

1. Matrix product rule.

$$[A_{m \times n}] \times [B_{n \times p}] = [C_{m \times p}]$$

① e. regular: row-col
in A in B

$$C_{34} = (\text{row 3 of } A) \cdot (\text{col 4 of } B)$$

$$= a_{31} \times b_{14} + a_{32} \times b_{24} + \dots = \sum_{k=1}^n a_{3k} \cdot b_{k4}.$$

②. col:

$$[\quad] \times [\begin{smallmatrix} \text{col 1} \\ | \end{smallmatrix}] = [\begin{smallmatrix} \text{col 1} \\ | \end{smallmatrix}]$$

Col 1 of C is $A = B$ col 1.
(all the cols)

matrix ↓
vector

→ Columns of C is linear combination of columns of A

③ row:

$$[A] \cdot [B] = [C]$$

row 1 of $A \cdot B$ = row 1 in C .
(all the rows)

↳ Rows of C is a linear combination of the rows in B

(7) $A \cdot B = \text{Sum of (cols of } A\text{)} \times \text{(rows of } B\text{)}$

$$\text{e.g. } \begin{bmatrix} 2 & 7 \\ 3 & 8 \\ 4 & 9 \end{bmatrix} \cdot \begin{bmatrix} 1 & 6 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 2 \\ \frac{3}{2} \end{bmatrix} \cdot [1 \ 6] + \begin{bmatrix} 7 \\ 8 \\ 9 \end{bmatrix} \cdot [0 \ 0] = \begin{bmatrix} 2 & 12 \\ 3 & 18 \\ 4 & 24 \end{bmatrix}$$

⑤ block:

$$\begin{array}{c}
 \left[\begin{array}{c|c} A_1 & A_2 \\ \hline A_3 & A_4 \end{array} \right] \cdot \left[\begin{array}{c|c} B_1 & B_2 \\ \hline B_3 & B_4 \end{array} \right] = \left[\begin{array}{c|c} A_1 B_1 + A_2 B_3 & A_1 B_2 + A_2 B_4 \\ \hline A_3 B_1 + A_4 B_3 & A_3 B_2 + A_4 B_4 \end{array} \right] \\
 \text{A} \qquad \qquad \qquad \text{B} \qquad \qquad \qquad \text{C}
 \end{array}$$

Permutation matrix / 亂換.

row: left product.

新矩阵的第1行
有0个1, 1个2
 $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \cdot \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} c & d \\ a & b \end{bmatrix}$

\downarrow
 P (permutation matrix).

column: right product.

列1 列2
 $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \cdot \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} b & a \\ d & c \end{bmatrix}$

新矩阵的第1列有0个1, 1个2

性质: $P^{-1} = P^T$

$$P^T \cdot P = I$$

Inverse matrix 逆.

keep row 1: $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

swap row 2 & 3: $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

keep row 3: $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

\downarrow
 E \rightarrow identity

inverse of $E: E^{-1}$

For rectangle matrix:

left inverse $\leftarrow A^{-1} A = I$

$$A \cdot I = A \cdot A^{-1} \rightarrow \text{right inverse}$$

invertible/non-singular: $A^{-1} A = I = A A^{-1}$ (square matrix)

e.g. No inverse: $A = \begin{bmatrix} 1 & 3 \\ 2 & 6 \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ 0 & 0 \end{bmatrix} \rightarrow$ Non-invertible, singular: has $Ax = 0$

e.g. Inverse of $A \cdot B = B^{-1} A^{-1}$

$$A B B^{-1} A^{-1} = I$$

Gauss-Jordan:

Augmented matrix: $A \left[\begin{array}{cc|cc} 1 & 3 & 1 & 0 \\ 2 & 7 & 0 & 1 \end{array} \right]$ find inverse

$$\left[\begin{array}{cc|cc} 1 & 3 & 1 & 0 \\ 2 & 7 & 0 & 1 \end{array} \right] \rightarrow \left[\begin{array}{cc|cc} 1 & 3 & 1 & 0 \\ 0 & 1 & -2 & 1 \end{array} \right] \rightarrow \left[\begin{array}{cc|cc} 1 & 0 & 7 & -3 \\ 0 & 1 & -2 & 1 \end{array} \right]$$

