<u>Lecture 7 – Image Reconstruction(图像重建)</u>

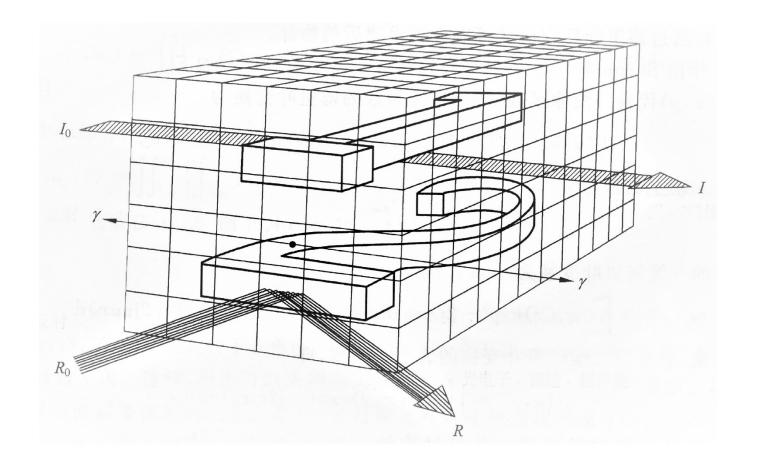
This lecture will cover:

- Reconstruction modalities (重建模式)
- Reconstruction from projection (投影重建算法)
 - Computed Tomography (计算机断层成像)
 - Radon transform (雷登变换)
 - The Fourier-Slice Theorem (傅里叶切片定理)
 - Parallel-Beam Filtered Backprojections (平行射线束滤波反投影)
 - Fan-Beam Filtered Backprojections(扇形射线束滤波反投影)
- Reflection imaging
 - Time of flight
 - Born Approximation and Inverse theory(玻恩近似与反演理论)



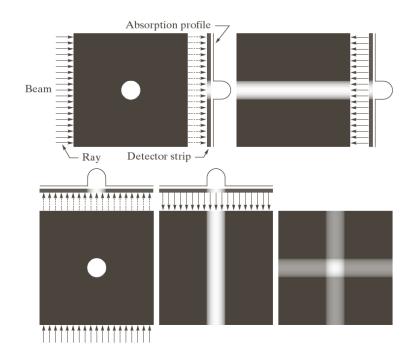
Reconstruction Modalities

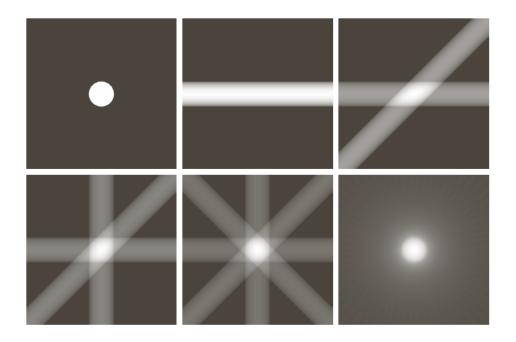
- > Transmission
- **Emission**
- Reflection





