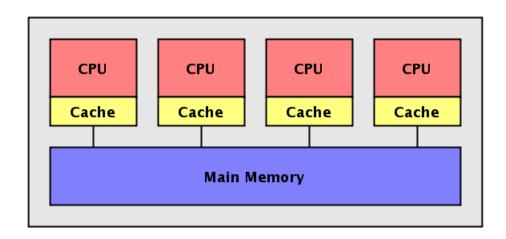
Shared Memory Programming and OpenMP

CS121 Parallel Computing Spring 2018

Shared memory multiprocessor



- Any memory location is accessible by any of the processors.
- A single address space exists.
 - □ Each memory location is given a unique address within a single range of addresses.
- Generally, more convenient than distributed memory programming.
 - But access to shared data needs to be controlled by the programmer, e.g. using critical sections.

Shared memory programming

- Threads (e.g. Pthreads, Java)
 - The programmer decomposes the program into individual sequences of instructions (threads) that can execute in parallel and access shared data.
 - Very general, but hard to use because programmer must manage everything.
- Parallel programming language / library
 - A parallel language or library is used to create code that can be executed on a shared memory parallel architecture.
 - □ Requires new compiler, programmers to learn new language, etc.
- Compiler directives (e.g. OpenMP)
 - □ The programmer inserts compiler directives into a sequential program to specify parallelism and indicate shared data and the compiler translates into threads.
 - □ Still uses threads underneath, but system manages the threads.
 - □ Easy to program (though loses some flexibility). Requires less changes to compiler.
 - Most popular option.

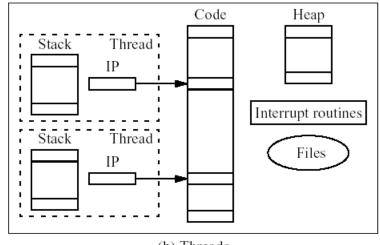


Processes and threads

- Process (e.g. MPI)
 - Separate program with its own variables, memory, stack and instruction pointer.
 - Different programs can't access each other's memory.
 - Stack Interrupt routines

 (a) Process

- Thread (e.g. OpenMP)
 - Concurrent routine that shares the variables and memory space, but has its own stack and instruction pointer.

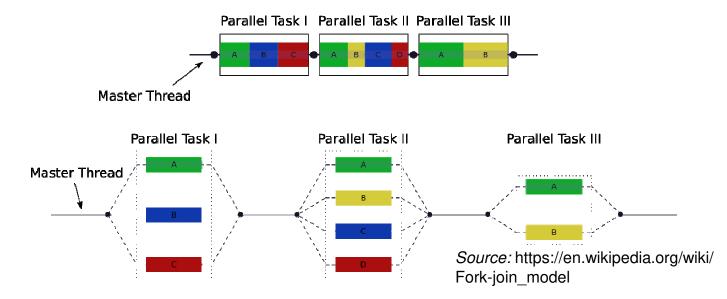


(b) Threads



Fork-join model

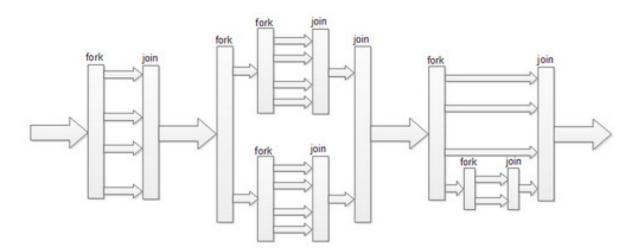
- A model for parallel computing using threads.
- Computation starts with master thread.
- If there is parallel work, master thread forks off slave threads.
 - Thread can be executed on same processor / core or a different one.
- When slave threads finish, they join (merge back into) master thread.





Fork-join model

- Spawned threads may recursively create further threads.
 - □ Slave threads join with the thread that spawned them.
 - Can also create detached threads, that don't do a join when they terminate.



