

# Tutorial 6

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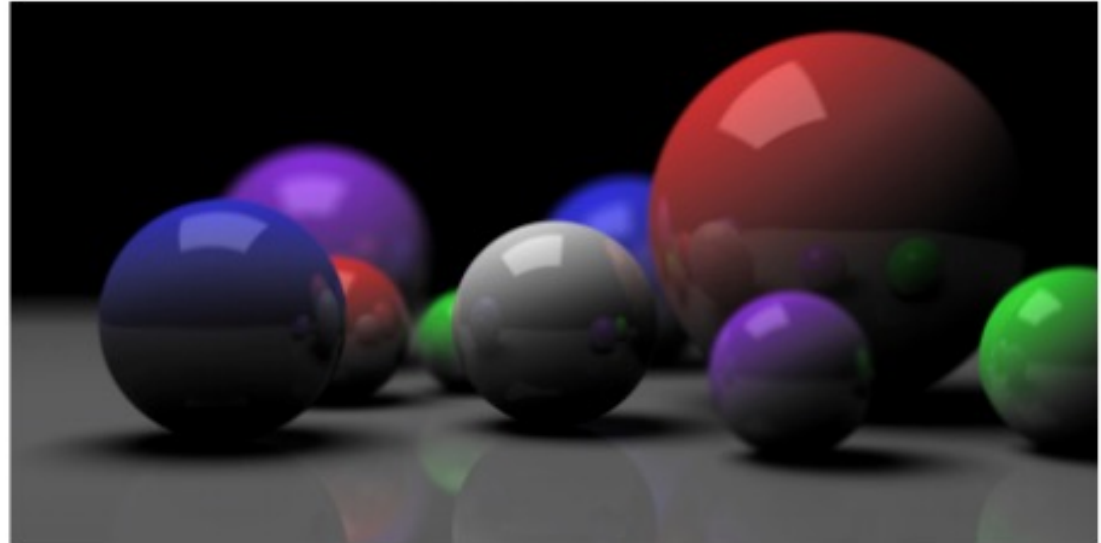
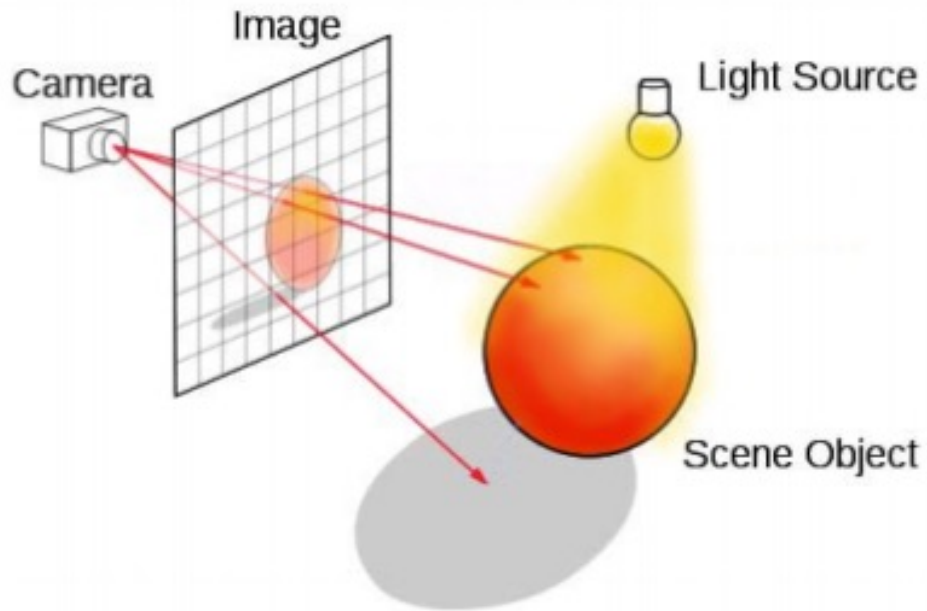
# Agenda

- Ray Tracing
- Direct Lighting
- Radiance
- Assignment 3

# Ray Tracing

# Ray Tracing

- Simulation of the realistic imaging process.
- Recall the imaging process for pin-hole cameras.

