## CSE 410 - AI: Homework 1

This homework will have, both a short written and coding assignment. The problems that are supposed to be written are clearly marked.

- 1) (30) (Written) Make heuristics Describe two heuristics for the slide problem and show (i.e. prove with words, equations, and diagrams), that they are admissible. Consistency is more difficult to show and don't have to (though the graph based A\* might return a suboptimal solution).
  - Which one do you believe will produce the smaller branching factor?
  - Consistency is more difficult to show but required for optimality in graph-type searches. What happens when you use an admissible heuristic in a graph search?
- 2) (10) (Written, submit plot) Sample 50 different, randomly generated initial states (make sure that there are at least some that have solution length of 10 or greater). Plot the optimal solution on the X-axis and the two heuristics on the Y axis. Label the graphs! You do not need to submit the code for generating the plot, only the code for the heuristic functions.
- 3) (60) Implementing A\* In this problem you will implement A\* using the two heuristics you designed in the first part. Make two functions h1(state,goal) and h2(state,goal) that return the computed heuristic value. The node object in the new code as slideproblem.py, has a field h that can store the heuristic value computed for the node, node also implements  $_-lt_-$ , so the object can be used directly by sorting functions and data structures that maintain sorted lists.

The problem breakdown will be %15 percent for each of the two heuristics, and %15 for each of the two  $A^*$  searches. Pick the better heuristic for your search implementation. The submissions will be ranked by their effective branching factor on test cases. Some notes:

- This code will need to run faster/explore fewer nodes than non-informed search in order to pass the tests.
- In order to accomplish this you need to use an appropriate data structure heapq and bisect are both good options. The node object in the new code as slideproblem.py, has a field f that can store the heuristic + path cost value computed for the node.
- Node also implements \_\_lt\_\_ based on the f-value, so the object can be used directly by sorting functions and data structures that maintain sorted lists.

Please submit searches.py with the functions:

```
h1(currstate : State, goalstate : State) -> numbers.Real:.
h2(currstate : State, goalstate : State) -> numbers.Real:.
a_star_tree(p : Problem) -> (actionlist: list, soludiondepth: int):.
a_star_graph(p : Problem) -> (tuple, int):.
```