

# Lecture 5-1 Geometry Operations and interpolation

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Course piazza link: [piazza.com/shanghaitech.edu.cn/spring2021/cs270spring2021](https://piazza.com/shanghaitech.edu.cn/spring2021/cs270spring2021)

# Outline

## ➤ Spatial Operations

- Affine transform (仿射变换)
- Projective transform

## ➤ Image interpolation

- Nearest-neighbor interpolation
- Linear & bi-linear interpolation

# Geometric operations

## ➤ Geometric

$$J(x, y) = I(T(x, y));$$

## ➤ Point operation

$$J(x, y) = T(I(x, y));$$

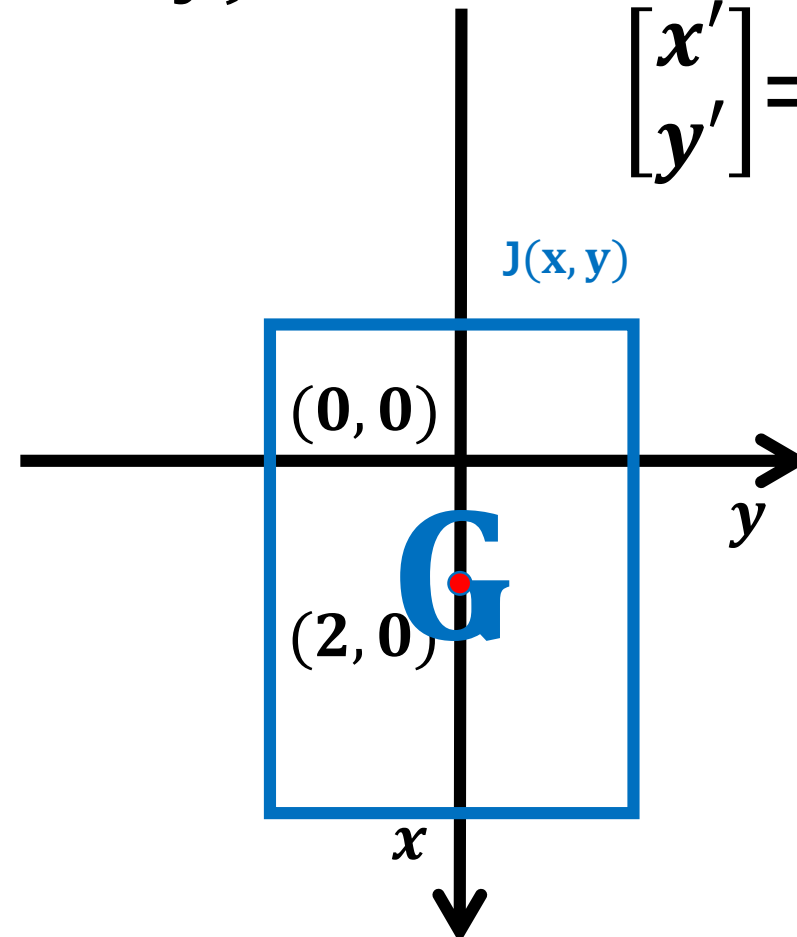
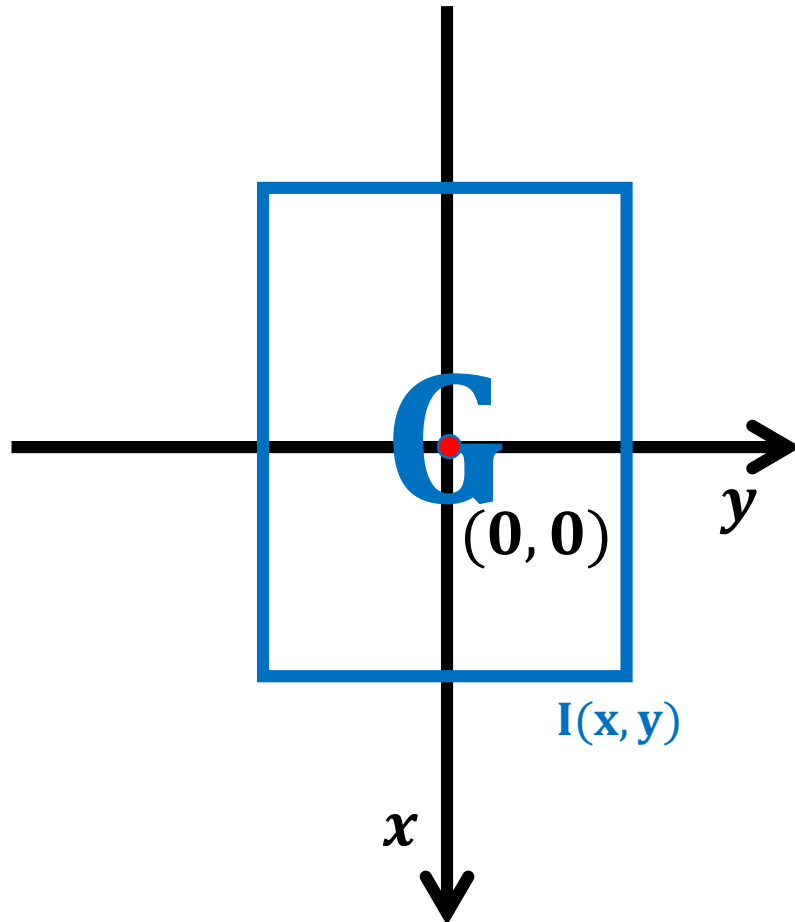
# Shift translation (Affine)

- Translate downwards by 2 pixels.

