

Outline

Introduction

Univariate Data

- Maximum Likelihood Estimation

- Bayesian Estimation

- Parametric Classification

- Regression

- Model Selection

Multivariate Data

- Parameter Estimation

- Multivariate Normal Distribution

- Parametric Classification

- Discrete Features

- Regression

Multivariate Data

Multivariate Parameters - I

- Mean vector:

$$\mathbb{E}[\mathbf{x}] = \boldsymbol{\mu} = (\mu_1, \dots, \mu_d)^T$$

- Covariance of x_i and x_j :

$$\sigma_{ij} = \text{Cov}(x_i, x_j) = \mathbb{E}[(x_i - \mu_i)(x_j - \mu_j)] = \mathbb{E}[x_i x_j] - \mu_i \mu_j$$

Typically the features are correlated, or else there will not be a need for multivariate analysis.

- The x_i and x_j are called **uncorrelated** if $\sigma_{ij} = \mathbb{E}[x_i x_j] - \mu_i \mu_j = 0$.
- The covariance between two random variables measures the degree to which they are (linearly) related.
- Variance of x_i :

$$\sigma_i^2 = \mathbb{E}[(x_i - \mu_i)^2]$$

- Note that:

$$\sigma_{ij} = \sigma_{ji} \quad \sigma_{ii} = \sigma_i^2$$

Multivariate Parameters - II

- Covariance matrix:

$$\mathbf{\Sigma} \equiv \text{Cov}(\mathbf{x}) = \mathbb{E}[(\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^T] = \mathbb{E}[\mathbf{x}\mathbf{x}^T] - \boldsymbol{\mu}\boldsymbol{\mu}^T = \begin{bmatrix} \sigma_1^2 & \sigma_{12} & \cdots & \sigma_{1d} \\ \sigma_{21} & \sigma_2^2 & \cdots & \sigma_{2d} \\ \vdots & & & \vdots \\ \sigma_{d1} & \sigma_{d2} & \cdots & \sigma_d^2 \end{bmatrix}$$

- Correlation between x_i and x_j :

$$\rho_{ij} \equiv \text{Corr}(x_i, x_j) = \frac{\sigma_{ij}}{\sigma_i \sigma_j}$$

The correlation (a.k.a. **Pearson correlation coefficient**) between x_i and x_j is in $[-1, +1]$, making it easier to interpret than the covariance.

- $\rho_{ij} \neq 0$: two variables x_i and x_j are **related** in a linear way

- Dependence vs. correlation:

$$x_i \text{ and } x_j \text{ are independent} \begin{matrix} \Rightarrow \\ \nLeftarrow \end{matrix} \sigma_{ij} = \rho_{ij} = 0$$

Parameter Estimation

- ▶ Sample mean:

$$\mathbf{m} = \frac{1}{N} \sum_{t=1}^N \mathbf{x}^t$$

- ▶ Sample covariance matrix:

$$\mathbf{S} = [s_{ij}]_{i,j=1}^d = \frac{1}{N} \sum_{t=1}^N (\mathbf{x}^t - \mathbf{m})(\mathbf{x}^t - \mathbf{m})^T$$

where $s_{ii} = s_i^2$

- ▶ Sample correlation matrix:

$$\mathbf{R} = [r_{ij}]_{i,j=1}^d \quad \text{where} \quad r_{ij} = \frac{s_{ij}}{s_i s_j}$$

Estimation of Missing Values

- ▶ What to do if the values of certain variables in some instances are missing?
- ▶ Discarding the instances: not a good idea if the sample is small and since the non-missing entries do contain information.
- ▶ **Imputation**: filling in the missing entries
 - **Mean imputation**: using the most likely value (e.g., mean or mode)
 - **Imputation by regression**: predicting the missing values based on the regression approach
 - **Matrix factorization**: using low-rank matrices as factors for matrix completion.

