Report Generated by Test Manager

Title: ControllerModeSelector REQ-Based Test

S

Author:

Date: 22-Sep-2021 19:06:39

Test Environment

Platform: PCWIN64 MATLAB: (R2022a)

Summary

ourning,		Duration
Name	Outcome	(Seconds)
Results: 2021-Sep-22 19:06:21	2 🗷 2 🕢	10.201
ControllerModeSelector_Test	2 🗷 2 🕢	10.202
requirements_based_tests	Ø	6.13
	Ø	6.13
interface tests	Ø	3.919
	Ø	3.92
injection tests	\bigcirc	0
	\bigcirc	0
resource_usage_tests	\bigcirc	0
<u>▼TC1</u>	\oslash	0.00099993

Results: 2021-Sep-22 19:06:21

Result Type: Result Set
Parent: None

Start Time: 22-Sep-2021 19:06:24 End Time: 22-Sep-2021 19:06:34

Outcome: Total: 4, Passed: 2, Disabled: 2

Aggregated Coverage Results

Analyzed Model	Sim Mode	Complexity	Decision	Condition	Execution
ControllerModeSelector	Normal	4	100%	100%	100%

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ControllerModeSelector_Test

Test Result Information

Result Type: Test File Result

Parent: Results: 2021-Sep-22 19:06:21

Start Time: 22-Sep-2021 19:06:24 End Time: 22-Sep-2021 19:06:34

Outcome: Total: 4, Passed: 2, Disabled: 2

Description:

Model Version: 4.0

Model Last Modified On: 22-Sep-2021 18:13:09

Checksum when Compiled as Referenced Model: 2294784352 2520475279

2926236726 1354712116

Test Suite Information

Name: ControllerModeSelector Test

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requirements_based_tests

Test Result Information

Result Type: Test Suite Result

Parent: <u>ControllerModeSelector Test</u>

Start Time: 22-Sep-2021 19:06:24 End Time: 22-Sep-2021 19:06:30 Outcome: Total: 1, Passed: 1

Test Suite Information

Name: requirements_based_tests

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TC1

Test Result Information

Result Type: Test Case Result

Parent: requirements based tests
Start Time: 22-Sep-2021 19:06:24

End Time: 22-Sep-2021 19:06:30

Outcome: Passed

Test Case Information

Name: TC1

Type: Baseline Test
Baseline Name: RegBaseline.mat

Baseline File: C:\Users\mabualqu\hlf2\ISO_06_09_SwUVer\WPs\I

 $SO_6_9_5_1_SwVerSpec\ControllerModeSelector\R$

eqBaseline.mat

Test Case Requirements

Description: SW HLF#7.3 Controller Mode Selection

Document: SSRS.slregx

Baseline Comparison

	Abs T	Rel To	Lead T	Lag T	Max Di	D-4- T 4 W-i4- 4	Sample Ti			Sample Tim		C
Name	ol	1	ol	ol	ff	Data Type 1 Units 1	me 1	Data Type 2	Units 2	e 2	Interp	Sync

braking_s witch	0	0	()	0		0	 uint8				BrStatus	 	0.1	zoh	union
Accelerati onCmd:1	0	0	()	0	-	0	 double	m/s^2	0.1	1	double	m/s^2	0.1	zoh	union

ReqBaseline.mat

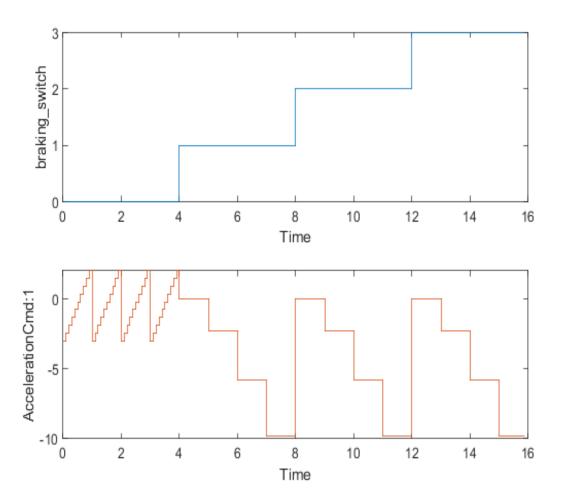
Baseline Information

Baseline Name:

