

9.1.5

EE24BTECH11004 - Ankit Jainar

Question

Solve the differential equation:

$$\frac{d^2y}{dx^2} = \cos(3x) + \sin(3x)$$

Solution: Theoretical Approach

Given:

$$\frac{d^2y}{dx^2} = \cos(3x) + \sin(3x) \quad (1)$$

Integrating both sides:

$$\frac{dy}{dx} = \int \cos(3x) dx + \int \sin(3x) dx + c_1 \quad (2)$$

$$= \frac{\sin(3x)}{3} - \frac{\cos(3x)}{3} + c_1 \quad (3)$$

Integrating again:

$$y = \int \left(\frac{\sin(3x)}{3} - \frac{\cos(3x)}{3} + c_1 \right) dx + c_2 \quad (4)$$

$$= -\frac{\cos(3x)}{9} - \frac{\sin(3x)}{9} + c_1x + c_2 \quad (5)$$

Solution: Theoretical Approach (contd.)

Assuming the initial conditions:

- $y(0) = 0$
- $y'(0) = 0$

Substituting $y(0) = 0$:

$$-\frac{\cos(0)}{9} - \frac{\sin(0)}{9} + c_1 \cdot 0 + c_2 = 0 \quad (6)$$

$$c_2 = \frac{1}{9} \quad (7)$$

Substituting $y'(0) = 0$:

$$\frac{\sin(0)}{3} - \frac{\cos(0)}{3} + c_1 = 0 \quad (8)$$

$$c_1 = \frac{1}{3} \quad (9)$$

Thus, the solution is:

$$y(x) = -\frac{\cos(3x)}{9} - \frac{\sin(3x)}{9} + \frac{x}{3} + \frac{1}{9} \quad (10)$$

Solution: Computational Approach

The given differential equation is:

$$\frac{d^2y}{dx^2} = \cos(3x) + \sin(3x) \quad (11)$$

Using discretization, the second-order derivative can be approximated as:

$$y''(t + h) = y''(t) + h \cdot (\cos(3t) + \sin(3t)) \quad (12)$$

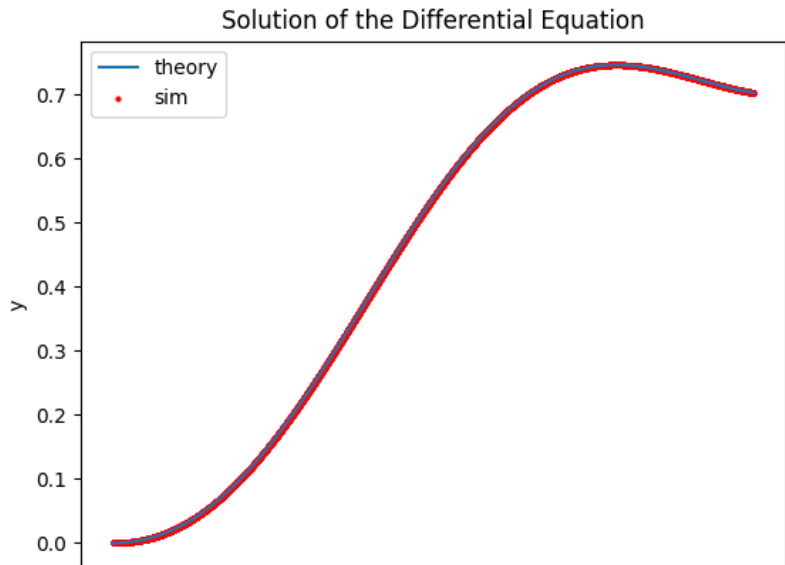
Solution: Computational Approach (contd.)

Expressing this as a system of equations:

$$\vec{y}_{k+1} = \begin{bmatrix} 1 & h & \frac{h^2}{2} \\ 0 & 1 & h \\ 0 & 0 & 1 \end{bmatrix} \cdot \vec{y}_k + \begin{bmatrix} 0 \\ 0 \\ h^2 (\cos(3x_k) + \sin(3x_k)) \end{bmatrix} \quad (13)$$

By iterating over time steps, the computational solution is computed. Comparison between the theoretical and computational solutions is shown below.

Comparison of Results



C-Code

```
1 #include <stdio.h>
2 #include <stdlib.h>
3 #include <math.h>
4
5 double h = 0.1; //step size which I am considering
6
7 double f(double x, double y, double v) {
8     return cos(3*x)+sin(3*x);          /* d2y/dx2 = f(x,y,dy/dx) */
9 }
10
11 void solve(double *x,double *y,double *v,int steps){
12     for(int i=0;i<steps;i++){
13         *y += h * (*v); //y value using dy/dx
14
15         *v += h * f(*x,*y,*v); //value v updating using d2y/dx2
16
17         *x += h; //x value
18     }
19 }
20
```


Code for plot

```
1 import ctypes
2 import numpy as np
3 import matplotlib.pyplot as plt
4
5 # Load the shared object file (assuming it's in the same directory)
6 code = ctypes.CDLL('./code.so')
7
8 # Define argument and return types for the solve function
9 code.solve.argtypes = [ctypes.POINTER(ctypes.c_double),
10                        ctypes.POINTER(ctypes.c_double),
11                        ctypes.POINTER(ctypes.c_double),
12                        ctypes.c_int]
13 # Parameters
14 h = 0.1 # step size
15 steps = 10000 # number of steps
16
17 # Initial values
18 x = 0.0
19 y = 0.0
20 v = 0.0
21
22 # Create arrays to hold the results
23 x_vals = np.zeros(steps)
24 y_vals = np.zeros(steps)
25 v_vals = np.zeros(steps)
26
27 # Prepare ctypes variables for passing to the solve function
28 x_ctypes = ctypes.c_double(x)
29 y_ctypes = ctypes.c_double(y)
30 v_ctypes = ctypes.c_double(v)
31
32 # Collect initial values
33 x_vals[0] = x
34 y_vals[0] = y
35 v_vals[0] = v
36
37 # Call the solve function and collect values at each step
38 for i in range(1, steps):
39     # Call the solve function for each step
40     code.solve(ctypes.byref(x_ctypes), ctypes.byref(y_ctypes), ctypes.byref(v_ctypes), 1)
41
42     # Store the results after the update
43     x_vals[i] = x_ctypes.value
44     y_vals[i] = y_ctypes.value
45     v_vals[i] = v_ctypes.value
46
47 # Plot the results
48 plt.plot(x_vals, y_vals, label='theory')
49 plt.xlabel('x')
50 plt.ylabel('y')
51 plt.scatter(x_vals, y_vals, color='red', s=4, label='sin')
52 plt.legend()
```