

ANKIT V. MANERIKAR

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PROFESSIONAL SUMMARY

A PhD in Computer Vision with a wide research and industry experience in the field of Tomographic Image Processing, Robotics and Machine Learning spanning a period of fourteen years, with authorship in multiple publications and encompassing contribution to over ten labs and companies.

EDUCATION

Purdue University, USA	Doctor of Philosophy (PhD) <i>Electrical and Computer Engineering</i>	3.80/4.00	Aug 2023
Purdue University, USA	Master of Science <i>Electrical and Computer Engineering</i>	3.84/4.00	Aug 2017
Mumbai University, India	Bachelor of Engineering <i>Electronics Engineering (First Class with Distinction)</i>	81.52% (1 st Rank)	July 2015
SBM Polytechnic, India	Pre-University Course (Engineering Diploma) <i>Industrial Electronics (First Class with Distinction)</i>	89.26% (1 st Rank)	July 2012

RESEARCH EXPERIENCE

- Robot Vision Lab, Purdue University** Jan 2017 – May 2022
Advisor: Dr Avinash Kak
Title: Graduate Research Assistant
West Lafayette

Major Projects:

- BAA-1703 Contract on Dual Energy ATR for Airport Security:**
A DoHS (Department of Homeland Security) project to research deep learning and adaptive boosting methods for threat detection in airport checkpoint security using Dual Energy CT security screeners.

Contributions:

- GANecdotes - Self-Supervised One Shot Learning for Automatic Segmentation of StyleGAN Images:**
A novel SwAV-based self-supervised learning framework for one-shot segmentation of GAN images – the proposed model outperforms baselines in terms of IoU (by 1.02 %) and speed (by a factor of 4.05).
- BagGAN – A StyleGAN-based Data Synthesis Tool for Baggage X-ray Scans:**
This research focuses on a mitigating the data availability problem for threat detector design by using adversarial networks for annotated data synthesis of baggage CT scans for explosives detection.
- DEBISim – A Simulation Pipeline for Dual Energy CT-Based baggage Inspection Systems:**
The initiative aims at designing a physics-based CT simulation framework for X-ray data generation to aid the testing/training of machine learning algorithms for threat detection with Single-/Dual-energy CT screening.
- Classifier Design for 3D Segmentation using Dual Energy X-ray Tomography:**
This project involves the design of improved classifier frameworks for X-ray based object detection using density and atomic number data from Dual Energy CT.
- ALERT TO-7 Adaptive ATR Initiative:**
An ALERT-sponsored project on Adaptive Automatic Target Recognition (AATR) for CT-based Threat Object Detection Systems for airport baggage screening.

Contributions:

- Adaptive Automatic Target Recognition (AATR) for CT-Based Object Detection Systems:**
This project was a part of the ALERT TO-7 AATR Initiative and involved the design of an Automatic Target Recognition System for adaptively identifying target objects of varying specifications. The design involves a hierarchical supervoxel segmenter coalesced with an AdaBoost classifier for threat object detection.

- **Hierarchical Visual SLAM for Hospital Robotics:**

A robot navigation project in collaboration with Botzee Inc., a robotic think-tank aiming at building dense visual maps for modular robot navigation in hospital environments.

Major Publications:

