

# CS120: Computer Networks

Lecture 10. Routing 1

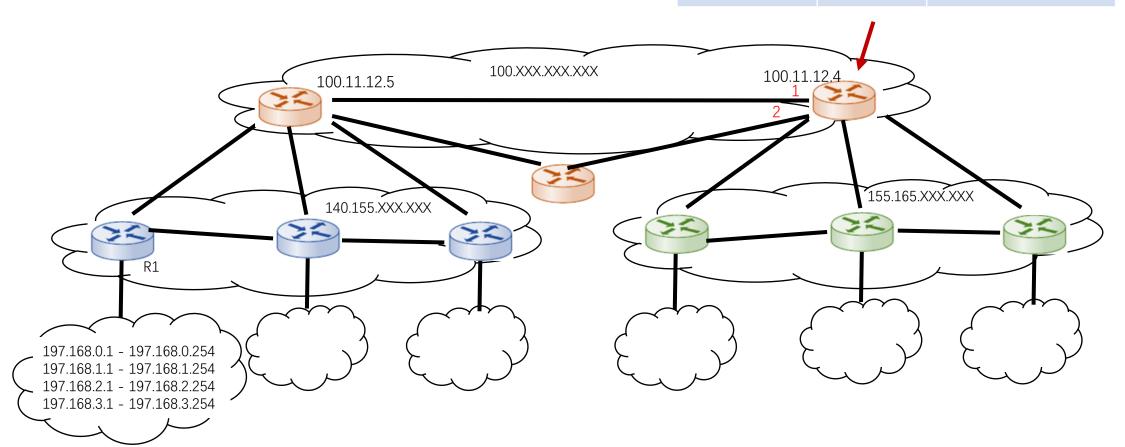
Zhice Yang

Routing Table

SubnetNum	NextHop
.97.168.0.0/22	100.11.12.5

#### Forwarding Table

destaddress	Interface	MAC
100.11.12.5	1	AB.CD.EF.12.34.56

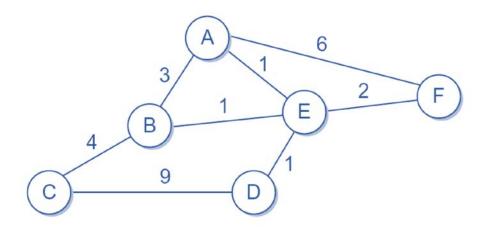


#### Forwarding Table vs. Routing Table

- Forwarding table
  - Determines local forwarding
    - Optimized for looking up an address when forwarding a packet
  - Normally in hardware
  - Contains the mapping from network numbers to outgoing interfaces and some MAC addresses
- Routing table
  - Built by the routing algorithm as a precursor to build the forwarding table
    - Optimized for calculating changes in network topology
  - Normally in software
  - Contains mapping from network numbers to next hops

#### Network as a Graph

- The basic problem of routing is to find the lowest-cost path between any two nodes
  - Static approach has several shortcomings
    - Can't handle node or link failures
    - Can't handle addition of new nodes or links
    - Edge costs cannot change
  - Centralized solution does not scale
  - ➤ Distributed and dynamic protocol



#### Routing Protocols

- Routing Information Protocol (RIP)
  - Algorithm: Distance Vector
- Open Shortest Path First (OSPF)
  - Algorithm: Link State
- Border Gateway Protocol (BGP)

Intradomain Routing Protocol

Interdomain Routing Protocol

Bellman-Ford equation

let

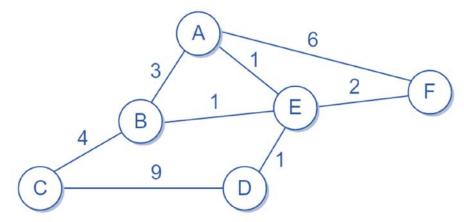
 $d_x(y)$  =cost of lowest-cost path from x to y

then

$$d_{x}(y) = \min_{v} \{c(x, v) + d_{v}(y)\}$$
lowest-cost from neighbor v to destination y cost to neighbor v
min taken over all neighbors v of x

#### Example

- $\bullet \ d_B(A) = 2$
- $\bullet \ d_D(A) = 2$
- $d_C(A) = \min(d_B(A) + 4, d_D(A) + 9) = 6$