$$J(x, y) = I(x - 2, y)$$

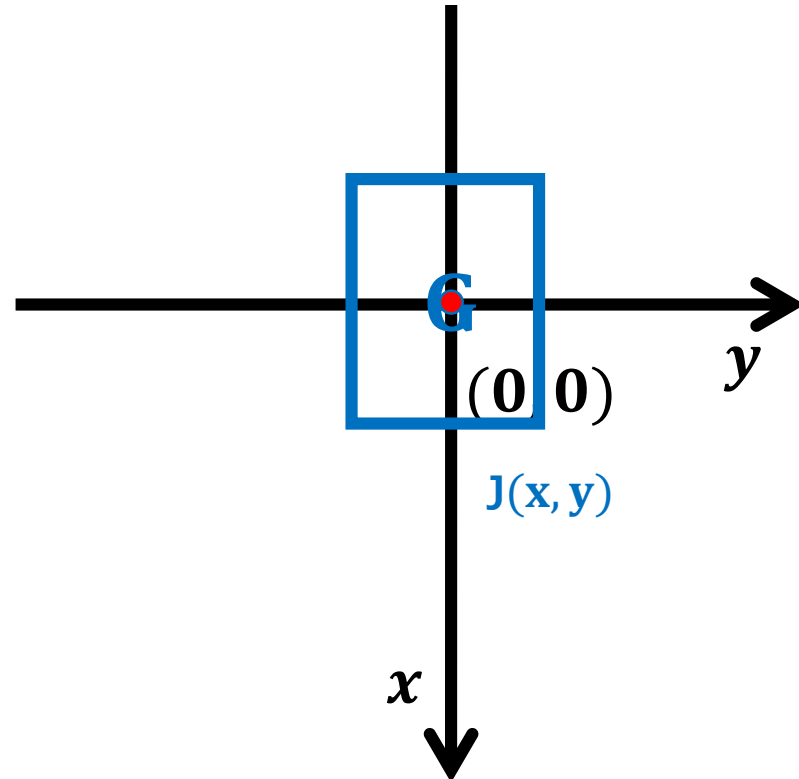
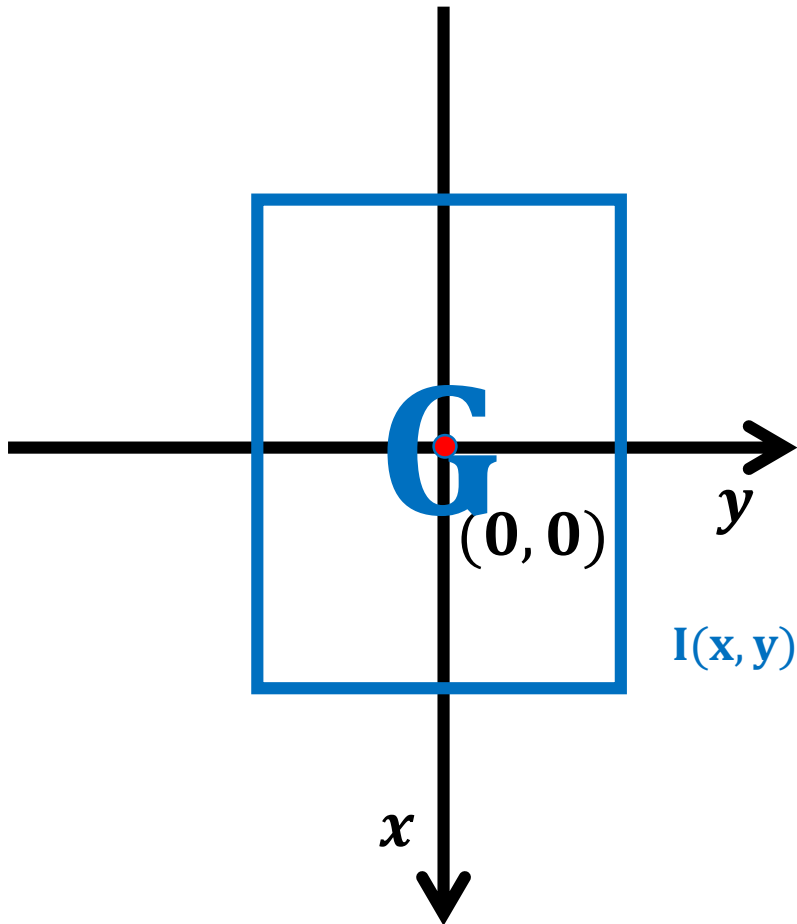
$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} x - 2 \\ y \end{bmatrix}$$

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$



# Scaling and translation

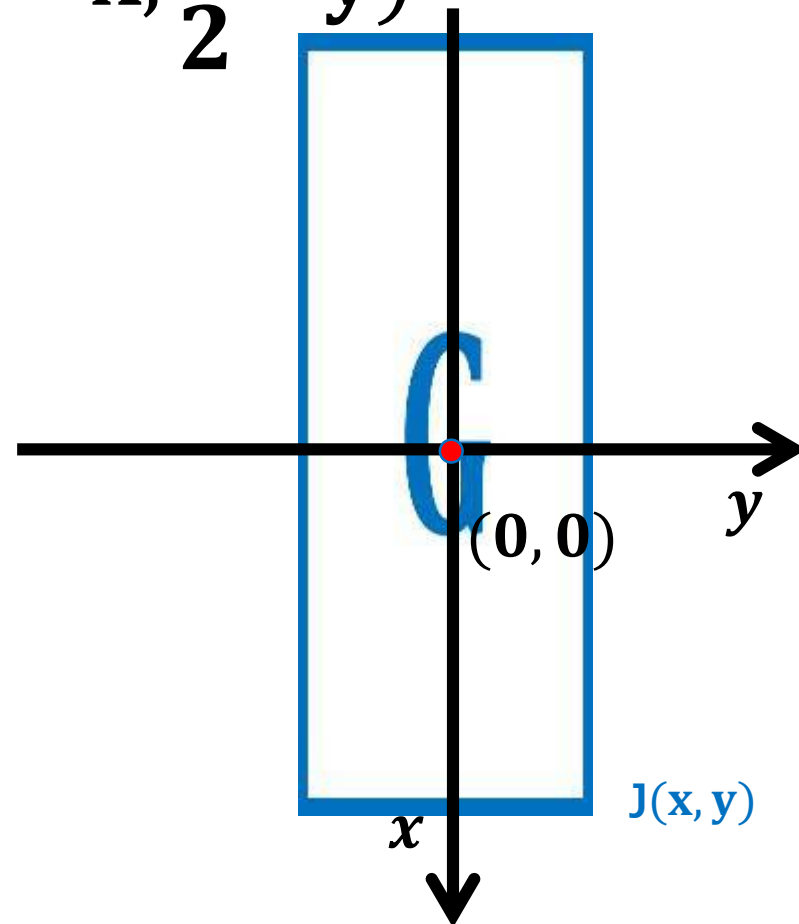
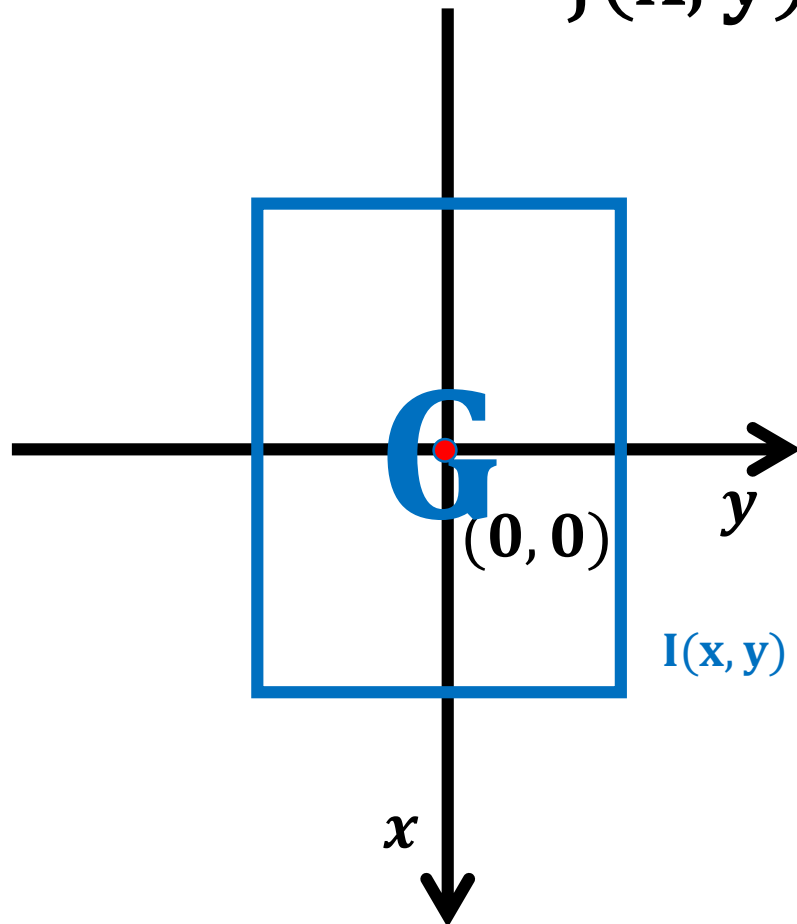
- Scale  $x$  and  $y$  by a factor of 2. 
$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 2 * x \\ 2 * y \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$



