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Code contains 3 files
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- -> Custom built library for matrix operations 1. matrix.cpp
- 2. matrix.h -> Header file for matrix.cpp
- 3. bfs.cpp -> Code to solve using Basic Feasible Solutions method

1. Code for matrix.cpp

```
#include <stdio.h>
#include <iostream>
#include <math.h>
#include "matrix.h'
using namespace std;
     Constructor for the matrix class
Matrix::Matrix(int a=0, int b=0)
  rows = a;
  mat = new double*[rows];
  for(int i = 0; i < rows; ++i)
     mat[i] = new double[cols];
     for(int j = 0; j < cols; j++)
       mat[i][j] = 0;
        Function to read a matrix
void Matrix::read_matrix()
  for(int i = 0; i < rows; i++)
     for(int j = 0; j<cols; j++)
       cin>>mat[i][j];
      Function to display a matrix
void Matrix::display_matrix()
  for(int i = 0; i < rows; i++)
     for(int j = 0; j < cols; j++)
       cout<<mat[i][j]<<"\t";
     cout<<endl;
  cout<<endl;
        Function to perform deep copy of matrix
Matrix Matrix::copy()
  Matrix clone(rows, cols);
```

```
for (int i = 0; i < rows; ++i)
     for (int j = 0; j < cols; ++j) clone.mat[i][j] = this->mat[i][j];
  return clone;
//
         Function to find transpose of a matrix
//---
Matrix Matrix::transpose()
{
  Matrix result(cols, rows);
  int i, j;
  for(i = 0; i < rows; i++)
     for(j = 0; j < cols; j++)
        result.mat[j][i] = this->mat[i][j];
  return result;
         Function to find the first non-zero element
//----
void Matrix::update_leading_0s(int *leading_0s, Matrix a)
{
  int i, j;
  for(i = 0; i < a.rows; ++i)
     leading 0s[i] = 0;
     for(j=0; (fabs(a.mat[i][j]) < 0.00001) && (j < a.cols); ++j) leading_0s[i]++;
}
// Function to rearrange arrange A such that pivot positions have 1
void Matrix::pivot_rearrange(int *leading_0s, Matrix a)
{
  int I, remrow, i, k, lastrow, large;
  double *rowtemn = new double[a.cols];
  lastrow = rows-1;
  for(I = 0; I < a.rows; ++I)
     large = leading_0s[0];
     for(i = 0; i < a.rows; ++i)
        if( large <= leading_0s[i])
          large=leading_0s[i];
          remrow=i;
  leading_0s[remrow] = leading_0s[lastrow];
  leading_0s[lastrow] = -1;
   for(k = 0; \ k < a.cols; ++k) \quad rowtemn[k] = a.mat[lastrow][k]; \\ for(k = 0; \ k < a.cols; ++k) \quad a.mat[lastrow][k] = a.mat[remrow][k]; \\ 
  for(k = 0; k < a.cols; ++k) a.mat[remrow][k] = rowtemn[k];</pre>
  lastrow--;
//
         Function definition to scale a A
//---
void Matrix::scale_A(int *leading_0s, Matrix a)
{
  double divisor;
  for(i = 0; i < a.rows; ++i)
     divisor = a.mat[i][leading_0s[i]];
```

```
for(j = leading\_0s[i]; j < a.cols; ++j) \quad a.mat[i][j] = a.mat[i][j] / divisor;
}
//
        Function to find trank of a matrix
//---
int Matrix::rank()
{
  Matrix a = this->copy();
  int i, next_row = 1, grp, p, r, j, *leading_0s, t, m, rank;
leading_0s = new int[a.rows];
  update_leading_0s(leading_0s, a);
  pivot_rearrange(leading_0s, a);
  if(fabs(a.mat[0][0]) < 0.00001)
     cout << "Not a valid matrix as pivot element is 0" << endl;
  update_leading_0s(leading_0s, a);
  scale_A(leading_0s, a);
  while(next_row == 1)
     grp = 0;
     for( i = 0; i < rows; ++i)
       p = 0;
       while(leading_0s[i+p] == leading_0s[i+p+1] && (i+p+1) < a.rows)
          grp++;
          p++;
       if(grp != 0)
          while(grp != 0)
            for(j = 0; j < a.cols; ++j) a.mat[i+grp][j] = a.mat[i+grp][j] - a.mat[i][j];
          break;
     update_leading_0s(leading_0s, a);
     pivot_rearrange(leading_0s, a);
     update_leading_0s(leading_0s, a);
     scale_A(leading_0s, a);
     next_row=0;
     for(r = 0; r < a.rows; ++r)
       if(leading_0s[r] == leading_0s[r+1] && r+1 < a.rows)
          if(leading_0s[r] != a.cols) next_row = 1;
     }
  rank = 0;
  for (i = 0; i < a.rows; ++i)
     if (leading_0s[i] != a.cols) ++rank;
  return rank;
        Function to find the determinant
//---
double Matrix::determinant()
  if(rows != cols) { cout<<" Not a square matrix !!"; return 0;}
```

```
int j,p,q;
  double det =0;
  if(rows == 2){ return (mat[0][0]*mat[1][1]) - (mat[0][1]*mat[1][0]); }
  Matrix b(rows-1, rows-1);
  for(j = 0; j < cols; j++)
     int r = 0, s = 0;
