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Computer Organization

and Architecture

6th Edition

Chapter 7

Input/Output

(revised 10/15/02)

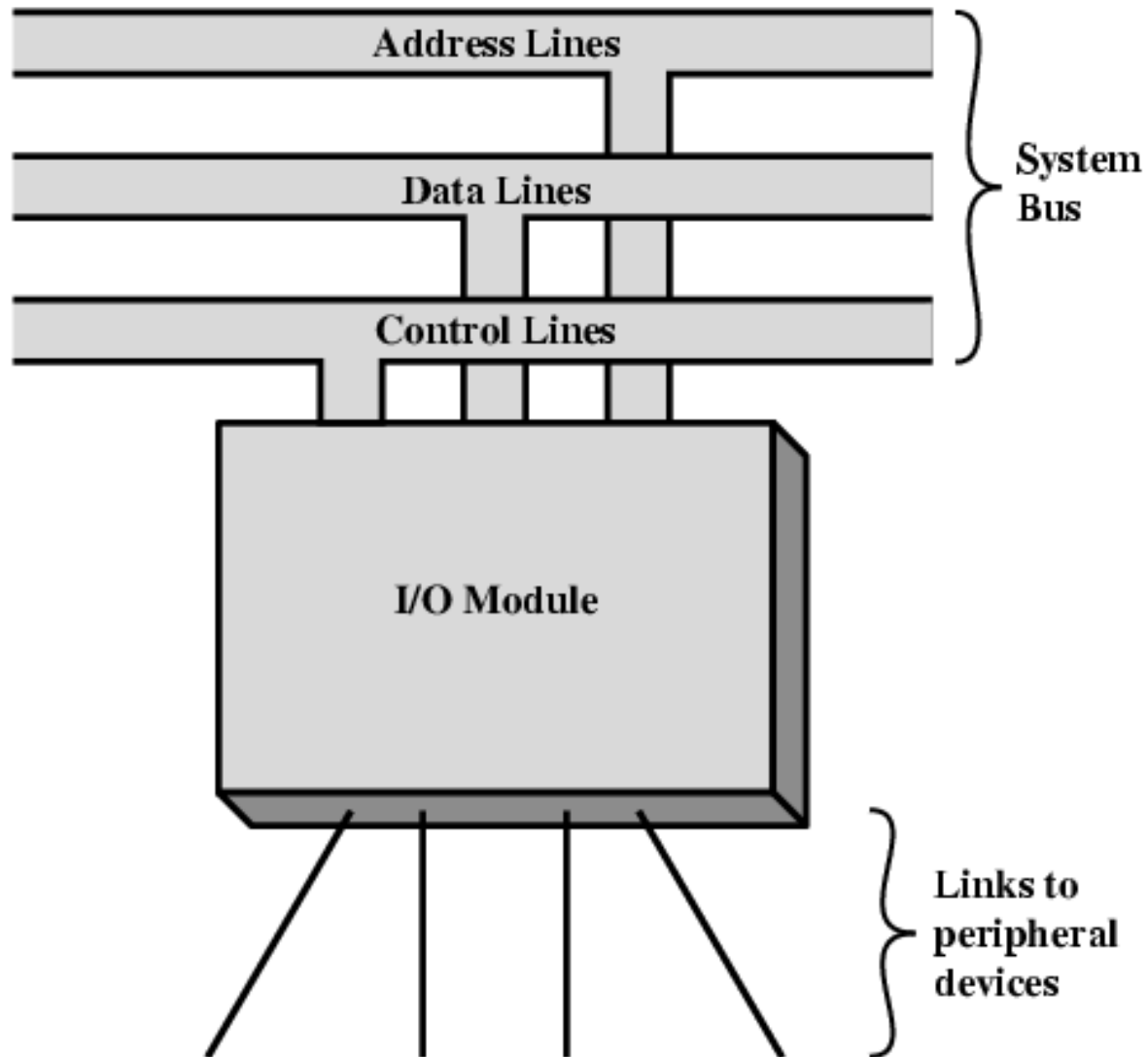
Input/Output Problems

- Wide variety of peripherals
 - Delivering different amounts of data
 - At different speeds
 - In different formats
- All slower than CPU and RAM
- Need I/O modules w/ some “intelligence”

