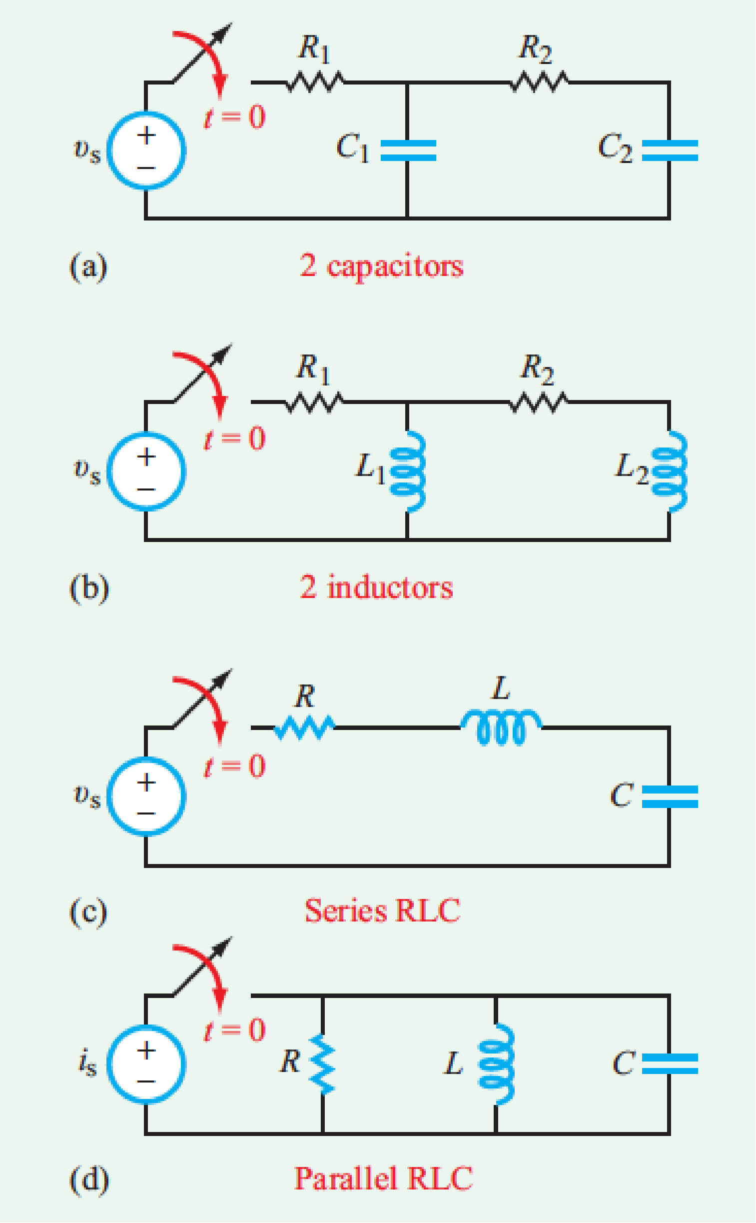
Lecture 6

- Second-Order Circuits

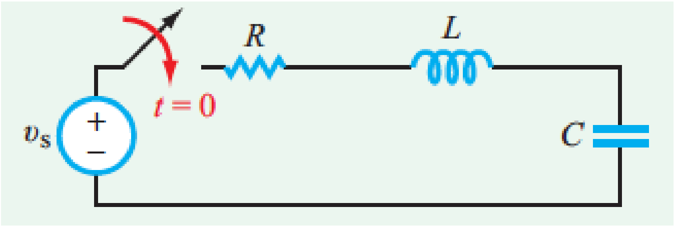
Second-Order Circuits

- Two energy storage elements
- Analysis: Determine voltage or current as a function of time
- Initial/final values of voltage/current, *and their derivatives are* needed

A second order circuit is characterized by a second order differential equation.

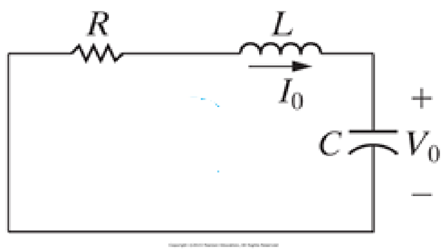


Series RLC Circuits



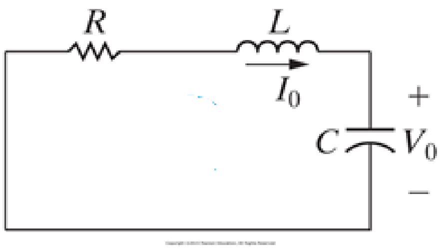
[Source: Berkeley]

Source-Free Series RLC



$$\frac{d^2v}{d^2t}+\frac{R}{L}\frac{dv}{dt}+\frac{1}{\mathrm{LC}}v=0$$

Source-Free Series RLC



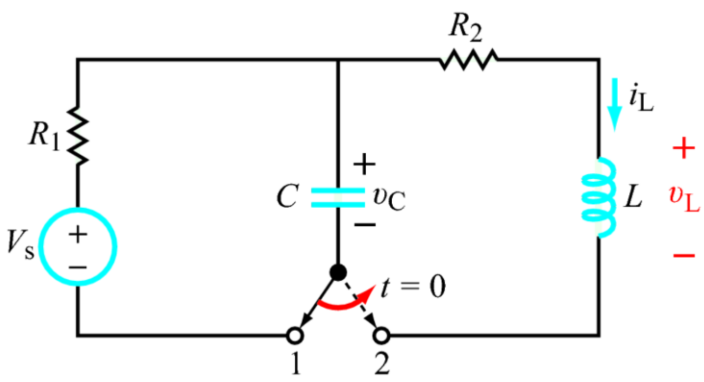
$$\frac{d^2v}{d^2t} + \frac{R}{L}\frac{dv}{dt} + \frac{1}{\mathrm{LC}}v = 0$$

$$\boxed{s^2 + \frac{R}{L}s + \frac{1}{LC} = 0}$$

$$s = -\frac{R}{2L} \pm \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}}$$

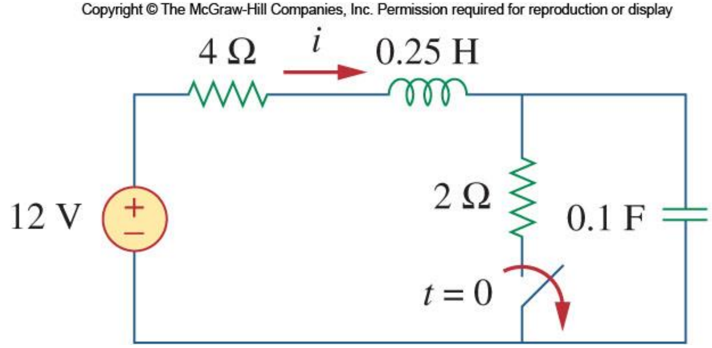
[Source: Berkeley]

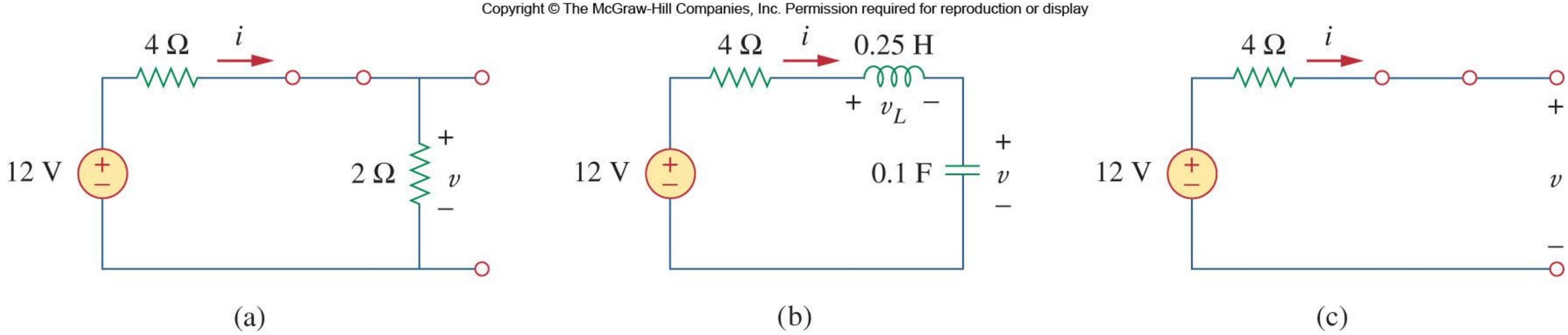
Initial and Final Conditions



Example

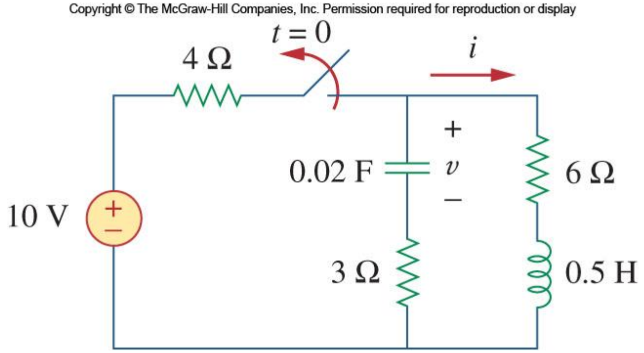
- The switch has been closed for a long time. It is open at $t = 0$. Find
  - $i(0^+)$, $v(0^+)$
  - $di(0^+)/dt$, $dv(0^+)/dt$
  - $i(\infty)$, $v(\infty)$