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Multivariate Data

Parameter Estimation

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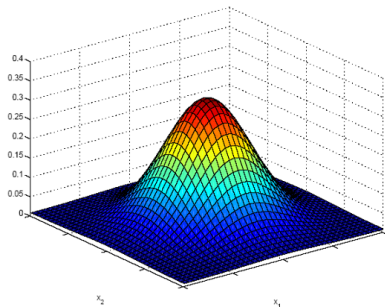
Parametric Classification

Discrete Features

Regression

Multivariate Data

Multivariate Normal Distribution - I



$$\mathbf{x} \sim \mathcal{N}_d(\boldsymbol{\mu}, \boldsymbol{\Sigma})$$

$$p(\mathbf{x} \mid \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{d/2} |\boldsymbol{\Sigma}|^{1/2}} \exp\left[-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu})\right]$$

Multivariate Normal Distribution - II

- ▶ Multivariate generalization of univariate normal distribution.
- ▶ Multivariate normal distribution $\mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma})$ with $d \times 1$ mean vector $\boldsymbol{\mu}$ and $d \times d$ covariance matrix $\boldsymbol{\Sigma}$.
- ▶ Probability density function:

$$p(\mathbf{x} \mid \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{d/2} |\boldsymbol{\Sigma}|^{1/2}} \exp\left[-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu})\right]$$

- ▶ Log likelihood:

$$\mathcal{L}(\boldsymbol{\mu}, \boldsymbol{\Sigma} \mid \mathcal{X}) = -\frac{Nd}{2} \log(2\pi) - \frac{N}{2} \log |\boldsymbol{\Sigma}| - \frac{1}{2} \sum_{t=1}^N (\mathbf{x}^t - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x}^t - \boldsymbol{\mu})$$

- ▶ Given sample $\mathcal{X} = \{\mathbf{x}^t\}_{t=1}^N$, ML estimates:

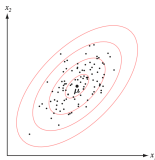
$$\mathbf{m} = \frac{1}{N} \sum_{t=1}^N \mathbf{x}^t \quad \mathbf{S} = \frac{1}{N} \sum_{t=1}^N (\mathbf{x}^t - \mathbf{m})(\mathbf{x}^t - \mathbf{m})^T$$

Multivariate Normal Distribution - III

- **Mahalanobis distance** measures the distance from \mathbf{x} to $\boldsymbol{\mu}$ in terms of $\boldsymbol{\Sigma}$ (normalized for differences in variance and covariance):

$$(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})$$

- $(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}) = c^2$ is the **d -dimensional hyperellipsoid** centered at $\boldsymbol{\mu}$. Its shape and orientation are defined by $\boldsymbol{\Sigma}$.



- **Euclidean distance** is a special case of Mahalanobis distance when $\boldsymbol{\Sigma} = s^2 \mathbf{I}$; the hyperellipsoid degenerates into a **hypersphere**.

Bivariate Normal Distribution - I

- ▶ Multivariate normal distribution with $d = 2$.
- ▶ Covariance matrix:

$$\Sigma = \begin{bmatrix} \sigma_1^2 & \rho\sigma_1\sigma_2 \\ \rho\sigma_2\sigma_1 & \sigma_2^2 \end{bmatrix}$$

- ▶ Joint density:

$$p(x_1, x_2) = \frac{1}{2\pi\sigma_1\sigma_2\sqrt{1-\rho^2}} \exp\left[-\frac{1}{2(1-\rho^2)}(z_1^2 - 2\rho z_1 z_2 + z_2^2)\right]$$

where

$$z_i = \frac{x_i - \mu_i}{\sigma_i} \text{ (z-normalization)}$$

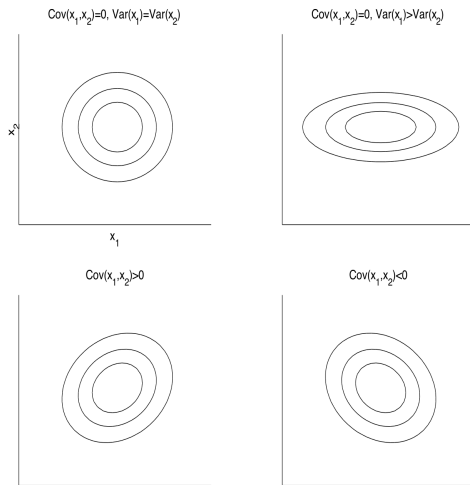
Bivariate Normal Distribution - II

- ▶ for $|\rho| < 1$, the equation of an ellipse

$$z_1^2 - 2\rho z_1 z_2 + z_2^2 = c^2$$

- if $\rho > 0$, the major axis of the ellipse has a positive slope
 - if $\rho < 0$, the major axis of the ellipse has a negative slope
 - If $\rho = 0$, the two variables are independent, the cross-term disappears, and we get a product of two univariate densities.
- ▶ If $\rho = \pm 1$, the two variables are linearly related, the observations are effectively one-dimensional, and one of the two variables can be disposed of.