\downarrow A^{-1}

Elimination:

$$EA = U$$

$$A = LU$$

L means

↳ If no row exchanges, multipliers go directly into L

e.g.: A

$$\begin{bmatrix} 2 & 1 \\ 8 & 7 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 0 & 3 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & \frac{1}{2} \\ 0 & 1 \end{bmatrix}$$

$A: 3 \times 3$ $E_{32} - E_{31} \cdot E_{21}$ A ^{diagonal}

e.g.:

$$E_{32} \xrightarrow{E} E_{21} \xrightarrow{U} A$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -5 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 10 & 5 & 1 \end{bmatrix}$$

Inverse:

$$\begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = L.$$

$$E_{21}^{-1} \quad E_{32}^{-1}$$

Theorem: For transposes:

$$\text{Theorem: } AA^{-1} = I \Rightarrow (A^{-1})^T \cdot A = I = (A^T)^{-1}$$

Inverse of A transpose = transpose of A^{-1}

Transpose: A^T i,j = $A_{j,i}$

$$\begin{bmatrix} 1 & 2 & 3 \\ 3 & 4 & 5 \\ 5 & 6 & 7 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 3 & 5 \\ 2 & 4 & 6 \\ 3 & 5 & 7 \end{bmatrix}$$

Symmetric matrix: $A^T = A$.

Property: $A \cdot A^T = A^T \cdot A$ $(A \cdot A^T)^T$.

(for all matrix) \hookrightarrow is ^{always} a symmetric matrix.

Property for Symmetric matrix:

① the eigenvalues are real numbers \mathbb{R} .

② The eigen vectors are orthogonal / perpendicular.

\hookrightarrow can be chosen.

\hookrightarrow can be orthonormal

eigenvectors

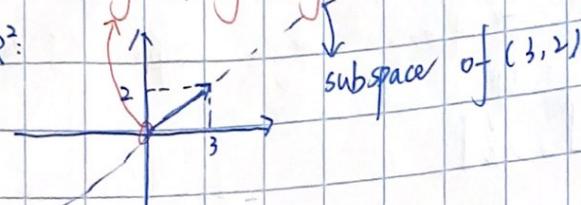
* usual: $A = S \Lambda S^{-1}$

$$\text{Symmetric: } A = Q \Lambda Q^{-1} = Q \Lambda Q^T$$

Vector Spaces:

subspace: must go through origin. 即经过原点.

e.g. \mathbb{R}^2 :



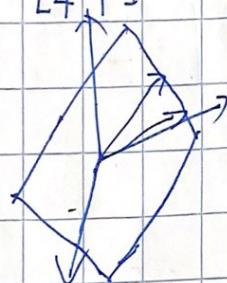
Subspaces of \mathbb{R}^2 : ① all of \mathbb{R}^2

② any line through zero vector $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$

③ $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$

Column space: eg: Columns in \mathbb{R}^3 :

$\begin{bmatrix} 1 & 3 & 7 \\ 2 & 3 & 1 \\ 4 & 1 & 1 \end{bmatrix}$: all their linear combination form a space



Rank: of a matrix: the number of pivots (also, pivot column)

pivot columns for A and A^T is the same

echelon form: 阶梯 $\begin{bmatrix} \overline{0} \\ \overline{0} \\ \overline{0} \\ \overline{0} \end{bmatrix}$

reduced echelon form: 每行首元素为1, 且是所在列的唯一非零元素

$$R = \begin{bmatrix} I & F \\ 0 & \dots & 0 \end{bmatrix}$$

$$\text{If } RN = 0 \Rightarrow N = \begin{bmatrix} -F \\ I \end{bmatrix} \rightarrow \text{how to get null space}$$

$$\begin{bmatrix} I & F \end{bmatrix} \cdot \begin{bmatrix} x_{\text{pivot}} \\ x_{\text{free}} \end{bmatrix} = 0$$

Nullspace: $Ax = 0$. $\underline{x} = ?$

$$\text{e.g. } A = \begin{bmatrix} 1 & 2 & 3 & 7 \\ 2 & 4 & 6 & 1 \\ 2 & 6 & 8 & 10 \\ 2 & 8 & 10 & 12 \end{bmatrix} \xrightarrow{\text{row operations}} \begin{bmatrix} 1 & 2 & 3 & 7 \\ 0 & 2 & 2 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{R: \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}}$$

