

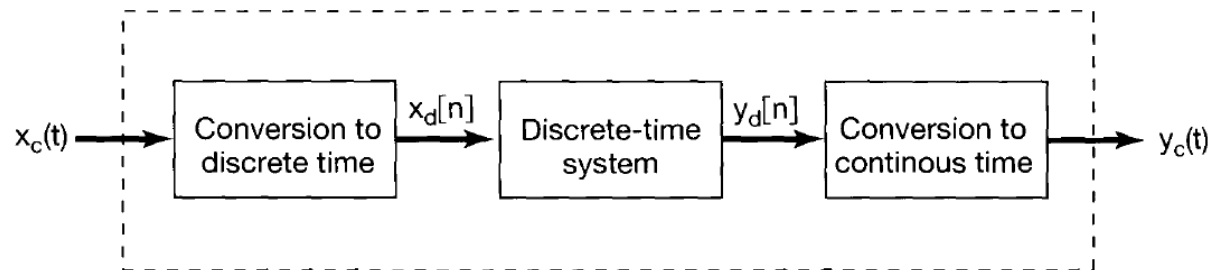
# Sampling (ch.7)

- ❑ Representation of a Continuous-Time Signal by Its Samples: The Sampling Theorem
- ❑ Reconstruction of a Signal from Its Samples Using Interpolation
- ❑ The Effect of Undersampling: Aliasing
- ❑ **Discrete-Time Processing of Continuous-Time Signals**
- ❑ Sampling of Discrete-Time signals

# Discrete-Time Processing of Continuous-Time Signals



## General scheme

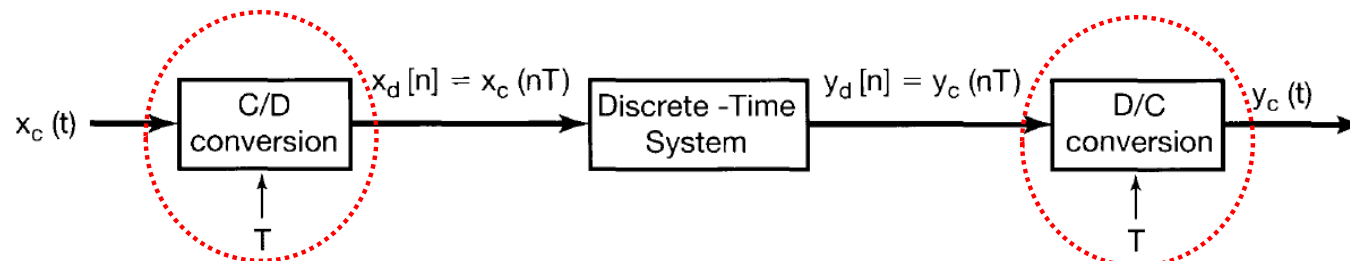


$$x_d[n] = x_c(nT)$$

$$y_d[n] = y_c(nT)$$

□ C/D: continuous-to-discrete-time conversion

□ D/C: discrete-to-continuous-time conversion



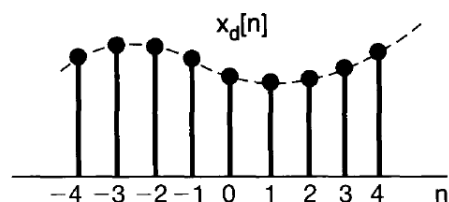
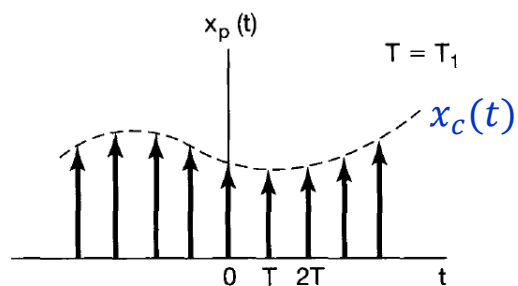
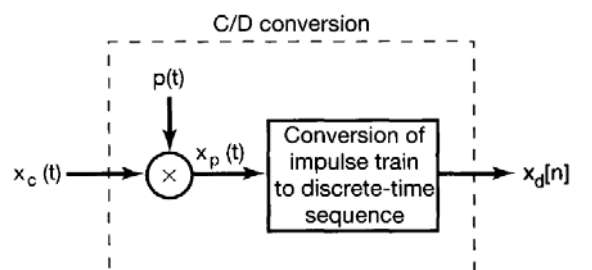
analog-to-digital (A/D) in practice

digital-to-analog (D/A) in practice

# Discrete-Time Processing of Continuous-Time Signals



## C/D conversion Time domain



$$x_p(t) = \sum_{n=-\infty}^{\infty} x(nT) \cdot \delta(t - nT)$$

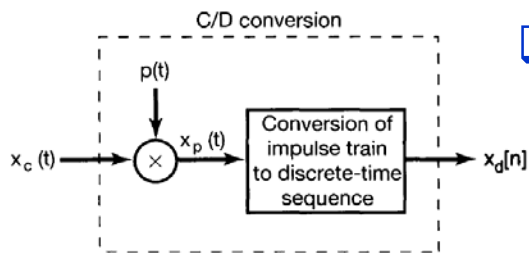
$$x_d[n] = x_c(nT)$$

# Discrete-Time Processing of Continuous-Time Signals



## C/D conversion

Frequency domain:  $\omega$  for continuous time and  $\Omega$  for discrete time

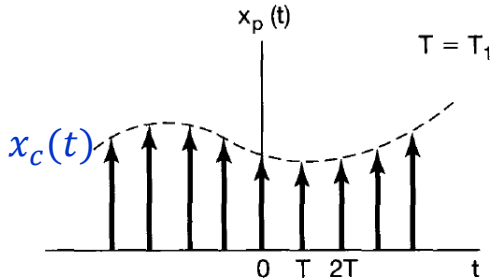


### □ Spectrum of $x_d[n]$

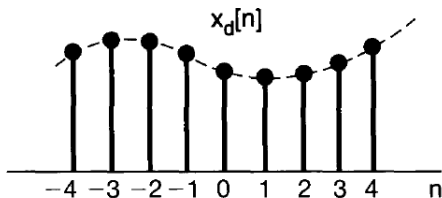
$$X_d(e^{j\Omega}) = \sum_{n=-\infty}^{\infty} x_d[n] e^{-jn\Omega} = \sum_{n=-\infty}^{\infty} x_c(nT) e^{-jn\Omega}$$

### □ Spectrum of $x_p(t)$

$$x_p(t) = \sum_{n=-\infty}^{\infty} x_c(nT) \cdot \delta(t - nT) \Rightarrow X_p(j\omega) = \sum_{n=-\infty}^{\infty} x_c(nT) \cdot e^{-j\omega nT}$$