- x maintains its distance vector estimate  $\mathbf{D}_{x}(y) = \{D_{x}(y): y \in N\}$
- x knows:
  - cost to each neighbor v: c(x, v)
  - neighbors' distance vectors estimate:  $\mathbf{D}_{v}(y) = \{D_{v}(y): y \in N\}$
- Algorithm idea:
  - From time-to-time, each node sends its own distance vector estimate to neighbors
  - When x receives new distance vector estimate from neighbor, it updates its own distance vector estimate using Bellman-Ford equation
  - Under minor, natural conditions, the estimate  $D_x(y)$  will converge to the actual lowest cost  $d_x(y)$

у	$D_A(y)$
Α	0
В	inf
С	inf
D	inf
Ε	inf
F	inf
G	inf

y	$D_{\mathrm{B}}(y)$
Α	inf
В	0
С	inf
D	inf
Ε	inf
F	inf
G	inf

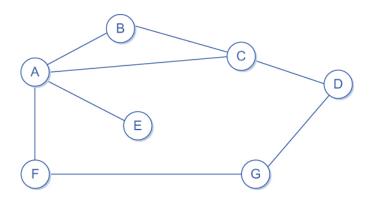
y	$D_{C}(y)$
Α	inf
В	inf
С	0
D	inf
Ε	inf
F	inf
G	inf

$D_D(y)$
inf
inf
inf
0
inf
inf
inf

y	$D_{E}(y)$
Α	inf
В	inf
С	inf
D	inf
Ε	0
F	inf
G	inf

17	$D_{F}(y)$
У	DF(y)
А	inf
В	inf
С	inf
D	inf
Ε	inf
F	0
G	inf

y	$D_{G}(y)$
Α	inf
В	inf
С	inf
D	inf
Ε	inf
F	inf
G	0



y	$D_A(y)$
Α	0
В	1
С	1
D	inf
Ε	1
F	1
G	inf

$D_{\mathrm{B}}(y)$
1
0
1
inf
inf
inf
inf

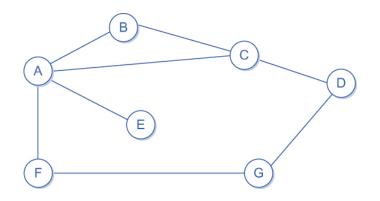
y	$D_{\mathbb{C}}(y)$
Α	1
В	1
С	0
D	1
Ε	inf
F	inf
G	inf

y	$D_D(y)$
Α	inf
В	inf
С	1
D	0
Ε	inf
F	inf
G	1

y	$D_{E}(y)$
Α	1
В	inf
С	inf
D	inf
Ε	0
F	inf
G	inf

y	$D_F(y)$
Α	1
В	inf
С	inf
D	inf
Ε	inf
F	0
G	1

$D_{G}(y)$
inf
inf
inf
1
inf
1
0



- Every T seconds each router sends its table to its neighbor
- Each router then updates its table based on the new information

y	$D_A(y)$
Α	0
В	1
С	1
D	inf
Ε	1
F	1
G	inf

y	$D_{\mathrm{B}}(y)$
Α	1
В	0
С	1
D	inf
Ε	inf
F	inf
G	inf

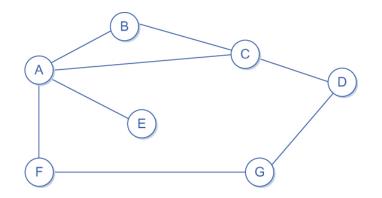
y	$D_{C}(y)$
Α	1
В	1
С	0
D	1
Ε	inf
F	inf
G	inf

D ( )
$D_{D}(y)$
inf
inf
1
0
inf
inf
1

y	$D_{E}(y)$
Α	1
В	inf
С	inf
D	inf
Ε	0
F	inf
G	inf

y	$D_F(y)$
Α	1
В	inf
С	inf
D	inf
Ε	inf
F	0
G	1

$D_{G}(y)$
inf
inf
inf
1
inf
1
0





y	$D_A(y)$
Α	0
В	1
С	1
D	inf
Ε	1
F	1
G	inf

y	$D_{\mathrm{B}}(y)$
Α	1
В	0
С	1
D	inf
Ε	inf
F	inf
G	inf

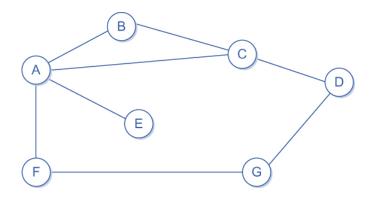
y	$D_{C}(y)$
Α	1
В	1
С	0
D	1
Ε	inf
F	inf
G	inf