Isoprobability Contour Plot of Bivariate Normal



Independent Inputs

- ▶ If x_i are independent, the off-diagonal entries σ_{ij} , $i \neq j$ of Σ are 0. The **joint density** becomes:

$$p(\mathbf{x}) = \prod_{i=1}^d p_i(x_i) = \frac{1}{(2\pi)^{d/2} \prod_{i=1}^d \sigma_i} \exp \left[-\frac{1}{2} \sum_{i=1}^d \left(\frac{x_i - \mu_i}{\sigma_i} \right)^2 \right]$$

Mahalanobis distance reduces to **weighted Euclidean distance** (with weightings $1/\sigma_i$).

- ▶ It further reduces to **Euclidean distance** if all variances σ_i^2 are equal.

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Model Selection

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Parametric Classification

Discrete Features

Regression

Multivariate Data

Parametric Classification

- ▶ In Bayes' decision rule for classification, the discriminant function for of class C_i is

$$p(\mathbf{x} \mid C_i)P(C_i) \text{ or } \log [p(\mathbf{x} \mid C_i)P(C_i)]$$

- ▶ Class-conditional densities $p(\mathbf{x} \mid C_i) \sim \mathcal{N}_d(\boldsymbol{\mu}_i, \boldsymbol{\Sigma}_i)$:

$$p(\mathbf{x} \mid C_i) = \frac{1}{(2\pi)^{d/2}|\boldsymbol{\Sigma}_i|^{1/2}} \exp\left[-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu}_i)^T \boldsymbol{\Sigma}_i^{-1}(\mathbf{x} - \boldsymbol{\mu}_i)\right]$$

- ▶ Discriminant functions:

$$\begin{aligned} g_i(\mathbf{x}) &= \log p(\mathbf{x} \mid C_i) + \log P(C_i) \\ &= -\frac{d}{2} \log 2\pi - \frac{1}{2} \log |\boldsymbol{\Sigma}_i| - \frac{1}{2}(\mathbf{x} - \boldsymbol{\mu}_i)^T \boldsymbol{\Sigma}_i^{-1}(\mathbf{x} - \boldsymbol{\mu}_i) + \log P(C_i) \end{aligned}$$

Estimation of Parameters

- ▶ Given a training sample for $K \geq 2$ classes, $\mathcal{X} = \{(\mathbf{x}^t, \mathbf{r}^t)\}_{t=1}^N$, where $r_i^t = 1$ if $\mathbf{x}^t \in C_i$ and 0 otherwise, parameters can be estimated separately for each class.
- ▶ Parameter estimates:

$$\begin{aligned}\hat{P}(C_i) &= \frac{1}{N} \sum_t r_i^t \\ \mathbf{m}_i &= \frac{\sum_t r_i^t \mathbf{x}^t}{\sum_t r_i^t} \\ \mathbf{S}_i &= \frac{\sum_t r_i^t (\mathbf{x}^t - \mathbf{m}_i)(\mathbf{x}^t - \mathbf{m}_i)^T}{\sum_t r_i^t}\end{aligned}$$

Quadratic Discriminant Functions - I

- ▶ The parameter estimates are then plugged into the discriminant functions:

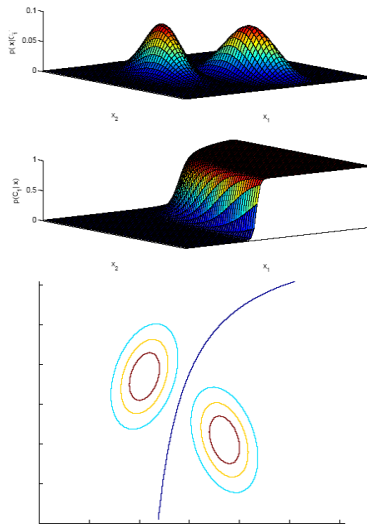
$$\begin{aligned}g_i(\mathbf{x}) &= -\frac{1}{2} \log |\mathbf{S}_i| - \frac{1}{2}(\mathbf{x} - \mathbf{m}_i)^T \mathbf{S}_i^{-1}(\mathbf{x} - \mathbf{m}_i) + \log \hat{P}(C_i) \\&= -\frac{1}{2} \log |\mathbf{S}_i| - \frac{1}{2}(\mathbf{x}^T \mathbf{S}_i^{-1} \mathbf{x} - 2\mathbf{x}^T \mathbf{S}_i^{-1} \mathbf{m}_i + \mathbf{m}_i^T \mathbf{S}_i^{-1} \mathbf{m}_i) + \log \hat{P}(C_i) \\&= \mathbf{x}^T \mathbf{W}_i \mathbf{x} + \mathbf{w}_i^T \mathbf{x} + w_{i0}\end{aligned}$$

