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**A Minor Project Final Defense Report On**  
**“ BIRD SPECIES DETECTION ”**  
**[CT-654]**

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A Minor Project Proposal report submitted to the Department of Electronics and Computer Engineering in the partial fulfillment of the requirements for degree of Bachelor of Engineering in Computer Engineering  
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ADVANCED COLLEGE OF ENGINEERING AND  
MANAGEMENT

DEPARTMENT OF COMPUTER AND ELECTRONICS ENGINEERING

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## ABSTRACT

Innumerable people visit bird sanctuaries to observe the elegance of different species of birds. Species identification is a challenging task which may result in many different labels. Sometimes even experts may disagree on species. It is both difficult of humans and computers that hit the limit of visual abilities. Hence, to help the bird spectator, we have developed deep learning based algorithms using the concept of image processing using the Convolutional Neural Network (CNN) algorithm. A CNN architecture is designed and trained using this dataset to learn discriminative features representative of different bird species. It will recognize the input image by comparing the model with a trained mode land then predict the bird species. Some of the basic details of the bird will be displayed as an output. Also, it will help us to create dataset if any image captured or uploaded by user is missing in dataset then user can add that image to dataset.

**Keywords:** *Bird species identification, deep learning, image processing, CNN*

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## **List of Abbreviations/Acronyms**

CNN- Convolutional Neural Network

IDE- Integrated Development Environment

IUCN- International Union for Conservation of Nature

ReLU- Rectified Linear Unit

RGB- Red Green Blue

SGD- Stochastic Gradient Descent

VGG Net- Visual Geometry Group Network

# **CHAPTER 1**

## **INTRODUCTION**

Deep Learning is a Machine Learning subfield which is in turn a subfield of Artificial Intelligence. Deep learning can be visualized as a platform where artificial, human brain inspired neural networks and algorithms learn from large amounts of data. Deep Learning allows computers to solve complex problems even though they use a very diverse, unstructured, and interconnected data set Identification of bird is a difficult process that often results in confusing labels bird species identification is seen as a perplexing problem which often leads to confusion collecting and gathering information on birds needs tremendous human effort. Many people visit bird sanctuaries to look at the birds while they barely recognize the differences between different species of birds and their characteristics. Even while various bird species share the same basic set of components, their form and appearance might vary. Attempts to automate species identification in audio recordings have included birds, amphibians, bats, insects, fish, and marine mammals.

To predict the birds in their natural habitats, we developed an interface to extract information from bird images using the Convolutional Neural Network (CNN) algorithm. First, a vast dataset of birds were gathered and localized. Second, CNN architecture was designed similar to the VGG Net Network. Now that the network was implemented, we trained the CNN model with the bird data set using Keras, and subsequently the classified, trained data was stored on the disk to identify a target object. Ultimately, the client-server architecture navigates a sample bird image submitted by an end-user to retrieve information and predict the bird species from the qualified model stored on the disk. This method allows the autonomous identification of birds from the captured images and can provide important, useful knowledge about bird species.

### **1.1 Background**

According to the International Union for Conservation of Nature (IUCN), More than 1300 species of birds are globally in danger of going extinct. Out of the 878 bird species recorded

in Nepal, 167 (19%) have been assessed as nationally threatened. The nationally threatened species comprise 67 (40%) which are considered Critically Endangered, 38 (23%) Endangered, and 62 (37%) Vulnerable species [6]. A total of 62 species have been assessed as Near Threatened. Nine species (1% of the total threatened) are Regionally Extinct; none of these have been recorded in Nepal since the 19th century. A total of 22 species (2.5% of the total) is considered Data Deficient Because of the vital functions that birds play in pollination, seed dissemination, and pest control, the loss of bird populations might have serious ecological repercussions [6]. Moreover, birds are essential indicators of the health of ecosystems, and their decline can signal broader ecological problems. Effective bird identification and monitoring can help researchers understand the factors contributing to population declines and develop effective conservation strategies

## **1.2 Motivation**

The development of the intelligent automated system for endangered bird species classification can have far-reaching implications beyond just conservation efforts. The use of deep learning in the industry of ornithology can help us better understand the ecology and behavior of bird species. By accurately identifying and tracking populations of different species, we can gather more data on their movements, habitat preferences, and overall behavior patterns. Thus overall improves the awareness of endangered bird species among the people.