Augmented:

$$\begin{bmatrix} 1 & 2 & 3 & | & 0 \\ 0 & 2 & 2 & | & 0 \\ 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \Rightarrow X = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \xrightarrow{F} \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \xrightarrow{I} \text{null space}$$

Solve $Ax = b$:

① * when B is in the column space of A :

And if a combination of rows in A gives zero row:

Then same combination of entries of B must give 0

$$\text{e.g. } \begin{array}{c|c} A & B \\ \hline 0 & 0 & 0 & | & 0 \end{array}$$

① $X_{\text{particular}}$: set all free variables to be 0.

solve $Ax = b$ for pivot variables

② $X_{\text{nullspace}}$: solve $Ax = 0$, get special solutions:

把其中一个 variable 设成 1, 其它全部为 0, 得到一个 vector

③ $X_{\text{complete}} = X_{\text{particular}} + X_{\text{nullspace}}$:

$$\text{e.g. } X_p = \begin{bmatrix} -2 \\ 0 \\ \frac{3}{2} \\ 0 \end{bmatrix} \quad (x_2, x_3 \text{ are free variables})$$

$$X_{\text{complete}} = \begin{bmatrix} -2 \\ 0 \\ \frac{3}{2} \\ 0 \end{bmatrix} + C_1 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + C_2 \begin{bmatrix} -2 \\ 0 \\ -2 \\ 1 \end{bmatrix} \quad \text{有 2 个 free variable, 故为 2.}$$

$$\text{proof: } Ax_p = b \text{ 成立, } Ax_n = 0 \Rightarrow A(X_p + X_n) = 0.$$

Solution state: For matrix $m \times n$.

① $r = n < m$: rank = col number

$Ax = b$ only has a particular solution / No solution

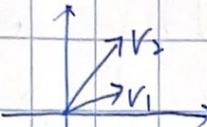
② $r = m < n$: Full rank.

$Ax = b$ for every b can be solved.

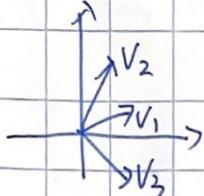
③ $r = m = n \rightarrow$ invertible.

$R = I$ $Ax = b$ has a unique solution

Independence: No linear combination gives zero vector. (except 0)

e.g. 

independent



exist
 $c_1 v_1 + c_2 v_2 + c_3 v_3$

which could be 0.
 \Rightarrow dependent.

In matrix: when v_1, v_2, \dots, v_n are columns of A :

They are independent if Nullspace of A is {zero vector}

They are dependent if $A\vec{c} = 0$ for some nonzero vector \vec{c}

Basis: for a space in a sequence of vectors v_1, v_2, \dots, v_n .

1. they are independent.
2. they span the space.

e.g. space in \mathbb{R}^3 :

one basis: $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

\Rightarrow n vectors give basis if the $n \times n$ matrix is invertible
dimension

* $\text{Rank}(A) = \text{pivot columns} = \text{pivots} = \text{dimension of column space of } A$.

4 important spaces for matrix A : $m \times n$.

① Column space $C(A)$ in \mathbb{R}^m

② Null space $N(A)$ in \mathbb{R}^n

③ Row space = all combinations of rows = all combinations of columns of A^T
 $= C(A^T)$ in \mathbb{R}^n

④ Null space of A^T = $N(A^T)$ in \mathbb{R}^m
(Left nullspace)

$A: m \times n$.

$C(A)$.

$N(A)$

$C(A^T)$ reduced echelon form

$N(A^T)$

basis: ~~all~~ pivot cols.

special solutions of A

first r rows of R

Dimension dim

rank

$n-r$

r

$m-r$

$$\star: N(A^T) = A^T \cdot y = 0$$

$$y^T A = 0^T$$

$$[y^T \mid I \mid A] = [0 \ 0 \ 0 \dots]$$

(calculation of $N(A^T)$):

e.g. $A \begin{bmatrix} 1 & 2 & 3 & 1 \\ 1 & 1 & 2 & 1 \\ 1 & 3 & 1 & 1 \end{bmatrix} \xrightarrow{\text{R2} \leftrightarrow \text{R3}} \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} = R$

$$A \begin{bmatrix} 1 & 2 & 3 & 1 & 1 & 0 & 0 \end{bmatrix} \xrightarrow{\begin{array}{l} \text{R1} \leftrightarrow \text{R2} \\ \text{R3} \rightarrow \text{R3} - 2\text{R1} \end{array}} \begin{bmatrix} 1 & 0 & 1 & 1 & 1 & -1 & 2 & 0 & 7 \\ 0 & 1 & 1 & 0 & 1 & 1 & -1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 1 \end{bmatrix}$$

$$\text{So } \begin{bmatrix} 1 & 2 & 0 \\ 1 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 2 & 3 & 1 \\ 1 & 1 & 2 & 1 \\ 1 & 3 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

but $N(A^T)$ should be 1 dimension, which is
because this line is zero vector.