y	$D_D(y)$
Α	inf
В	inf
С	1
D	0
Ε	inf
F	inf
G	1

y	$D_{E}(y)$
Α	1
В	inf
С	inf
D	inf
Ε	0
F	inf
G	inf

y	$D_F(y)$
Α	1
В	inf
С	inf
D	inf
Ε	inf
F	0
G	1

$D_{G}(y)$
inf
inf
inf
1
inf
1
0



у	$D_A(y)$
Α	0
В	1
С	1
D	2
Ε	1
F	1
G	inf

17	$D_{\mathrm{B}}(y)$
<i>y</i>	
А	1
В	0
С	1
D	inf
Ε	inf
F	inf
G	inf

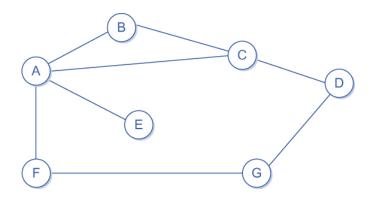
y	$D_{C}(y)$
Α	1
В	1
С	0
D	1
Ε	inf
F	inf
G	inf

	D ()
<i>y</i>	$D_{D}(y)$
Α	inf
В	inf
С	1
D	0
Ε	inf
F	inf
G	1

$D_{E}(y)$
1
inf
inf
inf
0
inf
inf

y	$D_F(y)$
Α	1
В	inf
С	inf
D	inf
Ε	inf
F	0
G	1

$D_{G}(y)$
inf
inf
inf
1
inf
1
0



y	$D_A(y)$
Α	0
В	1
С	1
D	2
Ε	1
F	1
G	inf

y	$D_{\mathrm{B}}(y)$
Α	1
В	0
С	1
D	inf
Ε	inf
F	inf
G	inf

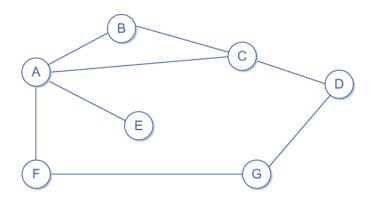
y	$D_{C}(y)$
Α	1
В	1
С	0
D	1
Ε	inf
F	inf
G	inf

y	$D_D(y)$
Α	inf
В	inf
С	1
D	0
Ε	inf
F	inf
G	1

y	$D_{E}(y)$
Α	1
В	inf
С	inf
D	inf
Ε	0
F	inf
G	inf

y	$D_{F}(y)$
Α	1
В	inf
С	inf
D	inf
Ε	inf
F	0
G	1

y	$D_{G}(y)$
Α	inf
В	inf
С	inf
D	1
Ε	inf
F	1
G	0



y	$D_A(y)$
Α	0
В	1
С	1
D	2
Ε	1
F	1
G	2

$D_{\mathrm{B}}(y)$
1
0
1
inf
inf
inf
inf

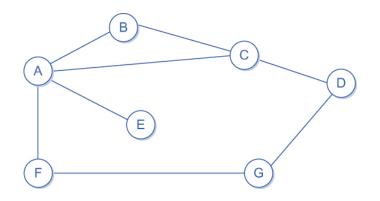
$D_{C}(y)$
1
1
0
1
inf
inf
inf

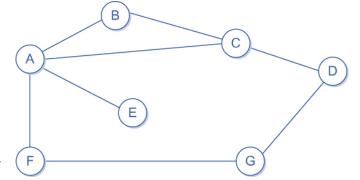
y	$D_D(y)$
Α	inf
В	inf
С	1
D	0
Ε	inf
F	inf
G	1

y	$D_{E}(y)$
Α	1
В	inf
С	inf
D	inf
Ε	0
F	inf
G	inf

y	$D_F(y)$
Α	1
В	inf
С	inf
D	inf
Ε	inf
F	0
G	1

$D_{G}(y)$
inf
inf
inf
1
inf
1
0



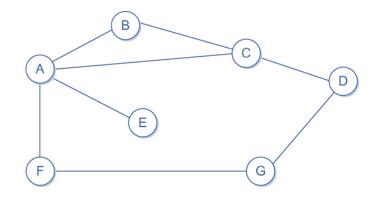


Information	Distance to Reach Node						
Stored at Node	Α	В	С	D	Е	F	G
А	0	1	1	2	1	1	2
В	1	0	1	2	2	2	3
С	1	1	0	1	2	2	2
D	2	2	1	0	3	2	1
E	1	2	2	3	0	2	3
F	1	2	2	2	2	0	1
G	2	3	2	1	3	1	0

