# Discussion0413

Yuyan Zhou

## MLE estimate of $\theta_{s|ij}$ from fully observed data

#### Maximum likelihood estimate

$$\theta \leftarrow \arg\max_{\theta} \log P(data|\theta)$$



$$P(data|\theta) = \prod_{k=1}^{K} P(f_k, a_k, s_k, h_k, n_k)$$

$$P(data|\theta) = \prod_{k=1}^{K} P(f_k)P(a_k)P(s_k|f_ka_k)P(h_k|s_k)P(n_k|s_k)$$

$$\log P(data|\theta) = \sum_{k=1}^K \log P(f_k) + \log P(a_k) + \log P(s_k|f_ka_k) + \log P(h_k|s_k) + \log P(n_k|s_k)$$

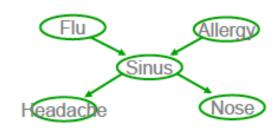
$$\frac{\partial \log P(data|\theta)}{\partial \theta_{s|ij}} = \sum_{k=1}^K \frac{\partial \log P(s_k|f_k a_k)}{\partial \theta_{s|ij}}$$

$$\theta_{s|ij} = \frac{\sum_{k=1}^{K} \delta(f_k = i, a_k = j, s_k = 1)}{\sum_{k=1}^{K} \delta(f_k = i, a_k = j)}$$

### Estimate $\theta$ from partly observed data

- What if FAHN observed, but not S?
- Can't calculate MLE

$$\theta \leftarrow \arg\max_{\theta} \log\prod_{k} P(f_k, a_k, s_k, h_k, n_k | \theta)$$



- Let X be all observed variable values (over all examples)
- Let Z be all unobserved variable values
- Can't calculate MLE:

$$\theta \leftarrow \arg\max_{\theta} \log P(X, Z|\theta)$$

EM seeks\* to estimate:

$$\theta \leftarrow \arg\max_{\theta} E_{Z|X,\theta}[\log P(X,Z|\theta)]$$

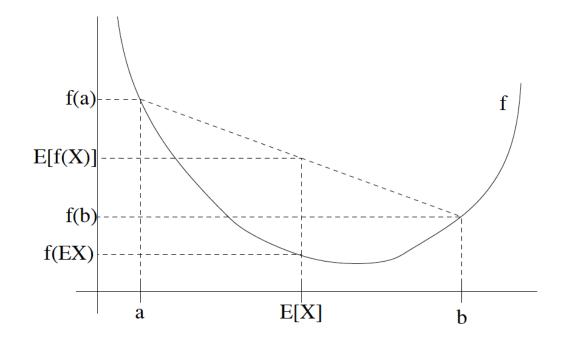
\* EM guaranteed to find local maximum

## Jensen's Inequality

**Theorem.** Let f be a convex function, and let X be a random variable. Then:

$$E[f(X)] \ge f(EX).$$

Moreover, if f is strictly convex, then E[f(X)] = f(EX) holds true if and only if X = E[X] with probability 1 (i.e., if X is a constant).



## Concavity of log function

$$\sum_{i} \log p(x^{(i)}; \theta) = \sum_{i} \log \sum_{z^{(i)}} p(x^{(i)}, z^{(i)}; \theta)$$

$$= \sum_{i} \log \sum_{z^{(i)}} Q_{i}(z^{(i)}) \frac{p(x^{(i)}, z^{(i)}; \theta)}{Q_{i}(z^{(i)})}$$

$$\geq \sum_{i} \sum_{z^{(i)}} Q_{i}(z^{(i)}) \log \frac{p(x^{(i)}, z^{(i)}; \theta)}{Q_{i}(z^{(i)})}$$

## EM algorithm

Initialize  $\theta$ Repeat

(E-step) For each i, set

$$Q_i(z^{(i)}) := p(z^{(i)}|x^{(i)};\theta).$$

(M-step) Set

$$\theta := \arg \max_{\theta} \sum_{i} \sum_{z^{(i)}} Q_i(z^{(i)}) \log \frac{p(x^{(i)}, z^{(i)}; \theta)}{Q_i(z^{(i)})}.$$