Example

```
mergesort(A, lo, hi):
                                                             38 27 43 3 9 82 10
     if lo < hi:
         mid = \lfloor (hi - lo) / 2 \rfloor
                                                           38 27 43 3
                                                                        9 82 10
          fork mergesort(A, lo, mid)
          mergesort(A, mid, hi)
                                                     38 27
                                                              43 3
                                                                                    10
          join
          merge(A, lo, mid, hi)
                                                             43
                                                38
                                                      27
                                                                   3
                                                                         9
                                                                               82
                                                                                     10
                                                     27 | 38
                                                                                    10
                                                                          9 82
                                                           3 27 38 43
                                                                        9 | 10 | 82
                                                               9 10 27 38 43 82
```

Source: https://en.wikipedia.org/wiki/Merge_sort



Statement execution order

- Single thread Execute statements in program order until blocked or end of time slice.
- Multi-threaded Instructions of different threads are interleaved in arbitrary order.
 - □ Correctness of program can't depend on particular interleaving order, or else race condition bug.
 - Ensuring no race conditions one of the primary challenges to shared memory programming.

Thread 1	Thread 2	Possible interleaving
Instruction 1.1	Instruction 2.1	Instruction 2.1
Instruction 1.2	Instruction 2.2	Instruction 1.1
Instruction 1.3	Instruction 2.3	Instruction 1.2
		Instruction 2.2
		Instruction 2.3
		Instruction 1.3



Race condition example

- Accessing shared data needs careful control because of interleaving of threads.
- Consider two threads which increment a shared counter x.
 - \square In sequential execution, x equals 2 at the end.
 - In parallel execution under given interleaving, x equals 1.

Thread 1

Thread 2

load x compute x+1 store x

```
load x
compute x+1
store x
```

Possible interleaving

```
load x
compute x+1
load x
store x
compute x+1
store x
// x == 1
```



Thread safe routines

- A routine is thread safe if it can be called from multiple threads simultaneously and always produces correct results.
 - □ Standard I/O routines are thread safe.
 - Ex messages are printed without interleaving the characters.
 - Other system routines may not be thread safe, e.g. some random number generators
- Routines that access shared data may require special care to be made thread safe.
- If a routine is not thread safe, it must be executed by only one thread at a time in a "critical section".



Critical sections

- A block of code that can be executed by only one thread at a time.
 - Multiple changes can be made to data without interruption, so that data transitions from safe state to safe state.
 - □ Also called mutual exclusion.
 - Also appears in operating systems and programming languages, e.g. Java's synchronized statement.
- Helps avoid the race condition bugs we saw earlier.

Thread 1	Thread 2	Possible interleaving
load x compute x+1 store x	load x compute x+1 store x	load x compute x+1 store x load x compute x+1 store x // x == 2



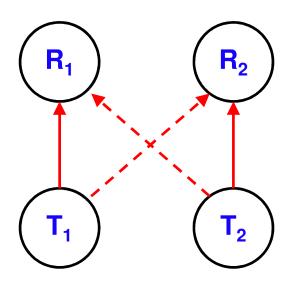
Locks

- A simple mechanism for ensuring mutual exclusion.
- A thread sets a lock before entering the critical section, and unsets it when it leaves.
- If a thread tries to set a lock and finds it locked, it blocks, i.e. waits for the lock to be unset.
 - □ So only the first thread to set the lock can execute the code in the critical section.
 - Other threads wait until the first thread finishes the critical section and unsets the lock, after which one of them can set the lock and perform the critical section.

```
set_lock(mutex);
critical section
...
unset_lock(mutex);
```

Deadlock

- A system state when all threads are stuck, i.e. can't take another step.
- Can occur when a thread T₁ waits for a resource held by T₂, while T₂ waits for a resource held by T₁.
- Can also have a waiting cycle of many threads.
- Can avoid deadlock by having all threads lock resources in same order.







Non-blocking locking

Attempt to lock without blocking.

