ANKIT V. MANERIKAR

West Lafayette, Indiana, USA

Contact: +17656026962 | Email ID: amanerik@purdue.edu | Web: ankitvm.github.io

EDUCATION:

Purdue University, USA	Doctor of Philosophy (PhD) Electrical and Computer Engineering	3.79/4.00	Feb 2023
Purdue University, USA	Master of Science Electrical and Computer Engineering	3.84/4.00	Aug 2017
Mumbai University, India	Bachelor of Engineering Electronics Engineering (First Class with Distinction)	81.52% (1 st Rank)	July 2015
SBM Polytechnic, India	Pre-University Course (Engineering Diploma) Industrial Electronics (First Class with Distinction)	89.26% (1 st Rank)	July 2012

WORK EXPERIENCE:

Intel Corporation

May 2022 – Present

Santa Clara. US

- Conducted design and development to build and optimize AI software for the latest Intel x86 isa.
- Profiled distributed deep learning models to identify performance bottlenecks for state-of-the-art ML workloads worked specifically on the profiling of 3D-UNets and Vision Transformers.
- Worked on ML-based autotuning of DGEMM kernels for deep learning workloads for varying hardware specifications.
- Robot Vision Lab, Purdue University

August 2017 – May 2022

West Lafayette, US

Title: Graduate Research Assistant

Title: Deep Learning SWE Intern

- **Project Member**, *BAA-1703 Contract on Dual Energy ATR for Airport Security* A DoHS (Department of Homeland Security) project to research machine learning methods for X-ray-based threat detection at airport checkpoints. [link]
- **Project Member**, *ALERT TO-7 AATR Initiative*: An ALERT-sponsored project on Adaptive Automatic Target Recognition (AATR) for CT-based Threat Detection Systems for airport baggage screening. [link]
- **Primary Author,** *BagGAN* a StyleGAN-based framework for high-resolution synthesis of baggage CT scans. The research also included one-shot learning for automatic segmentation of synthetic images using StyleGANs.
- **Primary Author**, *DEBISim* a model-based CT simulator software for security screening with ML-based threat detection. [link]
- Cloudmaster, The RVL Cloud (2020- Present) an Openstack-based custom cloud ecosystem for vision applications. [link]
- Developed Robot Motion Planning Algorithms in a ROS environment using RRT and CHOMP techniques. [link]
- Gade Autonomous Systems

June 2016 - July 2016

Title: Intern: Machine Learning, Firmware & Robotics

Mumbai/Frankfurt

- Headed the Firmware team to design HMM/Machine Learning Algorithms for smart devices in fitness/automotive applications.
- Citizen Scales India (P) Ltd.

Dec 2011 - May 2012

Title: Research Intern/Co-op

Mumbai

- Collaborated with the Firmware team for designing Moisture Analysis and Micro-Precision Weighers on an ARM7 platform.
- Technophilia Systems

June 2010 - Nov 2010

Title: Robotics Intern /Co-op

Mumbai

Designed navigation algorithms for a four-wheel drive robot with a centroid-based object-tracking algorithm.

Teaching Experience:

• Graduate Teaching Assistant, Purdue University, USA

Terms

Course: ECE 404 - Introduction to Computer Security

Jan 2021 - May 2021

- Course: ECE 382 - Feedback System Analysis and Design

Jan 2016 - May 2017

RESEARCH EXPERIENCE:

• One Shot Learning for Automatic Segmentation of Synthetic Images Using StyleGANs: [link] (DoHS AATR Initiative – Robot Vision Lab, Purdue University)

A hierarchical support set generator for one-shot learning and annotation of StyleGAN-generated images.