□ If  $\omega = \Omega/T$ ,  $X_d(e^{j\Omega}) = X_p(j\Omega/T)$



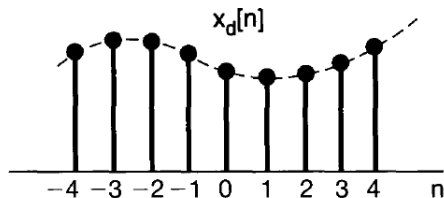
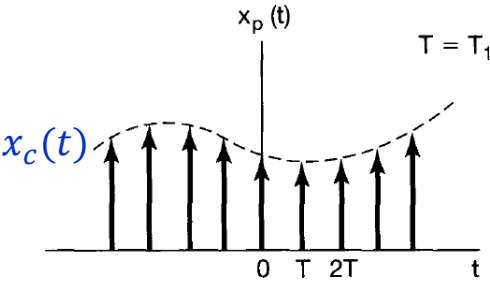
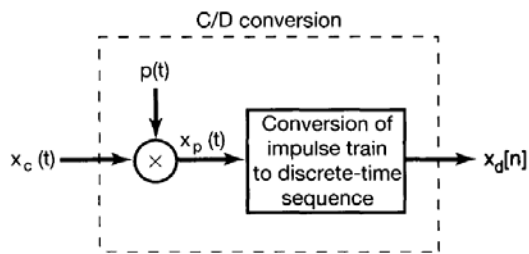
□ The spectrum of  $x_d[n]$  can be obtained from  $X_p(j\omega)$  by replacing  $\omega$  with  $\Omega/T$ .

# Discrete-Time Processing of Continuous-Time Signals



## C/D conversion

Frequency domain:  $\omega$  for continuous time and  $\Omega$  for discrete time



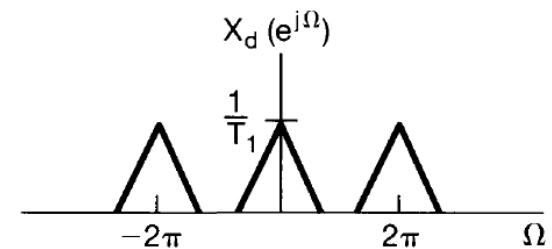
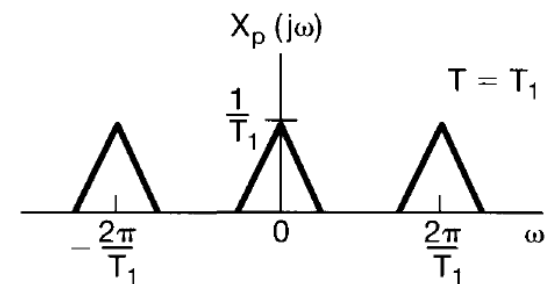
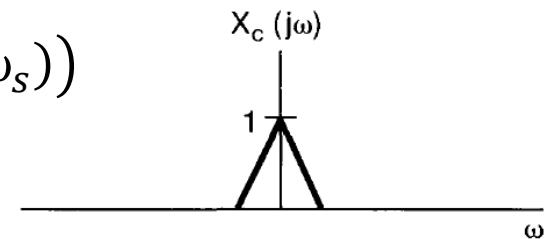
□ Recall:  $X_p(j\omega) = \frac{1}{T} \sum_{K=-\infty}^{\infty} X(j(\omega - k \cdot \omega_s))$

$$\therefore X_d(e^{j\Omega}) = \frac{1}{T} \sum_{K=-\infty}^{\infty} X(j(\Omega - 2k\pi)/T)$$

□  $X_d(e^{j\Omega})$  is a frequency-scaled version of  $X_p(j\omega)$ , and is periodic with period of  $2\pi$

□ Informally

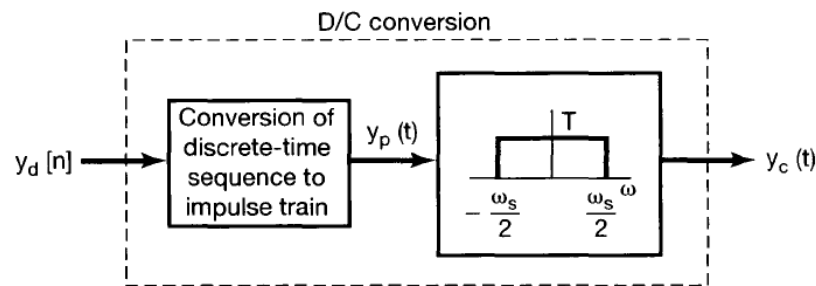
- $t$  to  $n$ : time scaling by  $1/T$
- $\omega$  to  $\Omega$ : frequency scaling by  $T$



# Discrete-Time Processing of Continuous-Time Signals



## D/C conversion



□  $Y_d(e^{j\Omega})$ : Spectrum of  $y_d[n]$

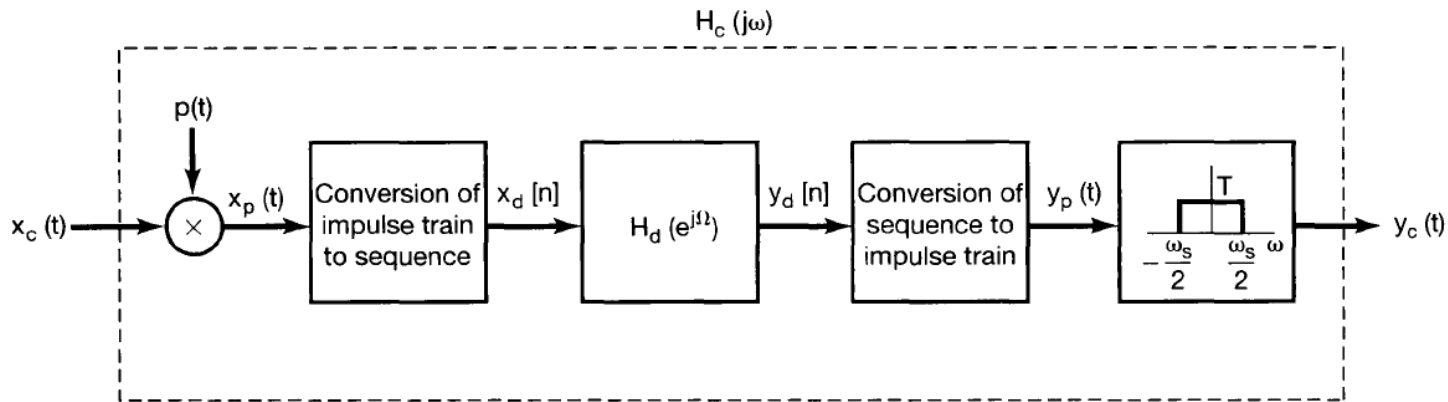
□  $Y_p(j\omega)$ : Spectrum of  $y_p(t)$

□  $Y_p(j\omega)$  can be obtained from  $Y_d(e^{j\Omega})$  by replacing  $\Omega$  with  $\omega T$ .