# Scaling and translation

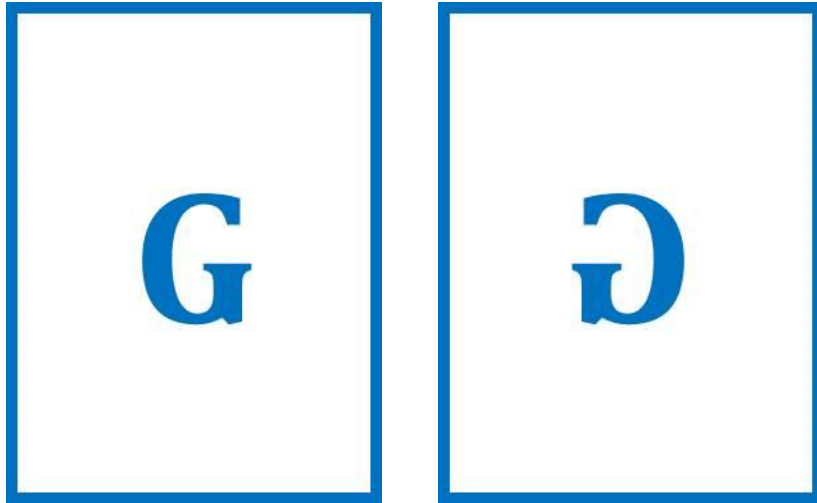
- Scale  $x$  and  $y$  by a factor of 2 and  $1/2$ , respectively.

$$J(\mathbf{x}, \mathbf{y}) = I(2 * \mathbf{x}, \frac{1}{2} * \mathbf{y})$$



# Flip translation

- $J(\mathbf{x}, \mathbf{y}) = I(\mathbf{x}, -\mathbf{y})$
- $J(\mathbf{x}, \mathbf{y}) = I(-\mathbf{x}, -\mathbf{y})$



$I(\mathbf{x}, \mathbf{y})$

$J(\mathbf{x}, \mathbf{y})$

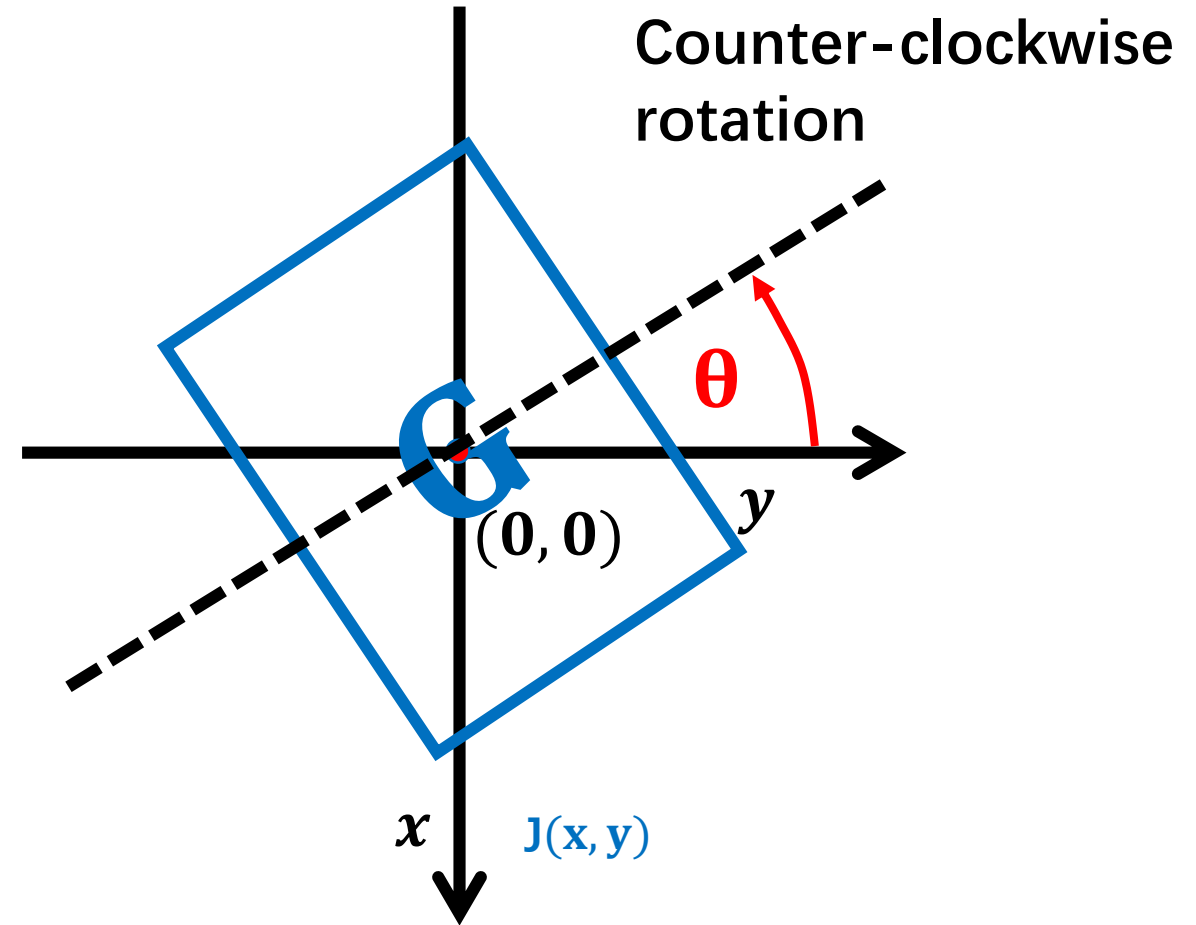
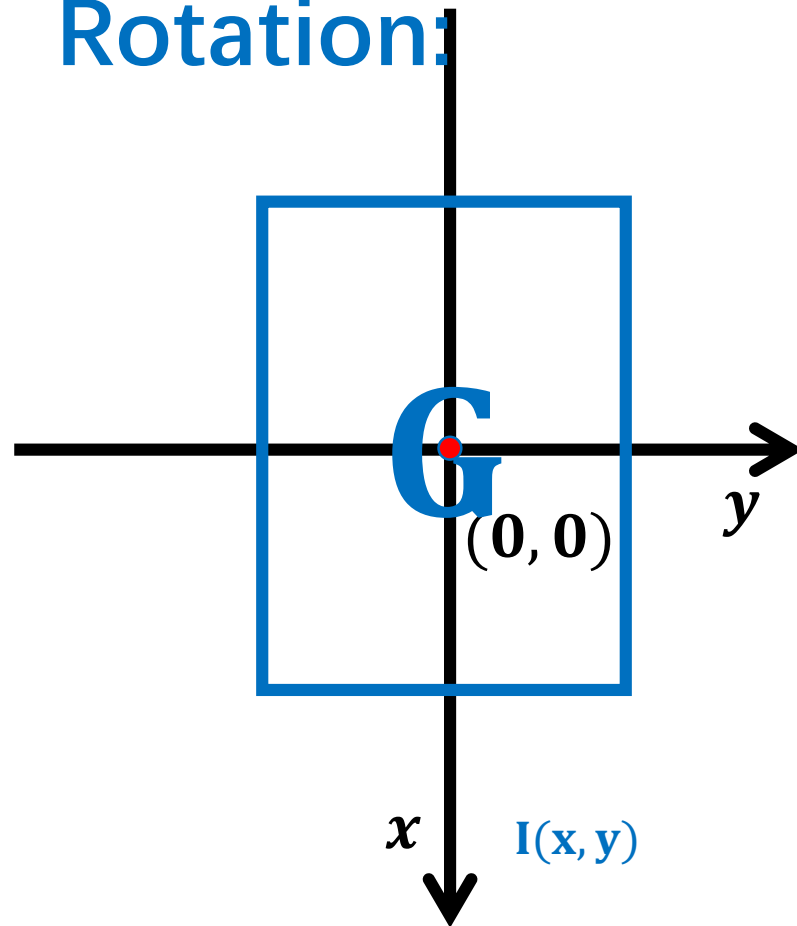