y	$D_A(y)$	via
Α	0	Α
В	1	В
С	1	С
D	2	С
Ε	1	Е
F	1	F
G	2	F

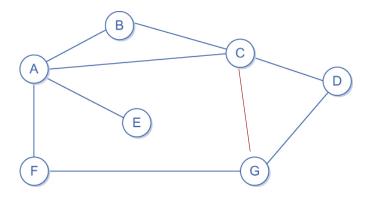
Good news travels fast

Information	Distance to Reach Node						
Stored at Node	Α	В	С	D	Е	F	G
А	0	1	1	2	1	1	2
В	1	0	1	2	2	2	3
С	1	1	0	1	2	2	2
D	2	2	1	0	3	2	1
Е	1	2	2	3	0	2	3
F	1	2	2	2	2	0	1
G	2	3	2	1	3	1	0

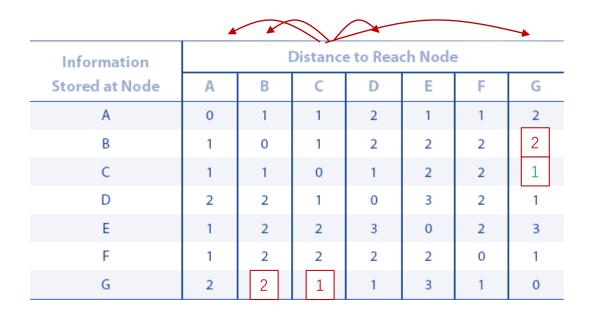


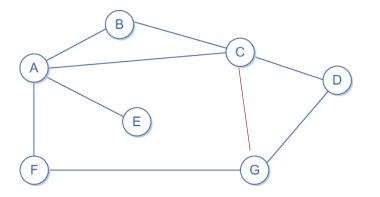
Good news travels fast

Information		Distance to Reach Node						
Stored at Node	Α	В	С	D	Е	F	G	
А	0	1	1	2	1	1	2	
В	1	0	1	2	2	2	3	
С	1	1	0	1	2	2	1	
D	2	2	1	0	3	2	1	
Е	1	2	2	3	0	2	3	
F	1	2	2	2	2	0	1	
G	2	3	1	1	3	1	0	



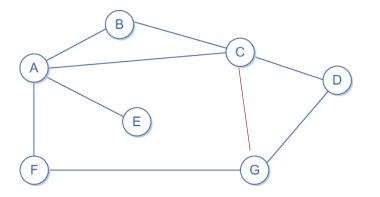
Good News Travels Fast



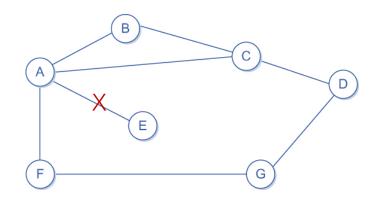


Good News Travels Fast

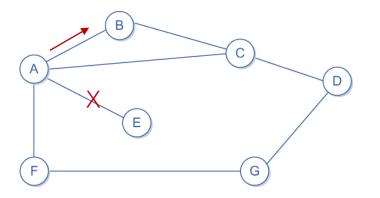
				4			
Information	Distance to Reach Node						
Stored at Node	Α	В	С	D	Е	F	G
А	0	1	1	2	1	1	2
В	1	0	1	2	2	2	2
С	1	1	0	1	2	2	1
D	2	2	1	0	3	2	1
E	1	2	2	3	0	2	3
F	1	2	2	2	2	0	1
G	2	2	1	1	3	1	0



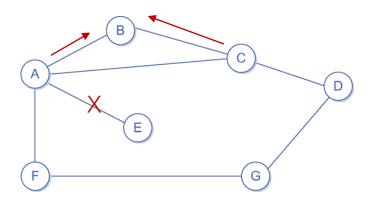
Information		Distance to Reach Node						
Stored at Node	Α	В	С	D	Е	F	G	
А	0	1	1	2	1	1	2	
В	1	0	1	2	2	2	3	
С	1	1	0	1	2	2	2	
D	2	2	1	0	3	2	1	
Е	inf	2	2	3	0	2	3	
F	1	2	2	2	2	0	1	
G	2	3	2	1	3	1	0	