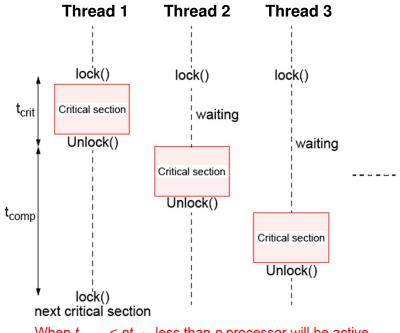
```
flag = test_lock(mutex);
if (!flag) {
    critical section
    unset_lock(mutex);
} else ...
```

- If lock currently unset, it will set it and return success.
- If lock currently set, it will return failure without blocking.
- Can avoid deadlock.
 - □ Threads can use test_lock to access resource.
- Can avoid waiting time associated with blocking.
 - ☐ Thread can do other work and test_lock again later.



Critical sections and performance

- Critical sections lead to serialization of code.
 - If multiple threads want access to a critical section and reach it at the same time, the threads must be executed sequentially.
 - Then the execution time becomes almost that of a single processor.
- For performance, avoid critical sections when possible, and minimize their size.



When $t_{comp} < pt_{crit}$, less than p processor will be active

Condition variables

- Often, a critical section needs to be executed only when a specific condition is met.
- Can use a condition variable.
 - □ Thread gets the lock for a critical section, then calls the condition variable to wait for condition to become true.
 - □ Waiting thread goes to sleep and releases lock, atomically.
 - ☐ If there are several waiters, they get put in a queue.
 - □ On a signal_all, one of the waking threads reacquires lock.
- More efficient than continually testing a lock to see when condition met.
- wait(cond, lock)
 - □ Atomically release lock and go to sleep. Upon waking, try to reacquire lock.
- signal(cond)
 - □ Wake up one sleeping thread waiting on cond.
- signal_all(cond)
 - □ Wake up all sleeping threads waiting on cond.

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Producer-consumer example

- Producer threads add items to a queue, consumer threads remove them.
 - ☐ If queue empty, consumers wait. If queue full, producers wait.
- Instead of continuously locking the queue and checking if it's full / empty, go to sleep until signaled.
- Accesses to queue still need to be protected using lock.
- Producers and consumers signal each other using condition variables not_full, not_empty.
- Use while loop around wait because there may be multiple producers, consumers.
 - □ E.g. producer's signal_all can wake several consumers, one of which consumes the queue item. So the other consumers should check again whether items == 0.

```
Producer() {
                                         Consumer() {
   set(lock)
                                            set(lock)
   while (items == N)
                                            while (items == 0)
      wait(not full, lock);
                                               wait(not empty, lock);
   /* access shared resource */
                                            /* access shared resource */
   items++;
                                            items--;
                                            signal all(not full);
   signal all(not empty);
   release(lock);
                                            release(lock);
```



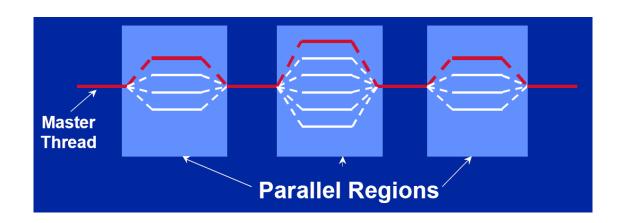
OpenMP

- OpenMP is a standard adopted by many hardware vendors and can be used with different languages, e.g. C, C++ and Fortran.
- Compiler directives are used to specify parallelism and to indicate shared data.
- An OpenMP compatible compiler produces parallel program using the directives. A noncompatible compiler produces correct sequential program using same code.
 - □ Several OpenMP compilers available, e.g. Intel C compiler.
- Can be used to add parallelism incrementally to a sequential program, e.g. by parallelizing for loops.
- Underneath, OpenMP still uses threads.
 - OpenMP gives a more convenient, succinct way to manage threads.
 - □ But it lacks some of the expressiveness of explicit threading.



