

Distributivity

$$(f+g) * h = h * (f+g)$$

commutativity,  
allows us to  
consider only one case,  
as they are equivalent

$$\begin{aligned} h * (f+g)(x) &= \int_{\mathbb{R}} h(x-x') (f(x') + g(x')) dx' \\ &= \int_{\mathbb{R}} [h(x-x') \cdot f(x') + h(x-x') g(x')] dx' \\ &= \int_{\mathbb{R}} h(x-x') \cdot f(x') dx' + \int_{\mathbb{R}} h(x-x') \cdot g(x') dx' \\ &= (h * f)(x) + (h * g)(x) = (f * h)(x) + (g * h)(x) \end{aligned}$$

Shift invariance

$(T_b f) * g = T_b(f * g)$  for all translations  $T_b$  with  $(T_b f)(x) := f(x-b)$ .

$$\begin{aligned} T_b(f * g)(x) &= (f * g)(x-b) \\ &= \int_{\mathbb{R}} f(x-b-x') g(x') dx' = L \\ [T_b(f) * g](x) &= \int_{\mathbb{R}} T_b(f)(x-x') g'(x) dx' \\ &= \int_{\mathbb{R}} f(x-x'-b) g'(x) dx' = P = L \end{aligned}$$

