Visual Recognition using Deep Learning

Tips for Final Project Presentation

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Presentation

- Your presentation/reports may include
  - Introduction
  - Related work
  - Proposed approach
  - Experimental results
  - Conclusions

- Presentation and reports need to include the link of your code

Presentation

- Your presentation
  - Introduction
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Introduction

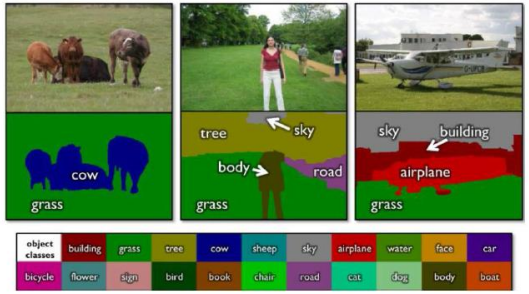
- Problem statement
- The importance of this problem
- The difficulties you address

Introduction

- Problem statement
- The importance of this problem
- The motivation or difficulty you address

Semantic Segmentation

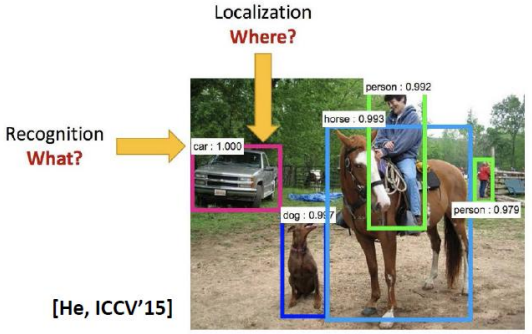
- Goal: Label each pixel to one of predefined classes (or background)
- Critical to high-level vision tasks such as scene understanding, robot navigation, and image retrieval



[*Shotton et al., 2007*]

Object Detection

- Goal: Detecting instances of semantic objects of certain classes
- Critical to high-level vision tasks such as surveillance, self-driving car, and image retrieval



[He, ICCV'15]

Introduction

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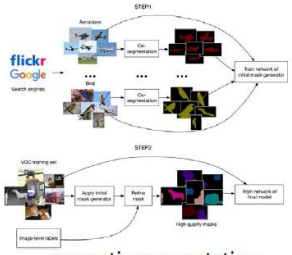
Why video interpolation

- High frame rate videos have temporally coherent content and smooth view transition
- Acquiring such videos leads to higher power consumption and more storage requirement
- Video interpolation compromises user experience and acquiring cost

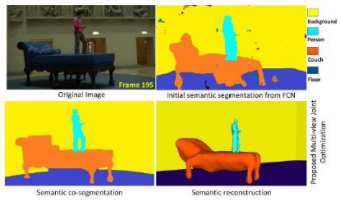
Why Co-segmentation

- Essential to many applications

image matching [Chen et al. PAMI'15]



semantic segmentation
[Shen et al. BMVC'17]



3D reconstruction
[Mustafa et al. CVPR'17]

Interduction

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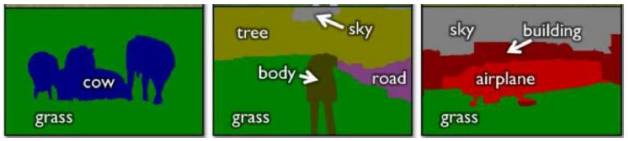
Motivation for algorithms with low annotation costs

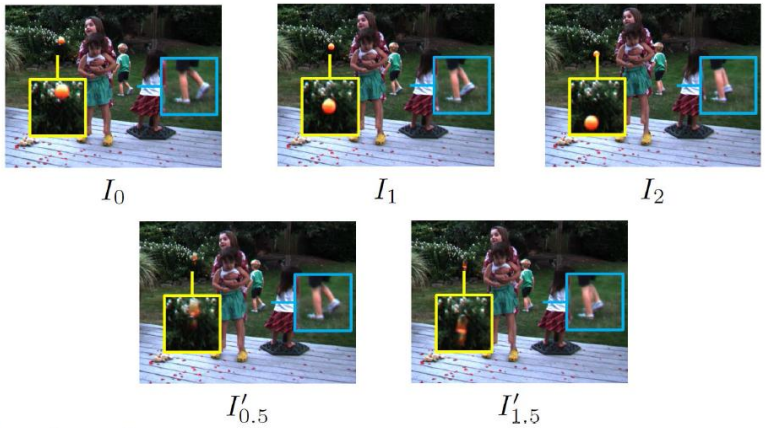
- Deep learning relies on a vast amount of training data
- This issue becomes worse for object segmentation
- Training data with pixel-wise annotations are required