    for(p = 0; p < rows; p++)
       for(q = 0; q < cols; q++)
       {
          if(p !=0 && q != j)
          {
            b.mat[r][s] = mat[p][q];
            s++;
            if(s > cols-2)
               {
                 s = 0;
       }
     det += (j%2 ? -1:1) * mat[0][j] * b.determinant();
  return det;
//
        Function to find the inverse
Matrix Matrix::inverse()
{
  double det = this->determinant();
  if( fabs(det) < 0.01)
  {
    cout << "Matrix is not invertible!" << endl;</pre>
  int i,j, q, p, sign, r, s;
  double cofdet;
  Matrix inv( rows, cols);
  Matrix cof( rows - 1, cols - 1);
  for(i = 0; i < rows; i++)
  {
     for(j = 0; j < cols; j++)
    {
       sign = ((i+j)%2 ? -1 : 1);
       r = 0, s = 0;
       for(p = 0; p < rows; p++)
          for(q = 0; q < cols; q++)
            if(p != i \&\& q != j)
               cof.mat[r][s] = mat[p][q];
               s++;
if(s > cols-2)
                 {
                    r++;
                    s = 0;
       cofdet = cof.determinant();
       inv.mat[i][j] = (fabs(cofdet) < 0.1 ? 0 : sign) * cofdet / det;
  }
  return inv.transpose();
//
        Function to multiply 2 matrices
```

```
Matrix Matrix::multiply(Matrix other)
  if(cols != other.rows) { cout<< " Invalid dimensions !"; return *this;}</pre>
  Matrix product(this-> rows, other.cols);
  int i, j, k;
  for(i = 0; i < this-> rows; i++)
     for(j = 0; j < other.cols; j++)
       for(k = 0; k < this-> cols; k++)
          product.mat[i][j] += this->mat[i][k] * other.mat[k][j];
     }
  return product;
        Function to truncate extremely small float values to 0
Matrix Matrix::readjust()
  for(int i = 0; i < rows; i++)
     for(int j = 0; j<cols; j++)
       if(fabs(mat[i][j]) < 0.00001) mat[i][j] = 0;
  return *this;
2. matrix.h
class Matrix{
public:
  int rows;
  int cols;
  double** mat;
  Matrix(int, int);
  void read_matrix(void);
  void display_matrix(void);
  Matrix copy();
  Matrix transpose();
  int rank(void);
  double determinant();
  Matrix inverse();
  Matrix multiply(Matrix);
  Matrix readjust();
  void scale_A(int *, Matrix);
  void pivot_rearrange(int *, Matrix);
void update_leading_0s(int *, Matrix);
};
3. bfs.cpp
#include <iostream>
#include <stdio.h>
#include <math.h>
#include "../Matrix/matrix.h"
#include <limits>
using namespace std;
int count = 0;
      Function to find the factorial of a number
```

```
int factorial(int n)
{
          if(n == 0 | | n == 1) return 1;
return n * factorial(n-1);
}
        Function to find al nCr combinations
//
//---
void combination(int *arr, int *data, int start, int end, int index, int r, int **comb)
  // Current combination is ready to be printed, print it
  if (index == r)
     for (int j = 0; j < r; j++)
       comb[::count][j] = data[j];
     ::count++;
     return;
  }
  // replace index with all possible elements. The condition
  // "end-i+1 >= r-index" makes sure that including one element
  // at index will make a combination with remaining elements
  // at remaining positions
  for (int i = start; i <= end && end-i+1 >= r-index; i++)
     data[index] = arr[i];
     combination(arr, data, i+1, end, index+1, r, comb);
        Function to solve a system of equations of form AX =b
//---
Matrix solve(Matrix A, Matrix b, int vars, int eqs, int *zeros)
{
           Matrix a = A.copy();
          int i,j;
           for( i = eqs; i < vars; i++)
                     a.mat[i][zeros[i-eqs]-1] = 1;
           if(fabs(a.determinant()) > 0.01)
                     return a.inverse().multiply(b);
           else
                     Matrix res(vars, 1);
                     for( i = 0; i < vars; i++) res.mat[i][0] = -1;
                     return res;
          }
}
        Function to find all solutions and then eliminate
//
                                all non-feasible solutions and to finally obtain
//
//
                                Basic Feasible solutions and find optimal solution
//-
void find_optimum(Matrix A, Matrix b, int **combinations, int vars, int eqs, int sols, Matrix Z, bool max)
{
          int i, j, flag;
           double min_z = std::numeric_limits<double>::max();
           double max_z = std::numeric_limits<double>::min();
           double z;
           Matrix basic(vars, 1);