- Manerikar, Ankit, and Avinash C. Kak. "Self-Supervised One-Shot Learning for Automatic Segmentation of StyleGAN Images." *arXiv preprint arXiv:2303.05639* (2023). [\[pdf\]](#) [\[code\]](#) (Under review by *IEEE T-PAMI*).
- Manerikar, Ankit, Fangda Li, and Avinash C. Kak. "DEBISim: A simulation pipeline for dual energy CT-based baggage inspection systems." *Journal of X-Ray Science and Technology* 29.2 (2021): 259-285. [\[pdf\]](#)[\[code\]](#)
- Manerikar, Ankit, Tanmay Prakash, and Avinash C. Kak. "Adaptive target recognition: A case study involving airport baggage screening." *Anomaly Detection and Imaging with X-Rays (ADIX) V*. Vol. 11404. International Society for Optics and Photonics, 2020. [\[pdf\]](#)
- Manerikar, Ankit, Fangda Li, and Avinash Kak. "A Spectrum-Adaptive Decomposition Method for Effective Atomic Number Estimation using Dual Energy CT." *IS&T Electronic Imaging: Computational Imaging VIII, IS&T International Symposium on Electronic Imaging*, 2020. [\[pdf\]](#)
- Li, Fangda, Ankit Manerikar, Tanmay Prakash, and Avinash Kak. "A Splitting-Based Iterative Algorithm for GPU-Accelerated Statistical Dual-Energy X-Ray CT Reconstruction." *IS&T Electronic Imaging: Computational Imaging VIII, IS&T International Symposium on Electronic Imaging*, 2020. [\[pdf\]](#)
- Li, Fangda, Ankit Manerikar, and Avinash C. Kak. "RMPD—A Recursive Mid-Point Displacement Algorithm for Path Planning." In *28th Intl. Conference on Automated Planning and Scheduling*. 2018. [\[pdf\]](#)
- **Digital Photogrammetry Research Group, Purdue University** Jun 2016 – May 2017
Advisors: Dr Ayman Habib, Dr Melba Crawford **West Lafayette**
Title: Graduate Researcher (Master's Degree)

Major Projects:

- **SLAM-Assisted Coverage Path Planning for Lidar Mapping Systems:**
The research for this project was centred on the development of an efficient Coverage Path Planner for Mapping Vehicles. The developed planner uses a variant of the Exact Cellular Decomposition Method using MSA optimality criterion to implement a routing algorithm to be used with online SLAM.
- **Pseudo-GNSS/INS Systems for Terrestrial/Aerial Photogrammetry Using Online SLAM:**
This implementation encompasses a SLAM-based Pseudo-GNSS/INS system for a Mapping Vehicle equipped with LiDARs and Cameras to operate in GPS-devoid environments. The system has been successfully implemented for indoor Lidar Mapping Systems on a Roomba iCreate2 and using Velodyne 3D LiDARs.

Major Publications:

- Shamseldin, Tamer, Ankit Manerikar, Magdy Elbahnasawy, and Ayman Habib. "SLAM-based Pseudo-GNSS/INS localization system for indoor LiDAR mobile mapping systems." In *2018 IEEE/ION Position, Location and Navigation Symposium (PLANS)*, pp. 197-208. IEEE, 2018. [\[pdf\]](#)
- Manerikar, Ankit, Tamer Shamseldin, and Ayman Habib. "SLAM-Assisted Coverage Path Planning for Indoor LiDAR Mapping Systems." *arXiv preprint arXiv:1811.04825* (2018). [\[pdf\]](#)

TEACHING EXPERIENCE

Purdue University – West Lafayette

Terms

Title: Graduate Teaching Assistant

- | | | | |
|---|------------------------|--|---------------------|
| - | Course: ECE 404 | <i>Introduction to Computer Security</i> | Jan 2021 – May 2021 |
| - | Course: ECE 382 | <i>Feedback System Analysis and Design</i> | Jan 2016 – May 2017 |

PUBLICATIONS:

- Manerikar, Ankit, and Avinash C. Kak. "Self-Supervised One-Shot Learning for Automatic Segmentation of StyleGAN Images." *arXiv preprint arXiv:2303.05639* (2023). [\[pdf\]](#) [\[code\]](#) (Submitted to and under review by *IEEE Transactions on Pattern Analysis and Machine Intelligence*).