# Discrete-Time Processing of Continuous-Time Signals



## Overall system



□  $x_c(t)$ : input

□  $y_c(t)$ : output

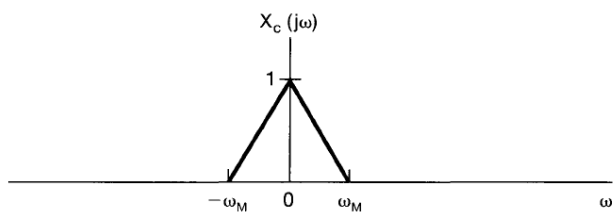
□ The overall system is equivalent to a continuous-time system with frequency response  $H_c(j\omega)$

□  $H_c(j\omega) = ?$

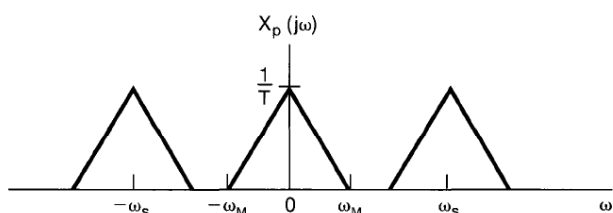
# Discrete-Time Processing of Continuous-Time Signals



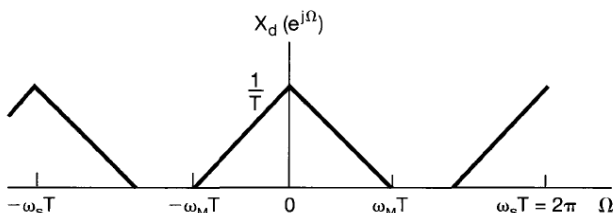
## Overall system



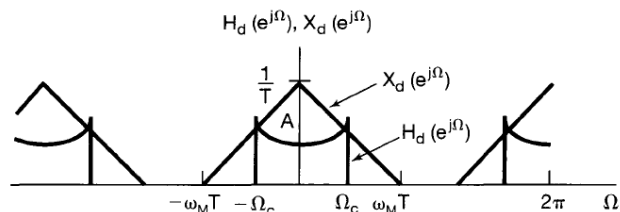
(a)



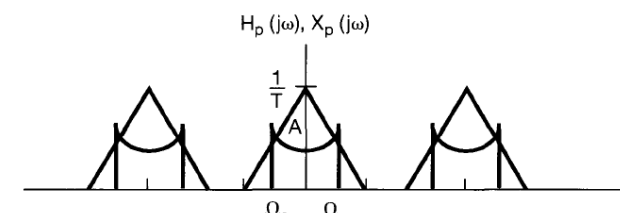
(b)



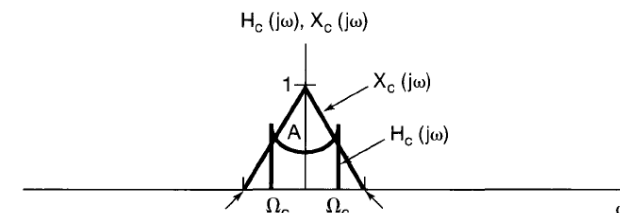
(c)



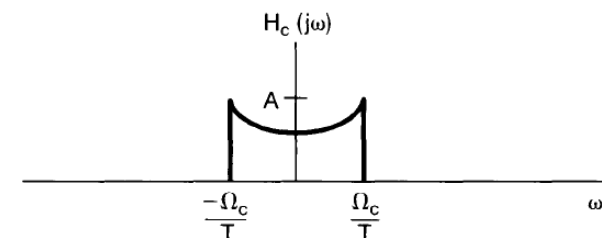
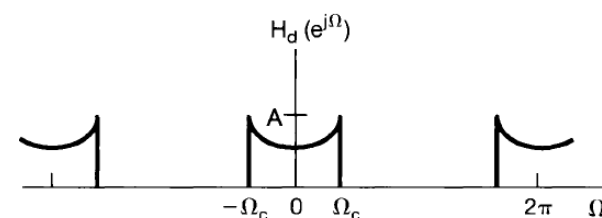
(d)



(e)



(f)



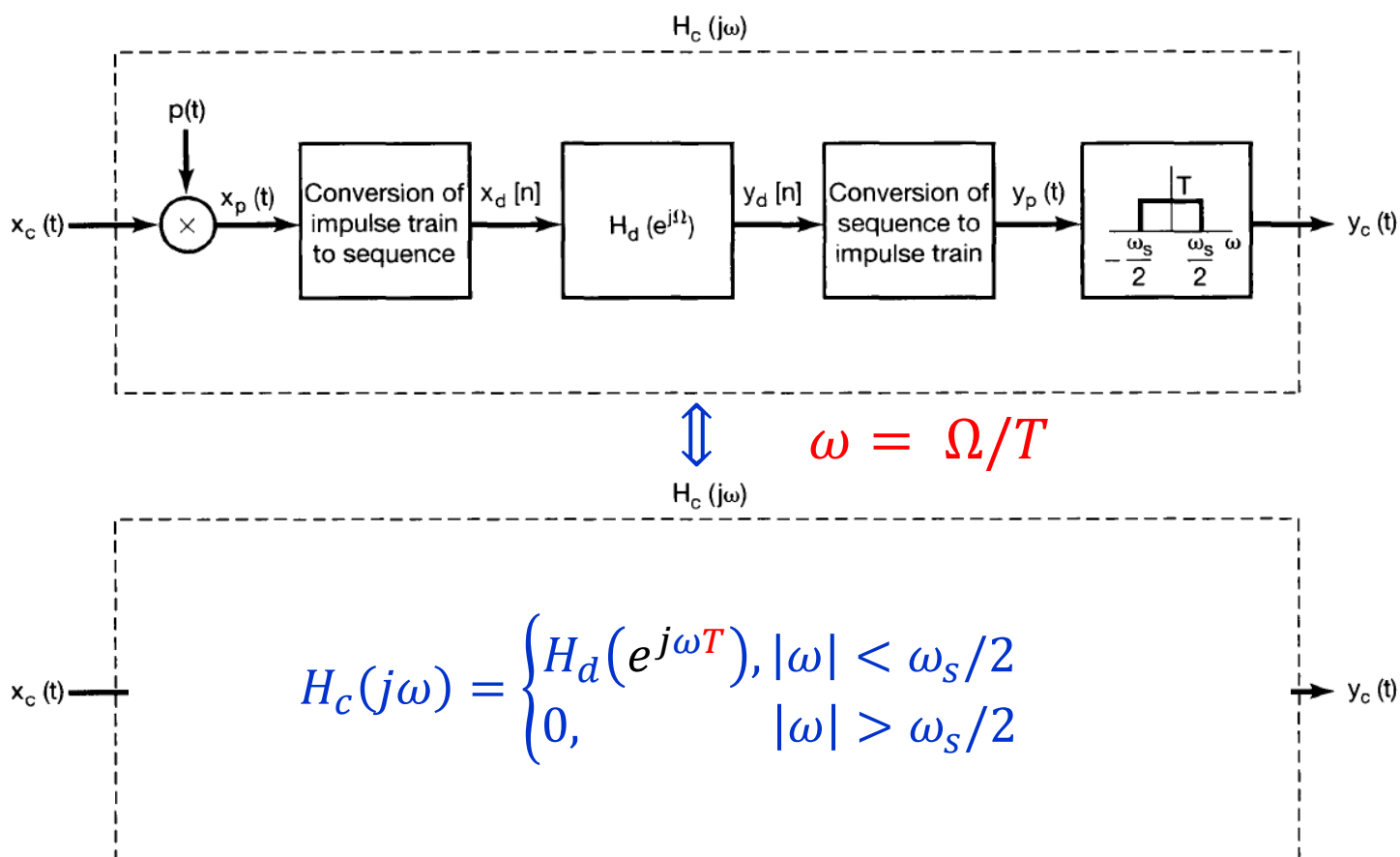
$$H_c(j\omega) = \begin{cases} H_d(e^{j\omega T}), & |\omega| < \omega_s/2 \\ 0, & |\omega| > \omega_s/2 \end{cases}$$