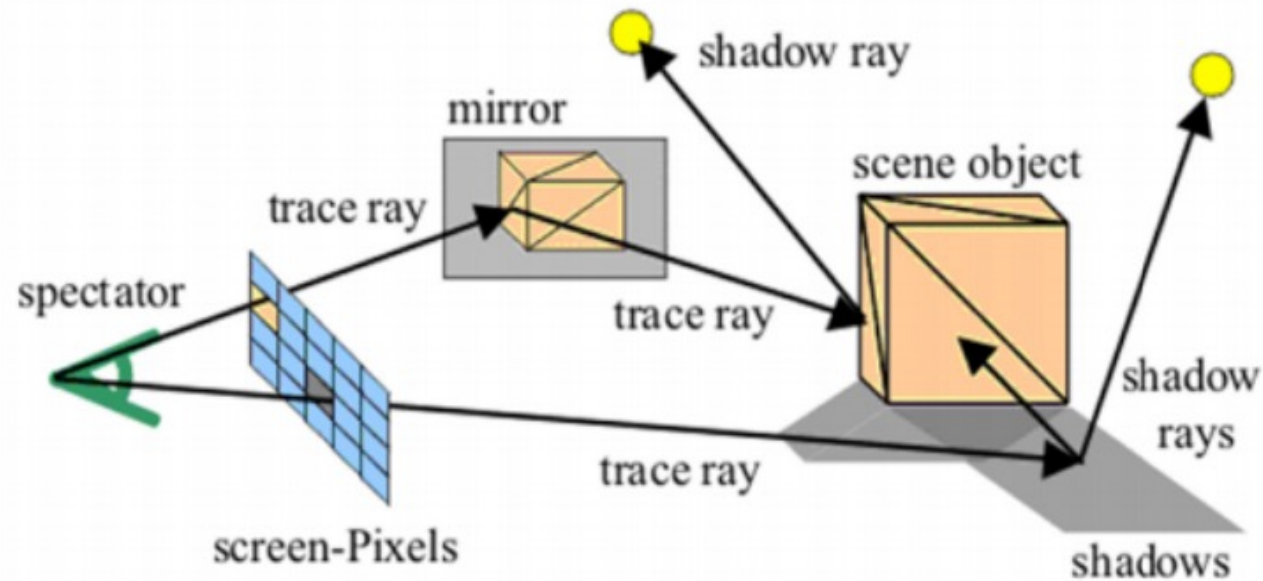


# Ray Tracing

- Differing from projection-based rendering, e.g., OpenGL, we cast rays into the scene to evaluate the radiance brought back by ray tracing.
- Ray tracing routine
  - In general, starts from the camera's pin-hole and directs to a point on the imaging plane.
  - When the ray intersects with some objects, perform reflections on the interaction point.
  - Repeat until the ray hits any light sources.
  - Traceback and compute the radiance brought back.

# Ray Tracing

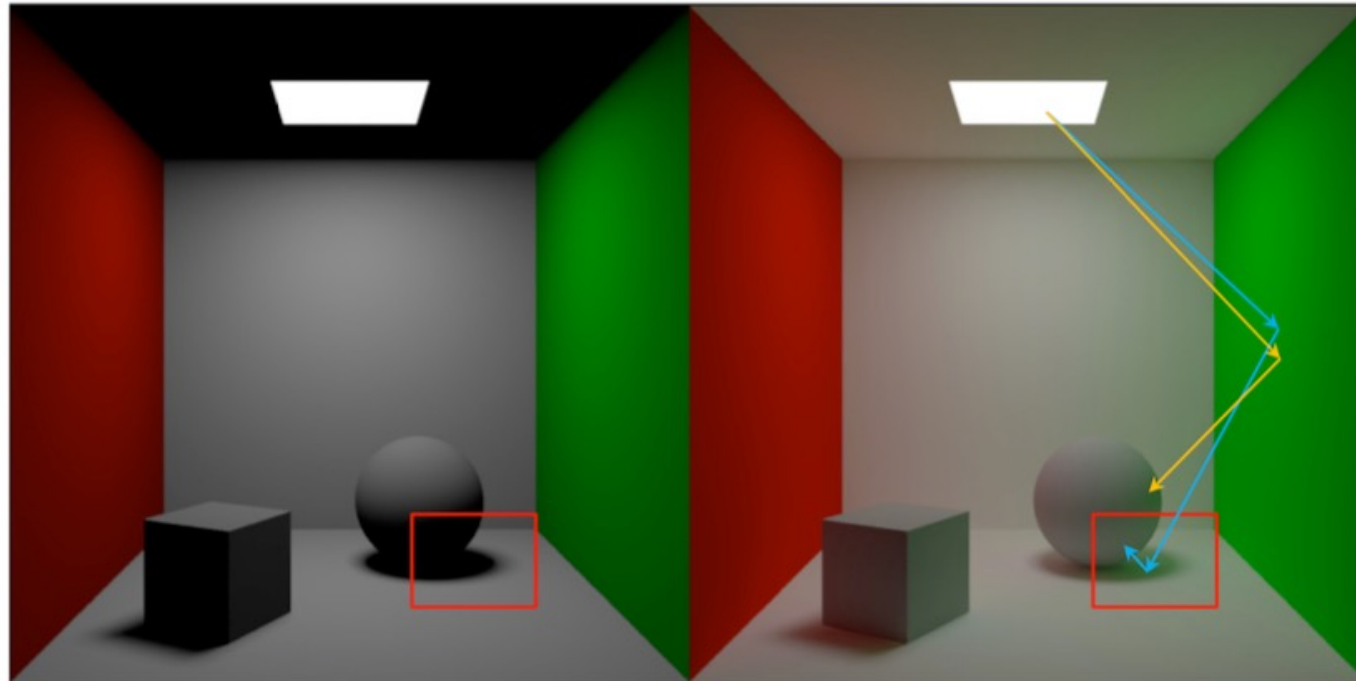
- For simplification, we consider merely two kinds of reflection
  - Specular reflection (e.g., mirror, icy surface)
  - Diffusion reflection (e.g., rough wall)



