Convex Functions

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Outline

- 1 Definition of Convex Function
- 2 Restriction of a Convex Function to a Line
- 3 First and Second Order Conditions
- 4 Operations that Preserve Convexity
- 5 Quasi-Convexity, Log-Convexity, and Convexity w.r.t. Generalized Inequalities

Definition of Convex Function

A function $f : \mathbb{R}^n \Rightarrow \mathbb{R}$ is said to be **convex** if the domain, **dom** f, is convex and for any $x, y \in \text{dom} f$ and $0 \le \theta \le 1$,

$$f(\theta x + (1 - \theta)y) \le \theta f(x) + (1 - \theta)f(y)$$



- *f* is **strictly convex** if the inequality is strict for $0 < \theta < 1$
- f is concave if -f is convex

Examples on \mathbb{R}

Convex functions:

- $affine: ax + b \text{ on } \mathbb{R}$
- powers of absolute value: $|x|^p$ on \mathbb{R} , for $p \ge 1$ (e.g., |x|)
- powers: x^p on \mathbb{R}_{++} , for $p \ge 1$ or $p \le 0$ (e.g., x^2)
- ightharpoonup exponential: e^{ax} on \mathbb{R}
- **№** negative entropy: $x \log x$ on \mathbb{R}_{++}

Concave functions:

- $affine: ax + b \text{ on } \mathbb{R}$
- **Proof** powers: x^p on \mathbb{R}_{++} , for $0 \le p \le 1$

Examples on \mathbb{R}^n

- Affine functions $f(x) = a^T x + b$ are convex and concave on \mathbb{R}^n
- Norms $\|x\|$ are convex on \mathbb{R}^n (e.g., $\|x\|_{\infty}, \|x\|_1, \|x\|_2$)
- Quadratic functions $f(x) = x^T P x + 2q^T x + r$ are convex \mathbb{R}^n if and only if $P \succeq 0$
- The geometric mean $f(\boldsymbol{x}) = (\prod_{i=1}^n x_i)^{1/n}$ is concave on \mathbb{R}^n_{++}
- The log-sum-exp $f(x) = \log \sum_i e^{x_i}$ is convex on \mathbb{R}^n (it can be used to approximate $\max_{i=1,\cdots,n} x_i$)
- Quadratic over linear: $f(x,y) = x^T x/y$ is convex on $\mathbb{R}^n \times \mathbb{R}_{++}$

Examples on $\mathbb{R}^{n \times n}$

Affine functions: (prove it!)

$$f(\boldsymbol{X}) = \text{Tr}(\boldsymbol{A}\boldsymbol{X}) + b$$

are convex and concave on $\mathbb{R}^{n \times n}$

Logarithmic determinant function: (prove it!)

$$f(\boldsymbol{X}) = \operatorname{logdet}(\boldsymbol{X})$$

is concave on $\mathbb{S}^n = \{ \boldsymbol{X} \in \mathbb{R}^{n \times n} \mid \boldsymbol{X} \succeq \boldsymbol{0} \})$

Maximum eigenvalue function: (prove it!)

$$f(\boldsymbol{x}) = \lambda_{\max}(\boldsymbol{X}) = \sup_{\boldsymbol{y} \neq \boldsymbol{0}} \frac{\boldsymbol{y}^T \boldsymbol{X} \boldsymbol{y}}{\boldsymbol{y}^T \boldsymbol{y}}$$

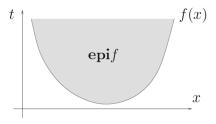
is convex on \mathbb{S}^n

Epigraph

ightharpoonup The **epigraph** of f if the set

epi
$$f = \{(\boldsymbol{x}, t) \in \mathbb{R}^{n+1} \mid \boldsymbol{x} \in \text{dom } f, \ f(\boldsymbol{x}) \le t\}$$

Relation between convexity in sets and convexity in functions: f is convex \iff epi f is convex



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Restriction of a Convex Function to a Line

•• $f: \mathbb{R}^n \longrightarrow \mathbb{R}$ is convex if and only if the function $g: \mathbb{R} \longrightarrow \mathbb{R}$

$$g(t) = f(\boldsymbol{x} + t\boldsymbol{v}), \quad \text{dom } g = \{t \mid \boldsymbol{x} + t\boldsymbol{v} \in \text{dom } f\}$$

is convex for any $x \in \text{dom } f$, $v \in \mathbb{R}^n$

- In words: a function is convex if and only if it is convex when restricted to an arbitrary line.
- Implication: we can check convexity of f by checking convexity of functions of one variable!
- **Example:** concavity of $\log \det(\mathbf{X})$ follows from concavity of $\log(x)$

Example

Example: concavity of logdet(X):

$$g(t) = \operatorname{logdet}(\boldsymbol{X} + t\boldsymbol{V}) = \operatorname{logdet}(\boldsymbol{X}) + \operatorname{logdet}(\boldsymbol{I} + t\boldsymbol{X}^{-1/2}\boldsymbol{V}\boldsymbol{X}^{-1/2})$$
$$= \operatorname{logdet}(\boldsymbol{X}) + \sum_{i=1}^{n} \operatorname{log}(1 + t\lambda_i)$$

where λ_i 's are the eigenvalues of $X^{-1/2}VX^{-1/2}$.