OpenMP

- OpenMP is based on threads, and uses the "forkjoin" model.
 - □ Initially, a single master thread exists.
 - Parallel regions (sections of code) can be executed by a team of threads.
 - Compiler takes care of creating and coordinating threads.
- Available for C / C++ and Fortran. Documentation at http://openmp.org/wp/openmp-specifications/



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Parallel regions

■ The parallel directive forks a team of threads, each of which executes the following region, enclosed in {...}.

```
#pragma omp parallel
structured-block // { ... code ... }
```

- Threads do a join at end of parallel region, and execution resumes with the single master thread.
- Number of threads can be set by
 - □ num_threads clause after the parallel directive.
 - omp_set_num_threads() library routine previously called.
 - ☐ Environment variable OMP NUM THREADS.
 - □ Recommendation is one thread per processor / core.
- Threads can do the work in the region in parallel.
 - □ Can do different things based on thread ID.
 - □ Can share work using for, sections, task, etc. directives.
- Parallel regions can be nested.

NA.

Parallel regions

Example

```
#pragma omp parallel private(iam, np)
    np = omp get num threads();
    iam = omp_get_thread_num();
    printf("Hello from thread %d out of %d\n",
            iam, np);
All threads in parallel region run this code.
  iam and np are private variables (i.e. instance of
   variable for each thread).
   omp get num threads() returns the number of
   threads n in the team used for the parallel region.
  omp_get_thread_num() returns thread number
   (identity) in range 0 to n-1 with master thread 0.

□ Messages printed in arbitrary order.
```

Work sharing

- Share some work inside a parallel region among threads.
- For example, for construct inside a parallel region partitions iterations of the loop among the threads.

- □ The way in which iterations are assigned to threads can be specified by an additional schedule clause.
- For this and other worksharing constructs:
 - Does not start a new team of threads that is done by an enclosing parallel construct.
 - □ Implicit barrier at the end of the construct unless a nowait clause is included. I.e. each thread will wait at end of construct for all other threads to finish.

Schedule clause

- Used for assigning iterations of parallel for to threads.
- schedule(static[,chunk])
 - □ Each thread gets a chunk of iterations of size "chunk" by default chunks approximately equal.
 - □ Chunks assigned in round robin order.
- schedule(dynamic[,chunk])
 - □ Each time a thread finishes its iterations, grabs "chunks" more iterations, until all have been executed – default is 1.
 - Dynamic scheduling has some overhead, but can result in better load balancing if iterations not all equal sized.
- schedule(guided[,chunk])
 - □ Each thread dynamically grabs iterations where the size starts large and shrinks down to "chunk".
 - Dynamic load balancing with less overhead.
- schedule(runtime)
 - Schedule type and chunk size taken from the OMP_SCHEDULE environment variable.

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Combined parallel for

If a parallel directive is followed by a single for directive, they can be combined.

```
#pragma omp parallel for schedule(static)
for (i=0; i<n; i++) { a[i] = a[i] + b[i];}</pre>
```

- Several restrictions on structure of for loop.
 - □ Number of iterations n must not change.
 - □ Loop increment must be fixed.
 - □ Must not exit loop prematurely (with break, goto, throw).
 - Purpose of restrictions is so amount of work in loop can be determined at start.

Different ways to parallelize for

```
// sequential
for (i=0; i<N; i++) {
    a[i] = a[i] + b[i];
}</pre>
```

```
// create parallel region
// then do worksharing

#pragma omp parallel {
    #pragma omp for
    for (i = 0; i < N; i++) {
        a[i] = a[i] + b[i];
    }
}</pre>
```

```
// create parallel region and do
//worksharing together

#pragma omp parallel for schedule(static)
   for (i = 0; i < N; i++) {
       a[i] = a[i] + b[i];
   }</pre>
```

```
// manual parallelization

#pragma omp parallel {
    int id, i, Nthreads, start, end;
    id = omp_get_thread_num();
    Nthreads = omp_get_num_threads();
    start = id * N / Nthreads;
    end = (id + 1) * N / Nthreads;
    for (i = start; i < end; i++) {
        a[i] = a[i] + b[i];
    }
}</pre>
```

```
// threads do redundant work

#pragma omp parallel {
    for (i = 0; i < N; i++) {
        a[i] = a[i] + b[i];
    }
}</pre>
```

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Other work sharing constructs

- Sections construct
 - Each thread assigned some sections of work.
 - ☐ Threads can be assigned 0, or multiple sections of work.
 - □ There's an implicit barrier at end of sections block, i.e. threads wait for each other to finish all sections before executing code after section.
 - ☐ Can turn off barrier using nowait.