# Discrete-Time Processing of Continuous-Time Signals



## Overall system



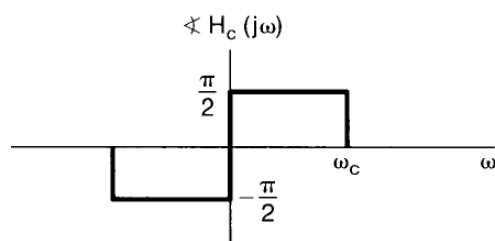
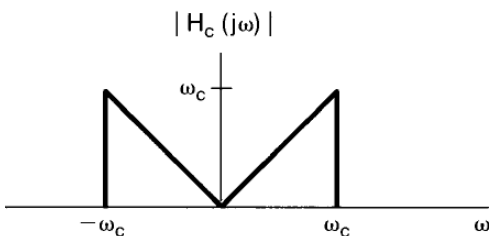
# Discrete-Time Processing of Continuous-Time Signals



## Digital differentiator: frequency response

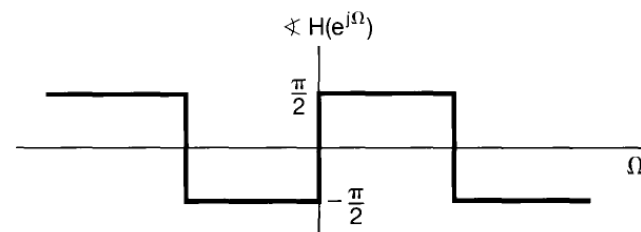
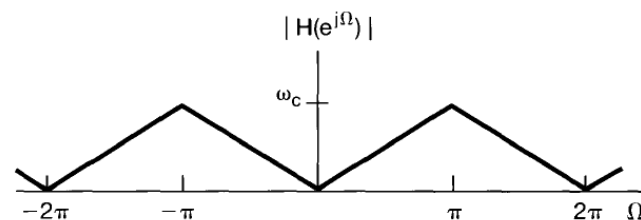
□ Band-limited CT differentiator  $\Leftrightarrow$  □ Corresponding DT differentiator

$$H_c(j\omega) = \begin{cases} j\omega, & |\omega| < \omega_c \\ 0, & |\omega| > \omega_c \end{cases}$$



$$H_d(e^{j\Omega}) = j \frac{\Omega}{T}, |\Omega| < \pi$$

$$\omega_c = \omega_s/2$$

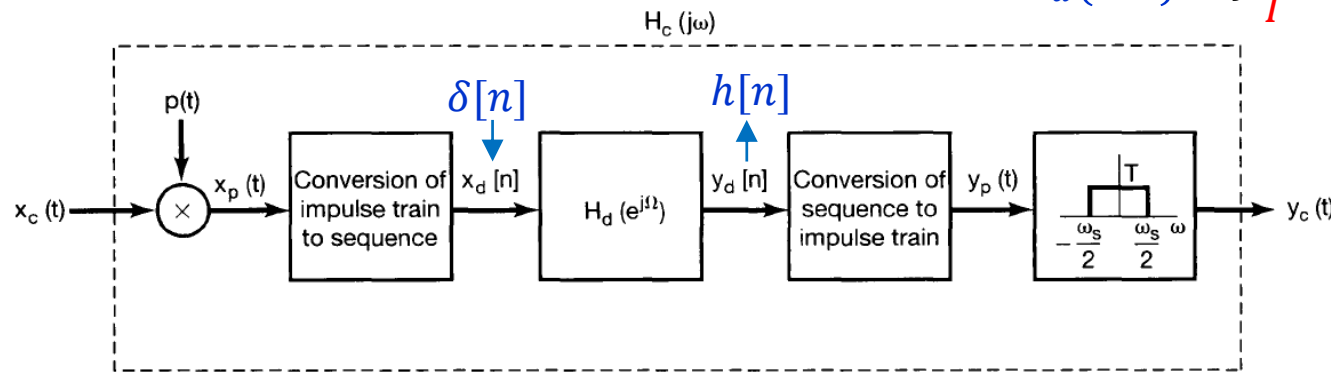


# Discrete-Time Processing of Continuous-Time Signals



## Digital differentiator: impulse response

$$H_d(e^{j\Omega}) = j \frac{\Omega}{T}, |\Omega| < \pi$$



$$\square x_c(t) = \frac{\sin(\pi t/T)}{\pi t} \Rightarrow x_d[n] = x_c(nT) = \frac{1}{T} \delta[n]$$

$$\square y_d[n] = y_c(nT) \quad y_c(t) = \frac{d}{dt} x_c(t) = \frac{\cos(\pi t/T)}{Tt} - \frac{\sin(\pi t/T)}{\pi t^2}$$

$$\square y_d[n] = \begin{cases} \frac{(-1)^n}{nT^2}, n \neq 0 \\ 0, n = 0 \end{cases} \Rightarrow \therefore h_d[n] = \begin{cases} \frac{(-1)^n}{nT}, n \neq 0 \\ 0, n = 0 \end{cases}$$