Input/Output Module

- Interface to CPU and Memory
- Interface to one or more peripherals

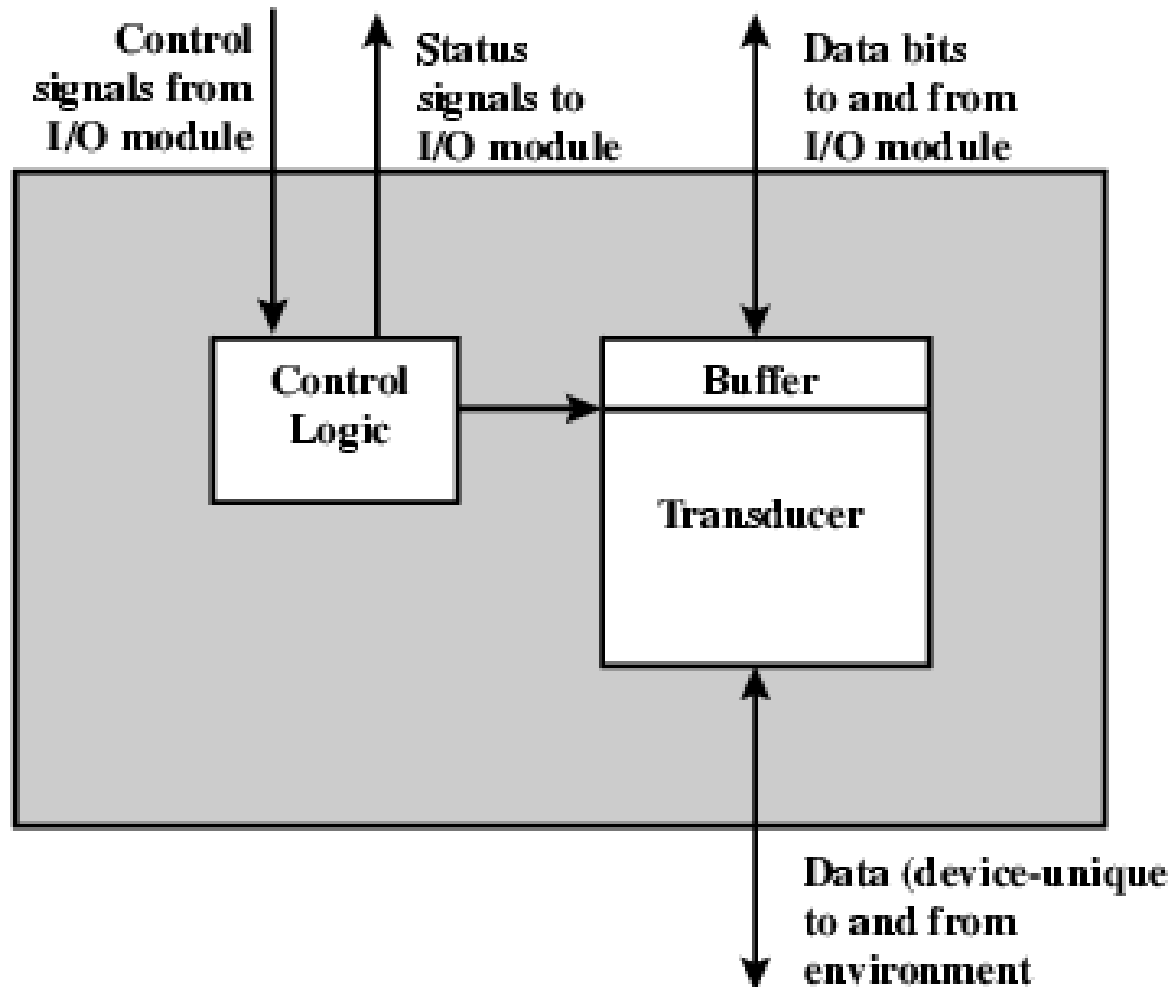
Generic Model of I/O Module



External Devices

- Human readable (human interface)
 - Monitor, printer, keyboard, mouse
- Machine readable
 - Disk, tape, sensors
- Communication
 - Modem
 - Network Interface Card (NIC)

External Device Block Diagram



I/O Module Function

- Control & Timing
- CPU (Processor) Communication
- Device Communication
- Data Buffering
- Error Detection (e.g., extra parity bit)