## **1.3 Statement of the Problem**

Manual identification of bird species is very tedious task as well as very unreliable as his/her knowledge may not be in-depth and limited to the local bird species. This process is a lot of time-consuming and it may contain some errors. There are lots of books that have been published for the process of helping a human incorrectly identifying bird species. The current bird species identification process involved using the bird audio which is recorded and fed into the system. Nevertheless, it requires the hundreds of hours to carefully analyzed and classify the species. Due to such a process, large scale bird identification is almost an impossible task. So, to automate the process is a more practical approach.

#### **1.4 Project objective**

The objective of our project is to accurately identify the bird species through Nepali image processing using deep convolution neural networks (CNNs).

#### **1.5 Significance of the study**

Our research aims to contribute to the development of effective, accurate, and scalable solutions for bird identification using deep learning techniques. Such solutions can help to protect and conserve endangered bird populations and ultimately contribute to the preservation of our planet's rich biodiversity. The development of deep learning algorithms for bird identification is an exciting and rapidly growing field, and we look forward to advancing this research further in the future.

## **CHAPTER 2**

### **LITERATURE REVIEW**

Bird species identification is an important task for preserving the biodiversity. Many automated systems are widely used in detecting various species of birds. Fagerlund used machine learning algorithms (support vector machine, k nearest neighbor) to detect bird species [1]. Even though these algorithm predict bird species accurately the visual features are handcrafted. Such way of extracting the feature on massive dataset is cumbersome.

To overcome the handcrafted features deep learning models like CNN for image recognition are much more efficient in accuracy as well as performance compared to machine learning models [2]. Further to improve the accuracy of the model as well as to have better performance the CNN architecture is optimized with Adam [3].

Adam [3] trains the weight of neural network using a separate learning rate for each weight parameter. And hence more efficient and has faster convergence rate than Stochastic Gradient Descent (SGD) [4]. Cross validation is an important hyper parameter tuning approach for training of the dataset. K-fold cross-validation is used to avoid overfitting and make the model more generalized [5].

Our project proposes the architecture using Convolution Neural Network (CNN) and Adam as the optimizer. Also CNN detects endangered Nepalese bird species with a Nepali name about the status species.

## CHAPTER 3

### REQUIREMENT ANALYSIS

Requirements analysis or requirements engineering is a process used to determine the needs and expectations of a new product. It involves frequent communication with the stakeholders and end-users of the product to define expectations, resolve conflicts, and document all the key requirements.

#### 3.1 Functional Requirements

Functional requirements are specifications that describe the functions and capabilities a system or product must have to meet its intended purpose.

**Bird identification:** Our system allows ornithologists and general people detecting different species of birds with greater accuracy.

**Bird Description:** Our system gives the Nepali name and scientific name of the predicted bird.

#### 3.2 Non-Functional Requirements

A Non-functional requirement is a requirement that specifies criteria that can be used to judge the operation of a system, rather than specific behaviors.

- i. **Accuracy:** The system has to give an accuracy greater than 75%.
- ii. **Training Time:** Estimated training time for the algorithm must be less.
- iii. **Maintenance:** The system should be easy to maintain and support.
- iv. **Response time:** Response time must be as quick as possible.

### **3.3 System Requirements**

#### **1. 3.3.1 Hardware Requirements**

- i. A multi-core CPU (e.g., quad-core) is typically sufficient for basic CNN training and inference.
- ii. NVIDIA GTX or AMD RX (GPU) can be used if needed.
- iii. A fast SSD with sufficient capacity (e.g., 256 GB) for storing datasets, model weights, and other training-related files.

#### **3.3.2 Software Requirements**

- Language: Python
- Pytorch
- Web framework: Flask
- Numpy, Sklearn, Optuna and Matplotlib
- Operating System: Windows and Linux
- Frontend: HTML,CSS and Javascript
- IDE: VS code, Jupyter Notebook

### **3.4 Feasibility Study**

In the feasibility study for the Bird Species Recognition project using CNN would typically include the following elements:

#### **3.4.1 Technical Feasibility**

Our model is capable of leveraging available hardware resources like GPUs for accelerated model training and inference. It utilizes the Pytorch

framework and relevant libraries, enabling seamless integration of state-of-the-art deep learning techniques and facilitating the development and deployment of the CNN-based solution. Our team possesses the necessary expertise in deep learning, and PyTorch framework, enabling us to effectively implement and maintain the CNN-based solution, and continually improve its performance through ongoing research and development efforts.

#### **3.4.2 Operational Feasibility**

Our model is designed to be user-friendly and intuitive, ensuring easy acceptance and adoption by wildlife researchers and conservationists who may not have extensive technical expertise in deep learning or computer vision. We provide comprehensive training materials, documentation, and ongoing support to users, empowering them to effectively utilize the bird species recognition system in their research and conservation efforts. With robust data management practices in place, our model efficiently handles data storage, retrieval, and organization tasks, ensuring data integrity, security, and compliance with regulatory requirements.