Direct Lighting

# Direct Lighting

- This routine is somewhat problematic and inefficient since the ray could be reflected thousands of times until meeting any light source.
- A practical method is to decompose the lighting into **direct** and **indirect**.

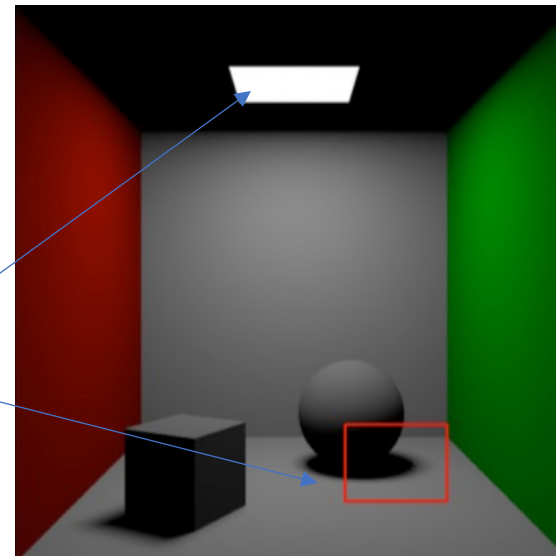




# Direct Lighting

- Direct lighting: once the shot rays hit any object, we directly reflect rays to the light sources.
- Shadow: But those rays may hit other objects when they are reflected to the light sources (sheltering/occlusion)
  - Which will result in the shadow
- If the light sources are area lights, some shadow has chances to be lighted
  - Which will result in the soft shadow.

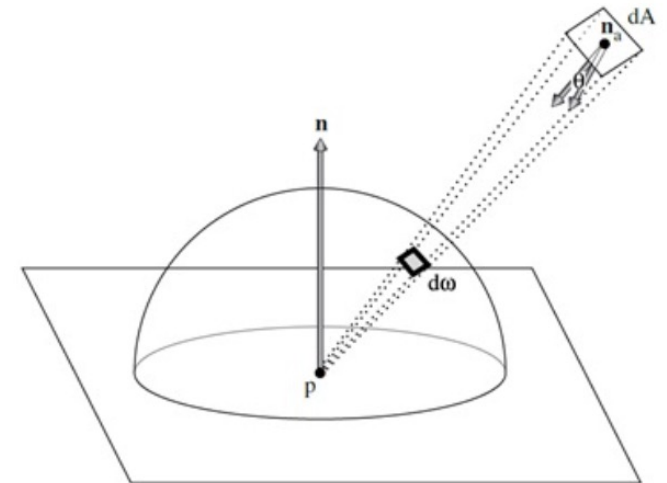
Area light, soft shadow, but direct illumination