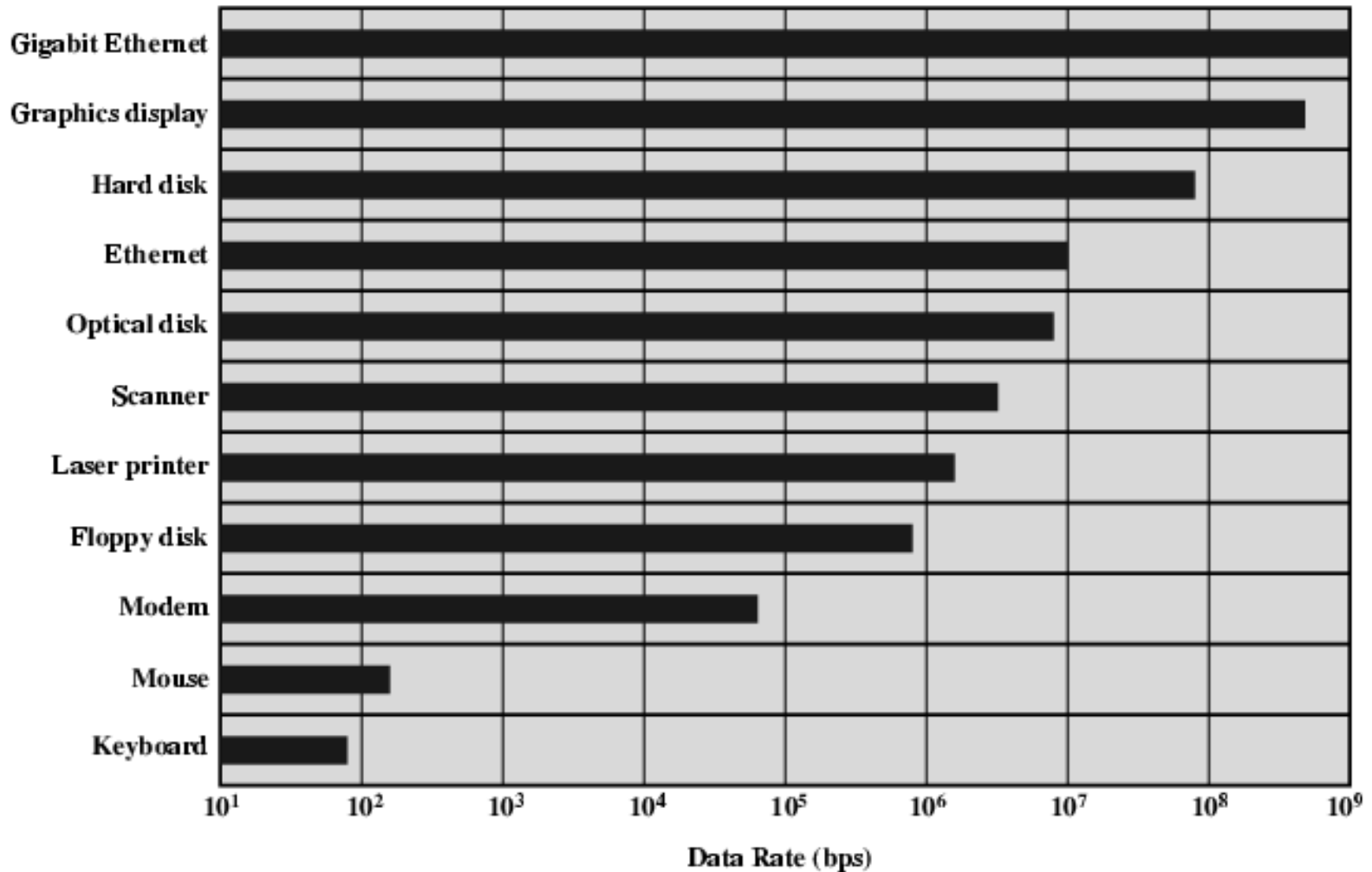
I/O Steps

- CPU checks (interrogates) I/O module device status
- I/O module returns status
- If ready, CPU requests data transfer by sending a command to the I/O module
- I/O module gets a unit of data (byte, word, etc.) from device
- I/O module transfers data to CPU
- Variations of these steps for output, DMA, etc.