Until convergence

## Why EM guaranteed to find local maximum

• We will prove  $l(\theta^{t+1}) \ge l(\theta^t)$ 

$$\ell(\theta^{(t+1)}) \geq \sum_{i} \sum_{z^{(i)}} Q_i^{(t)}(z^{(i)}) \log \frac{p(x^{(i)}, z^{(i)}; \theta^{(t+1)})}{Q_i^{(t)}(z^{(i)})}$$

$$\geq \sum_{i} \sum_{z^{(i)}} Q_i^{(t)}(z^{(i)}) \log \frac{p(x^{(i)}, z^{(i)}; \theta^{(t)})}{Q_i^{(t)}(z^{(i)})}$$

$$= \ell(\theta^{(t)})$$

## Why EM not suitable for continuous Z

$$Q_{i}(z^{(i)}) = \frac{p(x^{(i)}, z^{(i)}; \theta)}{\sum_{z} p(x^{(i)}, z; \theta)}$$

$$= \frac{p(x^{(i)}, z^{(i)}; \theta)}{p(x^{(i)}; \theta)}$$

$$= p(z^{(i)}|x^{(i)}; \theta)$$

#### Mixture Distributions

Model joint  $P(X_1 \dots X_n)$  as mixture of multiple distributions.

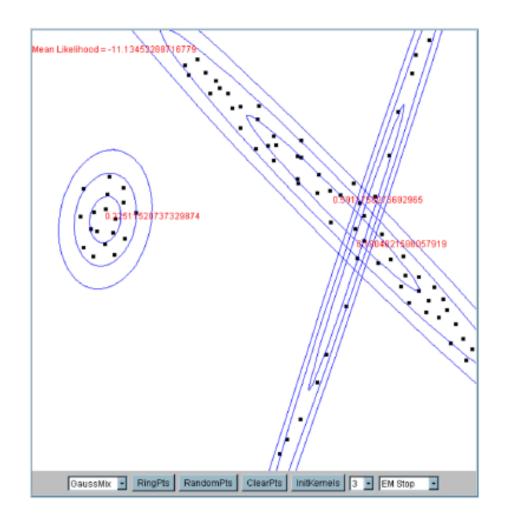
Use discrete-valued random var Z to indicate which distribution is being use for each random draw

So 
$$P(X_1 \dots X_n) = \sum_i P(Z=i) \ P(X_1 \dots X_n|Z)$$

#### Mixture of Gaussians:

- Assume each data point X=<X1, ... Xn> is generated by one of several Gaussians, as follows:
- 1. randomly choose Gaussian i, according to P(Z=i)
- 2. randomly generate a data point  $\langle x1, x2 ... xn \rangle$  according to  $N(\mu_i, \Sigma_i)$

### Mixture of Gaussians



### EM for Mixture of Gaussian Clustering

Let's simplify to make this easier:

 assume X=<X<sub>1</sub> ... X<sub>n</sub>>, and the X<sub>i</sub> are conditionally independent given Z.

$$P(X|Z=j) = \prod_{i} N(X_i|\mu_{ji}, \sigma_{ji})$$

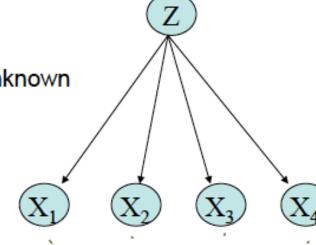
2. assume only 2 clusters (values of Z), and  $\forall i, j, \sigma_{ji} = \sigma$ 

$$P(\mathbf{X}) = \sum_{j=1}^{2} P(Z=j|\pi) \prod_{i} N(x_i|\mu_{ji}, \sigma)$$

3. Assume  $\sigma$  known,  $\pi_l \dots \pi_{K_l} \mu_{li} \dots \mu_{Ki}$  unknown

Observed:  $X = \langle X_1 \dots X_n \rangle$ 

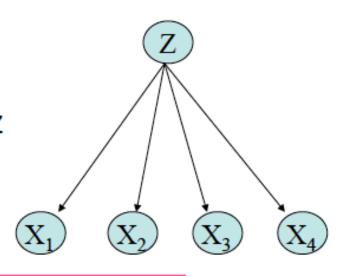
Unobserved: Z



#### EM

Given observed variables X, unobserved Z

Define 
$$Q(\theta'|\theta) = E_{Z|X,\theta}[\log P(X,Z|\theta')]$$
 where  $\theta = \langle \pi, \mu_{ji} \rangle$ 



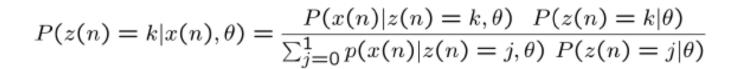
#### Iterate until convergence:

- E Step: Calculate  $P(Z(n)|X(n),\theta)$  for each example X(n). Use this to construct  $Q(\theta'|\theta)$
- M Step: Replace current  $\theta$  by  $\theta \leftarrow \arg\max_{\theta'} Q(\theta'|\theta)$

## EM – E Step

Calculate  $P(Z(n)|X(n),\theta)$  for each observed example X(n)

$$X(n) = \langle x_1(n), x_2(n), \dots x_T(n) \rangle.$$



$$P(z(n) = k|x(n), \theta) = \frac{\prod_{i} P(x_i(n)|z(n) = k, \theta)] P(z(n) = k|\theta)}{\sum_{j=0}^{1} \prod_{i} P(x_i(n)|z(n) = j, \theta) P(z(n) = j|\theta)}$$

$$P(z(n) = k|x(n), \theta) = \frac{\prod_{i} N(x_i(n)|\mu_{k,i}, \sigma)] (\pi^k (1 - \pi)^{(1-k)})}{\sum_{j=0}^{1} [\prod_{i} N(x_i(n)|\mu_{j,i}, \sigma)] (\pi^j (1 - \pi)^{(1-j)})}$$

First consider update for  $\pi$ 

EM - M Step

 $Q(\theta'|\theta) = E_{Z|X,\theta}[\log P(X,Z|\theta')] = E[\log P(X|Z,\theta') + \log P(Z|\theta')]$ 

π' has no influence

$$\pi \leftarrow \arg \max_{\pi'} E_{Z|X,\theta}[\log P(Z|\pi')]$$

z=1 for nth example

$$E_{Z|X,\theta}\left[\log P(Z|\pi')\right] = E_{Z|X,\theta}\left[\log \left(\pi'^{\sum_{n} z(n)} (1-\pi')^{\sum_{n} (1-z(n))}\right)\right]$$

 $\theta = \langle \pi, \mu_{ji} \rangle$ 

$$=E_{Z|X, heta}\left[\left(\sum_n z(n)
ight)\log \pi' + \left(\sum_n (1-z(n))
ight)\log (1-\pi')
ight]$$

$$= \left(\sum_n E_{Z|X,\theta}[z(n)]\right) \log \pi' + \left(\sum_n E_{Z|X,\theta}[(1-z(n)])\right) \log (1-\pi')$$

$$\frac{\partial E_{Z|X,\theta}[\log P(Z|\pi')]}{\partial \pi'} = \left(\sum_n E_{Z|X,\theta}[z(n)]\right) \frac{1}{\pi'} + \left(\sum_n E_{Z|X,\theta}[(1-z(n)])\right) \frac{(-1)}{1-\pi'}$$

$$\pi \leftarrow \frac{\sum_{n=1}^{N} E[z(n)]}{\left(\sum_{n=1}^{N} E[z(n)]\right) + \left(\sum_{n=1}^{N} (1 - E[z(n)])\right)} = \frac{1}{N} \sum_{n=1}^{N} E[z(n)]$$

First consider update for π

EM - M Step

 $Q(\theta'|\theta) = E_{Z|X,\theta}[\log P(X,Z|\theta')] = E[\log P(X|Z,\theta') + \log P(Z|\theta')]$ 

π' has no influence

$$\pi \leftarrow \arg \max_{\pi'} E_{Z|X,\theta}[\log P(Z|\pi')]$$

z=1 for nth example



 $\theta = \langle \pi, \mu_{ji} \rangle$ 

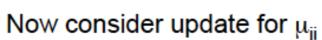
$$E_{Z|X,\theta}\left[\log P(Z|\pi')\right] = E_{Z|X,\theta}\left[\log\left(\pi'^{\sum_{n} z(n)}(1-\pi')^{\sum_{n}(1-z(n))}\right)\right]$$

$$= E_{Z|X,\theta} \left[ \left( \sum_{n} z(n) \right) \log \pi' + \left( \sum_{n} (1 - z(n)) \right) \log (1 - \pi') \right]$$

$$= \left(\sum_n E_{Z|X,\theta}[z(n)]\right) \log \pi' + \left(\sum_n E_{Z|X,\theta}[(1-z(n)])\right) \log (1-\pi')$$

$$\frac{\partial E_{Z|X,\theta}[\log P(Z|\pi')]}{\partial \pi'} = \left(\sum_n E_{Z|X,\theta}[z(n)]\right) \frac{1}{\pi'} + \left(\sum_n E_{Z|X,\theta}[(1-z(n)])\right) \frac{(-1)}{1-\pi'}$$

$$\pi \leftarrow \frac{\sum_{n=1}^{N} E[z(n)]}{\left(\sum_{n=1}^{N} E[z(n)]\right) + \left(\sum_{n=1}^{N} (1 - E[z(n)])\right)} = \frac{1}{N} \sum_{n=1}^{N} E[z(n)]$$