 $\label{lem:condition} ReqBaseline.mat $$C:\Users\mabualqu\hlf2\ISO_06_09_SwUVer\WPs\ISO_6_9_5_1_SwVerSpec\ControllerModeSelector\R eqBaseline.mat$ Baseline File:

Name	Data Type	Units	Sample Time	Interp	Sync	Link to Plo t
braking_switch	uint8			zoh	union	<u>Link</u>
AccelerationCmd:1	double	m/s^2	0.1	zoh	union	Link

Name	Data Type	Units	Sample Time	Interp	Sync
braking_switch	uint8			zoh	union
AccelerationCmd:1	double	m/s^2	0.1	zoh	union



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Input Data

Input Information

External Input ReqInputData.mat

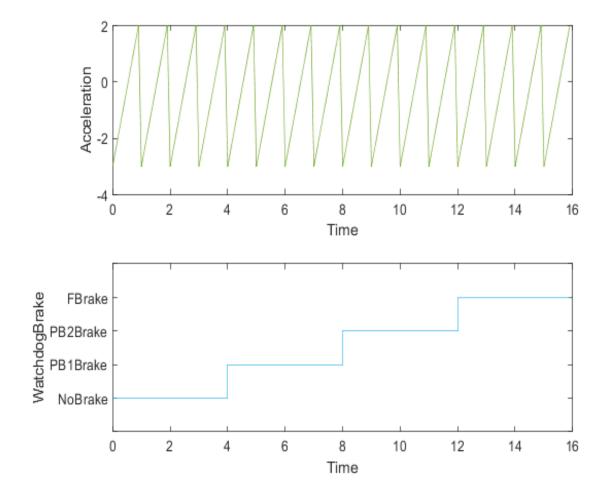
Name:

 $SO_6_9_5_1_SwVerSpec\ControllerModeSelector\R$

eqInputData.mat

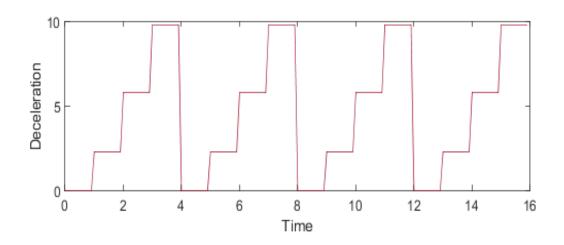
Name	Data Type	Units	Sample Time	Interp	Sync	Link to Plo t
Acceleration	double	 	Continuous	linear	union	<u>Link</u>
WatchdogBrake	BrStatus		 	zoh	union	<u>Link</u>
Deceleration	double		Continuous	linear	union	<u>Link</u>

Name	Data Type	Units	Sample Time	Interp	Sync
Acceleration	double	 	Continuous	linear	union
WatchdogBrake	BrStatus			zoh	union



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Name	Data Type	Units	Sample Time	Interp	Sync
Deceleration	double		Continuous	linear	union



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Simulation

System Under Test Information

Model: ControllerModeSelector

Harness: ControllerModeSelector Harness

Harness Owner: ControllerModeSelector

Release: Current Simulation Mode: normal

Override SIL or PIL 0

Mode:

Configuration Set: csMultiInstance External Input Name: ReqInputData.mat

External Input File: C:\Users\mabualqu\hlf2\ISO_06_09_SwUVer\WPs\I

SO_6_9_5_1_SwVerSpec\ControllerModeSelector\R

eqInputData.mat

Start Time: 0 Stop Time: 15.9

Checksum: 1169674009 36874468 980624401 834964869

Simulink Version: 10.4 Model Version: 3.0

Model Author: mabualqu

Date: Wed Sep 22 18:13:11 2021

User ID: mabualqu

Model Path: C:\Users\mabualqu\hlf2\ISO 06 08 SwU\WPs\ISO

6_8_5_1_SwUnDesSpec\ControllerModeSelector\C

ontrollerModeSelector Harness.slx

Machine Name: BAT917931WIN64 Solver Name: FixedStepDiscrete

Solver Type: Fixed-Step

Fixed Step Size: 0.10000000000000001 Simulation Start Time: 2021-09-22 19:06:24 Simulation Stop Time: 2021-09-22 19:06:26