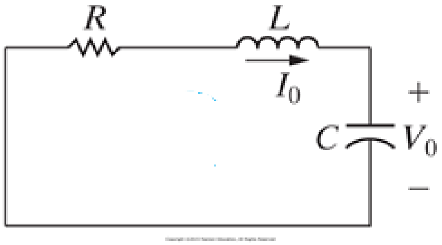


Exercise

- Assume the circuit has reached steady state at $t = 0^{-}$. Find
  - $i(0^{+})$, $v(0^{+})$
  - $di(0^{+})/dt$, $dv(0^{+})/dt$
  - $i(\infty)$, $v(\infty)$



Source-Free Series RLC

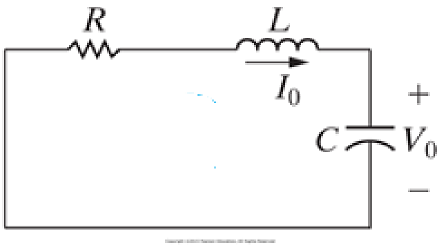


$$\frac{d^2v}{d^2t}+\frac{R}{L}\frac{dv}{dt}+\frac{1}{\mathrm{LC}}v=0$$

$$\boxed{s^2+\frac{R}{L}s+\frac{1}{LC}=0}$$

$$s=-\frac{R}{2L}\pm\sqrt{\left(\frac{R}{2L}\right)^2-\frac{1}{LC}}$$

Case 1: Overdamped ($\alpha>\omega_0$)

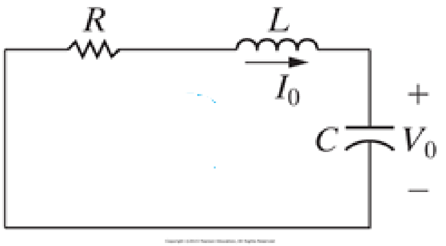


$$\frac{d^2v}{dt^2}+\frac{R}{L}\frac{dv}{dt}+\frac{1}{\mathrm{LC}}v=0$$

$$s=-\frac{R}{2L}\pm\sqrt{\left(\frac{R}{2L}\right)^2-\frac{1}{LC}}$$

$$\alpha=\frac{R}{2L}\qquad \omega_0=\frac{1}{\sqrt{LC}}$$

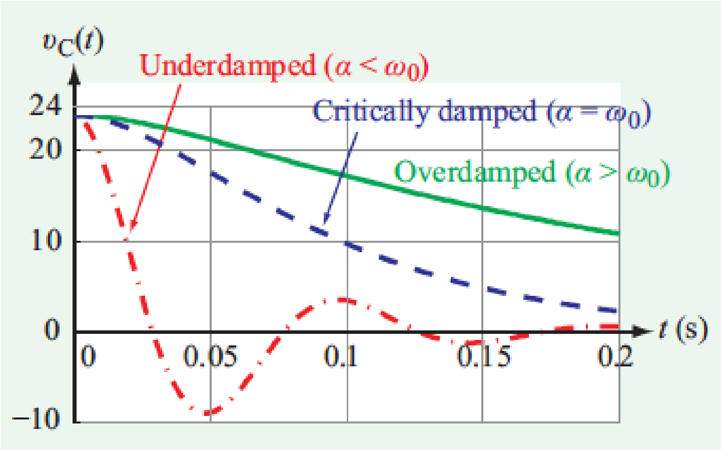
Case 1: Overdamped ($\alpha>\omega_0$)



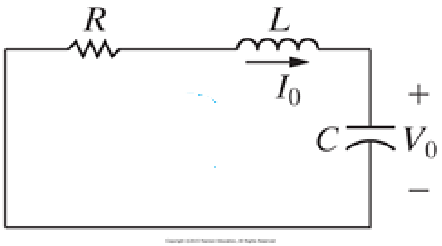
$$\frac{d^2v}{dt^2}+\frac{R}{L}\frac{dv}{dt}+\frac{1}{LC}v=0$$

$$s=-\frac{R}{2L}\pm\sqrt{\left(\frac{R}{2L}\right)^2-\frac{1}{LC}}$$

$$\alpha=\frac{R}{2L}\quad \omega_0=\frac{1}{\sqrt{LC}}$$



Case 2: Critically Damped ($\alpha=\omega_0$)



$$\frac{d^2v}{dt^2}+\frac{R}{L}\frac{dv}{dt}+\frac{1}{LC}v=0 \qquad s=-\frac{R}{2L}\pm\sqrt{\left(\frac{R}{2L}\right)^2-\frac{1}{LC}}$$

$$\alpha=\frac{R}{2L} \quad \omega_0=\frac{1}{\sqrt{LC}} \qquad s_1=-\alpha+\sqrt{\alpha^2-\omega_o^2} \quad s_2=-\alpha-\sqrt{\alpha^2-\omega_o^2}$$

$$s_1=s_2=-\alpha=-\frac{R}{2L} \qquad v(t)=A_1e^{s_1t}+A_2e^{s_2t}$$

Case 2: Critically Damped ($\alpha=\omega_0$)

Go back to

$$\frac{d^2v}{dt^2}+\frac{R}{L}\frac{dv}{dt}+\frac{1}{\mathrm{LC}}v=0 \qquad \alpha=\frac{R}{2L} \quad \omega_0=\frac{1}{\sqrt{LC}}$$

- When $\alpha=\omega_0=R/2L$, the equation becomes

$$\frac{d^2v}{dt^2}+2\alpha\frac{dv}{dt}+\alpha^2v=0$$

$$\Downarrow$$

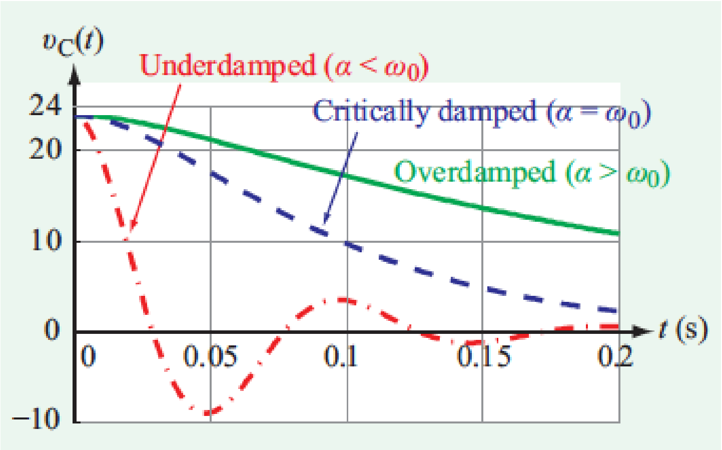
$$\frac{d}{dt}\left(\frac{dv}{dt}+\alpha v\right)+\alpha\left(\frac{dv}{dt}+\alpha v\right)=0$$

$$\Downarrow$$

$$v(t)=(A_1t+A_2)e^{-\alpha t}$$

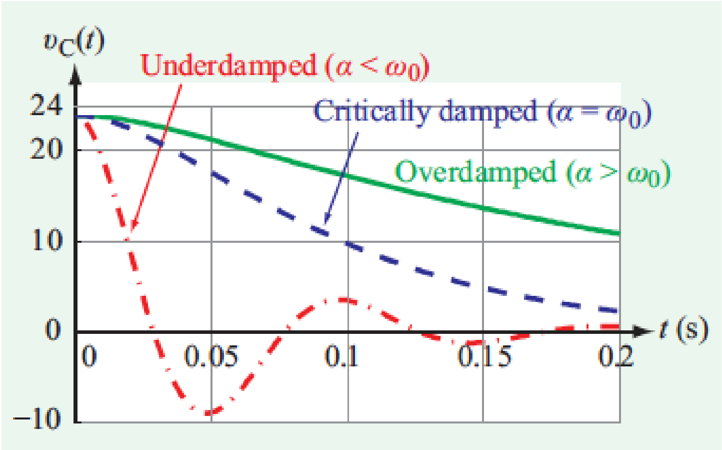
Case 2: Critically Damped ($\alpha=\omega_0$)

$$v(t) = (A_1 t + A_2)e^{-\alpha t}$$



Case 2: Critically Damped ($\alpha=\omega_0$)

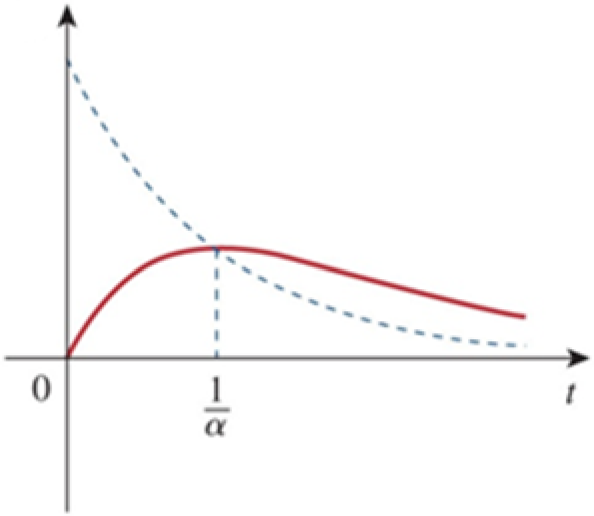
$$v(t) = (A_1 t + A_2)e^{-\alpha t}$$



(If $A_2 = 0, A_1 = 1$)

A typical critically damped response is shown

Why maximize at $t = \frac{1}{\alpha}$?