Other work sharing constructs

- Single construct
 - Structured block is executed by one thread of parallel region only (not necessarily master thread).
 - □ Barrier implied unless use nowait.
 - □ For doing tasks that should only be done by one thread when inside a parallel region.
- Master construct
 - Structured block is executed by master thread only. No implicit barrier at end.

```
#pragma omp parallel {
    #pragma omp single {
    // do stuff
    }
}
```

```
#pragma omp parallel {
    #pragma omp master {
    // do stuff
    }
}
```

Data environment

- OpenMP has a shared memory programming model.
 - □ Some variables are shared and accessible by all threads.
 - Other threads are private, and each thread has its own copy.
- Most variables are shared by default.
 - Global and static variables are shared.
 - □ Variables declared in master thread shared by default.
- Some variables parallel blocks private by default.
 - □ Loop index of for / parallel for construct.
 - Stack variables (e.g. function argument or local variable)
 created during execution of a parallel region.
 - □ Automatic variables in functions called in parallel region.



Data environment

 Variable status can be changed in parallel regions and worksharing constructs, except shared which only applies to parallel regions.

```
□ shared(variable-list)
□ private(variable-list)
```

 Can also add default(private) or default(shared) clause to make shared variables private or shared by default.

```
1 int x = 5;
2 #pragma omp parallel private(x) {
3   int p = omp_get_thread_num();
4   x = p;
5   printf("private x is %d\n",x);
6 }
7 printf("shared x is %d\n",x);
```

- ☐ At line 1, x is shared.
- At line 3, each thread has a private copy of x, but x's value is uninitialized.
- At line 5, every thread prints a different x.
- □ At line 7, master thread prints x is 5.

Data environment

- When entering parallel region, set the initial values of private variables to be its value outside region using firstprivate(variable-list)
- When exiting parallel for, set the values of private variables outside the region to be their values in the final iteration of the for loop using lastprivate(variable-list)

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Data environment

- Reduction combines values from threads.
 - □ reduction(op : variable-list)
 - Variables in the list must be shared in the enclosing parallel region.
 - Each thread initially makes a local copy of each list variable and updates it.
 - Local copies are reduced into a single global copy at the end of the construct.
 - More efficient than using a critical section.

```
#pragma omp parallel for reduction (+ : x)
for (i=0; i<n; i++) {
   x = x + a[i]; }</pre>
```

```
#pragma omp parallel for
for (i=0; i<n; i++) {
    #pragma omp critical
    {x = x + a[i];}}</pre>
```

Synchronization constructs

- OpenMP has critical sections and locks to protect accesses.
- Critical sections

```
#pragma omp critical [name] structured-block
```

- □ Only one thread can execute associated structured block at a time.
- Name can be used to identify the critical section. Critical sections with no name default to the same.

Locks

```
omp_init_lock(arg), omp_set_lock(arg), omp_unset_lock(arg),
omp_test_lock(arg), omp_destroy_lock(arg)
```

- □ arg is a memory location.
- Critical sections protect sections of code, but locks protect data.
- □ Ex Consider a hash function insert routine.
 - A critical section around the routine allows one thread to insert at a time, even when different threads want to insert to different locations.
 - We only want to prevent concurrent inserts to same table entry. So associate one lock with each table entry.

Barriers

```
#pragma omp barrier
```

All threads must reach the barrier before any can proceed.