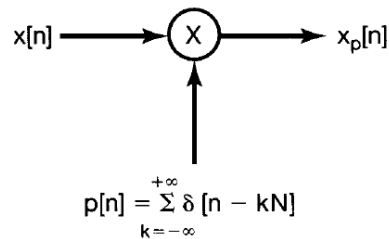
# Sampling (ch.7)

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- ❑ Sampling of Discrete-Time signals

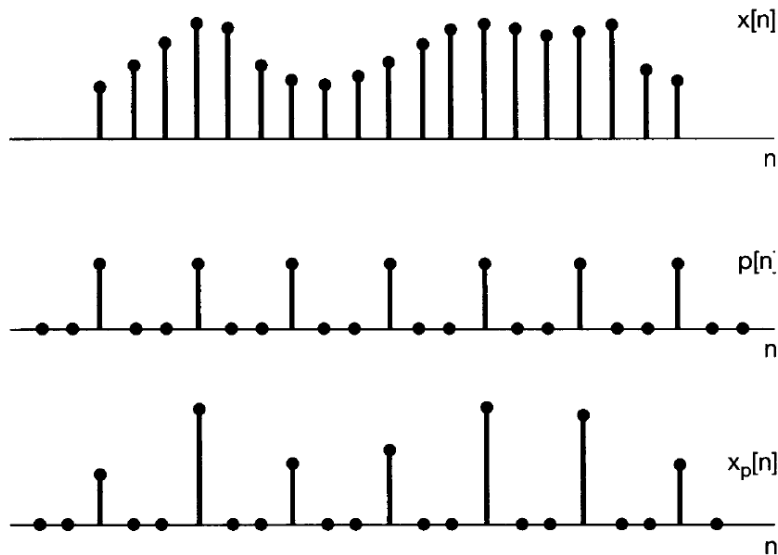
# Sampling of Discrete-Time Signals



## Impulse train sampling Time domain



N: sampling period



$$x_p[n] = x[n]p[n] = \sum_{k=-\infty}^{\infty} x[kN]\delta[n - kN]$$

$$= \begin{cases} x[n], & \text{if } n \text{ is an integer multiple of } N \\ 0, & \text{otherwise} \end{cases}$$

# Sampling of Discrete-Time Signals



## Impulse train sampling Frequency domain

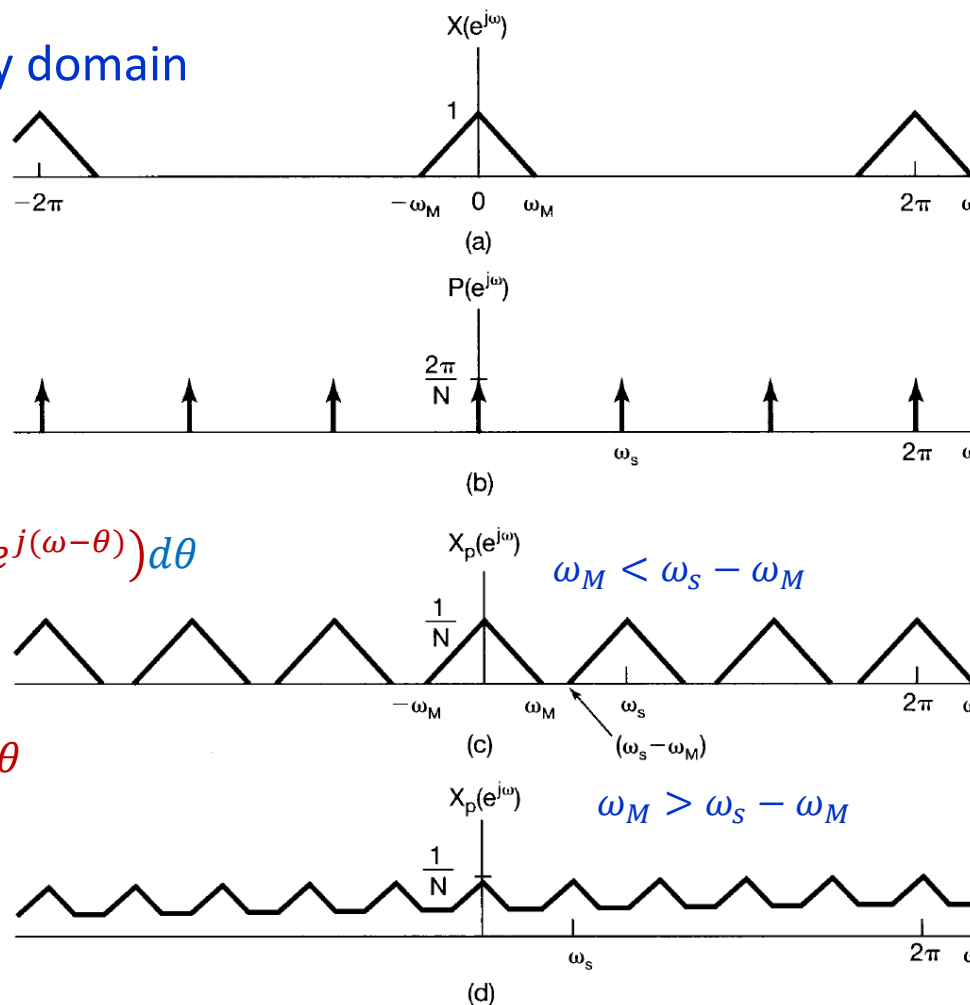
$$P(e^{j\omega}) = \frac{2\pi}{N} \sum_{K=-\infty}^{\infty} \delta(\omega - k\omega_s) \quad \omega_s = \frac{2\pi}{N}$$

$$X_p(e^{j\omega}) = \frac{1}{2\pi} \int_{2\pi} P(e^{j\theta}) X(e^{j(\omega-\theta)}) d\theta$$

$$= \frac{1}{2\pi} \cdot \frac{2\pi}{N} \int_{2\pi} \left[ \sum_{K=-\infty}^{\infty} \delta(\theta - k\omega_s) \right] X(e^{j(\omega-\theta)}) d\theta$$

$$= \frac{1}{N} \sum_{K=0}^{N-1} \int_{2\pi} \delta(\theta - k\omega_s) X(e^{j(\omega-\theta)}) d\theta$$