           for(i = 0; i < sols; i++)
           {
                     flag = 0;
                     basic = solve(A, b, vars, eqs, combinations[i]).copy();
                     basic.readjust();
                     cout << endl << "Solution is " << endl;
                     basic.transpose().display_matrix();
                     for(j = 0; j < vars; j++)
                                if(basic.mat[j][0] < 0) flag = 1;
                     if(flag)
```

```
{
                              cout << "Not a feasible solution" << endl;
                              continue;
                    else
                    {
                              cout << "Basic feasible solution found" << endl;
                              z = Z.multiply(basic).mat[0][0];
                              if(z > max_z) max_z = z;
                              if(z < min_z) min_z = z;
                              cout << "Value of Z is " << z << endl;
                    }
          if(max)
                    cout << endl << "Max value of Z is " << max z << endl;
          else
                    cout << endl << "Min value of Z is " << min z << endl;
int main()
{
  int vars, eqs, i, j, flag;
  double max_z, min_z;
  double *optimal sol;
  cout<<"Enter number of variables"<<endl;
  cin>> vars;
  cout << "Enter number of equations" << endl;
  cin>> eqs;
  Matrix A(eqs, vars);
  Matrix Z(1, vars);
  Matrix A_square(vars, vars);
  Matrix b_big(vars, 1);
  cout <<"Enter the data of matrix A"<<endl;
  A.read_matrix();
  cout <<"Matrix A :-"<<endl;
  A.display_matrix();
  flag = 0;
  while(A.rank() != eqs)
  {
          cout << "Rank is less than the number of equations" << endl;
          cout << "Check for linear dependency in constraints " << endl;
          eqs = A.rank();
          cout << "You should have " << eqs;
          cout << " independent equations " << endl;
          Matrix A(eqs, vars);
          cout << "Enter matrix A with independent equations" << endl;
          A.read_matrix();
  }
  Matrix b(eqs, 1);
  cout <<"Enter the data of matrix b"<<endl;
  b.read_matrix();
  cout <<"Matrix b :-"<<endl;</pre>
  b.display_matrix();
  cout <<"Enter the coefficients of the "<<vars<<" variables in the objective function Z in order"<<endl;
  Z.read_matrix();
  cout<< "Objective function is "<<endl;
  Z.display_matrix();
  cout << "Enter 1 if it is a maximization problem else 0" << endl;
  bool max_or_min;
  cin >> max_or_min;
  for(i = 0; i < eqs; i++)
  {
          for(j = 0; j < vars; j++)
                                         A_square.mat[i][j] = A.mat[i][j];
          b_big.mat[i][0] = b.mat[i][0];
  }
  int rank = A.rank();
  cout << endl << "Beginning Basic Feasible Solution Method . . ." <<endl;
```

```
cout << "We set " << vars - rank << " variables to be 0 at a time " <<endl;
  optimal_sol = new double[vars];
  int sols = factorial(vars) / (factorial(vars - rank) * factorial(rank));
  cout << "Number of solutions possible is " << sols <<endl;
  int **combinations = new int*[sols];
  for(i = 0; i < sols; i++)
         combinations[i] = new int[vars - rank];
  int *arr = new int[vars];
  for(i = 0; i < vars; i++) arr[i] = i+1;
  int* data = new int[rank];
  combination(arr, data, 0, vars-1, 0, vars - rank, combinations);
  find_optimum(A_square, b_big, combinations, vars, eqs, sols, Z, max_or_min);
  return 0;
RESULTS -
Problem 2.a (Max Problem)
Enter number of variables
Enter number of equations
Enter the data of matrix A
21-100
340-10
1200-1
Matrix A:-
2
3
                   0
          4
Enter the data of matrix b
20 50 20
Matrix b:-
20
50
20
Enter the coefficients of the 5 variables in the objective function Z in order
46000
Objective function is
                             0
                                       0
         6
Enter 1 if it is a maximization problem else 0
Beginning Basic Feasible Solution Method . . .
We set 2 variables to be 0 at a time
Number of solutions possible is 10
Solution is
                             -50
                                       -20
Not a feasible solution
Solution is
                   0
                             30
                                       20
Basic feasible solution found
Value of Z is 120
```