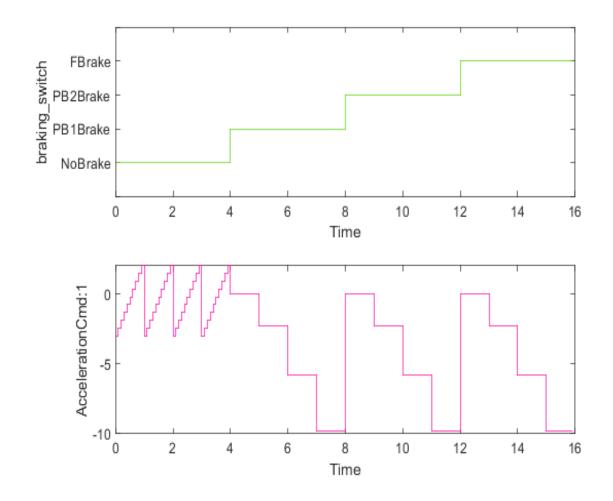
Platform: PCWIN64

Simulation Output

Name	Data Type	Units	Sample Time	Interp	Sync	Link to Plo t
braking_switch	BrStatus	 	0.1	zoh	union	<u>Link</u>

AccelerationCmd:1	double	m/s^2	0.1	zoh	union Link	
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Name	Data Type	Units	Sample Time	Interp	Sync
_braking_switch	BrStatus		0.1	zoh	union
AccelerationCmd:1	double	m/s^2	0.1	zoh	union



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Simulation Logs:

Simulation stopped at '15.9' because there is no input data after this time point.

Symbol 'BusMultiObjectTracker' is defined in <u>DD_HLF_DataTypes.sldd</u> and <u>base workspace</u>. The definition in <u>DD_HLF_DataTypes.sldd</u> is used.

Symbol 'BusMultiObjectTrackerTracks' is defined in <u>DD_HLF_DataTypes.sldd</u> and <u>base workspace</u>. The definition in <u>DD_HLF_DataTypes.sldd</u> is used.

Symbol 'BusRadarDetectionsObjectAttributes' is defined in DD_HLF_DataTypes.sldd and base workspace. The definition in DD_HLF_DataTypes.sldd is used.

Symbol 'BusVehiclePose' is defined in <u>DD_HLF_DataTypes.sldd</u> and <u>base workspace</u>. The definition in <u>DD_HLF_DataTypes.sldd</u> is used.

Symbol 'LaneSensor' is defined in <u>DD_HLF_DataTypes.sldd</u> and <u>base workspace</u>. The definition in <u>DD_HLF_DataTypes.sldd</u> is used.

Symbol 'LaneSensorBoundaries' is defined in <u>DD_HLF_DataTypes.sldd</u> and <u>base workspace</u>. The definition in <u>DD_HLF_DataTypes.sldd</u> is used.

Symbol 'Ts' is defined in <u>DD_HLF_Configuration.sldd</u> and <u>base workspace</u>. The definition in <u>DD_HLF_Configuration.sldd</u> is used.

Symbol 'max_ac' is defined in <u>DD_PFC_Configuration.sldd</u> and <u>base workspace</u>. The definition in <u>DD_PFC_Configuration.sldd</u> is used.

Symbol 'max_dc' is defined in <u>DD_PFC_Configuration.sldd</u> and <u>base workspace</u>. The definition in <u>DD_PFC_Configuration.sldd</u> is used.

Symbol 'tau' is defined in <u>DD_PFC_Configuration.sldd</u> and <u>base workspace</u>. The definition in <u>DD_PFC_Configuration.sldd</u> is used.

Symbol 'tau2' is defined in <u>DD_PFC_Configuration.sldd</u> and <u>base workspace</u>. The definition in DD_PFC_Configuration.sldd is used.

