

$$y = w_0 + w_1 e^{-x_1} + w_2 x_1 + w_3 x_1 x_2$$

Assuming squared loss;

loss function will be $(y - \hat{y})^2$

WKT:-

$$w_{\text{new}} = w_{\text{old}} - \eta \frac{\partial \text{Loss}}{\partial w_{\text{old}}} \quad \eta \rightarrow \text{learning rate}$$

$$\text{Loss} = (y - w_0 - w_1 e^{-x_1} - w_2 x_1 - w_3 x_1 x_2)^2$$

→ Partial derivative w.r.t w_0

$$\frac{\partial \text{Loss}}{\partial w_0} = -2(y - w_0 - w_1 e^{-x_1} - w_2 x_1 - w_3 x_1 x_2)$$

→ Partial derivative w.r.t w_1

$$\frac{\partial \text{Loss}}{\partial w_1} = 2(y - w_0 - w_1 e^{-x_1} - w_2 x_1 - w_3 x_1 x_2)(-e^{-x_1})$$

$$\frac{\partial \text{Loss}}{\partial w_1} = 2(y - w_0 - w_1 e^{-x_1} - w_2 x_1 - w_3 x_1 x_2)(w_1 e^{-x_1} - e^{-x_1})$$

$$\frac{\partial \text{Loss}}{\partial w_1} = 2(y - w_0 - w_1 e^{-x_1} - w_2 x_1 - w_3 x_1 x_2)e^{-x_1}(w_1 - 1)$$

$$\frac{\partial \text{Loss}}{\partial \omega_1} = 2e^{-(y - \omega_0 - \omega_1 e^{-x_1} - \omega_2 x_1 - \omega_3 x_1 x_2)} (\omega_1 - 1)$$

Partial derivative wrt ω_2 :-

$$\frac{\partial \text{Loss}}{\partial \omega_2} = 2(y - \omega_0 - \omega_1 e^{-x_1} - \omega_2 x_1 - \omega_3 x_1 x_2)(-x_1)$$

$$\frac{\partial \text{Loss}}{\partial \omega_2} = -2x_1(y - \omega_0 - \omega_1 e^{-x_1} - \omega_2 x_1 - \omega_3 x_1 x_2)$$

Partial derivative wrt ω_3 :-

$$\frac{\partial \text{Loss}}{\partial \omega_3} = 2(y - \omega_0 - \omega_1 e^{-x_1} - \omega_2 x_1 - \omega_3 x_1 x_2)(-x_1 x_2)$$

$$x_1 \frac{\partial \text{Loss}}{\partial \omega_3} = -2x_1 x_2(y - \omega_0 - \omega_1 e^{-x_1} - \omega_2 x_1 - \omega_3 x_1 x_2)$$

Therefore the updated weights are:-

$$\begin{aligned} \rightarrow \omega_{0 \text{ new}} &= \omega_0 + \eta \cdot 2(y - \omega_0 - \omega_1 e^{-x_1} - \omega_2 x_1 + \omega_3 x_1 x_2) \\ \rightarrow \omega_{1 \text{ new}} &= \omega_1 - 2\eta(\omega_1 - 1)e^{-(y - \omega_0 - \omega_1 e^{-x_1} - \omega_2 x_1 - \omega_3 x_1 x_2)} \\ \rightarrow \omega_{2 \text{ new}} &= \omega_2 + \eta * 2x_1(y - \omega_0 - \omega_1 e^{-x_1} - \omega_2 x_1 - \omega_3 x_1 x_2) \\ \rightarrow \omega_{3 \text{ new}} &= \omega_3 + \eta * 2x_1 x_2(y - \omega_0 - \omega_1 e^{-x_1} - \omega_2 x_1 - \omega_3 x_1 x_2) \end{aligned}$$