

# Greedy

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# What is Greedy?

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Follows the "looks good" strategy.



# Recap the Graph Algorithm

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- **DFS** (walking in a maze)
  - If we can explore, then explore.
  - If we can not explore, backtrack.
  - Do not re-visit a vertex.
  - Applications
    - Cycle
    - Topological
    - SCC



# Recap the Graph Algorithm

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- **BFS** (waterfront)
  - 1 step from  $r$
  - 2 steps from  $r$
  - ...
  - Application
    - Shortest Path



# Recap the Graph Algorithm

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- **Dijkstra** (a generalized BFS)
  - Explore  $s$ .
  - Explore the closet vertex from  $s$ .
  - Explore the second closest vertex from  $s$ .
  - ...
  - We can use **Fibonacci heap** to improve it.
- **Bellman-Ford**



Are they Greedy?

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Do we have any other  
Greedy?

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# Examples

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- Finding Shortest Path
  - Dijkstra.
- Finishing homework
  - Keep finishing the one with the **closest** deadline.



Is that optimal?

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# Formalize the problem

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- **Input:**  $n$  homework, each homework  $j$  has a size  $s_j$ , and a deadline  $d_j$ .
- **Output:** output a time schedule of doing homework!



# Algorithm

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- Greedy
  - Keep finishing the homework with the **closest** deadline.
- Prove it is optimal.
- What is optimal?
- Claim: If we can not finish all the homework by the greedy order, then no one can finish all the homework on time.

## Discussion



# Proof

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- Claim: If we can not finish all the homework by the greedy order, then no one can finish all the homework on time.
- Proof:
  - If there exist  $i$ , finished later than  $d_i$ , what do we have?



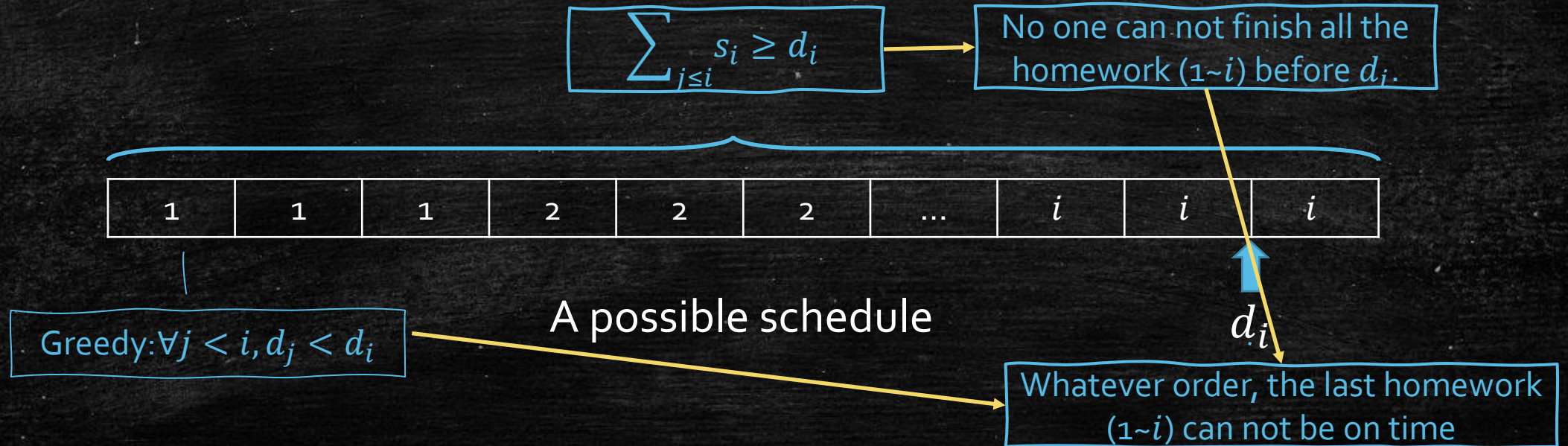
A possible schedule

  
 $d_i$



# Proof

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# Minimum Spanning Tree

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Prime & Kruskal



# Spanning Tree

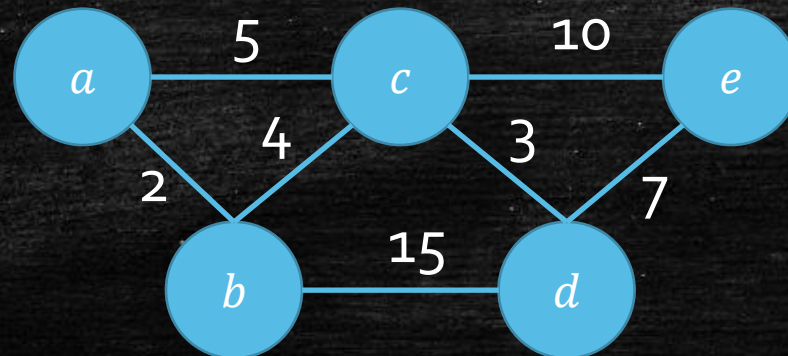
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- **Input:** Given a connected undirected graph  $G = (V, E)$
- **Output:** A spanning tree of  $G$  is, i.e., a subset of edges that forms a tree and contains all the vertices in  $G$ .
- Applications
  - Building a network, connecting all hubs via minimum number of cables.
- Solutions
  - BFS, DFS.



# Minimum Spanning Tree

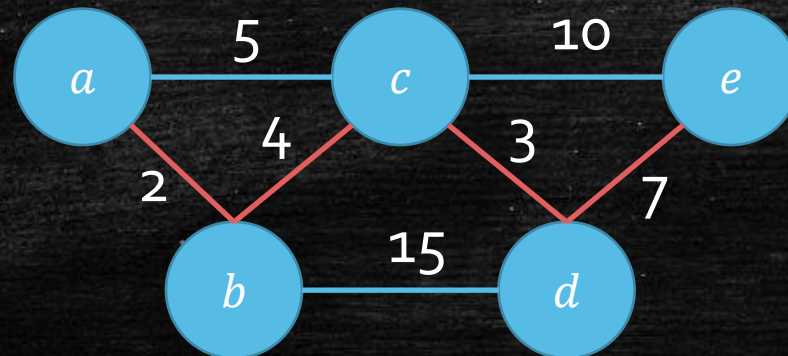
- **Input:** Given a connected undirected graph  $G = (V, E)$ , and a weight function  $w(e)$  for each  $e \in E$ .
- **Output:** A spanning tree of  $G$  is, i.e., a subset of edges, with minimized total weight.
- Applications
  - Building a network, connecting all hubs via minimum number of cables.





# Minimum Spanning Tree

- **Input:** Given a connected undirected graph  $G = (V, E)$ , and a weight function  $w(e)$  for each  $e \in E$ .
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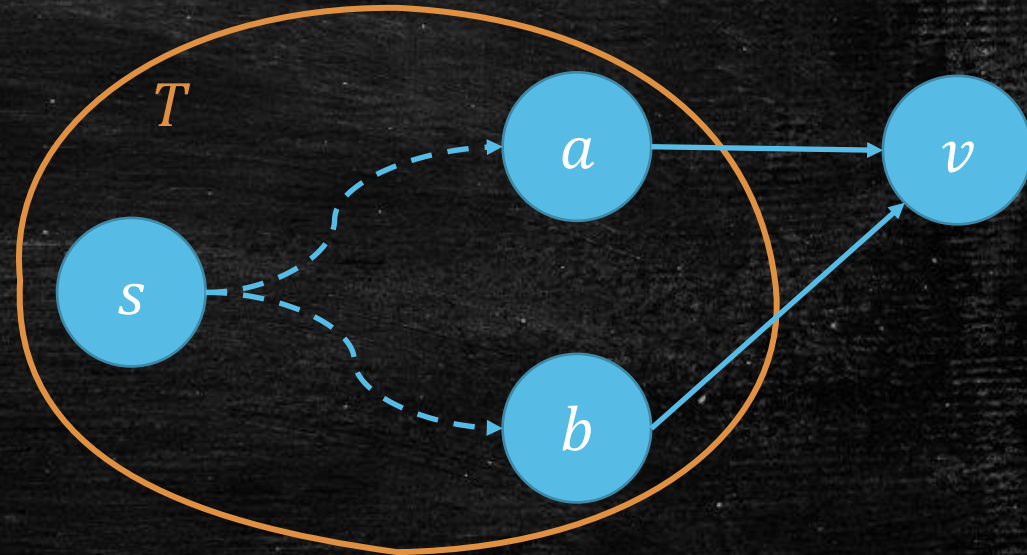




# Dijkstra's growing idea

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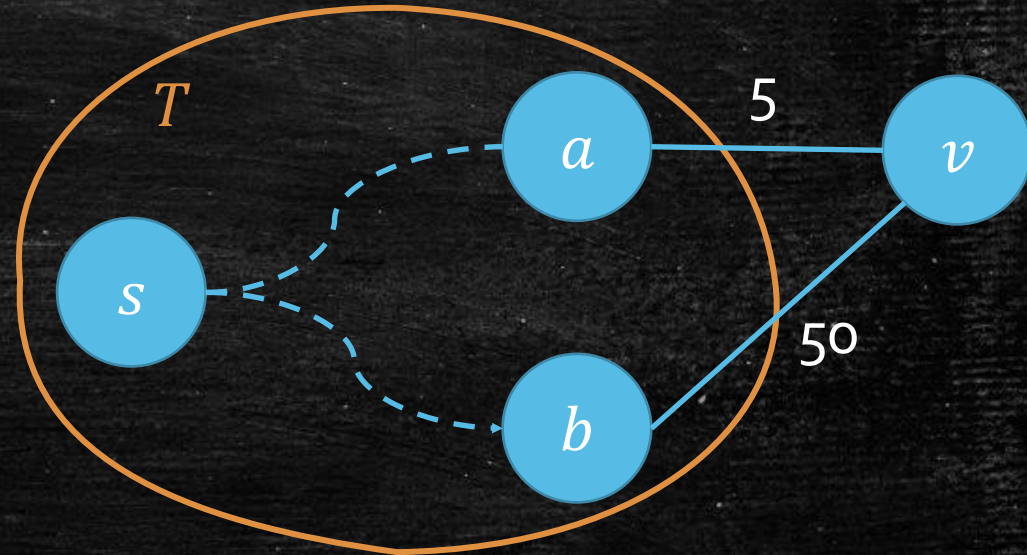
- Given a small **SPT**,
- choose a proper vertex  $v$  to find a larger **SPT**.
- New Plan for MST:
- Given a small **MST**,
- choose a proper vertex  $v$  to find a larger **MST**.





# Prim's growing idea

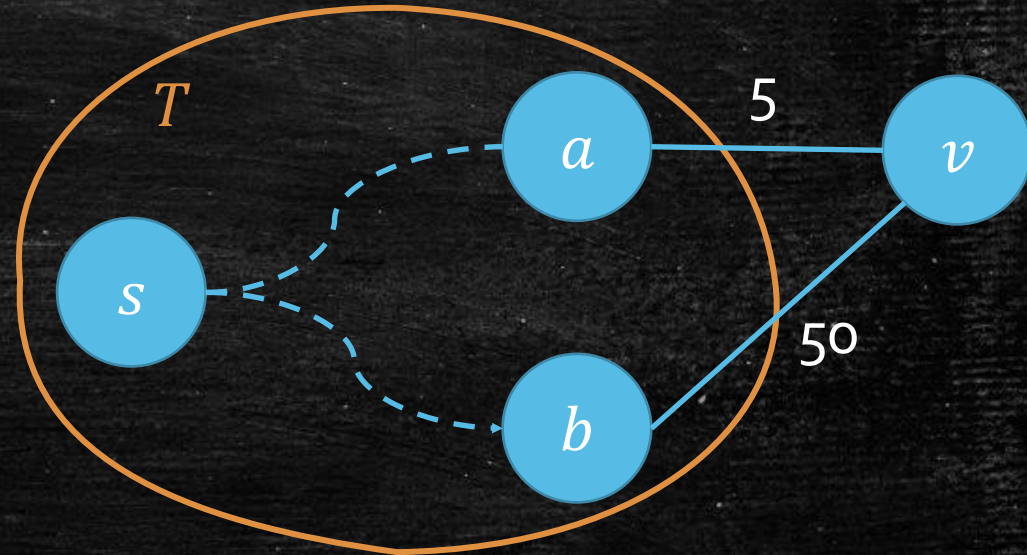
- Given a small **MST**,
- choose a proper vertex  $v$  to find a larger **MST**.
- Which  $v$  is good?
- Dijkstra:  $v$  with **smallest**  $T$ -distance to  $s$ .
- Now:  $v$  with **smallest** cost!





# Prim's growing idea

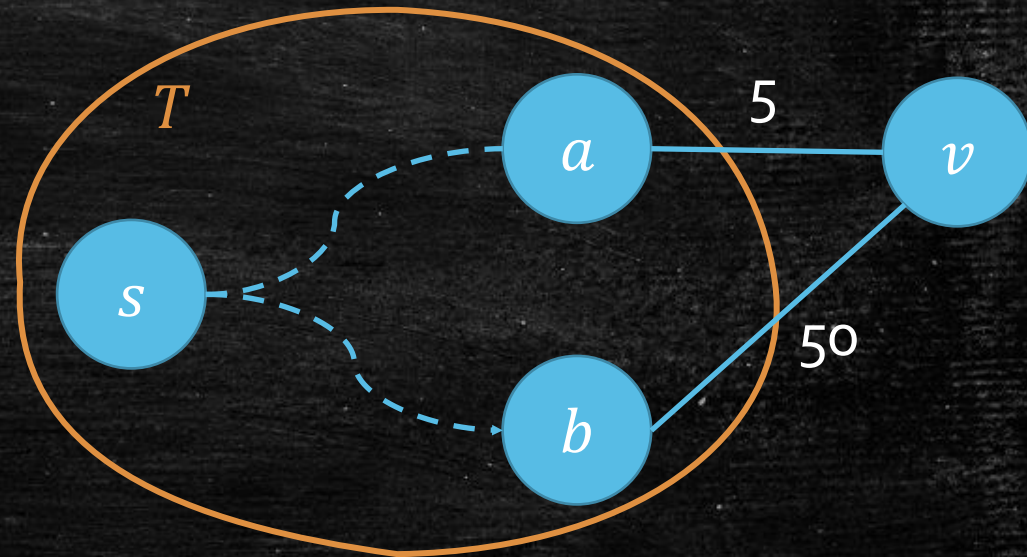
- Given a small **MST**,
- choose a proper vertex  $v$  to find a larger **MST**.
- Grow  $v$  with **smallest** cost!
- Is it correct?
- Challenge:
  - How to define small **MST**





# How to define small **MST**?

- $T = (V', E')$  is a small **MST** if it is an **MST** for  $V'$ .
- Problem
  - are those edges in  $T$  still ok?
- A better choice:
- $T$  is a **P-MST** (Partial MST) if it is a part of a complete **MST** for  $G$ .