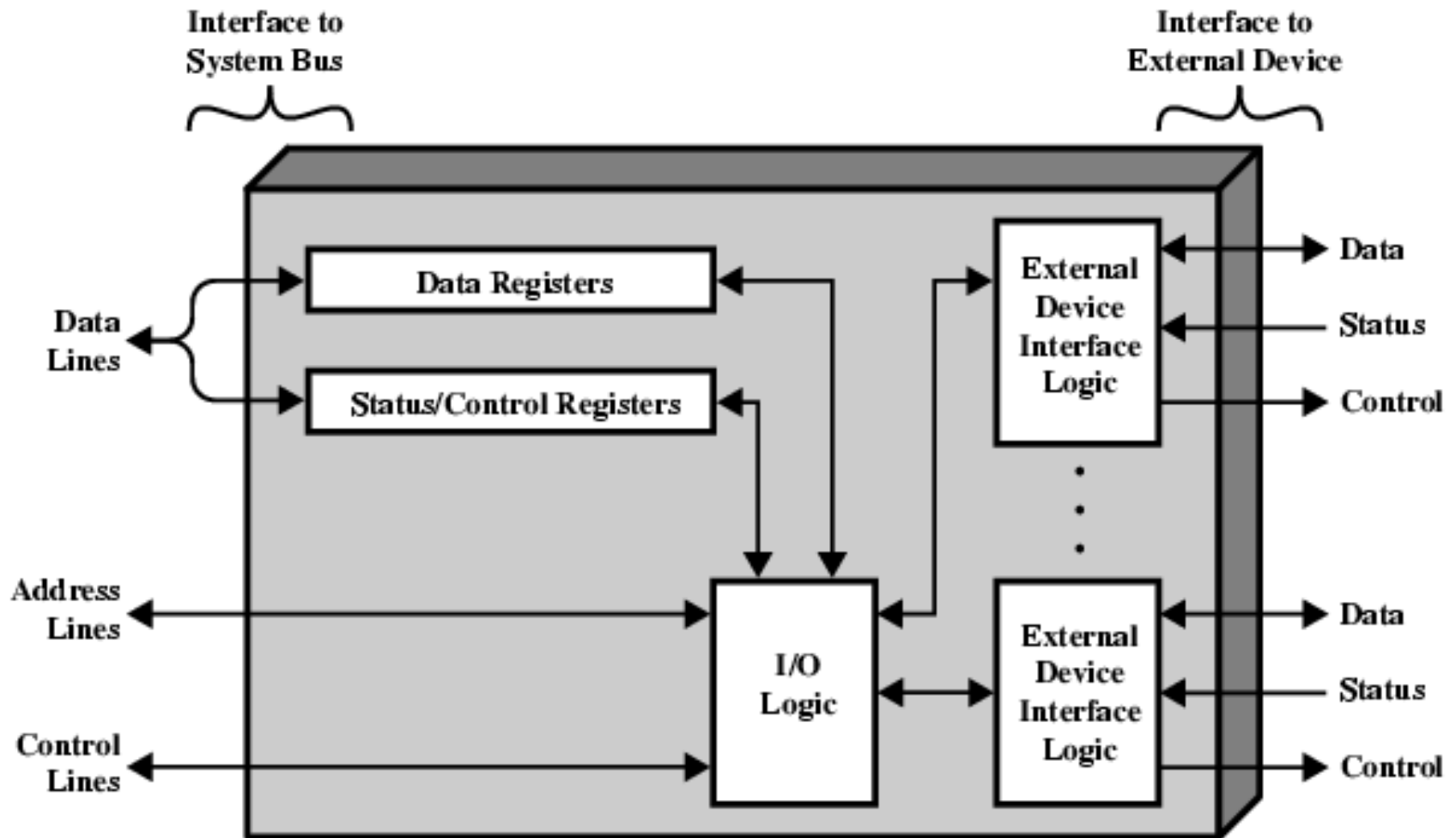
Processor/device Communications

- Command decoding
- Data
- Status reporting
- Address recognition

Need for Data Buffering: Typical I/O Data Rates



I/O Module Diagram



I/O Module Decisions

- Hide or reveal device properties to CPU
- Support multiple or single device
- Control device functions or leave for CPU
- Also O/S decisions
 - e.g. Unix treats everything it can as a file

Input Output Techniques

- Programmed
- Interrupt driven
- Direct Memory Access (DMA)

Programmed I/O

- CPU has direct control over I/O
 - Sensing status
 - Read/write commands
 - Transferring data
- CPU waits for I/O module to complete operation
- Wastes CPU time

Programmed I/O - detail

- CPU requests I/O operation
- I/O module performs operation
- I/O module sets status bits
- CPU checks status bits periodically
- I/O module does not inform CPU directly
- I/O module does not interrupt CPU
- CPU may wait or come back later

I/O Commands

- CPU issues address
 - Identifies module (& device if >1 per module)
- CPU issues command
 - Control - telling module what to do
 - e.g. spin up disk
 - Test - check status
 - e.g. power? Error?
 - Read/Write
 - Module transfers data via buffer from/to device

Addressing I/O Devices

- Under programmed I/O data transfer is very like memory access (CPU viewpoint)
- Each device given unique identifier
- CPU commands contain identifier (address)

I/O Mapping

- Memory mapped I/O
 - Devices and memory share an address space
 - I/O looks just like memory read/write
 - No special commands for I/O
 - Large selection of memory access commands available
- Isolated I/O
 - Separate address spaces
 - Need I/O or memory select lines
 - Special commands for I/O
 - Limited set

Interrupt Driven I/O

- Overcomes CPU waiting
- No repeated CPU checking of device
- I/O module interrupts when ready

Interrupt Driven I/O

Basic Operation

- CPU issues read command
- I/O module gets data from peripheral whilst CPU does other work
- I/O module interrupts CPU
- CPU requests data
- I/O module transfers data

CPU Viewpoint

- Issue read command
- Do other work
- Check for interrupt at end of each instruction cycle
- If interrupted:-
 - Save context (registers)
 - Process interrupt
 - Fetch data & store
- See Operating Systems notes

Design Issues

- How do you identify the module issuing the interrupt?
- How do you deal with multiple interrupts?
 - i.e. an interrupt handler being interrupted

Identifying Interrupting Module (1)

- Different line for each module
 - PC
 - Limits number of devices
- Software poll
 - CPU asks each module in turn
 - Slow

Identifying Interrupting Module (2)

- Daisy Chain or Hardware poll
 - Interrupt Acknowledge sent down a chain
 - Module responsible places vector on bus
 - CPU uses vector to identify handler routine
- Bus Master
 - Module must claim the bus before it can raise interrupt
 - e.g. PCI & SCSI

Multiple Interrupts

- Each interrupt line has a priority
- Higher priority lines can interrupt lower priority lines
- If bus mastering only current master can interrupt

Example - PC Bus

- 80x86 has one interrupt line
- 8086 based systems use one 8259A interrupt controller
- 8259A has 8 interrupt lines