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interface_tests

Test Result Information

Result Type: Test Suite Result

Parent: <u>ControllerModeSelector Test</u>

Start Time: 22-Sep-2021 19:06:30 End Time: 22-Sep-2021 19:06:34 Outcome: Total: 1, Passed: 1

Test Suite Information

Name: interface_tests

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TC1

Test Result Information

Result Type: Test Case Result Parent: interface tests

Start Time: 22-Sep-2021 19:06:30 End Time: 22-Sep-2021 19:06:34

Outcome: Passed

Test Case Information

Name: TC1

Type: Baseline Test

Baseline Name: InterfaceBaseline.mat

Baseline File: C:\Users\mabualqu\hlf2\ISO_06_09_SwUVer\WPs\I

SO_6_9_5_1_SwVerSpec\ControllerModeSelector\I

nterfaceBaseline.mat

Baseline Comparison

Name	Abs T	Rel T ol	Lead Tol	Lag T ol	Max Di ff	Data Type 1	Units 1	Sample Tim e 1	Data Type 2	Units 2	Sample Tim e 2	Interp	Sync
braking_s witch	0	0	0	0	0	BrStatus		0.1	BrStatus		0.1	zoh	union
Accelerati onCmd:1	0	0	0	0	0	double	m/s^2	0.1	double	m/s^2	0.1	zoh	union

InterfaceBaseline.mat

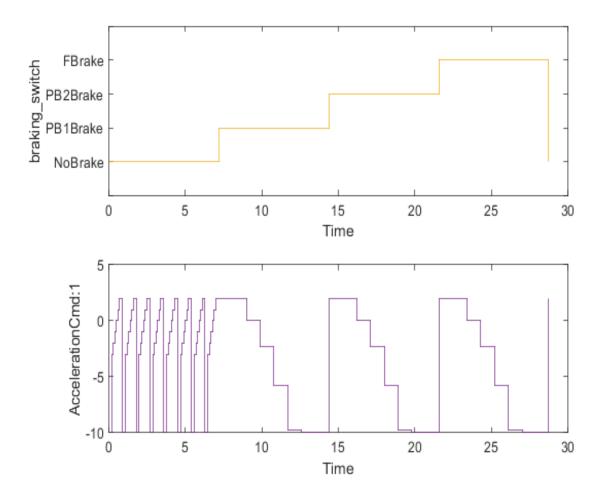
Baseline Information

Baseline Name: InterfaceBaseline.mat

C:\Users\mabualqu\hlf2\ISO_06_09_SwUVer\WPs\ISO_6_9_5_1_SwVerSpec\ControllerModeSelector\InterfaceBaseline.mat Baseline File:

Name	Data Type	Units	Sample Time	Interp	Sync	Link to Plo t
braking_switch	BrStatus	i 	0.1	zoh	union	<u>Link</u>
AccelerationCmd:1	double	m/s^2	0.1	zoh	union	<u>Link</u>

Name	Data Type	Units	Sample Time	Interp	Sync
braking_switch	BrStatus	i 	0.1	zoh	union
AccelerationCmd:1	double	m/s^2	0.1	zoh	union



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Input Data

Input Information

External Input InterfaceInputData.mat

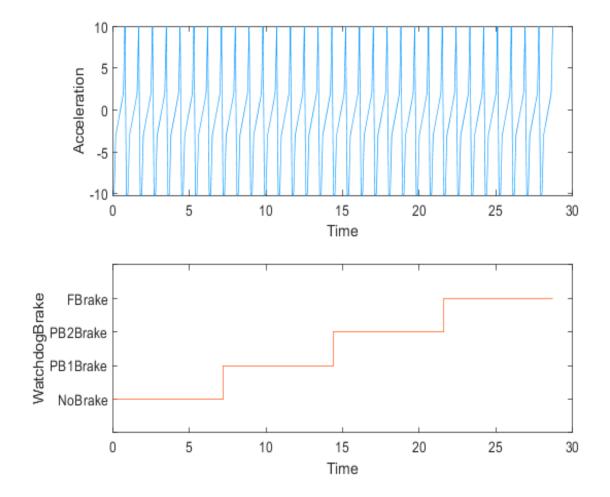
Name:

 $SO_6_9_5_1_SwVerSpec \backslash ControllerModeSelector \backslash I$

nterfaceInputData.mat

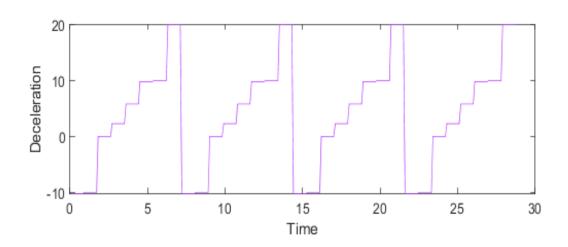
Name	Data Type	Units	Sample Time	Interp	Sync	Link to Plo t
Acceleration	double	i 	Continuous	linear	union	<u>Link</u>
WatchdogBrake	BrStatus	i 	 	zoh	union	<u>Link</u>
Deceleration	double		Continuous	linear	union	Link

Name	Data Type	Units	Sample Time	Interp	Sync
Acceleration	double		Continuous	linear	union
WatchdogBrake	BrStatus			zoh	union



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Name	Data Type	Units	Sample Time	Interp	Sync
Deceleration	double		Continuous	linear	union



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Simulation

System Under Test Information

Model: ControllerModeSelector

Harness: ControllerModeSelector Harness

Harness Owner: ControllerModeSelector

Release: Current Simulation Mode: normal

Override SIL or PIL 0

Mode:

Configuration Set: C:\Users\mabualqu\hlf2\ISO_06_09_SwUVer\WPs\I

SO_6_9_5_1_SwVerSpec\ControllerModeSelector\c

s Multi Instance Interface. mat

External Input Name: InterfaceInputData.mat

External Input File: C:\Users\mabualqu\hlf2\ISO_06_09_SwUVer\WPs\I

SO_6_9_5_1_SwVerSpec\ControllerModeSelector\I

nterfaceInputData.mat

Start Time: 0

Stop Time: 28.70000000000000

Checksum: 634788924 3835229932 155062810 554342077

Simulink Version: 10.4 Model Version: 3.0

Model Author: mabualqu

Date: Wed Sep 22 18:13:11 2021

User ID: mabualqu

Model Path: C:\Users\mabualqu\hlf2\ISO_06_08_SwU\WPs\ISO_

6_8_5_1_SwUnDesSpec\ControllerModeSelector\C

ontrollerModeSelector Harness.slx

Machine Name: BAT917931WIN64 Solver Name: FixedStepDiscrete

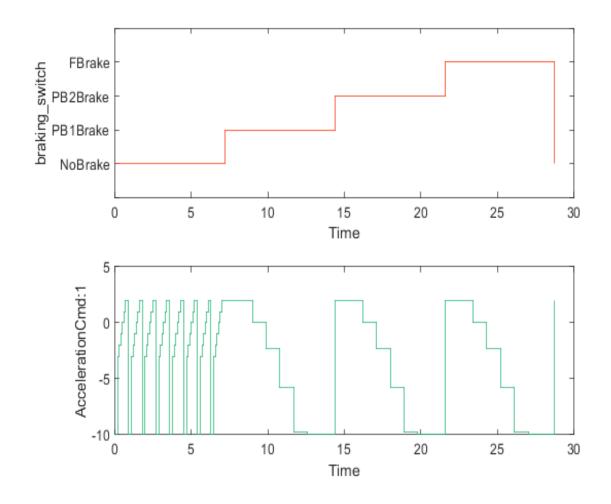
Solver Type: Fixed-Step

Platform: PCWIN64

Simulation Output

Name		Data Type	Units	Sample Time	Interp	Sync	Link to Plo t
_braking_swit	ch	BrStatus	i 	0.1	zoh	union	<u>Link</u>
Acceleration	Cmd:1	double	m/s^2	0.1	zoh	union	<u>Link</u>

Name	Data Type	Units	Sample Time	Interp	Sync
braking_switch	BrStatus		0.1	zoh	union
AccelerationCmd:1	double	m/s^2	0.1	zoh	union



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Simulation Logs:

Simulation stopped at '28.699999999999999999999999999999 because there is no input data after this time point.

Symbol 'BusMultiObjectTracker' is defined in <u>DD_HLF_DataTypes.sldd</u> and <u>base</u> workspace. The definition in <u>DD_HLF_DataTypes.sldd</u> is used.