The function g is concave in t for any choice of $X \succ 0$ and V; therefore, f is concave.

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First and Second Order Conditions I

™ Gradient (for differentiable *f*):

$$\nabla f(\boldsymbol{x}) = \begin{bmatrix} \frac{\partial f(\boldsymbol{x})}{\partial x_1} & \cdots & \frac{\partial f(\boldsymbol{x})}{\partial x_n} \end{bmatrix}^T \in \mathbb{R}^n$$

Hessian (for twice differentiable *f*):

$$\nabla^2 f(\boldsymbol{x}) = \left(\frac{\partial^2 f(\boldsymbol{x})}{\partial x_i \partial x_j}\right)_{ij} \in \mathbb{R}^{n \times n}$$

№ Taylor series:

$$f(\boldsymbol{x} + \boldsymbol{\delta}) = f(\boldsymbol{x}) + \nabla f(\boldsymbol{x})^T \boldsymbol{\delta} + \frac{1}{2} \boldsymbol{\delta}^T \nabla^2 f(\boldsymbol{x}) \boldsymbol{\delta} + o\left(\|\boldsymbol{\delta}\|^2\right)$$

First and Second Order Conditions II

• First-order condition: a differentiable *f* with convex domain is convex if and only if

$$f(\boldsymbol{y}) \ge f(\boldsymbol{x}) + \nabla f(\boldsymbol{x})^T (\boldsymbol{y} - \boldsymbol{x}) \quad \forall \boldsymbol{x}, \boldsymbol{y} \in \text{dom } f$$



- Interpretation: first-order approximation is a global under estimator
- Second-order condition: a twice differentiable *f* with convex domain is convex if and only if

$$\nabla^2 f(\boldsymbol{x}) \succeq \boldsymbol{0} \quad \forall \boldsymbol{x} \in \mathrm{dom}\, f$$

Examples

Quadratic function: $f(x) = \frac{1}{2}x^T P x + q^T x + r \text{(with } P \in \mathbb{S}^n \text{)}$

$$\nabla f(\mathbf{x}) = \mathbf{P}\mathbf{x} + \mathbf{q}, \qquad \nabla^2 f(\mathbf{x}) = \mathbf{P}$$

is convex if $P \succ 0$.

Least-squares objective: $f(x) = \|Ax - b\|_2^2$

$$\nabla f(\boldsymbol{x}) = 2\boldsymbol{A}^T(\boldsymbol{A}\boldsymbol{x} - \boldsymbol{b}), \qquad \nabla^2 f(\boldsymbol{x}) = 2\boldsymbol{A}^T\boldsymbol{A}$$

is convex.

Quadratic-over-linear: $f(x,y) = x^2/y$

$$\nabla^2 f(x,y) = \frac{2}{y^3} \begin{bmatrix} y \\ -x \end{bmatrix} \begin{bmatrix} y & -x \end{bmatrix} \succeq \mathbf{0}$$

is convex for y > 0.

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Operations that Preserve Convexity I

How to establish the convexity of a given function?

- Applying the definition
- With first- or second-order conditions
- By restricting to a line
- Showing that the functions can be obtained from simple functions by operations that preserve convexity:
 - nonnegative weighted sum
 - composition with affine function (and other compositions)
 - pointwise maximum and supremum, minimization
 - perspective

Operations that Preserve Convexity II

- Nonnegative weighted sum: if f_1 , f_2 are convex, then $\alpha_1 f_1 + \alpha_2 f_2$ is convex, with $\alpha_1, \alpha_2 \ge 0$.
- **Composition with affine functions:** if f is convex, then f(Ax + b) is convex (e.g., ||y Ax|| is convex, $\log \det(I + HXH^T)$ is concave).
- **Pointwise maximum:** $f := \max\{f_1, \dots, f_m\}$ is convex, if f_1, \dots, f_m are convex

Example: sum of r largest components of $x \in \mathbb{R}^n$:

$$f(\mathbf{x}) = x_{[1]} + x_{[2]} + \dots + x_{[r]}$$

where $x_{[i]}$ is the *i*th largest component of x.