$I(\mathbf{x}, \mathbf{y})$

$J(\mathbf{x}, \mathbf{y})$

# Rotation Transform

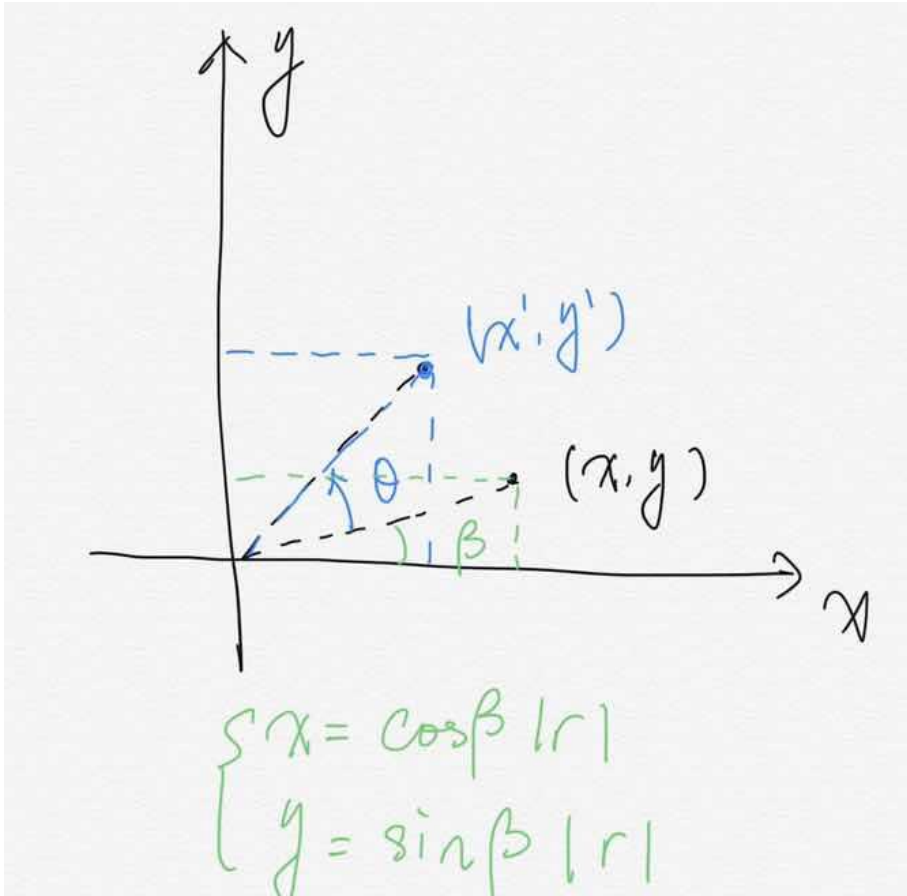
- Rotation:



Rigid body motion transform: **preserve shapes and angles.**



# Rotation Transform



$$x' = \cos(\theta + \beta) |r| = (\cos \theta \cos \beta - \sin \theta \sin \beta) |r|$$

$$y' = \sin(\theta + \beta) |r| = (\sin \theta \cos \beta + \cos \theta \sin \beta) |r|$$



$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

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Rotation matrix

# 2D Linear Transform

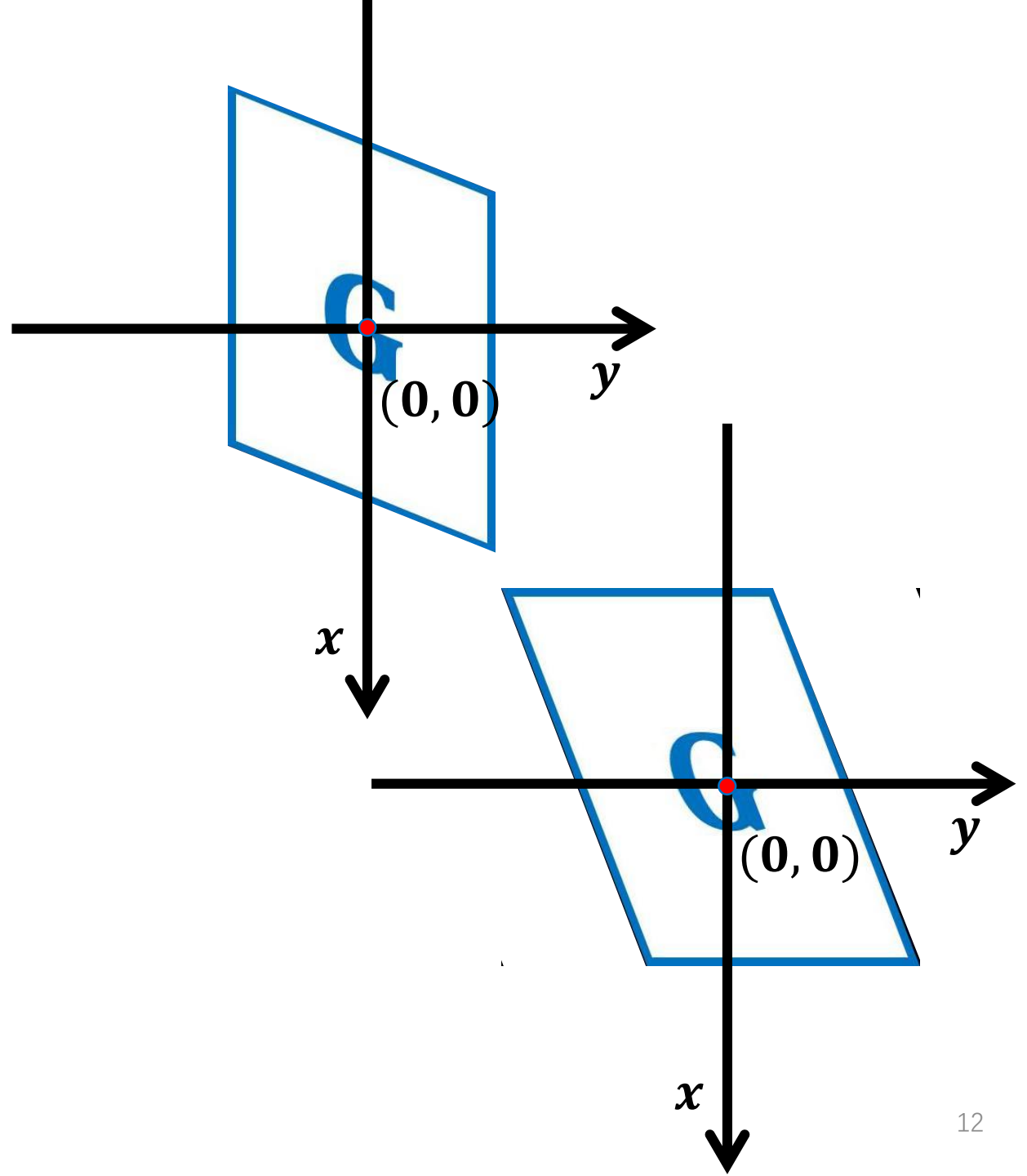
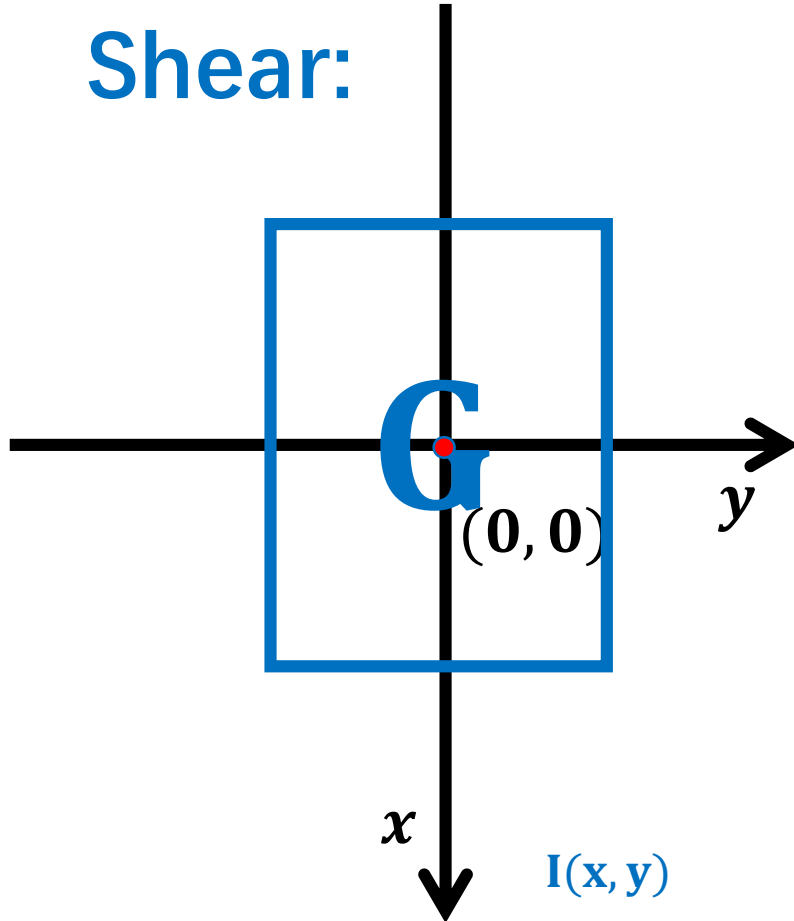
- It is common for **scale + rotate + shift** to be considered into a 2D linear transformation.