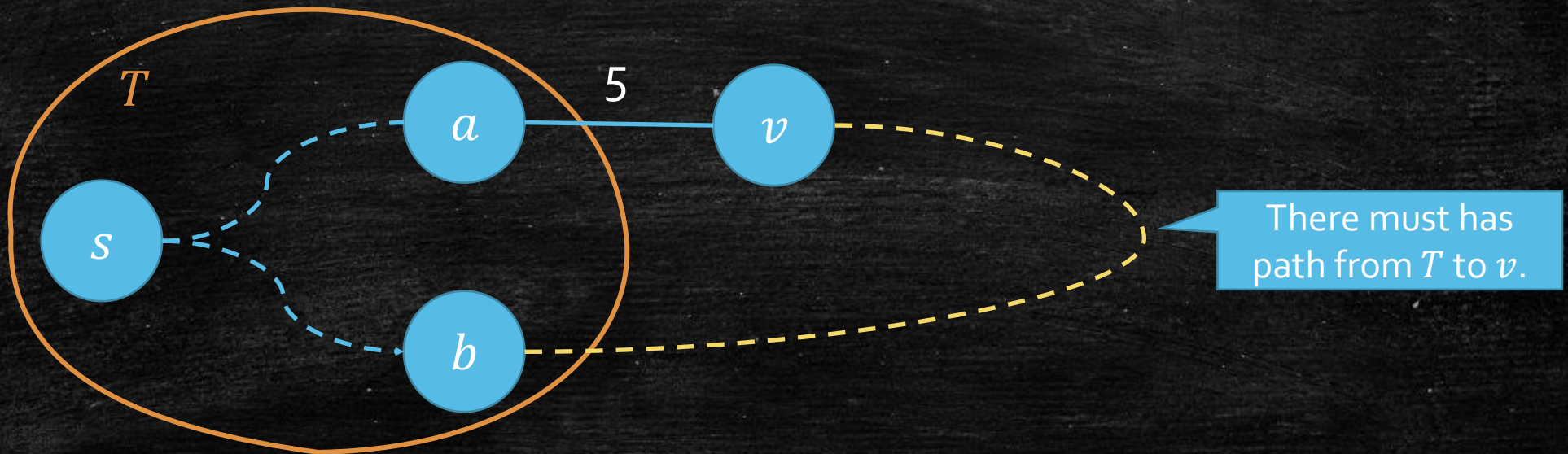




# Correctness of Prim's Growing idea

- Let's say  $T^*$  is the complete MST that contains  $T$ , and suppose  $(a, v) \notin T^*$ .

- Given:** a small P-MST  $T$ .
- Want:** a larger P-MST.
- Can we explore  $v$  (smallest cost) into  $T$ ?

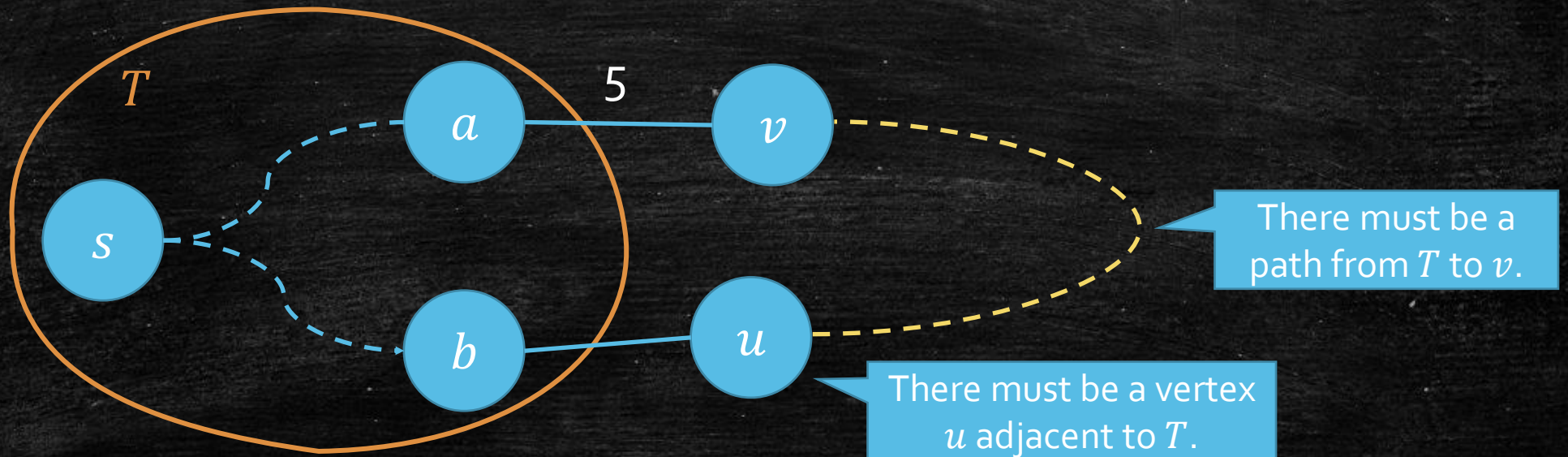




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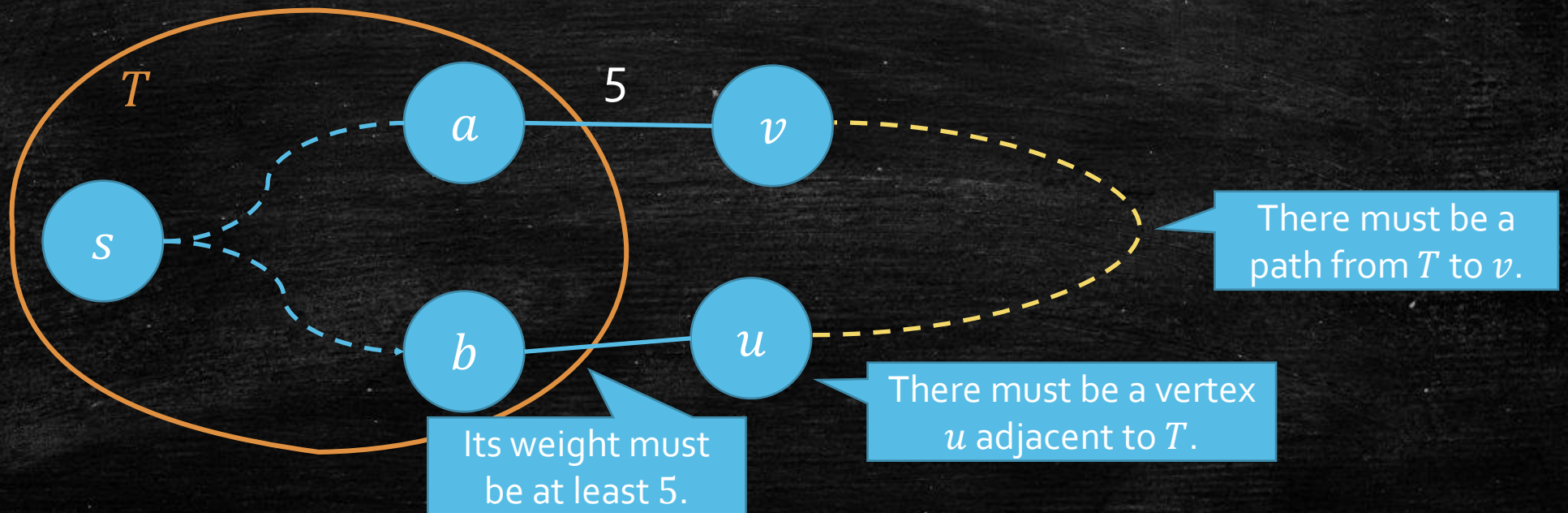




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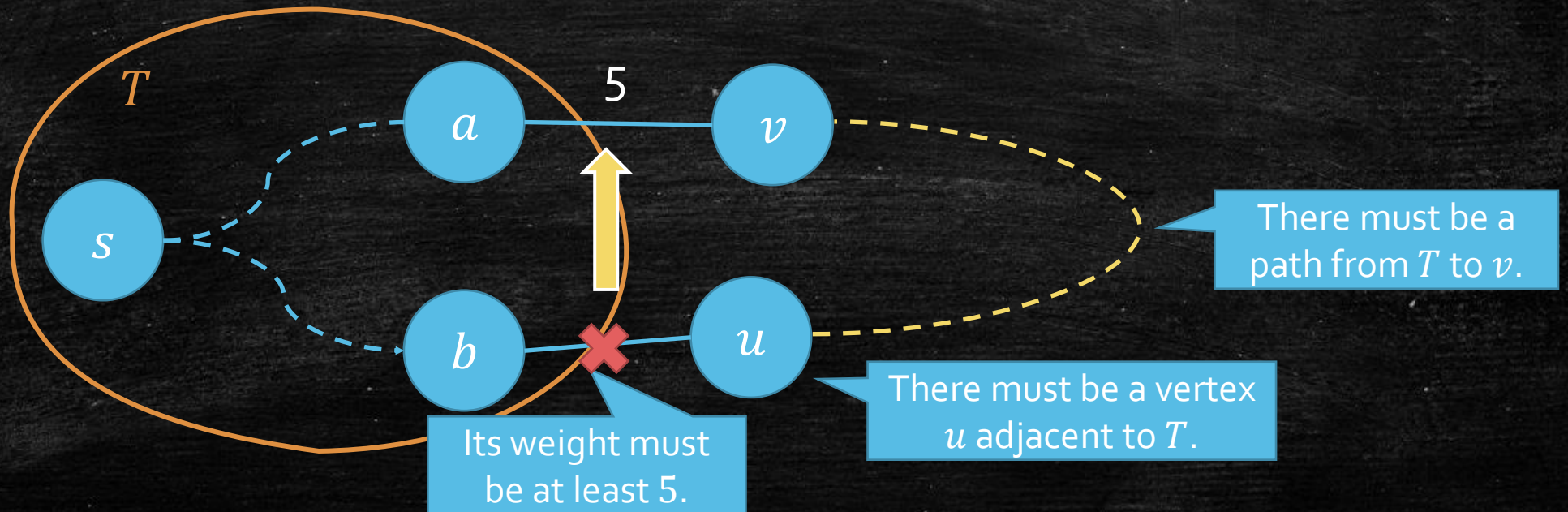




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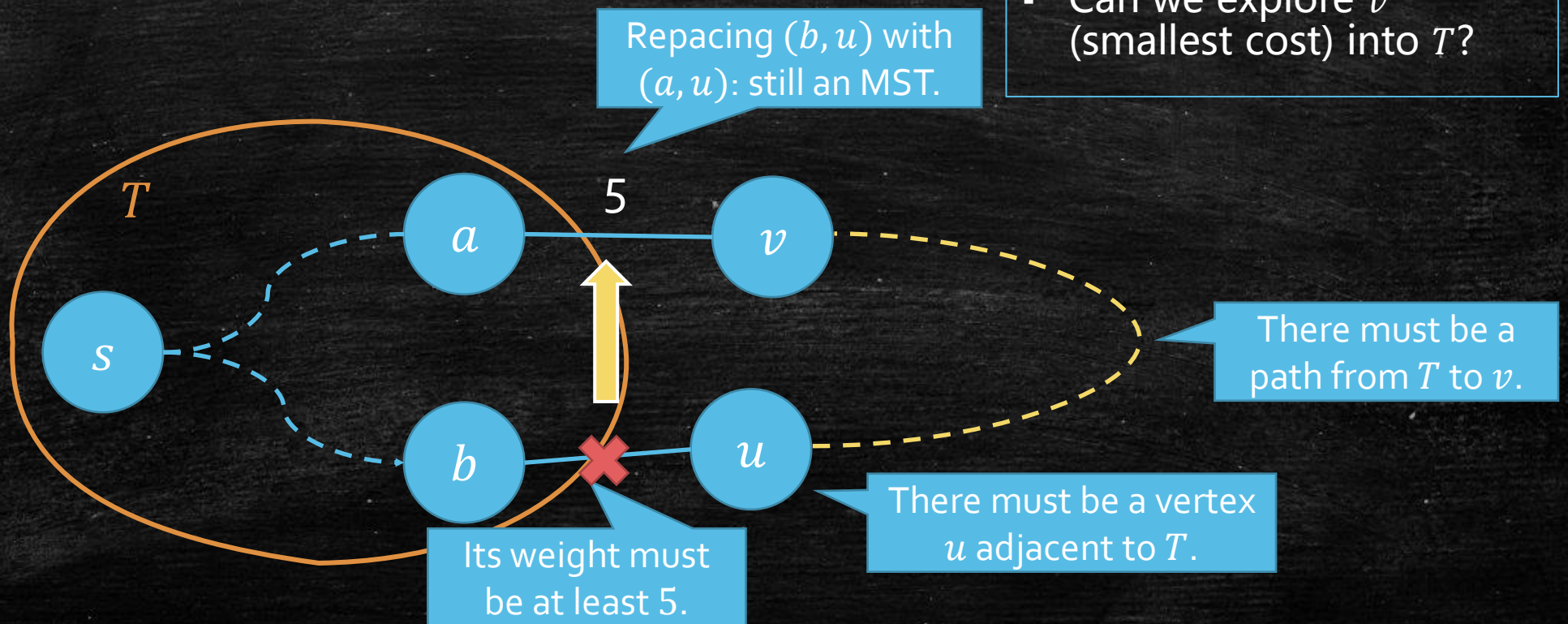




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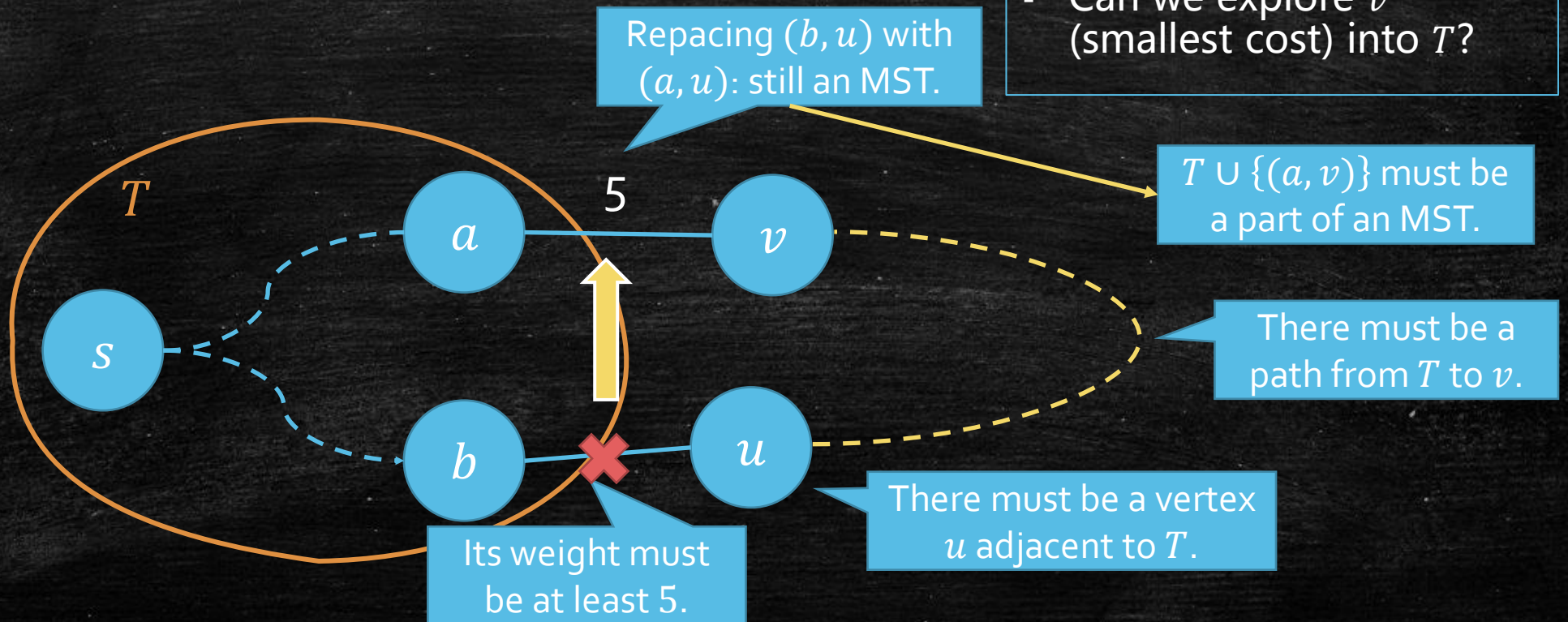




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# Prim Algorithm [Jarník '30, Prim '57, Dijkstra '59]

**Prim**( $G = (V, E)$ )

## 1. Initialize

- $T \leftarrow \{\}, S \leftarrow \{s\}$ ; #s is an arbitrary vertex.
- $cost[s] = 0$ ,  $cost[v] \leftarrow \infty$  for all  $v$  other than  $s$ .
- $cost[v] \leftarrow w(s, v)$ ,  $pre[v] = s$  for all  $(s, v) \in E$ .