#### **3.4.3 Economic Feasibility**

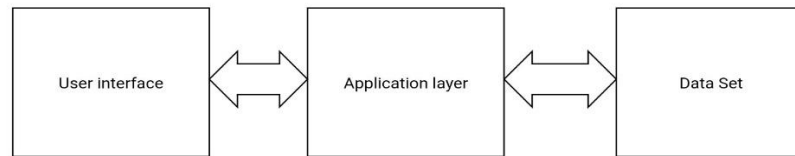
Our model offers a cost-effective solution for bird species recognition balancing initial investment with long term operational costs. Through thorough cost-benefit analysis, we've determined that the benefits of improved wildlife monitoring outweigh project costs, making it a sound investment. Our scalable approach optimizes resource utilization, maximizing return on investment for wildlife research and conservation efforts.



## CHAPTER 4

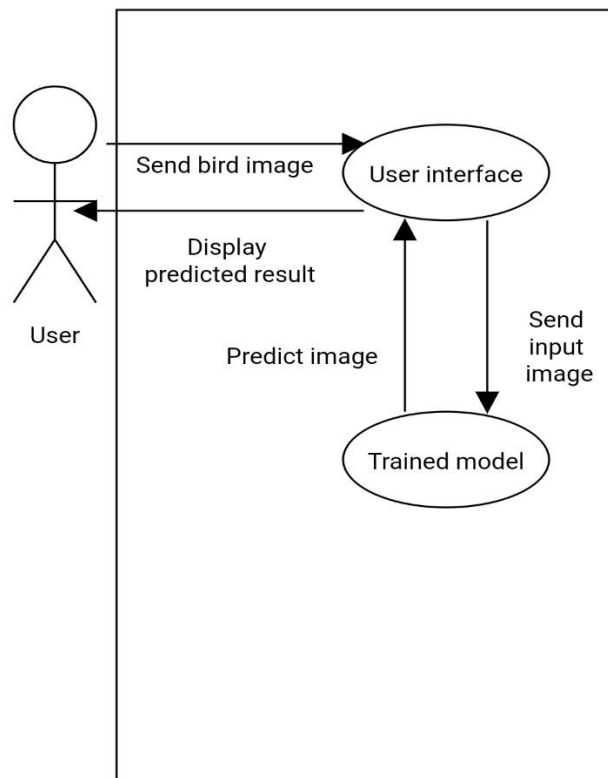
### SYSTEM DESIGN AND ARCHITECTURE

#### 4.1 System Architecture:-



*Fig 4.1: System Architecture*

#### 4.2 Use Case Diagram:-



*Fig 4.2: Use Case Diagram*

### 4.3 Flowchart:-

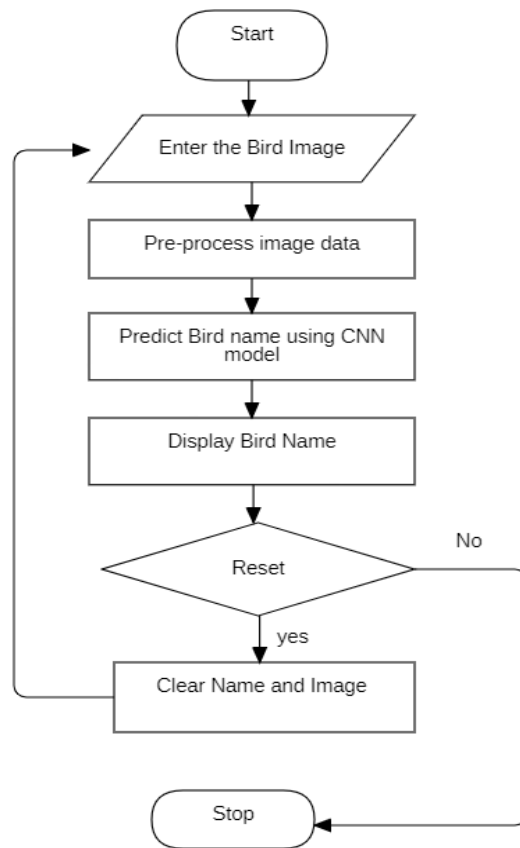


Fig 4.3: Flowchart

### 4.4 DFD Level 0:-

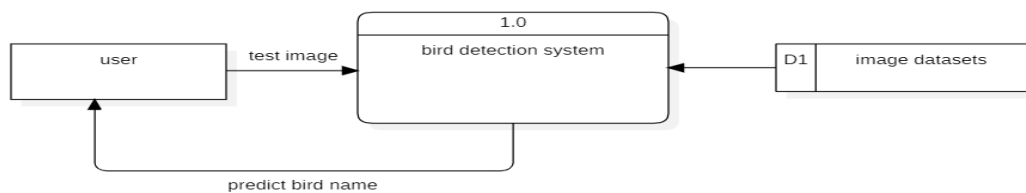


Fig 4.4: DFD Level 0

#### 4.5 DFD Level 1:-

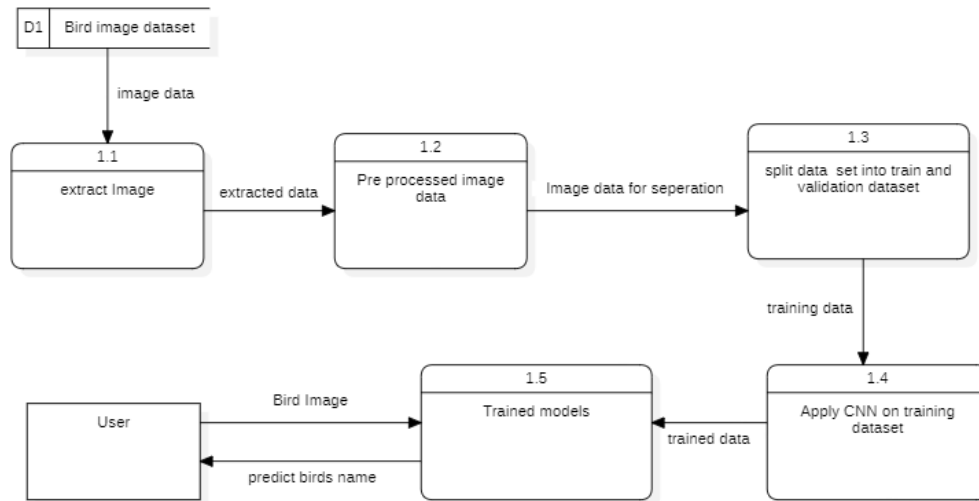


Fig 4.5: DFD Level 1

