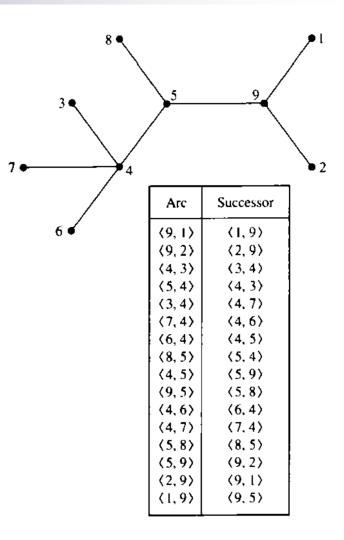
PRAM 2 Graph algorithms

CS121 Parallel Computing Spring 2017

Euler tours

- An Euler tour of a graph is a cycle that goes through every edge of the graph.
 - □ It may go through a vertex multiple times.
- A connected, directed graph has an Euler tour if and only if the indegree and outdegree of every vertex are equal.
- Suppose we take an undirected graph, and for edge (u,v), create two directed edges (u,v) and (v,u).
 - Then every vertex has equal indegree and outdegree, and so has an Euler tour.
- Consider a tree where each edge has been doubled.
 - To find an Euler tour of the tree, first order the edges adjacent to each node arbitrarily.
 - Say the neighbors of a node v are ordered $u_0, ..., u_{d-1}$. Then set the successor of edge (u_i, v) on the tour to $(v, u_{(i+1) \bmod d})$.
- The Euler tour of a tree can be computed in O(1) parallel time.



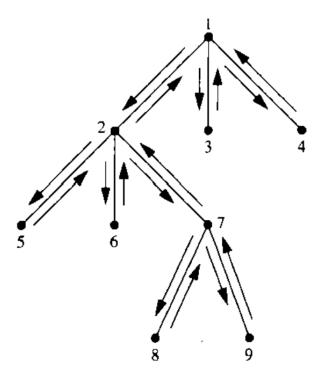
$$\langle 9, 1 \rangle \rightarrow \langle 1, 9 \rangle \rightarrow \langle 9, 5 \rangle \rightarrow \langle 5, 8 \rangle \rightarrow \langle 8, 5 \rangle \rightarrow \langle 5, 4 \rangle \rightarrow \langle 4, 3 \rangle \rightarrow \langle 3, 4 \rangle \rightarrow \langle 4, 7 \rangle \rightarrow \langle 7, 4 \rangle \rightarrow \langle 4, 6 \rangle \rightarrow \langle 6, 4 \rangle \rightarrow \langle 4, 5 \rangle \rightarrow \langle 5, 9 \rangle \rightarrow \langle 9, 2 \rangle \rightarrow \langle 2, 9 \rangle \rightarrow \langle 9, 1 \rangle$$

Source: Introduction to Parallel Algorithms, Jaja



Parallel tree operations

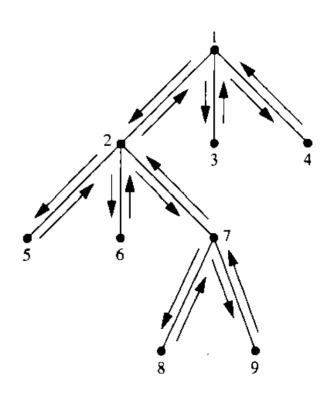
- Many operations on trees can be done in parallel using Euler tours and prefix sum.
- These operations in turn are used in other parallel graph algorithms.
- We first root a tree in parallel.
 - □ I.e. set an arbitrary node r as the tree's root. Then each node v needs to compute p(v), its parent in the rooted tree.
 - □ To do this, assign a weight of 1 to each edge in an Euler tour of the tree.
 - Then compute the parallel prefix sum of the edges.
 - □ For each edge (u,v), set u=p(v) whenever the prefix sum of (u,v) is less than the prefix sum of (v,u).
 - □ Thus, we can root a tree with n nodes in O(log n) time and O(n) work.





Node depths

- For each node, compute its depth in a rooted tree.
 - □ For each node v, let p(v) be its parent.
 - □ Set the weight of edge (p(v), v) to 1, an the weight of edge (v, p(v)) to -1.
 - Compute a parallel prefix sum of the Euler tour starting at the root.
 - □ The depth of node v is the prefix sum of edge (p(v), v).
- For a tree with n nodes, this takes O(log n) time using O(n) work.