## 2. Explore

- Find  $v \notin S$  with smallest  $cost[v]$ .
- $S \leftarrow S + \{v\}$ ;  $T \leftarrow T + \{(pre[v], v)\}$

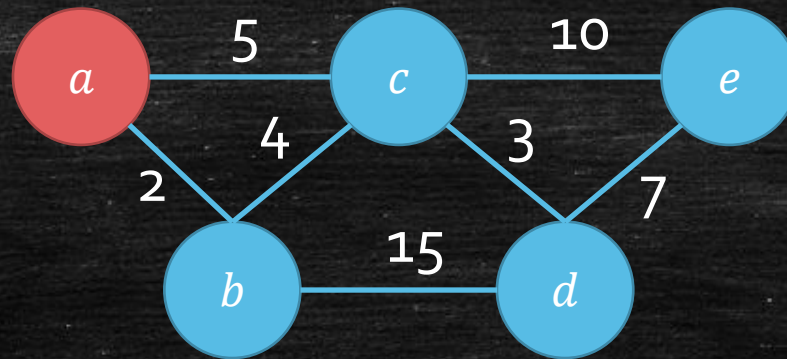
## 3. Update $cost[u]$

- $cost[u] = \min\{cost[u], w(v, u)\}$  for all  $(v, u) \in E$
- If  $cost[u]$  is updated, then  $pre[u] = v$ .



# Sample Run

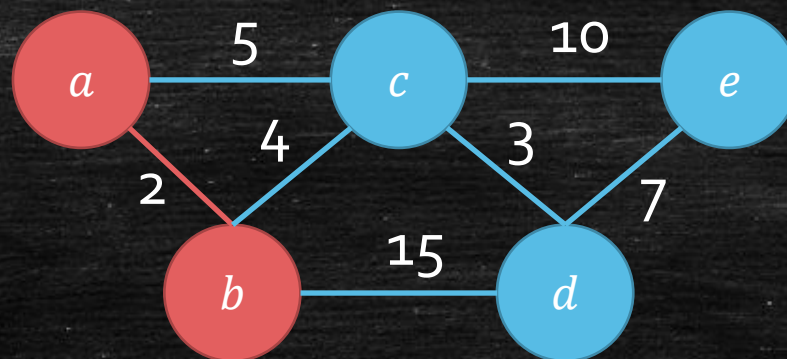
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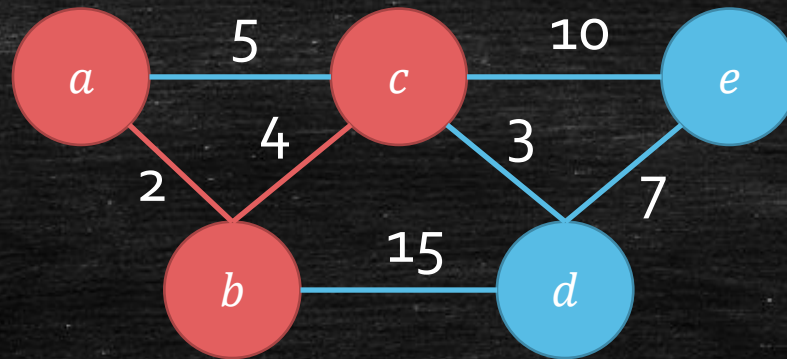
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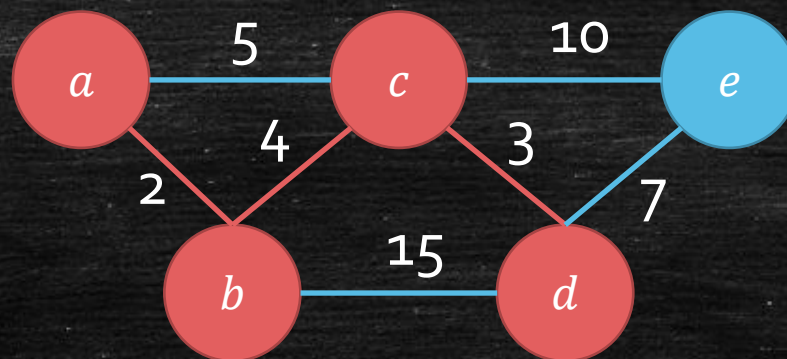
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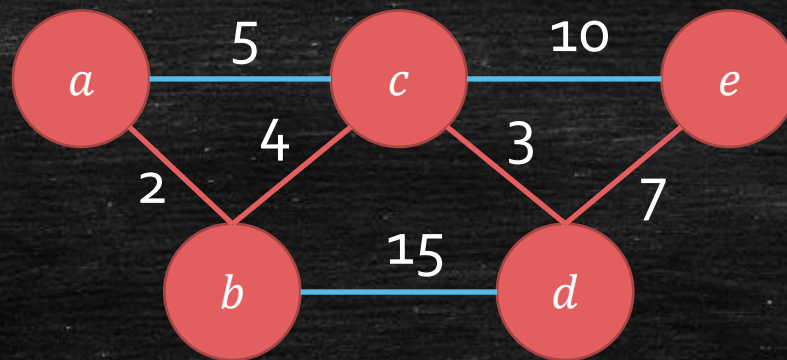
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# Sample Run

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# Running Time

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- I believe you know how to analyze it:
- We can do it in  $O(|E| + |V| \log |V|)$ .



# Kruskal Algorithm [Kruskal 1956]

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- Another Greedy!

**Kruskal**( $G = (V, E)$ )

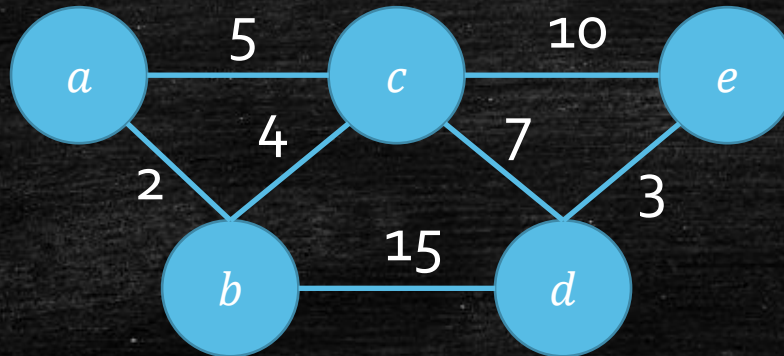
- Sort the edge set  $E$  to **descending order**.
- For each  $e \in E$  in **descending order**
  - If  $e$  do not create a **cycle**, then choose it.



# Kruskal Algorithm

**Kruskal**( $G = (V, E)$ )

- Sort the edge set  $E$  to **ascending order**.
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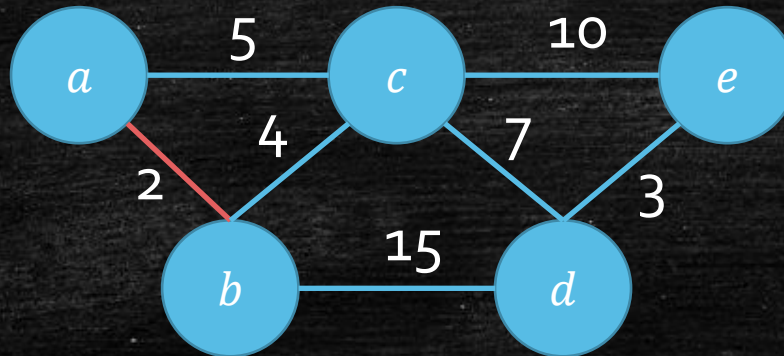
2	3	4	5	7	10	15
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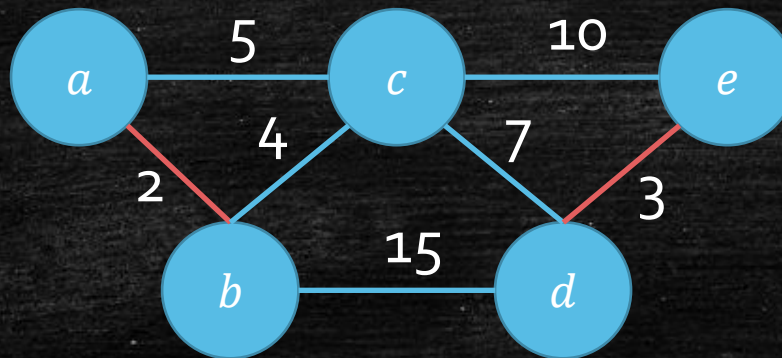
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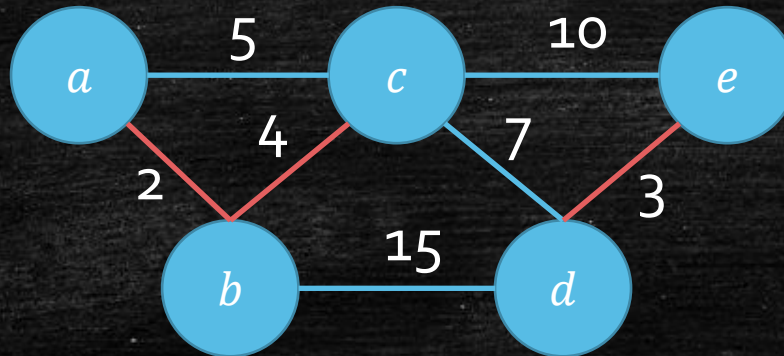
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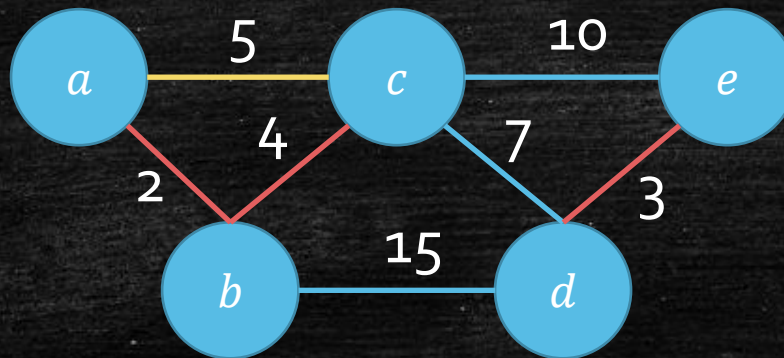
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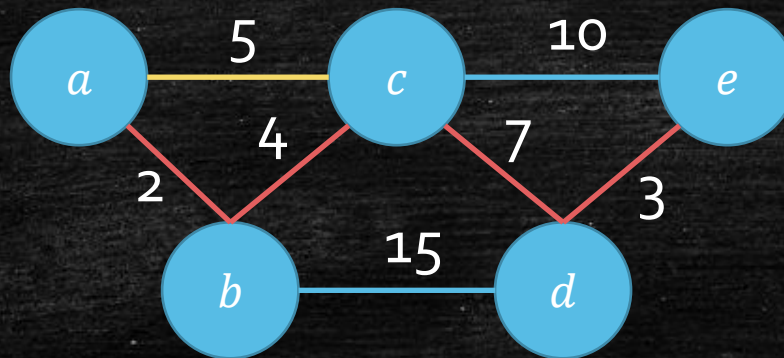
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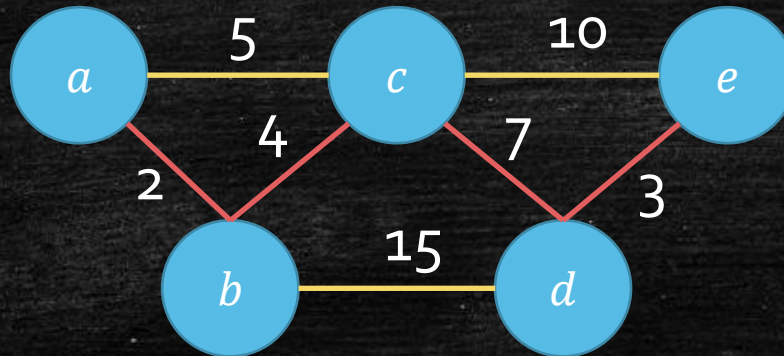
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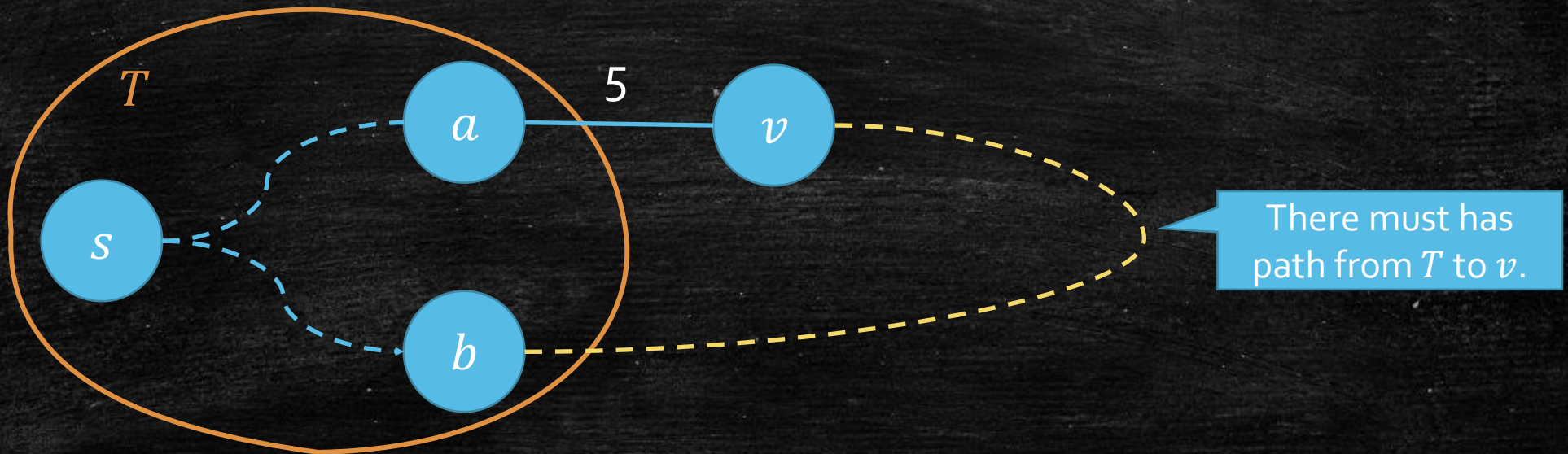
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# Correctness of Prim's Growing idea

- Let's say  $T^*$  is the complete MST that contains  $T$ , and suppose  $(a, v) \notin T^*$ .