# Direct Lighting

- Rendering equation:
  - $L_o(p, \omega_o) = \int_s f(p, \omega_i, \omega_o) L_i \cos \theta_i d\omega_i$
  - For discrete case, integral can be converted to summation
  - For Phong shading model, BRDF is modeled as diffusion + specular
- Discrete + Phong Shading (diffusion)
  - $L_o(p, \omega_o) = \sum_{L_i} diff \cdot L_i \cos \theta_i$

$$L_o(p, \omega_o) = \int_A f(p, \omega_o, \omega_i) L_i(p, \omega_i) |\cos \theta_i| \frac{dA \cos \theta}{r^2}$$



Radiance

# Radiance

- Notice that what we consider now is radiance for each pixel on the imaging film. Not RGB color yet.
- Color represents waves with different wavelengths, similar to radiance. In computer area, lights are decomposed to 3 components: Red, Green, Blue.
- For simplification in Phong lighting model, we can decompose radiance to RGB components and compute the radiance for the three channels, respectively.
- Finally, convert radiance to color via tone mapping (Gamma correction).

# Assignment 3

# Assignment 3: Ray Tracing with Direct Lighting

- **[must]** You are required to implement a pin-hole camera, which is able to shoot rays. And there should be at least one ray per pixel.
- **[must]** You are required to implement algorithms for the ray-triangle intersection (without the acceleration structure).
- **[must]** You are required to implement anti-aliasing for ray-tracing by using super sampling with the rotated grid.
- **[optional]** You may implement texturing.
- **[optional]** You may implement a mipmap for texturing in ray tracing.
- **[optional]** You may implement normal mapping.
- **[optional]** You may implement environment lighting with importance sampling.

# Code Structure

## ✓ include

C camera.h

- Data structure and methods for manipulating cameras.

C core.h

- Header files and declarations

C film.h

- Data structure storing each pixel's radiance.