Symbol 'BusMultiObjectTrackerTracks' is defined in <u>DD_HLF_DataTypes.sldd</u> and <u>base workspace</u>. The definition in <u>DD_HLF_DataTypes.sldd</u> is used.

Symbol 'BusRadarDetectionsObjectAttributes' is defined in DD_HLF_DataTypes.sldd and base workspace. The definition in DD_HLF_DataTypes.sldd is used.

Symbol 'BusVehiclePose' is defined in <u>DD_HLF_DataTypes.sldd</u> and <u>base workspace</u>. The definition in <u>DD_HLF_DataTypes.sldd</u> is used.

Symbol 'LaneSensor' is defined in <u>DD_HLF_DataTypes.sldd</u> and <u>base workspace</u>. The definition in <u>DD_HLF_DataTypes.sldd</u> is used.

Symbol 'LaneSensorBoundaries' is defined in <u>DD_HLF_DataTypes.sldd</u> and <u>base workspace</u>. The definition in <u>DD_HLF_DataTypes.sldd</u> is used.

Symbol 'Ts' is defined in <u>DD_HLF_Configuration.sldd</u> and <u>base workspace</u>. The definition in <u>DD_HLF_Configuration.sldd</u> is used.

Symbol 'max_ac' is defined in <u>DD_PFC_Configuration.sldd</u> and <u>base workspace</u>. The definition in <u>DD_PFC_Configuration.sldd</u> is used.

Symbol 'max_dc' is defined in <u>DD_PFC_Configuration.sldd</u> and <u>base workspace</u>. The definition in <u>DD_PFC_Configuration.sldd</u> is used.

Symbol 'tau' is defined in <u>DD_PFC_Configuration.sldd</u> and <u>base workspace</u>. The definition in DD_PFC_Configuration.sldd is used.

Symbol 'tau2' is defined in <u>DD_PFC_Configuration.sldd</u> and <u>base workspace</u>. The definition in <u>DD_PFC_Configuration.sldd</u> is used.

Inconsistent numeric values for port 1 of '<u>ControllerModeSelector Harness/Acceleration</u>': Output value (-10.2) at major time step 0 is less than minimum (-4) from '<u>ControllerModeSelector Harness/ControllerModeSelector</u>'

Inconsistent numeric values for port 1 of '<u>ControllerModeSelector_Harness/</u>
<u>Deceleration</u>': Output value (-10.2) at major time step 0 is less than minimum (0) from 'ControllerModeSelector Harness/ControllerModeSelector'

Inconsistent numeric values for port 1 of '<u>ControllerModeSelector Harness/</u>
<u>Acceleration</u>': Output value (10) at major time step 0.8 is greater than maximum (2) from 'ControllerModeSelector_Harness/ControllerModeSelector'

Inconsistent numeric values for port 1 of '<u>ControllerModeSelector_Harness/</u>
<u>Deceleration</u>': Output value (10) at major time step 5.4 is greater than maximum (9.8) from 'ControllerModeSelector_Harness/ControllerModeSelector'

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fault_injection_tests

Test Result Information

Result Type: Test Suite Result

Parent: ControllerModeSelector Test

 Start Time:
 22-Sep-2021 19:06:21

 End Time:
 22-Sep-2021 19:06:21

 Outcome:
 Total: 1, Disabled: 1

Test Suite Information

Name: fault injection tests

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TC1

Test Result Information

Result Type: Test Case Result
Parent: <u>fault injection tests</u>
Start Time: 22-Sep-2021 19:06:21
End Time: 22-Sep-2021 19:06:21

Outcome: Disabled

Test Case Information

Name: TC1

Type: Baseline Test

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resource_usage_tests

Test Result Information

Result Type: Test Suite Result

Parent: ControllerModeSelector_Test

 Start Time:
 22-Sep-2021 19:06:21

 End Time:
 22-Sep-2021 19:06:21

 Outcome:
 Total: 1, Disabled: 1

Test Suite Information

Name: resource_usage_tests

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TC1

Test Result Information

Result Type: Test Case Result

Parent: resource usage tests
Start Time: 22-Sep-2021 19:06:21
End Time: 22-Sep-2021 19:06:21

Outcome: Disabled

Test Case Information

Name: TC1

Type: Baseline Test

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