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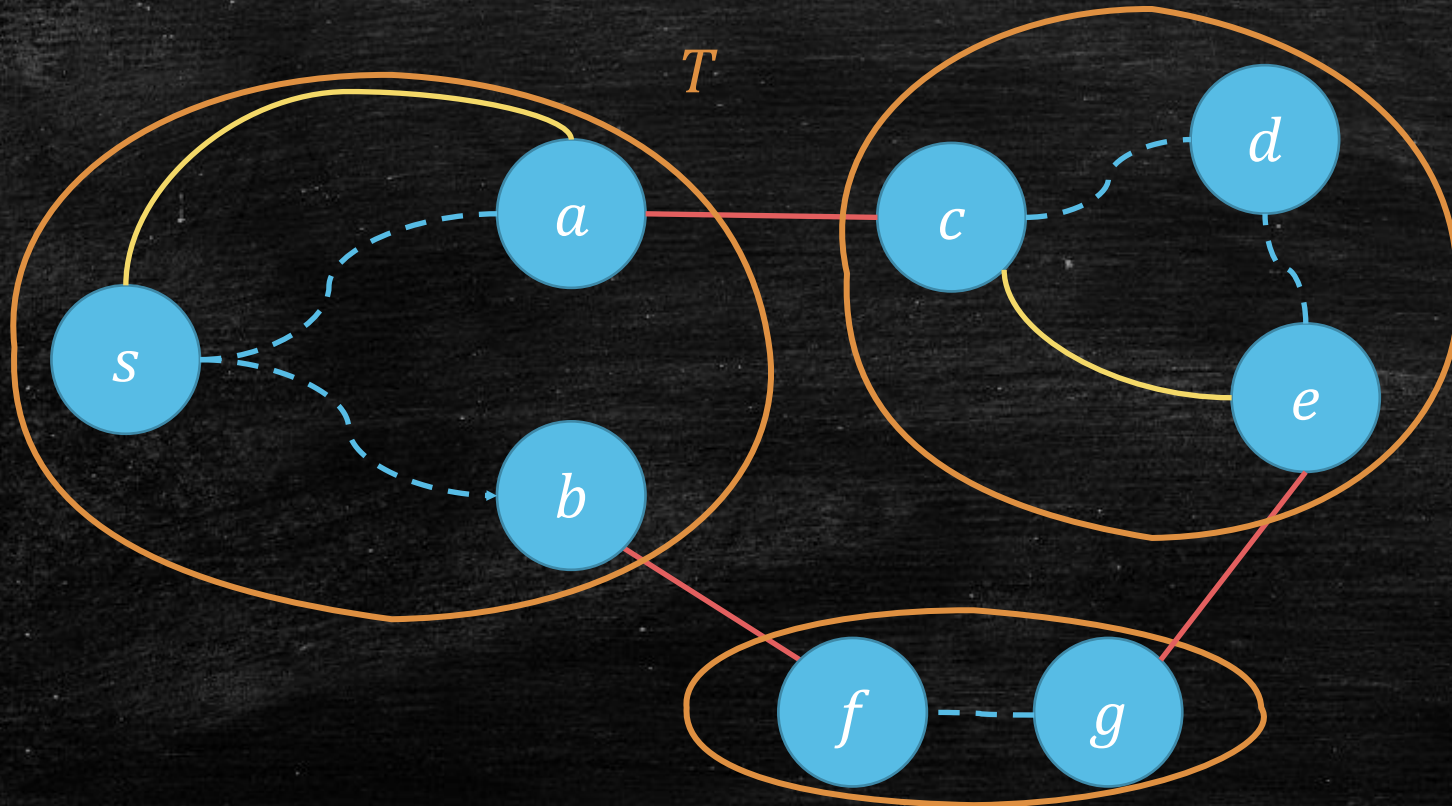




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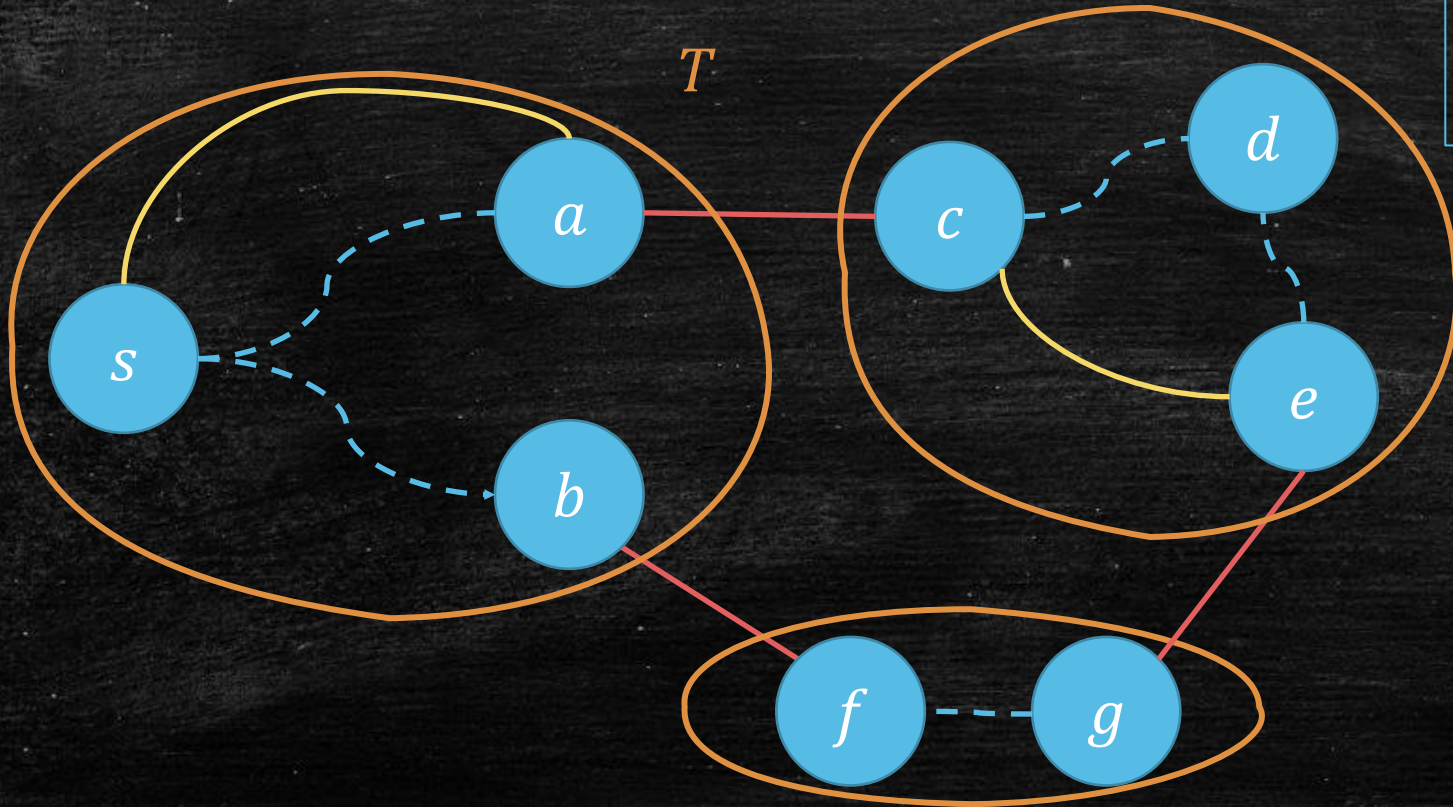




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- **Given:** a small P-MST  $T$ .
- **Want:** a larger P-MST.
- Add the smallest red edge get a larger P-MST.

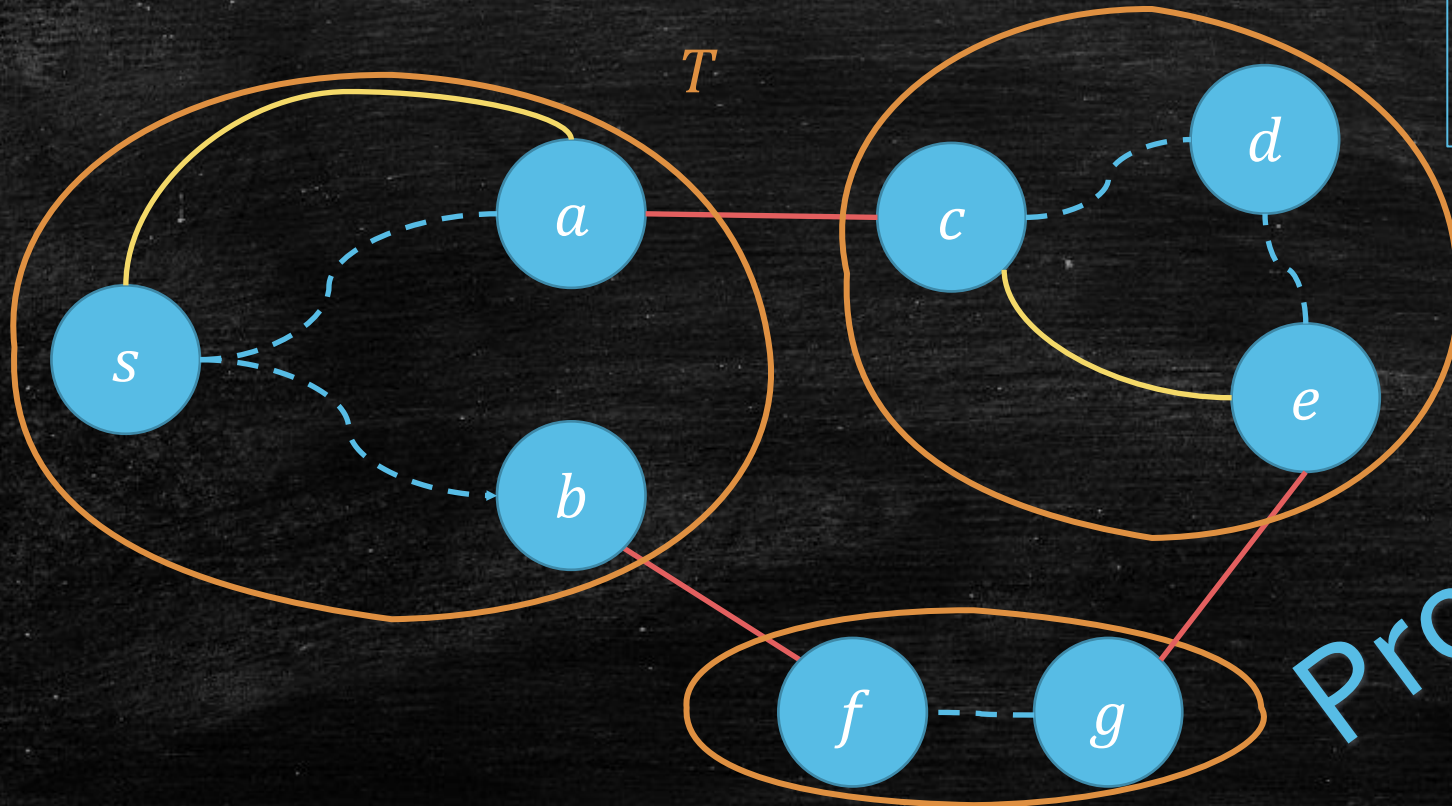




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Prove by yourself!



# Running Time

## Kruskal( $G = (V, E)$ )

- Sort the edge set  $E$  to **ascending order**.
- For each  $e \in E$  in **ascending order**
  - If  $e$  do not create a **cycle**, then choose it.
- $O(|E| \log |E|)$  for sorting.
- $|E|$  round: **check cycle!**



# Recall DFS

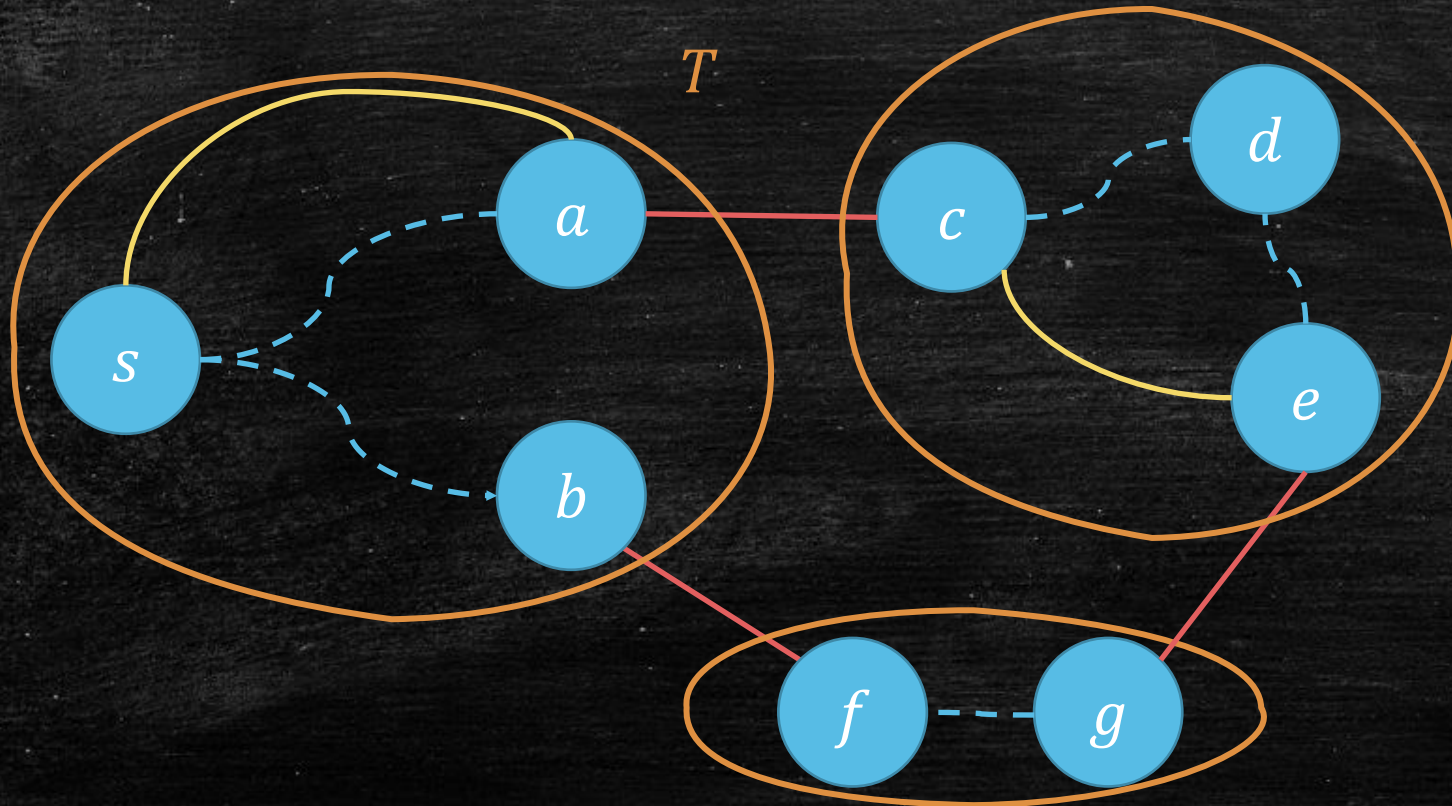
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- When an edge is a **back edge** (to marked vertices),
- It forms a cycle.



# During Kruskal

- When an edge connect the same group vertices,
- It forms a cycle.