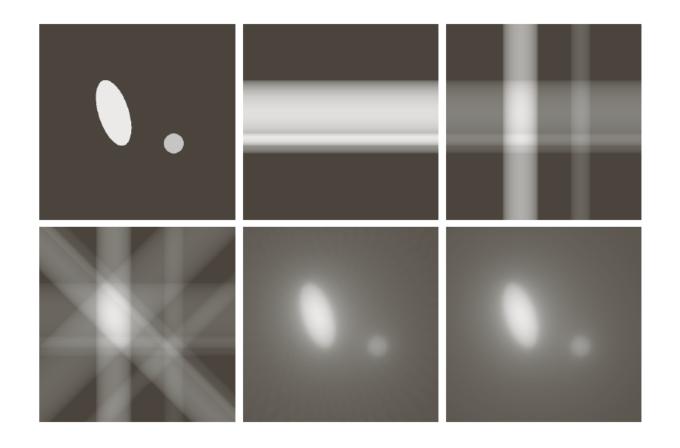
Back Projection





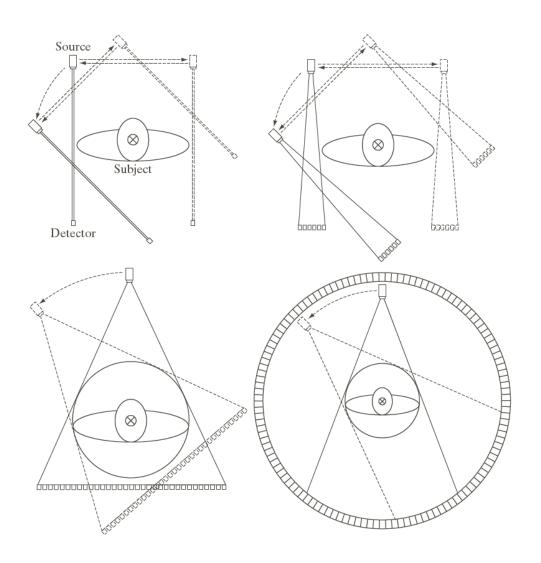


Back Projection





Computed Tomography





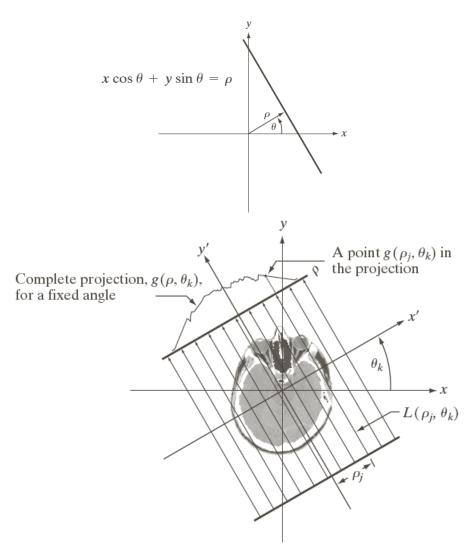
Radon Transform

Normal representation for a line:

$$x\cos\theta + y\sin\theta = \rho$$

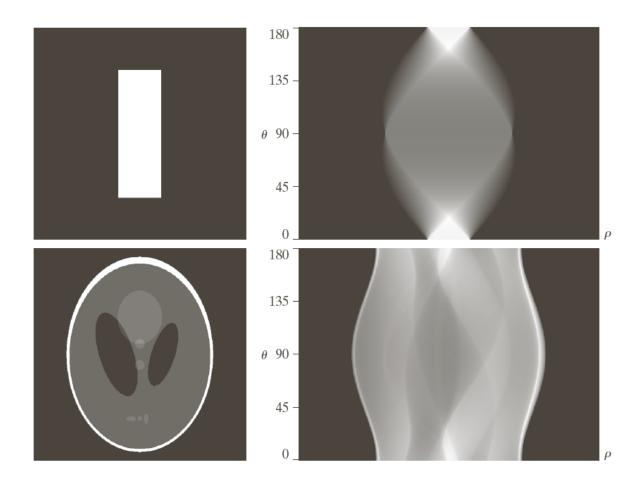
The projection of f(x, y) along an arbitrary line in the xy-plane:

$$g(\rho,\theta) = \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x,y) \delta(x\cos\theta + y\sin\theta - \rho)$$





Sinogram (正弦图)





Back Projection from Radon Transform

For a fixed value of rotation θ_k :

$$f_{\theta_k}(x, y) = g(\rho, \theta_k) = g(x \cos \theta_k + y \sin \theta_k, \theta_k)$$

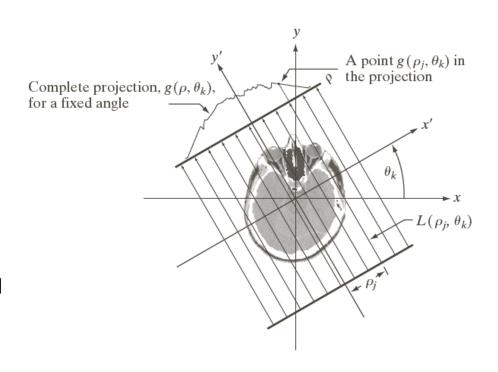
Then a single backprojection obtained at an angle θ :

$$f_{\theta}(x, y) = g(x \cos \theta + y \sin \theta, \theta)$$

Where $g(\rho, \theta)$ is the projection value.