$$X_p(e^{j\omega}) = \frac{1}{N} \sum_{K=0}^{N-1} X(e^{j(\omega - k\omega_s)})$$



# Sampling of Discrete-Time Signals



## Impulse train sampling Reconstruction of $x[n]$

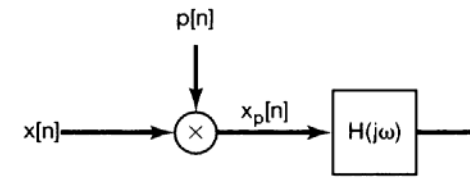
$$x_r[n] = x_p[n] * h[n] \quad \text{Time domain}$$

$$= \left[ \sum_{k=-\infty}^{\infty} x[kN] \cdot \delta[n - kN] \right] * h[n]$$

$$= \sum_{k=-\infty}^{\infty} x[kN] [\delta[n - kN] * h[n]]$$

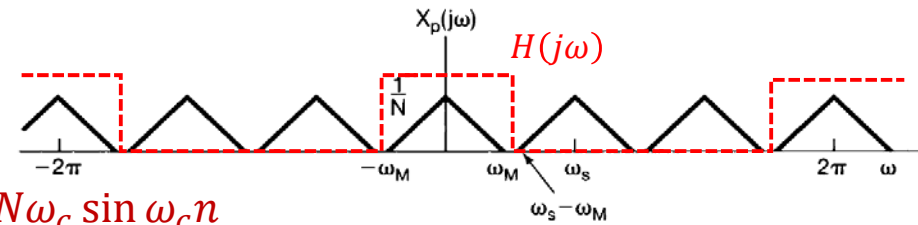
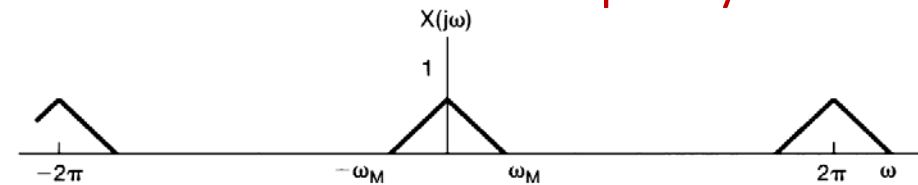
$$= \sum_{k=-\infty}^{\infty} x[kN] h[n - kN]$$

$$x_r[n] = \sum_{k=-\infty}^{\infty} x[kN] \frac{N\omega_c}{\pi} \frac{\sin \omega_c(n - kN)}{\omega_c(n - kN)}$$

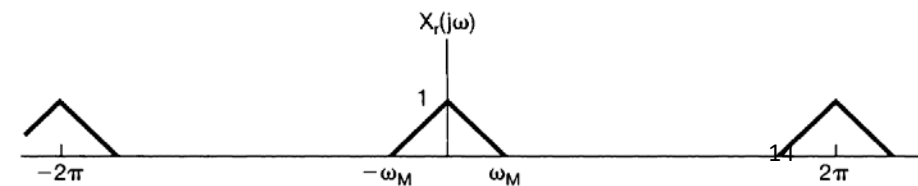
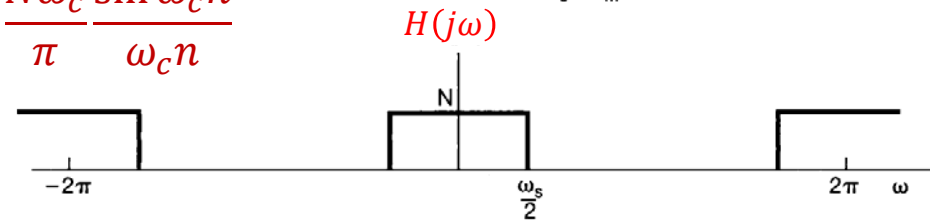


(a)

Frequency domain



$$h[n] = \frac{N\omega_c}{\pi} \frac{\sin \omega_c n}{\omega_c n}$$

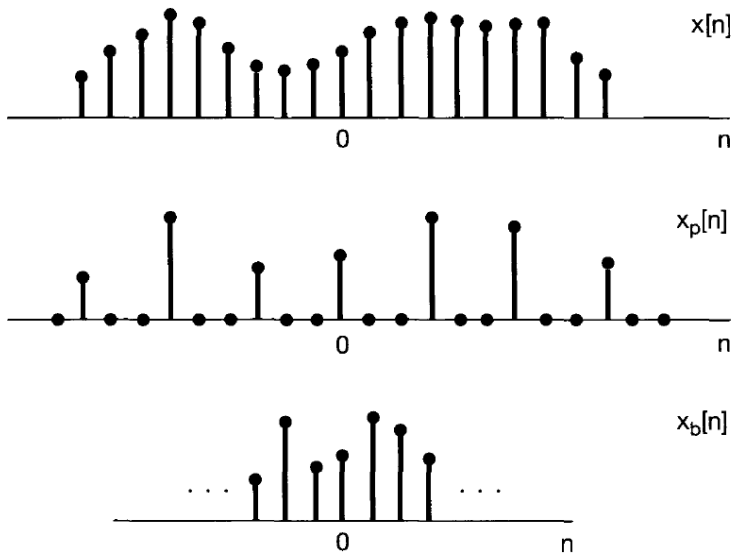


# Sampling of Discrete-Time Signals



## Decimation (sample rate decrease, SRD)

Time domain



$$x_b[n] = x_p[nN]$$

$$x_b[n] = x[nN]$$

Frequency domain

$$X_b(e^{j\omega}) = \sum_{K=-\infty}^{\infty} x_b[n] e^{-j\omega k}$$

$$X_b(e^{j\omega}) = \sum_{K=-\infty}^{\infty} x_p[kN] e^{-j\omega k} \quad n = kN$$

$$X_b(e^{j\omega}) = \sum_{\substack{n=\text{integer} \\ \text{number of } N}} x_p[n] e^{-j\omega n/N}$$

$$X_b(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x_p[n] e^{-j\omega n/N}$$