# Kruskal (refine)

**Kruskal**( $G = (V, E)$ )

- Sort the edge set  $E$  to **ascending order**.
- For each  $(u, v) \in E$  in **ascending order**
  - If  $group(u) \neq group(v)$ 
    - Choose  $(u, v)$ .
    - $union(group(u), group(v))$



# Running Time: Kruskal (refine)

## Kruskal( $G = (V, E)$ )

- Sort the edge set  $E$  to **ascending order**.
  - For each  $(u, v) \in E$  in **ascending order**
    - If  $group(u) \neq group(v)$ 
      - Choose  $(u, v)$ .
      - $union(group(u), group(v))$
- 
- $O(|E| \log |E|)$  for sorting.
  - $2|E|$  round: check group
  - $|V|$  round: union group



# Union-Find Set

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- Recall Union-Find Set

- Find:  $O(\log n)$
- Union:  $O(1)$

- Kruskal

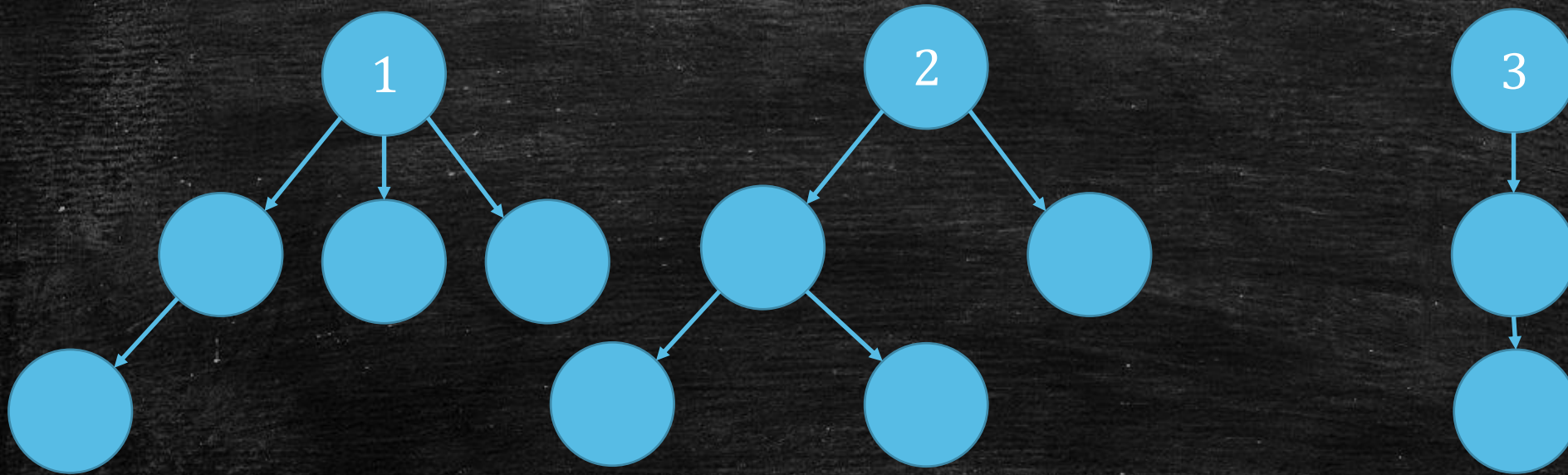
- $O(|E| \log |E|)$  for sorting.
- $2|E|$  round: check group
- $|V|$  round: union group
- $O(|E| \log |E|) = O(|E| \log |V|)$





# Review Union-Find Set

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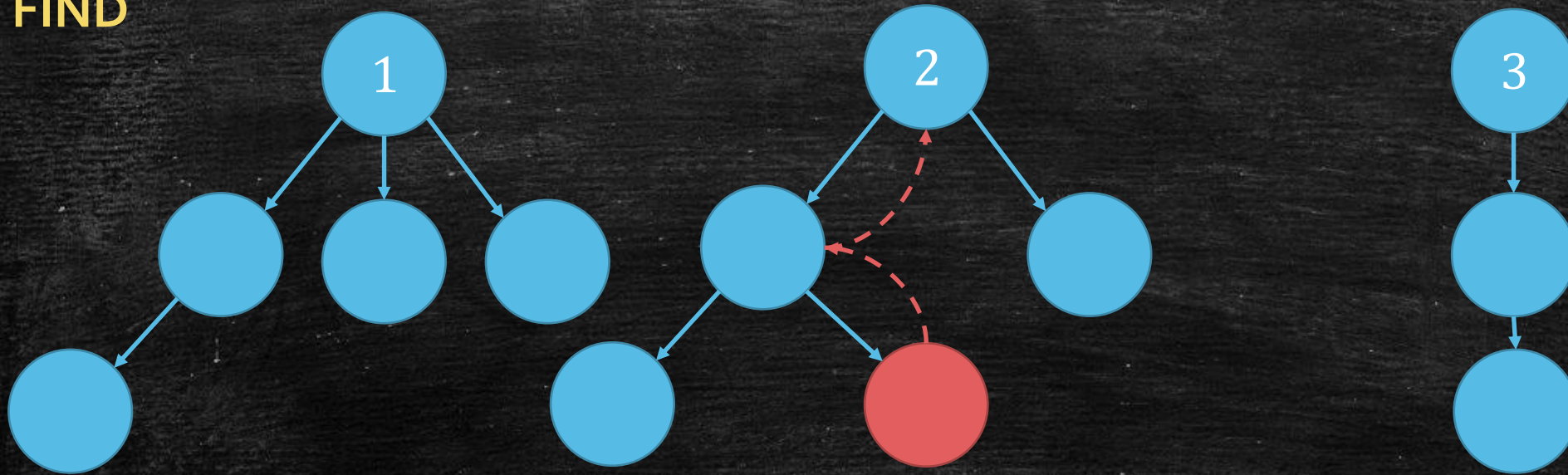




# Review Union-Find Set

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FIND

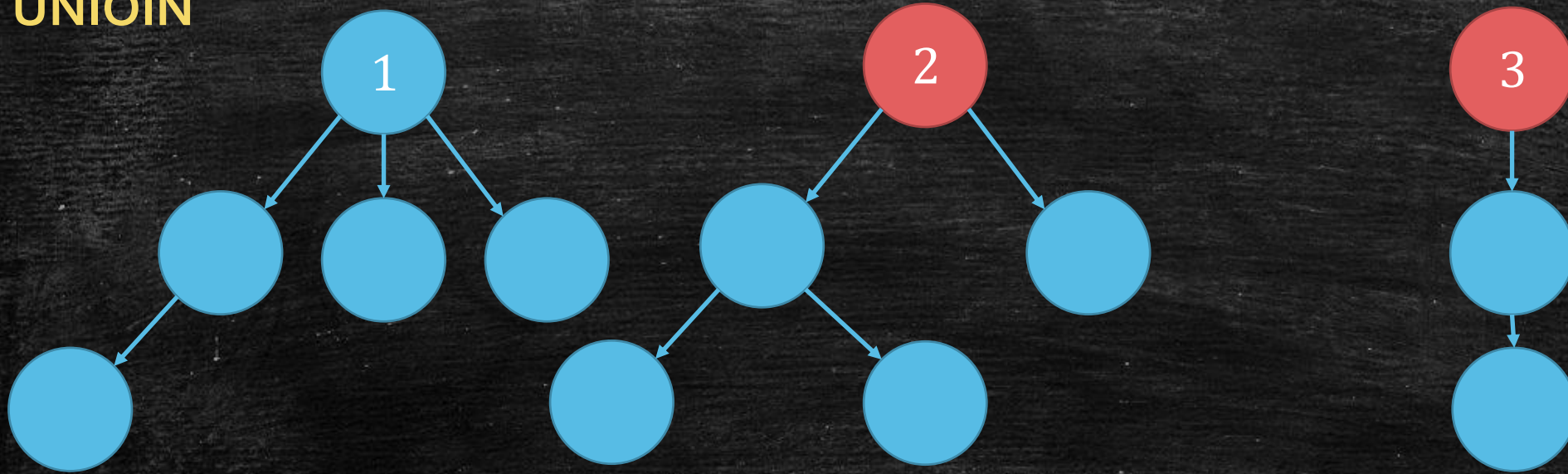




# Review Union-Find Set

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UNIOIN

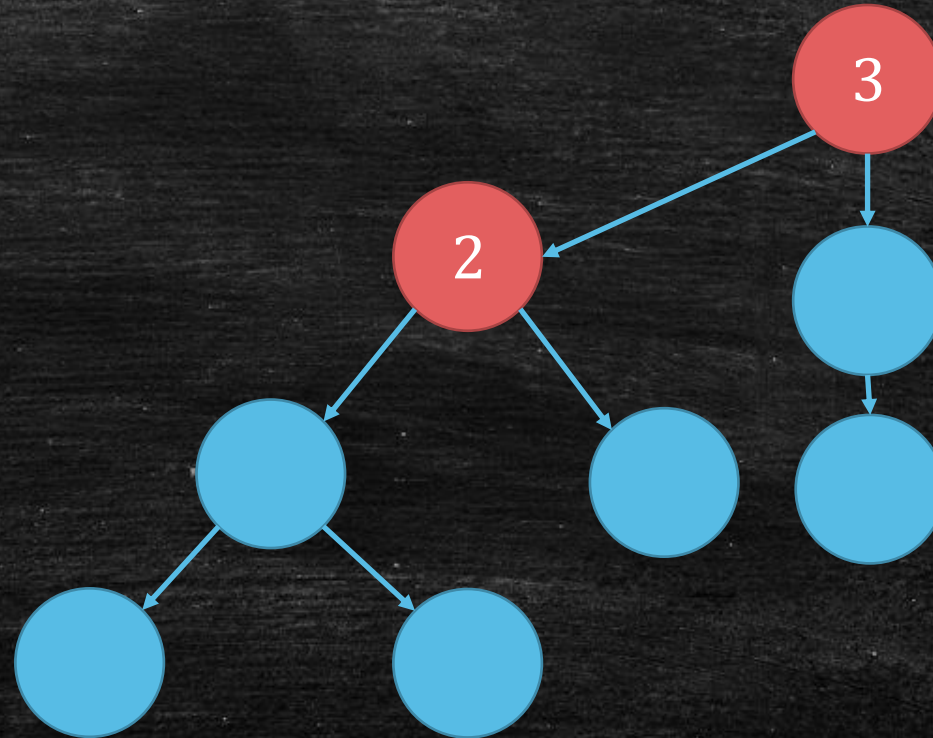
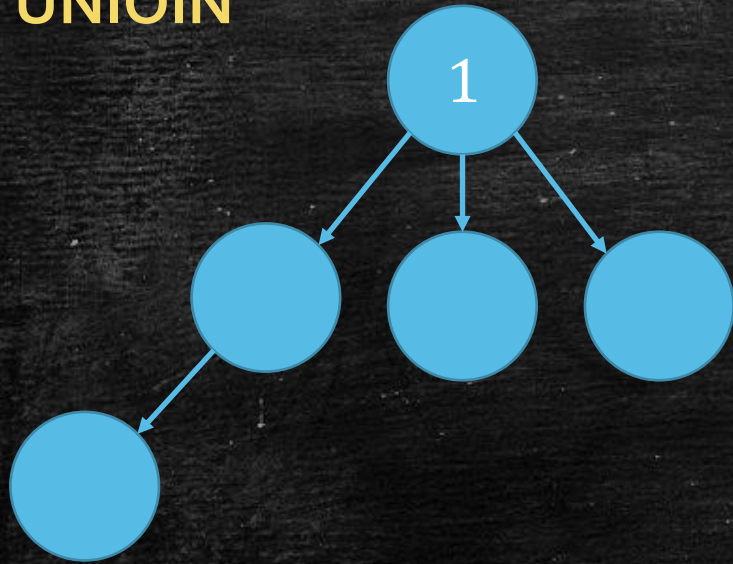




# Review Union-Find Set

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UNIOIN





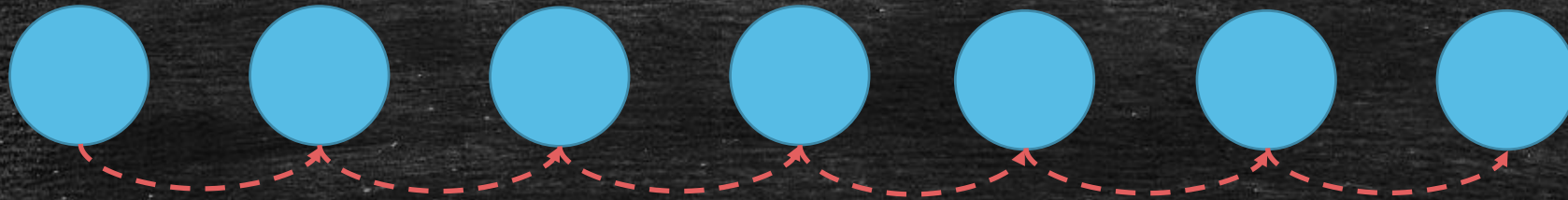
# Time Complexity

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- Find
  - $O(\max\{\textit{Tree height}\})$
- Union
  - $O(1)$