Case 3: Underdamped ($\alpha<\omega_0$)

$$s = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

$$s_1 = -\alpha + \sqrt{\alpha^2 - \omega_0^2} = -\alpha + \sqrt{-(\omega_0^2 - \alpha^2)} = -\alpha + j\omega_d$$
$$s_2 = -\alpha - \sqrt{\alpha^2 - \omega_0^2} = -\alpha - \sqrt{-(\omega_0^2 - \alpha^2)} = -\alpha - j\omega_d$$

where $j = \sqrt{-1}$ and $\omega_d = \sqrt{\omega_0^2 - \alpha^2}$.

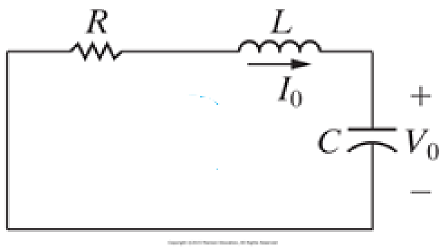
- ω_0 is often called the undamped natural frequency.
- ω_d is called the damped natural frequency.

The natural response

$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

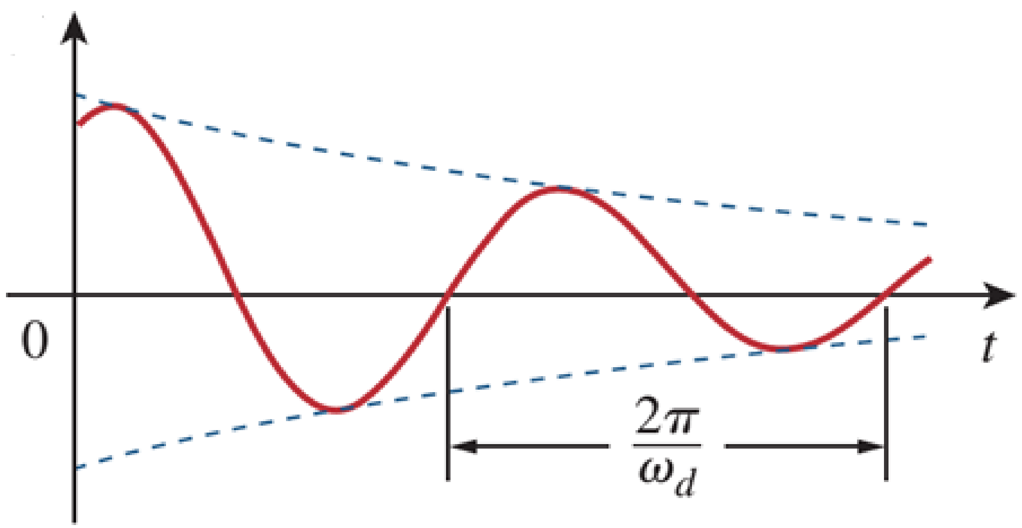
becomes

$$v(t) = e^{-\alpha t}(B_1 \cos\omega_d t + B_2 \sin\omega_d t)$$



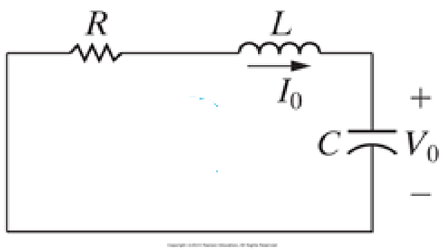
$$v(t) = e^{-\alpha t}(B_1 \cos \omega_d t + B_2 \sin \omega_d t)$$

- Exponential $e^{-\alpha t}$ * Sine/Cosine term
  - Exponentially damped, time constant = $1/\alpha$
  - Oscillatory, period $T = \frac{2\pi}{\omega_d}$



Properties of Series RLC Network

- Behavior captured by damping
  - Gradual loss of the initial stored energy
  - α determines the rate of damping



- $\alpha > \omega_0$ (i.e., $R > 2\sqrt{\frac{L}{C}}$), overdamped

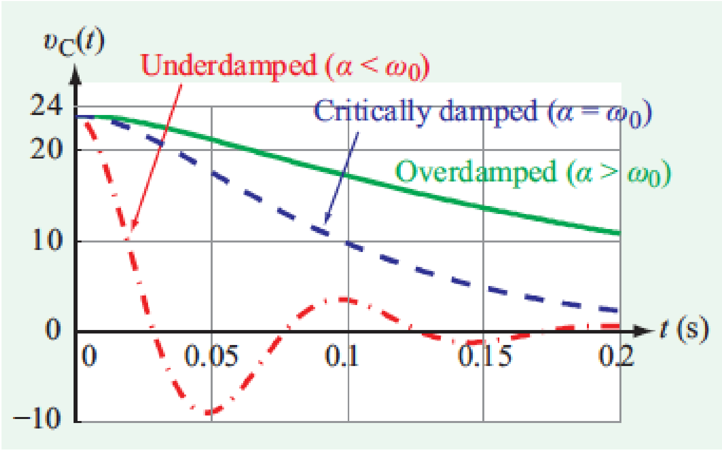
$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

- $\alpha = \omega_0$ (i.e., $R = 2\sqrt{\frac{L}{C}}$), critically damped

$$v(t) = (A_1 t + A_2)e^{-\alpha t}$$

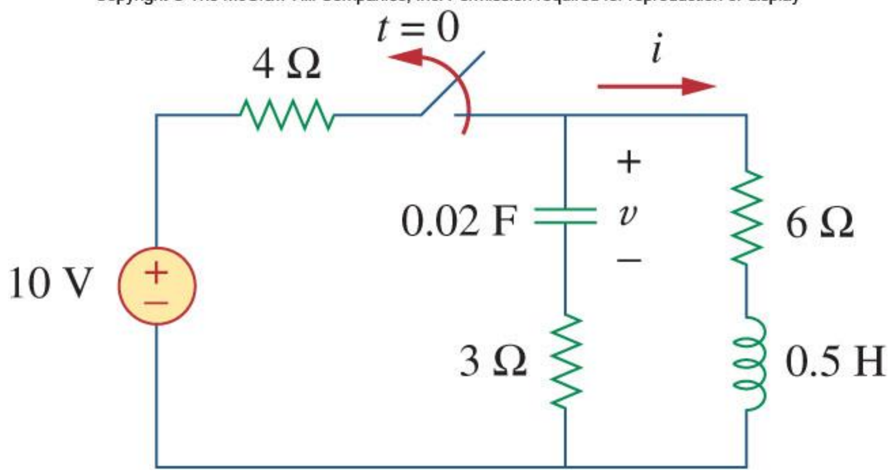
- $\alpha < \omega_0$ (i.e., $R < 2\sqrt{\frac{L}{C}}$), underdamped

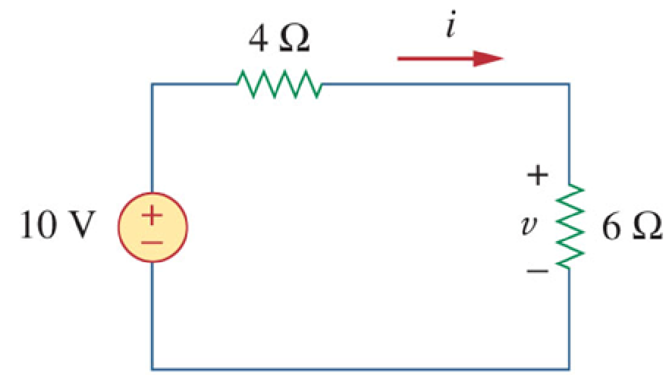
$$v(t) = e^{-\alpha t}(B_1 \cos \omega_d t + B_2 \sin \omega_d t)$$

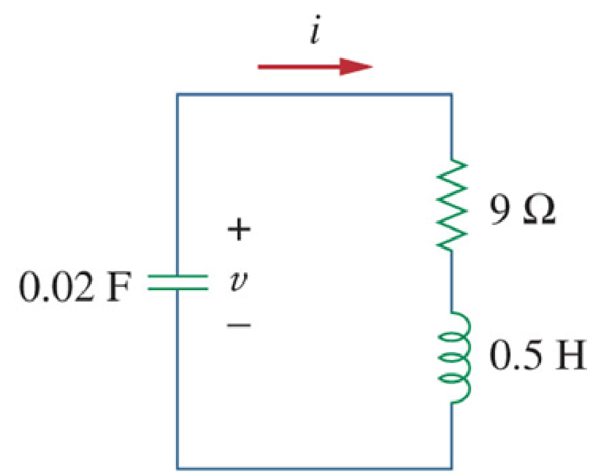


Example

- Find $v(t)$ &*i(t)* in the circuit below. Assume the circuit has reached steady state at $t = 0^-$.