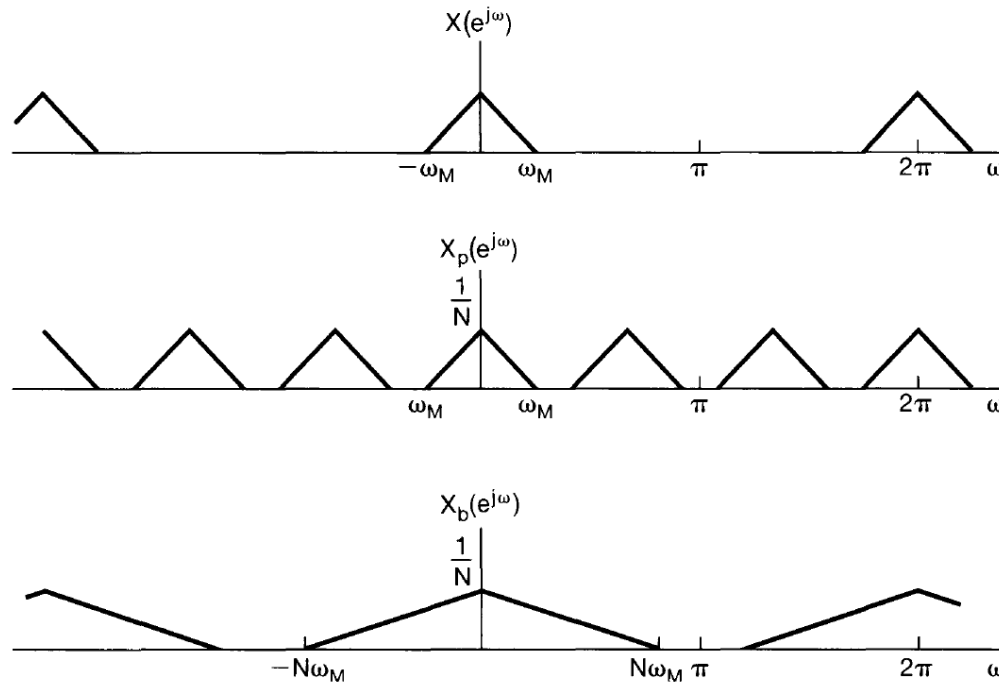
$$X_b(e^{j\omega}) = X_p(e^{j\omega/N})$$



# Sampling of Discrete-Time Signals



## Decimation



$$x_b[n] = x_p[nN]$$

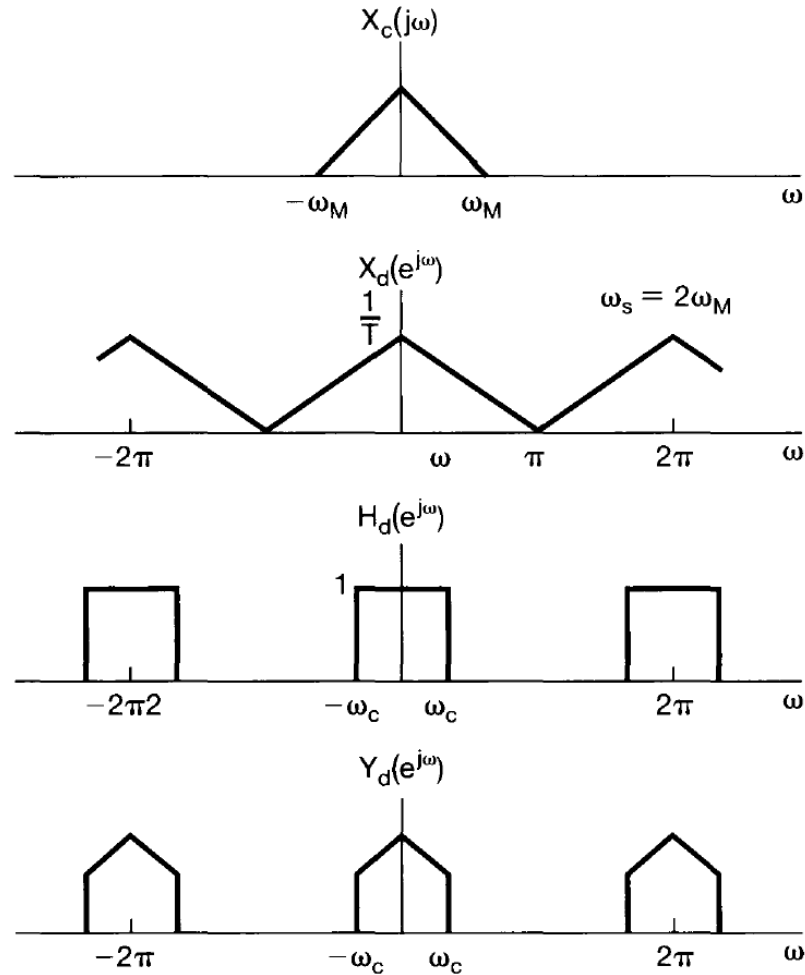
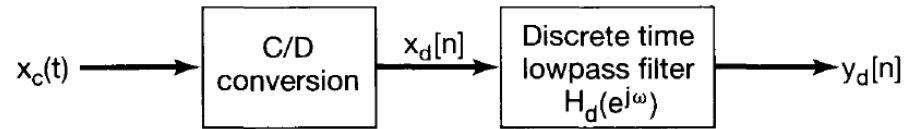
$$X_b(e^{j\omega}) = X_p(e^{j\omega/N})$$

Down-sampling if  $\omega_s = \frac{2\pi}{N} > 2\omega_m$

# Sampling of Discrete-Time

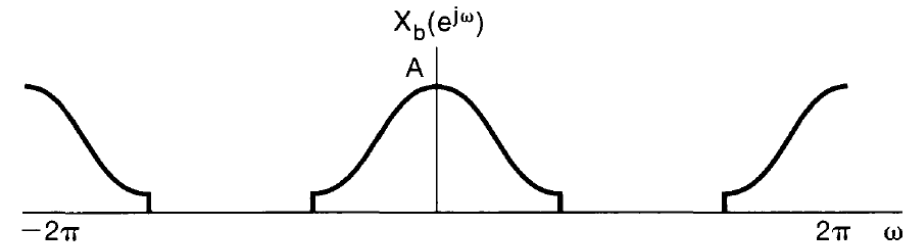
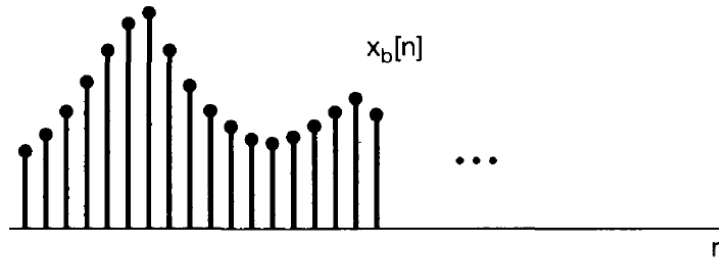
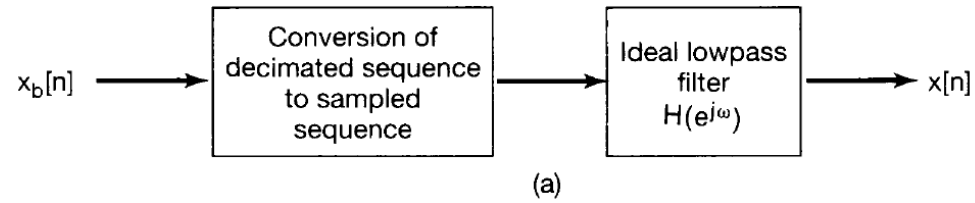
## Decimation