- Motivation is threefold:
  - 1. Segmentation is important
  - 2. Deep learning is data hungry
  - 3. Pixel-wise annotation is required for segmentation

CNN-based methods for intermediate frame prediction

- The problems: artifacts and over-smoothed results



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Related work

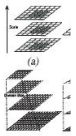
- Divide the related work/methods into groups
- For each group,
  - ➢ Give a high-level description about methods of this group
  - ➢ Summarize the pros and cons for each group

Related work

- Video frame interpolation
  - ➢ Conventional (non deep learning based) methods
    - Dense motion correspondences -> optical flow
    - Optimize complex objective function
    - ✗ time-consuming
    - ✗ computationally expensive
  - ➢ CNN-based methods
    - Predict the optical flow
    - Predict the intermediate frame

Using Powerful Handcrafted Features

- Conven
  handcra



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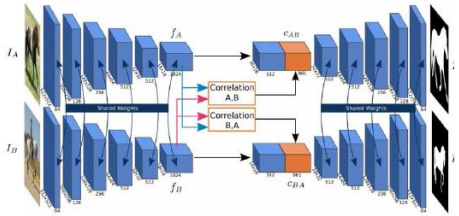
Using CNN

- Supervised CNN [1, 2] for joint feature extraction and co-segmentation



[Li et al. arXiv'18]

- Need pixel-wise annotated training data: violating the unsupervised nature of co-segmentation

[1] Yuan et al., "Deep-dense conditional random fields for object co-segmentation," *IJCAI*,17
[2] Li et al., "Deep Object Co-Segmentation", arXiv'18

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Proposed approach

- Overview: Network figure
- Details of your approach

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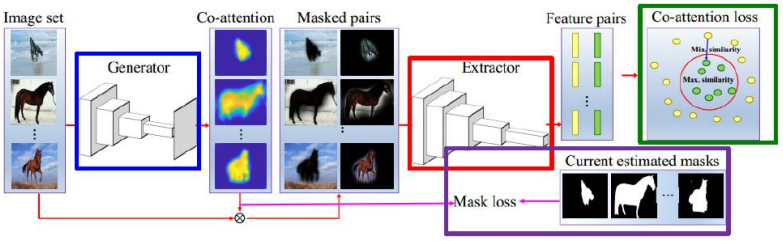
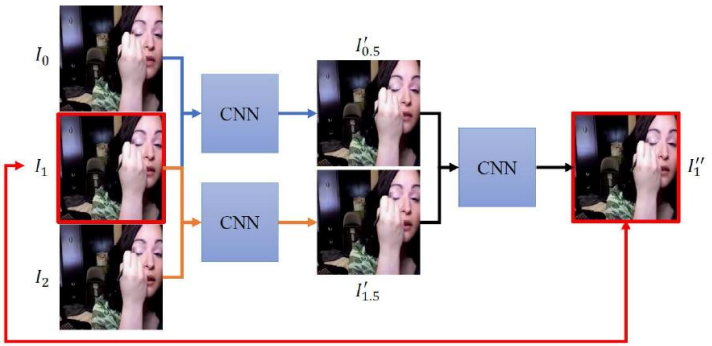
Approach Overview



- Two CNN modules: map generator and feature extractor
- Two loss functions: co-attention loss and mask loss

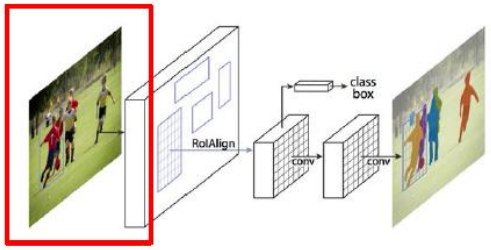
Our idea: Cycle consistency checking

- Observation: Over-smoothed frames or frames with artifacts cannot well reconstruct the original frames