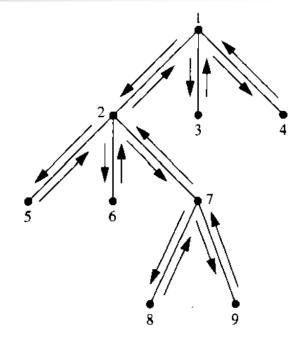


Postorder numbering

- Traverse a rooted tree in postorder, starting from the root r.
 - Start an Euler tour from r. For each node v, we want to visit v's children in the order of the tour, then visit v itself.

□ Ex	V	1	2	3	4	5	6	7	8	9
	n(v)	9	6	7	8	1	2	5	3	4

- □ For each node v, set the weight of edge (v, p(v)) to 1, and the weight of (p(v), v) weight 0.
- Compute a parallel prefix sum of the Euler tour.
- □ For each $v \neq r$, set n(v) to the prefix sum of edge (v, p(v)). Set n(r)=n.
- In a tree with n nodes, we can compute the postorder numbering in O(log n) time and O(n) work.

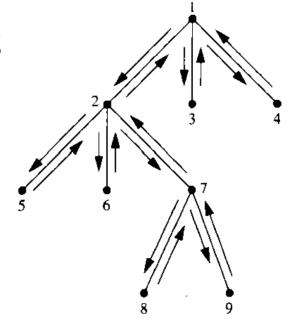


Euler Path	Weight	Prefix Sums
(1, 2)	0	0
(2, 5)	0	0
(5, 2)	l	1
(2, 6)	0	1
(6, 2)	ı	2
(2, 7)	0	2
(7, 8)	0	2
⟨8, 7⟩	1	3
⟨7,9⟩	0	3
(9, 7)	l	4
⟨7, 2⟩	l i	5
(2, 1)	1	6
(1, 3)	0	6
(3, 1)	I	7
⟨1,4⟩	0	7
(4, 1)	1	8



Number of descendant

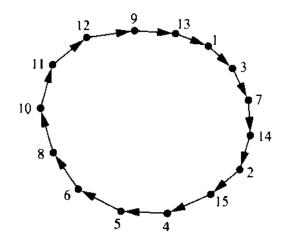
- For each node v in a rooted tree, compute the number of nodes in the subtree rooted at v.
- To do this, we compute prefix sums as in the postorder numbering.
- Then the number of descendants of a node v equals the prefix sum of (v, p(v)) minus the prefix sum of (p(v), v).
- In a tree with n nodes, we can compute the number of descendants in O(log n) time and O(n) work.



Euler Path	Weight	Prefix Sums		
(1, 2)	0	0		
(2, 5)	0	0		
(5, 2)	ι	1		
(2, 6)	0	1		
(6, 2)	ı	2		
(2, 7)	0	2		
(7, 8)	0	2		
(8, 7)	1	3		
(7,9)	0	3		
(9, 7)	l	4		
(7, 2)	l	5		
(2, 1)	1	6		
(1, 3)	0	6		
(3, 1)	I	7		
(1,4)	0	7		
(4, 1)	1	8		



- Given a graph G=(V,E), a k-coloring of G is a mapping $c: V \to \{0,1,...,k-1\}$ s.t. $c(i) \neq c(j)$ whenever $(i,j) \in E$.
- We give a super fast algorithm for 3-coloring a (directed) cycle of n nodes.
 - ☐ If n is odd, any coloring uses at least 3 colors.
 - □ Coloring the cycle is a form of symmetry breaking.
 - \Box For any node v, let S(v) be the node after v.
- The main subroutine is the following.
 - □ Initially, color every node by its node ID.
 - \Box Consider the binary representation of c(v) for a node v.
 - Let k be the least significant digit i which c(v) and c(S(v)) differ.
 - □ Set $c'(v)=2k+c(v)_k$, where $c(v)_k$ is the k'th digit of c(v).
- Claim If c is a valid coloring, then so is c'.
- Proof Since c is a valid coloring, then $c(v) \neq c(S(v))$, so k exists.
 - □ Suppose c'(v) = c'(u), for some v and u = S(v).
 - Then $c'(v) = 2k + c(v)_k$ and $c'(u) = 2l + c(u)_l$ for some k and l.
 - □ Since c'(v) = c'(u), then k=l, because $c(v)_k$, $c(u)_l < 2$.
 - \square But then $c(v)_k = c(u)_k$, contradicting the definition of k.