## CHAPTER 5

### METHODOLOGY

The proposed project aims to develop a system that can classify different species of birds.

#### **5.1 Software Development Model:**

Prototyping is defined as the process of developing a working replication of a product or system that has to be engineered. It offers a small-scale facsimile of the end product and is used for obtaining customer feedback.

In this model, a prototype of the end product is first developed, tested, and refined as per customer feedback repeatedly till a final acceptable prototype is achieved which forms the basis for developing the final product.

**Step 1: Initial Requirement:** This is the initial step in designing a prototype model. In this phase, users are asked about what they expect or what they want from the system.

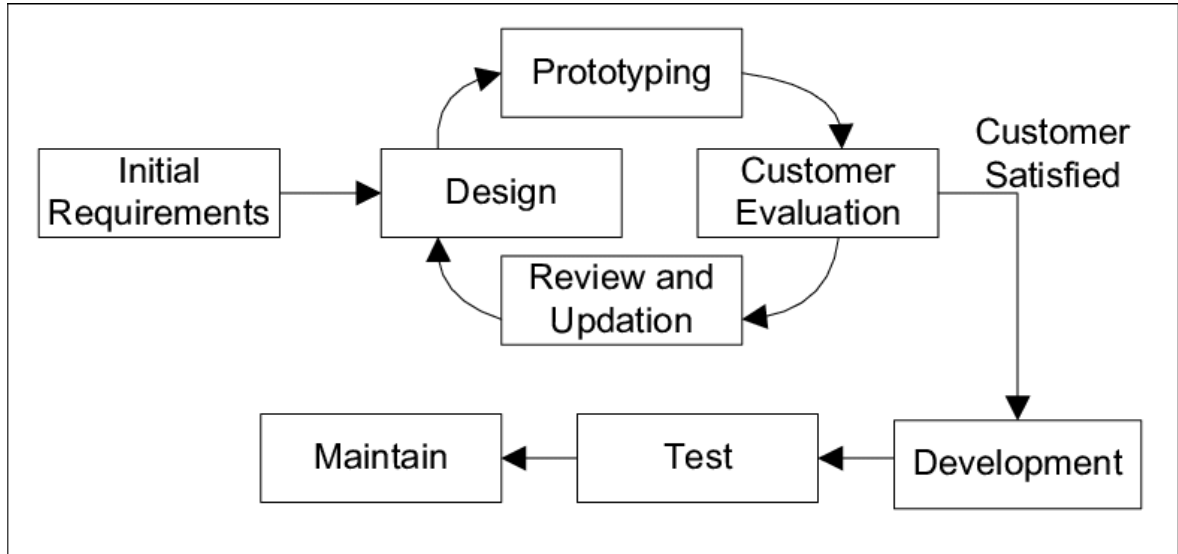
**Step 2: Quick Design:** This is the second step in Prototyping Model. This model covers the basic design of the requirement through which a quick overview can be easily described.