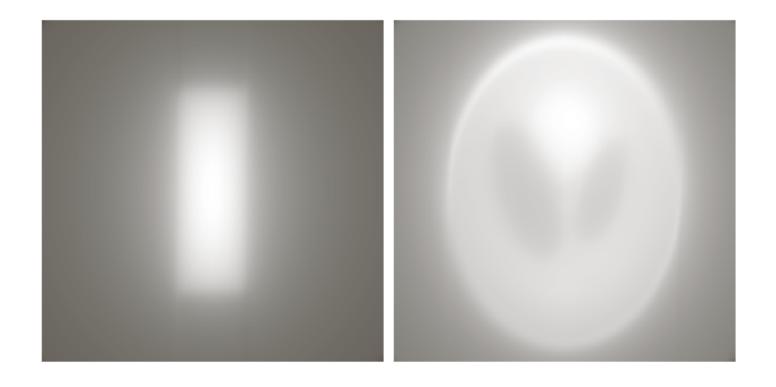
The final image by summing over all the back-projected images

$$f(x,y) = \sum_{\theta=0}^{\pi} f_{\theta}(x,y)$$





Back Projection from Radon Transform





The Fourier-Slice Theorem

The 1D FT of a projection with respect of ρ :

$$G(\omega,\theta) = \int_{-\infty}^{\infty} g(\rho,\theta) e^{-j2\pi\omega\rho} d\rho$$

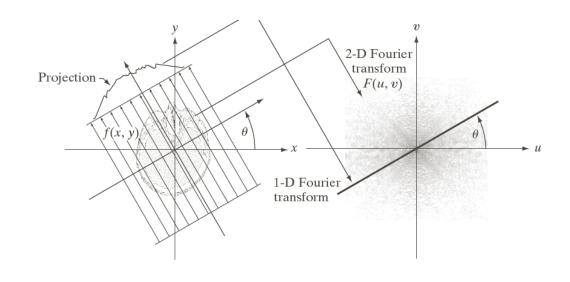
where projection $g(\rho, \theta)$ is

$$g(\rho,\theta) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x,y) \delta(x\cos\theta + y\sin\theta - \rho) dx dy$$

then

$$G(\omega, \theta) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) e^{-j2\pi\omega(x\cos\theta + y\sin\theta)} dx dy$$
$$= \left[\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) e^{-j2\pi(ux + vy)} dx dy \right]_{u = \omega\cos\theta: v = \omega\sin\theta}$$

Therefore $G(\omega, \theta) = F(\omega \cos \theta, \omega \sin \theta)$





Parallel-Beam Filtered Backprojections

The 2D IFT of F(u, v) with Fourier-slice theorem:

$$f(x,y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} F(u,v)e^{j2\pi(ux+vy)}dudv$$

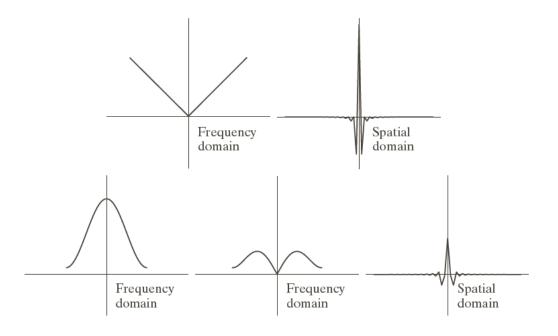
$$= \int_{0}^{2\pi} \int_{0}^{\infty} G(\omega,\theta)e^{j2\pi\omega(x\cos\theta+y\sin\theta)}\omega d\omega d\theta$$

$$= \int_{0}^{\pi} \left[\int_{-\infty}^{\infty} |\omega|G(\omega,\theta)e^{j2\pi\omega\rho}d\omega \right]_{\rho=x\cos\theta+y\sin\theta} d\theta$$

Convolution backprojection

$$f(x,y) = \int_0^{\pi} [s(\rho) \star g(\rho,\theta)]_{\rho = x \cos \theta + y \sin \theta} d\theta$$