- Prevent aliasing by LPF in front of SRD  $\Rightarrow$  Decimator

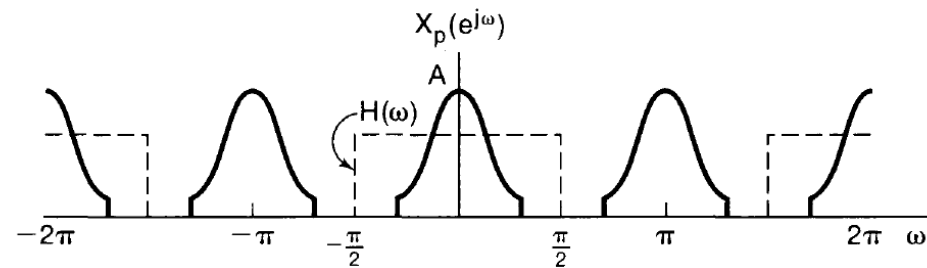
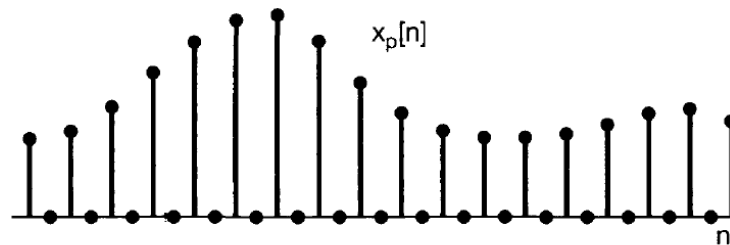


# Sampling of

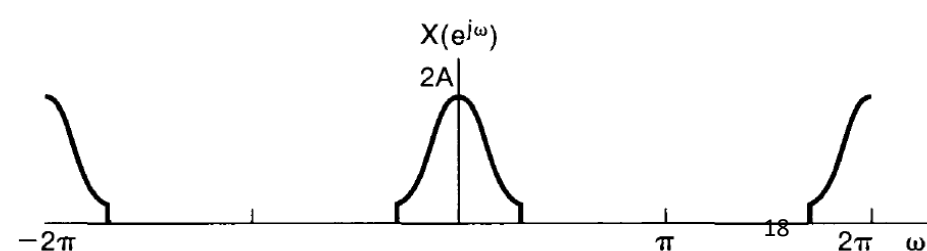
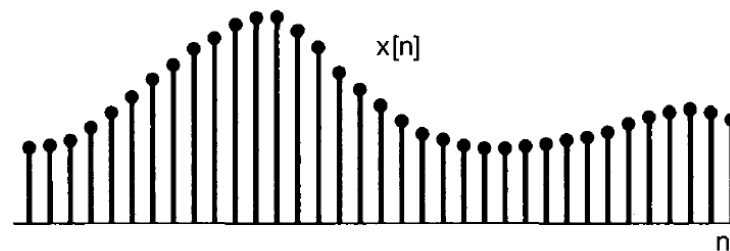
## Interpolation (SRI)



- Prevent mirrors by LPF after SRI  $\Rightarrow$  Interpolator

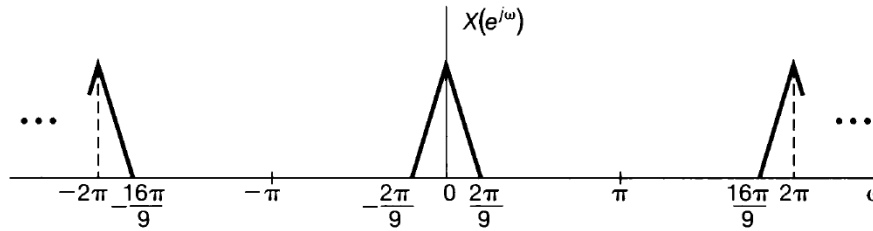


Upsampling by a factor of 2

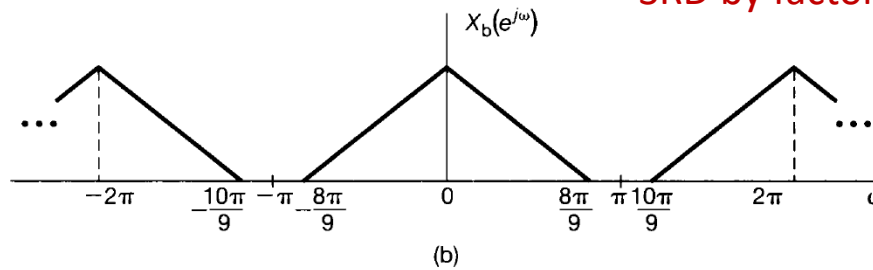


# Sampling of Discrete-

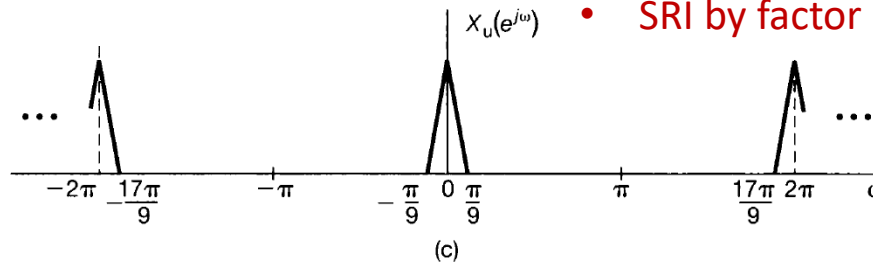
## Interpolation (SRI)



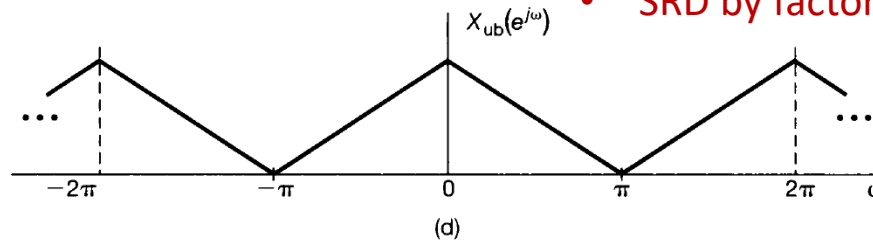
- SRD by factor of 4



- SRI by factor of 8



- SRD by factor of 9



- Overall, SRI by factor of 4.5