**Step 3: Build a Prototype:** This step helps in building an actual prototype from the knowledge gained from prototype design.

**Step 4: Initial User Evaluation:** This step describes the preliminary testing where the investigation of the performance model occurs, as the customer will tell the strength and weaknesses of the design, which was sent to the developer.

**Step 5: Refining Prototype:** If any feedback is given by the user, then improving the client's response to feedback and suggestions, the final system is approved.

**Step 6: Implement Product and Maintain:** This is the final step in the phase of the Prototyping Model where the final system is tested and distributed to production, here program is run regularly to prevent failures.



*Fig 5.1: Prototype model*

Source: [https://www.researchgate.net/figure/Prototype-Model-3\\_fig1\\_313786662](https://www.researchgate.net/figure/Prototype-Model-3_fig1_313786662)

## 5.2 Pre-processing:

Preprocessing is the removal of systematic noise from data and is usually necessary before image classification and analysis. The goal of preprocessing is to attempt to decrease undesirable variety in images due to lighting, scale, deformation, etc. Some of the common preprocessing techniques used in our model are:

### 5.2.1 Image Resize:-

Each image get resized to fixed size of (150,150) pixel in while training dataset.

### 5.2.2 Random Horizontal Flip:-

We implemented random flips of the images horizontally with a probability of 0.5 to induce diversity to training data, enhancing the model's robustness and generalization.

### **5.2.3 Random rotation:-**

The input images are rotated by maximum 15 degree for augmentation of dataset by introducing variation of images.

### **5.2.4 Random resized crop:-**

We randomly crop and resize the input images to a size of 150x150 pixels, with a random scale and aspect ratio for improving model's ability to learn invariant features.

### **5.2.5 Color Jitter:-**

The color of the input images are adjusted randomly by adjusting brightness, contrast and saturation.

### **5.2.6 Normalize:-**

Normalize the pixel values of the input images using specific mean and standard deviation values to standardize the pixel intensities across all images in the dataset.

### **5.2.7 Categorical Encoding:-**

Convert the name of bird to numeric value (labels).

### **5.2.8 Representation and Description:-**

Mapped their unique labels into their respective names in Nepali as well as English.

## **5.3 Algorithm: -**

### **5.3.1 Convolutional Neural Network (CNN): -**

Convolutional neural network (CNN) is designed for image classification. It consists of three convolutional layers followed by batch normalization, ReLU activation, max-pooling, and dropout regularization. The model processes input images through these layers to extract features and make predictions about the class labels. It utilizes a feedforward architecture, with information flowing from inputs to outputs, and employs convolution and pooling layers specifically tailored for image analysis tasks. The model is trained on a dataset containing images of various classes, enabling it to learn and recognize patterns associated with different objects or categories. Once trained, the model can be used to classify new images, providing valuable insights and predictions based on the

learned features. So, by the image, we can obtain information and predict the species from the trained model with the help of Figure 1.

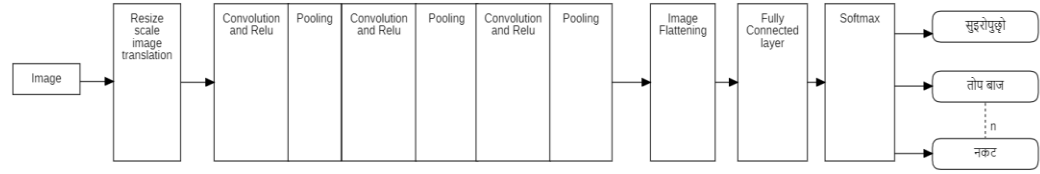


Fig 5.3.1.: Block diagram of system

### 5.3.2 Feature Extraction:-

Features are found whenever the network performs a sequence of convolutional and pooling procedures.