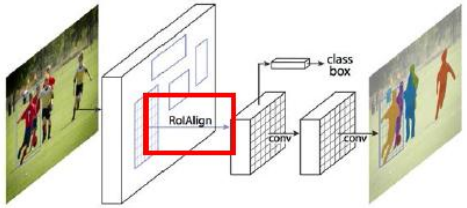


Proposed approach

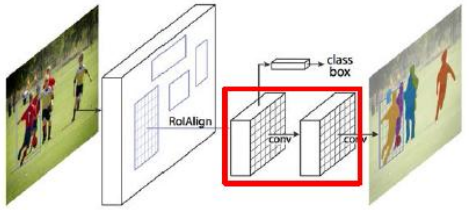
- Overview: Network figure with loss function
- Details of your approach



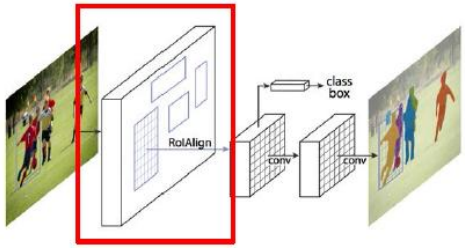
1. feature extractor



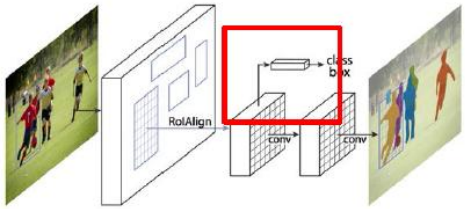
3. ROIAlign



5. segmentation branch



2. region proposal



4. detection branch

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Experiment results

- Dataset(s) and metric(s) for evaluation
- Comparison with state-of-the-arts
- Ablation studies

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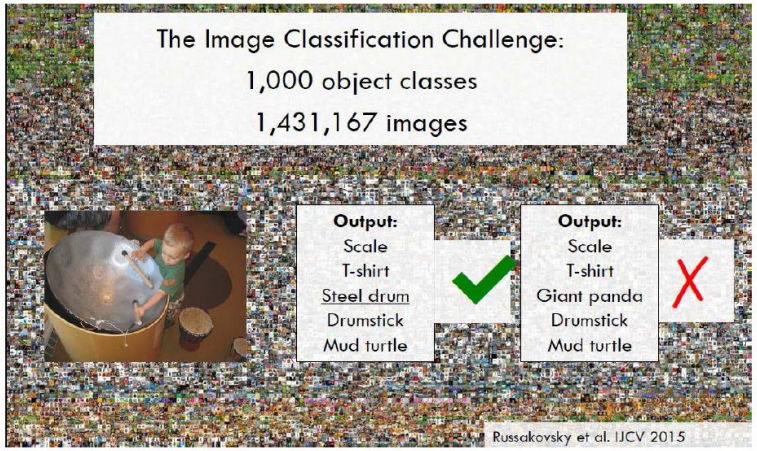
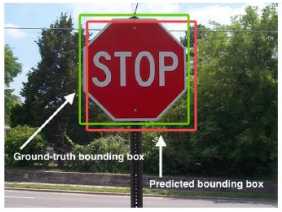
ImageNet large scale visual recognition challenge (ILSVRC)



Detection accuracy

- Intersection over union (IoU)



$$IoU = \frac{\text{Area of Overlap}}{\text{Area of Union}}$$

- IoU with a threshold to determine if an object is correctly detected
- Average Precision (AP): the average precision over thresholds
- mean AP (mAP): the mean of APs over classes

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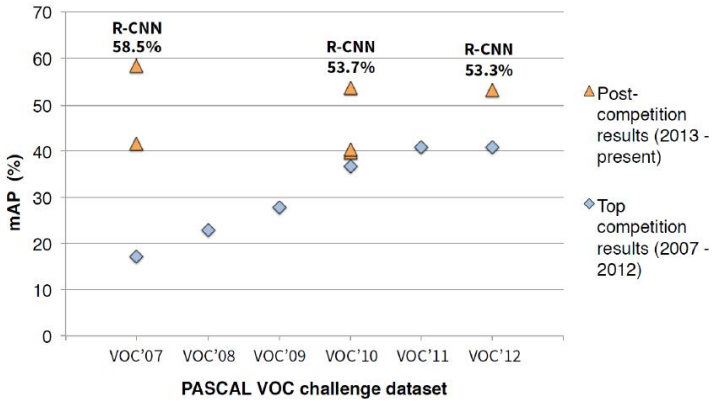
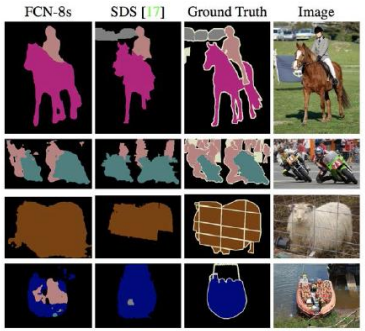
Experimental Results