Where $s(\rho) = IFT(|\omega|)$, $g(\rho, \theta) = IFT[G(\omega, \theta)]$





Parallel-Beam Filtered Backprojections





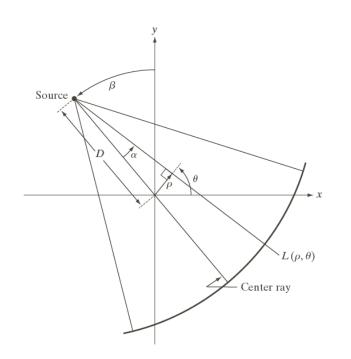


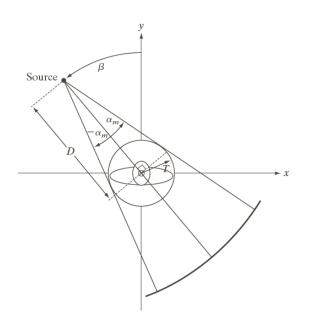
Fan-Beam Filtered Backprojections

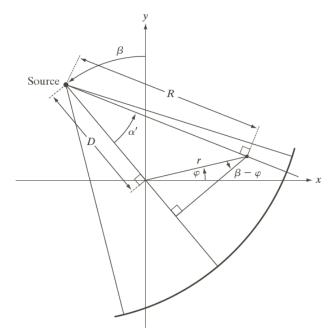
Fundamental fan-beam reconstruction based on filtered backprojection:

$$f(r,\varphi) = \int_0^{2\pi} \frac{1}{R^2} \left[\int_{-\alpha_m}^{\alpha_m} q(\alpha,\beta) h(\alpha' - \alpha) d\alpha \right] d\beta$$

Where
$$h(\alpha) = \frac{1}{2} \left(\frac{\alpha}{\sin \alpha}\right)^2 s(\alpha)$$
, $q(\alpha, \beta) = p(\alpha, \beta) D \cos \alpha$, $p(\alpha, \beta) = g(\rho, \theta) = g(D \sin \alpha, \alpha + \beta)$

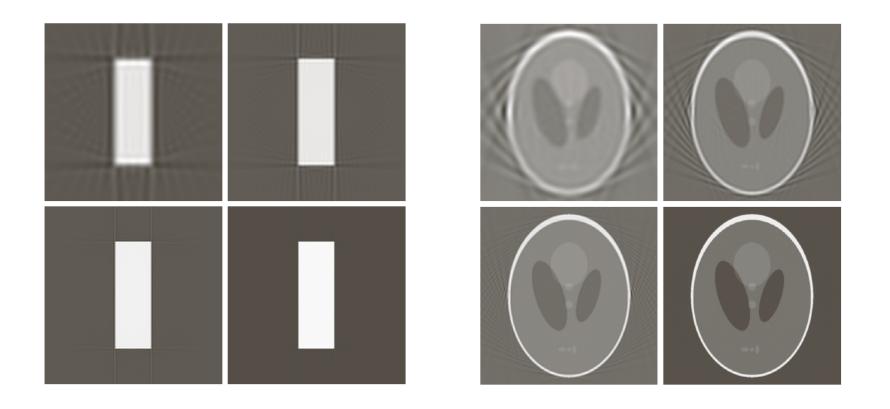








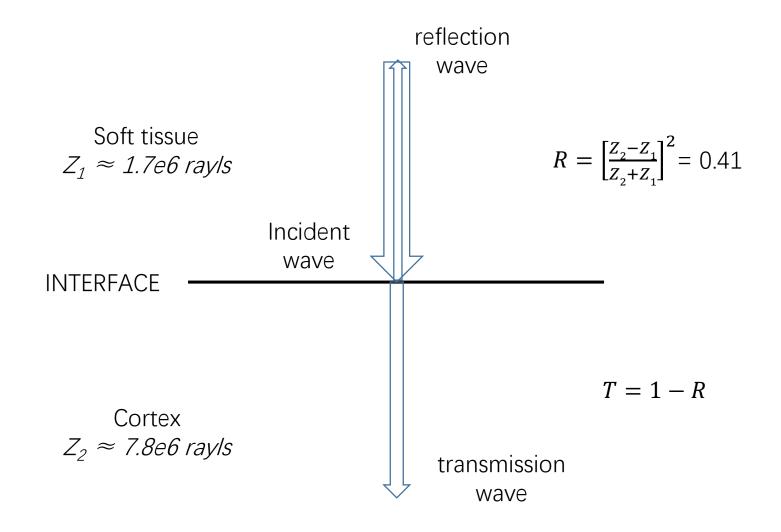
Fan-Beam Filtered Backprojections







Ultrasound wave reflection





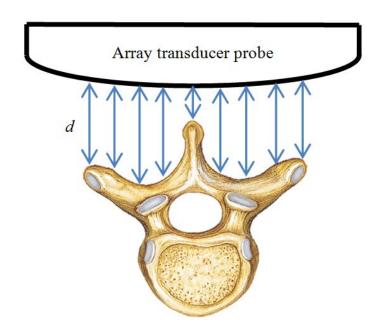


Ultrasound imaging

- Reflection from the interface between different tissues
- Using time of flight (t) to determine the distance (d) and locate the structures

$$t = \frac{2 * d}{V}$$

 Use gray level to indicate the amplitude (B mode)



The schematic of ultrasound reflection waves from the vertebra cortex / soft tissue interface.