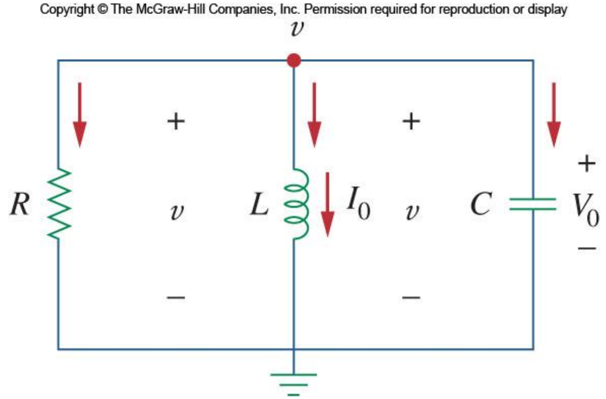




$$\alpha = \frac{R}{2L} = 9 \qquad \omega_0 = \frac{1}{\sqrt{LC}} = 10$$

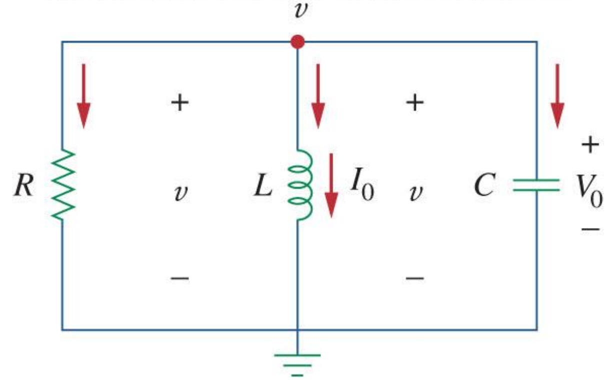
$$s_{1,2} = -\alpha \mp \sqrt{\alpha^2 - \omega_0^2} = -9 \mp j4.359$$

Source-Free Parallel RLC Network



Source-Free Parallel RLC Network

$$\frac{d^2 v}{dt^2}+\frac{1}{RC}\frac{dv}{dt}+\frac{1}{LC}v=0$$



- The characteristic equation is:

$$s^2+\frac{1}{RC}s+\frac{1}{LC}=0$$

From this, we can find the roots of the characteristic equation to be:

$$s_{1,2}=-\alpha\pm\sqrt{\alpha^2-\omega_0^2}$$

$$\alpha=\frac{1}{2RC}\qquad \omega_0=\frac{1}{\sqrt{LC}}$$

As in last time, there are three scenarios to consider.

Three Damping Cases

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

$$\frac{d^2v}{dt^2} + \frac{1}{RC}\frac{dv}{dt} + \frac{1}{LC}v = 0 \qquad \alpha = \frac{1}{2RC} \quad \omega_0 = \frac{1}{\sqrt{LC}}$$

- For the overdamped case, the roots are real and negative,

$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

- For critically damped, the roots are real and equal

$$v(t) = (A_2 + A_1 t)e^{-\alpha t}$$

- In the underdamped case, the roots are complex

$$v(t) = e^{-\alpha t}(A_1 \cos \omega_d t + A_2 \sin \omega_d t)$$

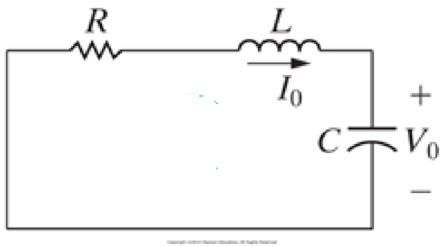
Series vs. Parallel (Source-Free RLC Network)

- Series

$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$$v(t) = (A_1 t + A_2) e^{-\alpha t}$$

$$\text{v}(t) = e^{-\alpha t}(B_1 \cos \omega_d t + B_2 \sin \omega_d t)$$

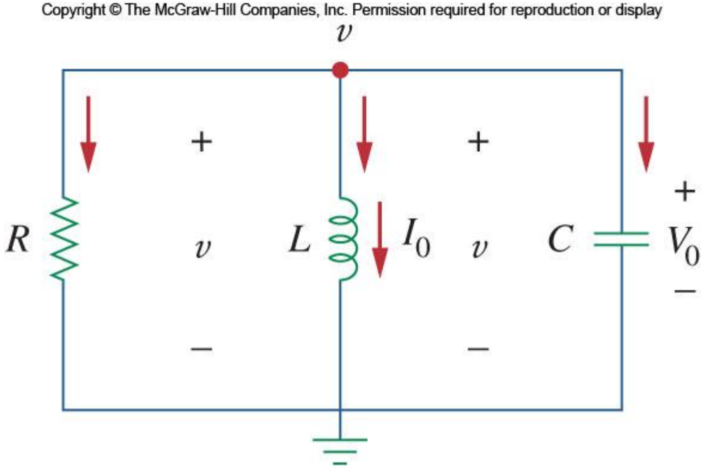


- Parallel

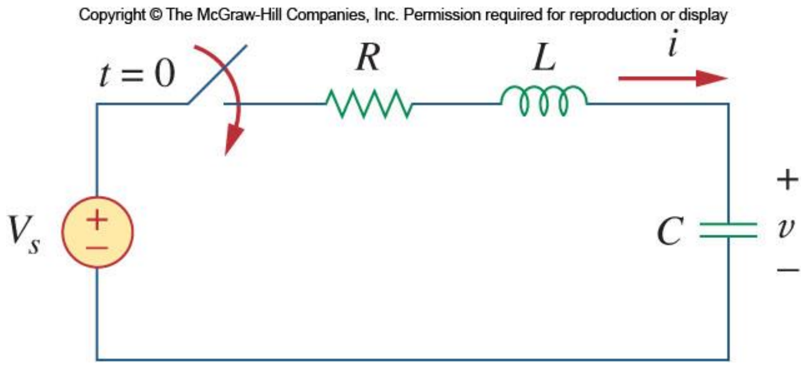
$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$$v(t) = (A_2 + A_1 t) e^{-\alpha t}$$

$$v(t) = e^{-\alpha t}(A_1 \cos \omega_d t + A_2 \sin \omega_d t)$$



Step Response of a Series RLC Circuit



$$\frac{d^2v}{dt^2} + \frac{R}{L}\frac{dv}{dt} + \frac{v}{LC} = \frac{V_s}{LC}$$

- The solution

$$v(t) = v_t(t) + v_{ss}(t)$$

- The complete solutions for the three conditions of damping are:

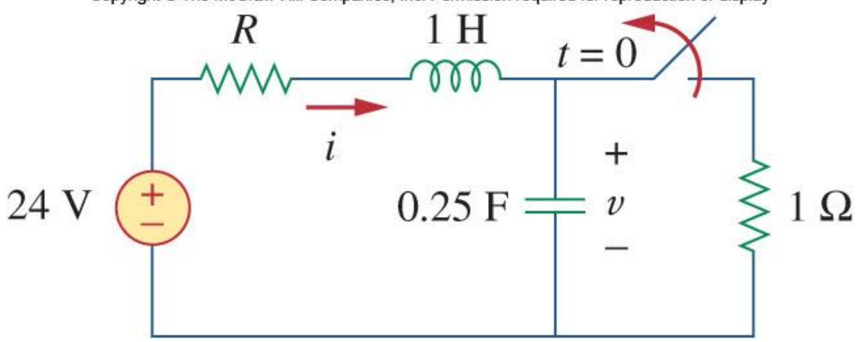
$$v(t) = V_s + (A_1 e^{s_1 t} + A_2 e^{s_2 t}) \text{ (Overdamped)}$$

$$v(t) = V_s + (A_1 + A_2 t)e^{-\alpha t} \text{ (Critically Damped)}$$

$$v(t) = V_s + (A_1 \cos\omega_d t + A_2 \sin\omega_d t)e^{-\alpha t} \text{ (Underdamped)}$$

Example

- Find $v(t)$ and $i(t)$ for $t > 0$.
  Consider three cases:
  - $R = 5\Omega$
  - $R = 4\Omega$
  - $R = 1\Omega$



When $R = 5\Omega$,

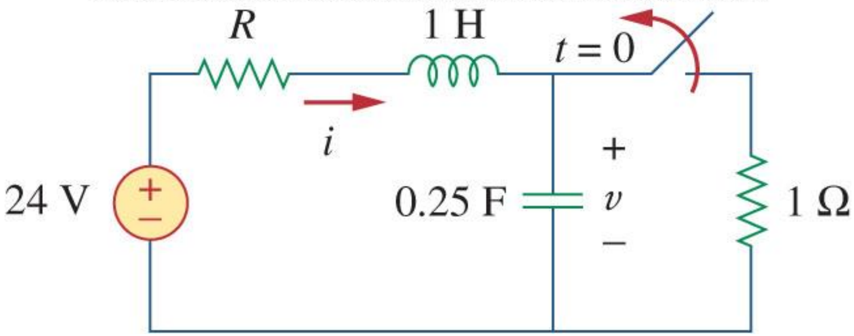
- For $t < 0$, switch closed, capacitor open, inductor shorted.