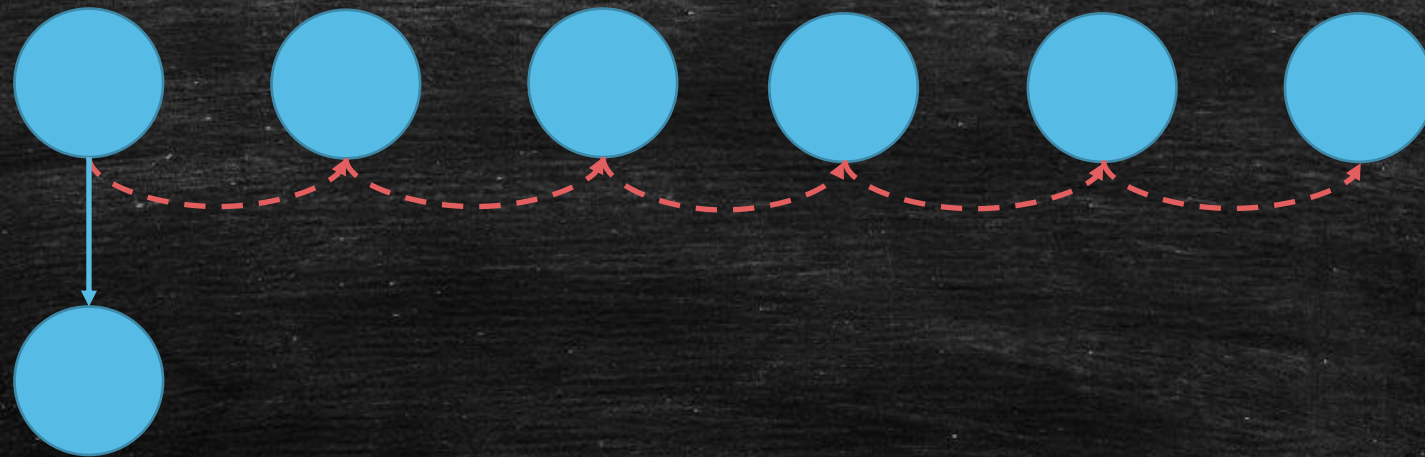
# A bad Case





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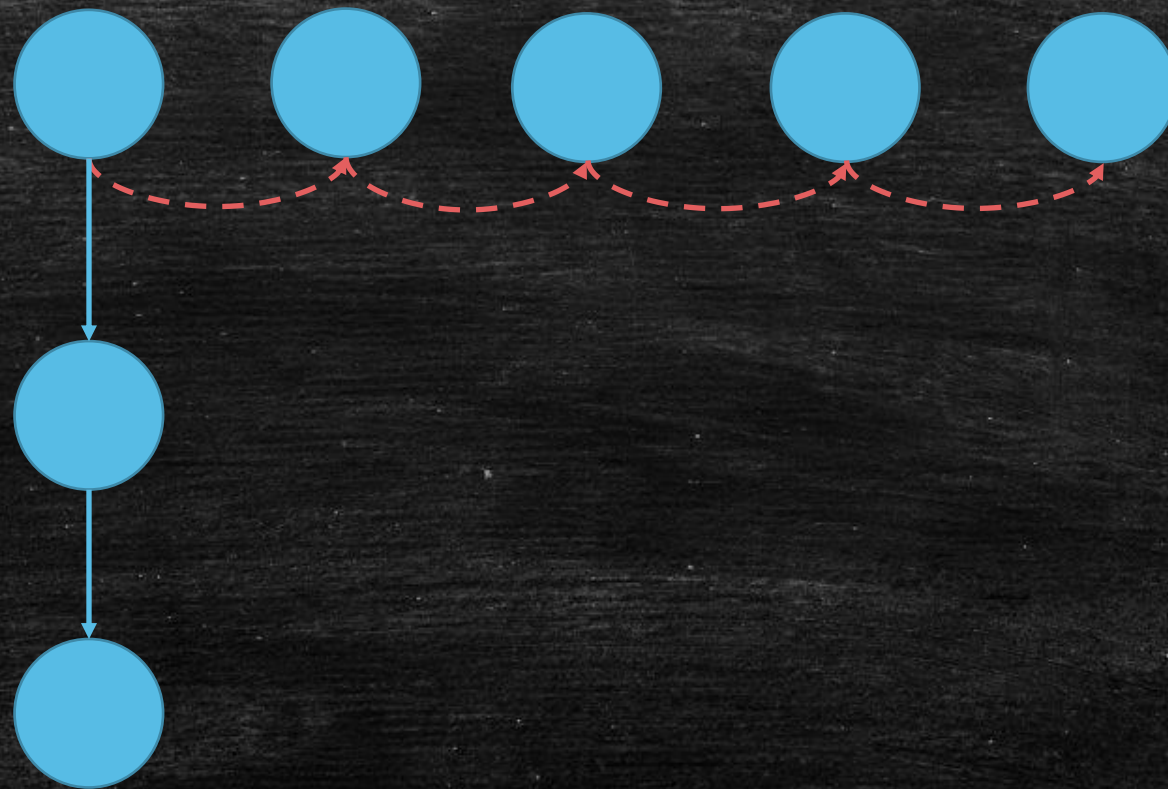
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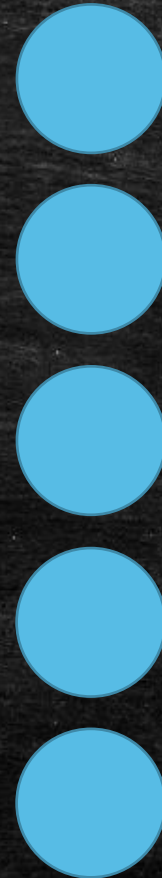




# A bad Case

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$O(n)$  tree height





# How to improve

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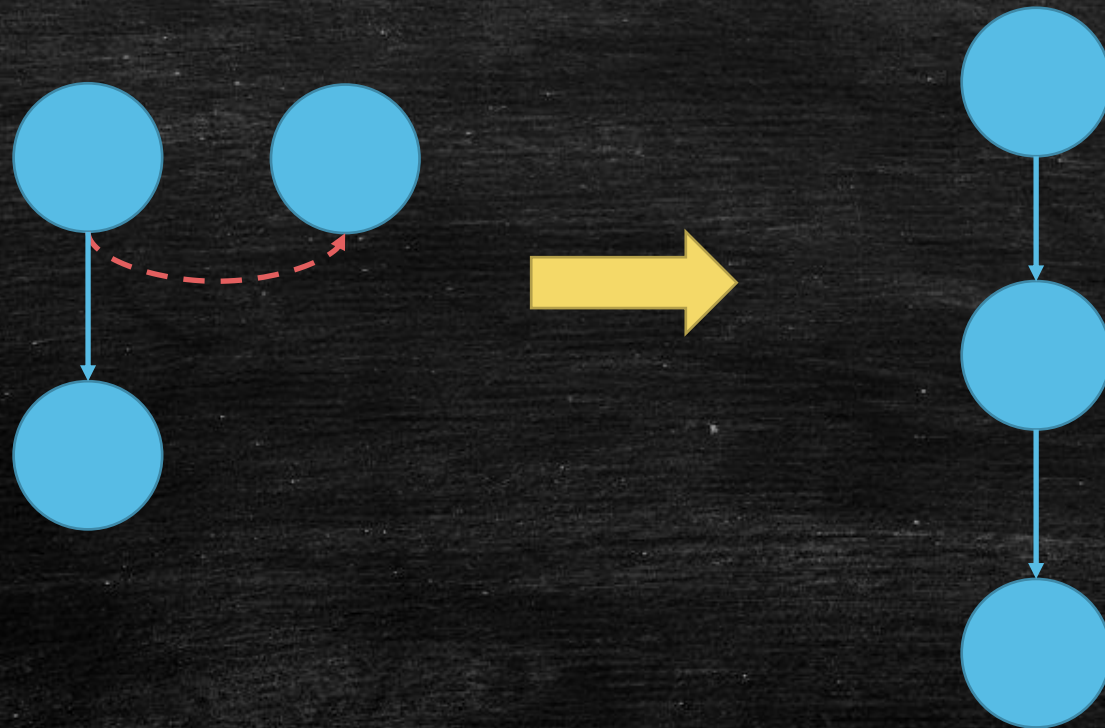
- Find
  - $O(\max\{\text{Tree height}\})$
  - $O(n)!$
- Union
  - $O(1)$
- To Do
  - Reduce Tree Height



# Intuition

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**BAD**

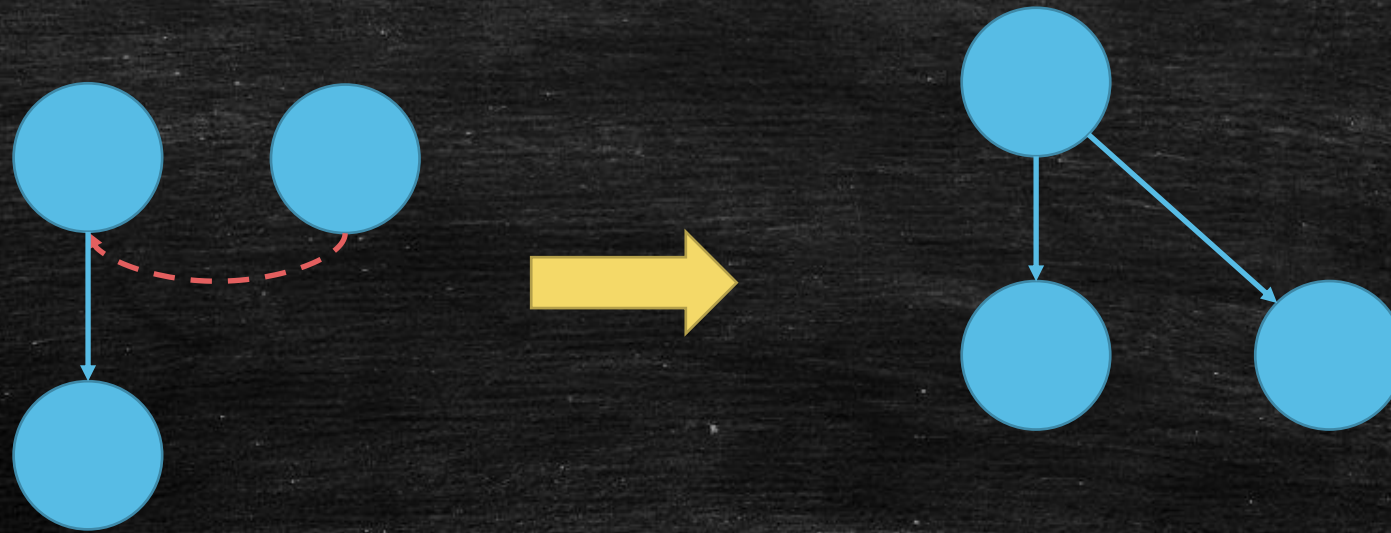




# Intuition

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GOOD



We should merge to a same root!  
We should merge short tree to high tree!



# Implement

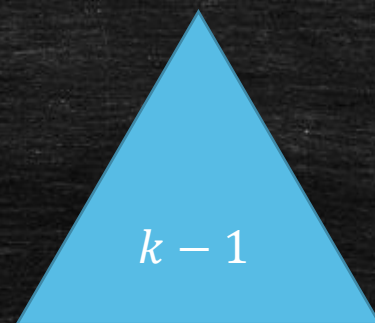
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- Record Tree's height (rank).
- $rank[v]$ : the rank of tree rooted at  $v$ .
- Union:  $u$  and  $v$ .
  - Rooted at  $u$ : if  $rank[u] \geq rank[v]$
  - Rooted at  $v$ : if  $rank[u] < rank[v]$
  - Update  $rank[u]++$ : if  $rank[u] = rank[v]$
- We make it hard to build a large rank tree!



# How to build a rank $k$ tree?

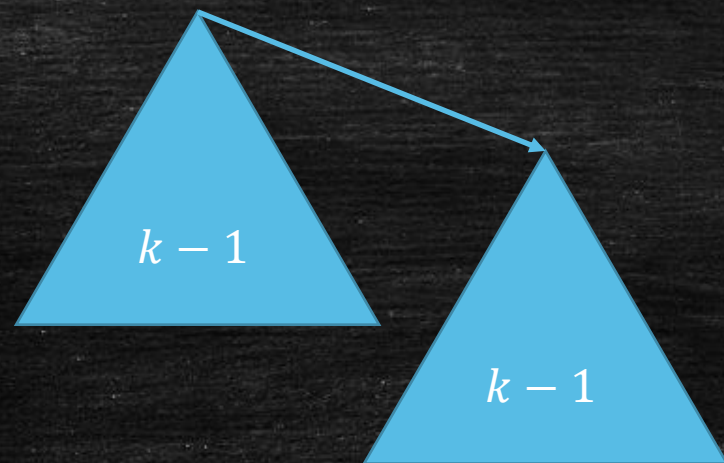
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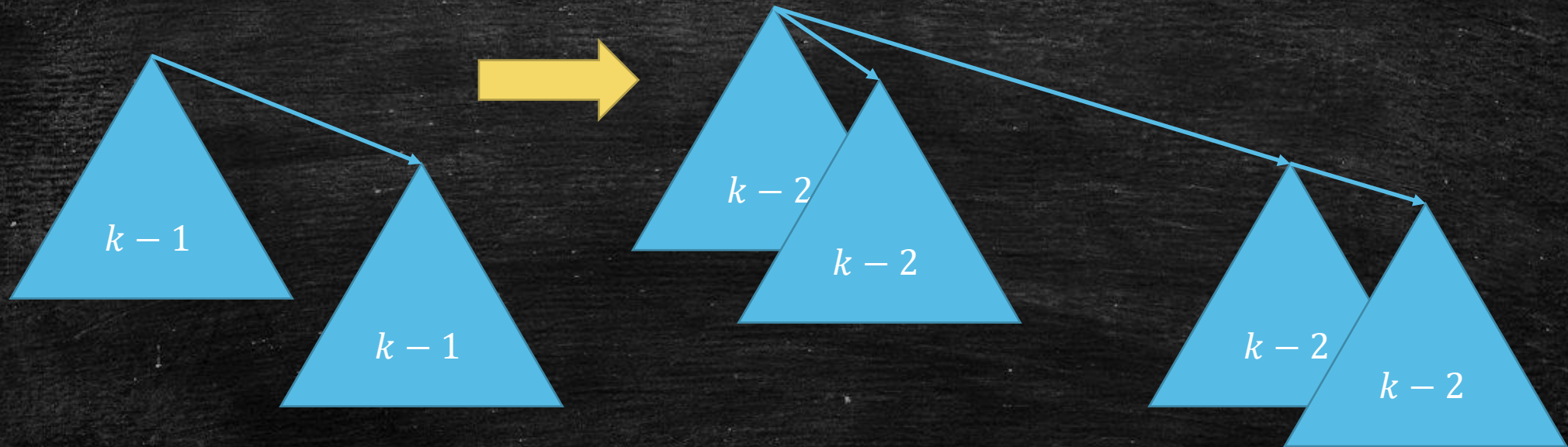
# How to build a rank $k$ tree?

---





# How to build a rank $k$ tree?



We should at least use  $2^k$  nodes!



# Max tree height

---

- Build a rank  $k$  tree: We should at least use  $2^k$  nodes!
- What is the max tree height (rank)?
- $O(\log n)$
- Find
  - $O(\max\{\text{Tree height}\})$
  - $O(\log n)!$
- Union (rank based)
  - $O(1)$



# Union-Find Set

---

- Recall Union-Find Set
  - Find:  $O(\log n)$
  - Union:  $O(1)$
- Kruskal
  - $O(|E| \log |E|)$  for sorting.
  - $2|E|$  round: check group
  - $|V|$  round: union group
  - $O(|E| \log |E|) = O(|E| \log |V|)$



# Can we do better?

---

- Karger-Klein Tarjan (1995)
  - $O(m)$  randomized algorithm.
- Chazelle (2000)
  - $O(m \cdot \alpha(n))$  deterministic algorithm.
  - $\alpha(n)$  is the inverse Ackermann function  $\alpha(9876!) \leq 5$ .
  - Ackermann function:  $A(4,4) \approx 2^{2^{2^{16}}}$ .
- Pettie-Ramachandran (2002)
  - $O(\text{optimal \#comparison to determine solution})$
  - We know  $\text{\#comparison} = \Omega(n) = O(m \cdot \alpha(n))$



# Can we do better for Union-Find Set?

---

- Have you heard **Path Compression**?

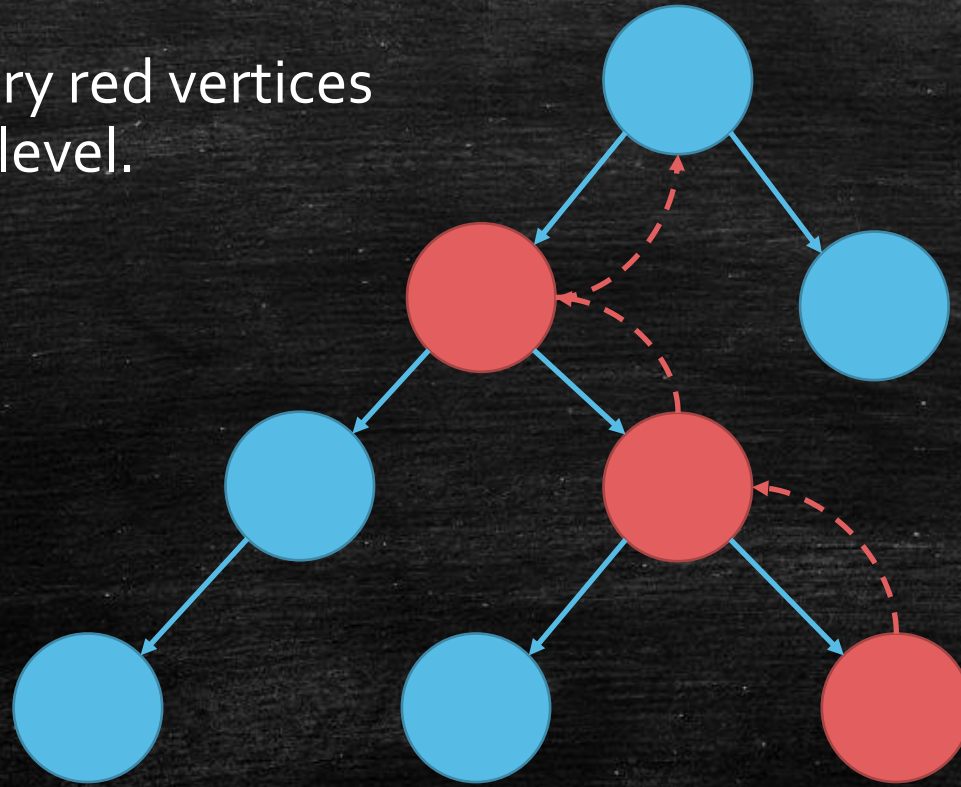


# Path Compression

---

## FIND

We put every red vertices to the first level.