- Manerikar, Ankit, Fangda Li, and Avinash C. Kak. "**DEBISim: A simulation pipeline for dual energy CT-based baggage inspection systems.**" *Journal of X-Ray Science and Technology* 29.2 (2021): 259-285. [[pdf](#)] [[code](#)]
- Manerikar, Ankit, Tanmay Prakash, and Avinash C. Kak. "**Adaptive target recognition: A case study involving airport baggage screening.**" *Anomaly Detection and Imaging with X-Rays (ADIX) V*. Vol. 11404. International Society for Optics and Photonics, 2020. [[pdf](#)]
- Manerikar, Ankit, Fangda Li, and Avinash Kak. "**A Spectrum-Adaptive Decomposition Method for Effective Atomic Number Estimation using Dual Energy CT.**" *IS&T Electronic Imaging: Computational Imaging VIII, IS&T International Symposium on Electronic Imaging*, 2020. [[pdf](#)]
- Li, Fangda, Ankit Manerikar, Tanmay Prakash, and Avinash Kak. "**A Splitting-Based Iterative Algorithm for GPU-Accelerated Statistical Dual-Energy X-Ray CT Reconstruction.**" *IS&T Electronic Imaging: Computational Imaging VIII, IS&T International Symposium on Electronic Imaging*, 2020. [[pdf](#)]
- Li, Fangda, Ankit V. Manerikar, and Avinash C. Kak. "**RMPD—A Recursive Mid-Point Displacement Algorithm for Path Planning.**" In *Twenty-Eighth International Conference on Automated Planning and Scheduling*. 2018. [[pdf](#)].
- Shamseldin, Tamer, Ankit Manerikar, Magdy Elbahnasawy, and Ayman Habib. "**SLAM-based Pseudo-GNSS/INS localization system for indoor LiDAR mobile mapping systems.**" In *2018 IEEE/ION Position, Location and Navigation Symposium (PLANS)*, pp. 197-208. IEEE, 2018. [[pdf](#)]
- Manerikar, Ankit, Tamer Shamseldin, and Ayman Habib. "**SLAM-Assisted Coverage Path Planning for Indoor LiDAR Mapping Systems.**" *arXiv preprint arXiv:1811.04825* (2018). [[pdf](#)]
- Manerikar, Ankit, and Anandpara, Tanvi. "**Design of a Practical Cat-righting Reflex (CRR) Model.**" *Procedia Computer Science* 45 (2015): 514-523. [[pdf](#)][[GitHub](#)]

HONORS AND AWARDS

- | | |
|--|--|
| • J.R.D. Tata Trust Scholarship Award | Scholarship for Undergraduate Engineering (Years: 2012-13, 2013-14) |
| • Best Student Paper Award | "Particle Swarm Optimization in Control Systems Design", <i>IEEE Technomania 2013</i> , |
| • Student Award for Academic Merit | 1 st Rank in B.E. (Electronics, DJSCoE),
6 th Rank in University of Mumbai. |
| • Juhu Lions Club Scholarship Award | 1 st Rank in Industrial Electronics
(Years: 2008-09, 2009-10, 2010-11, 2011-12) |

PROFESSIONAL EXPERIENCE

- | | |
|---|--|
| <ul style="list-style-type: none"> • Intel Corporation
<i>Title: AI Algorithm Engineer - oneDNN</i> | <p>Aug 2023 – Present
Hillsboro. US</p> |
| <ul style="list-style-type: none"> - Responsible for development and maintenance of oneDNN, a cross-platform performance library providing highly vectorized and TBB blocks for deep learning applications. [link] - Developed new features and algorithms for the library which are optimized for Intel processors, GPUs and other hardware. | |
| <ul style="list-style-type: none"> • Intel Corporation
<i>Title: Deep Learning SWE Intern</i> | <p>May 2022 – December 2022
Santa Clara. US</p> |
| <ul style="list-style-type: none"> - Conducted design and development to build and optimize AI software for the latest Intel x86 isa. - Profiled distributed deep learning models to identify performance bottlenecks for state-of-the-art ML workloads – worked specifically on the profiling of 3D-UNets and Vision Transformers. - Worked on ML-based autotuning of DGEMM kernels for DL workloads for varying hardware specifications. | |