$$i(0) = 4A = C\frac{dv(0)}{dt},\ \ v(0) = 4V,\ \ \frac{dv(0)}{dt} = 16$$

- For $t > 0$, switch open, a series RLC network

$$\alpha = \frac{R}{2L} = 2.5,\ \ \omega_0 = \frac{1}{\sqrt{LC}} = 2,\ \ s_{1,2} = -1, -4 \quad \text{Overdamped.}$$

$$v(t) = v_{ss} + (A_1 e^{-t} + A_2 e^{-4t})$$



When $R = 4\Omega$,

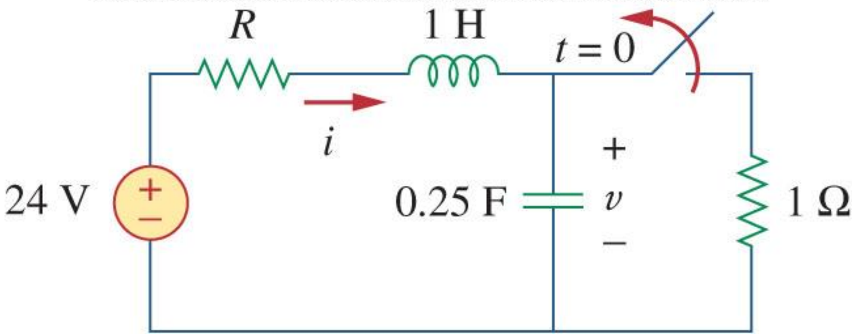
- For $t < 0$, switch closed, capacitor open, inductor shorted.

$$i(0) = 4.8A = C\frac{dv(0)}{dt},\ \ v(0) = 4.8V,\ \ \frac{dv(0)}{dt} = 19.2$$

- For $t > 0$, switch open, a series RLC network

$$\alpha = \frac{R}{2L} = 2,\ \ \omega_0 = \frac{1}{\sqrt{LC}} = 2,\ \ s_{1,2} = -2$$ Critically damped

$$v(t) = v_{ss} + (A_1 + A_2 t)e^{-2t}$$



When $R = 1\Omega$,

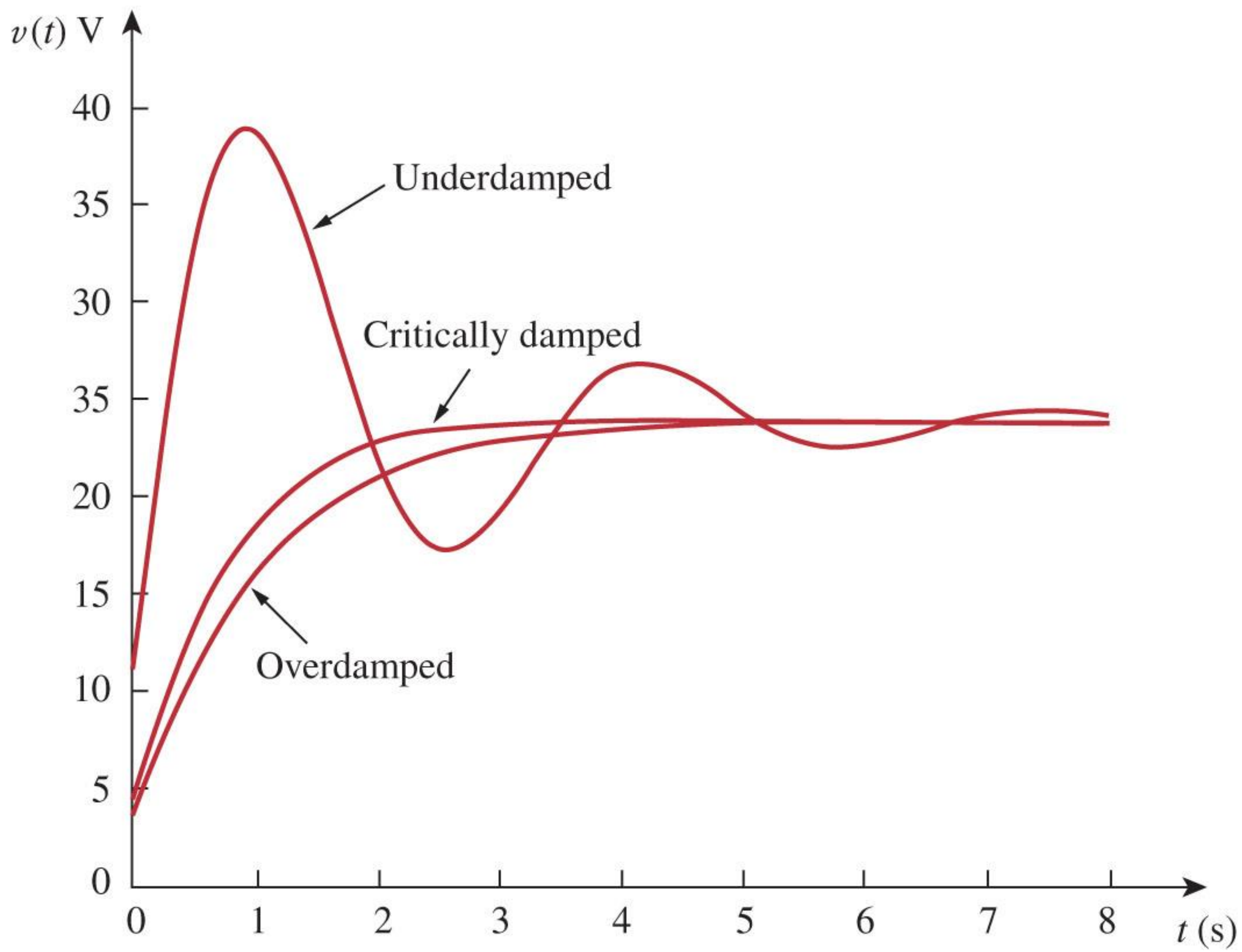
- For $t < 0$, switch closed, capacitor open, inductor shorted.

$$i(0) = 12A = C\frac{dv(0)}{dt},\ \ v(0) = 12V,\ \ \frac{dv(0)}{dt} = 48$$

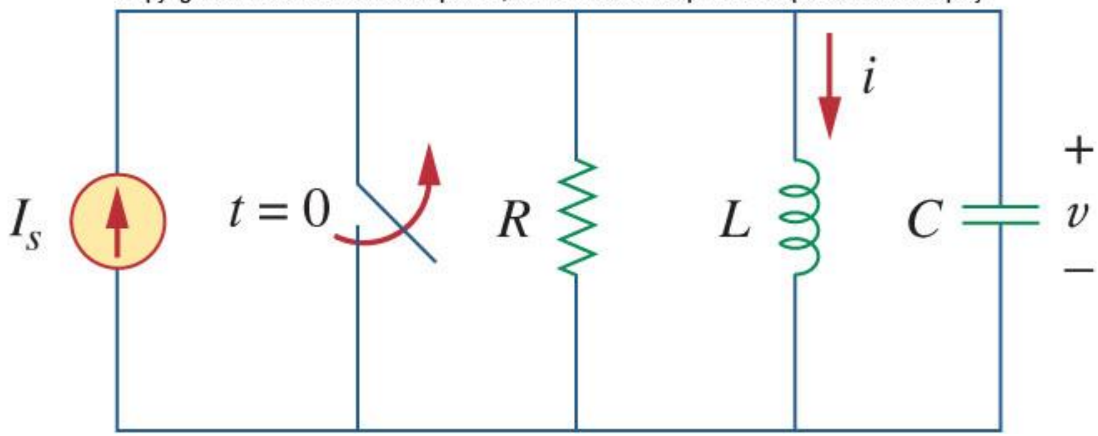
- For $t > 0$, switch open, a series RLC network

$$\alpha = \frac{R}{2L} = 0.5,\ \ \omega_0 = \frac{1}{\sqrt{LC}} = 2,\ \ s_{1,2} = -0.5 \mp j1.936$$ Underdamped

$$v(t) = v_{ss} + (A_1 \cos 1.936t + A_2 \sin 1.936t)e^{-0.5t}$$


v(t) V
40
35
30
35
20
15
10
5
0
Underdamped
Critically damped
Overdamped
0
1
2
3
4
5
6
7
8
t (s)

Step Response of a Parallel RLC Circuit



Apply KCL,

$$\frac{v}{R} + i + C\frac{dv}{dt} = I_s$$

But

$$v = L\frac{di}{dt}$$

So we get

$$\frac{d^2 i}{d^2 t} + \frac{1}{RC}\frac{di}{dt} + \frac{i}{LC} = \frac{I_s}{LC}$$

Step Response of a Parallel RLC Circuit

$$\frac{d^2 i}{d^2 t} + \frac{1}{RC}\frac{di}{dt} + \frac{i}{LC} = \frac{I_s}{LC}$$