#### 5.3.2.1 Convolutional layer:-

Convolutional layers, pooling layers, and fully connected layers are the three main types of convolutional neural network layers. Convolutional layers perform operations on their inputs before passing the result to the next layer. It applies a set of learnable filters known as the kernels of size 3x3 to the input images. It slides over the input image data and computes the dot product between kernel weight and the corresponding input image patch. The output of this layer is referred to as feature maps. Here we use a total of 12 filters for this layer we'll get an output volume of dimension 32 x 32 x 12.

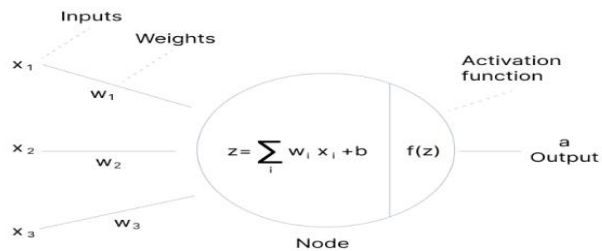


Fig5.3.2: Activation Function

Source: [https://www.researchgate.net/figure/Single-layer-perceptron-model\\_fig1\\_354134028](https://www.researchgate.net/figure/Single-layer-perceptron-model_fig1_354134028)

#### 5.3.2.2 Activation layer:-

By adding an activation function to the output of the preceding layer, activation layers add nonlinearity to the network. It will apply an element-wise activation function to the output of the convolution layer.

One common activation function is ReLU.

$$R(z)=\max(0,z)$$

ReLU is half rectified (from bottom). Here  $f(z)$  is zero when  $z$  is less than zero and  $f(z)$  is equal to  $z$  when  $z$  is above or equal to zero.

#### 5.3.2.3 Pooling layer:-

Local or global pooling layers of convolutional networks integrate the output of groups of neurons in one layer into individual neurons in the next layer. It assists in minimizing the size of the feature maps and increases the model's resistance to slight changes in the input pictures. We use max pooling in our neural network. Max pooling is a downsampling technique commonly used in convolutional neural networks (CNNs) to reduce the spatial dimensions of an input volume.

#### 5.3.2.4 Fully Connected layer:-

Connected layers allow every neuron in one layer to further communicate with every neuron in every other layer. It takes the input from the previous layer and computes the final classification or regression task. We use softmax function as:

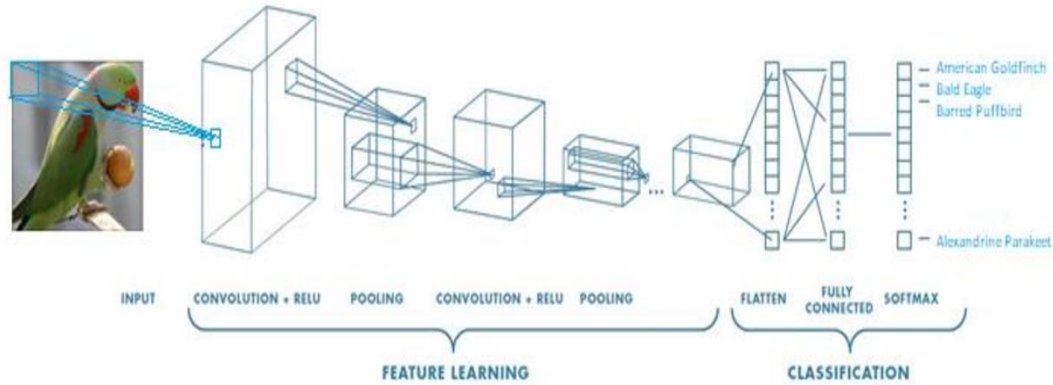
$$\sigma(z)_i = \frac{e^{z_i}}{\sum_{j=1}^K e^{z_j}}$$

#### 5.3.2.5 Classification:-

Putting anything or someone right into a certain organization or system primarily based on unique standards is the definition of classifying.

The classification module takes the pre-processed images and predicts the bird species. The results are then displayed to the user. The accuracy of the classification depends on the quality of the dataset, the training algorithm used, and the size of the training dataset.





*Fig 5.3.3: Convolutional operation*

Source: <https://www.semanticscholar.org/paper/IMAGE-BASED-BIRD-SPECIES-IDENTIFICATION-USING-DEEP-Siva-Reddy/9a8bcba6b02a8973f9f99217bfce6b67aa5980e7>

## 5.4 Optimizer

The optimizer plays a crucial role in training neural networks. In this implementation, the Adam optimizer is utilized, which is an adaptive learning rate optimization algorithm. It efficiently computes adaptive learning rates for each parameter based on their first and second-order moments of gradients. The optimizer is initialized with a learning rate of 0.0001 and a weight decay of 0.001 to encourage regularization during training. These hyper parameters can be adjusted based on the specific requirements of the training task and the characteristics of the dataset.