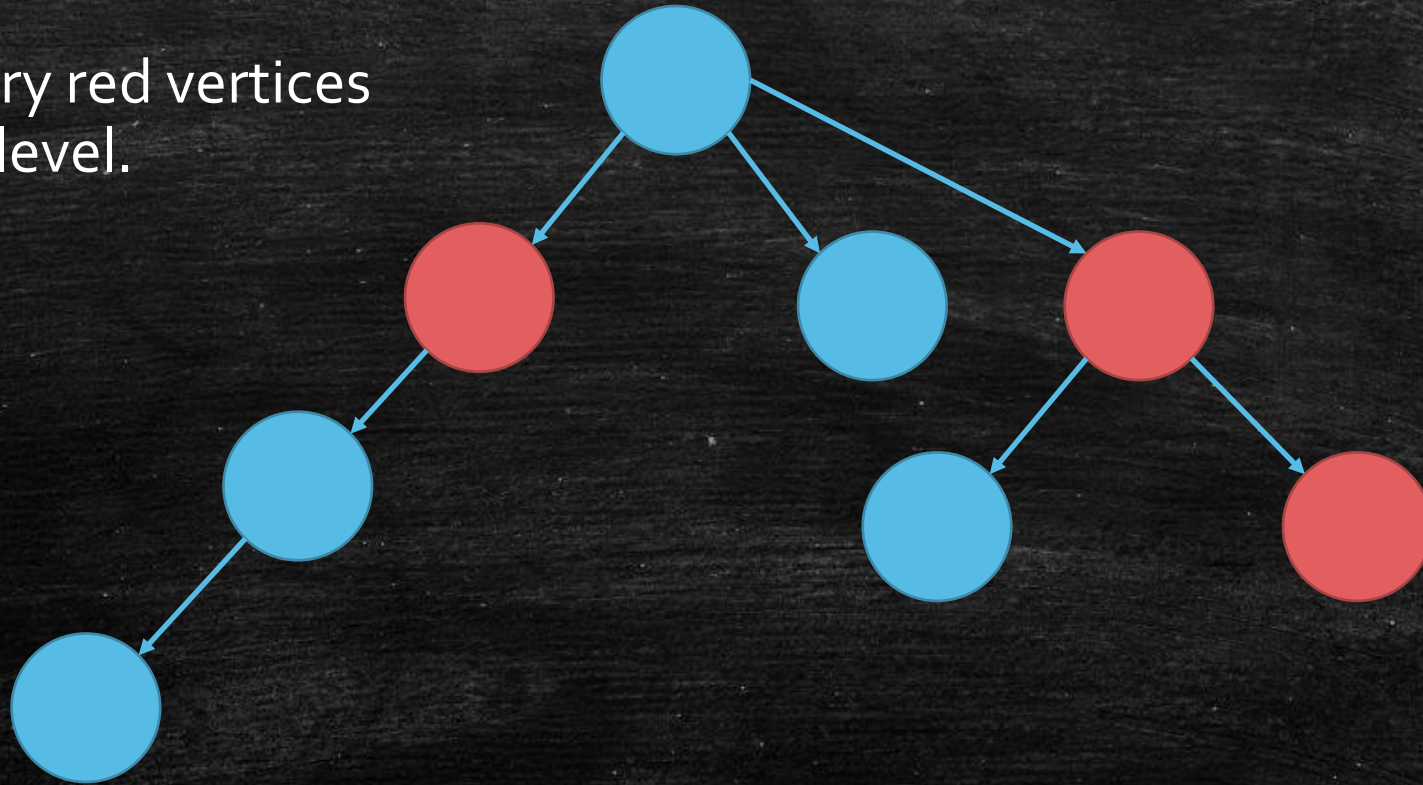


# Path Compression

---

## FIND

We put every red vertices to the first level.





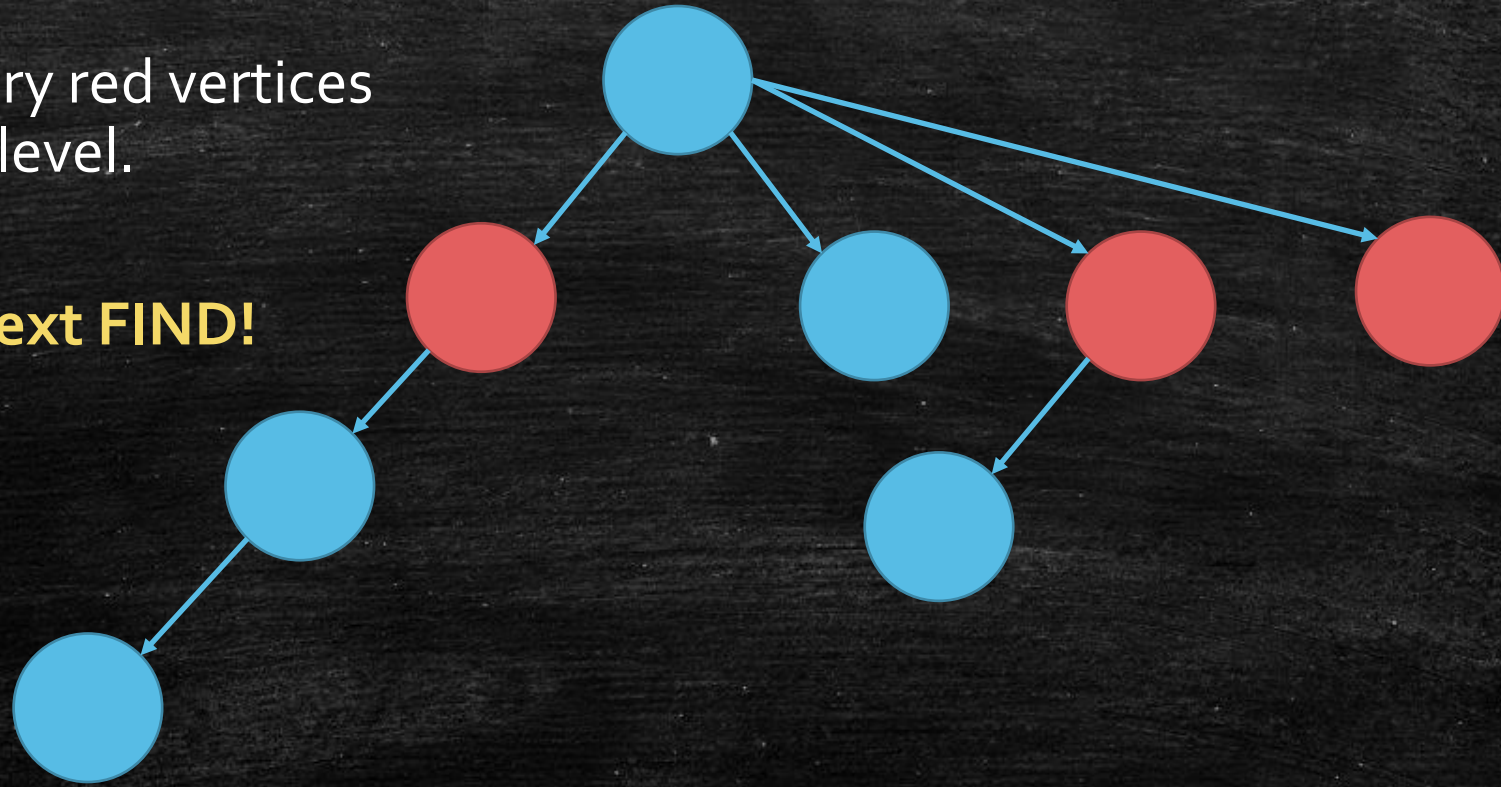
# Path Compression

---

## FIND

We put every red vertices to the first level.

**Good for next FIND!**





# You know what the next step!

---

Amortized Analysis



# Time Complexity

---

- Find (Path Compression)
  - $O(\log^* n)$  [Hopcroft & Ullman 1973]
  - $\log^*(2^{2^{2^2}}) = \log^*(2^{65536}) = 5$
  - $O(\alpha(n))$  [Tarjan 1975]
  - $\alpha(n)$  is the inverse Ackermann function  $\alpha(9876!) = 5$ .
- Union (rank based)
  - $O(1)$



# Rank Based Union + Find with Path Compression

---

- It is still an amortized analysis
- We prove:
  - $m$  find operation, totally cost  $O(m \log^* n)$ .

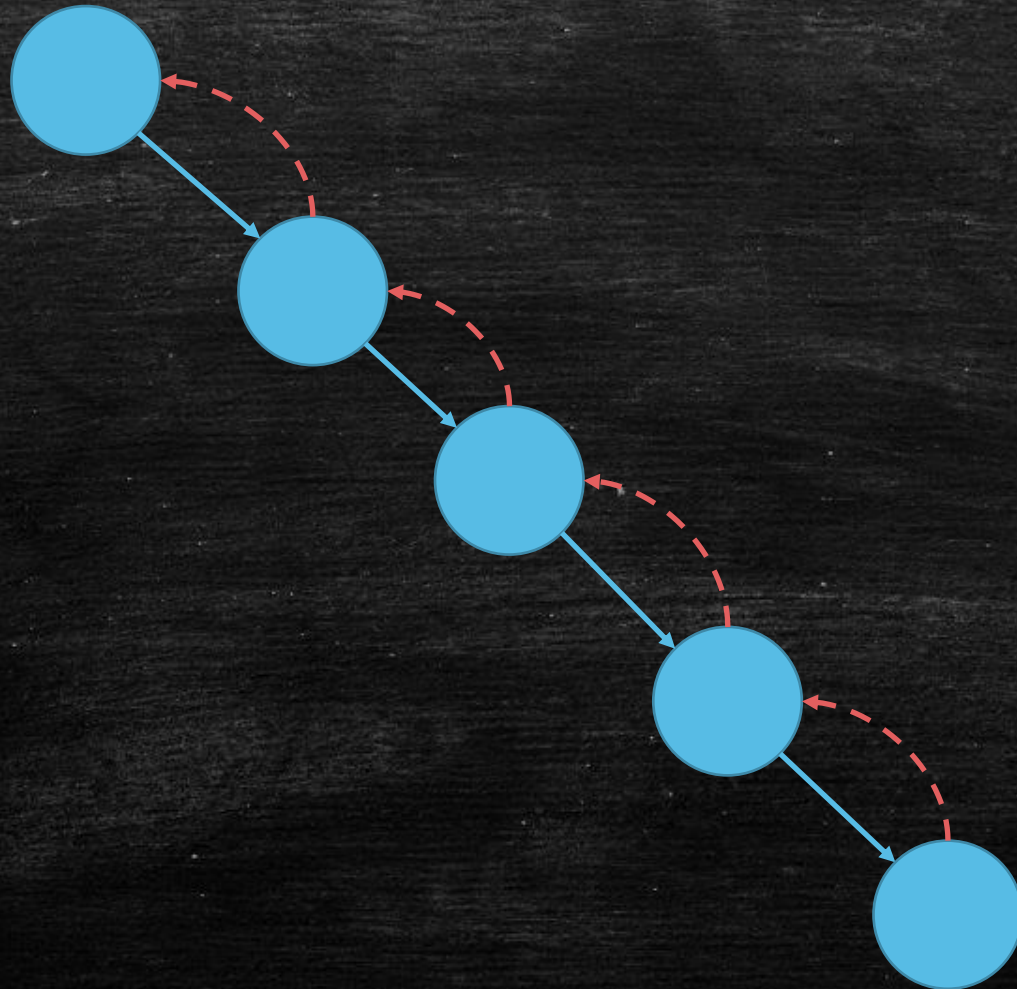


# Analysis

---

**FIND**

Cost=number  
of **red edges**.





# Key Idea: Charge Cost to Vertices

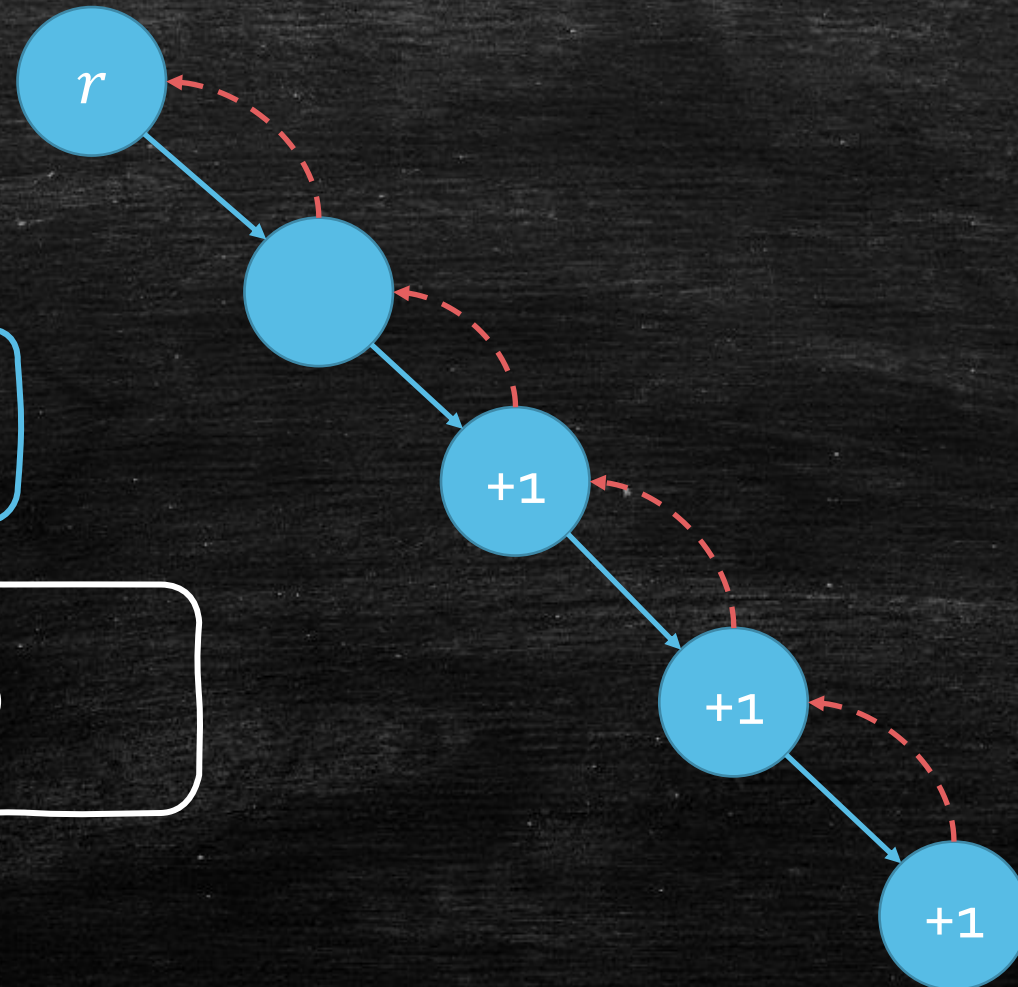
## FIND

Cost=number  
of **red edges**.