- As in the series RLC case, the response is a combination of transient and steady state responses:

$$i(t) = I_s + A_1 e^{\tau_1 t} + A_2 e^{\tau_2 t} \quad \text{(Overdamped)}$$

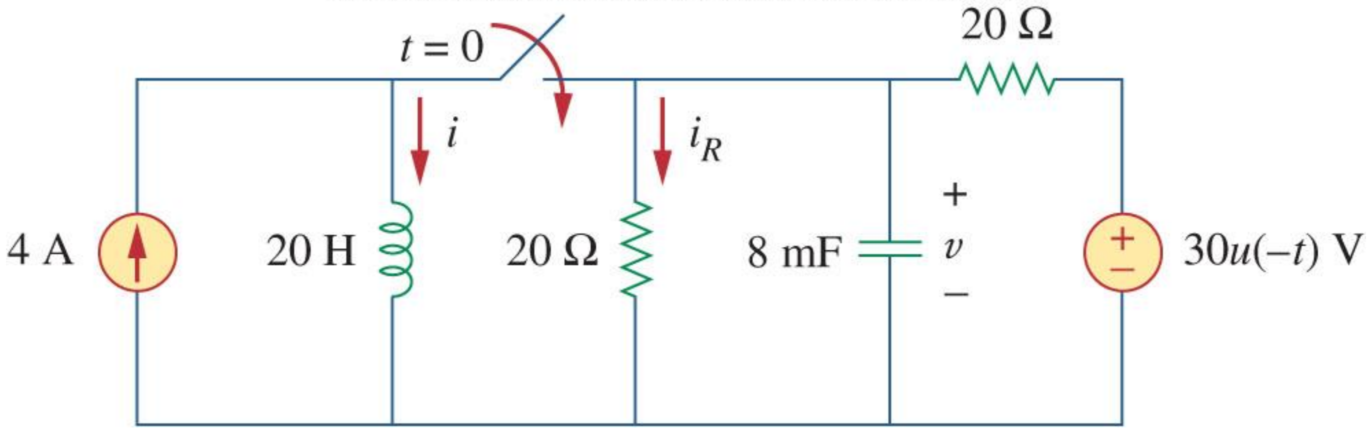
$$i(t) = I_s + (A_1 + A_2 t)e^{-\alpha t} \quad \text{(Critally Damped)}$$

$$i(t) = I_s + (A_1 \cos\omega_d t + A_2 \sin\omega_d t)e^{-\alpha t} \quad \text{(Underdamped)}$$

Here the variables A_1 and A_2 are obtained from the initial conditions, *i(0)* and *di(0)/dt*.

Example

- Find $i(t)$ and $i_R(t)$ for $t > 0$.



Initial values ($t < 0$): $i(0) = 4A$, $v(0) = \frac{20}{20+20} \times 30V = 15V = L\frac{di(0)}{dt}$

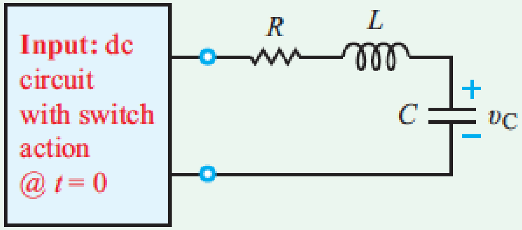
For $t > 0$, $\alpha = \frac{1}{2RC} = \frac{1}{2\times10\times8\times10^{-3}} = 6.25$, $\omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{20\times8\times10^{-3}}} = 2.5$

$$s_{1,2} = -6.25 \mp 5.7282$$

$$i(t) = I_s + A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

Step response of RLC circuits for $t \geq 0$.

Series RLC



Total Response

Overdamped ($\alpha > \omega_0$)

$$v_C(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t} + v_C(\infty)$$

$$A_1 = \frac{\frac{1}{C}\, i_C(0) - s_2[v_C(0) - v_C(\infty)]}{s_1 - s_2}$$

$$A_2 = \left[\frac{\frac{1}{C}\, i_C(0) - s_1[v_C(0) - v_C(\infty)]}{s_2 - s_1}\right]$$

Critically Damped ($\alpha = \omega_0$)

$$v_C(t) = (B_1 + B_2 t)e^{-\alpha t} + v_C(\infty)$$

$$B_1 = v_C(0) - v_C(\infty)$$

$$B_2 = \frac{1}{C}\, i_C(0) + \alpha[v_C(0) - v_C(\infty)]$$

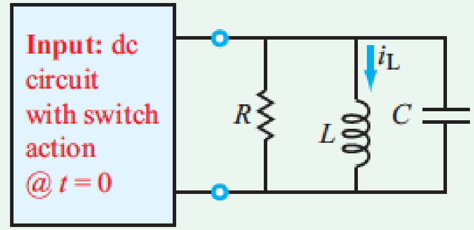
Underdamped ($\alpha < \omega_0$)

$$v_C(t) = e^{-\alpha t}(D_1 \cos\omega_d t + D_2 \sin\omega_d t) + v_C(\infty)$$

$$D_1 = v_C(0) - v_C(\infty)$$

$$D_2 = \frac{\frac{1}{C}\, i_C(0) + \alpha[v_C(0) - v_C(\infty)]}{\omega_d}$$

Parallel RLC



Total Response

Overdamped ($\alpha > \omega_0$)

$$i_L(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t} + i_L(\infty)$$

$$A_1 = \frac{\frac{1}{L}\, v_L(0) - s_2[i_L(0) - i_L(\infty)]}{s_1 - s_2}$$

$$A_2 = \left[\frac{\frac{1}{L}\, v_L(0) - s_1[i_L(0) - i_L(\infty)]}{s_2 - s_1}\right]$$

Critically Damped ($\alpha = \omega_0$)

$$i_L(t) = (B_1 + B_2 t)e^{-\alpha t} + i_L(\infty)$$

$$B_1 = i_L(0) - i_L(\infty)$$

$$B_2 = \frac{1}{L}\, v_L(0) + \alpha[i_L(0) - i_L(\infty)]$$

Underdamped ($\alpha < \omega_0$)

$$i_L(t) = e^{-\alpha t}(D_1 \cos\omega_d t + D_2 \sin\omega_d t) + i_L(\infty)$$

$$D_1 = i_L(0) - i_L(\infty)$$

$$D_2 = \frac{\frac{1}{L}\, v_L(0) + \alpha[i_L(0) - i_L(\infty)]}{\omega_d}$$

Auxiliary Relations

$$\alpha = \begin{cases} \dfrac{R}{2L} & \text{Series RLC} \\ \dfrac{1}{2RC} & \text{Parallel RLC} \end{cases}$$

$$\omega_0 = \frac{1}{\sqrt{LC}}$$

$$\omega_d = \sqrt{\omega_0^2 - \alpha^2}$$

$$s_1 = -\alpha + \sqrt{\alpha^2 - \omega_0^2} \qquad s_2 = -\alpha - \sqrt{\alpha^2 - \omega_0^2}$$

General Second-Order Circuits

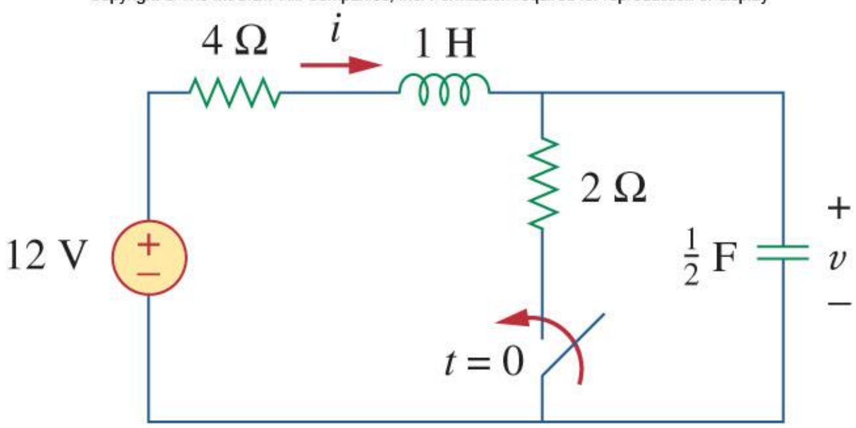
- The principles of the approach to solving the series and parallel forms of RLC circuits can be applied to general second order circuits, by taking the following four steps:
  1. First determine the initial conditions, *x(0)* and *dx(0)/dt*.
  2. Turn off the independent sources and find the form of the transient response by applying KVL and KCL.
     - Depending on the damping found, the unknown constants will be found.
  3. We obtain the steady-state response as:

     $$x_{ss}(t) = x(\infty)$$

     where $x(\infty)$ is the final value of *x* obtained in step 1.
  4. The total response = transient response + steady-state response.

$$x(t) = x_t(t) + x_{ss}(t)$$

General RLC Circuits

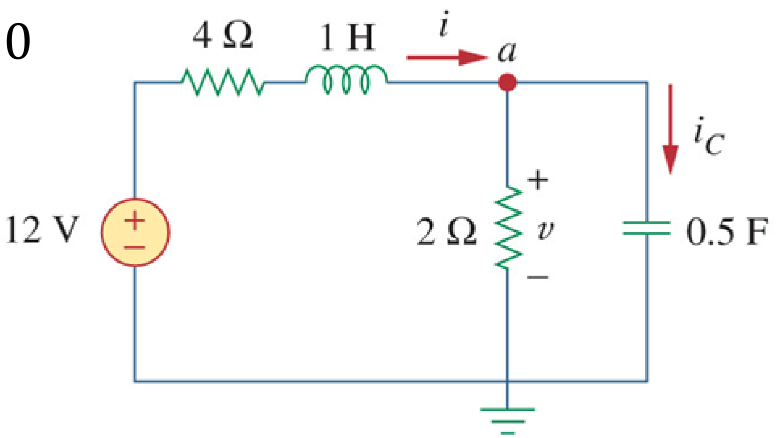


- Find the complete response v for $t > 0$ in the circuit.