## 5.5 Cross validation:

Cross-validation is a robust technique used to assess the performance and generalization ability of machine learning models. In this implementation, k-fold cross-validation is employed, where the dataset is divided into k subsets or folds. The model is trained k times, each time using k-1 folds for training and the remaining fold for validation. This process helps in obtaining a more reliable estimate of the model's performance by reducing bias and variance. Stratified k-fold cross-validation is used here to ensure that each fold maintains the same class distribution as the original dataset, thus avoiding potential biases. Early stopping is also implemented, which monitors the validation loss and terminates training if no improvement is observed for a certain number of epochs, thereby preventing overfitting and improving efficiency.



*Fig 5.5: Cross validation*

Source: [https://www.researchgate.net/figure/Schematic-diagram-of-Stratified-K-fold-cross-validation\\_fig3\\_367073570](https://www.researchgate.net/figure/Schematic-diagram-of-Stratified-K-fold-cross-validation_fig3_367073570)

## 5.6 Loss Function:

Our model employs the Cross-Entropy Loss function as its primary measure of performance during training. This loss function, tailored for multi-class classification tasks, quantifies the disparity between predicted class probabilities and true class labels. By penalizing incorrect classifications more heavily, Cross-Entropy Loss incentivizes the model to learn discriminative features essential for accurate predictions. This choice aligns with the nature of the image classification task undertaken by our model, facilitating efficient training and robust performance across diverse classes. Adjusting the loss function according to specific task requirements and dataset characteristics can significantly impact the model's convergence and final performance.

## CHAPTER 6

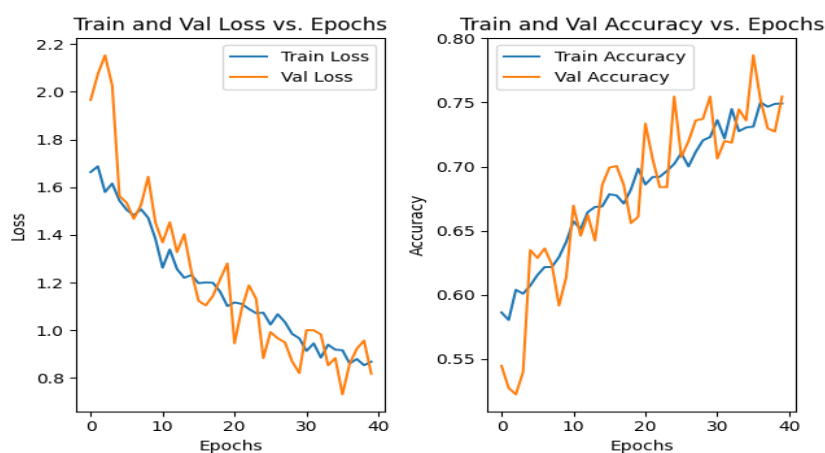
### RESULT AND ANALYSIS

#### 6.1 Dataset:

We gained our dataset from internet as endangered bird species dataset. This dataset contains the data of 38 birds' species with their scientific names and about 8073 images are there in training dataset and 402 images for testing dataset. We changed the name of each birds to unique labels so that we can map them to their respective Nepali names.

#### 6.2 Result:

Based on our codes and model design we have obtained different results on dataset. We have got the train accuracy as about 73% and Validation accuracy as 76%. Here is the accuracy graph of our model.