$$\begin{array}{c} \begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} * \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} shift_x \\ shift_y \end{bmatrix} \\ \uparrow \qquad \qquad \qquad \uparrow \\ J(x, y) \qquad \qquad I(x, y) \end{array}$$

# 2D Linear Transform

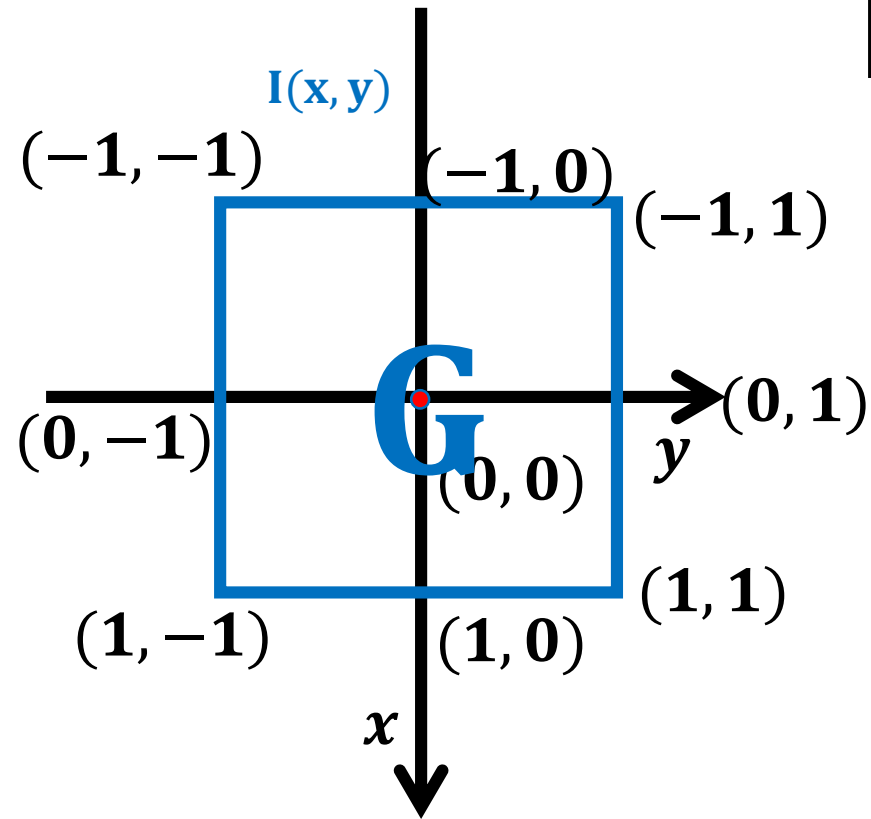
- **Scale:** 
$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix} * \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
- **Rotate:** 
$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} * \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
- **Shift:** 
$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} * \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} shift_x \\ shift_y \end{bmatrix}$$

- Shear:

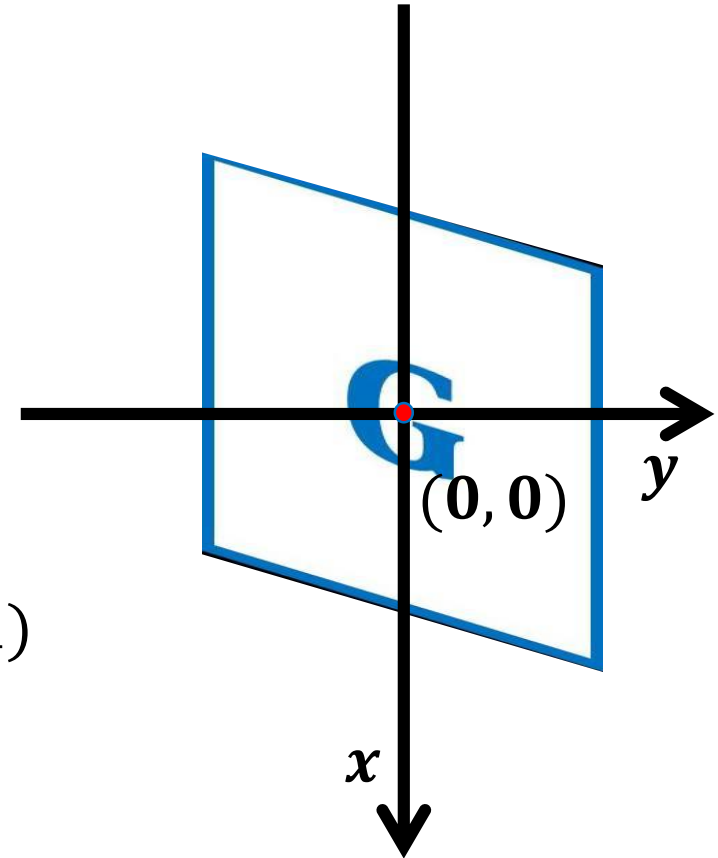


# Shear in x-axis

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 1 & b \\ 0 & 1 \end{bmatrix} * \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

