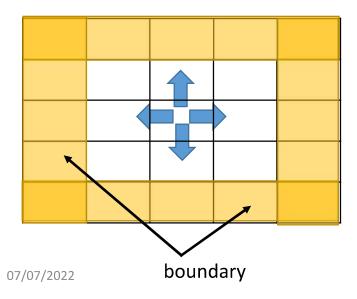
Jacobi MPI –example

Also known as 2D stencil or Laplace 2D operator

Jacobi Solver

- The Jacobi method is an iterative algorithm for solving a system of linear equations.
- In the 2D model an approximation can be made by taking the average of the 4 neighbouring values (4 point stencil).

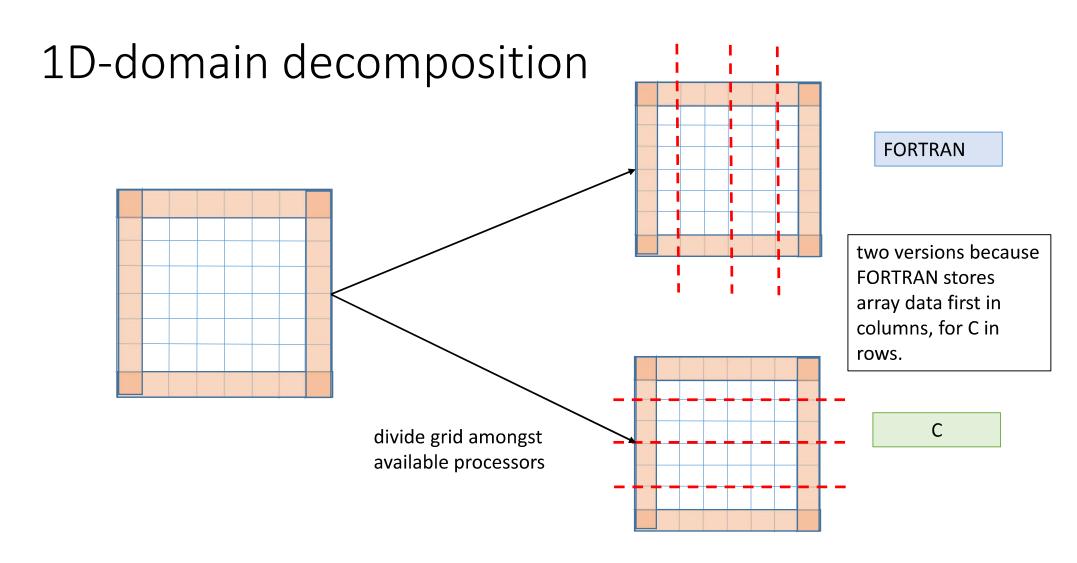


```
REAL A(0:n+1,0:n+1), B(1:n,1:n)
!Main Loop
DO WHILE(.NOT.converged)
                         ! perform 4 point stencil
                        DO j=1, n
                                                DO i=1, n
                                                                           B(i,j)=0.25*(A(i-1,j)+A(i+1,j)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-1)+A(i,j-
1)+A(i,j+1))
                                                   END DO
                        END DO
                         ! copy result back into array A
                        DO j=1, n
                                                 DO i=1, n
                                                                        A(i,j) = B(i,j)
                                                   END DO
                         END DO
! convergence test
END DO
```

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Jacobi in Parallel

- For simplicity, we will use 1D domain decomposition, dividing rows or columns of the grid among the MPI ranks.
- Since each rank will need data from neighbouring domains need to set up halo regions.
- For efficiency, exchange columns with Fortran and rows with C.
- As a first version, can use MPI_Send and MPI_Recv to exchange the data.



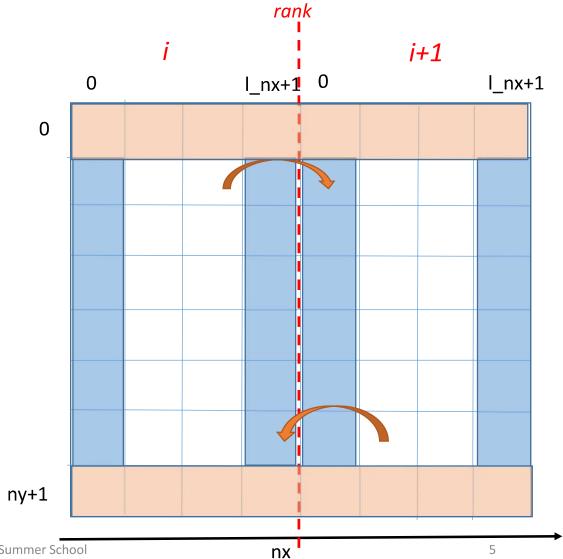
Halo exchange -Fortran Version

We start with a data grid(ny,nx) which becomes grid(0:ny+1,0:nx+1) when we include the boundaries.

Each local domain is $(1..ny,1..l_{nx})$ but with a halo region + boundaries we have

$$(0..ny+1,0..l_{nx}+1).$$

Ranks 0 and size-1 need only 1 halo region, since they must store the left and right border conditions.



halo

boundary

grid

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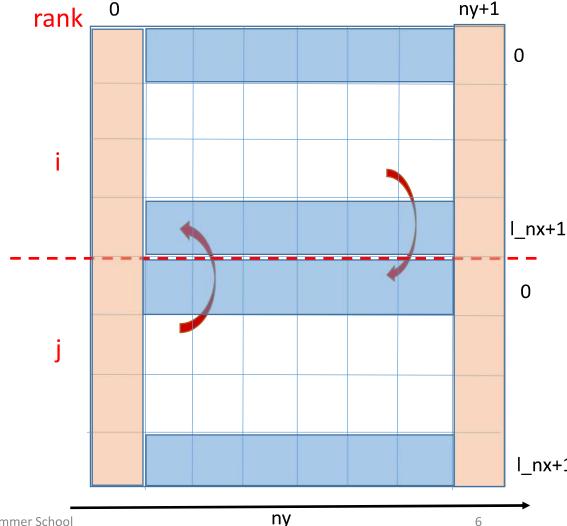
Halo exchange C Version

For C we exchange rows instead of columns, such that the rows are divided among the MPI ranks.

MPI ranks 0 and size-1 need only 1 halo region (and only 2 transfers) because they contain the top and bottom boundary conditions.

Note we have inverted the nx and ny axes with respect to the FORTRAN version.





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