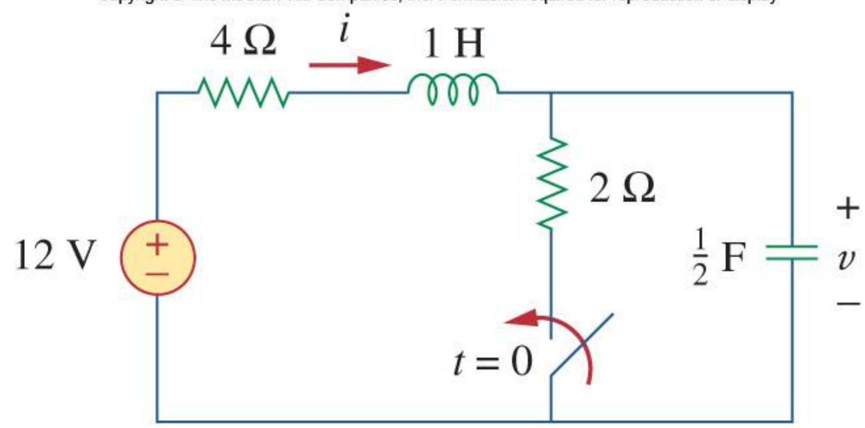
1. Initial conditions

$$v(0^+) = v(0^-) = 12V,\ i(0^+) = i(0^-) = 0$$

$$\frac{dv(0^+)}{dt} = \frac{i_C(0^+)}{C} = \frac{-12/2}{0.5} = -12\ V/s$$



General RLC Circuits



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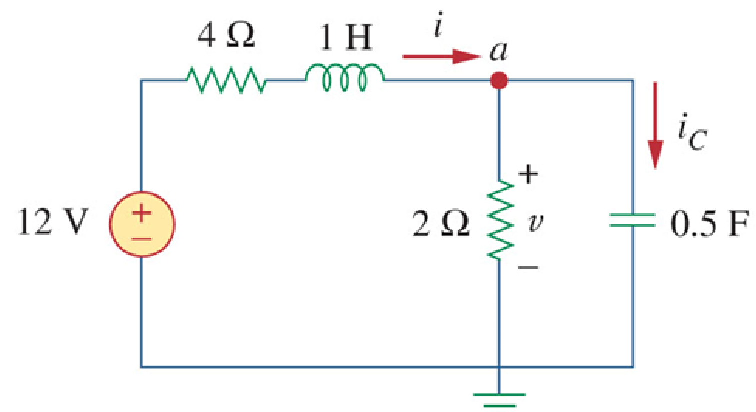


2. Transient response

KCL at node *a*: $i = \frac{v}{2} + 0.5\frac{dv}{dt}$

KVL on left mesh: $4i + 1\frac{di}{dt} + v = 0$

$$\Rightarrow \frac{d^2v}{dt^2} + 5\frac{dv}{dt} + 6v = 0 \Rightarrow v_t(t) = A_1e^{-2t} + A_2e^{-3t} = 12e^{-2t} - 4e^{-3t}$$

3. Steady-state response $v_{ss}(t) = 4V$

4. Put together

General solution for second-order circuits for $t \geq 0$.

$x(t)$ = unknown variable (voltage or current)

Differential equation:	$x'' + ax' + bx = c$
Initial conditions:	$x(0)$ and $x'(0)$
Final condition:	$x(\infty) = \dfrac{c}{b}$

$$\alpha = \frac{a}{2} \qquad \omega_0 = \sqrt{b}$$

Overdamped Response $\alpha > \omega_0$

$$x(t) = [A_1 e^{s_1 t} + A_2 e^{s_2 t} + x(\infty)]$$

$$s_1 = -\alpha + \sqrt{\alpha^2 - \omega_0^2} \qquad s_2 = -\alpha - \sqrt{\alpha^2 - \omega_0^2}$$

$$A_1 = \frac{x'(0) - s_2[x(0) - x(\infty)]}{s_1 - s_2} \qquad A_2 = -\left[\frac{x'(0) - s_1[x(0) - x(\infty)]}{s_1 - s_2}\right]$$

Critically Damped $\alpha = \omega_0$

$$x(t) = [(B_1 + B_2 t)e^{-\alpha t} + x(\infty)]$$

$$B_1 = x(0) - x(\infty) \qquad B_2 = x'(0) + \alpha[x(0) - x(\infty)]$$

Underdamped $\alpha < \omega_0$

$$x(t) = [D_1 \cos \omega_d t + D_2 \sin \omega_d t + x(\infty)]e^{-\alpha t}$$

$$D_1 = x(0) - x(\infty) \qquad D_2 = \frac{x'(0) + \alpha[x(0) - x(\infty)]}{\omega_d}$$

$$\omega_d = \sqrt{\omega_0^2 - \alpha^2}$$

$x(t) =$ unknown variable (voltage or current) **Differential equation:** $x'' + ax' + bx = c$ **Initial conditions:** $x(0)$ and $x'(0)$ **Final condition:** $x(\infty) = \dfrac{c}{b}$ $\alpha = \dfrac{a}{2}$ $\quad \omega_0 = \sqrt{b}$
Overdamped Response $\alpha > \omega_0$ $x(t) = [A_1 e^{s_1 t} + A_2 e^{s_2 t} + x(\infty)]\, u(t)$ $s_1 = -\alpha + \sqrt{\alpha^2 - \omega_0^2}$ $\quad s_2 = -\alpha - \sqrt{\alpha^2 - \omega_0^2}$ $A_1 = \dfrac{x'(0) - s_2[x(0) - x(\infty)]}{s_1 - s_2}$ $\quad A_2 = -\left[\dfrac{x'(0) - s_1[x(0) - x(\infty)]}{s_1 - s_2}\right]$
Critically Damped $\alpha = \omega_0$ $x(t) = [(B_1 + B_2 t)e^{-\alpha t} + x(\infty)]\, u(t)$ $B_1 = x(0) - x(\infty)$ $\quad B_2 = x'(0) + \alpha[x(0) - x(\infty)]$
Underdamped $\alpha < \omega_0$ $x(t) = [D_1 \cos \omega_d t + D_2 \sin \omega_d t + x(\infty)]e^{-\alpha t}\, u(t)$ $D_1 = x(0) - x(\infty)$ $\quad D_2 = \dfrac{x'(0) + \alpha[x(0) - x(\infty)]}{\omega_d}$ $\omega_d = \sqrt{\omega_0^2 - \alpha^2}$

[Important]

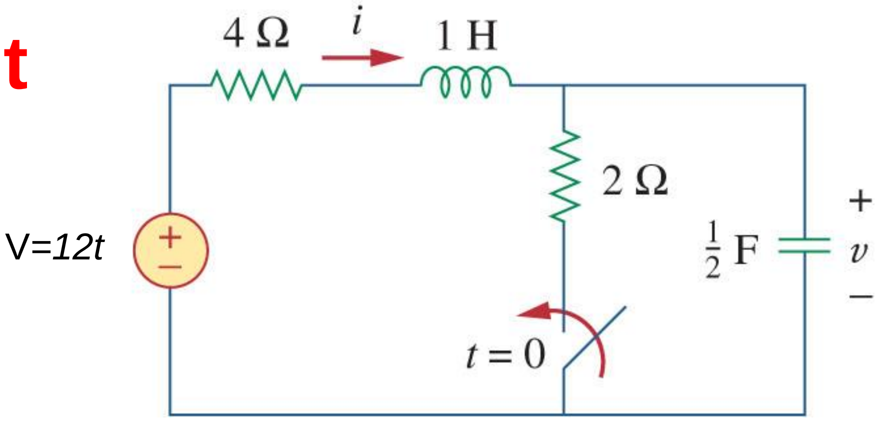
1.This table works well when c is a constant, as x(∞) is actually a particular solution (特解) of the equation.

2. While for c is a function of time (t), such as c= 5t; c= t^2+3; you should also be able to solve the equation (Requirement of the course).