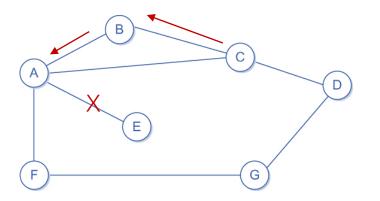
Information		2					
Stored at Node	Α	В	С	D	Е	F	G
А	0	1	1	2	1	1	2
В	1	0	1	2	2	2	3
С	1	1	0	1	2	2	2
D	2	2	1	0	3	2	1
Е	inf	inf	2	3	0	2	3
F	1	2	2	2	2	0	1
G	2	3	2	1	3	1	0



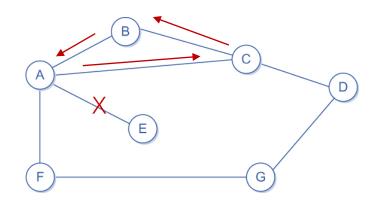
Information	Distance to Reach Node						
Stored at Node	Α	В	С	D	Е	F	G
А	0	1	1	2	1	1	2
В	1	0	1	2	2	2	3
С	1	1	0	1	2	2	2
D	2	2	1	0	3	2	1
Е	inf	3	2	3	0	2	3
F	1	2	2	2	2	0	1
G	2	3	2	1	3	1	0



Information		2					
Stored at Node	Α	В	С	D	Е	F	G
А	0	1	1	2	1	1	2
В	1	0	1	2	2	2	3
С	1	1	0	1	2	2	2
D	2	2	1	0	3	2	1
Е	4	3	2	3	0	2	3
F	1	2	2	2	2	0	1
G	2	3	2	1	3	1	0

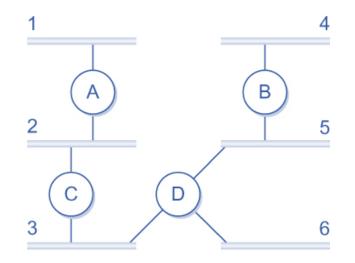


Information	Distance to Reach Node						
Stored at Node	Α	В	С	D	Е	F	G
A	0	1	1	2	1	1	2
В	1	0	1	2	2	2	3
С	1	1	0	1	2	2	2
D	2	2	1	0	3	2	1
E	4	3	5	3	0	2	3
F	1	2	2	2	2	0	1
G	2	3	2	1	3	1	0



#### Routing Information Protocol (RIP)

- Included in BSD-UNIX distribution in 1982
- Use distance vector algorithm
  - Distance metric: # hops (max = 15 hops), each link has cost 1
  - Distance Vectors exchanged with neighbors every 30 sec in response message
    - Each message: list of up to 25 destination subnets



#### Routing Table A

SubnetNum	Distance	NextHop
1	0	Net1
2	0	Net2
3	1	С
4	3	С
5	2	С
6	2	С

#### Routing Protocols

- Routing Information Protocol (RIP)
  - Algorithm: Distance Vector
- Open Shortest Path First (OSPF)
  - Algorithm: Link State
- Border Gateway Protocol (BGP)

Intradomain Routing Protocol

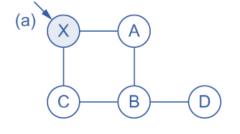
Interdomain Routing Protocol

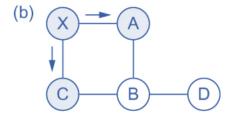
#### Link-State Routing Algorithm

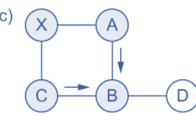
- Assumptions
  - Net topology, link costs known to all nodes
    - Accomplished via "Reliable Flooding"
    - Send to all nodes (not just neighbors) information about directly connected links (not the entire routing table).
      - Link state packet (LSP)
  - All nodes have same info
- Routing Method: Computes shortest paths from one node ('source') to all other nodes
  - Based on Dijkstra's Algorithm

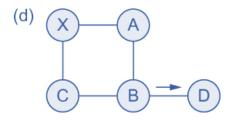
#### Reliable Flooding

- Designs
  - Keep LSP up to date
    - Generate new LSP periodically
      - on the order of hours
    - Generate new LSP when link states change
  - Abandon old link state information
    - Differentiates new LSP according to seq number (c)
    - Decreases TTL before flooding
    - Ages stored LSP
  - Limiting the flooding overhead
    - Forward LSP to all nodes but one that sent it