*Fig 6.1: Train and validation losses and accuracy graph*

### 6.3 Result Obtained:

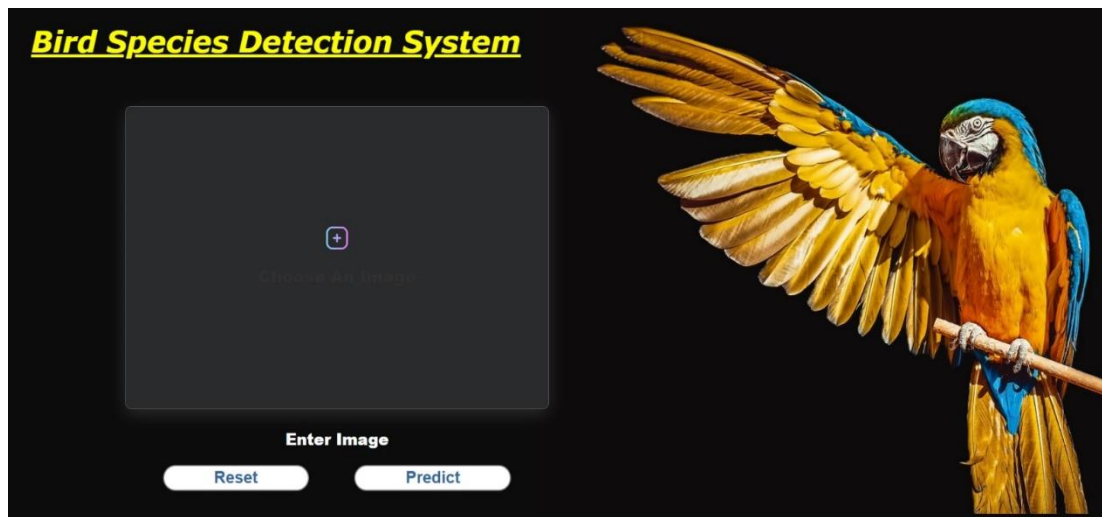


Figure 6.2: User interface

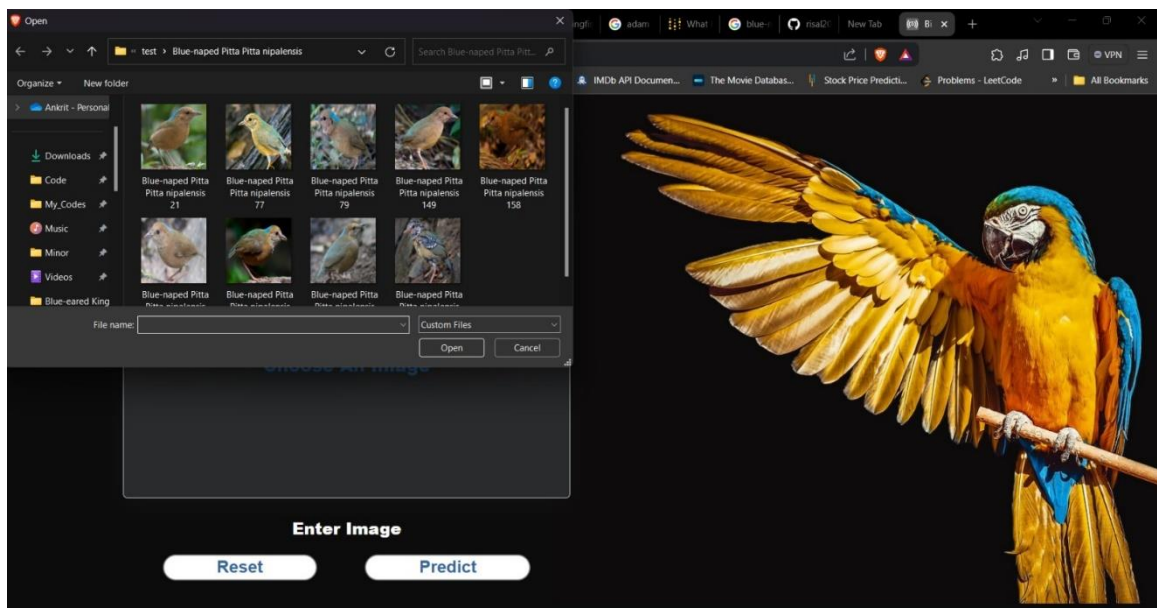


Figure 6.3 Upload photo



*Figure 6.4 Bird Recognition*

## **CHAPTER 7**

### **CONCLUSION, LIMITATIONS AND FUTURE ENHANCEMENT**

#### **7.1 Conclusion**

A Convolutional Neural Network (CNN) has been developed to accurately classify bird species from user-input images. Using this model we have achieved an accuracy of 77%. In this model we have integrated Cross-validation which helps to achieve higher accuracy and hyper-parameters tuning is done to identify the parameter values that is suitable for our model performance.

#### **7.2 Limitations**

There are a few drawbacks regarding bird species classification in our system:

- Our model is based on a limited dataset (38 bird species only).
- Ambiguity and Similarities between the species.
- Can give wrong information if the image is not clear.

#### **7.3 Future Enhancements**

There are several possible future enhancements that could be considered for Bird Species Recognition System:

- Collecting and using a larger, more recent dataset to train and evaluate the models.
- Integrate information from audio recording or environmental data.
- Combine prediction from variation of CNN models to improve performance.

## REFERENCES

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