V	С	k	c'	
1	0001	1	2	
3	0011	2	4	
7	0111	0	1	
14	1110	2	5	
2	0010	0	0	
15	1111	0	1	
4	0100	0	0	
5	0101	0	L	
6	0110	1	3	
8	1000	1	2	
10	1010	0	0	
11	1011	0	l l	
12	1100	0	0	
9	1001	2	4	
13	1101	2	5	

Coloring a cycle

- To analyze the time complexity, suppose in some round the max number of bits to represent any color is t.
- Then the max number of bits to represent any color in the next round is $\lceil \log t \rceil + 1$, because any color in the next round is $\leq 2t + 1$.
 - \square So the number of bits used to represent a color decreases from t to $\lceil \log t \rceil + 1$ in each round.
- Let $\log^{(i)} x = \log(\log^{(i-1)} x)$, i.e. we apply the log function i times to x.
- Let $\log^* x = \min\{i \mid \log^{(i)} x \le 1\}$ be the number of times we have to take log's until a value becomes ≤ 1 .
 - $\log^* x$ is incredibly small. In fact, $\log^* x \le 5$ for all $x \le 2^{65526}$!

Colorina

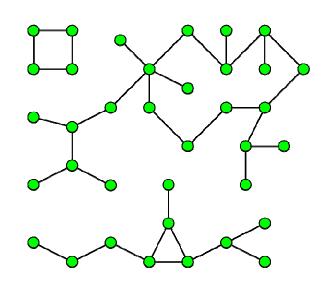
Coloring a cycle

- Since the number of bits to represent a color in the first round is $\log n$, then in $O(\log^* n)$ rounds, we can represent any color using O(1) bits.
 - □ In fact, we can apply the subroutine until we use 6 colors in a round.
 - With 6 colors, need 3 bits to represent a color. So in the next round, colors are between 0 and 2*2+1=5, and we again use up to 6 colors.
- To decrease the number of colors from 6 to 3, we run 3 more rounds.
 - □ In round i, take any node colored using color i+2 and color it using the min possible color in {0,1,2}, i.e. the min color not used by its neighbors.
- In total, we 3-color the ring in $O(\log^* n)$ rounds, using $O(n \log^* n)$ work.



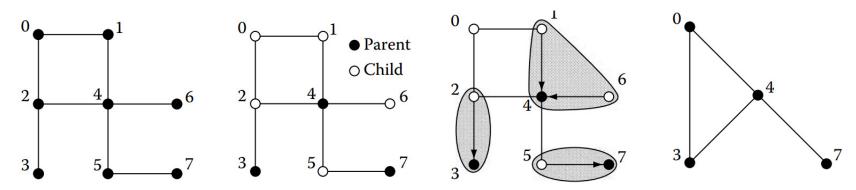
Connected components

- Given an undirected graph, partition it into maximal sets of nodes that are connected to each other.
- Can be solved sequentially in O(m) time using BFS / DFS.
 - m is number of edges, n is number of vertices.
- However, no efficient BFS / DFS PRAM algorithms known.
- Instead, use graph contractions.
 - In each phase, merge (contract) a set of connected nodes into a supernode.
 - Form a contracted graph on the supernodes, then apply algorithm recursively.
 - Eventually each connected component is contracted to one node.
 - Many different algorithms, depending on which nodes they contract.