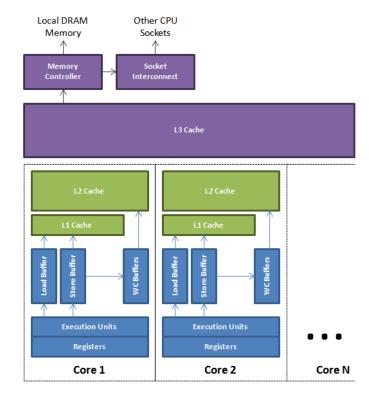


Synchronization constructs

- Atomic operations #pragma omp atomic expression-statement
 - Only one thread can execute the associated expressionstatement at a time.
 - \square Only works for simple statements such as x++, max, test&set, etc.
 - □ More efficient than critical section, done in hardware.

Flushing values

- □ #pragma omp flush [(var)]
- Writes listed variables from buffer to cache or memory to ensure all processors observe latest variable values.





Synchronization constructs

- Ordered statements are used in for and parallel for constructs to cause the subsequent structured block to be executed in strict loop order.
 - Code outside the ordered block can still execute in parallel.
- Can only have one ordered statement in each parallel for construct.

```
#pragma omp parallel for ordered schedule(static, 1)
for (i = 0; i < n; i += 2)
    // do stuff in interleaved order
    // s, t are increased / decreased in order 0, 2, ...
    #pragma omp ordered {
        s += i;
        t -= i;
    }
}</pre>
```



Runtime execution

Runtime environment routines

```
□ Number of threads
omp set num threads(), omp get num threads(),
omp_get_thread_num()
■ Number of processors
omp_num_procs(),
Currently in active region?
omp in parallel()
□ Allows number of threads in parallel regions
 to be adjusted dynamically
omp set dynamic(int), omp_get_dynamic()
```

OpenMP example

Mandelbrot Set

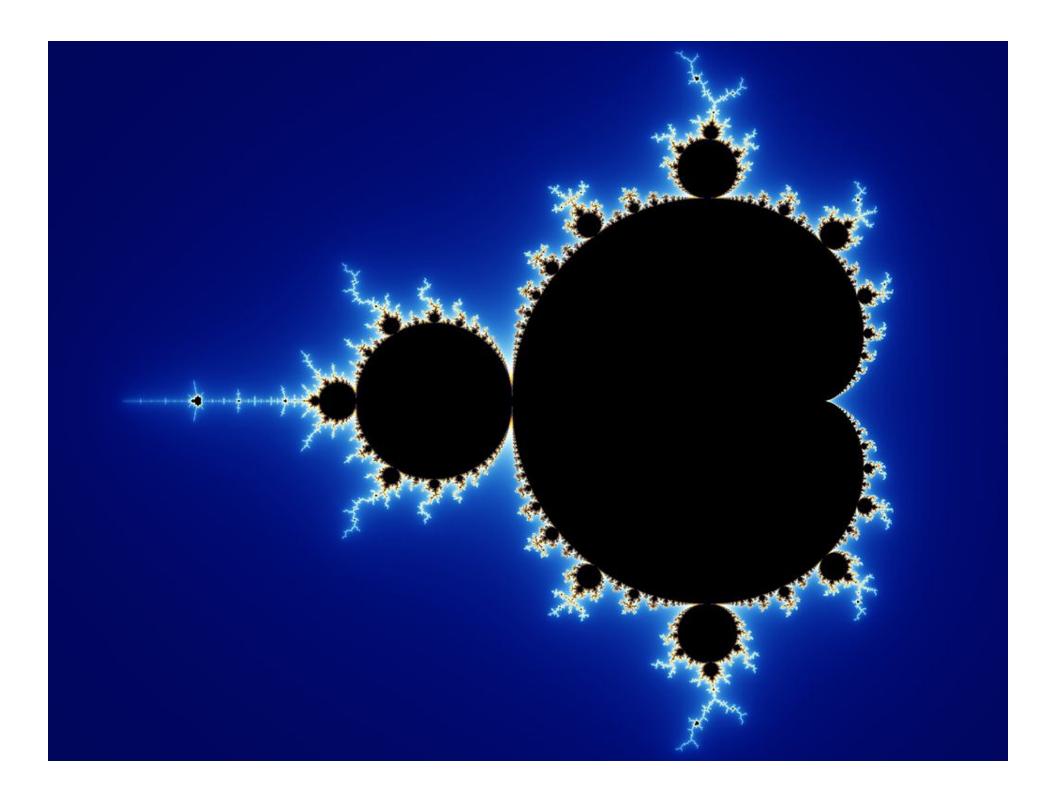
Set of points in a complex plane that are quasi-stable (will increase and decrease, but not exceed some limit) when computed by iterating the function

$$z_{k+1} = z_k^2 + c$$

where z_{k+1} is the (k + 1)th iteration of the complex number z = a + bi and c is a complex number giving position of point in the complex plane. The initial value for z is zero.