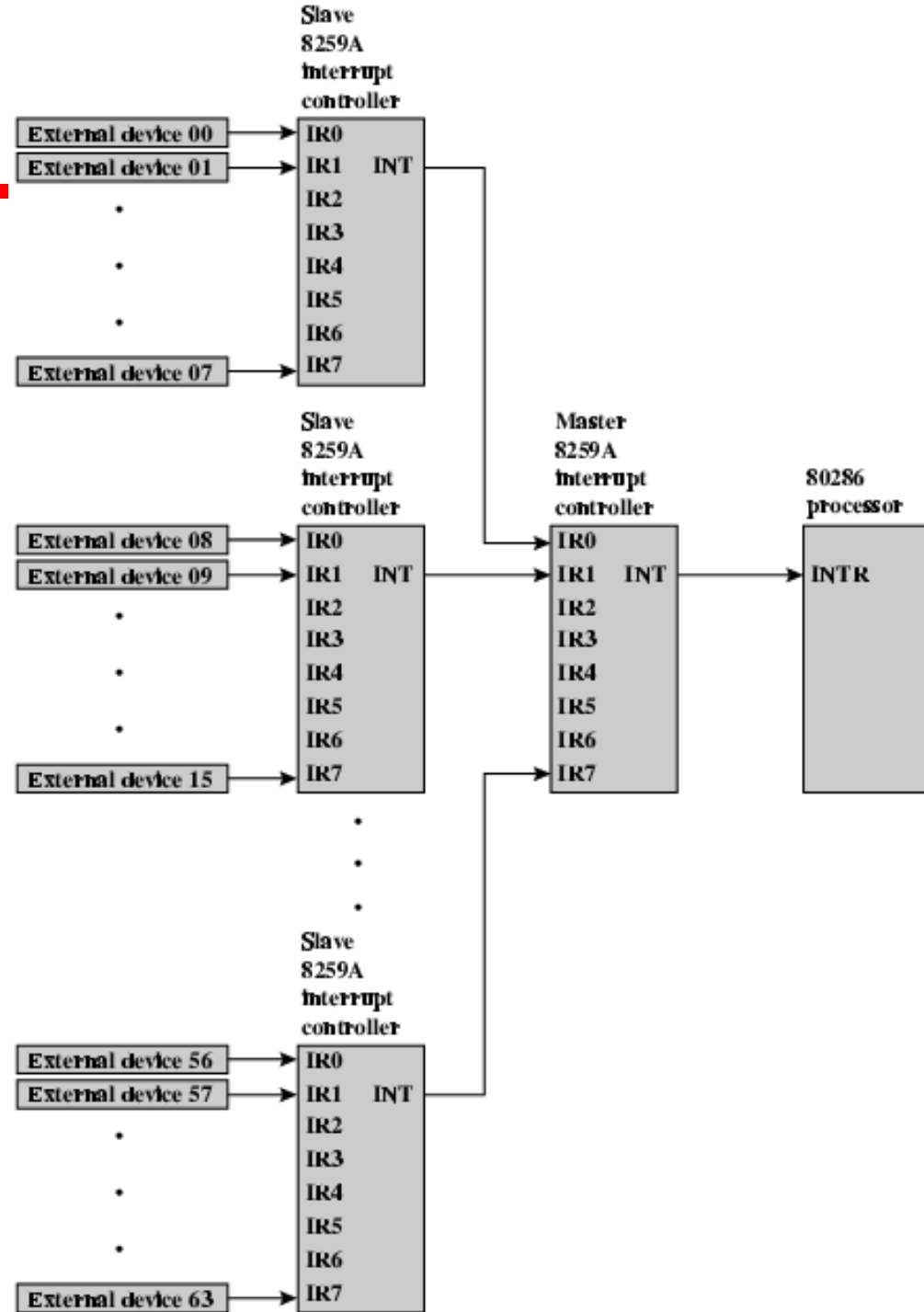
Sequence of Events

- 8259A accepts interrupts
- 8259A determines priority
- 8259A signals 8086 (raises INTR line)
- CPU Acknowledges
- 8259A puts correct vector on data bus
- CPU processes interrupt