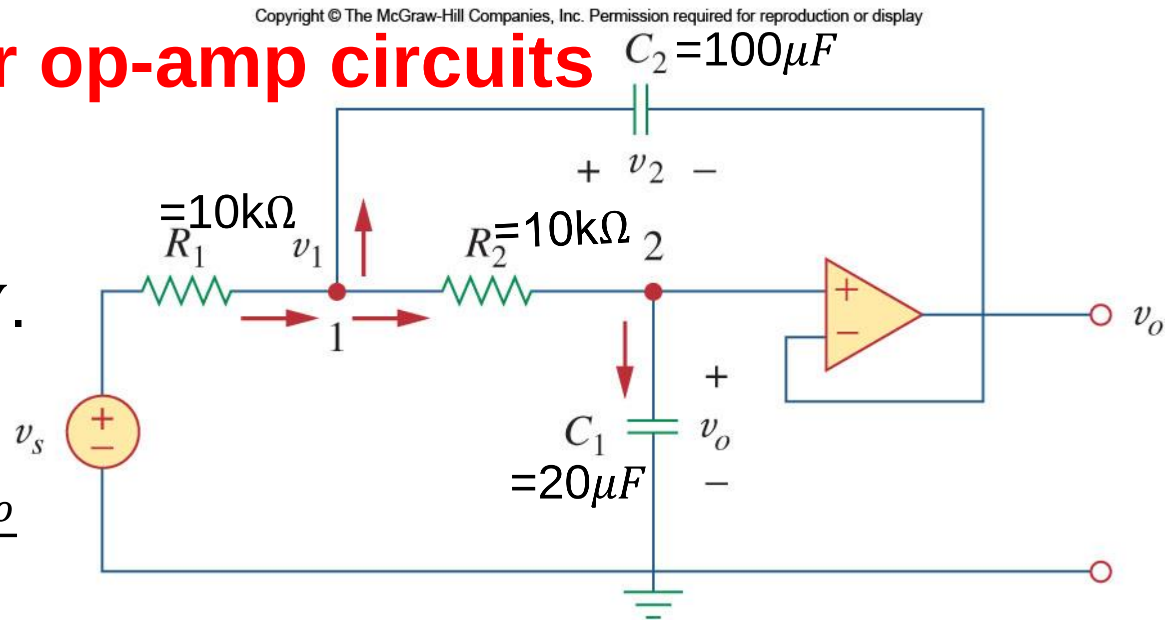
3. If you are not familiar with solving such an equation, read the material I uploaded.

Self-test-General RLC Circuit

- Find the complete response v for $t > 0$ in the circuit.



Example of 2nd-order op-amp circuits



- Find v_o for $t > 0$ when $v_s = 10u(t)mV$.

KCL at node 1:

$$\frac{v_s - v_1}{R_1} = C_2 \frac{dv_2}{dt} + \frac{v_1 - v_o}{R_2}$$

KCL at node 2:

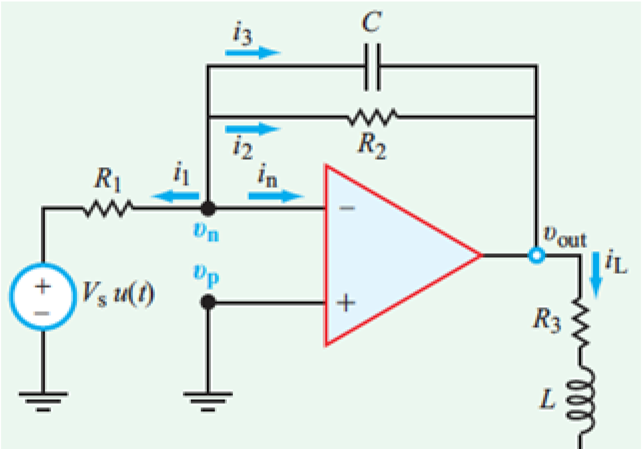
$$C_1 \frac{dv_o}{dt} = \frac{v_1 - v_o}{R_2}$$

$$v_1 - v_2 = v_o$$

$$\Rightarrow \quad \frac{d^2 v_o}{dt^2} + \left(\frac{1}{R_1 C_2} + \frac{1}{R_2 C_2}\right)\frac{dv_o}{dt} + \frac{v_o}{R_1 R_2 C_1 C_2} = \frac{v_s}{R_1 R_2 C_1 C_2}$$

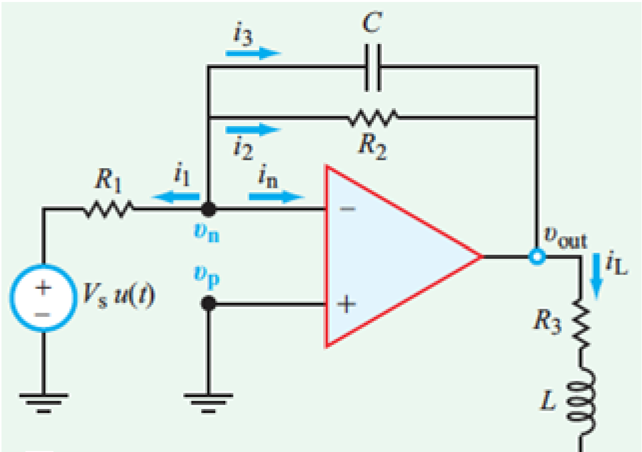
Initial conditions: $v_o(0^+) = 0$, $C_1 \frac{dv_o(0^+)}{dt} = \frac{v_1(0^+) - v_o(0^+)}{R_2} = \frac{v_2(0^+)}{R_2} = 0$

Example---求Vsu(t) 状态下I_L



Op-amp circuit

Example



Op-amp circuit

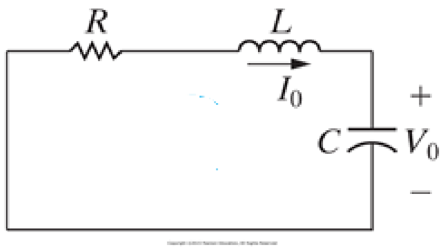
$$\frac{R_3}{R_2} i_L + \left(\frac{L}{R_2} + R_3 C\right) \frac{di_L}{dt} + LC \frac{d^2 i_L}{dt^2} = -\frac{V_s}{R_1}$$

$$i_L(\infty) = \frac{v_{out}(\infty)}{R_3} = -\frac{R_2 V_s}{R_1 R_3} = -1 \text{ mA}$$

$$i_L(0) = i_L(0^-) = 0, \quad i_L'(0) = \frac{1}{L} v_L(0) = 0.$$

Summary

- Source Free Series RLC



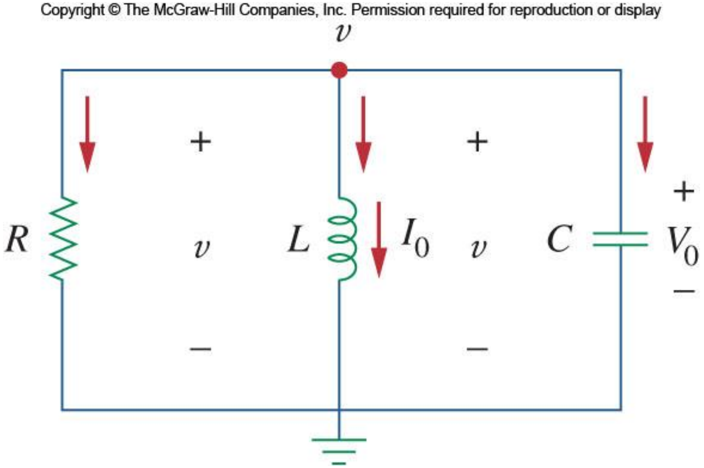
$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$$v(t) = (A_1 t + A_2) e^{-\alpha t}$$

$$v(t) = e^{-\alpha t}(B_1 \cos \omega_d t + B_2 \sin \omega_d t)$$

$$\frac{d^2 v}{d^2 t} + \frac{R}{L}\frac{dv}{dt} + \frac{1}{\text{LC}} v = 0$$

- Source Free Parallel RLC



$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

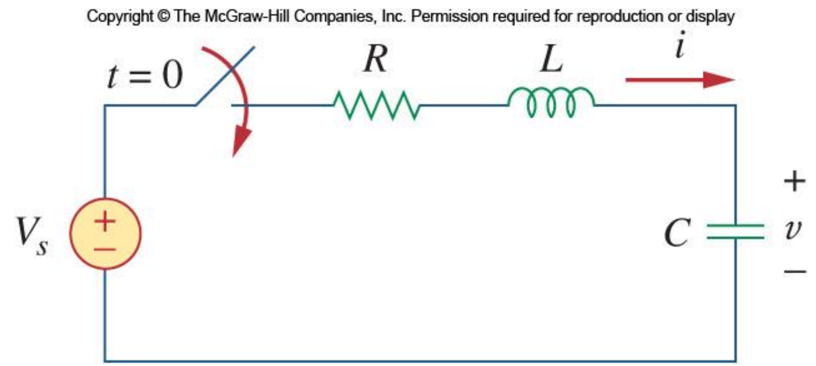
$$v(t) = (A_2 + A_1 t) e^{-\alpha t}$$

$$v(t) = e^{-\alpha t}(A_1 \cos \omega_d t + A_2 \sin \omega_d t)$$

$$\frac{d^2 v}{dt^2} + \frac{1}{RC}\frac{dv}{dt} + \frac{1}{LC} v = 0$$

Step Response of RLC Circuits

$$\frac{d^2v}{dt^2}+\frac{R}{L}\frac{dv}{dt}+\frac{v}{LC}=\frac{V_s}{LC}$$



$v(t) = V_s + (A_1 e^{s_1 t} + A_2 e^{s_2 t})$ (Overdamped)

$v(t) = V_s + (A_1 + A_2 t)e^{-\alpha t}$ (Critically Damped)

$v(t) = V_s + (A_1 \cos\omega_d t + A_2 \sin\omega_d t)e^{-\alpha t}$ (Underdamped)

$$\frac{d^2i}{d^2t}+\frac{1}{RC}\frac{di}{dt}+\frac{i}{LC}=\frac{I_s}{LC}$$