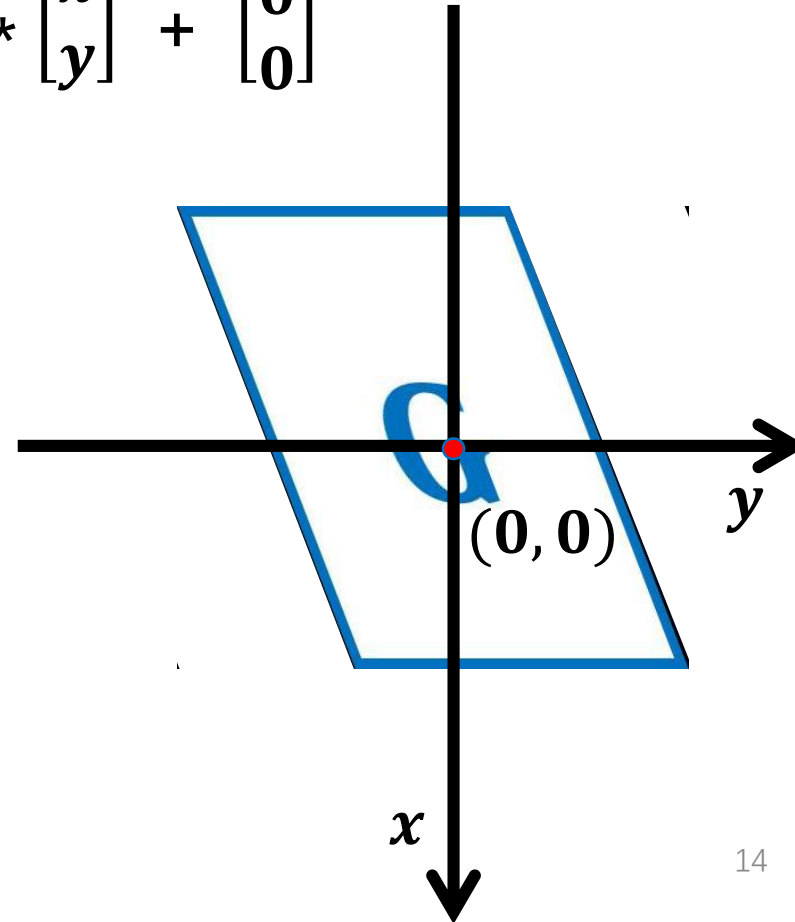
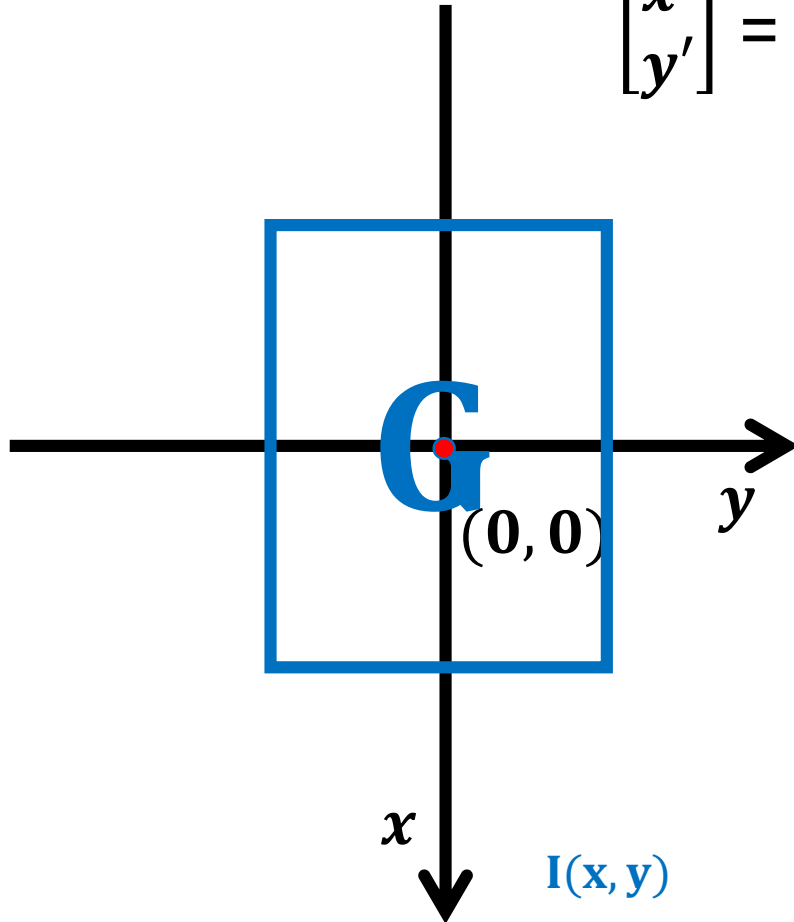


$$\begin{array}{l} (1, 0) \rightarrow (1, 0) \\ (0, 0) \rightarrow (0, 0) \\ (-1, 0) \rightarrow (-1, 0) \\ \hline (1, -1) \rightarrow (1 - b, -1) \\ (-1, -1) \rightarrow (-1 - b, -1) \\ (0, -1) \rightarrow (-b, -1) \\ \hline (1, 1) \rightarrow (b + 1, 1) \\ (0, 1) \rightarrow (b, 1) \\ (-1, 1) \rightarrow (b - 1, 1) \end{array}$$



# Shear in y-axis

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ b & 1 \end{bmatrix} * \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$



$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} * \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} shift_x \\ shift_y \end{bmatrix}$$

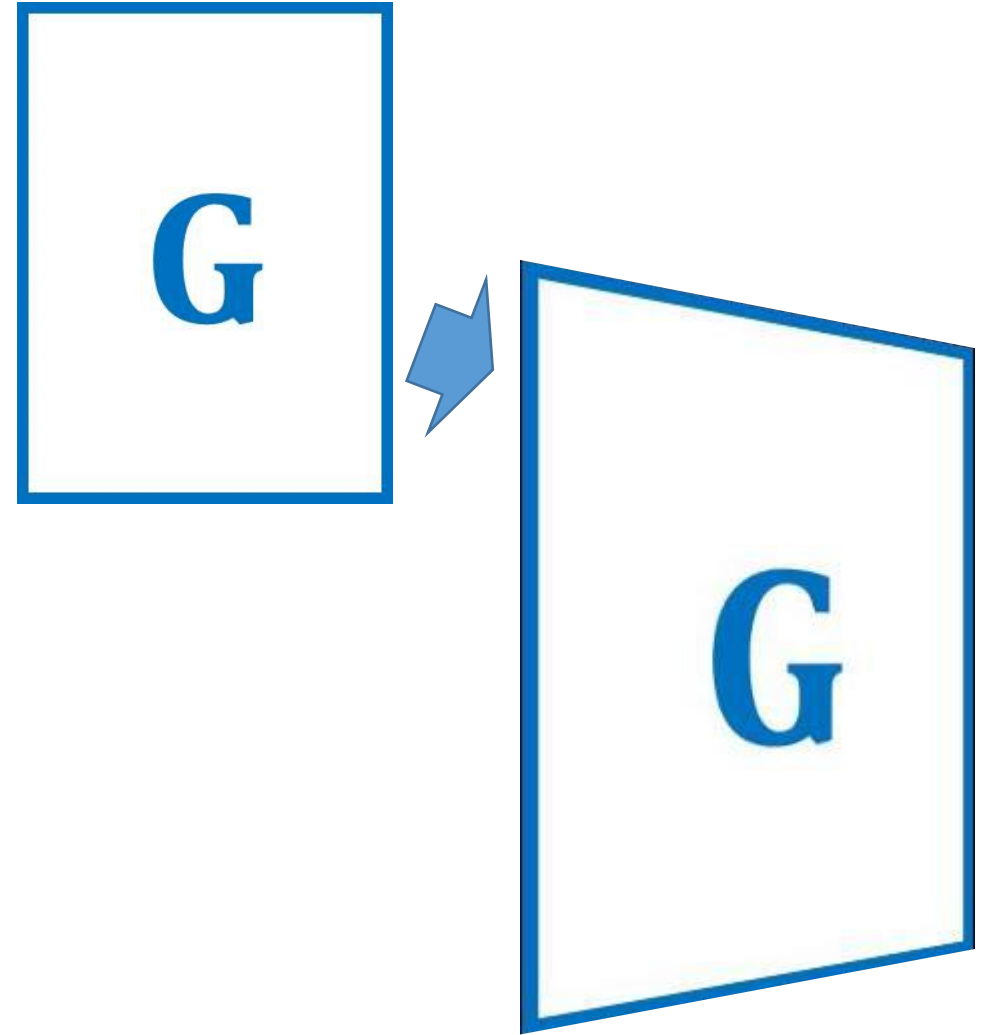
# 2D Linear Transform

$$\begin{array}{c} \begin{bmatrix} x' \\ y' \end{bmatrix} \\ \uparrow \\ \mathbf{J}(\mathbf{x}, \mathbf{y}) \end{array} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} * \begin{array}{c} \begin{bmatrix} x \\ y \end{bmatrix} \\ \uparrow \\ \mathbf{I}(\mathbf{x}, \mathbf{y}) \end{array} + \begin{bmatrix} shift_x \\ shift_y \end{bmatrix}$$