Iterations continued until magnitude of z is greater than 2 or number of iterations reaches arbitrary limit. Magnitude of z is the length of the vector given by

$$z_{\text{length}} = \sqrt{a^2 + b^2}$$



Sequential routine

```
Z_{k+1} = Z_k^2 + C
```

```
z^2 = (a + bi)^*(a + bi)
structure complex {
    float real;
                                                         = a^2 - b^2 + 2abi
    float imag;
};
                                                      count gives colour
                                                      (or intensity) to be
int calpixel(complex c) {
                                                      displayed
    int count, max;
    complex z;
                                                      It's known z will
    float temp, lengthsq;
                                                      diverge if |z| \ge 2.
    max = 256;
    z.real = 0; z.imag = 0;
    count = 0; /* number of iterations */
    do {
        temp = z.real * z.real - z.imag * z.imag + c.real;
        z.imag = 2 * z.real * z.imag + c.imag;
        z.real = temp;
        lengthsq = z.real * z.real + z.imag * z.imag;
        count++;
    } while ((lengthsq < 4.0) && (count < max));</pre>
    return count;
```

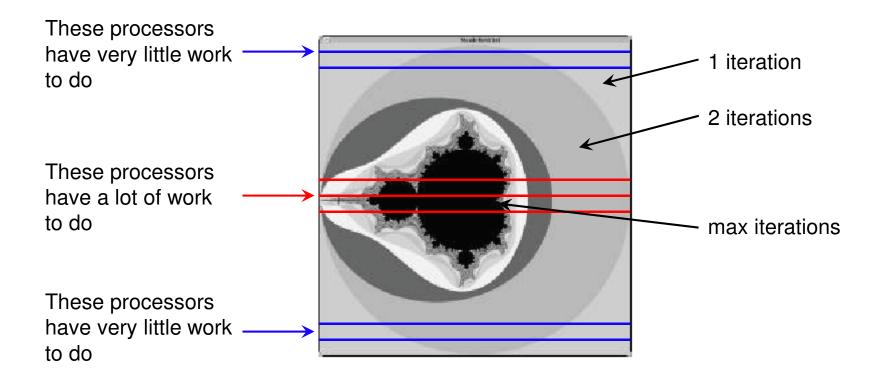


Parallelization of Mandelbrot

- Calculations for each pixel are independent.
 - Sometimes called an embarrassingly parallel computation.
- Static assignment
 - □ Divide the image into groups of pixels by row and assign each group to a separate thread.
 - □ By default, group (chunk) size is approximately equal.

□ Not efficient as different pixels require different numbers of iterations and the computation time of different strips will vary considerably.

Static schedule



This is a load balancing problem. Processors for top and bottom rows mostly idle, while processors for middle rows have lots of computation.

NA.

Parallelization of Mandelbrot

Cyclic assignment

```
#pragma omp parallel for private(j) schedule (static, 1)
for (i = 0; i < n; i++)
    for (j = 0; j < n; j++)
        colour[i][j] = calpixel(i,j);</pre>
```

- Iterations are assigned in a round robin manner.
 Each thread receives a mixed set of tasks, some
- Each thread receives a mixed set of tasks, some with a lot, some with little computation.
- Dynamic assignment

```
#pragma omp parallel for private(j) schedule (dynamic, 1)
for (i = 0; i < n; i++)
    for (j = 0; j < n; j++)
        colour[i][j] = calpixel(i,j);</pre>
```

□ When a thread has finished the current row, it receives a new row to compute (could use guided).