\star We are finding a set of rows which contains the rows of left nullspace.

More examples of matrix space:

① $M = \text{all } 3 \times 3 \text{ matrix } \dim M = 9$

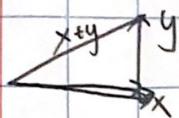
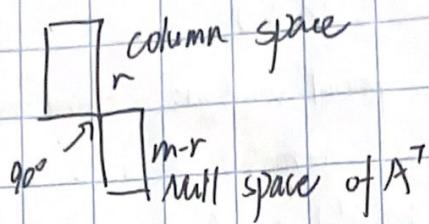
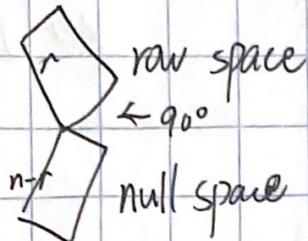
② $S = \text{all } 3 \times 3 \text{ symmetric matrices } \dim S = 6$

③ $U = \text{upper triangular } 3 \times 3 \text{ matrices } \dim U = 6$

④ $S \cap U = \text{symmetric upper triangular} = \text{diagonal } 3 \times 3 \text{ matrix}$

$$\dim(S \cap U) = 3$$

Orthogonal:



$$x^T \cdot y = 0 \Rightarrow \text{orthogonal} \quad / \text{perpendicular}$$
$$\|x\|^2 + \|y\|^2 = \|x+y\|^2$$
$$x^T \cdot x$$

$$\text{eg: } x = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \quad x^T = \begin{bmatrix} 1 & 2 & 3 \end{bmatrix} \quad \|x\|^2 = 14$$

Subspace S is orthogonal to subspace T means:

every vector in S is orthogonal to every vector in T.

Theorem 1: row space is orthogonal to null space

why: $Ax=0$ $A: \begin{bmatrix} \text{row 1 of } A \\ \text{row 2 of } A \\ \vdots \\ \text{row } m \text{ of } A \end{bmatrix} \quad x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$

x is orthogonal to every row.

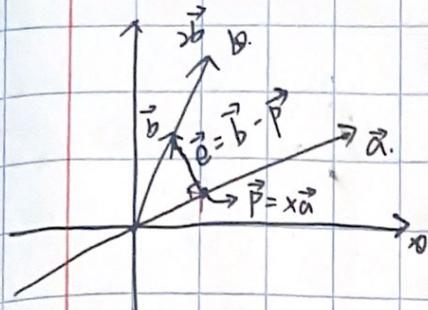
row space contains all the linear combinations of rows in A.

$$(\text{row 1})^T x = 0 \quad C_1(\text{row 1})^T x = 0 \quad C_1 \cdot (\text{row 1})^T x +$$
$$(\text{row 2})^T x = 0 \quad \Rightarrow \quad C_2(\text{row 2})^T x = 0 \quad \Rightarrow \quad C_2 \cdot (\text{row 2})^T x = 0$$

Theorem 2: $A^T A$ is invertible exactly if A has independent columns.

why: $A^T A x = 0$

$$x^T \cdot A^T A x = 0 \Rightarrow (x^T A)^T A x = 0 \Rightarrow A x = 0 \Rightarrow x = 0$$