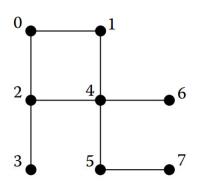
Randomized parallel algorithm

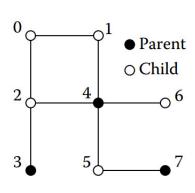
- Break graph into star graphs and contract each star.
- In each phase, do the following steps in parallel.
 - □ Every node flips a coin and chooses to be a parent or child node.
 - □ Each child node points to a parent node it's connected to.
 - Now have a set of stars, with the parent nodes as the centers.
 - If child not connected to any parent node, it forms its own star.
 - □ Contract each star to its center, then apply algorithm recursively.
 - Label all nodes in star by the label of the parent.
 - Keep the edges between differently labeled nodes.
 - After recursion returns, each child with a parent again takes parent's label, which might have changed.

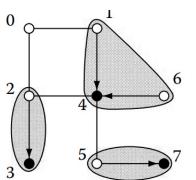


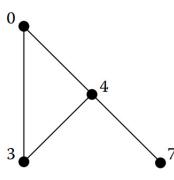
Implementation

- Use n+m processors, one processor for each vertex and edge.
 - □ Call these E and V procs, resp.
 - □ Each V proc has a label which can change over time.
 - \square Each E proc responsible for edge (u,v), where u, v are V procs.
 - □ V and E procs may become inactive over time.
- In each phase, each active V proc flips a coin to decide if it's a child or parent proc.
- Each active E proc (u,v) checks if u is a child proc and v is a parent (or vice versa).
 - \square If so, it sets u's label to v (or v's label to u).
 - □ Another E proc (u,v') could set u's label to v'. In this case, either the v or v' write succeeds.





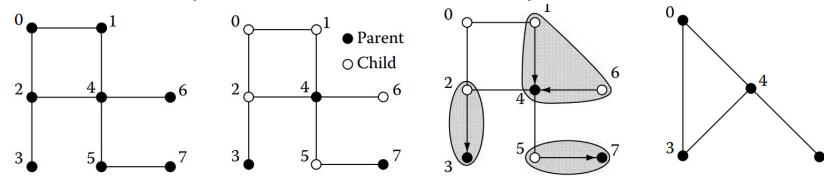






Implementation

- Each parent V proc, or child V proc whose label didn't change (i.e. it had no parent), stays active.
 - □ Other V procs become inactive.
- Each active E proc (u,v) where u, v have different labels stays active.
 - □ Other E procs become inactive.
 - From now on, E will be responsible for V processes (u',v'), where u' and v' are the labels of u and v, resp.
- The active V and E procs run the algorithm recursively.
- After recursion returns, inactive E procs (u,v) (where u is the child) write v's label to u.
- At end, all V procs in a connected component have same label.





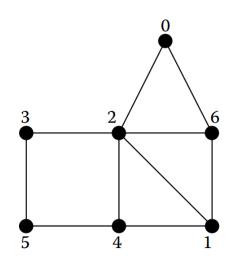
Complexity

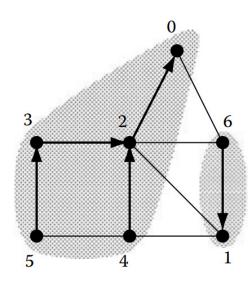
- Key fact is that number of active V procs decreases by 1/4 fraction in expectation each phase.
 - A V proc becomes inactive if it's a child node and one its neighbors is a parent node.
 - \square The former probability is 1/2, and the latter is \ge 1/2.
 - □ Thus each V proc becomes inactive with probability ≥ 1/4.
- With high probability, after O(log n) phases, there's only one V proc and recursion ends.
- Each phase takes O(1) time, and does O(m+n) work.
- Total time is O(log n), total work is O((m+n) log n).
 - □ This algorithm isn't work efficient.
 - □ There exist work efficient randomized CC algorithms.



Deterministic parallel algorithm

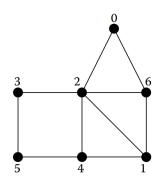
- Again work in phases, with following parallel steps.
 - □ Each node points to a neighbor with lower ID.
 - □ This breaks graph into a directed forest.
 - Contract each forest to the lowest ID node using pointer jumping.
 - □ Recurse on contracted graph.

