)$$

to show  $\nabla^2 f(x) \succeq 0$ , we must verify that  $v^T \nabla^2 f(x) v \geq 0$  for all  $v$ :

$$v^T \nabla^2 f(x) v = \frac{(\sum_k z_k v_k^2)(\sum_k z_k) - (\sum_k v_k z_k)^2}{(\sum_k z_k)^2} \geq 0$$

since  $(\sum_k v_k z_k)^2 \leq (\sum_k z_k v_k^2)(\sum_k z_k)$  (from Cauchy-Schwarz inequality)

**geometric mean:**  $f(x) = (\prod_{k=1}^n x_k)^{1/n}$  on  $\mathbf{R}_{++}^n$  is concave

(similar proof as for log-sum-exp)

# Epigraph and sublevel set

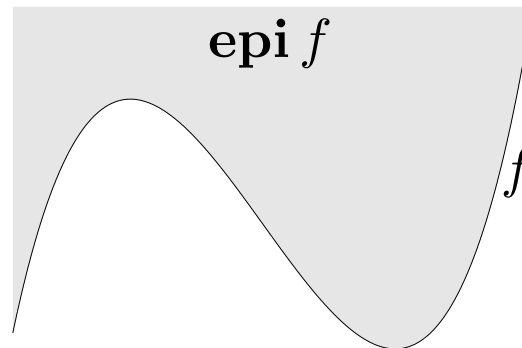
$\alpha$ -sublevel set of  $f : \mathbf{R}^n \rightarrow \mathbf{R}$ :

$$C_\alpha = \{x \in \mathbf{dom} f \mid f(x) \leq \alpha\}$$

sublevel sets of convex functions are convex (converse is false)

**epigraph** of  $f : \mathbf{R}^n \rightarrow \mathbf{R}$ :

$$\mathbf{epi} f = \{(x, t) \in \mathbf{R}^{n+1} \mid x \in \mathbf{dom} f, f(x) \leq t\}$$



$f$  is convex if and only if  $\mathbf{epi} f$  is a convex set

# Jensen's inequality

**basic inequality:** if  $f$  is convex, then for  $0 \leq \theta \leq 1$ ,

$$f(\theta x + (1 - \theta)y) \leq \theta f(x) + (1 - \theta)f(y)$$

**extension:** if  $f$  is convex, then

$$f(\mathbf{E} z) \leq \mathbf{E} f(z)$$

for any random variable  $z$

basic inequality is special case with discrete distribution

$$\mathbf{prob}(z = x) = \theta, \quad \mathbf{prob}(z = y) = 1 - \theta$$

# Operations that preserve convexity

practical methods for establishing convexity of a function

1. verify definition (often simplified by restricting to a line)
2. for twice differentiable functions, show  $\nabla^2 f(x) \succeq 0$
3. show that  $f$  is obtained from simple convex functions by operations that preserve convexity
  - nonnegative weighted sum
  - composition with affine function
  - pointwise maximum and supremum
  - composition
  - minimization
  - perspective



# Positive weighted sum & composition with affine function

**nonnegative multiple:**  $\alpha f$  is convex if  $f$  is convex,  $\alpha \geq 0$

**sum:**  $f_1 + f_2$  convex if  $f_1, f_2$  convex (extends to infinite sums, integrals)

**composition with affine function:**  $f(Ax + b)$  is convex if  $f$  is convex

## examples

- log barrier for linear inequalities

$$f(x) = - \sum_{i=1}^m \log(b_i - a_i^T x), \quad \text{dom } f = \{x \mid a_i^T x < b_i, i = 1, \dots, m\}$$

- (any) norm of affine function:  $f(x) = \|Ax + b\|$

## Pointwise maximum

if  $f_1, \dots, f_m$  are convex, then  $f(x) = \max\{f_1(x), \dots, f_m(x)\}$  is convex

### examples

- piecewise-linear function:  $f(x) = \max_{i=1,\dots,m}(a_i^T x + b_i)$  is convex
- sum of  $r$  largest components of  $x \in \mathbf{R}^n$ :

$$f(x) = x_{[1]} + x_{[2]} + \dots + x_{[r]}$$

is convex ( $x_{[i]}$  is  $i$ th largest component of  $x$ )

proof:

$$f(x) = \max\{x_{i_1} + x_{i_2} + \dots + x_{i_r} \mid 1 \leq i_1 < i_2 < \dots < i_r \leq n\}$$