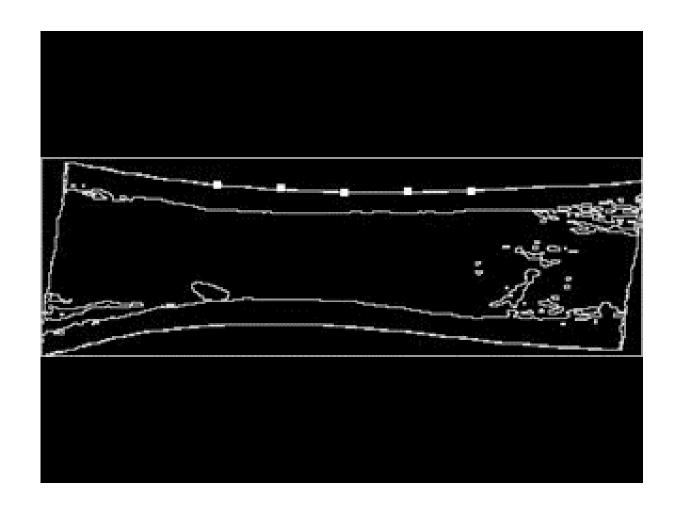


Ultrasound image





Wave Propagation





Born Approximation

Based on the perturbation velocity profile assumption:

$$\frac{1}{c^2(\vec{x})} = \frac{1}{c_0^2(\vec{x})} + f(\vec{x})$$

An approximate solution for acoustic wave equation (Born Approximation) is

$$d(\vec{s}, \vec{r}, \omega) = \omega^2 \int d^3x G_0(\vec{x}, \vec{r}, \omega) f(\vec{x}) G_0(\vec{s}, \vec{x}, \omega)$$

 $G_0(x,y,\omega)$: Green function

$$G_0(\vec{x}, \vec{y}, \omega) = A(\vec{x}, \vec{y})e^{-j\omega\tau(\vec{x}, \vec{y})}$$



Operator & cost function

Rewrite in operator form: $D(\vec{s}, \vec{r}) = L(\vec{s}, \vec{r}, \vec{x}, \omega_i) * F(\vec{x})$

Where, the cost function J

$$J = \left\| D - D^{obs} \right\|_2^2$$

Where

D: the theoretical data D^{obs} : the observed data

Inversion is to minimize *J* to find the best solution of $F(\vec{x})$



Operator & cost function

- Adjoint operator: $F(\vec{x}) = L^*(\vec{s}, \vec{r}, \vec{x}, \omega) * D(\vec{s}, \vec{r})$
- Minimum norm solution (LS): $J = ||LF D||_2^2$
- Damped minimum norm solution (DLS): $J = \|LF D\|_2^2 + \mu \|F\|_2^2$
- Weighted minimum norm solution (WLS): $J = \|LF D\|_2^2 + \mu \|WF\|_2^2$



Conjugate Gradient Method

Consider a system of linear equations: Lx=y

Let $\mathbf{x} = \mathbf{x}_0$, $\mathbf{p}_0 = \mathbf{r}_0 = \mathbf{y} - \mathbf{L}\mathbf{x}_0$, and $k = \mathbf{0}$. The following steps will be repeated until number of iterations or the tolerance limit for convergence is reached.

(a)
$$\alpha_k = \frac{\mathbf{r}_k^T \mathbf{r}_k}{\mathbf{p}_k^T \mathbf{L} \mathbf{p}_k}$$
.

(b)
$$\mathbf{x}_{k+1} = \mathbf{x}_k + \alpha_k \mathbf{p}_k$$
.

(c)
$$\mathbf{r}_{k+1} = \mathbf{y} - \mathbf{L}\mathbf{x}_{k+1}$$
.

(d)
$$\beta_k = \frac{\mathbf{r}_{k+1}^T \mathbf{r}_{k+1}}{\mathbf{r}_k^T \mathbf{r}_k}$$
.

(e)
$$\mathbf{p}_{k+1} = \mathbf{r}_{k+1} + \beta_k \mathbf{p}_k .$$

(f)
$$k = k + 1$$
.