C geometry.h

- Represents 3D geometries in the scene

C integrator.h

- Used to solve the rendering equation

C interaction.h

- Basic data structures for ray-object intersection

C light.h

- Represents light sources in the scene

C material.h

- Material information for geometries like Phong model

C ray.h

- Basic data structures for ray-object intersection

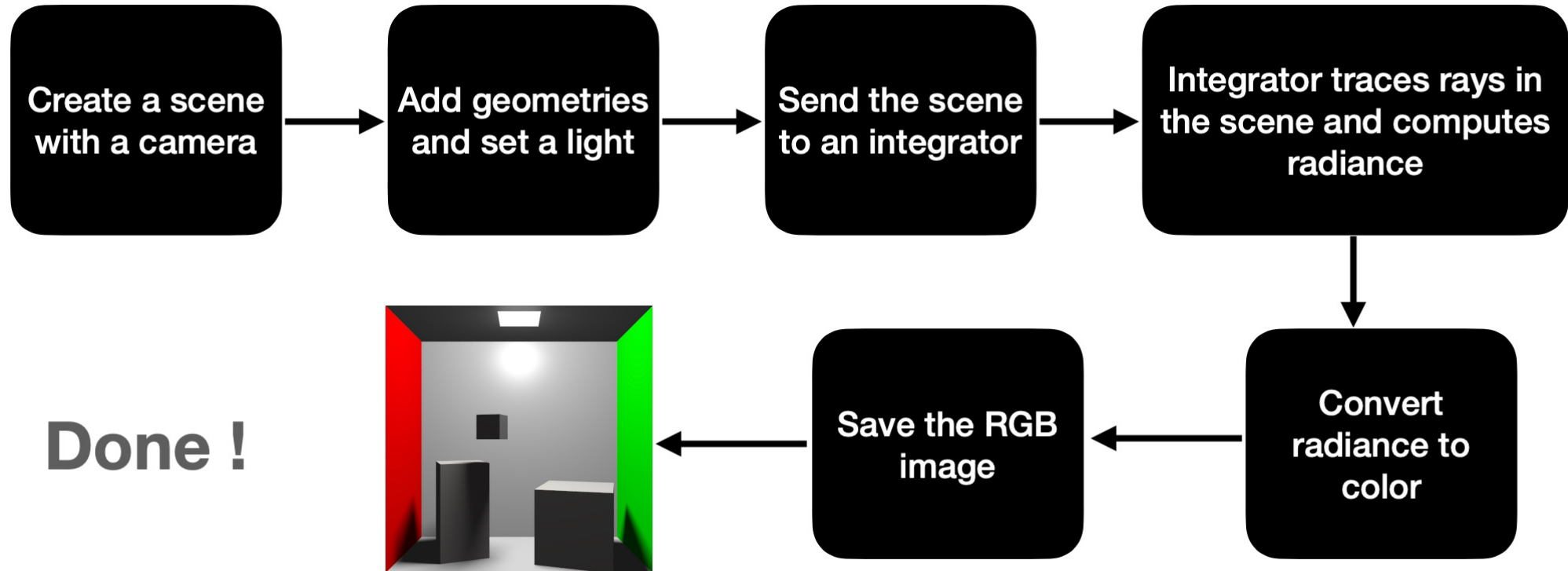
C scene.h

- Contains geometries and lights, with a camera attached

C texture.h

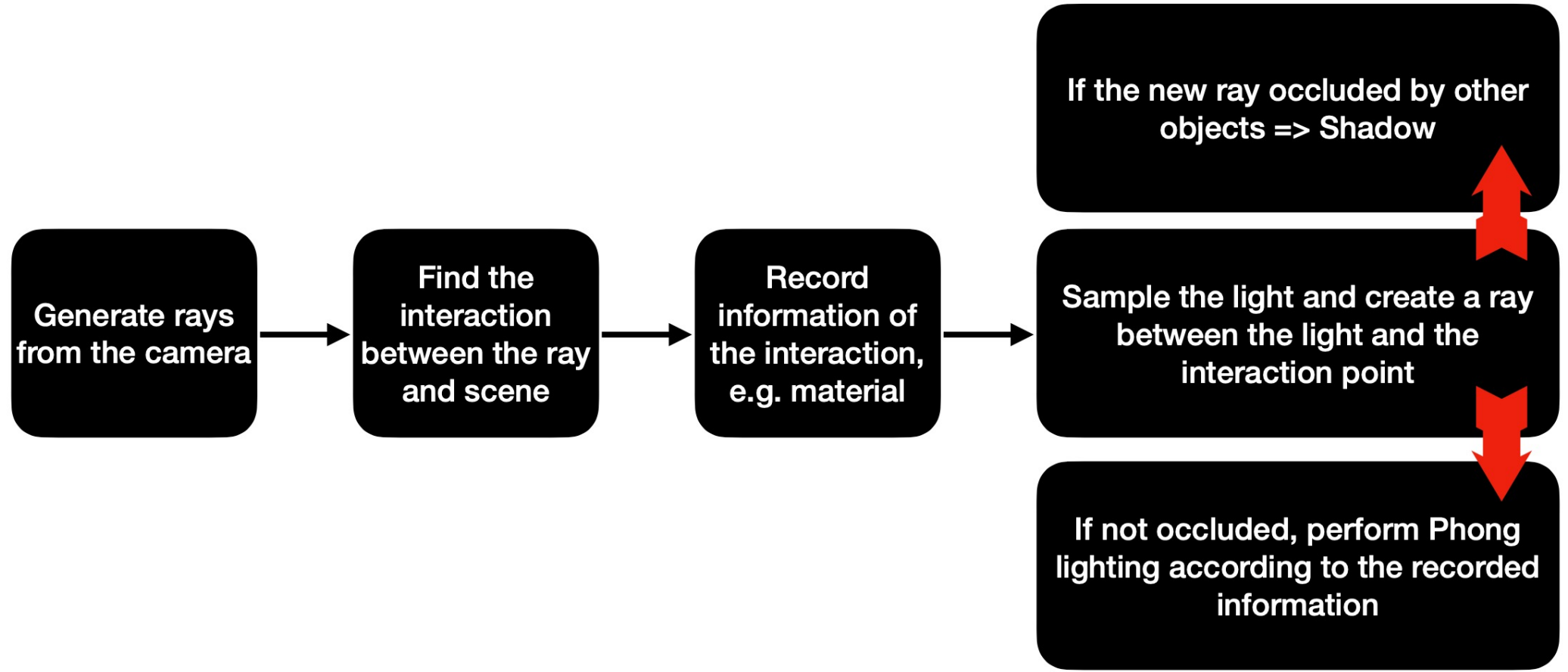
- Texture information for geometries

# Working Flow



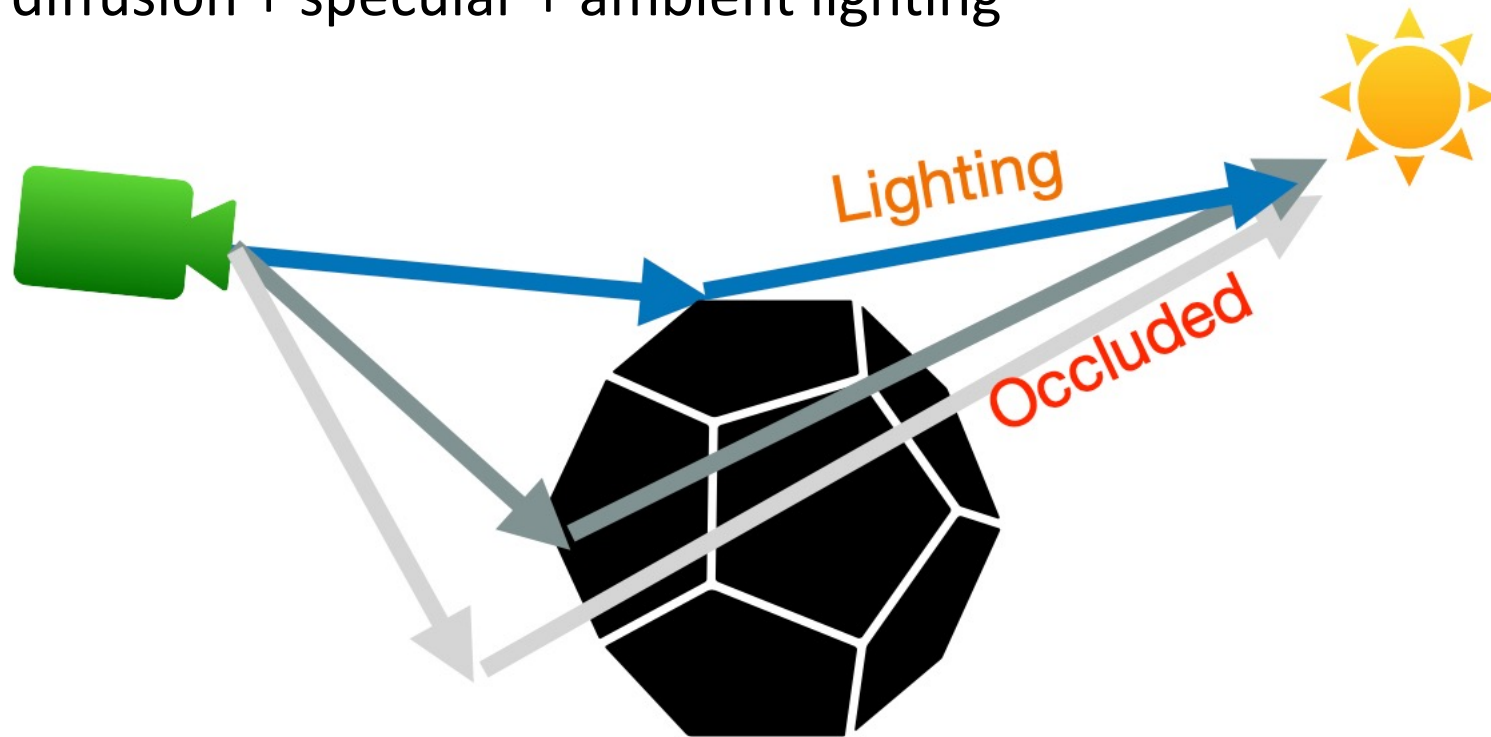


# Working Flow in the Integrator



# Algorithm for Direct Phong Lighting

- Create a new ray from P to a light
  - If intersects(scene, camera ray) at P source
  - If intersects(scene, new ray)
    - Return ambient lighting
  - Return diffusion + specular + ambient lighting



# Ray-Triangle intersection

- Define
  - The point in the triangle plane as  $p_1 = (1 - b_1 - b_2)p_0 + b_1p_1 + b_2p_2$
  - The point in the ray as  $p_2 = O + t\mathbf{d}$
- We have the relationship  $p_1 = p_2$

$$(-\mathbf{d} \quad \mathbf{e}_1 \quad \mathbf{e}_2) \begin{bmatrix} t \\ b_1 \\ b_2 \end{bmatrix} = s$$