$e \perp a$

$$\text{if } \vec{b} = 2\vec{b} \Rightarrow \vec{p} = 2\vec{p}$$

$$\text{if } \vec{a} = 2\vec{a} \Rightarrow \vec{p} = \vec{p}$$

$$a^T \cdot (b - x\vec{a}) = 0 \rightarrow \vec{a} \perp \vec{b} - x\vec{a}$$

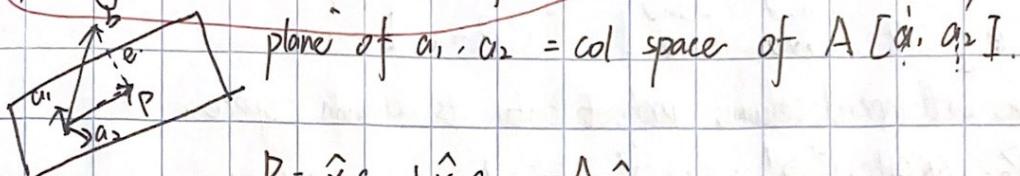
$$x\vec{a}^T \cdot \vec{a} = \vec{a}^T \vec{b}$$

$$x = \frac{\vec{a}^T \vec{b}}{\vec{a}^T \vec{a}}$$

$$\vec{p} = x\vec{a} = \frac{\vec{a}^T \vec{b}}{\vec{a}^T \vec{a}} \cdot \vec{a} \perp \vec{a}^T$$

projection matrix: $\vec{b} \leftarrow \vec{P} = \frac{\vec{a} \cdot \vec{a}^T}{\vec{a}^T \vec{a}}$ $C(\vec{P}) = \text{line through } \vec{a}, \text{ rank. } R(\vec{P}) = 1$

Theorem: property: $\vec{P}^T = \vec{P}$ $\vec{P}^2 = \vec{P}$



$$\vec{P} = \hat{x}_1 \vec{a}_1 + \hat{x}_2 \vec{a}_2 = \vec{A} \hat{x}$$

prof: $e = b - \vec{A} \hat{x}$ is perpendicular to the plane

$$\text{so } \begin{cases} \vec{a}_1^T (b - \vec{A} \hat{x}) = 0 \\ \vec{a}_2^T (b - \vec{A} \hat{x}) = 0 \end{cases} \Rightarrow \begin{bmatrix} \vec{a}_1^T \\ \vec{a}_2^T \end{bmatrix} (b - \vec{A} \hat{x}) = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \vec{A}^T (b - \vec{A} \hat{x}) = 0$$

$$\vec{A}^T \cdot e = 0$$

e in $N(\vec{A}^T)$. $e \perp C(\vec{A})$.

$$\hat{x} = (\vec{A}^T \vec{A})^{-1} \vec{A}^T \vec{b}$$

如果 \vec{A} 是列全 a .

$$\text{conclusion: } \vec{p} = \vec{A} \hat{x} = \vec{A} (\vec{A}^T \vec{A})^{-1} \vec{A}^T \vec{b}$$

$$\text{Matrix } \vec{P} = \vec{A} (\vec{A}^T \vec{A})^{-1} \vec{A}^T \rightarrow \text{逆解. } \vec{P} = \frac{\vec{a} \cdot \vec{a}^T}{\vec{a}^T \vec{a}}$$

If \vec{b} in column space of \vec{A} : $P_b = b$: $P_b = \vec{A} (\vec{A}^T \vec{A})^{-1} \vec{A}^T \vec{A} \hat{x} = \vec{A} \hat{x}$

If $b \perp$ column space of \vec{A} : $P_b = 0$

$$\text{Matrix } \vec{P} \cdot \vec{b} = \vec{P}_b$$

Orthonormal: orthogonal and length = 1

Orthonormal vectors:

$$q_i^T \cdot q_j = \begin{cases} 0 & \text{if } i \neq j \\ 1 & \text{if } i = j. \end{cases}$$

$$\begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$Q = [q_1 \ \dots \ q_n].$$

$$Q^T \cdot Q = \begin{bmatrix} q_1^T \\ \vdots \\ q_n^T \end{bmatrix} \cdot [q_1 \ \dots \ q_n] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Orthogonal matrix: Q . $\mathbb{R}^{\text{square}}$

\hookrightarrow 列与列之间正交

Property: $Q^T Q = I$ $Q^T = Q^{-1}$ if Q is square.

$$\text{e.g. } Q = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \quad Q = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

Q has orthonormal columns project onto its column space:

$$P_Q = Q(Q^T Q)^{-1} Q^T = Q Q^T \quad (=I \text{ if } Q \text{ is square})$$

$$\text{extension: } A^T A \hat{x} = A^T b$$

$$\text{Now } A \text{ is } Q: \quad Q^T Q \hat{x} = Q^T b \Rightarrow \hat{x} = Q^T b.$$

$$\hat{x}_i = q_i^T \cdot b$$

Gram-Schmidt:

Independent vectors $a, b \rightarrow$ orthogonal $A \perp B \rightarrow$ orthonormal.

$$B = b - \frac{A^T b}{A^T A} \cdot A$$

\hookrightarrow 为了 A 为正交矩阵

$$q_1 = \frac{A}{\|A\|} \quad q_2 = \frac{B}{\|B\|}$$

$$Q = [q_1 \ q_2]$$

$$a, b, c \rightarrow A, B, C \rightarrow$$

$$B = b - \frac{A^T b}{A^T A} A$$

$$C = c - \frac{A^T C}{A^T A} A - \frac{B^T C}{B^T B} B$$

$$\text{e.g. } a = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \quad b = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} - \frac{3}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$$

$$Q = [q_1 \ q_2] = \begin{bmatrix} \frac{1}{\sqrt{3}} & 0 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} \end{bmatrix} \rightarrow \text{和 } a, b \text{ 在同一平面, 但不正交.}$$

$\star q_1, q_2$ always $\perp A$.

Determinant:

property:

$$\textcircled{1} \quad \det I = 1.$$

$$\textcircled{1} \quad \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = 1$$

$$\textcircled{2} \quad \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = -1$$

\textcircled{2} Exchange rows in matrix: reverse the sign of det.

e.g. permutation $P: \det P = 1 \text{ or } -1$

e.g. $\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - cb$

$$\textcircled{3a} \quad \begin{vmatrix} ta & tb \\ c & d \end{vmatrix} = t \cdot \begin{vmatrix} a & b \\ c & d \end{vmatrix}$$

$$\textcircled{3b} \quad \begin{vmatrix} a+a' & b+b' \\ c+d & d \end{vmatrix} = \begin{vmatrix} a & b \\ c & d \end{vmatrix} + \begin{vmatrix} a' & b' \\ c & d \end{vmatrix}$$

★ linear for each row.

extension:

\textcircled{1} if 2 equal rows exist in matrix $\rightarrow \det = 0$

\textcircled{2} subtract $l \times \text{row } i$ from row k $\rightarrow \det$ does not change

\textcircled{3} Rows of zero $\rightarrow \det = 0$ from 3a: $\begin{vmatrix} 0 & a & b \\ c & 0 & b \\ c & d & 0 \end{vmatrix} = 0 \cdot \begin{vmatrix} a & b \\ c & d \end{vmatrix}$

e.g. $\begin{vmatrix} a & b \\ c-a & c-b \end{vmatrix} \textcircled{3b} \quad = \begin{vmatrix} a & b \\ c & d \end{vmatrix} + \begin{vmatrix} a & b \\ -a & -b \end{vmatrix}$

$$\textcircled{3b} \quad = \begin{vmatrix} a & b \\ c & d \end{vmatrix} - l \begin{vmatrix} a & b \\ a & b \end{vmatrix}$$

$$\textcircled{3b} \quad = \begin{vmatrix} a & b \\ c & d \end{vmatrix} \rightarrow \textcircled{3b}$$

\textcircled{4} $U = \begin{bmatrix} d_1 & & & \\ 0 & d_2 & & \\ 0 & 0 & d_3 & \\ \vdots & \vdots & \ddots & d_n \end{bmatrix}$ upper triangle matrix:

$$\det U = \text{product of } d_i's = d_1 \times d_2 \times d_3 \times \dots \times d_n$$

= product of pivots

\textcircled{5} $\det A = 0$ when A is singular \rightarrow row is all 0 exists

$\det \neq 0$: invertible $\rightarrow U \rightarrow$ Diagonal

$$\textcircled{6} \quad \det(A \cdot B) = \det A \cdot \det B$$

$$\text{e.g. } \det A^{-1} = \frac{1}{\det A}$$

$$A^{-1} \cdot A = I$$

$$\det A^{-1} \cdot \det A = 1 = \det(A^{-1} \cdot A)$$

$$\text{extension: } \det A^2 = (\det A)^2$$

$$\det 2A = 2^n \det A$$

$$\textcircled{7} \quad \det A^T = \det A.$$

Calculation:

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = \begin{vmatrix} a & 0 \\ c & 0 \end{vmatrix} + \begin{vmatrix} a & 0 \\ 0 & d \end{vmatrix} + \begin{vmatrix} 0 & b \\ c & 0 \end{vmatrix} + \begin{vmatrix} 0 & b \\ 0 & d \end{vmatrix} = ad - bc$$

$$\begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = a_{11} \begin{vmatrix} 0 & 0 \\ 0 & a_{22} \end{vmatrix} + a_{21} \begin{vmatrix} 0 & 0 \\ 0 & a_{32} \end{vmatrix} + a_{31} \begin{vmatrix} 0 & 0 \\ 0 & a_{22} \end{vmatrix} + a_{12} \begin{vmatrix} 0 & 0 \\ 0 & a_{33} \end{vmatrix} + a_{22} \begin{vmatrix} 0 & 0 \\ 0 & a_{33} \end{vmatrix} + a_{32} \begin{vmatrix} 0 & 0 \\ 0 & a_{23} \end{vmatrix} + a_{13} \begin{vmatrix} 0 & 0 \\ 0 & a_{23} \end{vmatrix} + a_{23} \begin{vmatrix} 0 & 0 \\ 0 & a_{13} \end{vmatrix} + a_{33} \begin{vmatrix} 0 & 0 \\ 0 & a_{13} \end{vmatrix}$$

$$= a_{11}a_{22}a_{33} - a_{11}a_{23}a_{32} - a_{12}a_{21}a_{33} + \dots$$

Regular formula:

$$\det A = \sum_{\text{all terms}} \pm a_{1\alpha} a_{2\beta} a_{3\gamma} \dots a_{n\omega}.$$

$$(\alpha, \beta, \gamma, \dots, \omega) = \text{permutation of } (1, 2, 3, \dots, n)$$

不重复选择.

$$\begin{bmatrix} + & - & + & - & + \\ - & + & - & + & - \\ + & - & + & - & + \\ - & + & - & + & - \end{bmatrix}$$

$$\text{e.g. } \begin{vmatrix} 0 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{vmatrix} \Rightarrow (3, 2, 1, 4) \cdot (4, 3, 2, 1)$$

Co-factors: 3×3

$$\det = a_{11} (a_{22}a_{33} - a_{23}a_{32}) - a_{12} (\dots) + a_{13} (\dots) \dots$$

$$C_{11} = \begin{vmatrix} a_{11} & 0 & 0 \\ 0 & a_{22} & a_{23} \\ 0 & a_{32} & a_{33} \end{vmatrix}$$

$$C_{12} = \begin{vmatrix} 0 & a_{12} & 0 \\ a_{21} & 0 & a_{23} \\ a_{31} & 0 & a_{33} \end{vmatrix}$$

along row 1: $\det A = a_{11}C_{11} + a_{12}C_{12} + \dots + a_{1n}C_{1n}$

判斷正負號: a_{ij} $i+j = \text{odd} \rightarrow -$

$i+j = \text{even} \rightarrow +$

Inverse: by determinant

$$\text{eg. } \begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad-bc} \cdot \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$A^{-1} = \frac{1}{\det A} \cdot C^T \quad \begin{bmatrix} d & b & e \\ d & e & f \\ g & h & i \end{bmatrix} = \begin{bmatrix} -ei-hf \\ -di-gf \\ -bi-cf \end{bmatrix}$$

轉置 A , 求每個位置的 cofactor.

Cramer's rules:

$$Ax = b. \quad x = A^{-1}b = \frac{1}{\det A} \cdot C^T \cdot b$$
$$= C_{11}b_1 + C_{12}b_2 + \dots$$

$$x_1 = \frac{\det B_1}{\det A} \quad x_2 = \frac{\det B_2}{\det A} \quad \dots \quad x_j = \frac{\det B_j}{\det A}.$$

$$B_j: \begin{bmatrix} b_1 & a_{12} & a_{13} & a_{14} & \dots & a_{1n} \end{bmatrix}.$$

$B_j = A$ with column j replaced by b .

Determinant application: $\det A = \text{volume}$

Eigenvalues: find Ax parallel to $x \Rightarrow Ax = \lambda x$.

λ : eigenvalue x : eigen vector.