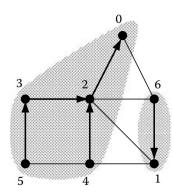




Implementation

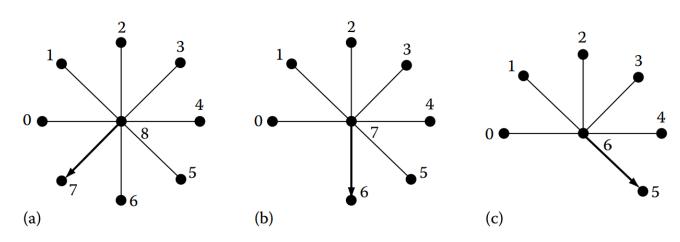
- As before, use n+m procs, for V and E.
 - □ But now, V procs always active. E procs may become inactive.
- Each E proc (u,v) checks if u<v, and if so sets v's label to u.</p>
 - □ Again, conflicts resolved arbitrarily.
- V procs then apply pointer jumping on the labels, taking the label of the proc it points to.
- Each active E proc (u,v) where u, v have different labels stays active.
 Other E procs become inactive.
 - □ From now on, E will be responsible for V processes (u',v'), where u' and v' are the labels of u and v, resp.
 - ☐ There may be multiple E procs responsible for same (u',v').
- The V procs and active E procs run algorithm recursively.
 - □ Note that in recursive call, all V procs apply pointer jumping.





Complexity

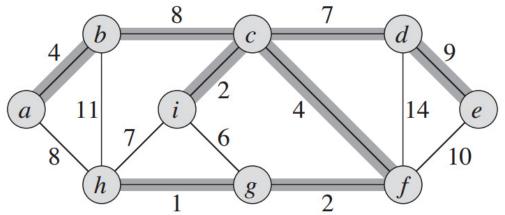
- The basic algorithm may take O(n) time on the graph below.
- But notice that if we made nodes point to higher neighbors, the graph would be solved in O(1) time.
- In each phase, if we consider either having nodes point to smaller neighbors, or pointing to higher neighbors, in one case ≥ n/2 nodes point to another node.
- Thus the algorithm finishes in O(log n) phases.
- Each phase does pointer jumping, which takes O(log n) time and O(n log n) work.
- Total time is $O(\log^2 n)$, and work is $O((m+n \log n) \log n)$.





Minimum spanning tree

- Given an undirected graph with edge weights, an MST is a connected subgraph containing all the vertices, which has minimum total weight.
- Can be solved in O(m + n log n) time sequentially by a greedy algorithm.
- Key property is that for any set of vertices W, the minimum cost edge from W to V \ W is in the MST.
 - □ So for any vertex v, min cost edge containing v is in MST.
- Will describe a parallel MST algorithm based on the randomized parallel algorithm for connected component.

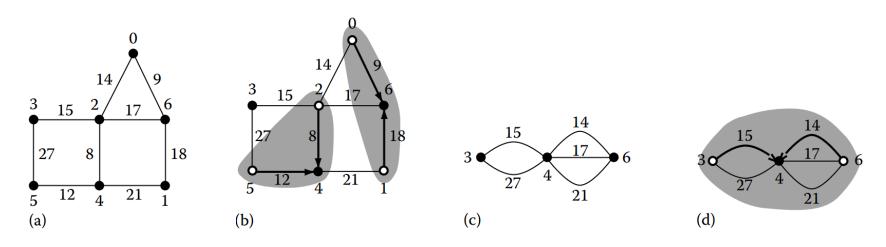


Source: Introduction to Algorithms, Cormen et al.

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Randomized parallel algorithm

- Each node randomly chooses to be a parent or child node.
- Each child node u finds min weight incident edge (u,v), and points to v if v is parent.
 - ☐ This forms a set of stars with parents as centers.
 - ☐ If v isn't a parent, u forms its own star.
- Contract each star to the parent, and run algorithm recursively.
- Finding min weight incident edge quickly is a little tricky.
 - □ One possibility is to use priority CRCW.
 - □ Presort the edges by nondecreasing weight. Then when each E proc (u,v) writes to u, min weight edge wins.



Complexity

- At least 1/4 of vertex processors become inactive each phase in expectation.
 - ☐ Given a node u and min weight edge (u,v), there's 1/4 probability u is child and v is parent.
- Thus, there are O(log n) phases with high probability.
 - □ Finding min weight incident edge takes O(1) time after presorting edge weights.
- Total time is O(log n), total work is O((m+n) log n).