- Rotation, Scaling, Shifting are all restricted 2D linear transform and are combined as rigid body transform.
- Shear transform preserves parallel lines from the original image.
- Shear + Rotation+ Scaling+ Shifting combined all the 2D linear/affine transform. (DOF = 6)

# Projective Transform

- $$\begin{bmatrix} \tilde{x}' \\ \tilde{y}' \\ \tilde{z}' \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & b_1 \\ a_{21} & a_{22} & b_2 \\ c_1 & c_2 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$



- $$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \frac{a_{11}x + a_{12}y + b_1}{c_1x + c_2y + 1} \\ \frac{a_{21}x + a_{22}y + b_2}{c_1x + c_2y + 1} \end{bmatrix} = \begin{bmatrix} \frac{\tilde{x}'}{\tilde{z}'} \\ \frac{\tilde{y}'}{\tilde{z}'} \end{bmatrix}$$



# Matlab commands

- `A = [1 0 0; 0.4 1 0; 0 0 1]; % vertical shear`
- `tf = affine2d(A);`
- `im2 = imwarp(im,tf);`
- `figure;imshow(im2);`

# Practice

- Using the zombie.jpg image, make a transform with  $35^\circ$  clock-wise rotation, 0.6 scaling and 50 shift on X-axial; 0.8 scaling and 15 shift on Y-axial.

# Outline

## ➤ Spatial Operations

- Affine transform (仿射变换)
- Projective transform

## ➤ Image interpolation

- Nearest-neighbor interpolation
- Linear & bi-linear interpolation

## A real example

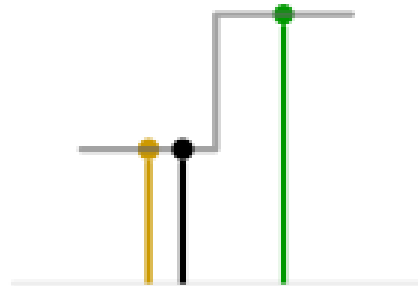
- $$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} * \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} shift_x \\ shift_y \end{bmatrix}$$

$a = 1.2, b = 1, c = 1, d = 0.8, shift_x = 3.2,$   
 $shift_y = -1.6$

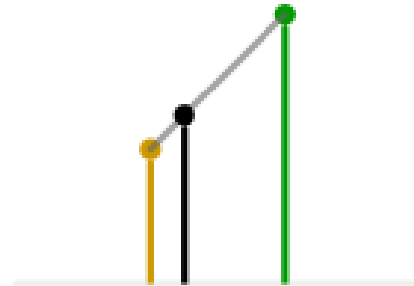
- $$\begin{bmatrix} 1 \\ 1 \end{bmatrix} \rightarrow \begin{bmatrix} 5.4 \\ 0.2 \end{bmatrix}$$

- Coordinate is not integer!! Then how to determinate intensity?

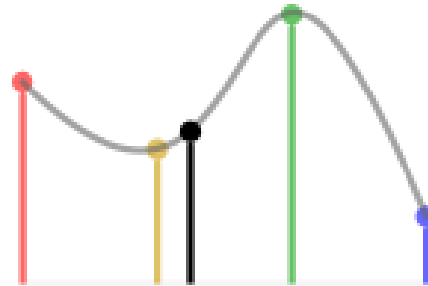
# Interpolation



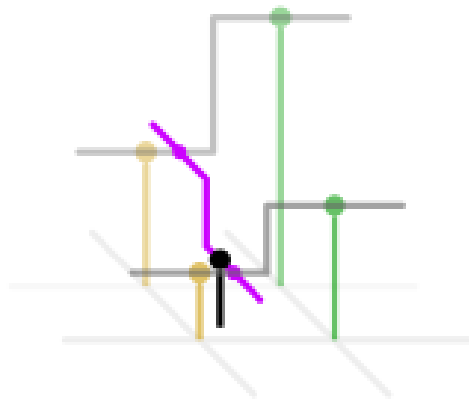
1D nearest-neighbour



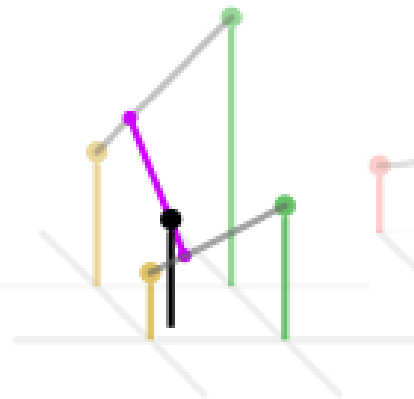
Linear



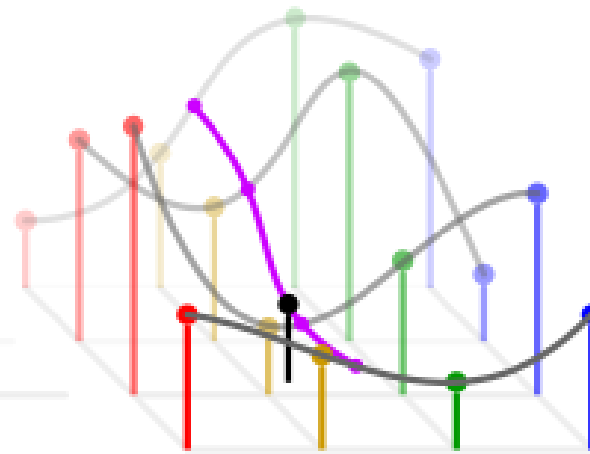
Cubic



2D nearest-neighbour

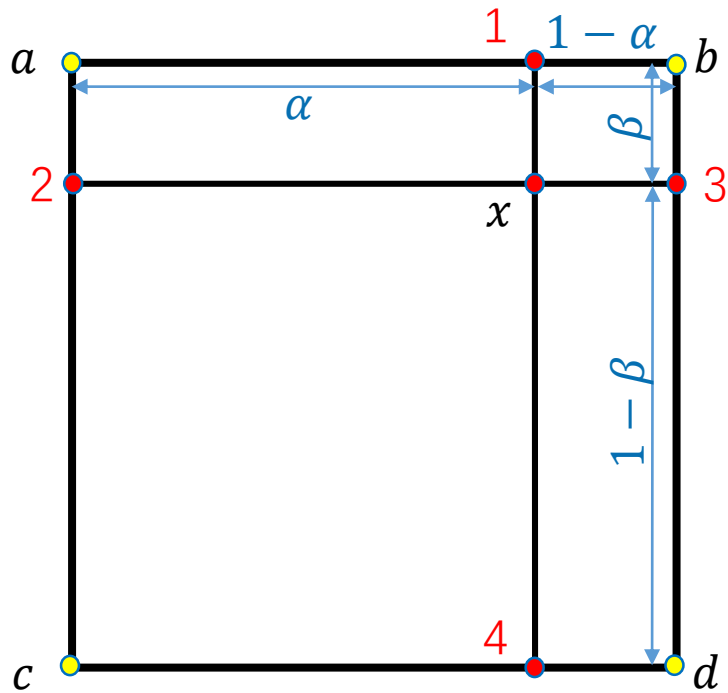


Bilinear



Bicubic

# Bilinear interpolation



$$x_{①} = (1-\alpha)a + \alpha \cdot b \quad \text{or} \quad \alpha \cdot a + (1-\alpha)b \quad ?$$