ISA Bus Interrupt System

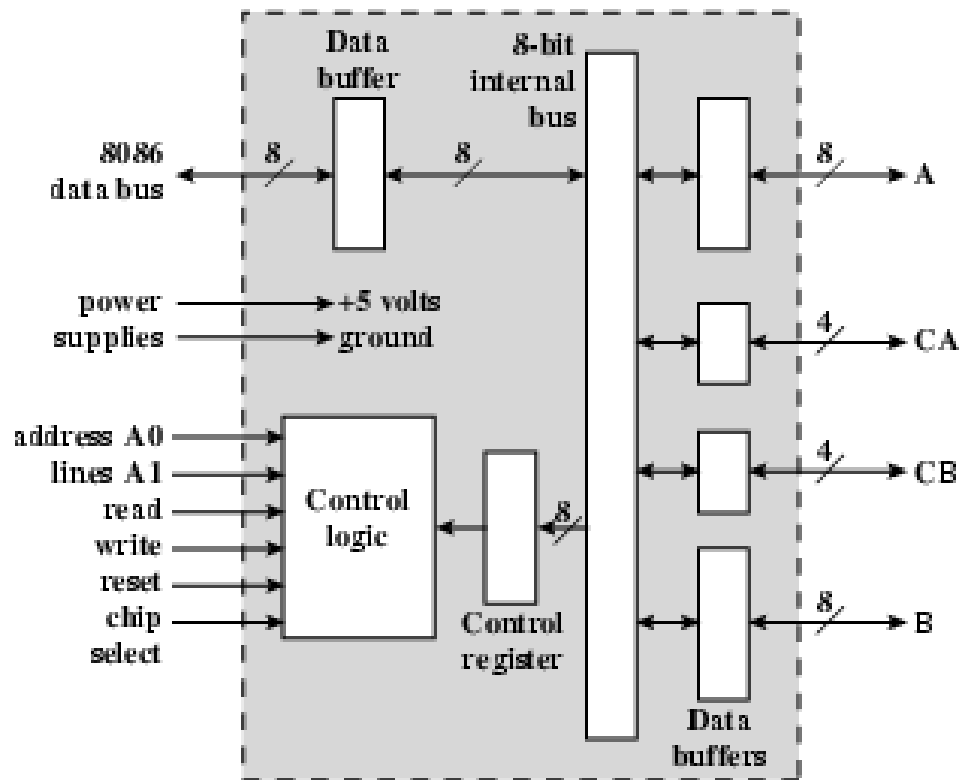
- ISA bus chains two 8259As together
- Link is via interrupt 2
- Gives 15 lines
 - 16 lines less one for link
- IRQ 9 is used to re-route anything trying to use IRQ 2
 - Backwards compatibility
- Incorporated in chip set