Solution is

12.5

-7.5

0

5

Not a feasible solution

Solution is

0 10 -10 -10 0

Not a feasible solution

Solution is

10 0 0 -20 -10

Not a feasible solution

Solution is

16.6667 0 13.3333 0 -3.33333

Not a feasible solution

Solution is

20 0 20 10 0

Basic feasible solution found

Value of Z is 80

Solution is

6 8 0 0 2

Basic feasible solution found

Value of Z is 72

Solution is

6.66667 6.66667 0 -3.33333 0

Not a feasible solution

Solution is

10 5 5 0 0

Basic feasible solution found

Value of Z is 70

Max value of Z is 120

Problem 3.b (Min Problem)

Enter number of variables

4

Enter number of equations

Enter the data of matrix A

 $1\ 2\ 3\ 1 \\ 3\ 2\ 2\ 1$

4452

Matrix A:-

1 2 3 1 3 2 2 1 4 4 5 2

Rank is less than the number of equations Check for linear dependency in constraints You should have 2 independent equations

Enter matrix A with independent equations

1231

3221

Enter the data of matrix b

90

150

Matrix b :-

90

150

Enter the coefficients of the 4 variables in the objective function Z in order 9 1 1 9

Objective function is 1 Enter 1 if it is a maximization problem else 0 Beginning Basic Feasible Solution Method . . . We set 2 variables to be 0 at a time Number of solutions possible is 6 Solution is 0 0 -60 270 Not a feasible solution Solution is -1 -1 -1 Not a feasible solution Solution is 0 135 -60 0 Not a feasible solution Solution is 30 0 60

Basic feasible solution found Value of Z is 810

Solution is 38.5714 0 17.1429 0

Basic feasible solution found Value of Z is 364.286

Solution is 30 0 0

Basic feasible solution found Value of Z is 300

Min value of Z is 300