

Assignment No: 4

Aim: Understanding the connectivity of Raspberry - Pi / Beagle board circuit with IR sensor write an application to detect obstacle & notify user using LED's.

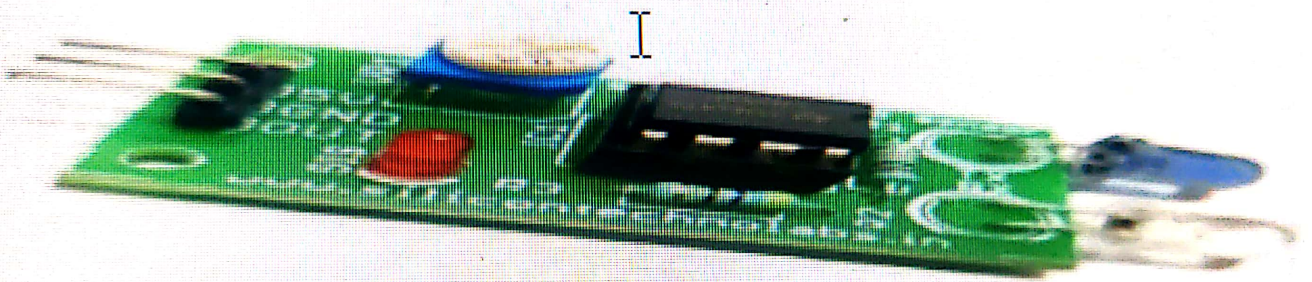
// Theory

- Emitter : The component continuously emits the signal
- Receiver : It waits for the signal which is bounced back by obstacle
- Indicator : An onboard LED to signal if obstacle is detected by the sensor.
- O/p : Could be used as I/p for future processing of the signal.
- Ground : Ground / Negative
- voltage : I/p 3.3V

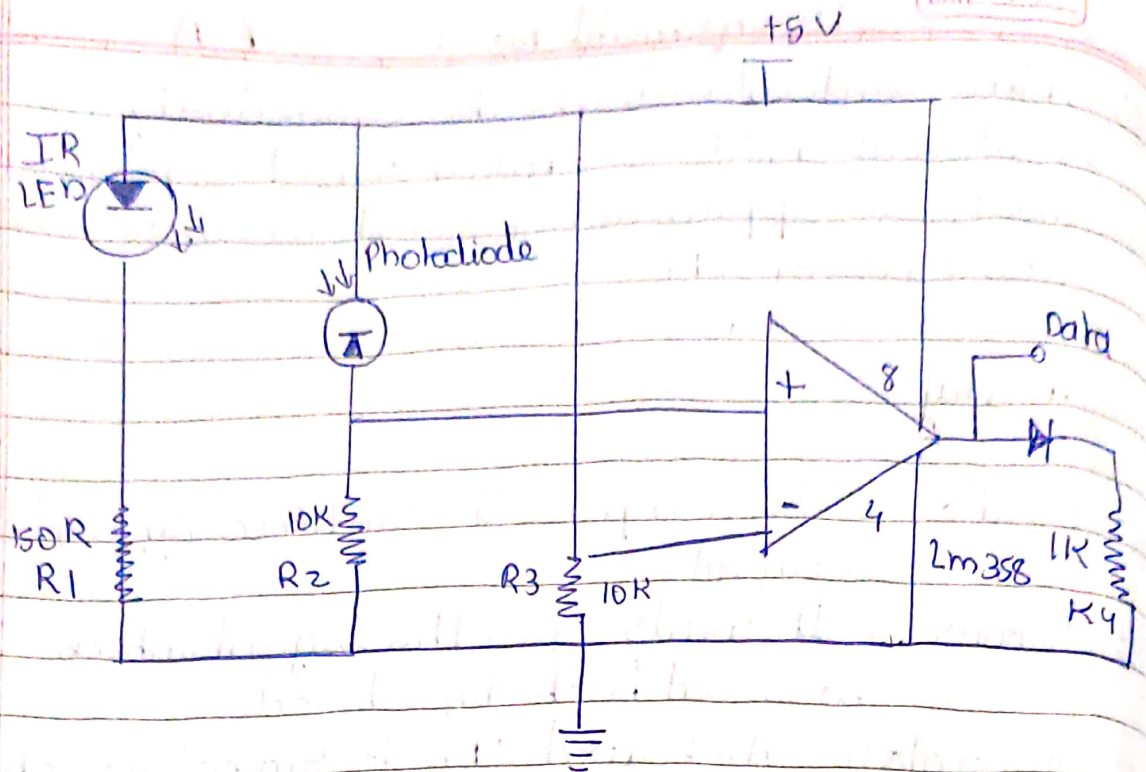
= Objective

We will be creating circuit using following components

- Raspberry pi-3
- IR sensor
- 1 LED
- 1 resistor (33 Ω)
- Few jumper cables
- 1 Breadboard



IR Sensor Fig.1



Circuit diagram for IR sensor

Circuit to detect obstacles

Part I Connecting IR sensor

IR sensor has 3 pins, V_{i2} , V_{cc} , GND & out. We will use GPIO for receiving ip from sensor.

1. Connect GPIO pin from Raspberry Pi to Breadboard
2. Connect output of sensor with Breadboard
3. Connect GND with -ve line on left side of the breadboard
4. Connect GND of IR sensor to breadboard
5. Connect GND for step 3 to breadboard
6. Connect V_{cc} of the IR sensor to breadboard
7. Connect 3V3 (Pin #1) to +ve line on right side of the breadboard.
8. Connect 3V3 to breadboard.

Now circuit is completed and sensor will detect the obstacle. It can be tested by putting

anything in front of IR sensor

Part 2 Connecting LED

Objective is to turn on LED when obstacle is detected

1. Connected GPIO 4 follow the board to the breadboard
 2. Connect the pt of LED to breadboard
 3. Connect -ve pt of LED to the breadboard
- Now we are ready to send signal based on i/p received from IR sensor to turn on/off the LED

Part 3: code to connect IR sensor I/p with LED status

Part 4: Executing the code

- open Terminal
- Navigate to directory where the above code is saved
- Type `python 3 ie obstacle.py` & press enter

Conclusion

Thus we have done connectivity of raspberry Pi / beagle board circuit with IR sensor. and wrote app to detect obstacle & notify user using LED.

Part 3: Code to Connect IR Sensor I/P with LED status

from GPO zero import LED

from signal import pause

import R pi.GPIO as GPIO

import time

```
GPO.set mode(GPIO.BCM)
```

```
LED_PIN = 27
```

```
IR_PIN = 17
```

```
indicator = LED(LED_PIN)
```

```
GPIO.setup(IR_PIN, GPIO.IN)
```

```
count = 1
```

```
while True:
```

```
    got_something = GPIO.input(IR_PIN)
```

```
    if got_something:
```

```
        indicator.on()
```

```
        print("{:>3} Got something".format(count))
```

```
    else:
```

```
        indicator.off()
```

```
        print("{:>3} Nothing detected".format(count))
```

```
        count += 1
```

```
    time.sleep(0.2)
```