- Citizen Scales India (P) Ltd.** Dec 2011 - May 2012
Title: *Research Intern/Co-op* **SEEPZ, Mumbai**
 - Collaborated with a team of Firmware Engineers for design of a Moisture Analysis Device on an ARM7 platform.
 - Implemented Regression-based algorithms for Temperature Compensation in Micro-Precision Weighing Scales.
- Technophilia Systems** June 2010 – Nov 2010
Title: *Robotics Intern /Co-op* **Mumbai**
 - Designed a Partial Gait Model for the Autonomous Navigation of a Biped.
 - Designed navigation algorithms on an Atmega-XX platform and with a centroid-based object-tracking algorithm.
- Consultancy Projects:**
- Rollform Equip. Pvt. Ltd.** (Delhi, India): "*Shear Measurement System for Rotary Blade Cutter*" - A. Choudhury.
- S M Technocrats Pvt. Ltd.** (Delhi, India): "*Efficiency Analysis for HF Induction Tube Welding*" - A. Choudhury.

LIST OF OTHER SELECT PROJECTS:

- HMM based Smart Gesture Recognition using Wearable Inertial Sensors:**
(Gade Autonomous Systems, Mumbai)
 - Developed a Machine-Learning algorithm using Hidden Markov Models to perform Gesture Recognition using wearable inertial sensors for adaptively learning a set of repetitive gestures made by an individual.
- Indoor Place Categorization for Visual SLAM:** [\[video\]](#) [\[GitHub\]](#)
(Course Project: BME595 (Deep Learning), Fall 2017 – Purdue University)
 - Developed a Place Recognition Classifier using ResNet CNNs and inductive transfer learning to learn indoor visual landmarks during mobile robot navigation.
- Optimal Constrained Coverage Path Planning for a Mobile Robot:** [\[pdf\]](#) [\[GitHub\]](#)
(Course Project: AAE568 (Applied Optimal Control & Estimation), Spring 2016 – Purdue University)
 - Developed a Pseudospectral Optimal Control based method for a Coverage Path Planning by a Mobile Robot.
 - Simulated a MATLAB model to generate Optimal CPP Trajectory for obstacle avoidance and complex boundaries.
- Position Control Using Ultrasonic Levitation Assembly:** [\[video\]](#)
(Undergraduate Senior Project, University of Mumbai.)
 - Designed a Contactless Precision Position Control system harnessing sound waves to suspend particles in mid-air.
 - Developed digital controller code for the levitation system using a Tiva C-series ARM processor.
- A Portable Soil Health Monitoring System for Dynamic Soil Mapping:** [\[video\]](#)
(Presented at Texas Instruments IIADC, 2014)
 - Implemented a portable UV-VIS spectrophotometer system allowing on-field spectral analysis of soil.
 - Developed a sensing mechanism for measurement of soil OC (Organic Carbon) content using NIR Spectral Peaks.
 - Designed an optoelectronic system as well as signal conditioning circuits for system operation.

SKILLS:

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|---------------------------------------|--|
| • Core Programming | Python (Expert), C++ (Expert), C (Proficient), Matlab (Proficient). |
| • Computer Vision | OpenCV , PCL, PyTorch3D. |
| • Machine Learning | PyTorch (Expert), TensorFlow, scikit-learn , OpenVINO , oneDNN . |
| • Computer Graphics/Simulation | Qt , MayaVi, ASTRA, Simulink. |
| • Robotics | ROS (Expert), Gazebo, ARIA |
| • Developer Tools/IDEs | VSCode , PyCharm , Eclipse IDE, AVR-gcc. |
| • Cloud Computing | Openstack (Expert), Eucalyptus, AWS. |

REFERENCES:

(Available upon request.)