- BagGAN A StyleGAN-based Data Synthesis Software for Baggage CT scans: [link]
 - (DoHS AATR Initiative Robot Vision Lab, Purdue University)
- A StyleGAN-based simulation software for data synthesis of baggage CT and X-ray scans.
- DEBISim A Simulation Pipeline for Material Detection using Dual Energy X-ray Inspection Systems: [pub] [code] (DoHS AATR Initiative – Robot Vision Lab, Purdue University)
- Research and development for a CT Simulation pipeline (DEBISim) for X-ray image data generation designed to train and test Single-/Dual-energy CT based object detection systems for non-destructive testing applications.
- Classifier Design for 3D Segmentation using Dual Energy X-ray Tomography: [pub] (DoHS AATR Initiative – Robot Vision Lab, Purdue University)
- This project involves the design of improved classifier and image reconstruction frameworks for X-ray based object detection.
- Adaptive Automatic Target Recognition (AATR) for CT-Based Object Detection Systems: [pub] (ALERT TO-7 AATR Initiative – Robot Vision Lab, Purdue University)
- This project deals with Adaboost-based X-ray Threat Detectors for segmenting target objects with varying specifications.
- Indoor Place Categorization for Visual SLAM: [video] [GitHub] (Course Project: BME595 (Deep Learning), Fall 2017 – Purdue University)
- Developed a Place Recognition Classifier using ResNet CNNs to learn indoor visual landmarks during mobile robot navigation.
- SLAM-Assisted Coverage Path Planning for Lidar Mapping Systems: [pub1] [pub2] (Digital Photogrammetry Research Group, Purdue University)
- Developed a SLAM-based Pseudo-GNSS/INS framework for a ROS Mobile-Mapping System for terrestrial/aerial mapping.
- Optimal Constrained Coverage Path Planning for Mobile Robot Navigation: [pub] [GitHub] (Course Project: AAE568 (Applied Optimal Control & Estimation), Spring 2016 – Purdue University)
- Developed a Pseudospectral Optimal Control Algorithm for Coverage Path Planning for complex obstacles and boundaries.

MAJOR PUBLICATIONS:

- Manerikar, Ankit, Fangda Li, and Avinash C. Kak. "DEBISim: A simulation pipeline for dual energy CT-based baggage inspection systems." Journal of X-Ray Science and Technology 29.2 (2021): 259-285. [pdf] [code]
- Manerikar, Ankit, Tanmay Prakash, and Avinash C. Kak. "Adaptive target recognition: A case study involving airport baggage screening." Anomaly Detection and Imaging with X-Rays (ADIX) V. Vol. 11404. International Society for Optics and Photonics, 2020. [pdf]
- Manerikar, Ankit, Fangda Li, and Avinash Kak. "A Spectrum-Adaptive Decomposition Method for Effective Atomic Number Estimation using Dual Energy CT." IS&T Electronic Imaging: Computational Imaging VIII, IS&T International Symposium on Electronic Imaging, 2020. [pdf]
- Li, Fangda, Ankit Manerikar, Tanmay Prakash, and Avinash Kak. "A Splitting-Based Iterative Algorithm for GPU-Accelerated Statistical Dual-Energy X-Ray CT Reconstruction." IS&T Electronic Imaging: Computational Imaging VIII, IS&T International Symposium on Electronic Imaging, 2020. [pdf]
- Li, Fangda, Ankit V. Manerikar, and Avinash C. Kak. "RMPD-A Recursive Mid-Point Displacement Algorithm for Path Planning." In Twenty-Eighth International Conference on Automated Planning and Scheduling. 2018. [pdf].
- Shamseldin, Tamer, Ankit Manerikar, Magdy Elbahnasawy, and Ayman Habib. "SLAM-based Pseudo-GNSS/INS localization system for indoor LiDAR mobile mapping systems." In 2018 IEEE/ION Position, Location and Navigation Symposium (PLANS), pp. 197-208. IEEE, 2018. [pdf]
- Manerikar, Ankit, Tamer Shamseldin, and Ayman Habib. "SLAM-Assisted Coverage Path Planning for Indoor LiDAR Mapping Systems." arXiv preprint arXiv:1811.04825 (2018). [pdf]
- Manerikar, Ankit, and Anandpara, Tanvi. "Design of a Practical Cat-righting Reflex (CRR) Model." Procedia Computer Science 45 (2015): 514-523. [pdf][GitHub]

SKILLS:

Core Programming

Computer Vision

Machine Learning

Computer Graphics/Simulation

Robotics

Cloud Computing

Python (Expert), C++ (Proficient), C (Proficient), Matlab (Proficient).

OpenCV, PCL, PyTorch3D.

PvTorch (Expert), TensorFlow, scikit-learn, oneDNN, OpenVINO.

Qt, MayaVi, ASTRA, Simulink. ROS (Expert), Gazebo, ARIA

Openstack (Expert), AWS.

HONORS/AWARDS:

J.R.D. Tata Trust Scholarship Award

Best Student Paper Award

Student Award for Academic Merit

Juhu Lions Club Scholarship Award

Scholarship for Undergraduate Engineering (Years: 2012-13, 2013-14)

"Particle Swarm Optimization in Control Systems Design", IEEE Technomania 2013,

1st Rank in B.E. (Electronics, DJSCoE), 6th Rank in University of Mumbai.

1st Rank in Industrial Electronics (Years: 2008-09, 2009-10, 2010-11, 2011-12)