Red edge charge cost  
to child vertex.

Total Cost of  $m$  FIND

- $O(m)$ (to root)
- Total Charging





How much each vertex will  
be charge?

---



# Group Vertices

---

- $rank(u)$  (slightly changed)
  - The rank of  $u$  when it become a child. (largest)
- Group vertices by rank

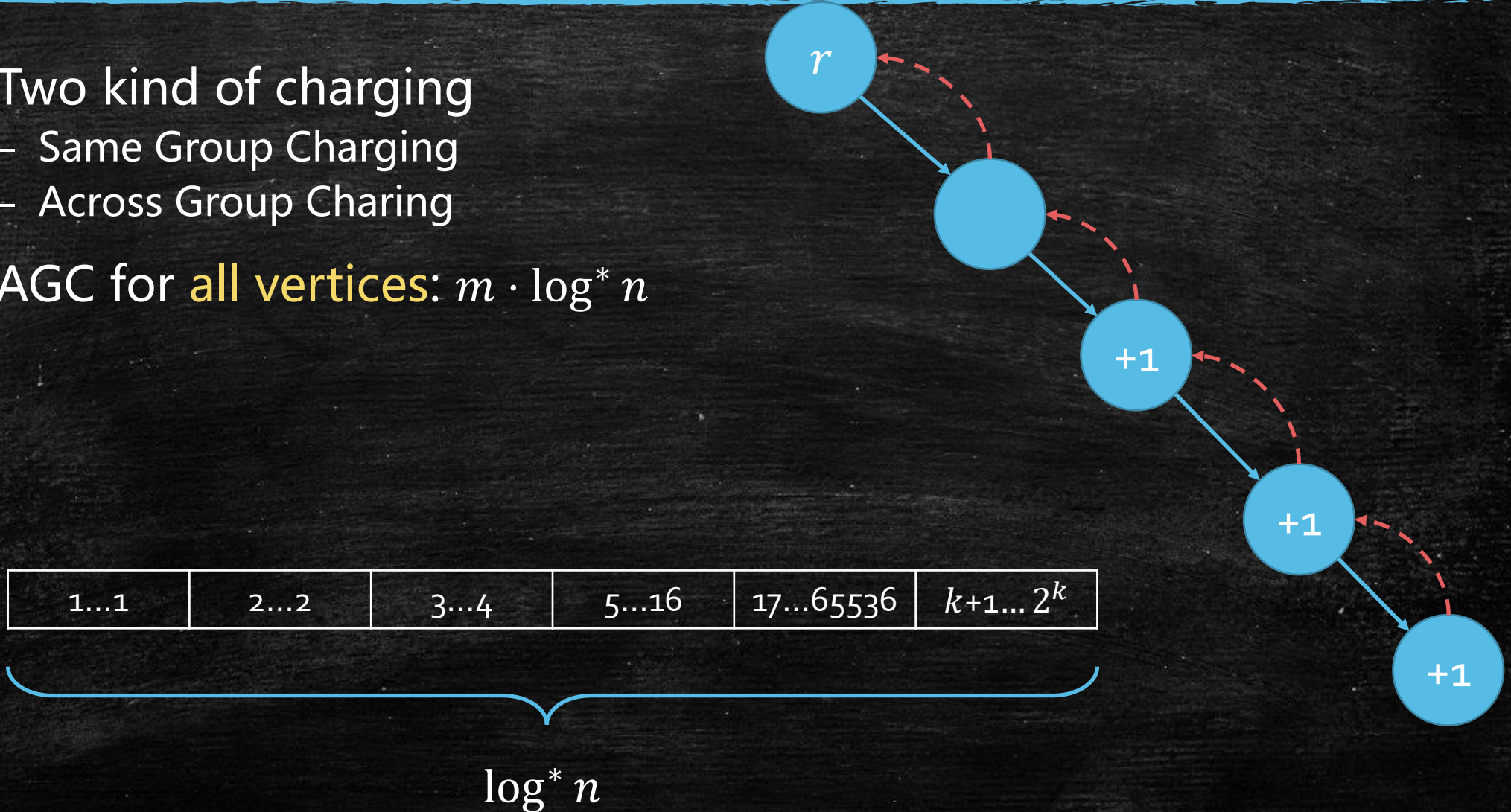
1...1	2...2	3...4	5...16	17...65536	$k+1... 2^k$
-------	-------	-------	--------	------------	--------------

$\log^* n$



# Different Type Charging

- Two kind of charging
  - Same Group Charging
  - Across Group Charging
- AGC for **all vertices**:  $m \cdot \log^* n$





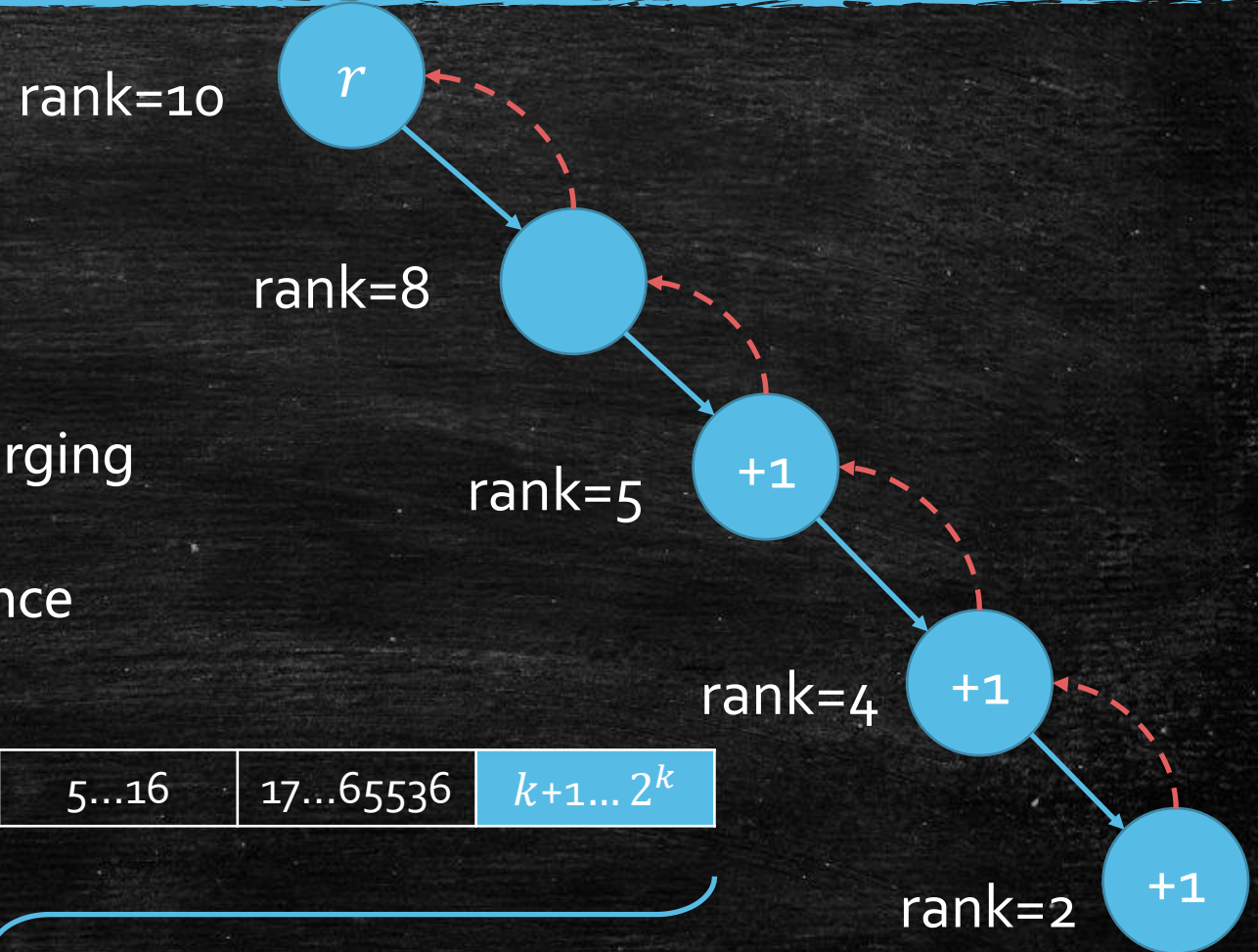
# Bound SGC

- SGC for  $v$
- One SGC
  - $\text{rank}(\text{parent}(v)) > \text{rank}(v)$
  - rank based union
  - $\text{rank}(\text{parent}(v))++$  after charging
  - path compression
  - For  $v$ , each rank charged once
  - Totally  $2^k - k \leq 2^k$  charging

1...1	2...2	3...4	5...16	17...65536	$k+1...2^k$
-------	-------	-------	--------	------------	-------------



$\log^* n$





# Bound Total cost

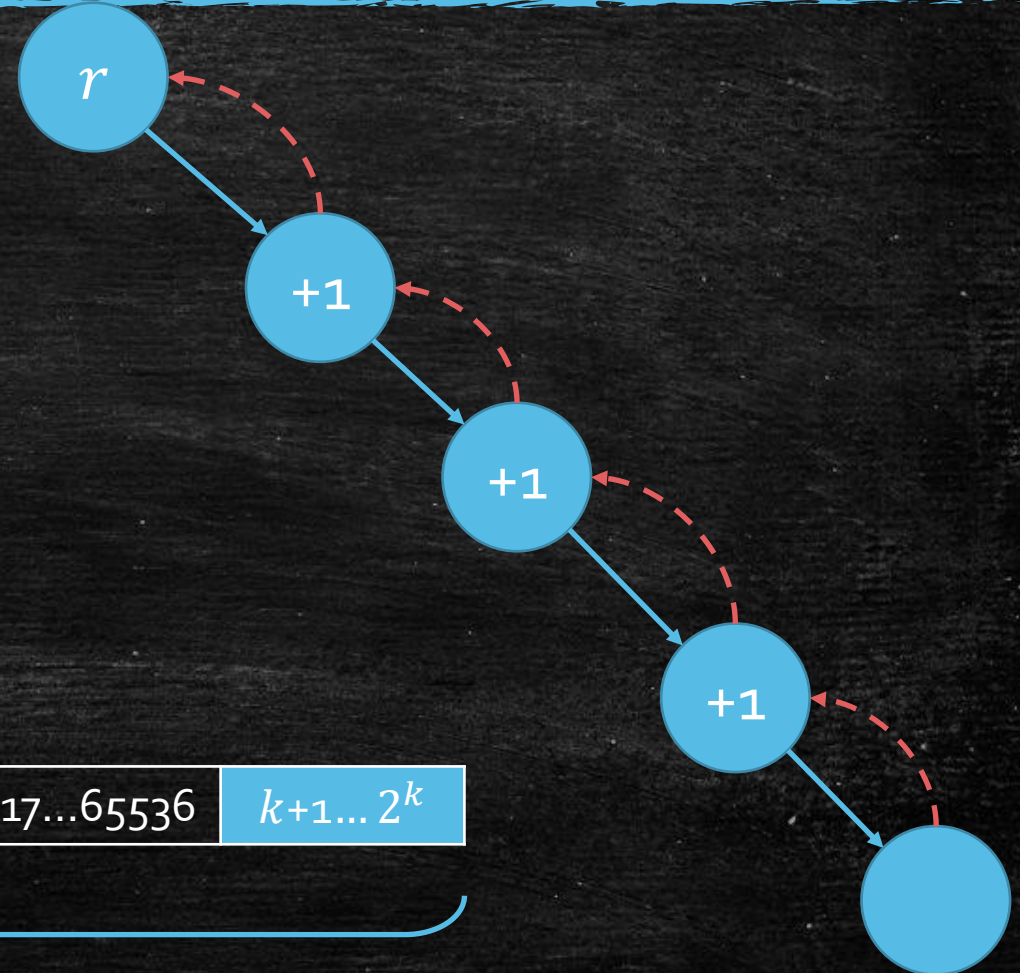
## ▪ Total Cost of $m$ FIND

- $O(m)(\text{to root})$
- Total AGC
  - $m \cdot \log^* n$
- Total SGC
  - $\sum_{\text{groups}} \# \text{vertices} \cdot 2^k$
  - $\# \text{vertices} \leq n/2^k$
  - $n \log^* n$
- Total :  $m \log^* n$

1...1	2...2	3...4	5...16	17...65536	$k+1 \dots 2^k$
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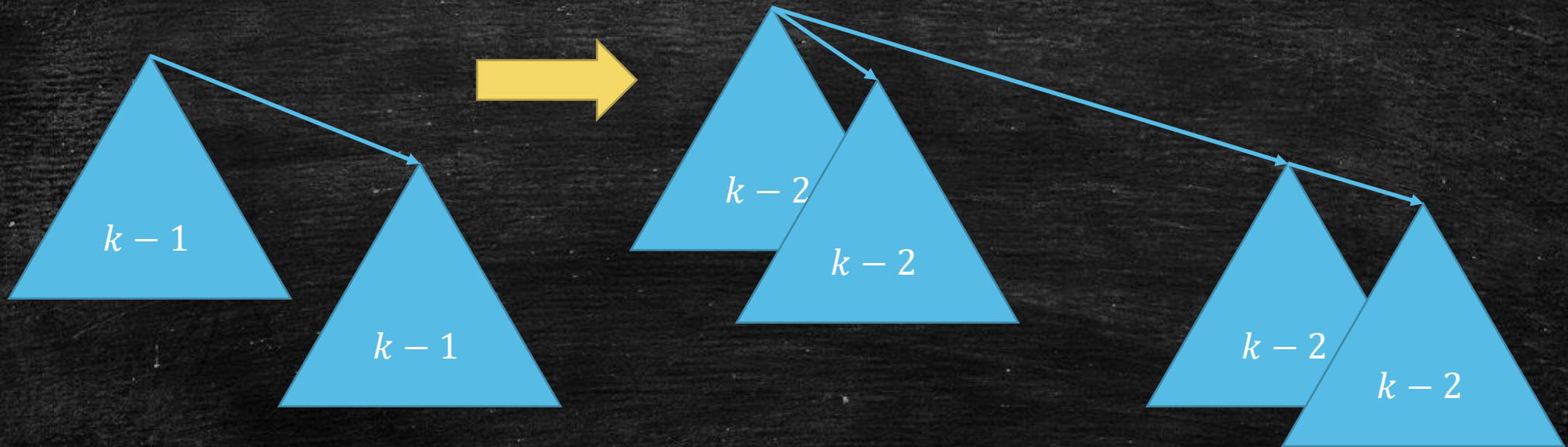


$\log^* n$





Why  $\#vertices \leq \frac{n}{2^k}$ ?



We should at least use  $2^k$  nodes!



# Today's goal

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- Learn what is **Greedy**!
- Learn to use **Greedy** to finish homework!
- Learn **Prim** and **Kruskal**!
- Again, how to use **Data Structure** to improve **Algorithms**.
- Review **Union-Find Set**!
- Learn another **Amortized Analysis**!