82C59A Interrupt Controller

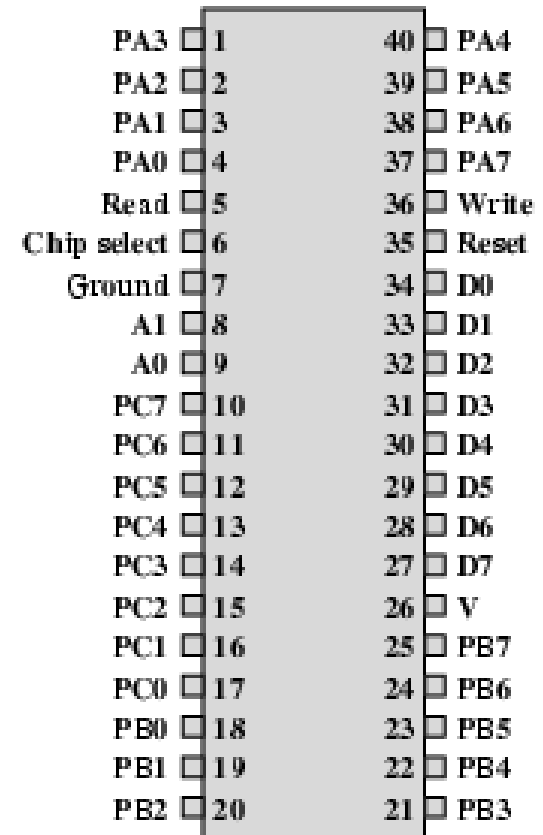


Intel 82C55A

Programmable Peripheral Interface

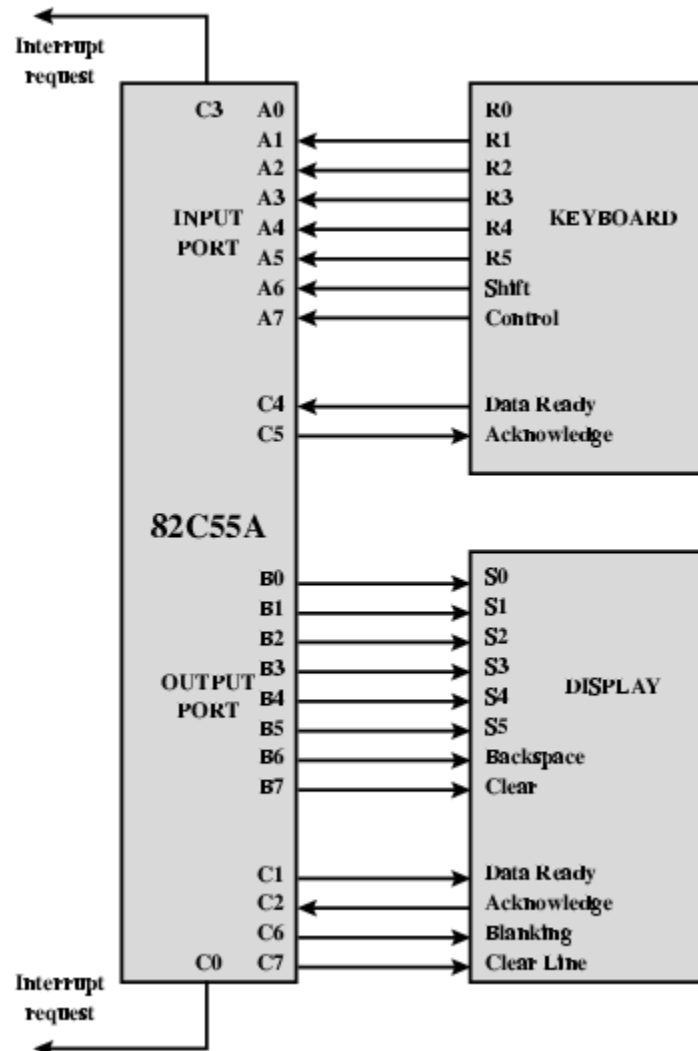


(a) Block diagram



(b) Pin layout

Using 82C55A To Control Keyboard/Display

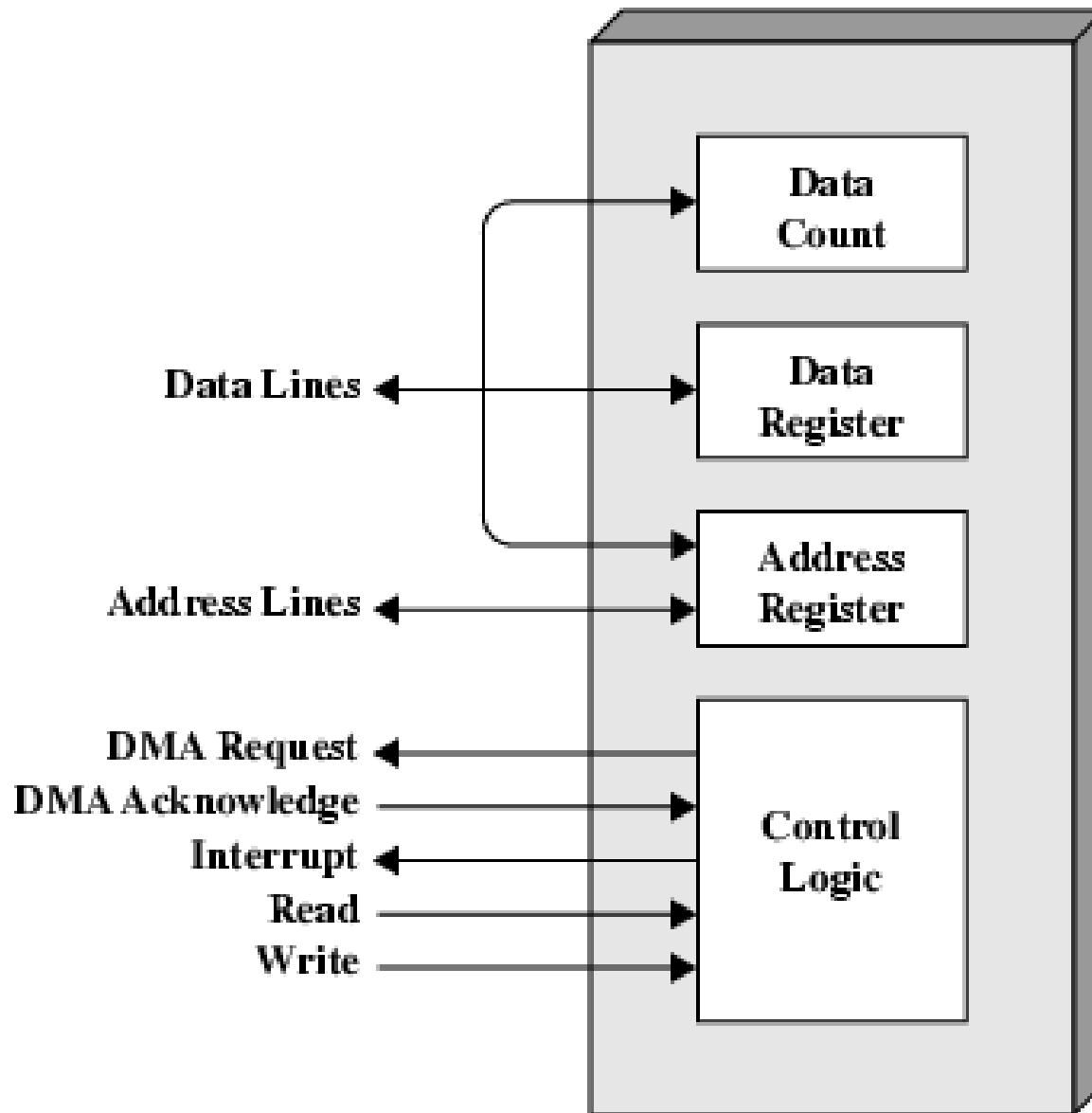


Direct Memory Access

- Interrupt driven and programmed I/O require active CPU intervention
 - Transfer rate is limited
 - CPU is tied up
- DMA is the answer

DMA Function

- Additional Module (hardware) on bus
- DMA controller takes over from CPU for I/O



DMA Operation

- CPU tells DMA controller:-
 - Read/Write
 - Device address
 - Starting address of memory block for data
 - Amount of data to be transferred
- CPU carries on with other work
- DMA controller deals with transfer
- DMA controller sends interrupt when finished

DMA Transfer Cycle Stealing

- DMA controller takes over bus for a cycle
- Transfer of one word of data
- Not an interrupt
 - CPU does not switch context
- CPU suspended just before it accesses bus
 - i.e. before an operand or data fetch or a data write
- Slows down CPU but not as much as CPU doing transfer