- Solve the linear equations using **Cramer's Rule**

$$\begin{bmatrix} t \\ b_1 \\ b_2 \end{bmatrix} = \frac{1}{|-\mathbf{d} \quad \mathbf{e}_1 \quad \mathbf{e}_2|} \begin{bmatrix} | \quad s \quad \mathbf{e}_1 \quad \mathbf{e}_2 | \\ | -\mathbf{d} \quad s \quad \mathbf{e}_2 | \\ | -\mathbf{d} \quad \mathbf{e}_1 \quad s | \end{bmatrix}$$

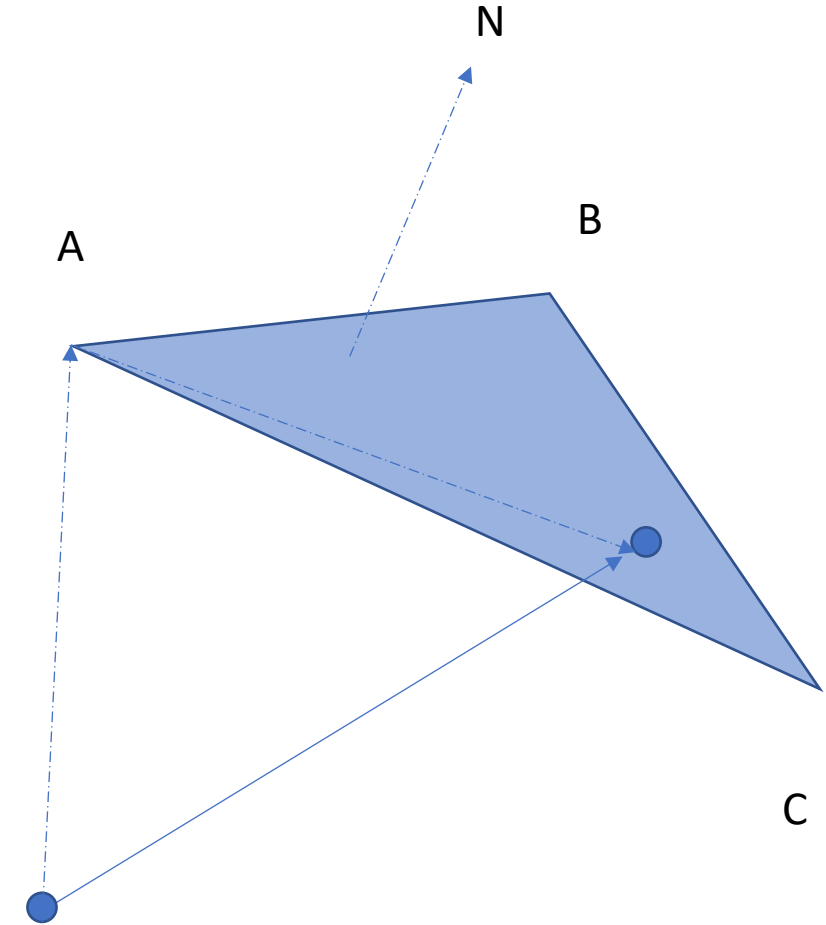
# Ray-Triangle intersection

- **Is this solver efficient?**
  - No!
- **More observation**
  - Determinant identification in 3D

$$| \mathbf{a} \quad \mathbf{b} \quad \mathbf{c} | = -(\mathbf{a} \times \mathbf{c}) \cdot \mathbf{b} = -(\mathbf{c} \times \mathbf{b}) \cdot \mathbf{a}$$



$$\begin{bmatrix} t \\ b_1 \\ b_2 \end{bmatrix} = \frac{1}{(\mathbf{d} \times \mathbf{e}_2) \cdot \mathbf{e}_1} \begin{bmatrix} (\mathbf{s} \times \mathbf{e}_1) \cdot \mathbf{e}_2 \\ (\mathbf{d} \times \mathbf{e}_2) \cdot \mathbf{s} \\ (\mathbf{s} \times \mathbf{e}_1) \cdot \mathbf{d} \end{bmatrix} \quad \rightarrow \quad \begin{bmatrix} t \\ b_1 \\ b_2 \end{bmatrix} = \frac{1}{\mathbf{s}_1 \cdot \mathbf{e}_1} \begin{bmatrix} \mathbf{s}_2 \cdot \mathbf{e}_2 \\ \mathbf{s}_1 \cdot \mathbf{s} \\ \mathbf{s}_2 \cdot \mathbf{d} \end{bmatrix}$$



Thanks