Proof:
$$f(\mathbf{x}) = \max\{x_{i_1} + x_{i_2} + \dots + x_{i_r} | 1 \le i_1 < i_2 < \dots < i_r \le n\}.$$

Operations that Preserve Convexity III

Pointwise supremum: if f(x, y) is convex in x for each $y \in A$, then

$$g(\boldsymbol{x}) = \sup_{\boldsymbol{y} \in \mathcal{A}} f(\boldsymbol{x}, \boldsymbol{y})$$

is convex.

Example: distance to farthest point in a set *C*:

$$f(\boldsymbol{x}) = \sup_{\boldsymbol{y} \in C} \|\boldsymbol{x} - \boldsymbol{y}\|$$

Example: maximum eigenvalue of symmetric matrix: for $X \in \mathbb{S}^n$,

$$\lambda_{\max}(\boldsymbol{X}) = \sup_{\boldsymbol{y} \neq \boldsymbol{0}} \frac{\boldsymbol{y}^T \boldsymbol{X} \boldsymbol{y}}{\boldsymbol{y}^T \boldsymbol{y}}$$

Operations that Preserve Convexity IV

- **Composition with scalar functions:** let $g: \mathbb{R}^n \longrightarrow \mathbb{R}$, $h: \mathbb{R} \longrightarrow \mathbb{R}$, then the function $f(\boldsymbol{x}) = h(g(\boldsymbol{x}))$ satisfies:
 - $f(\boldsymbol{x})$ is convex if $\frac{g}{g}$ convex, h convex nondecreasing g concave, h convex nonincreasing
- Minimization: if f(x, y) is convex in (x, y) and C is a convex set, then

$$g(\boldsymbol{x}) = \inf_{\boldsymbol{y} \in C} f(\boldsymbol{x}, \boldsymbol{y})$$

is convex (e.g., distance to a convex set).

Example: distance to a set *C*:

$$f(\boldsymbol{x}) = \inf_{\boldsymbol{y} \in C} \|\boldsymbol{x} - \boldsymbol{y}\|$$

is convex if *C* is convex.

Operations that Preserve Convexity V

Perspective: if f(x) is convex, then its perspective

$$g(\boldsymbol{x},t)=tf(\boldsymbol{x}/t),\quad \mathrm{dom}\,g=\{(\boldsymbol{x},t)\in\mathbb{R}^{n+1}|\boldsymbol{x}/t\in\mathrm{dom}\,f,t>0\}$$
 is convex.

Example: $f(x) = x^T x$ is convex; hence $g(x, t) = x^T x/t$ is convex for t > 0.

Example: the negative logarithm $f(x) = -\log x$ is convex; hence the relative entropy function $g(x,t) = t \log t - t \log x$ is convex on \mathbb{R}^2_{++} .

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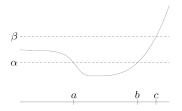
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Quasi-Convexity Functions

A function $f: \mathbb{R}^n \longrightarrow \mathbb{R}$ is quasi-convex if dom f is convex and the sublevel sets

$$S_{\alpha} = \{ \boldsymbol{x} \in \text{dom } f \mid f(\boldsymbol{x}) \le \alpha \}$$

are convex for all α .



 \bullet *f* is quasiconcave if -f is quasiconvex.

Examples

- $\sqrt{|x|}$ is quasiconvex on \mathbb{R}
- $\operatorname{ceil}(x) = \inf\{z \in \mathbb{Z} \mid z \ge x\}$ is quasilinear
- $f(x_1, x_2) = x_1 x_2$ is quasiconcave on \mathbb{R}^2_{++}
- the linear-fractional function

$$f(x) = \frac{a^T x + b}{c^T x + d}, \quad \text{dom } f = \{x \mid c^T x + d > 0\}$$

is quasilinear

Log-Convexity

A positive function f is log-concave is $\log f$ is concave:

$$f(\theta x + (1 - \theta)y) \ge f(x)^{\theta} f(y)^{1-\theta}$$
 for $0 \le \theta \le 1$

- \bullet *f* is log-convex if log *f* is convex.
- Example: x^a on \mathbb{R}_{++} is log-convex for $a \leq 0$ and log-concave for $a \geq 0$
- Example: many common probability densities are log-concave

Convexity w.r.t. Generalized Inequalities

* $f: \mathbb{R}^n \longrightarrow \mathbb{R}^m$ is K-convex if dom f is convex and for any $x, y \in \text{dom } f$ and $0 \le \theta \le 1$,

$$f(\theta x + (1 - \theta)y) \leq_K \theta f(x) + (1 - \theta)f(y)$$

Example: $f: \mathbb{S}^m \longrightarrow \mathbb{S}^m$, $f(X) = X^2$ is \mathbb{S}^m_+ -convex

Reference

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Book:

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