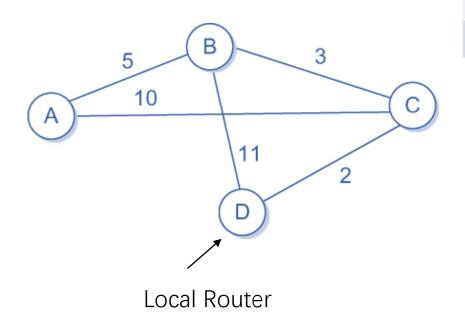




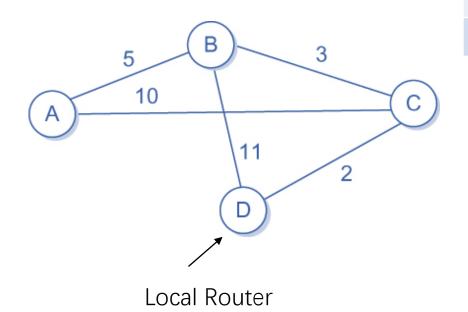


```
Initialization:
M = \{s\}
for all nodes v
  if v adjacent to s
then D_s(v) = c(u, v)
else D_s(v) = \inf
Loop
  find w not in M such that D_s(w) is a minimum
    add w to M
    update D_s(v) for all v adjacent to w and not in M:
        D_s(v) = \min(D_s(v), D_s(w) + c(w, v))
until all nodes in M
```

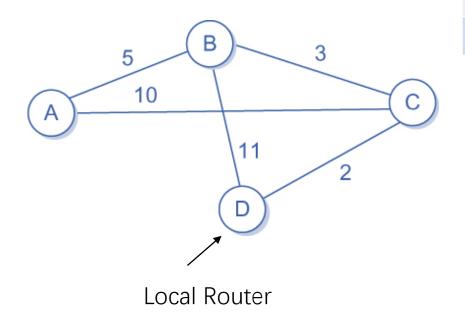
- M: set of node processed
- S: node of the local router
- v: node of other routers
- $D_s(v)$  distance from s to v
- c(u, v) link weight between node u and v



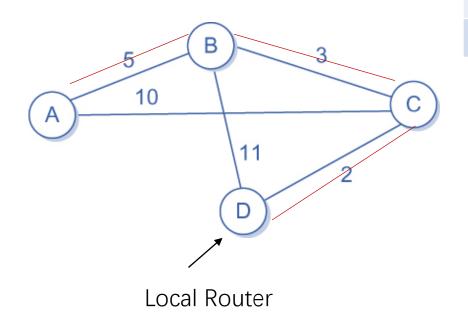
M	$D_{D}(A)$	$D_D(B)$	$D_D(C)$
{D}	Inf, from D	11, from D	2, from D



M	$D_{D}(A)$	$D_D(B)$	$D_D(C)$
[D}	Inf, from D	11, from D	2, from D
[D, C}	12, from C	5, from C	2, from D



M	$D_D(A)$	$D_D(B)$	$D_{D}(C)$
[D}	Inf, from D	11, from D	2, from D
[D, C}	12, from C	5, from C	2, from D
[D, C, B}	10, from B	5, from C	2, from D

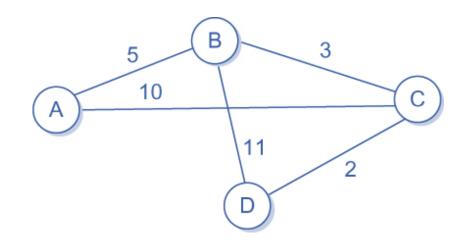


VI	$D_D(A)$	$D_D(B)$	$D_{\mathrm{D}}(C)$
D}	Inf, from D	11, from D	2, from D
D, C}	12, from C	5, from C	2, from D
D, C, B}	10, from B	5, from C	2, from D

#### Dijkstra's Algorithm (Another notation)

<Destination, Cost, Nexthop>

Step	Confirmed	Tentative
1	(D,0,-)	
2	(D,0,-)	(B,11,B) (C,2,C)
3	(D,0,-) (C,2,C)	(B,11,B)
4	(D,0,-) (C,2,C)	(B,5,C) (A,12,C)
5	(D,0,-) (C,2,C) (B,5,C)	(A,12,C)
6	(D,0,-) (C,2,C) (B,5,C)	(A,10,C)
7	(D,0,-) (C,2,C) (B,5,C) (A,10,C)	



#### Open Shortest Path First (OSPF)

- "Open": nonproprietary standard created under Engineering Task Force (IETF).
- Security: all OSPF messages authenticated (to prevent malicious intrusion)
- Hierarchical routing: OSPF in large domains
- Load balancing: multiple same-cost paths allowed (only one path in RIP)

#### Reference

• Textbook 3.3