Aside

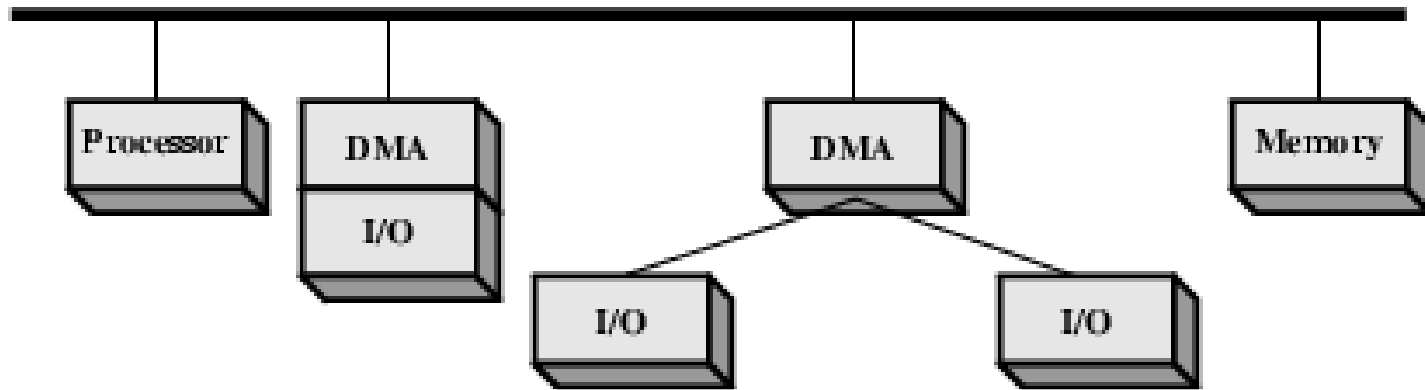
- What effect does caching memory have on DMA?
- Hint: how much are the system buses available?

DMA Configurations (1)



- Single Bus, Detached DMA controller
- Each transfer uses bus twice
 - I/O to DMA then DMA to memory
- CPU is suspended twice

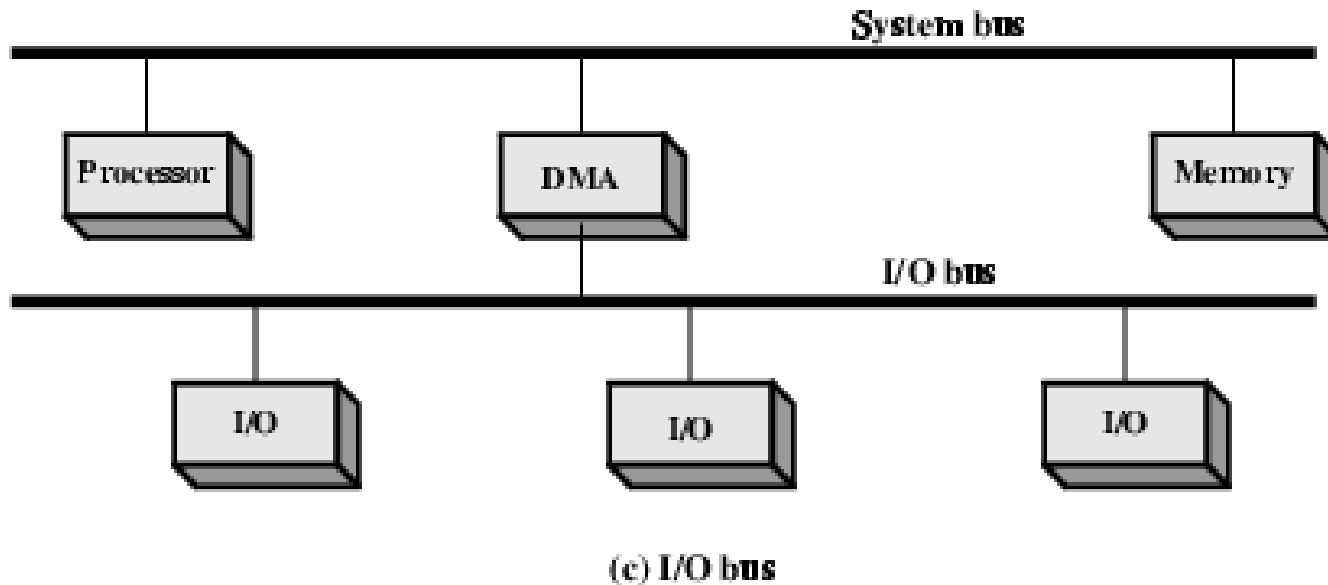
DMA Configurations (2)



(b) Single-bus, Integrated DMA-I/O

- Single Bus, Integrated DMA controller
- Controller may support >1 device
- Each transfer uses bus once
 - DMA to memory
- CPU is suspended once

DMA Configurations (3)



- Separate I/O Bus
- Bus supports all DMA enabled devices
- Each transfer uses bus once
 - DMA to memory
- CPU is suspended once