where

$$\begin{aligned}\mathbf{W}_i &= -\frac{1}{2} \mathbf{S}_i^{-1} \\ \mathbf{w}_i &= \mathbf{S}_i^{-1} \mathbf{m}_i \\ w_{i0} &= -\frac{1}{2} \mathbf{m}_i^T \mathbf{S}_i^{-1} \mathbf{m}_i - \frac{1}{2} \log |\mathbf{S}_i| + \log \hat{P}(C_i)\end{aligned}$$

- ▶ The discriminant functions are concave and **quadratic**.
- ▶ The decision surface between two categories are **hyperquadrics**.

Quadratic Discriminant Functions - II



Quadratic Discriminant Functions - III

- ▶ The number of parameters to be estimated are Kd for the means and $Kd(d + 1)/2$ for the covariance matrices.
- ▶ When d is large and samples are small, the estimation is not reliable.
- ▶ For the estimates to be reliable on small samples,
 - one may want to decrease dimensionality, d , by redesigning the feature extractor and select a subset of the features or somehow combine existing features.
 - another possibility is to pool the data and estimate a common covariance matrix for all classes.
- ▶ If the covariance for different class is different, we call it heteroscedasticity.

Equal Covariance Matrix \mathbf{S} - I

- ▶ Shared common sample covariance matrix (i.e., homoscedasticity):

$$\mathbf{S} = \sum_i \hat{P}(C_i) \mathbf{S}_i$$

- ▶ Discriminant functions are **linear**:

$$g_i(\mathbf{x}) = -\frac{1}{2}(\mathbf{x} - \mathbf{m}_i)^T \mathbf{S}^{-1}(\mathbf{x} - \mathbf{m}_i) + \log \hat{P}(C_i) + \text{const.}$$

- ▶ Ignoring terms that are the same for all classes

$$g_i(\mathbf{x}) = \mathbf{w}_i^T \mathbf{x} + w_{i0}$$

with

$$\mathbf{w}_i = \mathbf{S}^{-1} \mathbf{m}_i$$

$$w_{i0} = -\frac{1}{2} \mathbf{m}_i^T \mathbf{S}^{-1} \mathbf{m}_i + \log \hat{P}(C_i)$$

- ▶ The number of parameters is Kd for the means and $d(d+1)/2$ for the shared covariance matrix.

Equal Covariance Matrix \mathbf{S} - II

- ▶ The decision surfaces for a linear discriminant classifiers are **hyperplanes** defined by the linear equations $g_i(\mathbf{x}) = g_j(\mathbf{x})$.

- The equation can be written as

$$(\mathbf{w}_i - \mathbf{w}_j)^T \mathbf{x} + w_{i0} - w_{j0} = 0$$

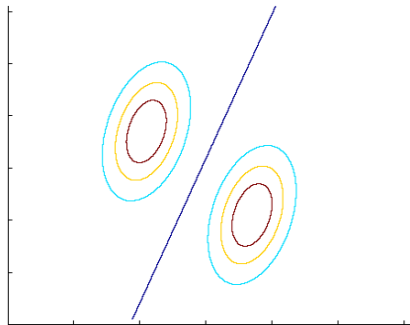
$$\mathbf{w}^T (\mathbf{x} - \mathbf{x}_0) = 0$$

$$\mathbf{w} = \mathbf{S}^{-1}(\mathbf{m}_i - \mathbf{m}_j)$$

$$\mathbf{x}_0 = \frac{1}{2} \mathbf{S}^{-1}(\mathbf{m}_i + \mathbf{m}_j) - \frac{1}{\|\mathbf{S}^{-1}(\mathbf{m}_i - \mathbf{m}_j)\|^2} \log \frac{\hat{P}(C_i)}{\hat{P}(C_j)} \mathbf{S}^{-1}(\mathbf{m}_i - \mathbf{m}_j)$$

- These equations define a hyperplane through point \mathbf{x}_0 with a normal vector \mathbf{w} .
- ▶ If the priors are equal, the optimal decision rule is to assign input to the class whose mean's Mahalanobis distance to the input is the smallest.
- ▶ Unequal priors shift the boundary toward the less likely class.

Equal Covariance Matrix S - III



Decision regions of such a linear classifier are convex.