 $\theta = \langle \pi, \mu_{ji} \rangle$ 

 $Q(\theta'|\theta) = E_{Z|X,\theta}[\log P(X,Z|\theta')] = E[\log P(X|Z,\theta') + \log P(Z|\theta')]$ 

 $\mu_{ji}{}^{\prime}$  has no influence

$$\mu_{ji} \leftarrow \arg\max_{\mu'_{ji}} E_{Z|X,\theta}[\log P(X|Z,\theta')]$$

...

$$\mu_{ji} \leftarrow \frac{\sum_{n=1}^{N} P(z(n) = j | x(n), \theta) \quad x_i(n)}{\sum_{n=1}^{N} P(z(n) = j | x(n), \theta)}$$

Compare above to MLE if Z were observable:

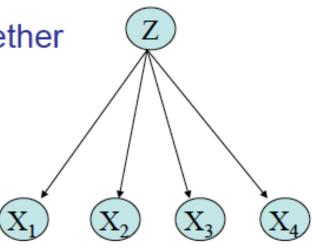
$$\mu_{ji} \leftarrow \frac{\sum_{n=1}^{N} \delta(z(n) = j) \quad x_i(n)}{\sum_{n=1}^{N} \delta(z(n) = j)}$$

.

### EM – putting it together

Given observed variables X, unobserved Z

Define 
$$Q(\theta'|\theta) = E_{Z|X,\theta}[\log P(X,Z|\theta')]$$
  
where  $\theta = \langle \pi, \mu_{ji} \rangle$ 



#### Iterate until convergence:

• E Step: For each observed example X(n), calculate  $P(Z(n)|X(n),\theta)$ 

$$P(z(n) = k \mid x(n), \theta) = \frac{\left[\prod_{i} N(x_{i}(n) \mid \mu_{k,i}, \sigma)\right] (\pi^{k} (1 - \pi)^{(1 - k)})}{\sum_{j=0}^{1} \left[\prod_{i} N(x_{i}(n) \mid \mu_{j,i}, \sigma)\right] (\pi^{j} (1 - \pi)^{(1 - j)})}$$

• M Step: Update  $\theta \leftarrow \arg \max_{\theta'} Q(\theta'|\theta)$ 

### How can we learn Bayes Net graph structure?

#### In general case, open problem

- can require lots of data (else high risk of overfitting)
- can use Bayesian methods to constrain search

#### One key result:

- Chow-Liu algorithm: finds "best" tree-structured network
- What's best?
  - suppose P(X) is true distribution, T(X) is our tree-structured network, where X = <X<sub>1</sub>, ... X<sub>n</sub>>
  - Chow-Liu minimizes Kullback-Leibler divergence:

$$KL(P(\mathbf{X}) \mid\mid T(\mathbf{X})) \equiv \sum_{k} P(\mathbf{X} = k) \log \frac{P(\mathbf{X} = k)}{T(\mathbf{X} = k)}$$

### Chow-Liu Algorithm

Key result: To minimize KL(P || T), it suffices to find the tree network T that maximizes the sum of mutual informations over its edges

Mutual information for an edge between variable A and B:

$$I(A,B) = \sum_{a} \sum_{b} P(a,b) \log \frac{P(a,b)}{P(a)P(b)}$$

This works because for tree networks with nodes  $\mathbf{X} \equiv \langle X_1 \dots X_n \rangle$ 

$$KL(P(\mathbf{X}) \mid\mid T(\mathbf{X})) \equiv \sum_{k} P(\mathbf{X} = k) \log \frac{P(\mathbf{X} = k)}{T(\mathbf{X} = k)}$$
$$= -\sum_{i} I(X_{i}, Pa(X_{i})) + \sum_{i} H(X_{i}) - H(X_{1} \dots X_{n})$$

## THANKS