## Pointwise supremum

if  $f(x, y)$  is convex in  $x$  for each  $y \in \mathcal{A}$ , then

$$g(x) = \sup_{y \in \mathcal{A}} f(x, y)$$

is convex

### examples

- support function of a set  $C$ :  $S_C(x) = \sup_{y \in C} y^T x$  is convex
- distance to farthest point in a set  $C$ :

$$f(x) = \sup_{y \in C} \|x - y\|$$

- maximum eigenvalue of symmetric matrix: for  $X \in \mathbf{S}^n$ ,

$$\lambda_{\max}(X) = \sup_{\|y\|_2=1} y^T X y$$

# Composition with scalar functions

composition of  $g : \mathbf{R}^n \rightarrow \mathbf{R}$  and  $h : \mathbf{R} \rightarrow \mathbf{R}$ :

$$f(x) = h(g(x))$$

$f$  is convex if  $\begin{array}{l} g \text{ convex, } h \text{ convex, } \tilde{h} \text{ nondecreasing} \\ g \text{ concave, } h \text{ convex, } \tilde{h} \text{ nonincreasing} \end{array}$

- proof (for  $n = 1$ , differentiable  $g, h$ )

$$f''(x) = h''(g(x))g'(x)^2 + h'(g(x))g''(x)$$

- note: monotonicity must hold for extended-value extension  $\tilde{h}$

## examples

- $\exp g(x)$  is convex if  $g$  is convex
- $1/g(x)$  is convex if  $g$  is concave and positive

# Vector composition

composition of  $g : \mathbf{R}^n \rightarrow \mathbf{R}^k$  and  $h : \mathbf{R}^k \rightarrow \mathbf{R}$ :

$$f(x) = h(g(x)) = h(g_1(x), g_2(x), \dots, g_k(x))$$

$f$  is convex if  $\begin{array}{l} g_i \text{ convex, } h \text{ convex, } \tilde{h} \text{ nondecreasing in each argument} \\ g_i \text{ concave, } h \text{ convex, } \tilde{h} \text{ nonincreasing in each argument} \end{array}$

proof (for  $n = 1$ , differentiable  $g, h$ )

$$f''(x) = g'(x)^T \nabla^2 h(g(x)) g'(x) + \nabla h(g(x))^T g''(x)$$

## examples

- $\sum_{i=1}^m \log g_i(x)$  is concave if  $g_i$  are concave and positive
- $\log \sum_{i=1}^m \exp g_i(x)$  is convex if  $g_i$  are convex

# Minimization

if  $f(x, y)$  is convex in  $(x, y)$  and  $C$  is a convex set, then

$$g(x) = \inf_{y \in C} f(x, y)$$

is convex

## examples

- $f(x, y) = x^T A x + 2x^T B y + y^T C y$  with

$$\begin{bmatrix} A & B \\ B^T & C \end{bmatrix} \succeq 0, \quad C \succ 0$$

minimizing over  $y$  gives  $g(x) = \inf_y f(x, y) = x^T (A - B C^{-1} B^T) x$

$g$  is convex, hence Schur complement  $A - B C^{-1} B^T \succeq 0$

- distance to a set:  $\mathbf{dist}(x, S) = \inf_{y \in S} \|x - y\|$  is convex if  $S$  is convex

# Perspective

the **perspective** of a function  $f : \mathbf{R}^n \rightarrow \mathbf{R}$  is the function  $g : \mathbf{R}^n \times \mathbf{R} \rightarrow \mathbf{R}$ ,

$$g(x, t) = tf(x/t), \quad \text{dom } g = \{(x, t) \mid x/t \in \text{dom } f, t > 0\}$$

$g$  is convex if  $f$  is convex

## examples

- $f(x) = x^T x$  is convex; hence  $g(x, t) = x^T x/t$  is convex for  $t > 0$
- negative logarithm  $f(x) = -\log x$  is convex; hence relative entropy  $g(x, t) = t \log t - t \log x$  is convex on  $\mathbf{R}_{++}^2$
- if  $f$  is convex, then

$$g(x) = (c^T x + d)f((Ax + b)/(c^T x + d))$$

is convex on  $\{x \mid c^T x + d > 0, (Ax + b)/(c^T x + d) \in \text{dom } f\}$