if  $\alpha = 0.7$

$$x_{②} = (1-\beta)a + \beta \cdot c$$

$$x_{③} = (1-\beta)b + \beta \cdot d$$

$$x_{④} = (1-\alpha)c + \alpha \cdot d$$

$$x = (1-\beta) \cdot x_{①} + \beta \cdot x_{④}$$

$$\text{or} = (1-\alpha)x_{②} + \alpha \cdot x_{③}$$

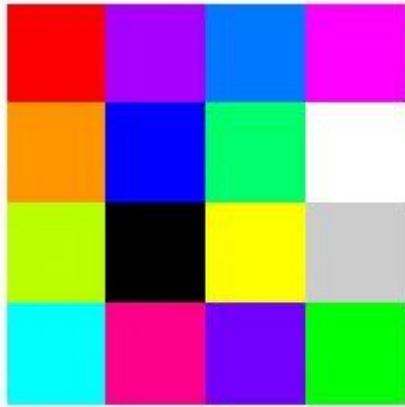
$$= (1-\beta)[(1-\alpha)a + \alpha b] + \beta[(1-\alpha)c + \alpha d]$$

$$= (1-\beta)(1-\alpha) \cdot a + \alpha(1-\beta)b + \beta(1-\alpha)c + \alpha\beta \cdot d$$

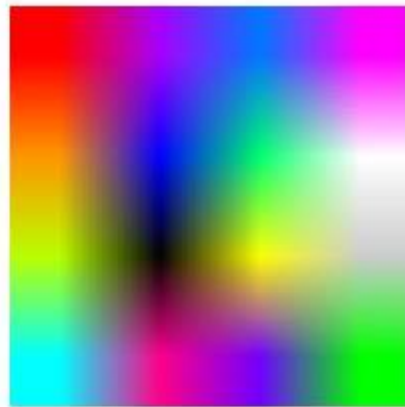
$$\alpha = 0.7, \beta = 0.2$$

$$= 0.24a + 0.56b + 0.06c + 0.14d$$

# Nearest-neighbor vs Bilinear vs Bicubic interpolation



Nearest neighbor



Bilinear



Bicubic



# Image Registration

- To align two or more images of the same scene
- Given input and output images, to estimate the transformation functions and then use it to register the two images

Image 1

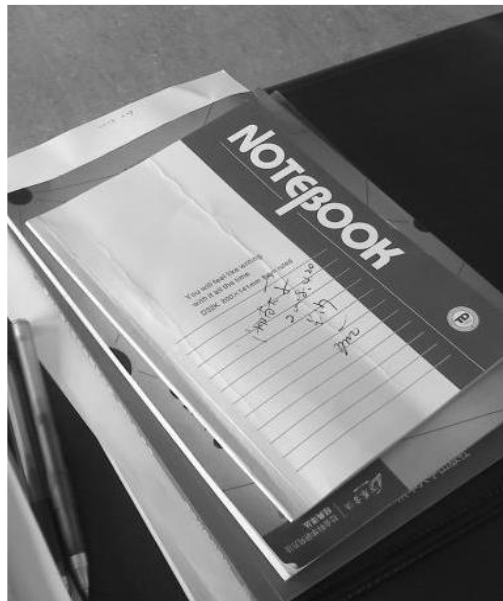
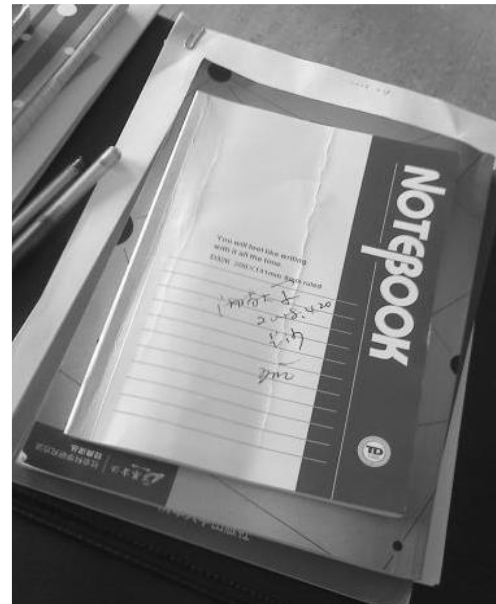
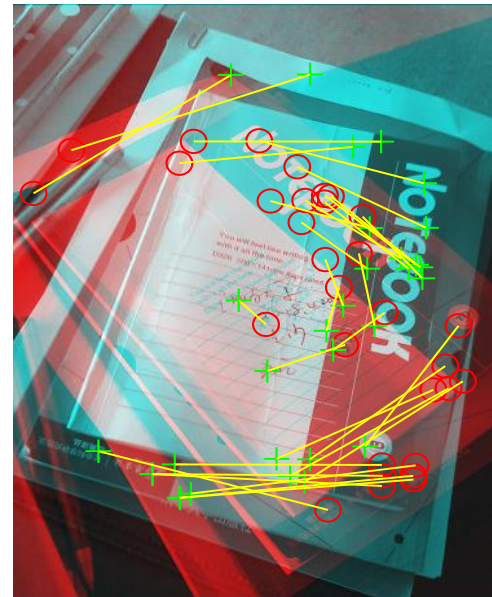


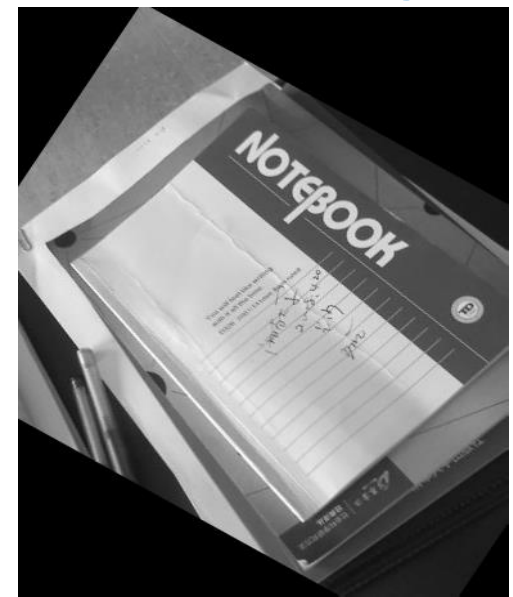
Image 2



Key points  
matching



Estimated  
rotated image





# SIFT- Scale Invariant Feature Transform

## Approach:

- Create a scale space of images
  - Construct a set of progressive Gaussian blurred images
  - Take the differences to get a difference of Gaussian pyramid (like a Laplacian)
- Find local extrema in this space. Choose the key points from extrema.
- For each key point, in a 16x16 window, find the histograms of gradient directions
- Create a feature vector out of these.

# Take home message

- Spatial transform: how does parameter effect on special transform. Rigid-body, shear, projective.
- Interpolation: To look like the nearest-neighbors and to involve more close-by neighbors.