Equal and Diagonal S - I

- ▶ Naive Bayes' classifier: if the variables are independent, Σ becomes a diagonal matrix.
- ▶ Class-conditional densities:

$$p(\mathbf{x} \mid C_i) = \prod_j p(x_j \mid C_i)$$

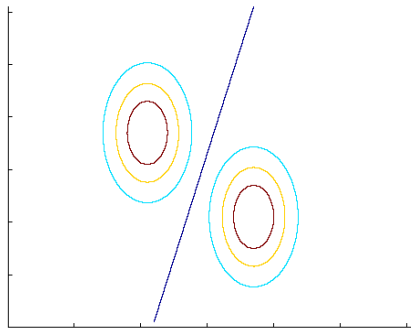
where $p(x_j \mid C_i)$ are univariate Gaussian distributions.

- ▶ Discriminant functions:

$$g_i(\mathbf{x}) = -\frac{1}{2} \sum_{j=1}^d \left(\frac{x_j - m_{ij}}{s_j} \right)^2 + \log \hat{P}(C_i)$$

- ▶ Classification based on weighted Euclidean distance.
- ▶ The number of parameters is Kd for the means and d for the variances.

Equal and Diagonal S - II



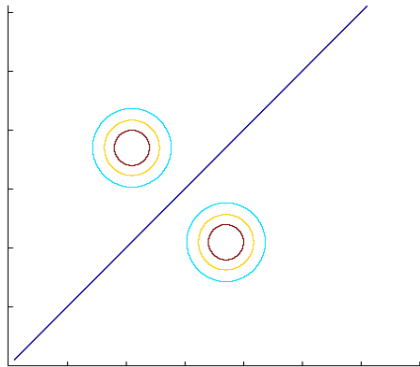
Equal and Diagonal Σ with Equal Variances - I

- ▶ If we assume further that all variances are equal, i.e., $\Sigma = s^2 \mathbf{I}$, weighted Euclidean distance reduces to **Euclidean distance**.
- ▶ Discriminant functions:

$$\begin{aligned} g_i(\mathbf{x}) &= -\frac{1}{2s^2} \|\mathbf{x} - \mathbf{m}_i\|^2 + \log \hat{P}(C_i) \\ &= -\frac{1}{2s^2} \sum_{j=1}^d (x_j - m_{ij})^2 + \log \hat{P}(C_i) \end{aligned}$$

- ▶ Discriminant functions are linear.
- ▶ The number of parameters in this case is Kd for the means and 1 for s^2 .
- ▶ If the priors are equal, we have $g_i(\mathbf{x}) = -\|\mathbf{x} - \mathbf{m}_i\|^2$
 - **nearest mean classifier**: it assigns the input to the class of the nearest mean
 - **template matching** procedure: each mean acts as a **prototype/template** for the class.

Equal and Diagonal S with Equal Variances - II

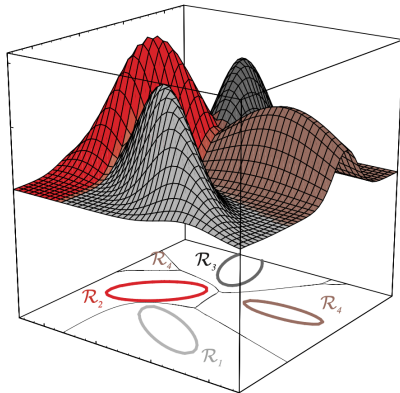


Tuning Model Complexity

Assumption	Covariance matrix	No. of parameters
Shared, hyperspherical	$\mathbf{S}_i = \mathbf{S} = s^2 \mathbf{I}$	1
Shared, axis-aligned	$\mathbf{S}_i = \mathbf{S}$, with $s_{ij} = 0$	d
Shared, hyperellipsoidal	$\mathbf{S}_i = \mathbf{S}$	$d(d+1)/2$
Different, hyperellipsoidal	\mathbf{S}_i	$Kd(d+1)/2$

- Complexity increases (i.e., less restricted \mathbf{S})
⇒ bias decreases and variance increases
- Regularization: uses strong bias to control model complexity.