If A is singular $\rightarrow \lambda = 0$ is an eigenvalue

e.g.  For projection matrix:

Any x in plane: $Px = x \quad \lambda = 1$

Any $x \perp$ plane: $Px = 0(x) \quad \lambda = 0$

e.g: permutation matrix:

$$P_1 = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \quad x_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \Rightarrow Ax = x \quad \lambda = 1$$

$$x_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \Rightarrow Ax = -x \quad \lambda = -1$$

* The sum of eigenvalues = the sum down the diagonal (trace)

Solve $Ax = \lambda x$: $(A - \lambda I)x = 0$
singular.

$\det(A - \lambda I) = 0 \rightarrow \text{Find } \lambda \rightarrow \text{Find } x$

e.g. $A = \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix}$ $\det(A - \lambda I) = \begin{vmatrix} 3-\lambda & 1 \\ 1 & 3-\lambda \end{vmatrix} = (3-\lambda)^2 - 1$
 $= \lambda^2 - 6\lambda + 8 = (\lambda-4)(\lambda-2)$
 trace \downarrow determinant.

$\lambda_1 = 4 \quad A - 4I = \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} \quad x_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$
 $\lambda_2 = 2 \quad A - 2I = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \quad x_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$

property: ① $A + nI \rightarrow$ eigenvalues + n \rightarrow eigenvectors 不变

② trace = the sum of eigenvalues.

③ eigen vectors of a symmetric matrix is orthogonal.

e.g. $\alpha = \begin{bmatrix} \cos 90^\circ & \sin 90^\circ \\ \sin 90^\circ & -\cos 90^\circ \end{bmatrix} \rightarrow$ orthogonal

$\alpha^T = -\alpha \rightarrow \text{anti-symmetric}$

$\det \alpha = 1 = \lambda_1 \lambda_2$

trace = 0 = $\lambda_1 + \lambda_2$

$\det(\alpha - \lambda I) = \begin{vmatrix} \lambda & -1 \\ 1 & \lambda \end{vmatrix} = \lambda^2 + 1 = 0 \quad \lambda_1 = i$
 $\lambda_2 = -i$

→ upper-triangle matrix in eigenvalues 在对角线上

e.g. $A = \begin{bmatrix} 3 & 1 \\ 0 & 3 \end{bmatrix} \quad \det(A - \lambda I) = \begin{vmatrix} 3-\lambda & 1 \\ 0 & 3-\lambda \end{vmatrix} = (3-\lambda)^2$

$\lambda_1 = \lambda_2 = 3$

$x = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \rightarrow \text{degenerate matrix}$

diagonal: A has n independent eigenvectors of
put them in columns of $S \rightarrow$ spectrum

$$AS = A[x_1 \ x_2 \ x_3 \ \dots \ x_n] = [\lambda_1 x_1 \ \lambda_2 x_2 \ \dots \ \lambda_n x_n]$$
$$= [x_1 \ x_2 \ \dots \ x_n] \cdot \begin{bmatrix} \lambda_1 & & & & \\ & \lambda_2 & & & \\ & & \ddots & & \\ & & & \ddots & \lambda_n \end{bmatrix} = S\Lambda \text{ lambda}$$

$$AS = S\Lambda$$

$$S^{-1}AS = \Lambda$$

$$A = S\Lambda S^{-1}$$

$$Ax = \lambda x$$

$$A^2x = \lambda Ax = \lambda^2 x$$

$$A^2 = S\Lambda S^{-1} \cdot S\Lambda S^{-1} = S\Lambda^2 S^{-1}$$

$$A^k = S\Lambda^k S^{-1}$$

property: $A^k \rightarrow 0$ as $k \rightarrow \infty$ if all $|\lambda| < 1$.

Diagonalizable: A is sure to have n independent eigenvectors.
(be diagonalizable) if all the λ s are different.

algebraic multiplicity: λ_1 is eigenvalue $\lambda_2 = 2$

$$\text{e.g.: } A = \begin{bmatrix} 2 & 1 \\ 0 & 2 \end{bmatrix} \quad \det(A - \lambda I) = \begin{vmatrix} 2-\lambda & 1 \\ 0 & 2-\lambda \end{vmatrix} = (2-\lambda)^2 = 0$$

$$\lambda_1 = \lambda_2 = 2$$

$$A - 2I = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \quad x_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad A \text{ is not diagonalizable.}$$

* 如果一个 value 对应 2 个 vector 仍然可 diagonalizable

if A has 1 eigenvalue, the eigenspace is dimension