- Evaluation on Pascal VOC dataset



Experimental Results on Pascal VOC

	mean IU VOC2011 test	mean IU VOC2012 test	inference time
R-CNN [12]	47.9	-	-
SDS [17]	52.6	51.6	~ 50 s
FCN-8s	**62.7**	**62.2**	~ **175 ms**



Experiment results

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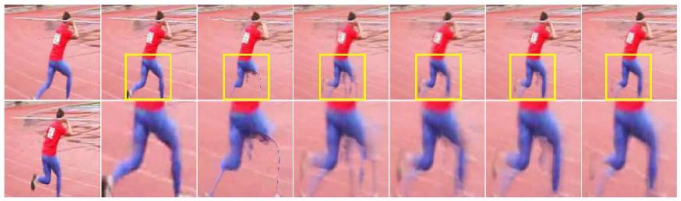
Experimental results: Ablation studies on UCF dataset

	PSNR	SSIM
Baseline (DVF)	35.89	0.945
+ *Cycle*	36.71 (+0.82)	0.950 (+0.005)
+ *Cycle* + *Motion*	36.85 (+0.96)	0.950 (+0.005)
+ *Cycle* + *Edge*	36.86 (+0.97)	0.952 (+0.007)
full model	**36.96** (+1.07)	**0.953** (+0.008)



Input (a) Ground truth (b) Baseline (DVF) (c) + Cycle (d) + Cycle + Motion (e) + Cycle + Edge (f) Full model

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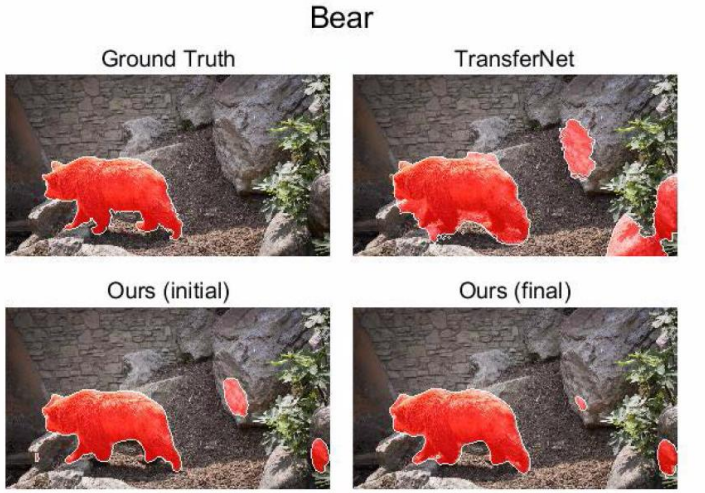
Demo video

Code Available at:
https://github.com/wenz116/TransferSeg



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Conclusions

- Summarize your work
- Summarize what you learned/found in the final project

Presentation & Reports & Code

- Your presentation/reports should include
  - GitHub/ GitLab link of your code
  - Introduction
  - Related work
  - Proposed approach
  - Experiment results
  - Conclusions
- Meeting all aforementioned requirements gets 80% of the scores for this part

Presentation & Reports & Code

- Your presentation/reports should include
  - The link to your code
  - Introduction: How you advance this field/topic?
  - Related work: What are the advantages of your method over all existing methods?
  - Proposed approach: How to design your approach to achieve the advantages you claim? Is your method technically sound?
  - Experiment results: Does your approach achieve SOTA results? Do ablation studies support the claimed advantages?
  - Conclusions: Any new and insightful findings or conclusions?
- Meeting all aforementioned requirements gets 80% of the scores for this part

Team member contribution

- Specify the contribution made by each team member to each of the following five tasks in the report:

Tasks	contributors (%)
Literature survey	0856065 (100%)
Approach design	0856078 (50%), 0856605 (50%)
Approach implementation (experiment)	0856078 (30%), 0856605 (70%)
Report writing	0856065 (80%), 0856078 (20%)
Slide making and oral presentation	0856605 (33%), 0856065 (33%), 0856078 (33%)

Thank You for Your Attention!

Yen-Yu Lin (林彥宇)

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