General Case for Multiple Classes



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Introduction

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Parameter Estimation

Multivariate Normal Distribution

Parametric Classification

Discrete Features

Regression

Multivariate Data

Discrete Features: Bernoulli

- ▶ Bernoulli (or binary) variables x_j :

$$p_{ij} \equiv p(x_j = 1 \mid C_i)$$

- ▶ If x_j 's are **independent** given C_i (i.e, naive Bayes'):

$$p(\mathbf{x} \mid C_i) = \prod_{j=1}^d p_{ij}^{x_j} (1 - p_{ij})^{1-x_j}$$

giving **linear** discriminant functions:

$$\begin{aligned} g_i(\mathbf{x}) &= \log p(\mathbf{x} \mid C_i) + \log P(C_i) \\ &= \sum_j \left[x_j \log p_{ij} + (1 - x_j) \log(1 - p_{ij}) \right] + \log P(C_i) \end{aligned}$$

- ▶ Given sample $\mathcal{X} = \{\mathbf{x}^t\}_{t=1}^N$, the maximum likelihood estimators:

$$\hat{p}_{ij} = \frac{\sum_t x_j^t r_i^t}{\sum_t r_i^t}$$

Discrete Features: Generalized Bernoulli

- ▶ Generalized Bernoulli (or multinomial) variables $x_j \in \{v_1, \dots, v_{n_j}\}$
- ▶ Indicator variables:

$$z_{jk} = \begin{cases} 1 & \text{if } x_j = v_k \\ 0 & \text{otherwise} \end{cases}$$

- ▶ Define

$$p_{ijk} \equiv p(z_{jk} = 1 \mid C_i) = p(x_j = v_k \mid C_i)$$

- ▶ If x_j 's are independent:

$$p(\mathbf{x} \mid C_i) = \prod_{j=1}^d \prod_{k=1}^{n_j} p_{ijk}^{z_{jk}}$$

$$g_i(\mathbf{x}) = \sum_j \sum_k z_{jk} \log p_{ijk} + \log P(C_i)$$

- ▶ Given sample $\mathcal{X} = \{\mathbf{x}^t\}_{t=1}^N$, the maximum likelihood estimators:

$$\hat{p}_{ijk} = \frac{\sum_t z_{jk}^t r_i^t}{\sum_t r_i^t}$$

Outline

Introduction

Univariate Data

- Maximum Likelihood Estimation

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Multivariate Data

Multivariate Linear Regression

- ▶ Multivariate linear regression:

$$r = f(\mathbf{x}) + \epsilon$$

where $f(\mathbf{x}) \approx$ estimator $g(\mathbf{x} \mid w_0, w_1, \dots, w_d) = w_0 + w_1 x_1 + \dots + w_d x_d$.

- ▶ In some literature (especially statistical literature), this is called multiple linear regression; statisticians use the term multivariate when there are multiple outputs.
- ▶ Given $\mathcal{X} = \{(\mathbf{x}^t, r^t)\}_{t=1}^N$, **error function**:

$$E(w_0, w_1, \dots, w_d \mid \mathcal{X}) = \frac{1}{2} \sum_t \left(r^t - w_0 - w_1 x_1^t - \dots - w_d x_d^t \right)^2$$

- ▶ Maximizing the Gaussian likelihood is equivalent to minimizing the sum of squared errors.

Normal Equations

- ▶ Taking the derivative with respect to the parameters, we get the **normal equations** for multivariate linear regression:

$$\mathbf{X}^T \mathbf{X} \mathbf{w} = \mathbf{X}^T \mathbf{r}$$

where

$$\mathbf{X} = \begin{bmatrix} 1 & x_1^1 & x_2^1 & \cdots & x_d^1 \\ 1 & x_1^2 & x_2^2 & \cdots & x_d^2 \\ \vdots & & & & \\ 1 & x_1^N & x_2^N & \cdots & x_d^N \end{bmatrix}$$

$$\mathbf{w} = (w_0, w_1, \dots, w_d)^T$$

$$\mathbf{r} = (r^1, r^2, \dots, r^N)^T$$

- ▶ Estimated parameters (assuming that $\mathbf{X}^T \mathbf{X}$ is invertible):

$$\hat{\mathbf{w}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{r}$$

Multivariate Polynomial Regression

- ▶ Define new **higher-order variables**, e.g.

$$z_1 = x_1, \quad z_2 = x_2 \quad z_3 = (x_1)^2, \quad z_4 = (x_2)^2, \quad z_5 = x_1 x_2$$

- ▶ Apply multivariate linear regression in the new **z** space.
- ▶ Actually using higher-order terms of inputs as additional inputs is only one possibility; we can define any nonlinear function of the original inputs using basis functions, like $z = \sin(x)$.
- ▶ This idea of generalizing the linear model is frequently used in later course.